

FIXED POINT THEOREMS IN MENGER SPACES USING AN IMPLICIT RELATION

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Abstract. In 2008, Al-Thagafi and Shahzad [Generalized I -nonexpansive selfmaps and invariant approximations, *Acta Math. Sinica*, 24(5) (2008), 867-876] introduced the notion of occasionally weakly compatible mappings in metric spaces. In this paper, we prove some common fixed point theorems for families of occasionally weakly compatible mappings in Menger spaces using an implicit relation. We also give an illustrative example to support our main result.

1. Introduction

The concept of probabilistic metric space was first introduced and studied by Menger [30], which is a generalization of the metric space. The study of this space was expanded rapidly with the pioneering works of Schweizer and Sklar [40, 41] and some of their coworkers. Such a probabilistic generalization of metric spaces appears to be well adapted for the investigation of physiological thresholds and physical quantities. It is also of fundamental importance in probabilistic functional analysis, nonlinear analysis and applications (see [18, 19, 24]). In 1972, Sehgal and Bharucha-Reid [42] initiated the study of contraction mappings in probabilistic metric spaces (briefly, PM-spaces) which is an important concept in the development of fixed point theorems.

Jungck and Rhoades [26] introduced the notion of weakly compatible mappings in metric spaces. Singh and Jain [45] formulated the notion of weakly compatible mappings in probabilistic settings and proved some fixed point theorems in Menger spaces. In 2008, Al-Thagafi and Shahzad [7] introduced the notion of occasionally weakly compatible (briefly, owc)

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mappings in metric spaces, while Chandra and Bhatt [17] extended the notion of owc mappings in probabilistic setting. It is worth to mention that every pair of weak compatible self mappings is owc but the converse is not always true. Many authors proved common fixed point theorems using the notion of owc mappings in different settings (see [1, 2, 3, 4, 5, 6, 7, 8, 10, 11, 12, 13, 14, 15, 16, 17, 20, 21, 22, 23, 27, 28, 29, 32, 33, 34, 35, 36, 39, 46]).

In 1999, Popa used the family of implicit real functions and proved some common fixed point theorems (see [37, 38]). These observations motivated us to prove common fixed point theorems for families of owc mappings in Menger spaces. We also give an example to support our main result.

2. Preliminaries

Definition 2.1. [41] A mapping $\Delta : [0, 1] \times [0, 1] \rightarrow [0, 1]$ is t -norm if Δ is satisfying the following conditions:

- (1) Δ is commutative and associative,
- (2) $\Delta(a, 1) = a$ for all $a \in [0, 1]$,
- (3) $\Delta(a, b) \leq \Delta(c, d)$ whenever $a \leq c$ and $b \leq d$ and $a, b, c, d \in [0, 1]$.

The following are the basic t -norms:

$$\begin{aligned}\Delta(a, b) &= \min\{a, b\}, \\ \Delta(a, b) &= ab, \\ \Delta(a, b) &= \max\{a + b - 1, 0\}.\end{aligned}$$

Definition 2.2. [41] A mapping $F : \mathbb{R} \rightarrow \mathbb{R}^+$ is called a distribution function if it is non-decreasing and left continuous with $\inf\{F(t) : t \in \mathbb{R}\} = 0$ and $\sup\{F(t) : t \in \mathbb{R}\} = 1$.

We shall denote by \mathfrak{S} the set of all distribution functions defined on $(-\infty, \infty)$ while $H(t)$ will always denote the specific distribution function defined by

$$H(t) = \begin{cases} 0, & \text{if } t \leq 0; \\ 1, & \text{if } t > 0. \end{cases}$$

If X is a non-empty set, $\mathcal{F} : X \times X \rightarrow \mathfrak{S}$ is called a probabilistic distance on X and the value of \mathcal{F} at $(x, y) \in X \times X$ is represented by $F_{x,y}$.

