

SOLITONS OF KÄHLERIAN NORDEN SPACE-TIME MANIFOLDS

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ABSTRACT. We study solitons of Kählerian Norden space-time manifolds and Bochner curvature tensor in almost pseudo symmetric Kählerian space-time manifolds. It is shown that the steady, expanding or shrinking solitons depend on different relations of energy density/isotropic pressure, the cosmological constant, and gravitational constant.

1. Introduction

Relativistic fluid models play a very important role in different branches of astrophysics, plasma physics, nuclear physics and cosmology. The space-time of general relativity and cosmology is studied using a four-dimensional pseudo-Riemannian manifold with Lorentzian metric, (M^4, g) , where g is considered as a perfect fluid space-time. See [21] for an introduction to these topics.

The application of pseudo-Riemannian geometry in relativity is discussed by Neill [18] and by Kaigorodov [15] on the structure of space-time in 1983. In [7], Chaki and Roy explored that a general relativistic space-time with covariant constant energy-momentum tensor is Ricci symmetric. Many differential geometers have been extended the study to the curvature structure of space-time with special properties [11, 22, 23].

Definition 1.1. A non-flat Riemannian manifold M of dimension $n > 2$ is said to be an almost pseudo symmetric manifold [10] if its curvature tensor R satisfies the condition

$$\begin{aligned}(\nabla_X R)(Y, Z, U, W) &= [A(X) + B(X)]R(Y, Z, U, W) \\ &\quad + A(Y)R(X, Z, U, W) + A(Z)R(Y, X, U, W) \\ &\quad + A(U)R(Y, Z, X, W) + A(W)R(Y, Z, U, X),\end{aligned}$$

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where A, B are two non zero 1-forms defined by

$$g(X, \rho) = A(X), \quad g(X, Q) = B(X),$$

$X, Y, Z, W \in \chi(M)$; ρ and Q are called the associated vector fields corresponding to the 1-forms A and B , respectively.

On the other side, the Ricci flow introduced by Hamilton [13] is an excellent mathematical model for simplifying the structure of the manifold. It is given by a partial differential equation connecting Ricci and metric tensors. Ricci solitons are self-similar solutions of this partial differential equation. Thus Ricci, Einstein and conformal Ricci flows are intrinsic geometric flows on a pseudo-Riemannian manifold, whose fixed points are solitons. Ricci solitons, Einstein solitons, and conformal Ricci solitons, which generate self-similar solutions of the Ricci flow, Einstein flow, and conformal Ricci flow are given by:

$$\frac{\partial g}{\partial t} = -2S, \quad \frac{\partial g}{\partial t} = -2(S - \frac{r}{2}g), \quad \frac{\partial g}{\partial t} = -2(S + \frac{g}{n}) - \phi g, \quad \text{and } r = -1.$$

In the papers (see [4, 16, 17]) solitons are studied to a great extent within the background of Riemannian geometry. In [8], Cho and Kimura defined an η -Ricci soliton as

$$(1.1) \quad L_{\xi}g + 2S + 2ag + 2b\eta \otimes \eta = 0,$$

where g is a pseudo-Riemannian metric, S is the Ricci curvature, ξ is a vector field, η is a 1-form and a and b are real constants. The data (g, ξ, a, b) in (1.1) is said to be an η -Ricci soliton in M^4 ; and in particular, if $b = 0$, (g, ξ, a) is a Ricci soliton [13] and it is called shrinking, steady or expanding according as a is negative, zero or positive, respectively [9].

Writing explicitly the Lie derivative $(L_{\xi}g)(X, Y)$ we get

$$(1.2) \quad (L_{\xi}g)(X, Y) = g(\nabla_X \xi, Y) + g(X, \nabla_Y \xi)$$

and from (1.1) we obtain:

$$(1.3) \quad S(X, Y) = -ag(X, Y) - b\eta(X)\eta(Y) - \frac{1}{2}[g(\nabla_X \xi, Y) + g(X, \nabla_Y \xi)]$$

for any $X, Y \in \chi(M^4)$.

