

## A GAP RESULT OF SIMONS' TYPE FOR FREE BOUNDARY CMC- $H$ SURFACES

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ABSTRACT. We provide a gap theorem of Simons' type for free boundary minimal and constant mean curvature surfaces in the unit ball in 3-dimensional Euclidean space.

### 1. Introduction

Let  $B$  be the unit ball centered at the origin in  $\mathbb{R}^3$ . A compact immersed surface  $\Sigma \subset B$  is said to be a free boundary cmc- $H$  surface in the unit ball if the mean curvature  $H$  of  $\Sigma$  in  $\mathbb{R}^3$  is constant and  $\Sigma$  meets  $\partial B$  orthogonally along its boundary  $\partial\Sigma$ . By using the first variation formula, a free boundary cmc- $H$  surface  $\Sigma$  in the unit ball can be characterized as a critical point of area-functional for volume-preserving variations of  $\Sigma$  (resp. for variations of  $\Sigma$  if  $H = 0$ ) satisfying  $\partial\Sigma \subset \partial B$ . In particular, it is called a free boundary minimal surface in the unit ball if  $H = 0$ .

The simplest examples of free boundary cmc- $H$  surfaces are topological disks, equatorial disks and spherical caps. Nitsche [21] marked a turning point in research of free boundary cmc- $H$  surfaces. He proved that the only free boundary cmc- $H$  disks in the unit ball are equatorial disks and spherical caps. Ros-Souam [24] and Souam [28] extended this result to capillary cmc- $H$  disks in the unit ball in  $\mathbb{R}^3$  and free boundary

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Received August 06, 2021; Accepted August, 10, 2021.

2010 Mathematics Subject Classification: Primary 53C20, 53C42; Secondary 53A10.

Key words and phrases: gap theorem, minimal surface, constant mean curvature surface, free boundary.

\*This research was supported by Basic Science Research Program through the National Research Foundation of Korea(NRF) funded by the Ministry of Education (Grant Number: 2017R1D1A1B03036369).

cmc- $H$  disks in geodesic balls in the 3-dimensional space forms, respectively. Recently, Fraser-Schoen [11] generalized Nitsche and Souam's results to free boundary minimal disks in geodesic balls of  $n$ -dimensional space forms.

After the pioneering works [10, 12] by Fraser-Schoen, there has been remarkable growth in the research of free boundary cmc- $H$  surfaces. The critical catenoid is the next simplest example of a free boundary minimal surface in the unit ball. It is the specific scaling of a catenoid to satisfy the free boundary condition. Part of a Delaunay surface is a corresponding example for non-vanishing constant mean curvature. Until that time, these were all known embedded examples of cmc- $H$  surfaces in the unit ball. Currently, a lot of examples of various topology are constructed in some ways (Steklov eigenvalues [12], the min-max construction [6, 15], and the desingularization method [9, 13, 14]). A characterization of the critical catenoid is one of the most interesting problems in this field. Some recent results in this regard are as follows: In [8, 27, 29], the authors computed the Morse index and the nullity of the critical catenoid. Symmetry for a free boundary minimal surface to become the critical catenoid is found in [16, 19]. In relation to the Steklov eigenvalue or Jacobi-Steklov eigenvalue, some characterization results are proved in [12, 30]. In [2, 5], a gap theorem is obtained, about which we will explain more below.

Bringing the focus back to works by Fraser-Schoen, they found that there is a strong relation between free boundary minimal surfaces in the unit ball in  $\mathbb{R}^n$  and the first non-zero eigenvalue, which is called the first Steklov eigenvalue, of the Dirichlet-Neumann map. Such a relevance can also be found in  $\mathbb{S}^n$ : Closed minimal surfaces in  $\mathbb{S}^n$  are related to the first eigenvalue of the Laplacian. Moreover, free boundary minimal surfaces in the unit ball in  $\mathbb{R}^n$  is quite analogous to closed minimal surfaces in  $\mathbb{S}^n$ . For example, Nitsche's result corresponds to the following: The equator is the only immersed minimal surface in  $\mathbb{S}^3$  of genus 0 (see [1]). Such similarity can also be confirmed in some of the recent results mentioned above.