Definition 2.3. [41] A PM-space is an ordered pair (X, \mathcal{F}) , where X is a nonempty set of elements and \mathcal{F} is a probabilistic distance satisfying the following conditions: for all $x, y, z \in X$ and $t, s > 0$,

- (1) $F_{x,y}(t) = H(t)$ for all $t > 0$ if and only $x = y$,
- (2) $F_{x,y}(0) = 0$,
- (3) $F_{x,y}(t) = F_{y,x}(t)$,
- (4) if $F_{x,y}(t) = 1$ and $F_{y,z}(s) = 1$ then $F_{x,z}(t + s) = 1$.

The ordered triplet (X, \mathcal{F}, Δ) is called a Menger space if (X, \mathcal{F}) is a PM-space, Δ is a t -norm and the following inequality holds:

$$F_{x,y}(t + s) \geq \Delta(F_{x,z}(t), F_{z,y}(s)),$$

for all $x, y, z \in X$ and $t, s > 0$.

Every metric space (X, d) can always be realized as a PM-space by considering $\mathcal{F} : X \times X \rightarrow \mathfrak{S}$ defined by $F_{x,y}(t) = H(t - d(x, y))$ for all $x, y \in X$. So PM-spaces offer a wider framework than that of metric spaces and are better suited to cover even wider statistical situations.

Definition 2.4. [45] A pair (A, S) of self mappings of a Menger space (X, \mathcal{F}, Δ) is said to be weakly compatible (or coincidentally commuting) if they commute at their coincidence points, that is, if $Ax = Sx$ for some $x \in X$, then $ASx = SAx$.

The concept of owc mappings due to [7] is a proper generalization of nontrivial weakly compatible mappings which do have a coincidence point. The counterpart of the concept of owc maps in PM-spaces is as follows:

Definition 2.5. A pair (A, S) of self mappings of a Menger space (X, \mathcal{F}, Δ) is owc if and only if there is a point $x \in X$ which is a coincidence point of A and S at which A and S commute.

From the following example it is clear that owc is more general than weak compatibility.

Example 2.1. Let (X, \mathcal{F}, Δ) be a Menger space, where $X = \mathbb{R}$ and

$$F_{x,y}(t) = \begin{cases} \frac{t}{t+|x-y|}, & \text{if } t > 0; \\ 0, & \text{if } t = 0. \end{cases}$$

Define $A, S : \mathbb{R} \rightarrow \mathbb{R}$ by $Ax = 3x$ and $Sx = x^2$ for all $x \in \mathbb{R}$. Then $Ax = Sx$ for $x = 0, 3$ but $AS(0) = SA(0)$, and $AS(3) \neq SA(3)$. Thus A and S are owc mappings but not weakly compatible.

Lemma 2.1. [27] *Let (X, \mathcal{F}, Δ) be a Menger space, A and S are owc self mappings of X . If A and S have a unique point of coincidence, $w = Ax = Sx$, then w is the unique common fixed point of A and S .*

3. Implicit Relation

Many authors proved a number of common fixed point theorems using the notion of implicit relation on different spaces (see [9], [25], [37], [38], [44]). Recently, Sedghi et al. [43] proved a common fixed point theorem in fuzzy metric spaces by using the following implicit relation:

Let \mathcal{T} be the set of all continuous functions $T : [0, 1]^5 \rightarrow [-1, 1]$ satisfying the following conditions:

(T_1) $T(t_1, \dots, t_5)$ is increasing in t_1 and decreasing in t_2, \dots, t_5 .

(T_2) $T(u, v, v, v, v) \geq 0$ implies that $u > v, \forall v \in [0, 1]$ and $\forall u \in [0, 1]$.

Remark 3.1. [43] It is easy to see that $T(v, v, v, v, v) \geq 0$ implies that $v = 1$. If $v \neq 1$, by (T_2), $T(v, v, v, v, v) \geq 0$ implies that $v > v$, is a contradiction. Thus $v = 1$.

Example 3.1. [43] Let $T : [0, 1]^5 \rightarrow [-1, 1]$ be defined by $T(t_1, t_2, t_3, t_4, t_5) = t_1 - (\min\{t_2, t_3, t_4, t_5\})^h$ for some $0 < h < 1$.

4. Results

In this section, first we prove a common fixed point theorem for any even number of owc mappings in Menger space employing an implicit relation.