Blaga defined an η -Einstein soliton which is defined as [2]

$$(1.4) \quad L_{\xi}g + 2S + (2a - r)g + 2b\eta \otimes \eta = 0,$$

where g, S, r, ξ, η, a and b have the meaning are already stated. The data (g, ξ, a, b) in (1.4) is said to be an η -Einstein soliton in M^4 ; and in particular, if $b = 0$, (g, ξ, a) is an Einstein soliton [5]. Using (1.2) in (1.4) we get

$$(1.5) \quad S(X, Y) = -(a - \frac{r}{2})g(X, Y) - b\eta(X)\eta(Y) - \frac{1}{2}[g(\nabla_X \xi, Y) + g(X, \nabla_Y \xi)]$$

for any $X, Y \in \chi(M^4)$.

In [24] Siddique studied a conformal η -Ricci soliton which is defined as

$$(1.6) \quad L_\xi g + 2S + [2a - (\phi + \frac{2}{n})]g + 2b\eta \otimes \eta = 0,$$

where ϕ is a time dependent scalar field, n is dimension of the manifold and g, S, ξ, η, a, b have the meaning are already stated. The data (g, ξ, a, b) in (1.6) is said to be a conformal η -Ricci soliton in M^4 ; and in particular, if $b = 0$, (g, ξ, a) is a conformal Ricci soliton [1]. Using (1.2) in (1.6) we get

$$(1.7) \quad \begin{aligned} S(X, Y) = & - [a - \frac{1}{2}(\phi + \frac{1}{2})]g(X, Y) - b\eta(X)\eta(Y) \\ & - \frac{1}{2}[g(\nabla_X \xi, Y) + g(X, \nabla_Y \xi)] \end{aligned}$$

for any $X, Y \in \chi(M^4)$.

In [19, 20] Praveena and Bagewadi studied Ricci solitons and obtained results in almost pseudo symmetric Kähler manifolds. In [25, 26], Venkatesha and Kumara studied conformally flat quasi-Einstein space-times with applications in general relativity and Ricci soliton structure in a perfect fluid space-time whose time like velocity vector field ξ is torse-forming. Blaga [3] investigated that if perfect fluid space-time (M^4, g) is either an η -Ricci soliton or an η -Einstein soliton with $\xi = \text{grad}(f)$, where f is a scalar function, then Laplacian of f can be expressed as a linear combination of the cosmological constant, isotropic pressure, energy density and gravitational constant. Siddiqi and Siddiqui [24] explored if perfect fluid space-time (M^4, g) is a conformal η -Ricci soliton with $\xi = \text{grad}(f)$, where f is a scalar function, then Laplacian of f can be expressed as a linear combination of the cosmological constant, isotropic pressure, energy density, gravitational constant and time-dependent scalar field. Recently, Praveena and Bagewadi [21] studied solitons of an almost pseudo symmetric Kählerian space-time manifold with different curvature tensors. Motivated by the above studies in this paper we study solitons (an η -Ricci soliton, an η -Einstein soliton and a conformal- η -Ricci soliton) of Kählerian Norden space-time manifolds and Bochner curvature tensor in almost pseudo symmetric Kählerian Norden space-time manifolds.

2. Basic properties of Kählerian Norden space-time manifold

A four-dimensional manifold has general relativistic perfect fluid space-time such type of manifold is said to be a Kählerian Norden space-time manifold if it admits Norden metric which satisfies

$$J^2(Z) = -Z, \quad g(JZ, JY) = -g(Z, Y), \quad \text{and} \quad (\nabla_Z J)(Y) = 0,$$

where J is a $(1, 1)$ tensor and g is a pseudo-Riemannian metric. We know that in a Kähler Norden manifold the Riemannian curvature tensor R and Ricci tensor S satisfy [12]

$$(2.1) \quad R(JX, JY, Z, W) = -R(X, Y, Z, W),$$

$$(2.2) \quad S(JZ, JY) = -S(J, Y), \quad S(Z, JY) - S(JZ, Y) = 0,$$

$$(2.3) \quad g(JZ, JY) = -S(J, Y), \quad g(Z, JY) - g(JZ, Y) = 0.$$

Let E_1, E_2, \dots, E_n be an orthonormal frame in a Kähler Norden manifold. Then $g(E_i, E_i) = \dim(M)$ and $g(JE_i, E_i) = 0$.

The scalar curvature r and the $*$ -scalar curvature r^* which are defined as the trace $S(E_i, E_i)$ and $S(JE_i, E_i)$, respectively.

We define the following for almost pseudo symmetric and Bochner curvature tensor in a Kähler Norden manifold. It is similar to Definition 1.1.

