

RESOLUTION OF QUOTIENT SINGULARITIES VIA G -CONSTELLATIONS

SEUNG-JO JUNG

ABSTRACT. For a finite subgroup G of $\mathrm{GL}_n(\mathbb{C})$, the moduli space \mathcal{M}_θ of θ -stable G -constellations is rarely smooth. This note shows that for a group G of type $\frac{1}{r}(1, a, b)$ with $r = abc + a + b$, there is a generic stability parameter $\theta \in \Theta$ such that the birational component Y_θ of θ -stable G -constellations provides a resolution of the quotient singularity $X := \mathbb{C}^3/G$.

1. Introduction

For a finite subgroup G of $\mathrm{GL}_n(\mathbb{C})$, a G -equivariant sheaf \mathcal{F} on \mathbb{C}^n with $H^0(\mathcal{F})$ isomorphic to the regular representation $\mathbb{C}[G]$ of G is called a G -constellation. The GIT parameter space for G -constellations is defined to be

$$\Theta = \{ \theta \in \mathrm{Hom}_{\mathbb{Z}}(R(G), \mathbb{Q}) \mid \theta(\mathbb{C}[G]) = 0 \},$$

where $R(G)$ is the representation space of G . For $\theta \in \Theta$, we say that:

- (i) a G -constellation \mathcal{F} is θ -(semi)stable if $\theta(\mathcal{G}) \geq 0$ ($\theta(\mathcal{G}) > 0$) for every proper subsheaf \mathcal{G} of \mathcal{F} .
- (ii) θ is generic if every θ -semistable G -constellation is θ -stable.

The moduli spaces of θ -stable G -constellations provide good birational models of the quotient variety \mathbb{C}^n/G . For example, for $G \subset \mathrm{SL}_3(\mathbb{C})$ and generic θ , the moduli space of θ -stable G -constellations is a crepant resolution of \mathbb{C}^n/G (see [1, 2, 7, 9]). However, it is very rare for the moduli space of stable G -constellations to be smooth.

This note proves that for some abelian groups in $\mathrm{GL}_3(\mathbb{C})$, there is a generic stability parameter $\theta \in \Theta$ such that Y_θ is a resolution of the quotient singularity $X := \mathbb{C}^3/G$.

Theorem 1.1 (Main Theorem). *Let $G \subset \mathrm{GL}_3(\mathbb{C})$ be the finite group of type $\frac{1}{r}(1, a, b)$ with $r = abc + a + b$, where a, b, c are positive integers and b is coprime*

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to a . Then the birational component Y_θ of θ -stable G -constellations is smooth for a suitable parameter θ .

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2. Moduli spaces of G -constellations and G -bricks

Through this section, we consider the group G of type $\frac{1}{r}(1, a, b)$, that is,

$$G = \langle \text{diag}(\epsilon, \epsilon^a, \epsilon^b) \mid \epsilon^r = 1 \rangle \subset \text{GL}_3(\mathbb{C}).$$

As G is abelian, the set of irreducible representations of G can be identified with the character group $G^\vee := \text{Hom}(G, \mathbb{C}^\times)$ of G . With this identification, we say that an irreducible representation ρ is of weight i if ρ maps $\text{diag}(\epsilon, \epsilon^a, \epsilon^b)$ to ϵ^i , where $0 \leq i < r$. In this case, we let $\text{wt}(\rho)$ denote the weight of ρ and ρ_i the representation of weight i .

Set $\bar{L} = \mathbb{Z}^3$ and define the lattice

$$L = \bar{L} + \mathbb{Z} \cdot \frac{1}{r}(1, a, b).$$

We may identify the dual lattices $\bar{M} = \text{Hom}_{\mathbb{Z}}(\bar{L}, \mathbb{Z})$ and $M = \text{Hom}_{\mathbb{Z}}(L, \mathbb{Z})$ with Laurent monomials and G -invariant Laurent monomials, respectively. There is a surjective homomorphism

$$\text{wt}: \bar{M} \longrightarrow G^\vee$$

induced by the embedding of G into the torus $(\mathbb{C}^\times)^3 \subset \text{GL}_3(\mathbb{C})$.