Theorem 4.1. Let $P_1, P_2, \dots, P_{2n}, A$ and B be self mappings of a Menger space (X, \mathcal{F}, Δ) with $\Delta(a, a) = a$ for all $a \in [0, 1]$ satisfying the following conditions:

(1) there exists $k \in (0, 1)$ and $T \in \mathcal{T}$ such that

$$T \left(\begin{array}{l} F_{Ax, By}(kt), F_{P_1 P_3 \dots P_{2n-1} x, P_2 P_4 \dots P_{2n} y}(t), \\ F_{Ax, P_1 P_3 \dots P_{2n-1} x}(t), F_{By, P_2 P_4 \dots P_{2n} y}(t), \\ \Delta(F_{By, P_1 P_3 \dots P_{2n-1} x}(\alpha t), F_{Ax, P_2 P_4 \dots P_{2n} y}(2t - \alpha t)) \end{array} \right) \geq 0,$$

for all $x, y \in X, \alpha \in (0, 2)$ and $t > 0$.

(2) Suppose that

$$\left\{ \begin{array}{l} P_1(P_3 \dots P_{2n-1}) = (P_3 \dots P_{2n-1})P_1, \\ P_1P_3(P_5 \dots P_{2n-1}) = (P_5 \dots P_{2n-1})P_1P_3, \\ \vdots \\ P_1 \dots P_{2n-3}(P_{2n-1}) = (P_{2n-1})P_1 \dots P_{2n-3}, \\ A(P_3 \dots P_{2n-1}) = (P_3 \dots P_{2n-1})A, \\ A(P_5 \dots P_{2n-1}) = (P_5 \dots P_{2n-1})A, \\ \vdots \\ AP_{2n-1} = P_{2n-1}A, \\ P_2(P_4 \dots P_{2n}) = (P_4 \dots P_{2n})P_2, \\ P_2P_4(P_6 \dots P_{2n}) = (P_6 \dots P_{2n})P_2P_4, \\ \vdots \\ P_2 \dots P_{2n-2}(P_{2n}) = (P_{2n})P_2 \dots P_{2n-2}, \\ B(P_4 \dots P_{2n}) = (P_4 \dots P_{2n})B, \\ B(P_6 \dots P_{2n}) = (P_6 \dots P_{2n})B, \\ \vdots \\ BP_{2n} = P_{2n}B \end{array} \right.$$

Then, if the pairs $(A, P_1P_3 \dots P_{2n-1})$ and $(B, P_2P_4 \dots P_{2n})$ are each owc, it follows that $P_1, P_2, \dots, P_{2n}, A$ and B have a unique common fixed point in X .

Proof. Since the pairs $(A, P_1P_3 \dots P_{2n-1})$ and $(B, P_2P_4 \dots P_{2n})$ are each owc, there exist points $u, v \in X$ such that $Au = P_1P_3 \dots P_{2n-1}u$, $A(P_1P_3 \dots P_{2n-1})u = (P_1P_3 \dots P_{2n-1})Au$ and $Bv = P_2P_4 \dots P_{2n}v$, $B(P_2P_4 \dots P_{2n})v = (P_2P_4 \dots P_{2n})Bv$. Now we assert that $Au = Bv$. Putting $x = u, y = v$ and $\alpha = 1$ in inequality (1), we get

$$T \left(\begin{array}{l} F_{Au, Bv}(kt), F_{P_1P_3 \dots P_{2n-1}u, P_2P_4 \dots P_{2n}v}(t), \\ F_{Au, P_1P_3 \dots P_{2n-1}u}(t), F_{Bv, P_2P_4 \dots P_{2n}v}(t), \\ \Delta (F_{Bv, P_1P_3 \dots P_{2n-1}u}(t), F_{Au, P_2P_4 \dots P_{2n}v}(t)) \end{array} \right) \geq 0,$$

$$T \left(\begin{array}{l} F_{Au, Bv}(kt), F_{Au, Bv}(t), F_{Au, Au}(t), \\ F_{Bv, Bv}(t), \Delta (F_{Bv, Au}(t), F_{Au, Bv}(t)) \end{array} \right) \geq 0.$$

