# ON TRANSLATION SURFACES WITH ZERO GAUSSIAN CURVATURE IN LORENTZIAN SOL $_{3}$ SPACE 

LAKEHAL BELARBI* AND HANIFI ZOUBIR


#### Abstract

In this work we classified translation invariant surfaces with zero Gaussian curvature in the 3 -dimensional Sol Lie group endowed with Lorentzian metric.


AMS Mathematics Subject Classification : 49Q20, 53C22.
Key words and phrases : Flat Surfaces, homogeneous space, Lorentzian metric.

## 1. Introduction

During the recent years, there has been a rapidly growing interest in the geometry of surfaces in the homogeneous space $\mathrm{Sol}_{3}$ focusing on minimal and constant mean curvature and totally umbilic surfaces. This was initiated by R.Souam and E.Toubiana [24, 25], and by R.Lopez and M.I.Munteanu [14, 15] . More general many works are devoted to studying the geometry of surfaces in 3-homogeneous space $\mathrm{Sol}_{3}$. See for example [16], [13],[18], [10],,[19].
The $S o l_{3}$ geometry is eight models geometry of Thurston, see [27] .It is a Lie group endowed with a left-invariant metric, it is a homogeneous simply connected 3 -manifold with a 3 -dimensional isometry group, see [8]. It is isometric to $\mathbb{R}^{3}$ equipped with the Lorentzian metric

$$
d s^{2}=e^{2 z} d x^{2}-e^{-2 z} d y^{2}+d z^{2}
$$

where $(x, y, z)$ the usual coordinates of $\mathbb{R}^{3}$.
The group structure of $\mathrm{Sol}_{3}$ is given by

$$
\left(x^{\prime}, y^{\prime}, z^{\prime}\right) \star(x, y, z)=\left(e^{-z^{\prime}} x+x^{\prime}, e^{z^{\prime}} y+y^{\prime}, z+z^{\prime}\right) .
$$

The isometries are

$$
(x, y, z) \mapsto\left( \pm e^{-c} x+a, \pm e^{c} y+b, z+c\right)
$$

[^0]where $a, b$ end $c$ are any real numbers.
A left-invariant orthonormal frame $\left\{E_{1}, E_{2}, E_{3}\right\}$ in the Lorentzian $\operatorname{Sol}_{3}$ Lie group is given by
\[

$$
\begin{equation*}
E_{1}=e^{-z} \frac{\partial}{\partial x}, E_{2}=e^{z} \frac{\partial}{\partial y}, E_{3}=\frac{\partial}{\partial z} \tag{1}
\end{equation*}
$$

\]

The Levi-Civita connection $\nabla$ of the Lorentzian Sol $_{3}$ Lie group with respect to this frame is

$$
\left\{\begin{array}{l}
\nabla_{E_{1}} E_{1}=-E_{3}, \nabla_{E_{1}} E_{2}=0, \nabla_{E_{1}} E_{3}=E_{1}  \tag{2}\\
\nabla_{E_{2}} E_{1}=0, \nabla_{E_{2}} E_{2}=-E_{3}, \nabla_{E_{2}} E_{3}=-E_{2} \\
\nabla_{E_{3}} E_{1}=0, \nabla_{E_{3}} E_{2}=0, \nabla_{E_{3}} E_{3}=0 .
\end{array}\right.
$$

The non-vanishing curvature tensor $R$ components are computed as

$$
\left\{\begin{array}{l}
R\left(E_{1}, E_{2}\right) E_{1}=-E_{2}, R\left(E_{1}, E_{2}\right) E_{2}=-E_{1}  \tag{3}\\
R\left(E_{1}, E_{3}\right) E_{1}=E_{3}, R\left(E_{1}, E_{3}\right) E_{3}=-E_{1} \\
R\left(E_{2}, E_{3}\right) E_{2}=-E_{3}, R\left(E_{2}, E_{3}\right) E_{3}=-E_{2}
\end{array}\right.
$$

The Ricci curvature components $\left\{R i c_{i j}\right\}$ are computed as

$$
\begin{equation*}
\operatorname{Ric}_{11}=\text { Ric }_{12}=\text { Ric }_{13}=\text { Ric }_{23}=\text { Ric }_{22}=0, \quad \text { Ric }_{33}=-2 \tag{4}
\end{equation*}
$$

The scalar curvature $\tau$ of the Lorentzian $\mathrm{Sol}_{3}$ Lie group is constant and we have

$$
\begin{equation*}
\tau=\operatorname{trRic}=\sum_{i=1}^{3} g\left(E_{i}, E_{i}\right) \operatorname{Ric}\left(E_{i}, E_{i}\right)=-2 \tag{5}
\end{equation*}
$$