Let $\bar{M}_{\geq 0}$ denote genuine monomials in \bar{M} , i.e.,

$$\bar{M}_{\geq 0} = \{x_1^{m_1} x_2^{m_2} x_3^{m_3} \in \bar{M} \mid m_i \geq 0 \text{ for all } i\}.$$

For a subset A of Laurent monomials, let $\langle A \rangle$ denote the $\mathbb{C}[x_1, x_2, x_3]$ -submodule of $\mathbb{C}[x_1^\pm, x_2^\pm, x_3^\pm]$ generated by A .

Let σ_+ be the cone generated by $\{e_1, e_2, e_3\}$, where $\{e_1, e_2, e_3\}$ is the standard basis of $\bar{L} = \mathbb{Z}^3$. By toric geometry, the quotient variety $X = \mathbb{C}^3/G$ is isomorphic to $U_{\sigma_+} = \text{Spec } \mathbb{C}[\sigma_+^\vee \cap M]$.

2.1. G -constellations

Definition 2.1. A G -constellation on \mathbb{C}^3 is a G -equivariant coherent sheaf \mathcal{F} on \mathbb{C}^3 with $H^0(\mathcal{F})$ isomorphic to $\mathbb{C}[G]$ as a G -representation.

With the following GIT stability parameter space

$$\Theta = \{\theta \in \text{Hom}_{\mathbb{Z}}(R(G), \mathbb{Q}) \mid \theta(\mathbb{C}[G]) = 0\},$$

we define the stability of G -constellations as follows.

Definition 2.2. For $\theta \in \Theta$ and a G -constellation \mathcal{F} , we say that:

- (i) \mathcal{F} is θ -semistable if $\theta(\mathcal{G}) \geq 0$ for every nonzero proper subsheaf \mathcal{G} of \mathcal{F} .

- (ii) \mathcal{F} is θ -stable if $\theta(\mathcal{G}) > 0$ for every nonzero proper subsheaf \mathcal{G} of \mathcal{F} .
- (iii) $\theta \in \Theta$ is *generic* if every θ -semistable G -constellation is θ -stable.

Let θ be generic. By King’s result in [6], there is a quasiprojective scheme \mathcal{M}_θ which is a fine moduli space of θ -stable G -constellations. Moreover by [3, Theorem 1.1], the moduli space \mathcal{M}_θ has a distinguished component Y_θ birational to \mathbb{C}^3/G and that there is a projective morphism $Y_\theta \rightarrow \mathbb{C}^3/G$ obtained by variation of GIT quotient.

Definition 2.3. The unique irreducible component Y_θ is called the *birational component* of the moduli space \mathcal{M}_θ .

2.2. G -bricks and the birational component Y_θ

To describe the affine local charts of the birational component Y_θ , we introduce the notion of G -bricks (see [4]).

Definition 2.4. A subset Γ of Laurent monomials is called a G -prebrick if:

- (i) the monomial $\mathbf{1}$ is in Γ ;
- (ii) there exists a unique Laurent monomial $\mathbf{m}_\rho \in \Gamma$ of weight ρ for each weight $\rho \in G^\vee$.
- (iii) if $\mathbf{p}' \cdot \mathbf{p} \cdot \mathbf{m}_\rho \in \Gamma$ for $\mathbf{m}_\rho \in \Gamma$ and $\mathbf{p}, \mathbf{p}' \in \overline{M}_{\geq 0}$, then $\mathbf{p} \cdot \mathbf{m}_\rho \in \Gamma$;
- (iv) the set Γ is *connected* in the sense that for any element \mathbf{m}_ρ , there is a (fractional) path in Γ from \mathbf{m}_ρ to $\mathbf{1}$ whose steps consist of multiplying or dividing by one of x_i .