Definition 2.1. A Kähler Norden manifold is called an almost pseudo Bochner symmetric manifold if its Bochner curvature tensor D of type $(0,4)$ is not zero and satisfies the condition

$$(2.4) \quad \begin{aligned} (\nabla_X D)(Y, Z, U, V) = & [A(X) + B(X)]D(Y, Z, U, V) \\ & + A(Y)D(X, Z, U, V) + A(Z)D(Y, X, U, V) \\ & + A(U)D(Y, Z, X, V) + A(V)D(Y, Z, U, X), \end{aligned}$$

where A, B are 1-forms (not simultaneously zero) and D is given by [27],

$$(2.5) \quad \begin{aligned} D(X, Y, Z, U) = & R(X, Y, Z, U) - \frac{1}{2n+4}[g(Y, Z)S(X, U) - S(X, Z)g(Y, U) \\ & + g(JY, Z)S(JX, U) - S(JX, Z)g(JY, U) \\ & + S(Y, Z)g(X, U) - g(X, Z)S(Y, U) \\ & + S(JY, Z)g(JX, U) - g(JX, Z)S(JY, U) \\ & - 2S(Y, JX)g(JZ, U) - 2S(JZ, U)g(JX, Y)] \\ & + \frac{r}{(2n+2)(2n+4)}[g(Y, Z)g(X, U) - g(X, Z)g(Y, U) \\ & + g(JY, Z)g(JX, U) - g(JX, Z)g(JY, U) \\ & - 2g(JX, Y)g(JZ, U)]. \end{aligned}$$

Put $X = Y = E_i$ in the above equation we get

$$(2.6) \quad K(Y, Z) = \frac{n}{2n+4}[S(Y, Z) - \frac{r}{2(n+1)}g(Y, Z) - \frac{r^*}{n}g(JY, Z)].$$

We know that the Einstein equation with cosmological constant for the perfect fluid space-time is given by

$$(2.7) \quad S(X, Y) = -(\lambda - \frac{r}{2} - kp)g(X, Y) + k(\sigma + p)\eta(X)\eta(Y),$$

for any $X, Y \in \chi(M^4)$, where p is the isotropic pressure, σ is the energy-density, λ is the cosmological constant, k is the gravitational constant, g is the metric tensor of Minkowski space-time [14], ξ is the velocity vector of the fluid and η is associated 1-form $\eta(\xi) = -1$, S is the Ricci tensor and r is the scalar curvature of g .

Here the Ricci tensor S is a functional combination of g and $\eta \otimes \eta$ and is called quasi-Einstein [6]. Quasi-Einstein manifolds arose during the study of exact solutions of Einstein field equations.

Consider $\{E_i\}_{1 \leq i \leq 4}$ an orthonormal frame field, i.e., $g(E_i, E_j) = \varepsilon_{ij} \delta_{ij}$, $i, j \in \{1, 2, 3, 4\}$ with $\varepsilon_{11} = -1$, $\varepsilon_{ii} = -1$, $i \in \{2, 3, 4\}$, $\varepsilon_{ij} = 0$, $i, j \in \{1, 2, 3, 4\}$, $i \neq j$. Let $\xi = \sum_{i=1}^4 \xi^i E_i$. Then

$$(2.8) \quad -1 = g(\xi, \xi) = \sum_{1 \leq i, j \leq 4} \xi^i \xi^j g(E_i, E_j) = \sum_{i=1}^4 \varepsilon_{ii} (\xi^i)^2,$$

and

$$(2.9) \quad \eta(E_i) = g(E_i, \xi) = \sum_{j=1}^4 \xi^j g(E_i, E_j) = \varepsilon_{ii} \xi^i.$$

Contracting (2.7) and taking into account that $g(\xi, \xi) = -1$, we get:

$$(2.10) \quad r = 4\lambda + k(\sigma - 3p).$$

Substitute above value in equation (2.7), we get:

$$(2.11) \quad S(X, Y) = \left(\lambda + \frac{k(\sigma - p)}{2}\right)g(X, Y) + k(\sigma + p)\eta(X)\eta(Y)$$

for any $X, Y \in \chi(M^4)$.

Example 2.1. A radiation fluid has constant scalar curvature equal to 4λ .

