# $F$-BIHARMONIC CURVES IN THREE-DIMENSIONAL GENERALIZED SYMMETRIC SPACES 

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#### Abstract

In this work we give the necessary and sufficient conditions for $f$-biharmonic curves in three-dimensional generalized symmetric spaces.

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## 1. Introduction

Let $\varphi:\left(M^{m}, g\right) \longrightarrow\left(N^{n}, h\right)$ be a smooth map between two pseudo-Riemannian manifolds. We will call $e(\varphi)_{x}=\frac{1}{2} \sum_{i=1}^{m} h\left(d \varphi\left(E_{i}\right), d \varphi\left(E_{i}\right)\right)$ the energy density of $\varphi$ at $x$ for any $\left\{E_{i}\right\}_{i=1}^{m}$ orthonormal basis of the tangent space $T_{x} M$ can then be integrated over $M$, and with an eye toward the physical concept of kinetic energy $\frac{m v^{2}}{2}$ then the energy functional is defined by

$$
\begin{equation*}
E(\varphi)=\frac{1}{2} \int_{M}|d \varphi|^{2} d v_{g} \tag{1}
\end{equation*}
$$

A harmonic map $\varphi$ is also a critical point of the energy functional $E$. The map $\varphi$ being harmonic means that

$$
\frac{d}{d t} E\left(\varphi_{t}\right)_{t=0}=0
$$

holds for arbitrary smooth variation $\varphi_{t}$ of $\varphi$, and denote the tension field $\tau(\varphi)$ of $\varphi$ by

$$
\begin{equation*}
\tau(\varphi)=\operatorname{tr}_{g} \nabla d \varphi=\sum_{i=1}^{m} \epsilon_{i}\left(\nabla_{E_{i}}^{\varphi} E_{i}-d \varphi\left(\nabla_{E_{i}} E_{i}\right)\right) \tag{2}
\end{equation*}
$$

[^0]where $\epsilon_{i}=g\left(E_{i}, E_{i}\right)= \pm 1$.
The notion of harmonicity generalizes the usual one for mappings between Euclidean spaces, well known examples include geodesic curves. Next, the biharmonic maps $\varphi:\left(M^{m}, g\right) \longrightarrow\left(N^{n}, h\right)$ are defined as critical points of the bienergy functional:
\[

$$
\begin{equation*}
E_{2}(\varphi)=\frac{1}{2} \int_{M} h(\tau(\varphi), \tau(\varphi)) d v_{g} \tag{3}
\end{equation*}
$$

\]

The Euler-Lagrange equation attached to the bienergy is

$$
\begin{equation*}
\tau_{2}(\varphi)=0 \tag{4}
\end{equation*}
$$

where $\tau_{2}(\varphi)$ is the bitension field given by

$$
\begin{equation*}
\tau_{2}(\varphi)=-\left(\Delta^{\varphi} \tau(\varphi)+t r_{g} R^{N}(\tau(\varphi), d \varphi) d \varphi\right) \tag{5}
\end{equation*}
$$

where $\Delta=\operatorname{trace}\left(\nabla^{\varphi} \nabla^{\varphi}-\nabla_{\nabla}^{\varphi}\right)$ is the rough Laplacian on the sections of the pullback bundle $\varphi^{-1} T N, \nabla^{\varphi}$ is the pull-back connection, and $R^{N}$ is the curvature tensor on $N$.
Let $f: M \rightarrow \mathbb{R}$ be a smooth positive function on $M$. The $f$-energy functional of the map $\varphi$ is given by

$$
\begin{equation*}
E_{f}(\varphi)=\frac{1}{2} \int_{M} f h\left(d \varphi\left(E_{i}\right), d \varphi\left(E_{i}\right)\right) d \nu_{g} \tag{6}
\end{equation*}
$$