Since T is increasing in t_1 and decreasing in t_2, \dots, t_5 , we get

$$T (F_{Au, Bv}(t), F_{Au, Bv}(t), F_{Au, Bv}(t), F_{Au, Bv}(t), F_{Au, Bv}(t)) \geq 0.$$

Thus by Remark 3.1, we have $F_{Au, Bv}(t) = 1$. Hence $Au = Bv$. Moreover, if there is another point z such that $Az = (P_1P_3 \dots P_{2n-1})z$. Then using inequality (1), it follows that $Az = (P_1P_3 \dots P_{2n-1})z = Bv = (P_2P_4 \dots P_{2n})v$, or $Au = Az$. Hence $w = Au = (P_1P_3 \dots P_{2n-1})u$ is the

unique point of coincidence of A and $P_1P_3 \dots P_{2n-1}$. By Lemma 2.1, it follows that w is the unique common fixed point of A and $P_1P_3 \dots P_{2n-1}$. By symmetry, $q = Bv = (P_2P_4 \dots P_{2n})v$ is the unique common fixed point of B and $P_2P_4 \dots P_{2n}$. Since $w = q$, we obtain that w is the unique common fixed point of B and $P_2P_4 \dots P_{2n}$. Now we show that w is the fixed point of all the component mappings. By putting $x = (P_3 \dots P_{2n-1})w$, $y = w$, $\alpha = 1$, $P'_1 = P_1P_3 \dots P_{2n-1}$ and $P'_2 = P_2P_4 \dots P_{2n}$ in inequality (1), we have

$$T \begin{pmatrix} F_{AP_3 \dots P_{2n-1}w, Bw}(kt), F_{P'_1P_3 \dots P_{2n-1}w, P'_2w}(t), \\ F_{AP_3 \dots P_{2n-1}w, P'_1P_3 \dots P_{2n-1}w}(t), F_{Bw, P'_2w}(t), \\ \Delta \left(F_{Bw, P'_1P_3 \dots P_{2n-1}w}(t), F_{AP_3 \dots P_{2n-1}w, P'_2w}(t) \right) \end{pmatrix} \geq 0,$$

$$T \begin{pmatrix} F_{P_3 \dots P_{2n-1}w, w}(kt), F_{P_3 \dots P_{2n-1}w, w}(t), \\ F_{P_3 \dots P_{2n-1}w, P_3 \dots P_{2n-1}w}(t), F_{w, w}(t), \\ \Delta \left(F_{w, P_3 \dots P_{2n-1}w}(t), F_{P_3 \dots P_{2n-1}w, w}(t) \right) \end{pmatrix} \geq 0.$$

Since T is increasing in t_1 and decreasing in t_2, \dots, t_5 , we get

$$T \begin{pmatrix} F_{P_3 \dots P_{2n-1}w, w}(t), F_{P_3 \dots P_{2n-1}w, w}(t), F_{P_3 \dots P_{2n-1}w, w}(t), \\ F_{P_3 \dots P_{2n-1}w, w}(t), F_{P_3 \dots P_{2n-1}w, w}(t) \end{pmatrix} \geq 0.$$

Thus by Remark 3.1, we have $F_{P_3 \dots P_{2n-1}w, w}(t) = 1$ that is $P_3 \dots P_{2n-1}w = w$. Hence, $P_1w = w$. Continuing this procedure, we have

$$Aw = P_1w = P_3w = \dots = P_{2n-1}w = w.$$

So,

$$Bw = P_2w = P_4w = \dots = P_{2n}w = w.$$

That is, w is the unique common fixed point of $P_1, P_2, \dots, P_{2n}, A$ and B . \square

The following result is a slight generalization of Theorem 4.1.

