# A Novel Approach of Feature Extraction for Analog Circuit Fault Diagnosis Based on WPD-LLE-CSA

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**Abstract** – The rapid development of large-scale integrated circuits has brought great challenges to the circuit testing and diagnosis, and due to the lack of exact fault models, inaccurate analog components tolerance, and some nonlinear factors, the analog circuit fault diagnosis is still regarded as an extremely difficult problem. To cope with the problem that it's difficult to extract fault features effectively from masses of original data of the nonlinear continuous analog circuit output signal, a novel approach of feature extraction and dimension reduction for analog circuit fault diagnosis based on wavelet packet decomposition, local linear embedding algorithm, and clone selection algorithm (WPD-LLE-CSA) is proposed. The proposed method can identify faulty components in complicated analog circuits with a high accuracy above 99%. Compared with the existing feature extraction methods, the proposed method can significantly reduce the quantity of features with less time spent under the premise of maintaining a high level of diagnosing rate, and also the ratio of dimensionality reduction was discussed. Several groups of experiments are conducted to demonstrate the efficiency of the proposed method.

**Keywords**: Feature extraction, Analog circuit fault diagnosis, Wavelet packet decomposition, Local linear embedding, Dimensionality reduction.

#### 1. Introduction

The rapid development of large-scale integrated circuits led to its widely using in military, communication, automatic control and other fields. While most of the electronic systems are digitized, 80% or so faults occur in the analog part [1]. Analog circuit fault detection and diagnosis are still considered as an extremely difficult problem [2-4] and have several conundrums due to the following characteristics: the lack of exacted fault models, inaccurate analog components tolerance, the nonlinear nature of the problem, and so on. Thus, test and diagnosis on analog circuits are still evolved very slowly. When the analog circuit fails, the corresponding fault symptoms must be shown, such as voltage and current signal. These symptoms contain the running information and fault information of circuits. Therefore, by collecting the original signals such as voltage and current that reflect the real operation state of the circuit, the accurate fault analysis and pattern extraction can train the accurate fault classifier containing all the known fault information to diagnose the known fault type. The essence of analog circuit fault diagnosis is to classify the fault and locate the faulty component in the circuit, so it is actually a typical pattern

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recognition problem. The widespread PR-based analog circuit fault diagnosis approaches generally include 5 steps: (i) circuit data acquisition, (ii) fault feature extraction, (iii) typical feature construction, (iv) classification algorithm, and (v) diagnosis result evaluation and feedback. A welltrained diagnosis approach is based not only on an appropriate classification algorithm, but also on the large amount of training data that should cover every fault class as well as effective feature extracting process that is used to select the fault features [5]. Feature extraction appears to be an important part of analog circuit fault detection and diagnosis. In fact, PR-based diagnosis algorithms are critical procedure which to find some efficient methods to extract more valid features and reduce the dimension of input data to minimize its training and processing time simultaneously. In the literature [6-8], the technique of wavelet analysis is used to extract fault features and it performs well. Due to the perfect local property of wavelet in both time and frequency domain, feature extraction using wavelet analysis technique has become the most appealing fault feature extraction method to process noisy and unstable signals, such as transient response of analog circuit [3]. This type of transformation usually requires continuous sampling of the fault circuit to obtain the critical information of the circuit state. However, the fault features constructed by this process were of high dimension and large quantity. When these features were input to a classifier algorithm directly, it will impose a large amount of computational complexity and may result slowly convergence. Therefore, it is vital to reduce the

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circuit [3]. This typ continuous sampling critical information fault features construction

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dimension of the obtained fault feature data after wavelet analysis in analog circuit fault diagnosis.