3. Solitons of Kählerian Norden space-time manifold

Now replacing X and Y by JX and JY , respectively, in (2.11) and using equations (2.2) and (2.3) we get

$$(3.1) \quad -S(X, Y) = -\left(\lambda + \frac{k(\sigma - p)}{2}\right)g(X, Y) + k(\sigma + p)\eta(JX)\eta(JY).$$

Adding (3.1) from (2.11), we have

$$k(\sigma + p)[\eta(JX)\eta(JY) + \eta(X)\eta(Y)].$$

Put $Y = \xi$ in above equation we obtained

$$k(\sigma + p)\eta(x) = 0.$$

Since $k \neq 0$ and $\eta(X) \neq 0$, we have

$$\sigma = -p.$$

Now using this in (3.1) we get

$$(3.2) \quad S(X, Y) = (\lambda + \sigma k)g(X, Y).$$

From (3.2) and (1.3) we get

$$(3.3) \quad (\lambda + \sigma k) g(X, Y) = -ag(X, Y) - b\eta(X)\eta(Y) - \frac{1}{2}[g(\nabla_X \xi, Y) + g(X, \nabla_Y \xi)].$$

Multiplying (3.3) by ε_{ii} and summing over i for $X = Y := E_i$ and then using equations (2.8) and (2.9), we get:

$$(3.4) \quad 4a - b = -4(\lambda + \sigma k) - \operatorname{div}\xi.$$

Writing $X = Y = \xi$ in (3.3), we obtain:

$$(3.5) \quad a - b = -(\lambda + \sigma k).$$

Solving (3.4) and (3.5) we have

$$a = -(\lambda + \sigma k) - \frac{\operatorname{div}\xi}{3} \quad \text{and} \quad b = \frac{-\operatorname{div}\xi}{3}.$$

If $b = 0$, then we obtain the Ricci soliton with $a = -(\lambda + \sigma k)$ which is steady if $\sigma = -\frac{\lambda}{k}$, expanding if $\sigma < -\frac{\lambda}{k}$ and shrinking if $\sigma > -\frac{\lambda}{k}$.

Theorem 3.1. *Let (g, ξ, a, b) be an η -Ricci soliton in a Kählerian Norden space-time manifold with $p = -\sigma$ and $b = 0$. Then it is steady if $\sigma = -\frac{\lambda}{k}$, expanding if $\sigma < -\frac{\lambda}{k}$ and shrinking if $\sigma > -\frac{\lambda}{k}$.*

From (3.2) and (1.5) we get

$$(\lambda + \sigma k)g(Y, Z) = -(a - \frac{r}{2})g(Y, Z) - b\eta(Y)\eta(Z) - \frac{1}{2}[g(\nabla_Y\xi, Z) + g(Y, \nabla_Z\xi)],$$

then we write the above equation

$$(3.6) \quad [(\lambda + \sigma k) + (a - \frac{r}{2})]g(Y, Z) + b\eta(Y)\eta(Z) + \frac{1}{2}[g(\nabla_Y\xi, Z) + g(Y, \nabla_Z\xi)] = 0.$$

Multiplying (3.6) by ε_{ii} and contracting over Y and Z and then using equations (2.8), (2.10) and (2.9), we get:

$$(3.7) \quad 4a - b = 4\lambda + 4k\sigma - \operatorname{div}\xi.$$

Writing $Y = Z = \xi$ in (3.6) and using (2.10) we obtain:

$$(3.8) \quad a - b = \lambda + k\sigma,$$

solving (3.7) and (3.8) we get

$$a = \lambda + k\sigma - \frac{\operatorname{div}\xi}{3} \quad \text{and} \quad b = -\frac{\operatorname{div}\xi}{3}.$$

If $b = 0$, then we obtain Einstein soliton with $a = \lambda + k\sigma$ which is steady if $\sigma = -\frac{\lambda}{k}$, expanding if $\sigma > -\frac{\lambda}{k}$ and shrinking if $\sigma < -\frac{\lambda}{k}$.