## 2. Flat Translation Surfaces in Lorentzian Sol $_{3}$ space

2.1. In this section we classified complete flat translation surfaces $(\Sigma)$ in Lorentzian $\mathrm{Sol}_{3}$ space which are invariant under the one parameter group of isometries $(x, y, z) \mapsto(x, y+c, z)$. Clearly, such a surface is generated by a curve $\gamma$ in the totally geodesic plane $\{y=0\}$. Discarding the trivial case of a vertical plane $\left\{x=x_{0}\right\}$, we can assume that $\gamma$ is locally is a graph over the $x$-axis. Thus $\gamma$ is given by $\gamma(x)=(x, 0, z(x))$. Therefore the generated surface is parameterized by

$$
X(x, y)=(x, y, z(x)),(x, y) \in \mathbb{R}^{2}
$$

We have an orthogonal pair of vector fields on $(\Sigma)$, namely,

$$
e_{1}:=X_{x}=\left(1,0, z^{\prime}\right)=e^{z} E_{1}+z^{\prime} E_{3}
$$

and

$$
e_{2}:=X_{y}=(0,1,0)=e^{-z} E_{2}
$$

The coefficients of the first fundamental form are:

$$
E=<e_{1}, e_{1}>=z^{\prime 2}+e^{2 z}, F=<e_{1}, e_{2}>=0, G=<e_{2}, e>=-e^{-2 z}
$$

As a unit normal field we can take

$$
N=\frac{-z^{\prime} e^{-z}}{\sqrt{1+z^{\prime 2} e^{-2 z}}} E_{1}+\frac{1}{\sqrt{1+z^{\prime 2} e^{-2 z}}} E_{3}
$$

The covariant derivatives are

$$
\begin{gathered}
\widetilde{\nabla}_{e_{1}} e_{1}=2 z^{\prime} e^{z} E_{1}+\left(z^{\prime \prime}-e^{2 z}\right) E_{3} \\
\widetilde{\nabla}_{e_{1}} e_{2}=-z^{\prime} e^{-z} E_{2} \\
\widetilde{\nabla}_{e_{2}} e_{2}=-e^{-2 z} E_{3} .
\end{gathered}
$$

The coefficients of the second fundamental form are

$$
\begin{gathered}
l=<\widetilde{\nabla}_{e_{1}} e_{1}, N>=\frac{-2 z^{\prime 2}+z^{\prime \prime}-e^{2 z}}{\sqrt{1+z^{\prime 2} e^{-2 z}}} \\
m=<\widetilde{\nabla}_{e_{1}} e_{2}, N>=0 \\
n=<\widetilde{\nabla}_{e_{2}} e_{2}, N>=\frac{-e^{-2 z}}{\sqrt{1+z^{\prime 2} e^{-2 z}}}
\end{gathered}
$$

Let $K_{\text {ext }}$ be the extrinsic Gauss curvature of $(\Sigma)$,

$$
\begin{equation*}
K_{e x t}=\frac{l n-m^{2}}{E G-F^{2}}=-\frac{-2 z^{\prime 2} e^{-2 z}+z^{\prime \prime} e^{-2 z}-1}{\left(1+z^{\prime 2} e^{-2 z}\right)^{2}} \tag{6}
\end{equation*}
$$

In order to obtain the intrinsic Gauss curvature $K_{\text {int }}$, recall that $K_{\text {int }}=K_{\text {ext }}+$ $K\left(e_{1} \wedge e_{2}\right)$, where $K\left(e_{1} \wedge e_{2}\right)$ is the sectional curvature of each tangent plane spanned by $e_{1}$ and $e_{2}$, and

$$
K\left(e_{1} \wedge e_{2}\right)=\frac{\left\langle R\left(e_{1}, e_{2}\right) e_{2}, e_{1}\right\rangle}{<e_{1}, e_{1}><e_{2}, e_{2}>-<e_{1}, e_{2}>^{2}}
$$

where

$$
R\left(e_{1}, e_{2}\right) e_{2}=\widetilde{\nabla}_{e_{1}} \widetilde{\nabla}_{e_{2}} e_{2}-\widetilde{\nabla}_{e_{2}} \widetilde{\nabla}_{e_{1}} e_{2}-\widetilde{\nabla}_{\left[e_{1}, e_{2}\right]} e_{2}
$$

Now we easily compute

$$
\begin{gathered}
\widetilde{\nabla}_{e_{1}} \widetilde{\nabla}_{e_{2}} e_{2}=-e^{-z} E_{1}+2 z^{\prime} e^{-2 z} E_{3} \\
\widetilde{\nabla}_{e_{2}} \widetilde{\nabla}_{e_{1}} e_{2}=z^{\prime} e^{-2 z} E_{3} \\
\widetilde{\nabla}_{\left[e_{1}, e_{2}\right]} e_{2}=0
\end{gathered}
$$