In the field of machine learning, dimensionality reduction refers to use a mapping method to obtain a low-dimensional manifold which is embedded in the high-dimensional pixel space. In many algorithms, the reduced dimension algorithm becomes part of the data preprocessing [9]. One of the most widely used methods for dimensionality reduction in many different applications is PCA (principal component analysis) and LDA (linear discriminant analysis). PCA [10] "picks the dimensions of the greatest variance in the initial data and maps all the points to the new coordinate system which is built by the maximum variance directions". LDA [11] uses the category information to obtain the optimal projection direction by maximizing the ratio of the divergence of the data class to the divergence of the class divergence. But PCA and LDA were usually be used in linear dimensionality reduction applications. Unfortunately, the data of most engineering application are non-linear. Therefore, some typical nonlinear dimensionality reduction algorithms were widely used, such as kernel PCA and manifold learning dimension reduction algorithm. The weaknesses of kernel PCA is that it has no theoretical basis for the selection of kernel functions [12-13]. ISOMAP and LLE are typical representation of the nonlinear dimensionality reduction algorithm based on manifold learning. ISOMAP is global method which "try to preserve the global structure of the information by sustaining pairwise distances between all points in pair, but it impose high computational complexity" [14]. LLE algorithm was proposed by Saul and Roweis in 2000 based on manifold learning, which has the ability to transform the global nonlinearity into local linearity, and extends the perception of diminishing dimensionality [15]. With the advantages of simple parameters and low time complexity [16], LLE is a suitable choice for this problem. In 2016, Deng [17] proposed a method based on wavelet packet and ELM, and applied to analog circuit soft fault diagnosis successfully, but they didn't discuss the decomposition level of wavelet packet.

In order to fully excavate the fault information and reduce the dimension of input eigenvector, in this paper, a feature extraction and dimension reduction method based on wavelet packet decomposition and LLE algorithm was proposed, and the diagnostic module mainly completes the training with clone selection algorithm and identifies the faults. The WPD-LLE method sovled the problem that the feature dimension of wavelet packet decomposition is increasing exponentially with the growth of decomposition level, which leads to the inefficiency or non-convergence of the diagnosis algorithm. The experimental results show that the proposed fault feature extraction method can well reflect the essential characteristics of fault response signal, not only show better performance than other feature extraction methods, but also well satisfied the two indicators of computation time and diagnosis rate.

The structure of this paper as follows: Section 2 mainly introduces the WPD technology and the LLE algorithm. Section 3 briefly introduces the framework of the whole system. After that, extensive comparative experiments are presented in Section 4 which present the simulation example of WPD-LLE-CSA system on a two-stage four-op-amp biquad low-pass filter circuit. The conclusion is given in the section 5.

## 2. Method

## 2.1 Wavelet packet decomposition

Wavelet packet decomposition (WPD) is an extension of the wavelet transform by combining multiresolution approximation with wavelets [18]. WPD can decompose the high-frequency part and low-frequency part of the of the input signal at the same time, so as to fully exploit the hidden features in the input signal [19]. Thus, assuming the decomposition level is  $n, w_{ik}$  the quantity of the nodes after decomposition is  $2^n$ .

The methods of extracting wavelet feature vectors include information entropy, extreme value and energy distribution. The wavelet packet energy spectrum includes the characteristic information such as amplitude, period and frequency of corresponding voltage signal, which is the extraction of the intrinsic characteristic of the circuit signal. In general, the output response of analog circuit is a continuous non-stationary signal. When the circuit fails, the energy distribution of each frequency band is obviously affected. The purpose of the diagnosis is to detect the information that is hidden in the mass spectra of energy spectrum in the most efficient way as possible.

The low pass filter h(k) coefficients and the high pass filter g(k) coefficients are respectively in the corresponding multiscale analysis. For a set of discrete signal X(t), the wavelet packet decomposition and reconstruction algorithm as follows:

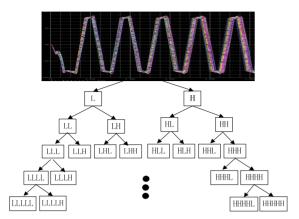
$$d_{j+1}^{2n} = \sum_{k} h(k-2t)d_{j}^{n}(k)$$

$$d_{j+1}^{2n+1} = \sum_{k} g(k-2t)d_{j}^{n}(k)$$
(1)