For $\mathbf{m} \in \overline{M}$, we define $\text{wt}_\Gamma(\mathbf{m})$ to be the unique element \mathbf{m}_ρ in Γ of the same weight as \mathbf{m} .

For a G -prebrick $\Gamma = \{\mathbf{m}_\rho\}$, let $S(\Gamma)$ denote the subsemigroup of M generated by

$$\frac{\mathbf{n} \cdot \mathbf{m}_\rho}{\text{wt}_\Gamma(\mathbf{n} \cdot \mathbf{m}_\rho)}$$

for all $\mathbf{n} \in \overline{M}_{\geq 0}$, $\mathbf{m}_\rho \in \Gamma$. It turns out that the semigroup $S(\Gamma)$ is finitely generated. Thus $S(\Gamma)$ defines a (not-necessarily-normal) affine toric variety $U(\Gamma) := \text{Spec } \mathbb{C}[S(\Gamma)]$.

Definition 2.5. A G -prebrick Γ is called a G -brick if $U(\Gamma)$ contains a torus fixed point.

For a G -brick Γ , we define

$$C(\Gamma) := \langle \Gamma \rangle / \langle B(\Gamma) \rangle,$$

where $B(\Gamma) := \{x_i \cdot \mathbf{m}_\rho \mid \mathbf{m}_\rho \in \Gamma\} \setminus \Gamma$. The module $C(\Gamma)$ becomes a torus invariant G -constellation.

Remark 2.6. The G -brick Γ is a \mathbb{C} -basis of G -constellations over $U(\Gamma)$. Moreover, a submodule \mathcal{G} of $C(\Gamma)$ is determined by a subset $A \subset \Gamma$, which forms a \mathbb{C} -basis of \mathcal{G} . This makes it easy to determine whether $C(\Gamma)$ is θ -stable or not.

Definition 2.7. A G -brick Γ is said to be θ -stable if $C(\Gamma)$ is θ -stable.

Definition 2.8. Let G be a finite diagonal group $G \subset \text{GL}_3(\mathbb{C})$. Assume that we have a proper birational morphism $Y \rightarrow X := \mathbb{C}^3/G$ with a normal toric variety Y . Let Σ_{\max} be the set of the 3-dimensional cones in the fan of Y . A G -brickset for Y is a set \mathfrak{S} of G -bricks satisfying:

- (i) there is a bijective map $\Sigma_{\max} \rightarrow \mathfrak{S}$ sending σ to Γ_σ ;
- (ii) $S(\Gamma_\sigma) = \sigma^\vee \cap M$.

Lemma 2.9 ([5, Proposition 2.16]). *Let Y be a normal toric variety with a proper birational morphism $Y \rightarrow X := \mathbb{C}^3/G$. Assume that there exist:*

- (i) a G -brickset \mathfrak{S} for $Y \rightarrow X$, and
- (ii) a generic stability parameter θ such that $\Gamma \in \mathfrak{S}$ is θ -stable.

Then Y is isomorphic to Y_θ .

3. Main result

In this section, we assume that G is the finite group of type $\frac{1}{r}(1, a, b)$ with $r = abc + a + b$, where a, b, c are positive integers and b is coprime to a . We may assume that $a < b$. We apply the methods in [5] for this case to prove the main theorem. For the convenience, set $a_1 = 1, a_2 = a, a_3 = b$.

3.1. Star subdivisions at v and the resolution

Recall the lattice

$$L = \mathbb{Z}^3 + \mathbb{Z} \cdot \frac{1}{r}(1, a, b),$$

and the cone $\sigma_+ = \text{Cone}(e_1, e_2, e_3)$. Let X_v be the corresponding to the star subdivision of σ_+ at the lattice point $v = \frac{1}{r}(1, a, b)$, i.e., the fan of X_v consists of the following cones

$$\sigma_1 = \text{Cone}(v, e_2, e_3), \quad \sigma_2 = \text{Cone}(e_1, v, e_3), \quad \sigma_3 = \text{Cone}(e_1, e_2, v).$$

Let U_k denote the affine toric variety corresponding to σ_k .