A map $\varphi$ is called $f$-harmonic if it is a critical point of the energy functional $E_{f}$. The Euler-Lagrange equation attached to the $f$-energy is

$$
\tau_{f}(\varphi)=0
$$

where $\tau_{f}(\varphi)$ is the $f$-tension field given by

$$
\tau_{f}(\varphi)=f \tau(\varphi)+d \varphi(\operatorname{gradf})
$$

On the other hand the $f$-bienergy functional of the $\operatorname{map} \varphi$ is defined by

$$
\begin{equation*}
E_{2, f}(\varphi)=\frac{1}{2} \int_{M} f h(\tau(\varphi), \tau(\varphi)) d v_{g} \tag{7}
\end{equation*}
$$

A map $\varphi$ is called $f$-biharmonic if it is a critical point of the energy functional $E_{2, f}$. The Euler-Lagrange equation attached to the $f$-bienergy is

$$
\begin{equation*}
\tau_{2, f}(\varphi)=0 \tag{8}
\end{equation*}
$$

where $\tau_{2, f}(\varphi)$ is the $f$-bitension field given by

$$
\begin{equation*}
\tau_{2, f}(\varphi)=f \tau_{2}(\varphi)+\triangle f \tau(\varphi)+2 \nabla_{g r a d f}^{\varphi} \tau(\varphi) \tag{9}
\end{equation*}
$$

Clearly, any $f$-harmonic map was always a $f$-biharmonic map, and a proper $f$-biharmonic map can not be $f$-harmonic. (see [27]).
Biharmonic and nonharmonic submanifolds have been studied by many authors in $[14,12,13,16,15,30]$. In [21], J. Inoguchi study biminimal submanifolds in contact 3 -manifolds and biminimality of Legendre curves and Hopf cylinders. In [29], Ye-Lin Ou , the author introduced the concept of $f$-biharmonic submanifold. In [20], S. Güvenç and C. Özgür studied $f$-biharmonic Legendre curves in Sasakian manifold.

In this paper, we study the $f$-biharmonicity curves in three-dimensional generalized symmetric spaces and we give the necessary and sufficient conditions for $f$-biharmonic curves in $\mathbb{M}_{3}$.

## 2. Preliminaries

The $\mathbb{M}_{3}$ generalized symmetric space is the three-dimensional real space $\mathbb{R}^{3}$ endowed with the pseudo-Riemannian metric $g_{\epsilon, \lambda}$ given by

$$
\begin{equation*}
g_{\epsilon, \lambda}=\epsilon\left(e^{2 t} d x^{2}+e^{-2 t} d y^{2}\right)+\lambda d t^{2} \tag{10}
\end{equation*}
$$

where $\epsilon= \pm 1$ and $\lambda \neq 0$ is a real constant. Depending on the values of $\epsilon$ and $\lambda$. We take the following orthonormal basis on $\mathbb{M}_{3}$

$$
\begin{equation*}
E_{1}=e^{-t} \frac{\partial}{\partial x}, E_{2}=e^{t} \frac{\partial}{\partial y}, E_{3}=\frac{1}{\sqrt{|\lambda|}} \frac{\partial}{\partial t} \tag{11}
\end{equation*}
$$

The non-vanishing components of the Levi-Civita connection are given by:

$$
\begin{equation*}
\nabla_{E_{1}} E_{1}=-\frac{\epsilon \epsilon_{1}}{\sqrt{|\lambda|}} E_{3}, \quad \nabla_{E_{1}} E_{3}=\frac{1}{\sqrt{|\lambda|}} E_{1}, \quad \nabla_{E_{2}} E_{2}=\frac{\epsilon \epsilon_{1}}{\sqrt{|\lambda|}} E_{3}, \quad \nabla_{E_{2}} E_{3}=-\frac{1}{\sqrt{|\lambda|}} E_{2}, \tag{12}
\end{equation*}
$$

where $\epsilon_{1}=\frac{\lambda}{|\lambda|}$.
The non-vanishing Lie brackets are given by:

$$
\begin{equation*}
\left[E_{2}, E_{3}\right]=\frac{-1}{\sqrt{|\lambda|}} E_{2}, \quad\left[E_{1}, E_{3}\right]=\frac{1}{\sqrt{|\lambda|}} E_{1} \tag{13}
\end{equation*}
$$