Thus we have

$$
K\left(e_{1} \wedge e_{2}\right)=-\frac{1-z^{\prime 2} e^{-2 z}}{1+z^{\prime 2} e^{-2 z}}
$$

Consequently, the intrinsic Gauss curvature is

$$
\begin{equation*}
K_{i n t}=-\frac{e^{-2 z}\left[z^{\prime \prime}-2 z^{\prime 2}-z^{\prime 4} e^{-2 z}\right]}{\left(1+z^{\prime 2} e^{-2 z}\right)^{2}} \tag{7}
\end{equation*}
$$

So that $(\Sigma)$ is a flat surface in Lorentzian $S o l_{3}$ if and only if

$$
K_{i n t}=0
$$

that is, if and only if

$$
\begin{equation*}
z^{\prime \prime}-2 z^{\prime 2}-z^{\prime 4} e^{-2 z}=0 \tag{8}
\end{equation*}
$$

to classify flat surfaces must solve the equation (8)
We note that for $z$ equal to a constant $\left(z=z_{0}\right)$ is a solution of the equation (8). If $z$ is not constant $\left(z^{\prime} \neq 0\right)$,suppose that $z^{\prime}=p$, and

$$
z^{\prime \prime}=\frac{d p}{d x}=\frac{d p}{d z} \frac{d z}{d x}=p \cdot p^{\prime}(z)
$$

equation (8) becomes

$$
p \cdot p^{\prime}=2 p^{2}+p^{4} e^{-2 z}
$$

or

$$
\begin{equation*}
p^{-3} \cdot p^{\prime}=2 p^{-2}+e^{-2 z} \tag{9}
\end{equation*}
$$

and suppose that $p^{-2}=h$, equation (9) becomes

$$
\begin{equation*}
\frac{-1}{2} h^{\prime}=2 h+e^{-2 z} . \tag{10}
\end{equation*}
$$

homogeneous solutions of equation (10) is

$$
h(z)=K \cdot e^{-4 z}
$$

and general solutions of the equation (10) is

$$
h(z)=e^{-4 z}\left(a-e^{2 z}\right)
$$

where $a \in \mathbb{R}^{*,+}$ and $\left.z \in\right]-\infty, \ln (\sqrt{a})[$. Therefore

$$
p(z)= \pm \frac{1}{\sqrt{h(z)}}= \pm \frac{e^{2 z}}{\sqrt{a-e^{2 z}}}
$$

and we have

$$
z^{\prime}= \pm \frac{e^{2 z}}{\sqrt{a-e^{2 z}}}
$$

or

$$
\frac{d z}{d x}= \pm \frac{e^{2 z}}{\sqrt{a-e^{2 z}}}
$$

so separating variables, we obtain

$$
\int d x=\int \pm \frac{\sqrt{a-e^{2 z}}}{e^{2 z}} d z
$$

i.e

$$
x= \pm \int \frac{\sqrt{a-e^{2 z}}}{e^{2 z}} d z+\alpha
$$

where $\alpha \in \mathbb{R}$.
we substitute $\tanh (t)=\frac{\sqrt{a-e^{2 z}}}{\sqrt{a}}, d z=-\tanh (t) d t$, and $e^{2 z}=\frac{a}{\cosh ^{2}(t)}$, therefore

$$
\int \frac{\sqrt{a-e^{2 z}}}{e^{2 z}} d z=-\frac{-1}{\sqrt{a}} \int \sinh ^{2}(t) d t=-\frac{1}{8 \sqrt{a}}\left[e^{2 t}-e^{-2 t}\right]+\frac{t}{2 \sqrt{a}}
$$

and as $t=\operatorname{arctanh}\left(\frac{\sqrt{a-e^{2 z}}}{\sqrt{a}}\right)=\frac{1}{2} \ln \left(\frac{1+\frac{\sqrt{a-e^{2 z}}}{\sqrt{a}}}{1-\frac{\sqrt{a-e^{2 z}}}{\sqrt{a}}}\right)$, thus

$$
\begin{aligned}
\int \frac{\sqrt{a-e^{2 z}}}{e^{2 z}} d z=- & \frac{1}{8 \sqrt{a}}\left[\left(\frac{\sqrt{a}+\sqrt{a-e^{2 z}}}{\sqrt{a}-\sqrt{a-e^{2 z}}}\right)-\left(\frac{\sqrt{a}-\sqrt{a-e^{2 z}}}{\sqrt{a}+\sqrt{a-e^{2 z}}}\right)\right] \\
& +\frac{1}{2 \sqrt{a}} \operatorname{arctanh}\left(\frac{\sqrt{a-e^{2 z}}}{\sqrt{a}}\right)
\end{aligned}
$$

and is calculated by the following

$$
\int \frac{\sqrt{a-e^{2 z}}}{e^{2 z}} d z=\frac{1}{2 \sqrt{a}} \operatorname{arctanh}\left(\frac{\sqrt{a-e^{2 z}}}{\sqrt{a}}\right)-\frac{\sqrt{a-e^{2 z}}}{2 e^{2 z}} .
$$