We define the energy content  $E_{i,j}(k)$  in each subfrequency band as :

$$E_{i,j} = \sum_{k=1}^{N} |d_{i,j}(k)|^2$$
 (2)

 $d_{i,j}(k)$  represents the wavelet packet coefficients, N represents the length of the signal. Thus, the high/low frequency coefficients of each layer constitute the energy value of each frequency band. In most cases, the energy spectrum can be regarded as features to construct a feature



**Fig. 1.** The tree structure of five layer wavelet packet decomposition

vector for faults classification. This energy eigenvector acting as fault feature eigenvector is defined as

$$T = [E_1, E_2, ..., E_n]$$
 (3)

To eliminate the influence of absolute value of each component, all these components of the vector were usually normalized before they were put into use. This process is the so-called energized procedure.

The algorithm is a step by step decomposing a node into two nodes., subdivide the entire frequency band of the sampling signal into small segments as shown in Fig. 1. In this way, by increasing the number of decomposed layers, WPD can extract the high frequency components and low frequency components of the input signal to any details.

In Fig. 1, the feature dimension of WPD feature extraction technology increases exponentially with the growth of the decomposition layer. In fact, if the decomposed level of wavelet is too small, valid information cannot be completely extracted. However, if the decomposition level is too large, the feature dimension increases which will fully tap the error message, but this approach would lead to "the curse of dimensionality" problem, that influences the training time and diagnostic speed of the classifier. As a result, how to solve "the curse of dimensionality" problem by WPD, there were no effective guidance rules. Focus on this problem, the WPD-LLE method was proposed to extract the fault features.

## 2.2 LLE dimensionality reduction algorithm

With the advantages of simple parameters and low time complexity, LLE is suitable for this problem as the LLE algorithm preserves the local geometric structure in the process of dimensionality reduction [20]. The key to the dimension reduction of nonlinear high dimensional data is to find the low dimensional structure hidden in high dimensional data. It tries to keep the linear relationship between the samples in the neighborhood. For a set of data sets with embedded properties, the relationship between the

intrinsic low-dimensional space and the local neighborhood of the embedded space should be constant.

$$x_{i} = W_{ij} X_{j} + W_{ik} X_{jk} + W_{il} X_{l}$$
 (4)

where  $W_{ij}$ ,  $W_{ik}$ ,  $W_{il}$  is weight coefficient, the sample is reduced after the LLE dimension, The projection of  $x_i$  in low dimensional space corresponds to  $x_i'$  and  $x_j$ ,  $x_k$ ,  $x_l$  corresponds to  $x_j'$ ,  $x_k'$ ,  $x_l'$  respectively, also through a linear combination of reconstruction, that is

$$x_{i}' \approx w_{ij} x_{j}' + w_{ik} x_{jk}' + w_{il} x_{l}'$$
 (5)

Thus,  $W_{ij}$ ,  $W_{ik}$ ,  $W_{il}$  to be maintained after mapping.

In conclusion, the linear combination can only play a role in the vicinity of the neighborhood, and the samples with far distance from the sample point have no effect on the local linear combination, which can reduce the complexity of the dimension reduction.

LLE first finds its neighbor subscript set  $Q_i$  for each sample  $x_i$ , then the coefficients  $x_i$  for linear reconstruction of  $x_i$  based on the sample points in  $Q_i$  were calculate:

$$\frac{\min}{w_{1}, w_{2}, ..., w_{m}} \sum_{i=1}^{m} \left\| x_{i} - \sum_{j \in Q_{i}} w_{ij} x_{j} \right\|_{2}^{2}$$
s.t. 
$$\sum_{j \in Q_{i}} w_{ij} = 1$$
(6)

$$C_{jk} = (x_i - x_j)^T (x_i - x_k)$$
,  $w_{ij}$  has a closed solution,

$$w_{ij} = \frac{\sum_{k \in Q_i} C_{jk}^{-1}}{\sum_{l,s \in Q_i} C_{ls}^{-1}}$$
 (7)