Let L_1, L_2 and L_3 be the sublattices of L generated by $\{v, e_2, e_3\}, \{e_1, v, e_3\}$ and by $\{e_1, e_2, v\}$, respectively. Let M_k denote the dual lattice of L_k . Note that M_2 has the dual basis $\{\zeta_1, \zeta_2, \zeta_3\}$ and M_3 has the dual basis $\{\eta_1, \eta_2, \eta_3\}$, where

$$\begin{aligned} \xi_1 &= x_1 x_2^{-\frac{1}{a}}, & \xi_2 &= x_2^{\frac{r}{a}}, & \xi_3 &= x_3 x_2^{-\frac{b}{a}}, \\ \eta_1 &= x_1 x_3^{-\frac{1}{b}}, & \eta_2 &= x_2 x_3^{-\frac{a}{b}}, & \eta_3 &= x_3^{-\frac{r}{b}}. \end{aligned}$$

Note that the lattice inclusion $L_k \hookrightarrow L$ induces a toric morphism

$$\bar{\pi}_k : \text{Spec } \mathbb{C}[\sigma_k^\vee \cap M_k] \rightarrow U_k := \text{Spec } \mathbb{C}[\sigma_2^\vee \cap M]$$

with $\text{Spec } \mathbb{C}[\sigma_k^\vee \cap M_k] \cong \mathbb{C}^3$ and $U_k \cong \mathbb{C}^3/G_k$, where $G_k := L/L_k$. Thus we have:

- (i) U_1 is smooth.

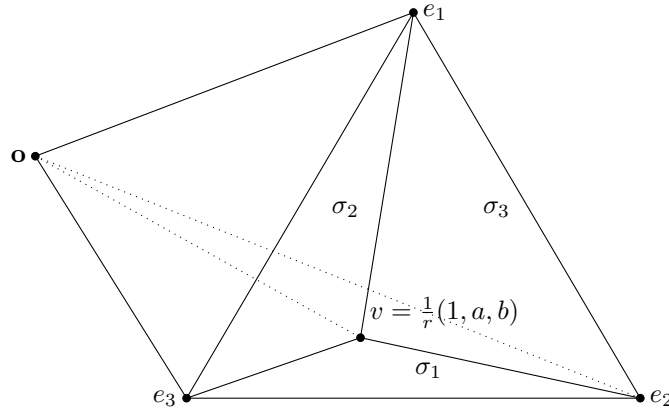


FIGURE 3.1. Star subdivision at v

- (ii) U_2 is \mathbb{C}^3/G_2 , where G_2 is of type $\frac{1}{a}(1, -b, b)$.
- (iii) U_3 is \mathbb{C}^3/G_3 , where G_3 is of type $\frac{1}{b}(1, a, -a)$.

Note that U_2 and U_3 are terminal 3-fold quotient singularities. Since X_v has only terminal singularities, X_v is the relative minimal model over $X = \mathbb{C}^3/G$.

Since each terminal 3-fold quotient singularity has an economic resolution (see [8]), we have the following three resolutions of singularities:

- (i) $\bar{\varphi}_1: Y_1 \rightarrow U_1 = \mathbb{C}^3$;
- (ii) $\bar{\varphi}_2: Y_2 \rightarrow U_2 = \mathbb{C}^3/G_2$;
- (iii) $\bar{\varphi}_3: Y_3 \rightarrow U_3 = \mathbb{C}^3/G_3$,

which induce a projective birational morphism $\varphi: Y \rightarrow X$ factoring through X_v fitting into the following commutative diagram:

$$\begin{array}{ccc}
 Y & \xrightarrow{\bar{\varphi}} & X_v \\
 & \searrow \varphi & \downarrow \\
 & & X.
 \end{array}$$

In what follows, we find a moduli description of the resolution Y in terms of G -constellations.