Therefore

$$
x(z)= \pm\left(\frac{1}{2 \sqrt{a}} \operatorname{arctanh}\left(\frac{\sqrt{a-e^{2 z}}}{\sqrt{a}}\right)-\frac{\sqrt{a-e^{2 z}}}{2 e^{2 z}}\right)+\alpha .
$$

As conclusion, we have
Theorem 2.1. •The only non extendable flat translation surfaces in Lorentzian Sol $_{3}$ space which are invariant under the one parameter group of isometries $(x, y, z) \mapsto(x, y+c, z)$, are the surfaces whose parametrization is $X(x, y)=$ $(x, y, z(x))$ where $x$ and $z$ satisfy

$$
x= \pm\left(\frac{1}{2 \sqrt{a}} \operatorname{arctanh}\left(\frac{\sqrt{a-e^{2 z}}}{\sqrt{a}}\right)-\frac{\sqrt{a-e^{2 z}}}{2 e^{2 z}}\right)+\alpha .
$$

where $a \in \mathbb{R}^{*,+}, \alpha \in \mathbb{R}$ and $\left.z \in\right]-\infty, \ln (\sqrt{a})[$.

- In particular the only complete flat translation surfaces in Lorentzian Sol ${ }_{3}$ space which are invariant under the one parameter group of isometries $(x, y, z) \mapsto$ $(x, y+c, z)$, are the planes $z=z_{0}$.

Theorem 2.2. •The only complete extrinsically flat translation surfaces in Lorentzian Sol $_{3}$ space which are invariant under the one parameter group of isometries $(x, y, z) \mapsto(x, y+c, z)$, are parameterized by

$$
X(x, y)=\left(x, y, \ln \left(\frac{1}{\sqrt{-x^{2}+2 \lambda x+\mu}}\right)\right)
$$

where $\lambda, \mu \in \mathbb{R}$, and $\lambda^{2}+2 \mu>0 \alpha \in \mathbb{R}$ and $\left.x \in\right] \lambda-\sqrt{\lambda^{2}+2 \mu}, \lambda+\sqrt{\lambda^{2}+2 \mu}[$.

Proof. We know that $\Sigma$ is extrinsically surface if and only if $K_{\text {ext }}=0$, and we have $K_{\text {ext }}=0$ equivalent to

$$
2 z^{\prime 2} e^{-2 z}-z^{\prime \prime} e^{-2 z}=-1
$$



Figure 1. Non extendable flat surface in Lorentzian Sol $_{3}$ $: x(z)= \pm\left(\frac{1}{2 \sqrt{0.2}} \operatorname{arctanh}\left(\frac{\sqrt{0.2-e^{2 z}}}{\sqrt{0.2}}\right)-\frac{\sqrt{0.2-e^{2 z}}}{2 e^{2 z}}\right)+2, a=$ $0.2, z=-6 . .-1, y=-4 . .8$.
we remark that $2 z^{\prime 2} e^{-2 z}-z^{\prime \prime} e-2 z=\left(-z^{\prime} e^{-2 z}\right)^{\prime}$, thus

$$
\begin{equation*}
-z^{\prime} e^{-2 z}=-x+\lambda, \tag{11}
\end{equation*}
$$

where $\lambda \in \mathbb{R}$,and we integrate the equation 11

$$
z(x)=\ln \left(\frac{1}{\sqrt{-x^{2}+2 \lambda+2 \mu}}\right)
$$

where $\mu \in \mathbb{R}$, and $\lambda^{2}+2 \mu>0 \alpha \in \mathbb{R}$ and $\left.x \in\right] \lambda-\sqrt{\lambda^{2}+2 \mu}, \lambda+\sqrt{\lambda^{2}+2 \mu}[$.
2.2. In this section we classified complete flat translation surfaces $(\Sigma)$ in Lorentzian $\mathrm{Sol}_{3}$ space which are invariant under the one parameter group of isometries $(x, y, z) \mapsto(x+c, y, z)$. Clearly, such a surface is generated by a curve $\beta$ in the totally geodesic plane $\{x=0\}$. Discarding the trivial case of a vertical plane $\left\{y=y_{0}\right\}$, we can assume that $\beta$ is locally is a graph over the $y$-axis. Thus $\beta$ is given by $\beta(y)=(0, y, z(y))$. Therefore the generated surface is parameterized by