LLE keeps  $w_i$  unchanged in low dimensional space, thus the low-dimensional spatial coordinates  $z_i$  corresponding to  $x_i$  can be solved by:

$$\frac{\min}{z_{1}, z_{2}, \dots, z_{m}} \sum_{i=1}^{m} \left\| z_{i} - \sum_{j \in Q_{i}} w_{ij} z_{j} \right\|_{2}^{2}$$
 (8)

(6) is the same as the optimization target of (8). The only difference is that  $w_i$  is needed in (6), and the lower dimension space coordinates  $z_i$  corresponding to  $x_i$  are needed in (8).

$$\begin{split} Z = & \left(z_1, z_2, \dots, z_m\right) \in \mathbb{R}^{\mathbf{d}' \times \mathbf{m}} \;,\; \left(W\right)_{ij} = w_{ij} \\ M = & \left(I - W\right)^T \left(I - W\right) \end{split} \tag{9}$$

(8) can be rewritten:

$$\min_{\mathbf{z}} \operatorname{tr}(\mathbf{Z}\mathbf{M}\mathbf{Z})^{\mathrm{T}} \quad \text{s.t.} \quad \mathbf{Z}\mathbf{Z}^{\mathrm{T}} = \mathbf{I}$$
 (10)

where (10) can be solved by eigenvalue decomposition:

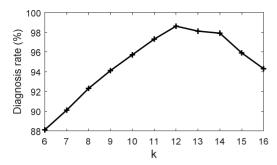


Fig. 2. k value experiments result

M is the smallest d'eigenvalue corresponding to the eigenvector matrix  $Z^T$  the LLE algorithm can be described as follows:

Input: sample set  $\mathcal{D} = \{x_1, x_2, ..., x_m\}$ ; neighbor parameter k; Low dimension space d'.

Since the problems such as noise interference and sparse sampling are often associated with the acquisition of data, the stability of the LLE algorithm is greatly affected, so the stability of the LLE algorithm needs to be strengthened. The weight of each sample is calculated to reflect its importance, so the robustness of the LLE algorithm is improved by reducing the influence of noise point after weighting.

Compared with other dimensionality reduction methods, the advantage of local linear embedding algorithm is to define the only parameters which is the k neighborhood number. The performance of the LLE algorithm depends on the selection of the k neighborhood parameter, so how to select the optimal k neighborhood parameter is crucial. However, there is no clear guide principle for the selection of k values. For different data sets, the choice of the best k value may be different. If the selected k value is too small, it may lead to the loss of the important characteristics of the original data. But if the selection of k value is too large, although it can retain most of the original information, the irrelevant data points will also play a role in the judgment, making the judgment wrong and the performance of the reduction will be worse.

The k values determined by different methods are very different, and it is very important to find the correct k value. In practical engineering applications, the k value usually select a small number, in this paper, using cross validation method, namely the selection of part of samples for training set, part of the sample do test set, to select the optimal value of k. As shown in Fig. 2, by conducting a series of experiments, k was put to 12, which performs better than other choices through experimental verification.

## 3. The Framework Based on WPD-LLE-CSA

In this investigation, a novel analog circuit fault diagnosis method based on WPD-LLE-CSA which combined with wavelet packet decomposition, local linear embedding

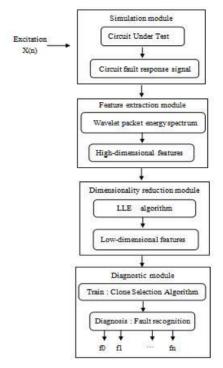


Fig. 3. WPD-LLE-CSA analog circuit fault diagnosis framework

algorithm and clonal selection algorithm was proposed. The general framework was shown in Fig. 3.