Theorem 3.2. *Let (g, ξ, a, b) be an η -Einstein soliton in a Kählerian Norden space-time manifold with $p = -\sigma$ and $b = 0$. Then it is steady if $\sigma = -\frac{\lambda}{k}$, expanding if $\sigma > -\frac{\lambda}{k}$ and shrinking if $\sigma < -\frac{\lambda}{k}$.*

From (3.2) and (1.7) we get

$$\begin{aligned} (\lambda + k\sigma)g(Y, Z) = & -[a - \frac{1}{2}(\phi + \frac{1}{2})]g(Y, Z) - b\eta(Y)\eta(Z) \\ & - \frac{1}{2}[g(\nabla_Y\xi, Z) + g(Y, \nabla_Z\xi)], \end{aligned}$$

then we write the above equation

$$(3.9) \quad [(\lambda + k\sigma) + (a - \frac{1}{2}(\phi + \frac{1}{2}))]g(Y, Z) + b\eta(Y)\eta(Z) + \frac{1}{2}[g(\nabla_Y\xi, Z) + g(Y, \nabla_Z\xi)] = 0.$$

Multiplying (3.9) by ε_{ii} and contracting over Y and Z and then using equations (2.8) and (2.9), we get:

$$(3.10) \quad 4a - b = -4(\lambda + k\sigma) + 2\phi + 1 - \text{div}\xi.$$

Writing $Y = Z = \xi$ in (3.9) then we obtain:

$$(3.11) \quad a - b = -(\lambda + k\sigma) + \frac{1}{2}(\phi + \frac{1}{2}),$$

solving (3.10) and (3.11) we get

$$a = -(\lambda + k\sigma) + \frac{1}{2}\phi + \frac{1}{4} - \frac{\text{div}\xi}{3} \quad \text{and} \quad b = -\frac{\text{div}\xi}{3}.$$

If $b = 0$, then we obtain an Einstein soliton with $a = -(\lambda + k\sigma) + \frac{1}{2}\phi + \frac{1}{4}$ which is steady if $\sigma = -\frac{\lambda}{k} + \frac{\phi}{2k} + \frac{1}{4k}$, expanding if $\sigma > -\frac{\lambda}{k} + \frac{\phi}{2k} + \frac{1}{4k}$ and shrinking if $\sigma < -\frac{\lambda}{k} + \frac{\phi}{2k} + \frac{1}{4k}$.

Theorem 3.3. *Let (g, ξ, a, b) be an η -Einstein soliton in a Kählerian Norden space-time manifold with $p = -\sigma$ and $b = 0$. Then it is steady if $\sigma = -\frac{\lambda}{k} + \frac{\phi}{2k} + \frac{1}{4k}$, expanding if $\sigma > -\frac{\lambda}{k} + \frac{\phi}{2k} + \frac{1}{4k}$ and shrinking if $\sigma < -\frac{\lambda}{k} + \frac{\phi}{2k} + \frac{1}{4k}$.*

4. Almost pseudo Bochner symmetric Kählerian Norden space-time manifold

In this section we study solitons of an almost pseudo symmetric Bochner curvature tensor in a Kählerian Norden space-time manifold. Using (2.1), (2.2), and (2.3) in (2.5) we have

$$(4.1) \quad D(JY, JZ, U, V) = -D(Y, Z, U, V).$$

Taking the covariant derivative of (4.1), we get

$$(4.2) \quad (\nabla_X D)(JY, JZ, U, V) = -(\nabla_X D)(Y, Z, U, V).$$

Using (2.4) in (4.2), we get

$$(4.3) \quad -A(Y)D(X, Z, U, V) - D(Z)R(Y, X, U, V) = A(JY)D(X, JZ, U, V) + A(JZ)D(JY, X, U, V).$$

Setting $Z = U = E_i$ in (4.3) then we have

$$-A(Y)K(X, V) + A(D(Y, X)V) = A(JY)K(JX, V) - A(D(JY, X)JV).$$

Again putting $Y = \rho = E_i$ in the above equation we get

$$(4.4) \quad K(X, V) = 0.$$

Using equation (4.4) in (2.6) we obtain

$$(4.5) \quad S(Y, Z) = \frac{r}{10}g(Y, Z) + \frac{r^*}{4}g(JY, Z).$$

From (4.5) and (1.3) we get

$$(4.6) \quad \begin{aligned} \frac{r}{10}g(Y, Z) + \frac{r^*}{4}g(JY, Z) &= -ag(Y, Z) - b\eta(Y)\eta(Z) \\ &\quad - \frac{1}{2}[g(\nabla_Y \xi, Z) + g(Y, \nabla_Z \xi)]. \end{aligned}$$