In a celebrated paper [26], Simons proved the following theorem:

**THEOREM (Simons [26]).** Let  $\Sigma$  be a closed minimal hypersurface in  $\mathbb{S}^{n+1}$ . Then

- either  $\Sigma$  is a totally geodesic;
- or  $|A|^2 \equiv n$  on  $\Sigma$ ;
- or  $|A|^2(x) > n$  at some point  $x \in \Sigma$ ,

where  $|A|^2$  is the squared norm of the second fundamental form of  $\Sigma$ .

Remark that if  $|A|^2 < n$ , then  $|A|^2 \equiv 0$  on  $\Sigma$ . Right after, Cherndo Carmo-Kobayashi [7] and Lawson [17] independently proved that if  $|A|^2 \equiv n$  on  $\Sigma$ , then it is a Clifford minimal hypersurface,  $\mathbb{S}^m \left(\sqrt{\frac{m}{n}}\right) \times \mathbb{S}^{n-m} \left(\sqrt{\frac{n-m}{n}}\right)$  for  $1 \leq m \leq n-1$ . Motivated by this result, Ambrozio-Nunes [2] proved the following gap theorem for free boundary minimal surfaces in the unit ball.

**THEOREM** (Ambrozio-Nunes [2]). Let  $\Sigma$  be a compact free boundary minimal surface in the unit ball in  $\mathbb{R}^3$ . Assume that for every point  $x \in \Sigma$ ,

$$|A|^2(x) \langle x, \nu(x) \rangle^2 \leq 2,$$

where  $\nu(x)$  denotes the unit normal vector at the point  $x$  and  $A$  denotes the second fundamental form of  $\Sigma$ . Then

1. either  $|A|^2(x) \langle x, \nu(x) \rangle^2 \equiv 0$  and  $\Sigma$  is an equatorial flat disk;
2. or  $|A|^2(x) \langle x, \nu(x) \rangle^2 = 2$  at some point  $p \in \Sigma$  and  $\Sigma$  is a critical catenoid.

Barbosa-Cavalcante-Pereira [3] extended this result to free boundary cmc- $H$  surfaces in the unit ball as follows.

**THEOREM** (Barbosa-Cavalcante-Pereira [3]). Let  $\Sigma$  be a compact free boundary constant mean curvature surface in the unit ball in  $\mathbb{R}^3$ . Assume for all point  $x \in \Sigma$ ,

$$|\mathring{A}|^2(x) \langle x, \nu(x) \rangle^2 \leq \frac{1}{2} (2 + H \langle x, \nu(x) \rangle)^2,$$

where  $\mathring{A}$  is the traceless second fundamental form of  $\Sigma$ . Then

1. either  $|\mathring{A}|^2(x) \langle x, \nu(x) \rangle^2 \equiv 0$  and  $\Sigma$  is a spherical cap;
2. or equality occurs at some point  $p \in \Sigma$  and  $\Sigma$  is part of a Delaunay surface.

Similar gap theorems hold in some 3-dimensional space different from  $\mathbb{R}^3$ : Li-Xiong [18] obtained a similar gap theorem for free boundary minimal surfaces in geodesic balls of 3-dimensional space forms, and Min-Seo [20] for cmc- $H$  surfaces in a strictly convex domain of a 3-dimensional Riemannian manifold.

The main purpose of this paper is to prove a gap theorem of Simons' type for a free boundary cmc- $H$  surface in the unit ball in 3-dimensional Euclidean space as follows.

**THEOREM** (see Theorem 3.3). Let  $\Sigma$  be a free boundary *cmc-H* surface in the unit ball in  $\mathbb{R}^3$ . Then

- either  $|\mathring{A}|^2 \equiv 0$  and  $\Sigma$  is totally umbilical, i.e.,  $\Sigma$  is an equatorial disk if  $H = 0$  and a spherical cap if  $H \neq 0$ , respectively;
- or  $|\mathring{A}|^2(x) \geq 2H^2 + 4 + 4H\langle x, \nu(x) \rangle$  at some point  $x \in \Sigma$ , furthermore,  $|A|^2(x) > 4$  at some point  $x \in \Sigma$  if  $H = 0$ .

**REMARK.** The author found out about the work by Barbosa-Freitas-Melo-Vitório ([4], Theorem 9). They proved that Theorem 3.3 for a free boundary minimal submanifold  $\Sigma^n$  in  $\mathbb{R}^{n+1}$ , and the results are the same when  $n = 2$ . However the proofs have been obtained independently in different ways.