$$
X(x, y)=(x, y, z(y)), \quad(x, y) \in \mathbb{R}^{2}
$$

We have an orthogonal pair of vector fields on $(\Sigma)$, namely,

$$
e_{1}:=X_{x}=(1,0,0)=e^{z} E_{1}
$$

and

$$
e_{2}:=X_{y}=\left(0,1, z^{\prime}\right)=e^{-z} E_{2}+z^{\prime} E_{3} .
$$

The coefficients of the first fundamental form are:

$$
E=<e_{1}, e_{1}>=e^{2 z}, F=<e_{1}, e_{2}>=0, G=<e_{2}, e_{2}>=z^{\prime 2}-e^{-2 z}
$$

As a unit normal field we can take

$$
N=\frac{z^{\prime} e^{z}}{\sqrt{\left|-1+z^{\prime 2} e^{2 z}\right|}} E_{2}+\frac{1}{\sqrt{\left|-1+z^{\prime 2} e^{2 z}\right|}} E_{3}
$$

The covariant derivatives are

$$
\begin{gathered}
\widetilde{\nabla}_{e_{1}} e_{1}=-e^{2 z} E_{3} \\
\widetilde{\nabla}_{e_{1}} e_{2}=z^{\prime} e^{z} E_{1}, \\
\widetilde{\nabla}_{e_{2}} e_{2}=-2 z^{\prime} e^{-z} E_{2}+\left(z^{\prime \prime}-e^{-2 z}\right) E_{3}
\end{gathered}
$$

The coefficients of the second fundamental form are

$$
\begin{gathered}
l=<\widetilde{\nabla}_{e_{1}} e_{1}, N>=\frac{-e^{2 z}}{\sqrt{\mid-1+z^{\prime 2} e^{2 z \mid}}} \\
m=<\widetilde{\nabla}_{e_{1}} e_{2}, N>=0 \\
n=<\widetilde{\nabla}_{e_{2}} e_{2}, N>=\frac{2 z^{\prime 2}+z^{\prime \prime}-e^{-2 z}}{\sqrt{\mid-1+z^{\prime 2} e^{2 z \mid}}}
\end{gathered}
$$

Let $K_{\text {ext }}$ be the extrinsic Gauss curvature of $(\Sigma)$,

$$
\begin{equation*}
K_{e x t}=\frac{l n-m^{2}}{E G-F^{2}}=\frac{2 z^{\prime 2} e^{2 z}+z^{\prime \prime} e^{2 z}-1}{\left(-1+z^{\prime 2} e^{2 z}\right)^{2}} \tag{12}
\end{equation*}
$$

In order to obtain the intrinsic Gauss curvature $K_{\text {int }}$, recall that $K_{\text {int }}=K_{\text {ext }}+$ $K\left(e_{1} \wedge e_{2}\right)$, where $K\left(e_{1} \wedge e_{2}\right)$ is the sectional curvature of each tangent plane spanned by $e_{1}$ and $e_{2}$, and

$$
\begin{aligned}
K\left(e_{1} \wedge e_{2}\right) & =\frac{\left\langle R\left(e_{1}, e_{2}\right) e_{2}, e_{1}\right\rangle}{\left\langle e_{1}, e_{1}\right\rangle\left\langle e_{2}, e_{2}\right\rangle-\left\langle e_{1}, e_{2}\right\rangle^{2}} \\
& =\frac{R_{1212+z^{\prime 2} R_{1313}}^{-1+z^{\prime 2} e^{2 z}}}{} \\
& =\frac{-1-z^{\prime 2} e^{2 z}}{-1+z^{\prime 2} e^{2 z}}
\end{aligned}
$$

Consequently, the intrinsic Gauss curvature is

$$
\begin{equation*}
K_{i n t}=\frac{e^{2 z}\left[z^{\prime \prime}+2 z^{\prime 2}-z^{\prime 4} e^{2 z}\right]}{\left(-1+z^{\prime 2} e^{2 z}\right)^{2}} \tag{13}
\end{equation*}
$$

So that $(\Sigma)$ is a flat surface in Lorentzian $\mathrm{Sol}_{3}$ if and only if

$$
K_{i n t}=0
$$

that is, if and only if

$$
\begin{equation*}
z^{\prime \prime}+2 z^{\prime 2}-z^{\prime 4} e^{2 z}=0 \tag{14}
\end{equation*}
$$

to classify flat surfaces must solve the equation (14)
We note that for $z$ equal to a constant $\left(z=z_{0} \in \mathbb{R}\right)$ is a solution of the equation (14).

