

COMMON FIXED POINTS OF w -COMPATIBLE MAPS IN MODULAR A -METRIC SPACES

ELIF KAPLAN^{a,*} AND SERVET KUTUKCU^b

ABSTRACT. The aim of this paper is to prove a common fixed point theorem for two w -compatible maps in modular A -metric spaces. The main result is also illustrated by an example to demonstrate the degree of validity of our hypothesis.

1. INTRODUCTION

Modular metric spaces are a natural generalization of metric spaces. The introduction of this new concept was given by V. V. Chistyakov [2], [3]. In the last decade, there has been an enormous progress in modular metric.

In 2017, Aydin and Kutukcu [1] introduced a new structure of generalized metric space and called it modular A -metric space.

Now, we give some definitions and results which are used in this paper.

Definition 1.1 ([1]). The modular A -metric on X where X is non-empty is defined by a mapping $A_\lambda : (0, \infty) \times X^n \rightarrow [0, \infty]$ that satisfying following conditions for all $x_i, a \in X$ and $\lambda, \lambda_i > 0$ for $i = \overline{1, n}$:

- (A1) $A_\lambda(x_1, x_2, x_3, \dots, x_{n-1}, x_n) \geq 0$,
- (A2) $A_\lambda(x_1, x_2, x_3, \dots, x_{n-1}, x_n) = 0$ if and only if $x_1 = x_2 = \dots = x_{n-1} = x_n$
- (A3) $A_{\lambda_1 + \lambda_2 + \dots + \lambda_n}(x_1, x_2, x_3, \dots, x_{n-1}, x_n) \leq A_{\lambda_1}(x_1, x_1, \dots, (x_1)_{n-1}, a)$
 $+ A_{\lambda_2}(x_2, x_2, \dots, (x_2)_{n-1}, a)$
 \vdots
 $+ A_{\lambda_n}(x_n, x_n, \dots, (x_n)_{n-1}, a)$

The pair (X, A) is said to be a *modular A -metric space*.

Received by the editors November 03, 2020. Accepted March 11, 2021.

2010 *Mathematics Subject Classification*. 47H10; 54H25.

Key words and phrases. modular A -metric, w -compatible maps, fixed point, generalized metric.

*Corresponding author.

Lemma 1.2 ([1]). *Let (X, A) be a modular A -metric space. If for each $x_1, \dots, x_n \in X$, the mapping $A(\cdot, x_1, x_2, \dots, x_n) : (0, \infty) \rightarrow [0, \infty]$ is continuous, then the following equality is true*

$$A_\lambda(x, x, \dots, x, y) = A_\lambda(y, y, \dots, y, x)$$

for each $x, y \in X$ and $\lambda > 0$.

Theorem 1.3 ([1]). *Let (X, A) be a modular A -metric space and the mapping $A(\cdot, x_1, x_2, \dots, x_n) : (0, \infty) \rightarrow [0, \infty]$ is continuous for each $x_1, x_2, \dots, x_n \in X$. Then, there are the following inequalities such that*

$$A_\lambda(x, x, x, \dots, x, z) \leq (n-1)A_{\frac{\lambda}{n}}(x, x, x, \dots, x, y) + A_{\frac{\lambda}{n}}(z, z, z, \dots, z, y)$$

and

$$A_\lambda(x, x, x, \dots, x, z) \leq (n-1)A_{\frac{\lambda}{n}}(x, x, x, \dots, x, y) + A_{\frac{\lambda}{n}}(y, y, y, \dots, y, z)$$

for each $x, y, z \in X$.

Proposition 1.4 ([1]). *Let (X, A) be a modular A -metric space and the mapping $A(\cdot, x_1, x_2, \dots, x_n) : (0, \infty) \rightarrow [0, \infty]$ is continuous for each $x_1, x_2, \dots, x_n \in X$. Then, the following inequality*

$$A_\lambda(x, x, \dots, x, y) \leq A_{\frac{\lambda}{n}}(x, x, \dots, x, y) \leq A_{\frac{\lambda}{n^2}}(x, x, \dots, x, y)$$

is satisfied for $\frac{\lambda}{n^2} \leq \frac{\lambda}{n} \leq \lambda$.

Proof. If it is taken $a = x$ in the condition (A3) and used the inequality in Theorem (1.3), the following inequality is written:

$$\begin{aligned} A_\lambda(x, x, \dots, x, y) &\leq (n-1)A_{\frac{\lambda}{n}}(x, x, \dots, x, x) + A_{\frac{\lambda}{n}}(y, y, \dots, y, x) \\ &= A_{\frac{\lambda}{n}}(y, y, \dots, y, x) \\ &\leq (n-1)A_{\frac{\lambda}{n^2}}(y, y, \dots, y, y) + A_{\frac{\lambda}{n^2}}(x, x, \dots, x, y) \\ &= A_{\frac{\lambda}{n^2}}(x, x, \dots, x, y) \end{aligned}$$