The scheme model contains four parts: simulation module, feature extraction module, dimension reduction module, diagnostic module. The simulation module used Pspice software to simulate the circuit under test in the normal mode and every fault mode, and to obtain the response data of circuit. The feature extraction module extracted the wavelet packet energy spectrum as the high-dimensional features. The LLE algorithm is used to reconstruct the features after WPD, and the low-dimensional features were constructed.

The LLE algorithm is one of the most commonly used algorithms to emphasize local optimization, which has the global optimal solution and is suitable for solving practical problems. The feature dimension of wavelet packet energy spectrum diagram increases exponentially with the increase of the wavelet packet decomposition level n:

$$y = \frac{x}{2^n} \tag{11}$$

In the formula (11), y represents the dimension after dimension reduction, for example, when the wavelet decomposes 6 layers, the original characteristic dimension is 64 dimension, and the dimension is reduced to 32, 16, 8, 4 and 2, and the output results are tested. The wavelet packet energy spectrum diagram was shown in Fig. 4.

In order to analyze the performance of the diagnosis scheme, we used the fault classifier after training to diagnose the fault and evaluate the performance with diagnosis rate.

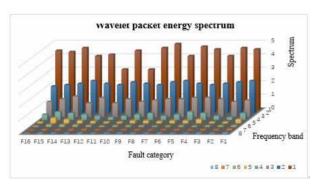


Fig. 4. Wavelet packet energy spectrum diagram

Diagnostic classification algorithm using the technique of artificial immune clonal selection algorithm, the most prominent technology in this is far more than the neural network has a proven solution fast convergence ability of classification algorithm.

Clone selection algorithm is a kind of directed random search technique that mimics the antigen-antibody reaction of the immune system in mammals [23]. In the field of analog circuit fault diagnosis, the antibodies are vectors corresponding to various trained fault class centers, and the antigens are the faults that need to be identified by the classifier [5]. Clone selection algorithm for troubleshooting mainly consists of three steps: (i) Select the fault training sample. (ii) The training samples were used to train the system, and the clustering centers of each fault mode were obtained. (iii) Using the obtained clustering center to classify the various fault samples of the circuit, and locating the faulty components. Its fast convergence speed can avoid the algorithm falling into local optimum, so this paper adopts the clonal selection algorithm for the fault training and diagnosis algorithm.

## 4. Experimental Results and Analysis

## 4.1 Fault settings and experimental environment

In order to verify the feasibility of our method, we would use a two-stage four-op-amp biquad low-pass filter [3] as benchmark CUT. This type of analog circuit is very common in existing equipment and also is well studied in [8] due to its importance. As to parametric faults, we followed the category description in [3] including mounting of components with values out of tolerance on this biquad low-pass filter. Circuit structure was shown in Fig. 5.

Parameters and fault settings are consistent with [3,8], which set the capacitor capacitance tolerance of  $\pm$  10%, the resistance tolerance of  $\pm$  5%. The input excitation signal was set to 5V, the width of 10µs narrow pulse. In the test, 15 fault modes were set and the normal mode is shown in Table 1.  $\uparrow$  and  $\downarrow$  represent the fault value more than and less than the nominal value.