If $z$ is not constant $\left(z^{\prime} \neq 0\right)$,suppose that $z^{\prime}=q$, and

$$
z^{\prime \prime}=\frac{d q}{d x}=\frac{d q}{d z} \frac{d z}{d x}=q \cdot q^{\prime}(z)
$$

equation (14) becomes

$$
q \cdot q^{\prime}=-2 q^{2}+q^{4} e^{2 z}
$$

or

$$
\begin{equation*}
q^{-3} \cdot q^{\prime}=-2 q^{-2}+e^{2 z} . \tag{15}
\end{equation*}
$$

and suppose that $q^{-2}=g$, equation (15) becomes

$$
\begin{equation*}
\frac{-1}{2} g^{\prime}=-2 g+e^{2 z} \tag{16}
\end{equation*}
$$

homogeneous solutions of equation (16) is

$$
g(z)=K \cdot e^{4 z}
$$

and general solutions of the equation (16) is

$$
g(z)=e^{4 z}\left(a+e^{-2 z}\right)
$$

where $a \in \mathbb{R}^{*,-}$ and $\left.z \in\right]-\infty, \ln \left(\frac{1}{\sqrt{-a}}\right)[$. Therefore

$$
q(z)= \pm \frac{1}{\sqrt{g(z)}}= \pm \frac{e^{-2 z}}{\sqrt{a+e^{-2 z}}}
$$

and we have

$$
z^{\prime}= \pm \frac{e^{-2 z}}{\sqrt{a+e^{-2 z}}}
$$

or

$$
\frac{d z}{d y}= \pm \frac{e^{-2 z}}{\sqrt{a+e^{-2 z}}}
$$

so separating variables, we obtain

$$
\int d y=\int \pm \frac{\sqrt{a+e^{-2 z}}}{e^{-2 z}} d z
$$

i.e

$$
y=\int \pm \frac{\sqrt{a+e^{-2 z}}}{e^{-2 z}} d z+\delta
$$

where $\delta \in \mathbb{R}$.
we substitute $\tanh (t)=\frac{\sqrt{a+e^{-2 z}}}{\sqrt{a}}, d z=\tanh (t) d t$, and $e^{-2 z}=\frac{a}{\cosh ^{2}(t)}=a(1-$ $\left.\tanh ^{2}(t)\right)$, therefore

$$
\int \frac{\sqrt{a+e^{-2 z}}}{e^{-2 z}} d z=\frac{1}{\sqrt{a}} \int \sinh ^{2}(t) d t=-\frac{1}{8 \sqrt{a}}\left[e^{2 t}-e^{-2 t}\right]+\frac{t}{2 \sqrt{a}}
$$

and as $t=\operatorname{arctanh}\left(\frac{\sqrt{a+e^{-2 z}}}{\sqrt{a}}\right)=\frac{1}{2} \ln \left(\frac{1+\frac{\sqrt{a+e^{-2 z}}}{\sqrt{a}}}{1-\frac{\sqrt{a+e^{-2 z}}}{\sqrt{a}}}\right)$, thus

$$
\begin{aligned}
\int \frac{\sqrt{a+e^{-2 z}}}{e^{-2 z}} d z=- & \frac{1}{8 \sqrt{a}}\left[\left(\frac{\sqrt{a}+\sqrt{a+e^{-2 z}}}{\sqrt{a}-\sqrt{a+e^{-2 z}}}\right)-\left(\frac{\sqrt{a}-\sqrt{a+e^{-2 z}}}{\sqrt{a}+\sqrt{a+e^{-2 z}}}\right)\right] \\
& +\frac{1}{2 \sqrt{a}} \operatorname{arctanh}\left(\frac{\sqrt{a+e^{-2 z}}}{\sqrt{a}}\right)
\end{aligned}
$$

and is calculated by the following

$$
\int \frac{\sqrt{a+e^{-2 z}}}{e^{-2 z}} d z=\frac{1}{2 \sqrt{a}} \operatorname{arctanh}\left(\frac{\sqrt{a+e^{-2 z}}}{\sqrt{a}}\right)+\frac{\sqrt{a+e^{-2 z}}}{2 e^{-2 z}} .
$$

As conclusion, we have
Theorem 2.3. •The only non extendable flat translation surfaces in Lorentzian $S^{S o l}{ }_{3}$ which are invariant under the one parameter group of isometries $(x, y, z) \mapsto$ $(x+c, y, z)$, are the surfaces whose parametrization is $X(x, y)=(x, y, z(y))$ where $y$ and $z$ satisfy

$$
y= \pm\left(\frac{1}{2 \sqrt{a}} \operatorname{arctanh}\left(\frac{\sqrt{a+e^{-2 z}}}{\sqrt{a}}\right)+\frac{\sqrt{a+e^{-2 z}}}{2 e^{-2 z}}\right)+\delta
$$

where $a \in \mathbb{R}^{*,-}, \delta \in \mathbb{R}$ and $\left.z \in\right]-\infty, \ln \left(\frac{1}{\sqrt{-a}}\right)[$.