3.2. Round down functions for star subdivisions

Definition 3.1 (Round down functions). The *round down functions*

$$\phi_2: \bar{M} \rightarrow M_2, \quad \phi_3: \bar{M} \rightarrow M_3$$

for the star subdivision at $\frac{1}{r}(1, a, b)$ are defined by

$$\phi_2(x_1^{m_1} x_2^{m_2} x_3^{m_3}) = \xi_1^{m_1} \xi_2^{\lfloor \frac{1}{r}(m_1 + am_2 + bm_3) \rfloor} \xi_3^{m_3},$$

$$\phi_3(x_1^{m_1}x_2^{m_2}x_3^{m_3}) = \eta_1^{m_1}\eta_2^{m_2}\eta_3^{\lfloor \frac{1}{r}(m_1+am_2+bm_3) \rfloor},$$

where $\lfloor \cdot \rfloor$ is the floor function. For a G_k -brick Γ' , we define

$$\phi_k^*(\Gamma') := \{\mathbf{m} \in \overline{M} \mid \phi_k(\mathbf{m}) \in \Gamma'\}.$$

Proposition 3.2 ([4, Proposition 4.5]). *For a G_k -brick Γ' , the set $\Gamma := \phi_k^*(\Gamma')$ is a G -brick with $S(\Gamma) = S(\Gamma')$. For $\mathbf{m} \in \overline{M}$, we have*

$$\text{wt}_{\Gamma'}(\phi_k(\mathbf{m})) = \phi_k(\text{wt}_{\Gamma}(\mathbf{m})).$$

The key theorem in [5] is the following.

Theorem 3.3 ([5, Theorem 3.12]). *Assume that each $Y_k \rightarrow U_k$ has a G_k -brickset \mathfrak{S}_k . Define*

$$\mathfrak{S} := \bigcup_k \{\phi_k^*(\Gamma') \mid \Gamma' \in \mathfrak{S}_k\}.$$

Then \mathfrak{S} is a G -brickset for the morphism $Y \rightarrow X$.

For a monomial \mathbf{m} of weight $\rho \in G^\vee$, we define $\phi_k(\rho)$ is the weight of $\phi_k(\mathbf{m})$. This induces a well-defined surjective map

$$(3.4) \quad \phi_k: G^\vee \rightarrow G_k^\vee, \quad \text{wt}(\mathbf{m}) \mapsto \text{wt}(\phi_k(\mathbf{m})).$$

From this, we define the linear map

$$(\phi_k)_*: \Theta \rightarrow \Theta^{(k)}$$

defined by

$$(3.5) \quad [(\phi_k)_*(\theta)](\chi) = \sum_{\phi_k(\rho)=\chi} \theta(\rho) \text{ for } \chi \in G_k^\vee.$$

Lemma 3.6 ([5, Lemma 3.16]). *Suppose that we have $\theta^{(2)} \in \Theta^{(2)}$ and $\theta^{(3)} \in \Theta^{(3)}$. Then there is $\theta_P \in \Theta$ satisfying*

$$(3.7) \quad (\phi_k)_*(\theta_P) \equiv \theta^{(k)} \text{ for all } k.$$

3.3. Proof of the main theorem

Through this section, we prove the following theorem. Recall we set $a_1 = 1$, $a_2 = a$, $a_3 = b$.