Multiplying (4.6) by ε_{ii} and summing over i for $Y = Z := E_i$ then using equations (2.8), (2.10) and (2.9), we get:

$$(4.7) \quad 4a - b = \frac{-2[4\lambda + k(\sigma - 3p)]}{5} - \operatorname{div}\xi.$$

Put $X = Y = \xi$ in (4.6) then we obtain:

$$(4.8) \quad a - b = \frac{-[4\lambda + k(\sigma - 3p)]}{10}.$$

Solving (4.7) and (4.8) we get

$$a = \frac{-[4\lambda + k(\sigma - 3p)]}{10} - \frac{\operatorname{div}\xi}{3} \quad \text{and} \quad b = \frac{-\operatorname{div}\xi}{3}.$$

If $b = 0$, then we obtain Ricci soliton $a = \frac{-[4\lambda + k(\sigma - 3p)]}{10}$ which is steady if $p = \frac{4}{3}(\frac{\lambda}{k}) + \frac{\sigma}{3}$, expanding if $p > \frac{4}{3}(\frac{\lambda}{k}) + \frac{\sigma}{3}$ and shrinking if $p < \frac{4}{3}(\frac{\lambda}{k}) + \frac{\sigma}{3}$.

Theorem 4.1. *Let (g, ξ, a, b) be an η -Ricci soliton in an almost pseudo Bochner symmetric Kählerian Norden space-time manifold with $b = 0$. Then it is steady if $p = \frac{4}{3}(\frac{\lambda}{k}) + \frac{\sigma}{3}$, expanding if $p > \frac{4}{3}(\frac{\lambda}{k}) + \frac{\sigma}{3}$ and shrinking if $p < \frac{4}{3}(\frac{\lambda}{k}) + \frac{\sigma}{3}$.*

Remark 4.2. For radiation fluid $\sigma = 3p$ we have $a = -\frac{2\lambda}{5} - \frac{\operatorname{div}\xi}{3}$ and $b = -\frac{\operatorname{div}\xi}{3}$.

From (4.5) and (1.5) we get

$$(4.9) \quad \begin{aligned} \frac{r}{10}g(Y, Z) + \frac{r^*}{4}g(JY, Z) &= -(a - \frac{r}{2})g(Y, Z) - b\eta(Y)\eta(Z) \\ &\quad - \frac{1}{2}[g(\nabla_Y \xi, Z) + g(Y, \nabla_Z \xi)]. \end{aligned}$$

Multiplying (4.9) by ε_{ii} and contracting over Y and Z then using equations (2.8), (2.10) and (2.9), we get:

$$(4.10) \quad 4a - b = \frac{8[4\lambda + k(\sigma - 3p)]}{5} - \operatorname{div}\xi.$$

Setting $Y = Z = \xi$ in (4.9) and using (2.10) we obtain:

$$(4.11) \quad a - b = \frac{2[4\lambda + k(\sigma - 3p)]}{5},$$

solving (4.10) and (4.11) we get

$$a = \frac{2[4\lambda + k(\sigma - 3p)]}{5} - \frac{\operatorname{div}\xi}{3} \quad \text{and} \quad b = -\frac{\operatorname{div}\xi}{3}.$$

If $b = 0$, then we obtain a Einstein soliton with $a = \frac{2[4\lambda + k(\sigma - 3p)]}{5}$ which is steady if $p = \frac{4}{k}(\frac{\lambda}{3}) + \frac{\sigma}{3}$, expanding if $p > \frac{4}{k}(\frac{\lambda}{3}) + \frac{\sigma}{3}$ and shrinking if $p < \frac{4}{k}(\frac{\lambda}{3}) + \frac{\sigma}{3}$.

Theorem 4.3. *Let (g, ξ, a, b) be an η -einstein soliton in an almost pseudo Bochner symmetric Kählerian Norden space-time manifold with $b = 0$. Then it is steady if $p = \frac{4}{3}(\frac{\lambda}{k}) + \frac{\sigma}{3}$, expanding if $p > \frac{4}{3}(\frac{\lambda}{k}) + \frac{\sigma}{3}$ and shrinking if $p < \frac{4}{3}(\frac{\lambda}{k}) + \frac{\sigma}{3}$.*

Remark 4.4. For radiation fluid $\sigma = 3p$ we have $a = \frac{8\lambda}{5} - \frac{\operatorname{div}\xi}{3}$ and $b = -\frac{\operatorname{div}\xi}{3}$.