- In particular the only complete flat translation surfaces in Lorentzian Sol $_{3}$ which are invariant under the one parameter group of isometries $(x, y, z) \mapsto$ $(x+c, y, z)$, are the planes $z=z_{0}$.

Theorem 2.4. •The only complete extrinsically flat translation surfaces in Lorentzian $\mathrm{Sol}_{3}$ which are invariant under the one parameter group of isometries $(x, y, z) \mapsto(x+c, y, z)$, are parameterized by

$$
X(x, y)=\left(x, y, \ln \left(\sqrt{y^{2}+2 \lambda y+\mu}\right)\right)
$$

where $\lambda, \mu \in \mathbb{R}$, and $\lambda^{2}-2 \mu>0 \alpha \in \mathbb{R}$ and $\left.y \in\right]-\infty, \lambda-\sqrt{\lambda^{2}-2 \mu}[\cup] \lambda+$ $\sqrt{\lambda^{2}-2 \mu},+\infty[$.
Proof. We know that $\Sigma$ is extrinsically flat surface if and only if $K_{\text {ext }}=0$, and we have $K_{e x t}=0$ equivalent to

$$
2 z^{\prime 2} e^{2 z}+z^{\prime \prime} e^{2 z}=1
$$



Figure 2. Non extendable flat surface in Lorentzian $\mathrm{Sol}_{3}$ $: y(z)= \pm\left(\frac{1}{2 \sqrt{0.2}} \operatorname{arctanh}\left(\frac{\sqrt{0.2-e^{-2 z}}}{\sqrt{0.2}}\right)-\frac{\sqrt{0.2-e^{-2 z}}}{2 e^{-2 z}}\right)+2, a=$ $0.2, z=-0.5 . .6, x=-4 . .8$.
we remark that $2 z^{\prime 2} e^{2 z}+z^{\prime \prime} e^{2 z}=\left(z^{\prime} e^{2 z}\right)^{\prime}$, thus

$$
\begin{equation*}
z^{\prime} e^{2 z}=y+\lambda, \tag{17}
\end{equation*}
$$

where $\lambda \in \mathbb{R}$, and we integrate the equation 17

$$
z(y)=\ln \left(\sqrt{y^{2}+2 \lambda y+2 \mu}\right)
$$

where $\mu \in \mathbb{R}$, and $\lambda^{2}-2 \mu>0 \alpha \in \mathbb{R}$ and $\left.y \in\right]-\infty, \lambda-\sqrt{\lambda^{2}-2 \mu}[\cup] \lambda+$ $\sqrt{\lambda^{2}-2 \mu},+\infty[$.

Acknowledgements : The authors would like to thank the Referees for all helpful comments and suggestions that have improved the quality of our initial manuscript. The authors were supported by The National Agency Scientific Research (DGRSDT).