Corollary 4.1. Let $\{L_\zeta\}_{\zeta \in J}$ and $\{P_i\}_{i=1}^{2n}$ be two families of self mappings of a Menger space (X, \mathcal{F}, Δ) with $\Delta(a, a) = a$ for all $a \in [0, 1]$ satisfying the following conditions:

(1) there exists a fixed $\eta \in J, k \in (0, 1)$ and $T \in \mathcal{T}$ such that

$$T \begin{pmatrix} F_{L_\zeta x, L_\eta y}(kt), F_{P_1P_3 \dots P_{2n-1}x, P_2P_4 \dots P_{2n}y}(t), \\ F_{L_\zeta x, P_1P_3 \dots P_{2n-1}x}(t), F_{L_\eta y, P_2P_4 \dots P_{2n}y}(t), \\ \Delta \left(F_{L_\eta y, P_1P_3 \dots P_{2n-1}x}(\alpha t), F_{L_\zeta x, P_2P_4 \dots P_{2n}y}(2t - \alpha t) \right) \end{pmatrix} \geq 0,$$

for all $x, y \in X, \alpha \in (0, 2)$ and $t > 0$.

(2) Suppose that

$$\left\{ \begin{array}{l} P_1(P_3 \dots P_{2n-1}) = (P_3 \dots P_{2n-1})P_1, \\ P_1P_3(P_5 \dots P_{2n-1}) = (P_5 \dots P_{2n-1})P_1P_3, \\ \vdots \\ P_1 \dots P_{2n-3}(P_{2n-1}) = (P_{2n-1})P_1 \dots P_{2n-3}, \\ L_\zeta(P_3 \dots P_{2n-1}) = (P_3 \dots P_{2n-1})L_\zeta, \\ L_\zeta(P_5 \dots P_{2n-1}) = (P_5 \dots P_{2n-1})L_\zeta, \\ \vdots \\ L_\zeta P_{2n-1} = P_{2n-1}L_\zeta, \\ P_2(P_4 \dots P_{2n}) = (P_4 \dots P_{2n})P_2, \\ P_2P_4(P_6 \dots P_{2n}) = (P_6 \dots P_{2n})P_2P_4, \\ \vdots \\ P_2 \dots P_{2n-2}(P_{2n}) = (P_{2n})P_2 \dots P_{2n-2}, \\ L_\eta(P_4 \dots P_{2n}) = (P_4 \dots P_{2n})L_\eta, \\ L_\eta(P_6 \dots P_{2n}) = (P_6 \dots P_{2n})L_\eta, \\ \vdots \\ L_\eta P_{2n} = P_{2n}L_\eta \end{array} \right.$$

Then, if the pairs $(L_\zeta, P_1P_3 \dots P_{2n-1})$ and $(L_\eta, P_2P_4 \dots P_{2n})$ are each owc, it follows that all $\{P_i\}$ and $\{L_\zeta\}$ have a unique common fixed point in X .

Corollary 4.2. Let $P_1, P_2, \dots, P_{2n}, A$ and B be self mappings of a Menger space (X, \mathcal{F}, Δ) with $\Delta(a, a) = a$ for all $a \in [0, 1]$ satisfying the following conditions:

(1) there exists $k \in (0, 1)$ and $T \in \mathcal{T}$ such that

$$F_{Ax,By}(kt) \geq \left(\min \left\{ \begin{array}{l} F_{P_1P_3 \dots P_{2n-1}x, P_2P_4 \dots P_{2n}y}(t), F_{Ax, P_1P_3 \dots P_{2n-1}x}(t), \\ F_{By, P_2P_4 \dots P_{2n}y}(t), \\ \Delta(F_{By, P_1P_3 \dots P_{2n-1}x}(\alpha t), F_{Ax, P_2P_4 \dots P_{2n}y}(2t - \alpha t)) \end{array} \right\} \right)^h,$$

for all $x, y \in X, \alpha \in (0, 2), 0 < h < 1$ and $t > 0$.