The Riemannian curvature operator is given by

$$
\begin{equation*}
\mathbf{R}(X, Y) Z=\nabla_{X} \nabla_{Y} Z-\nabla_{Y} \nabla_{X} Z-\nabla_{[X, Y]} Z \tag{14}
\end{equation*}
$$

The Riemannian curvature tensor is given by

$$
\begin{equation*}
\mathbf{R}(X, Y, Z, W)=-g(\mathbf{R}(X, Y) Z, W) \tag{15}
\end{equation*}
$$

Moreover we put

$$
\begin{equation*}
\mathbf{R}_{a b c}=\mathbf{R}\left(E_{a}, E_{b}\right) E_{c}, \quad \mathbf{R}_{a b c d}=\mathbf{R}\left(E_{a}, E_{b}, E_{c}, E_{d}\right) \tag{16}
\end{equation*}
$$

By using equation 12, 13 and 14 , we have

$$
\begin{cases}\mathbf{R}\left(E_{1}, E_{2}\right) E_{1}=-\frac{\epsilon}{\lambda} E_{2}, & \mathbf{R}\left(E_{1}, E_{2}\right) E_{2}=\frac{\epsilon}{\lambda} E_{1}  \tag{17}\\ \mathbf{R}\left(E_{1}, E_{3}\right) E_{1}=\frac{\epsilon}{\lambda} E_{3}, & \mathbf{R}\left(E_{1}, E_{3}\right) E_{3}=-\frac{1}{|\lambda|} E_{1} \\ \mathbf{R}\left(E_{2}, E_{3}\right) E_{2}=\frac{\epsilon}{\lambda} E_{3}, & \mathbf{R}\left(E_{2}, E_{3}\right) E_{3}=-\frac{1}{|\lambda|} E_{2}\end{cases}
$$

and

$$
\left\{\begin{array}{l}
\mathbf{R}_{1212}=\frac{1}{\lambda}, \quad \mathbf{R}_{1221}=-\frac{1}{\lambda}  \tag{18}\\
\mathbf{R}_{1313}=-\frac{\epsilon}{|\lambda|}, \quad \mathbf{R}_{1331}=\frac{\epsilon}{|\lambda|} \\
\mathbf{R}_{2323}=-\frac{\epsilon}{|\lambda|}, \quad \mathbf{R}_{2332}=\frac{\epsilon}{|\lambda|}
\end{array}\right.
$$

The non-vanishing Ricci curvature components $\left\{\mathbf{R i c}_{i j}\right\}$ are given by

$$
\begin{equation*}
\boldsymbol{R i c}_{33}=-\frac{2}{|\lambda|} \tag{19}
\end{equation*}
$$

## 3. Main results

3.1. In this section we give the necessary and sufficient conditions for $f$-biharmonic curves in $\mathbb{M}_{3}$. Suppose that $\gamma: I \rightarrow \mathbb{M}_{3}$ is a curve parameterized by arc-length. The Frenet orthonormal frame $\left\{\mathbf{T}=\gamma^{\prime}, \mathbf{N}, \mathbf{B}\right\}$ associated to the $\gamma$ are following the Frenet formulas

$$
\left\{\begin{array}{l}
\nabla_{\gamma^{\prime}} \mathbf{T}=\epsilon k \mathbf{N} \\
\nabla_{\gamma^{\prime}} \mathbf{N}=-\epsilon k \mathbf{T}+\epsilon_{1} \tau \mathbf{B} \\
\nabla_{\gamma^{\prime}} \mathbf{B}=-\epsilon \tau \mathbf{N}
\end{array}\right.
$$

where $k=\left|\nabla_{\gamma^{\prime}} \gamma^{\prime}\right|$ is the geodesic curvature of $\gamma$ and $\tau$ its the geodesic torsion and

$$
g(\mathbf{T}, \mathbf{T})=g(\mathbf{N}, \mathbf{N})=\epsilon, g(\mathbf{B}, \mathbf{B})=\epsilon_{1} .
$$