## References

1. U. Abresch and H. Rozenberg, A Hopf differential for constant mean curvature surfaces in $\mathbb{S}^{2} \times \mathbb{R}$ and $\mathbb{H}^{2} \times \mathbb{R}$, Acta Math. 193 (2004), 141-174.
2. L. Belarbi, On the symmetries of the $\mathrm{Sol}_{3}$ Lie group, J. Korean Math. Soc. 57 (2020), 523-537.
3. L. Belarbi, Surfaces with constant extrinsically Guassian curvature in the Heisenberg group, Ann. Math. Inform. 50 (2019), 5-17.
4. L. Belarbi and M. Belkhelfa, On The Ruled Minimal Surfaces in Heisenberg 3-Space With Density, Journal of Interdisciplinary Mathematics 23 (2020), 1141-1155.
5. D. Bensikaddour and L. Belarbi, Minimal Translation Surfaces in Lorentz-Heiesenberg 3Space, Nonlinear Stud. 24 (2017), 859-867.
6. D. Bensikaddour and L. Belarbi, Minimal Translation Surfaces in Lorentz Heisenberg Space $\left(\mathcal{H}_{3}, g_{2}\right)$, Journal of Interdisciplinary Mathematics 24 (2021), 881-896.
7. D. Bensikaddour and L. Belarbi, Minimal Translation Surfaces in Lorentz-Heiesenberg 3space with Flat Metric, Differential Geometry-Dynamical Systems 20 (2018), 1-14.
8. F. Bonahon, Geometric structures on 3-manifolds, In Handbook of geometric topology, North-Holland, Amsterdam, 2002, 93-164.
9. R. Cadeo, P. Piu and A. Ratto, $S O(2)$-invariant minimal and constant mean curvature surfaces in 3-dimensional homogeneous spaces, Maniscripta Math. 87 (1995), 1-12.
10. B. Daniel, Isometric immersions into 3-dimensional homogeneous manifolds, Comment. Math. Helv. 82 (2007), 87-131.
11. R. Sa Erap and E. Toubiana, Screw motion surfaces in $\mathbb{H}^{2} \times \mathbb{R}$ and $\mathbb{S}^{2} \times \mathbb{R}$, Illinois J. Math. 49 (2005), 1323-1362.
12. J. Inoguchi, Flat translation surfaces in the 3-dimensional Heisenberg group, J. Geom. 82 (2005), 83-90.
13. R. López, Constant mean curvature surfaces in Sol with non-empty boundary, Houston. J. Math. 38 (2012), 1091-1105.
14. R. López and M.I. Munteanu, Invariant surfaces in homogeneous space Sol with constant curvature, Math. Nach. 287 (2014), 1013-1024.
15. R. López and M.I. Munteanu, Minimal translation surfaces in Sol $3_{3}$, J. Math. Soc. Japan 64 (2012), 985-1003.
16. J.M. Manzano and R. Souam, The classification of totally ombilical surfaces in homogeneous 3-manifolds, Math. Z. 279 (2015), 557-576.
17. W.S. Massey, Surfaces of Gaussian curvature zero in euclidean 3-space, Tohoku Math. J. 14 (1962), 73-79.
18. W.H. Meeks, Constant mean curvature spheres in Sol ${ }_{3}$, Amer. J. Math. 135 (2013), 1-13.
19. W.H. Meeks and J. Pérez, Constant mean curvature in metric Lie groups, Contemp. Math. 570 (2012), 25-110.
20. W.H. Meeks III and H. Rosenberg, The theory of minimal surfaces in $\mathbb{M} \times \mathbb{R}$, Comment. Math. Helv. 80 (2005), 811-885.
21. B. Nelli and H. Rozenberg, Minimal surfaces in $\mathbb{H}^{2} \times \mathbb{R}$, Bull. Braz. Math. Soc. 33 (2002), 263-292.
22. H. Rosenberg, Minimal surfaces in $\mathbb{M}^{2} \times \mathbb{R}$, Illinois J. Math. 46 (2002), 1177-1195.
23. P. Scott, The geometries of 3-manifolds, Bull. London Math. Soc. 15 (1983), 401-487.
24. R. Souam and E. Toubiana, On the classification and regularity of umbilic surfaces in homogeneous 3-manifolds, Mat. Contemp. 30 (2006), 201-215.
25. R. Souam and E. Toubiana, Totally umbilic surfaces in homogeneous 3 -manifolds, Comm. Math. Helv. 84 (2009), 673-704.
26. R. Souam, On stable constant mean curvature surfaces in $\mathbb{S}^{2} \times \mathbb{R}$ and $\mathbb{H}^{2} \times \mathbb{R}$, Trans. Amer. Math. Soc. 362 (2010), 2845-2857.
27. W.M. Thurston, Three-dimensional Geometry and Topology I, Princeton Math. Series(Levi, S. ed) 1997.

Lakehal Belarbi received Magister Thesis from Mascara University and Ph.D. at University of Sidi Bel Abbes. He is currently a professor at Abdelhamid Ibn Badis University of Mostaganem since 2012. His research interests include Differential Geometry and Topology.
Department of Mathematics, Laboratory of Pure and Applied Mathematics, University of Mostaganem (U.M.A.B.), B.P.227,27000, Mostaganem, Algeria.
e-mail: lakehalbelarbi@gmail.com
Hanifi Zoubir received Magister Thesis and Ph.D. from Oran 1 University. He is currently a professor at École Nationale Polytechnique d'Oran since 2004. His research include Differential Geometry and Topology.
École Nationale Polytechnique d'Oran B.P 1523 El M'naouar Oran 31000, Algeria.
e-mail: zoubirhanifi@yahoo.fr


[^0]:    Received April 15, 2021. Revised March 5, 2022 . Accepted March 6, 2022. ${ }^{*}$ Corresponding author.
    © 2022 KSCAM.