## 2. Preliminaries

In this section, we begin with some notions. Let  $\Sigma$  be an immersed surface in  $\mathbb{R}^3$ . The second fundamental form of  $\Sigma$  is a symmetric two tensor  $A : T\Sigma \otimes T\Sigma \rightarrow C^\infty(\Sigma)$  defined to be, for all tangent vector fields  $X, Y \in T\Sigma$ ,

$$A(X, Y) = \langle \bar{\nabla}_X Y, \nu \rangle,$$

where  $\langle \cdot, \cdot \rangle$  and  $\bar{\nabla}$  denote the metric and the Riemannian connection on  $\mathbb{R}^3$ , respectively, and  $\nu$  is the unit normal vector field of  $\Sigma$ . Denoted by  $H$  the mean curvature of  $\Sigma$ , that is given by

$$H = \frac{1}{2} \text{trace}(A) = \frac{1}{2} (\lambda_1 + \lambda_2),$$

where  $\lambda_1, \lambda_2$  are the principal curvatures of  $\Sigma$ . If  $H$  is constant on  $\Sigma$ , then  $\Sigma$  is said to be a constant mean curvature surface. To emphasize  $H$  we will call it *cmc-H surface*. In particular, if  $H \equiv 0$  on  $\Sigma$ , then it is said to be a *minimal surface*.

**DEFINITION 2.1.** Let  $B = \{x \in \mathbb{R}^3 : \langle x, x \rangle = 1\}$  be the unit ball centered at the origin in  $\mathbb{R}^3$ . Let  $\Sigma \subset B$  be an immersed surface in the unit ball  $B$  and  $x : \Sigma \rightarrow B$  be the immersion of  $\Sigma$  such that  $x(\text{int}\Sigma) \subset \text{int}B$  and  $x(\partial\Sigma) \subset \partial B$ . Then  $\Sigma$  is called a *free boundary cmc-H surface in the unit ball* if the following conditions hold:

- $H$  is constant on  $\Sigma$ ;
- $\Sigma$  meets  $\partial B$  orthogonally along the boundary  $\partial\Sigma$ .

For later use, we introduce two results were shown by Ros-Vergasta in [25]. Note that they originally considered  $n$ -dimensional free boundary cmc- $H$  hypersurfaces in the unit ball. For the sake of completeness, we describe the proofs for  $n = 2$ . Let  $\Sigma$  be a free boundary cmc- $H$  surface in the unit ball. Let  $\eta$  be the inward pointing unit conormal vector field of  $\partial\Sigma$  in  $\Sigma$ . Free boundary condition implies that  $\eta = -x$  along  $\partial\Sigma$ . Then the geodesic curvature  $\kappa_g$  of  $\partial\Sigma$  with respect to  $\eta$  is obtained as follows (see [25]):

$$\begin{aligned} \kappa_g &= \langle \bar{\nabla}_T T, \eta \rangle \\ &= \langle \bar{\nabla}_T(-\eta), T \rangle \\ &= \langle \bar{\nabla}_T x, T \rangle \\ &= \langle T, T \rangle \\ &= 1, \end{aligned}$$

where  $T$  denotes the unit tangent vector field of  $\partial\Sigma$ . Here, the third equality holds because  $x$  is the position vector.

LEMMA 2.2. *Let  $\Sigma$  be a free boundary cmc- $H$  surface in the unit ball. Then  $\partial\Sigma$  is a line of curvature of  $\Sigma$  and the geodesic curvature of  $\partial\Sigma$  in  $\Sigma$  with respect to the inward pointing unit conormal vector field is equal to 1.*

Remark that the first part of Lemma 2.2 is obtained directly from Joachimsthal's theorem.

LEMMA 2.3 (First Minkowski formula). *Let  $\Sigma$  be a free boundary cmc- $H$  surface in the unit ball. Then*

$$L(\partial\Sigma) = 2 \left( A(\Sigma) + \int_{\Sigma} H \langle x, \nu \rangle dA \right),$$

where  $L(\partial\Sigma)$  and  $A(\Sigma)$  denote the length of  $\partial\Sigma$  and the area of  $\Sigma$ , respectively.