We have

$$
\begin{align*}
\tau(\gamma) & =\nabla_{\frac{\partial}{\partial s}}^{\gamma}\left(d \gamma\left(\frac{\partial}{\partial s}\right)\right)-d \gamma\left(\nabla_{\frac{\partial}{\partial s}} \frac{\partial}{\partial s}\right) \\
& =\nabla_{\frac{\partial}{\partial s}}^{\gamma}\left(d \gamma\left(\frac{\partial}{\partial s}\right)\right)=\nabla_{\gamma^{\prime}} \gamma^{\prime}=\nabla_{\mathbf{T}} \mathbf{T}=\epsilon k \mathbf{N} . \tag{20}
\end{align*}
$$

and by definition we have

$$
\begin{align*}
\mathbf{R}(\mathbf{T}, \mathbf{N}, \mathbf{T}, \mathbf{N})= & \frac{1}{\lambda}\left(2 B_{3}^{2}-1\right)  \tag{21}\\
\mathbf{R}(\mathbf{T}, \mathbf{N}, \mathbf{T}, \mathbf{B}) & =-\frac{2}{\lambda} N_{3} B_{3} \tag{22}
\end{align*}
$$

where $N_{3}$ and $B_{3}$ are the third components of the vectors $\mathbf{N}$ and $\mathbf{B}$ respectively.
By replacing equation 20 in the equation of bitension field 5 , we get

$$
\begin{align*}
\tau_{2}(\gamma)= & \nabla_{\mathbf{T}}^{3} \mathbf{T}-\mathbf{R}\left(\nabla_{\mathbf{T}} \mathbf{T}, \mathbf{T}\right) \mathbf{T} \\
= & -3 k k^{\prime} \mathbf{T}+\left(\epsilon k^{\prime \prime}-\epsilon k^{3}-\epsilon_{1} k \tau^{2}\right) \mathbf{N} \\
& +\left(2 \epsilon \epsilon_{1} k^{\prime} \tau+\epsilon \epsilon_{1} k \tau^{\prime}\right) \mathbf{B}-\epsilon k \mathbf{R}(\mathbf{N}, \mathbf{T}) \mathbf{T} . \tag{23}
\end{align*}
$$

and

$$
\begin{equation*}
\nabla_{g r a d f}^{\gamma} \tau(\gamma)=\nabla_{g r a d f}^{\gamma} \epsilon k \mathbf{N}=f^{\prime} \nabla_{\mathbf{T}}(\epsilon k \mathbf{N})=f^{\prime}\left(-k^{2} \mathbf{T}+\epsilon k^{\prime} \mathbf{N}+\epsilon \epsilon_{1} k \tau \mathbf{B}\right) \tag{24}
\end{equation*}
$$

From equations 20, 23 and 24 we calculate the $f$-bitension field of the curve $\gamma$

$$
\begin{align*}
\tau_{2, f}(\gamma)=- & 3 f k k^{\prime} \mathbf{T}+f\left(\epsilon k^{\prime \prime}-\epsilon k^{3}-\epsilon_{1} k \tau^{2}\right) \mathbf{N}+f\left(2 \epsilon \epsilon_{1} k^{\prime} \tau+\epsilon \epsilon_{1} k \tau^{\prime}\right) \mathbf{B} \\
& +f^{\prime \prime} \epsilon k \mathbf{N}+2 f^{\prime}\left(-k^{2} \mathbf{T}+\epsilon k^{\prime} \mathbf{N}+\epsilon \epsilon_{1} k \tau \mathbf{B}\right)-f \epsilon k R(\mathbf{N}, \mathbf{T}) \mathbf{T} \tag{25}
\end{align*}
$$