(2) Suppose that

$$\left\{ \begin{array}{l} P_1(P_3 \dots P_{2n-1}) = (P_3 \dots P_{2n-1})P_1, \\ P_1P_3(P_5 \dots P_{2n-1}) = (P_5 \dots P_{2n-1})P_1P_3, \\ \vdots \\ P_1 \dots P_{2n-3}(P_{2n-1}) = (P_{2n-1})P_1 \dots P_{2n-3}, \\ A(P_3 \dots P_{2n-1}) = (P_3 \dots P_{2n-1})A, \\ A(P_5 \dots P_{2n-1}) = (P_5 \dots P_{2n-1})A, \\ \vdots \\ AP_{2n-1} = P_{2n-1}A, \\ P_2(P_4 \dots P_{2n}) = (P_4 \dots P_{2n})P_2, \\ P_2P_4(P_6 \dots P_{2n}) = (P_6 \dots P_{2n})P_2P_4, \\ \vdots \\ P_2 \dots P_{2n-2}(P_{2n}) = (P_{2n})P_2 \dots P_{2n-2}, \\ B(P_4 \dots P_{2n}) = (P_4 \dots P_{2n})B, \\ B(P_6 \dots P_{2n}) = (P_6 \dots P_{2n})B, \\ \vdots \\ BP_{2n} = P_{2n}B \end{array} \right.$$

Then, if the pairs $(A, P_1P_3 \dots P_{2n-1})$ and $(B, P_2P_4 \dots P_{2n})$ are each owc, it follows that $P_1, P_2, \dots, P_{2n}, A$ and B have a unique common fixed point in X .

Proof. The Corollary follows easily from Theorem 4.1, if we define $T(t_1, t_2, t_3, t_4, t_5) = t_1 - (\min\{t_2, t_3, t_4, t_5\})^h$ in Theorem 4.1, for some $0 < h < 1$. □

Corollary 4.3. Let $P_1, P_2, \dots, P_{2n}, A$ and B be self mappings of a Menger space (X, \mathcal{F}, Δ) with $\Delta(a, a) = a$ for all $a \in [0, 1]$ satisfying the following conditions:

(1) there exists $k \in (0, 1)$ such that

$$F_{Ax, By}(kt) \geq (F_{P_1P_3 \dots P_{2n-1}x, P_2P_4 \dots P_{2n}y}(t))^h,$$

for all $x, y \in X, 0 < h < 1$ and $t > 0$.

(2) Suppose that

$$\left(\begin{array}{l} P_1(P_3 \dots P_{2n-1}) = (P_3 \dots P_{2n-1})P_1, \\ P_1P_3(P_5 \dots P_{2n-1}) = (P_5 \dots P_{2n-1})P_1P_3, \\ \vdots \\ P_1 \dots P_{2n-3}(P_{2n-1}) = (P_{2n-1})P_1 \dots P_{2n-3}, \\ A(P_3 \dots P_{2n-1}) = (P_3 \dots P_{2n-1})A, \\ A(P_5 \dots P_{2n-1}) = (P_5 \dots P_{2n-1})A, \\ \vdots \\ AP_{2n-1} = P_{2n-1}A, \\ P_2(P_4 \dots P_{2n}) = (P_4 \dots P_{2n})P_2, \\ P_2P_4(P_6 \dots P_{2n}) = (P_6 \dots P_{2n})P_2P_4, \\ \vdots \\ P_2 \dots P_{2n-2}(P_{2n}) = (P_{2n})P_2 \dots P_{2n-2}, \\ B(P_4 \dots P_{2n}) = (P_4 \dots P_{2n})B, \\ B(P_6 \dots P_{2n}) = (P_6 \dots P_{2n})B, \\ \vdots \\ BP_{2n} = P_{2n}B \end{array} \right)$$

Then, if the pairs $(A, P_1P_3 \dots P_{2n-1})$ and $(B, P_2P_4 \dots P_{2n})$ are each owc, it follows that $P_1, P_2, \dots, P_{2n}, A$ and B have a unique common fixed point in X .

Proof. The Corollary follows easily if we define $T(t_1, t_2, t_3, t_4, t_5) = t_1 - (t_2)^h$ in Theorem 4.1, for some $0 < h < 1$. \square

Corollary 4.4. Let A, B, P and Q be self maps of a Menger space (X, \mathcal{F}, Δ) with $\Delta(a, a) = a$ for all $a \in [0, 1]$ satisfying the following condition:

(1) there exists $k \in (0, 1)$ and $T \in \mathcal{T}$ such that

$$T \left(\begin{array}{l} F_{Ax,By}(kt), F_{Px,Qy}(t), F_{Ax,Px}(t), F_{By,Qy}(t), \\ \Delta(F_{By,Px}(\alpha t), F_{Ax,Qy}(2t - \alpha t)) \end{array} \right) \geq 0,$$

for all $x, y \in X, \alpha \in (0, 2)$ and $t > 0$.