*Proof.* Let  $r$  be the distance function measured from the origin in  $\mathbb{R}^3$ . Restricted to  $\Sigma$ , taking the Laplacian, we have

$$\begin{aligned} \Delta_{\Sigma} r^2 &= \Delta_{\Sigma} \langle x, x \rangle \\ &= 2 \langle \Delta_{\Sigma} x, x \rangle + 2|\nabla x|^2, \end{aligned}$$

where  $\nabla$  and  $\Delta_{\Sigma}$  are the Riemannian connection and the Laplacian of  $\Sigma$ , respectively. Since  $|\nabla x|^2 = 2$  and  $\Delta_{\Sigma} x = 2H\nu$ , the following holds.

$$(2.1) \quad \Delta_{\Sigma} r^2 = 4(1 + H \langle x, \nu \rangle).$$

On the other hand, integrating the left hand side of (2.1) on  $\Sigma$ , we have

$$\begin{aligned}
 \int_{\Sigma} \Delta_{\Sigma} r^2 dA &= \int_{\partial\Sigma} -2r \frac{\partial r}{\partial \eta} ds \\
 &= \int_{\partial\Sigma} 2r \langle \nabla r, x \rangle ds \\
 (2.2) \qquad &= \int_{\partial\Sigma} 2 ds
 \end{aligned}$$

by using the divergence theorem. In the last equality, the facts that  $r = 1$  and  $\nabla r$  is parallel to  $x$  on  $\partial\Sigma$  are used. From (2.1) and (2.2),

$$\begin{aligned}
 L(\partial\Sigma) &= \frac{1}{2} \int_{\Sigma} \Delta_{\Sigma} r^2 dA \\
 &= 2 \int_{\Sigma} (1 + H \langle x, \nu \rangle) dA.
 \end{aligned}$$

We get the conclusion.  $\square$

### 3. A gap theorem of Simons' type

Let  $\Sigma$  be a cmc- $H$  surface in  $\mathbb{R}^3$ . The traceless second fundamental form  $\mathring{A}$  is defined to be

$$\mathring{A} = A - H \circ g_{\Sigma},$$

where  $g_{\Sigma}$  is the induced metric on  $\Sigma$ . The squared norm of the traceless second fundamental form is easily computed in terms of that of the second fundamental form such that

$$|\mathring{A}|^2 = (\lambda_1 - H)^2 + (\lambda_2 - H)^2 = |A|^2 - 2H^2.$$

If  $\Sigma$  is minimal, then  $\mathring{A} = A$ . We say that a point  $p \in \Sigma$  is a *umbilical point* if  $\mathring{A}(p) = 0$ , which is equivalent to  $\lambda_1 = \lambda_2$  at  $p$ . It is well-known that either the set of umbilical points of a cmc- $H$  surface  $\Sigma$  is isolated, or  $\Sigma$  is totally umbilical, i.e., every point of  $\Sigma$  is a umbilical point. Moreover, if  $\Sigma$  is a totally umbilical cmc- $H$  surface in  $\mathbb{R}^3$ , then  $\Sigma$  is part of a totally geodesic plane when  $H = 0$ , or is part of a round sphere when  $H \neq 0$ , respectively. For any free boundary cmc- $H$  surface in the unit ball, the following integral equality holds.

**PROPOSITION 3.1.** *Let  $\Sigma$  be a free boundary cmc- $H$  surface in the unit ball in  $\mathbb{R}^3$ . Then*

$$(3.1) \quad \int_{\Sigma} |\mathring{A}|^2 dA = \int_{\Sigma} (2H^2 + 4(1 + H \langle x, \nu \rangle)) dA - 4\pi\chi(\Sigma),$$

where  $\chi(\Sigma)$  is the Euler characteristic of  $\Sigma$ .

*Proof.* The squared norm of the second fundamental form is given by

$$(3.2) \quad |A|^2 = \lambda_1^2 + \lambda_2^2 = (\lambda_1 + \lambda_2)^2 - 2\lambda_1\lambda_2 = 4H^2 - 2K.$$

From Lemma 2.2 and Lemma 2.3,

$$\int_{\partial\Sigma} \kappa_g ds = L(\partial\Sigma) = 2 \int_{\Sigma} (1 + H\langle x, \nu \rangle) dA.$$

By using the equation (3.2), we obtain

$$\int_{\Sigma} K dA = \frac{1}{2} \int_{\Sigma} (4H^2 - |A|^2) dA = \frac{1}{2} \int_{\Sigma} (2H^2 - |\mathring{A}|^2) dA.$$

Therefore with the aid of the Gauss-Bonnet formula, the following equality holds:

$$\int_{\Sigma} (2H^2 - |\mathring{A}|^2) dA + 4 \int_{\Sigma} (1 + H\langle x, \nu \rangle) dA = 4\pi\chi(\Sigma).$$