Theorem 3.8 (Main Theorem). *Let $G \subset \text{GL}_3(\mathbb{C})$ be the finite group of type $\frac{1}{r}(1, a, b)$ with $r = abc + a + b$, where a, b, c are positive integers and b is coprime to a . Then the birational component Y_θ of θ -stable G -constellations is smooth for a suitable parameter θ .*

For the smooth model $Y \rightarrow X$ constructed in Section 3.1 above, recall we have

$$\overline{\varphi}_2: Y_2 \rightarrow U_2 = \mathbb{C}^3/G_2, \quad \overline{\varphi}_3: Y_3 \rightarrow U_3 = \mathbb{C}^3/G_3$$

which are the economic resolutions of U_2 and U_3 , respectively.

By [4, Theorem 4.19], the economic resolution of a terminal 3-fold quotient singularity \mathbb{C}^3/G' is isomorphic to the birational components of stable G' -constellations. This means for $k \in \{2, 3\}$, we have a G_k -brickset \mathfrak{S}_k for $Y_k \rightarrow U_k$ such that $\Gamma \in \mathfrak{S}_k$ is $\theta^{(k)}$ -stable.

Combining this with Theorem 3.3, we have a G -brickset

$$(3.9) \quad \mathfrak{S} := \bigcup_k \{ \phi_k^*(\Gamma') \mid \Gamma' \in \mathfrak{S}_k \}$$

for the morphism $Y \rightarrow X$. Thus by Lemma 2.9, it is enough to find generic $\theta \in \Theta$ such that every $\Gamma \in \mathfrak{S}$ is θ -stable.

Lemma 3.10. *For a G -brick Γ in \mathfrak{S} , let $A \subset \Gamma$ be a \mathbb{C} -basis of a submodule \mathcal{G} of $C(\Gamma)$. Assume that*

$$A \neq \phi_k^{-1}(\phi_k(A)) := \{ \mathbf{m} \in \overline{M} \mid \phi_k(\mathbf{m}) \in \phi_k(A) \}.$$

- (i) *If \mathbf{m}_ρ is in $\phi_k^{-1}(\phi_k(A)) \setminus A$, then $0 \leq \text{wt}(\rho) < r - a_k$.*
- (ii) *There is a monomial \mathbf{m}_ρ of weight ρ in $\phi_k^{-1}(\phi_k(A)) \setminus A$ with $0 \leq \text{wt}(\rho) < a_k$.*

Proof. For (i), assume that \mathbf{m}_ρ is in $\phi_k^{-1}(\phi_k(A)) \setminus A$. From the definition of ϕ_k , we have $\phi_k(x_k^l \cdot \mathbf{m}_\rho) = \phi_k(\mathbf{m}_\rho)$ for $l > 0$. This is equivalent to that $0 \leq \text{wt}(\rho) < r - a_k l$.

For (ii), assume that \mathbf{m} is in $\phi_k^{-1}(\phi_k(A)) \setminus A$. Choose $l := \lfloor \frac{\text{wt}(\mathbf{m})}{a_k} \rfloor$ and set \mathbf{m}_ρ to be the monomial with $\mathbf{m} = x_k^l \cdot \mathbf{m}_\rho$. Then we have $\phi_k(\mathbf{m}_\rho) = \phi_k(\mathbf{m})$ with $\text{wt}(\mathbf{m}_\rho) < a_k$. \square

Lemma 3.11. *Let $\psi \in \Theta$ be the GIT parameter defined by*

$$(3.12) \quad \psi(\rho) = \begin{cases} -1 & \text{if } 0 \leq \text{wt}(\rho) < b, \\ 1 & \text{if } r - b \leq \text{wt}(\rho) < r, \\ 0 & \text{otherwise.} \end{cases}$$

Then ψ satisfies the following:

- (i) *For every ρ with $0 \leq \text{wt}(\rho) < b$, we have $\psi(\rho) < 0$.*
- (ii) *For each k and for every $\chi \in G_k^\vee$, we have*

$$\sum_{\phi_k(\rho)=\chi} \psi(\rho) = 0.$$

Proof. From the definition of ψ , (i) follows. We prove (ii) for the case $k = 2$. First note that $\phi_2(\rho) = \chi$ if and only if $\text{wt}(\rho) \equiv \text{wt}(\chi) \pmod{a}$. Since $r = abc + a + b$, we have i and $i + (r - b)$ are equivalent modulo a . Thus for $0 \leq i < b$, we get $\phi_2(\rho_i) = \phi_2(\rho_{i+r-b})$ and $\psi(\rho_i) + \psi(\rho_{i+r-b}) = 0$. This proves (ii). \square

Remark 3.13. Here, (ii) means that for any monomial \mathbf{m} we have

$$\sum_{\phi_k(\rho)=\phi_k(\mathbf{m})} \psi(\rho) = 0.$$

Theorem 3.14. Fix $\theta_P \in \Theta$ satisfying (3.7). For a sufficiently large m , set

$$\theta := \theta_P + m\psi.$$

Then every G -brick $\Gamma \in \mathfrak{S}$ defined by (3.9) is θ -stable.

Proof. Let σ be the corresponding cone to the G -brick Γ . Then σ is contained in one of the cones $\sigma_1, \sigma_2, \sigma_3$.

Suppose that $\sigma \subset \sigma_1$. This means that $\sigma = \sigma_1$ and

$$\Gamma = \{1, x_1, x_1^2, \dots, x_1^{r-2}, x_1^{r-1}\}.$$

Any nonzero proper submodule of $C(\Gamma)$ has a \mathbb{C} -basis of the form

$$A = \{x_1^j, x_1^{j+1}, \dots, x_1^{r-2}, x_1^{r-1}\}$$

for $1 \leq j < r$. Since $\psi(A) > 0$, Γ is θ -stable for $m \gg 0$.

Let us assume that $\sigma \subset \sigma_k$. Then we have the corresponding G_k -brick Γ' to Γ , i.e., $\Gamma = \phi_k^*(\Gamma') = \{\mathbf{m} \in \overline{M} \mid \phi_k(\mathbf{m}) \in \Gamma'\}$. Let \mathcal{G} be a nonzero proper submodule of $C(\Gamma)$. We need to show that $\theta(\mathcal{G}) > 0$. Let $A \subsetneq \Gamma$ be a \mathbb{C} -basis of \mathcal{G} . We have the following two cases:

$$(1): A \subsetneq \phi_k^{-1}(\phi_k(A)) \quad \text{or} \quad (2): A = \phi_k^{-1}(\phi_k(A)).$$

In case (1), by Remark 3.13 and Lemma 3.10, we have

$$\sum_{\rho \in \phi_k^{-1}(\phi_k(A))} \psi(\rho) = 0, \quad \text{and} \quad \sum_{\rho \in \phi_k^{-1}(\phi_k(A)) \setminus A} \psi(\rho) < 0.$$

Therefore $\psi(\mathcal{G}) > 0$ and $\theta(\mathcal{G}) > 0$ for sufficiently large m .

In case (2), by (ii) of Lemma 3.11, we have $\psi(\mathcal{G}) = 0$. Note that $\phi_k(A)$ defines a nonzero proper submodule \mathcal{G}' of $C(\Gamma')$. Since $C(\Gamma')$ is $\theta^{(k)}$ -stable, we have $\theta^{(k)}(\mathcal{G}') > 0$. From (3.7), we have $\theta(\mathcal{G}) = \theta^{(k)}(\mathcal{G}') > 0$. \square

Corollary 3.15. With the notation above, the birational component Y_θ is isomorphic to Y defined in Section 3.1.

This completes the proof of Theorem 3.8.

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SEUNG-JO JUNG
DEPARTMENT OF MATHEMATICS EDUCATION, AND
INSTITUTE OF PURE AND APPLIED MATHEMATICS
JEONBUK NATIONAL UNIVERSITY
JEONJU 54896, KOREA
Email address: seungjo@jbnu.ac.kr