From (4.5) and (1.7) we get

$$\begin{aligned} \frac{r}{10}g(Y, Z) + \frac{r^*}{4}g(JY, Z) &= -(a - \frac{r}{2})g(Y, Z) - b\eta(Y)\eta(Z) \\ (4.12) \qquad \qquad \qquad &\quad - \frac{1}{2}[g(\nabla_Y \xi, Z) + g(Y, \nabla_Z \xi)]. \end{aligned}$$

Multiplying (4.12) by ε_{ii} and contracting over Y and Z then using equations (2.8), (2.10) and (2.9), we get:

$$(4.13) \qquad 4a - b = \frac{-[4\lambda + k(\sigma - 3p)]}{5} + 2\phi + 1 - \operatorname{div}\xi.$$

Setting $Y = Z = \xi$ in (4.12) and using (2.10) we obtain:

$$(4.14) \qquad a - b = \frac{-[4\lambda + k(\sigma - 3p)]}{10} + \frac{\phi}{2} + \frac{1}{4},$$

solving (4.13) and (4.14) we get

$$a = \frac{-[4\lambda + k(\sigma - 3p)]}{10} + \frac{\phi}{2} + \frac{1}{4} - \frac{\operatorname{div}\xi}{3} \quad \text{and} \quad b = -\frac{\operatorname{div}\xi}{3}.$$

If $b = 0$, then we obtain a conformal Ricci soliton with $a = \frac{-[4\lambda + k(\sigma - 3p)]}{10} + \frac{\phi}{2} + \frac{1}{4}$ which is steady if $p = \frac{4}{k}(\frac{\lambda}{3}) + \frac{\sigma}{3} - \frac{5\phi}{3} - \frac{5}{6}$, expanding if $p > \frac{4}{k}(\frac{\lambda}{3}) + \frac{\sigma}{3} - \frac{5\phi}{3} - \frac{5}{6}$ and shrinking if $p < \frac{4}{k}(\frac{\lambda}{3}) + \frac{\sigma}{3} - \frac{5\phi}{3} - \frac{5}{6}$.

Theorem 4.5. *Let (g, ξ, a, b) be an conformal η -Ricci soliton in an almost pseudo Bochner symmetric Kählerian Norden space-time manifold with $b = 0$. Then it is steady if $p = \frac{-[4\lambda + k(\sigma - 3p)]}{10} + \frac{\phi}{2} + \frac{1}{4}$, expanding if $p > \frac{-[4\lambda + k(\sigma - 3p)]}{10} + \frac{\phi}{2} + \frac{1}{4}$ and shrinking if $p < \frac{-[4\lambda + k(\sigma - 3p)]}{10} + \frac{\phi}{2} + \frac{1}{4}$.*

Remark 4.6. For radiation fluid $\sigma = 3p$ we have $a = \frac{-2\lambda}{5} + \frac{\phi}{2} + \frac{1}{4} - \frac{\operatorname{div}\xi}{3}$ and $b = -\frac{\operatorname{div}\xi}{3}$.

5. Conclusion

It is proved in the theorems of Section 3 solitons of Kählerian Norden space-time manifolds depend on energy density σ , cosmological constant λ and gravitational constant k because energy density is expressed as a linear combination of cosmological constant and gravitational constant. Since a content matter of the fluid is not the pure and perfect fluid is dust which looks isotropic or stars in its rest frame. In modern cosmology, it is considered as a candidate for dark energy, the cause of the acceleration of the expansion of the universe. We also proved in the theorems of Section 4 that solitons of almost pseudo-Bochner symmetric Kählerian Norden space-time manifolds depend on isotropic pressure p , cosmological constant λ , energy density σ and gravitational constant k because isotropic pressure is expressed as a linear combination of cosmological constant, energy density and gravitational constant. Since the content matter of the fluid is viscous and perfect hence it is known as a viscous fluid and is further distinguished as Newtonian fluids if the viscosity of the fluid is constant for a different rate of shear stress concerning time. The matter content of the universe is assumed to perform like a perfect fluid in standard cosmological models. It is concluded that the evolution of the universe depends on Ricci, Einstein, and conformal Ricci solitons.

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