According to Table 1, the normal state of the circuit and

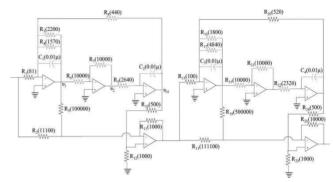


Fig. 5. The schematic two-stage four-op-amp biquad lowpass filter circuit

Table 1. Circuit fault mode

Fault state	Fault type	Nominal value	Fault value
F0	None		
F1	C1↑	$0.01 \mu F$	$0.051 \mu F$
F2	C2↑	$0.01 \mu F$	$0.02 \mu F$
F3	C3↑	$0.01 \mu F$	$0.048 \mu F$
F4	C4↑	$0.01 \mu F$	$0.031 \mu F$
F5	R3↑	$2.2k\Omega$	$5k\Omega$
F6	R4↓	$1.57 \mathrm{k}\Omega$	$0.6 \mathrm{k}\Omega$
F7	R6↑	$10 \mathrm{k}\Omega$	$16.5 \mathrm{k}\Omega$
F8	R7↓	$10k\Omega$	$5.5$ k $\Omega$
F9	R8↑	$0.44 \mathrm{k}\Omega$	$2.2k\Omega$
F10	R9↑	$2.64 \mathrm{k}\Omega$	$4.3k\Omega$
F11	R16↑	$1.8 \mathrm{k}\Omega$	$7.8 \mathrm{k}\Omega$
F12	R17↓	$4.84 \mathrm{k}\Omega$	$1.6 \mathrm{k}\Omega$
F13	R19↑	$10 \mathrm{k}\Omega$	$30 \mathrm{k}\Omega$
F14	R21↓	$10 \mathrm{k}\Omega$	$3.75 \mathrm{k}\Omega$
F15	R22↑	$2.32k\Omega$	$7 \mathrm{k}\Omega$

the 15 fault states were simulated separately. Each time one fault was injected during the experiment, while all the other components change their value within their tolerance alternatively. With this two stage four-op-amp biquad low-pass filter, we input a single impulse of height 5V and duration of 10s and observed its responses. The transient simulation time in P spice was set to 1000µs and the sampling time was set to 2us. A total of 50 Monte Carlo analyzes were performed on each fault mode and normal mode of the circuit. A total of 800 sets of data were sampled. For each pattern, 30 groups of data selected from the 50 groups were used to train the clonal selection algorithm, and the remained 20 groups of data were used as diagnostic test. The simulation data of the corresponding 16 fault modes (including the normal state) were obtained.

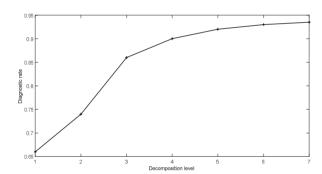
#### 4.2 Experiment results

Since the fault features extracted by Haar show the good performance in the previous experiments [5], thus Haar was selected as the wavelet packet basis function in this paper. As mentioned in the third part, the parameter k of the LLE is selected as 12. The clonal selection classifier was used to calculate the diagnosing rate for each group of experiments. The threshold value of the total population affinity was T=0.01. When the variation value of the affinity between the two generations of antibody was less than 0.01, the iteration stopped. Clone scale Kscale=8, learning factor =0.3, and antibody inhibition rate was 10%. The optimal antibody selection number n is set to 5.

As shown in Fig. 6, the diagnosis accuracy was improved with the increasing of decomposition level of the wavelet packet. But the attendant question is: the dimension of features is also in exponential growth.

Extensive experiments were conduct to figure out the best proportion of the dimension reduction. Under the primise that 6 levels of decomposition, all experimental conditions remain unchanged, only the ratio of reduction keep changed.

Lots of experiments were conducted on different levels of decomposition, and compared to reveal the tradeoff between accuracy and time consume of traning and test. The optimal diagnosis effect was achieved by studying the combination of different decomposition levels and different dimensionality ratios. According to Table 2, after the original data was decomposed to 6 levels, the best accuracy of dimensional reduction was achieved. When the dimensionality reduction rate was 50%, the fault diagnosing rate was as high as 99.38%. And when the dimensionality reduction rate was 75%, the diagnostic rate



**Fig. 6.** The schematic two-stage four-op-amp biquad low-pass filter circuit

remained at a high level of 99.06%, the time consumption is reduced by a third. But with the increase in the degree of reduction, lots of useful information was discarded, the fault diagnosis effect quickly deteriorated. For instance, when dropped to 2 dimension, the obtained feature dimension is lower than the intrinsic dimension, and the fault diagnosis rate appear a sharp decline, which was only 40% approximately.

As shown in Table 3, the training and test time required for different feature dimensions are listed. It can be clearly seen from the table: the time of training and test was shortened greatly after reducing dimension.