Now, by taking the inner product of equation 25 and using equations 21 and 22 respectively with $\mathbf{T}, \mathbf{N}$ and $\mathbf{B}$, we have:

Theorem 3.1. The curve $\gamma$ is $f$-biharmonic curve in $\mathbb{M}_{3}$ if and only if the following equations hold

$$
\left\{\begin{array}{l}
3 f k k^{\prime}=-2 f^{\prime} k^{2}  \tag{26}\\
f k^{\prime \prime}-f k^{3}-f \epsilon \epsilon_{1} k \tau^{2}+f \frac{1}{\lambda} k=2 f \frac{1}{\lambda} k B_{3}^{2}-2 f^{\prime} k^{\prime}+f^{\prime \prime} k \\
-2 f k^{\prime} \tau-f k \tau^{\prime}=f \frac{2 \epsilon_{1}}{\lambda} k N_{3} B_{3}+2 f^{\prime} k \tau
\end{array}\right.
$$

3.2. In this section we discus the $f$-harmonicity of the curve $\gamma$, depending on the value of $k$ and $\tau$.

- If the curvature $k=c_{1} \neq 0$ of $\gamma$ is constant non null, the first equation in 26 gives that

$$
f^{\prime}=0 \Rightarrow f=\text { constant }=c_{2}
$$

By replacing $k$ and $f$ in the second and the third equations in 26 , we get the conditions of the $f$-biharmonicity of $\gamma$ given by

$$
\left\{\begin{array}{l}
-c_{1}-\epsilon \epsilon_{1} \tau^{2}+\frac{1}{\lambda}=2 \frac{1}{\lambda} B_{3}^{2}  \tag{27}\\
\tau^{\prime}=-\frac{2 \epsilon_{1}}{\lambda} N_{3} B_{3}
\end{array}\right.
$$

Corollary 3.2. Let $\gamma$ be a curve in $\mathbb{M}_{3}$ with non-null constant curvature in $\mathbb{M}_{3}$. Then $\gamma$ is $f$-biharmonic curve if and only if the equations given in 27 are satisfied.

- If the torsion $\tau=c_{3} \neq 0$ of $\gamma$ is constant non-null, the first equation in 26 gives that

$$
\begin{equation*}
f=c_{4} k^{\frac{-3}{2}} \tag{28}
\end{equation*}
$$

And the third equation in 26 gives that

$$
\begin{equation*}
-2 c_{3}(f k)^{\prime}=\frac{2 \epsilon_{1}}{\lambda} N_{3} B_{3} f k \Leftrightarrow f=\frac{c_{5}}{k} e^{\frac{-\epsilon_{1}}{c_{3} \lambda} \int N_{3} B_{3} d s} \tag{29}
\end{equation*}
$$

Now, combining both equations 28 and 29 gives

$$
\begin{equation*}
k=\sqrt{\frac{c_{4}}{c_{5}}} e^{\frac{\epsilon_{1}}{2 c_{3} \lambda} \int N_{3} B_{3} d s} . \tag{30}
\end{equation*}
$$

By replacing $f$ given in 28 in the second equation in 26 , we get the conditions of the $f$-biharmonicity of $\gamma$ given by

$$
\begin{equation*}
c_{4} k^{\prime \prime} k^{\frac{-3}{2}}-c_{4} k^{\frac{3}{2}}+\left(-c_{4} c_{3}^{2} \epsilon \epsilon_{1}+\frac{1}{\lambda} 2 c_{4} \frac{1}{\lambda} B_{3}^{2}\right) k^{\frac{-1}{2}}=3 c_{4} k^{2} k^{\frac{-5}{2}}+\frac{15}{4} c_{4} k^{\prime 2} k^{\frac{-5}{2}}-\frac{3}{2} c_{4} k^{\prime \prime} k^{\frac{-3}{2}} . \tag{31}
\end{equation*}
$$

Corollary 3.3. Let $\gamma$ be a curve in $\mathbb{M}_{3}$ with a non-null constant torsion in $\mathbb{M}_{3}$. Then $\gamma$ is $f$-biharmonic curve if and only if the curvature $k$ of the curve $\gamma$ given in the equation 30 satisfied the equations given in 31.