Arranging the expression, we get the conclusion. □

**PROPOSITION 3.2.** *Let  $\Sigma$  be a free boundary cmc- $H$  surface in the unit ball in  $\mathbb{R}^3$ . Assume  $|\mathring{A}|^2$  is constant on  $\Sigma$ . Then  $\Sigma$  is totally umbilical.*

*Proof.* The famous Simons' identity for a cmc- $H$  surface in  $\mathbb{R}^3$  (see [22]) is as follows.

$$\Delta_{\Sigma}|\mathring{A}| - \frac{|\nabla|\mathring{A}||^2}{|\mathring{A}|} + (|\mathring{A}|^2 - 2H^2)|\mathring{A}| = 0.$$

If  $|\mathring{A}|^2$  is constant, then  $(|\mathring{A}|^2 - 2H^2)|\mathring{A}| = 0$ . It follows that either  $\Sigma$  is a totally umbilical, or  $K \equiv 0$  and therefore each principal curvature is constant. As consequences,  $\Sigma$  is a right angular cylinder unless it is totally umbilical. But a right angular cylinder does not satisfy the free boundary condition. This proves the Proposition 3.2. □

The main theorem is a gap result for free boundary cmc- $H$  surfaces in the unit ball. It can be thought as that for free boundary cmc- $H$  surfaces analogous to a gap theorem for closed minimal surfaces in  $\mathbb{S}^3$  by Simons. But except a totally umbilical surface,  $|\mathring{A}|^2$  cannot be constant on free boundary cmc- $H$  surfaces in  $\mathbb{R}^3$  unlike as in  $\mathbb{S}^3$ .

**THEOREM 3.3.** *Let  $\Sigma$  be a free boundary cmc- $H$  surface in the unit ball in  $\mathbb{R}^3$ . Then*

- either  $|\mathring{A}|^2 \equiv 0$  and  $\Sigma$  is totally umbilical, i.e.,  $\Sigma$  is an equatorial disk if  $H = 0$  and a spherical cap if  $H \neq 0$ , respectively;
- or  $|\mathring{A}|^2(x) \geq 2H^2 + 4 + 4H\langle x, \nu(x) \rangle$  at some point  $x \in \Sigma$ , furthermore,  $|A|^2(x) > 4$  at some point  $x \in \Sigma$  if  $H = 0$ .

*Proof.* Note that  $\Sigma$  is a surface with boundary. Therefore  $\chi(\Sigma) \leq 1$ . Suppose that  $\chi(\Sigma) = 1$ . Then  $\Sigma$  is a topological disk. Remind that the only free boundary cmc- $H$  surface in the unit ball is part of an equatorial disk or part of a spherical cap by Nitsche [21], and hence  $\mathring{A} \equiv 0$ . Now we may assume that  $\chi(\Sigma) \leq 0$ . From the equation (3.1), an integral inequality holds as follows.

$$(3.3) \quad \int_{\Sigma} |\mathring{A}|^2 dA \geq \int_{\Sigma} (2H^2 + 4 + 4H\langle x, \nu \rangle) dA.$$

Suppose that  $|\mathring{A}|^2(x) < 2H^2 + 4 + 4H\langle x, \nu(x) \rangle$  for any point  $x \in \Sigma$ . Integrating both sides, we have

$$\int_{\Sigma} |\mathring{A}|^2 dA < \int_{\Sigma} (2H^2 + 4 + 4H\langle x, \nu \rangle) dA.$$

Comparing with the inequality (3.3), we get a contradiction. To prove the remaining part, let  $\Sigma$  be a minimal surface. Suppose that  $|A|^2(x) \leq 4$  for all  $x \in \Sigma$ . Then  $|A|^2 \equiv 4$  on  $\Sigma$ . Since  $|A|^2 = 2\lambda_1^2 = 2\lambda_2^2$ , the curvature  $\kappa$  of  $\partial\Sigma$  is given by

$$\kappa^2 = \kappa_n^2 + \kappa_g^2 = \lambda_1^2 + 1 = 3$$

because  $\partial\Sigma$  is a line of curvature of  $\Sigma$ . And therefore, each component of  $\partial\Sigma$  is a circle in a plane which meets  $\Sigma$  at a constant contact angle along  $\partial\Sigma$ . Any immersed minimal surface meets a plane at a constant contact angle along a circle is part of a catenoid (see [23]). But  $|A|^2$  is not constant on a catenoid. It is a contradiction.  $\square$

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