Under the premise of maintaining a high level of diagnosing rate, the computation complexity was greatly reduced. As shown in Table IV, when the feature dimension was compressed to the original 1/4, the diagnosing rate reaching 99.06%, which performs better than that WPD method mentioned in paper [17](96.4%) and [21] (94.4%). The reason of the proposed WPD-LLE-CSA method outperforms other methods consist two main aspects: First, the scheme further excavates the decomposition level of wavelet packet. Second, the LLE algorithm has the advantage that it doesn't suffer from short-circuiting

**Table 3.** Comparison of results with time consume

Feature dimension	Training time/s	Test time/s	
64	2.69	1.92	
32	2.36	1.55	
16	1.91	1.18	
8	1.57	0.99	
4	0.95	0.66	
2	0.38	0.23	

**Table 4.** Comparison of results with different methods

Paper	Method	Fault mode	Diagnostic rate
Paper [17]	WPD+SVM	7	96.4%
Paper [21]	WPD+ELM	8	94.4%
This paper	WPD+LLE+CSA	16	99.06%

Table 2. WPD-LLE-CSA Fault recognition results under 6 decomposition levels

Fault	Fault	64-2dimension	64-4dimension	64-8dimension	64-16dimension	64-32dimension
state	type	Diagnostic rate				
F0	C1↑	45.00%	100.00%	100.00%	100.00%	100.00%
F1	C2↑	15.00%	100.00%	100.00%	100.00%	100.00%
F2	C3↑	0.00%	70.00%	100.00%	95.00%	100.00%
F3	C4↑	100.00%	100.00%	100.00%	100.00%	100.00%
F4	R3↑	45.00%	80.00%	95.00%	95.00%	100.00%
F5	R4↓	30.00%	95.00%	100.00%	100.00%	100.00%
F6	R6↑	15.00%	95.00%	80.00%	100.00%	95.00%
F7	R7↓	15.00%	85.00%	100.00%	100.00%	100.00%
F8	R8↑	100.00%	90.00%	95.00%	100.00%	95.00%
F9	R9↑	55.00%	85.00%	100.00%	95.00%	100.00%
F10	R16↑	65.00%	100.00%	100.00%	100.00%	100.00%
F11	R17↓	15.00%	100.00%	100.00%	100.00%	100.00%
F12	R19↑	0.00%	100.00%	100.00%	100.00%	100.00%
F13	R21↓	0.00%	90.00%	100.00%	100.00%	100.00%
F14	R22↑	55.00%	100.00%	100.00%	100.00%	100.00%
F15	Normal	75.00%	95.00%	95.00%	100.00%	100.00%
	Average	39.38%	92.81%	97.81%	99.06%	99.38%

referring to erroneous connections in the neighborhood graph, which may seriously influence the pairwise geodesic distances and cause high-dimensional data points poorly to map to a lowdimensional space. It also make the algorithm avoid local optimization. Then, CSA is an efficient classification algorithm, and in previous studies [5] it has been proved that CSA is a method applicable to the research field.

#### 5. Conclusion

In this study, an intelligent fault diagnosis method the two-stage four-op-amp biquad low-pass filter circuit was proposed. First, the fault features are extracted from the original circuit data through wavelet packet decomposition technology, and the high dimensional eigenvectors are acquired. Then, this paper focused on how to determine the appropriate proportion of the dimension reduction. Finally, the clonal selection classifier is used to training and testing to verify and evaluate the feasibility of the scheme. A large number of experimental studies have been conducted on decomposition level and the scale of dimension reduction. The experimental results confirmed the applicability of LLE algorithm in analog circuit fault diagnosis, which provided a useful reference for complicated and practical engineering application.

In future, dimension reduction theory has a good prospect of in the application of analog circuit fault diagnosis. But it is still in the initial stage, the parameter selection of nonlinear reduction algorithm is in the experimental stage, and there is no clear theory guiding principle. It is necessary to pay attention to the development of dimension reduction theory and its research prospect in the field of analog circuit fault diagnosis.

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