- If the torsion of the curve $\gamma$ is null $(\tau=0)$, according to the value of $f$ given in 28 and the second and third equations in 26 , we get the conditions of the $f$-biharmonicity of $\gamma$ given by

$$
\left\{\begin{array}{l}
c_{4} k^{\prime \prime} k^{\frac{-3}{2}}-c_{4} k^{\frac{3}{2}}+\left(\frac{1}{\lambda} 2 c_{4} \frac{1}{\lambda} B_{3}^{2}\right) k^{\frac{-1}{2}}=3 c_{4} k^{2} k^{\frac{-5}{2}}+\frac{15}{4} c_{4} k^{2} k^{\frac{-5}{2}}-\frac{3}{2} c_{4} k^{\prime \prime} k^{\frac{-3}{2}}  \tag{32}\\
N_{3} B_{3}=0
\end{array}\right.
$$

Corollary 3.4. Let $\gamma$ be a curve in $\mathbb{M}_{3}$ with null torsion. Then $\gamma$ is $f$-biharmonic curve if and only if the curvature $k$ of the curve $\gamma$ given in the equation 30 satisfied the equations given in 32.

- If $\gamma$ be a curve with constant non-null curvature and constant non-null torsion. So immediately by the first equation in 26 gives that $f$ is constant and the third equation in 26 gives $N_{3} B_{3}=0$. We get the conditions of the $f$-biharmonicity of $\gamma$ given by

$$
\left\{\begin{array}{l}
\text { If } B_{3} \neq 0: B_{3}^{2}=\frac{\lambda}{2}\left(k+\tau^{2} \epsilon \epsilon_{1}-\frac{1}{\lambda}\right)  \tag{33}\\
\operatorname{If} B_{3}=0: k+\tau^{2} \epsilon \epsilon_{1}-\frac{1}{\lambda}=0
\end{array}\right.
$$

Corollary 3.5. Let $\gamma$ be a curve in $\mathbb{M}_{3}$ with constant non-null curvature and constant non-null torsion in $\mathbb{M}_{3}$. Then $\gamma$ is $f$-biharmonic curve if and only if the equations given in 33 are satisfied.

Theorem 3.6. Let $\gamma$ be a curve in $\mathbb{M}_{3}$, then $\gamma$ is proper $f$-biharmonic if and only if :
(i) $\tau=0, f=c_{4} k^{-\frac{3}{2}}$ and the curvature $k$ of the curve $\gamma$ satisfied the equation

$$
3\left(k^{\prime}\right)^{2}-2 k k^{\prime \prime}=4 k^{2}\left(k^{2}+2 \frac{1}{\lambda} B_{3}^{2}-\frac{1}{\lambda}\right)
$$

(ii) $\tau \neq 0, \frac{\tau}{k}=\frac{\exp ^{\int} \frac{-2 N_{3} B_{3}}{|\lambda| \tau}}{c_{1}{ }^{2}}$, and the curvature $k$ satisfied the equation

$$
3\left(k^{\prime}\right)^{2}-2 k k^{\prime \prime}=4 k^{2}\left(k^{2}\left(1+\epsilon \epsilon_{1} \frac{\exp ^{\int} \frac{-4 N_{3} B_{3}}{\tau|\lambda|}}{c_{4}^{4}}\right)+2 \frac{1}{\lambda} B_{3}^{2}-\frac{1}{\lambda}\right)
$$

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