Then, if the pairs (A, P) and (B, Q) are each owc, it follows that A, B, P and Q have a unique common fixed point in X .

Proof. If we set $P_1P_3 \dots P_{2n-1} = P$ and $P_2P_4 \dots P_{2n} = Q$ in Theorem 4.1, then the result follows. \square

Corollary 4.5. Let A, B, P and Q be self mappings of a Menger space (X, \mathcal{F}, Δ) with $\Delta(a, a) = a$ for all $a \in [0, 1]$ satisfying the following condition:

(1) there exists $k \in (0, 1)$ and $T \in \mathcal{T}$ such that

$$F_{Ax,By}(kt) \geq \left(\min \left\{ \begin{array}{l} F_{Px,Qy}(t), F_{Ax,Px}(t), F_{By,Qy}(t), \\ \Delta(F_{By,Px}(\alpha t), F_{Ax,Qy}(2t - \alpha t)) \end{array} \right\} \right)^h,$$

for all $x, y \in X, \alpha \in (0, 2), 0 < h < 1$ and $t > 0$.

Then, if the pairs (A, P) and (B, Q) are each owc, it follows that A, B, P and Q have a unique common fixed point in X .

Proof. The Corollary follows easily from Corollary 4.4, if we define $T(t_1, t_2, t_3, t_4, t_5) = t_1 - (\min\{t_2, t_3, t_4, t_5\})^h$ in Corollary 4.4, for some $0 < h < 1$. \square

Now, we give an example which illustrates Corollary 4.4.

Example 4.1. Let $X = [0, 2]$ with the metric d defined by $d(x, y) = |x - y|$ and for each $t \in [0, 1]$, define

$$F_{x,y}(t) = \begin{cases} \frac{t}{t+|x-y|}, & \text{if } t > 0; \\ 0, & \text{if } t = 0, \end{cases}$$

for all $x, y \in X$. Clearly (X, \mathcal{F}, Δ) be a Menger space, where $\Delta(a, b) = \min\{a, b\}$. Define the self mappings A, B, P and Q defined by

$$A(x) = \begin{cases} x, & \text{if } 0 \leq x \leq 1; \\ 2, & \text{if } 1 < x \leq 2. \end{cases} \quad P(x) = \begin{cases} 1, & \text{if } 0 \leq x \leq 1; \\ 0, & \text{if } 1 < x \leq 2. \end{cases}$$

$$B(x) = \begin{cases} 1, & \text{if } 0 \leq x \leq 1; \\ 2, & \text{if } 1 < x \leq 2. \end{cases} \quad Q(x) = \begin{cases} 1, & \text{if } 0 \leq x \leq 1; \\ \frac{x}{2}, & \text{if } 1 < x \leq 2. \end{cases}$$

If we consider $T(t_1, t_2, t_3, t_4, t_5) = t_1 - (\min\{t_2, t_3, t_4, t_5\})^h$, for some $h, k \in (0, 1)$, then the inequality

$$F_{Ax,By}(kt) \geq \left(\min \left\{ \begin{array}{l} F_{Px,Qy}(t), F_{Ax,Px}(t), F_{By,Qy}(t), \\ \Delta(F_{By,Px}(\alpha t), F_{Ax,Qy}(2t - \alpha t)) \end{array} \right\} \right)^h,$$

is satisfied for all $x, y \in X$, for every $t > 0$ and for every $\alpha \in (0, 2)$. Clearly all the conditions of Corollary 4.4 are satisfied with respect to the distribution function $F_{x,y}$.

That is,

$$A(1) = 1 = P(1) \text{ and } AP(1) = 1 = PA(1),$$

and

$$B(1) = 1 = Q(1) \text{ and } BQ(1) = 1 = QB(1).$$

So, A and P as well as B and Q are owc mappings. Also 1 is the unique common fixed point of A, B, P and Q . On the other hand, it is clear to see that the mappings A, B, P and Q are discontinuous at 1.

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