Thus,

$$A_\lambda(x, x, \dots, x, y) \leq A_{\frac{\lambda}{n}}(x, x, \dots, x, y) \leq A_{\frac{\lambda}{n^2}}(x, x, \dots, x, y)$$

is obtained with Lemma (1.2). □

Example 1.5 ([1]). Let $X = \mathbf{R}$. Define a function $A_\lambda : (0, \infty) \times X^n \rightarrow [0, \infty]$ by

$$\begin{aligned} A_\lambda(x_1, x_2, x_3, \dots, x_{n-1}, x_n) &= \frac{\lambda}{n} |x_1 - x_2| + |x_1 - x_3| + \dots + |x_1 - x_n| \\ &\quad + |x_2 - x_3| + |x_2 - x_4| + \dots + |x_2 - x_n| \\ &\quad \vdots \\ &\quad + |x_{n-2} - x_{n-1}| + |x_{n-2} - x_n| \\ &\quad + |x_{n-1} - x_n| \\ &= \frac{\lambda}{n} \sum_{i=1}^n \sum_{i < j} |x_i - x_j| \end{aligned}$$

for all $\lambda > 0$ and $x_1, x_2, \dots, x_n \in X$.

Then, (X, A) is a usual modular A -metric space on X .

Definition 1.6 ([1]). Let (X, A) be a modular A -metric space and let $x_0 \in X$. Then, for any $r > 0$, the set

$$B_{A_\lambda}(x_0, r) = \{y \in X : A_\lambda(y, y, y, \dots, y, x_0) < r\}$$

is defined as an open ball with center x_0 and radius r .

Definition 1.7 ([1]). Let (X, A) be a modular A -metric space and $Y \subset X$.

- (1) If there exists a $r > 0$ such that $B_{A_\lambda}(x, r) \subset Y$ for each $x \in Y$ and $\lambda > 0$, then Y is called be an *open set*.
- (2) Let

$$\tau_A := \{Y \subset X : x \in Y \text{ iff there exists a } r > 0 \text{ such that } B_{A_\lambda}(x, r) \subset Y\}.$$

In this case, (X, τ_A) is a topological space.

Theorem 1.8 ([1]). Let A be a modular A -metric on X . In this case, (X, τ) is a Hausdorff space.

Definition 1.9 ([1]). Let A be a modular A -metric on X , $\{x_k\}_{k \in \mathbf{N}} \subset X$ and $x \in X$.

- (1) $\{x_k\}$ converges to x if $A_\lambda(x_k, x_k, x_k, \dots, x_k, x) \rightarrow 0$ as $k \rightarrow \infty$ for all $\lambda > 0$. In other words, for each $\varepsilon > 0$, there exists a natural number $k_0(\varepsilon) \in \mathbf{N}$ such that for all $k \geq k_0$, $A_\lambda(x_k, x_k, x_k, \dots, x_k, x) \leq \varepsilon$.

- (2) $\{x_k\}$ is said to be a *Cauchy sequence* if $A_\lambda(x_k, x_k, x_k, \dots, x_k, x_m) \rightarrow 0$ as $k, m \rightarrow \infty$ for all $\lambda > 0$. In other words, for each $\varepsilon > 0$, there exists a natural number $k_0(\varepsilon) \in \mathbb{N}$ such that for all $k, m \geq k_0$,

$$A_\lambda(x_k, x_k, x_k, \dots, x_k, x_m) \leq \varepsilon.$$

- (3) (X, A) is said to be *complete modular A -metric space* if every Cauchy sequence in X is convergent.

Theorem 1.10 ([1]). *Let A be a modular A -metric on X . If the sequence $\{x_k\}_{k \in \mathbb{N}} \in X$ converges to x in X , in this case x is unique.*

Theorem 1.11 ([1]). *Let A be a modular A -metric on X . If $\{x_k\}_{k \in \mathbb{N}} \subset X$ is a convergent sequence in X , then $\{x_k\}_{k \in \mathbb{N}}$ is a Cauchy sequence.*

2. w -COMPATIBLE MAPS IN MODULAR A -METRIC SPACES

In 1986, Jungck [4] introduced the concept of compatible maps in metric spaces as follows:

Definition 2.1. Let (M, d) be a metric space and $f, g : M \rightarrow M$. The mappings f and g are said to be *compatible* if $\lim_{k \rightarrow \infty} d(fgx_k, gfx_k) = 0$, whenever $\{x_k\}$ is a sequence in M such that $\lim_{k \rightarrow \infty} fx_k = \lim_{k \rightarrow \infty} gx_k = z$ for some $z \in M$.

In modular A -metric spaces, the notion of w -compatible maps is given as follows:

Definition 2.2 ([5]). *Let M and N be two self maps on a modular A -metric space (X, A) . If*

$$\lim_{k \rightarrow \infty} A_\lambda(MNx_k, \dots, MNx_k, NMx_k) = 0$$

where $\{x_k\}$ is a sequence in X which satisfies $\lim_{k \rightarrow \infty} Mx_k = \lim_{k \rightarrow \infty} Nx_k = t$ for some point $t \in X$ and $\lambda > 0$, the maps M and N are said to be *w -compatible*.

Example 2.3. Let $X = \mathbf{R}$ and A be a function on X defined by

$$A_\lambda(x_1, x_2, \dots, x_n) = \frac{\lambda}{n} \sum_{i=1}^n \sum_{j=i+1}^n |x_i - x_j|$$

for all $\lambda > 0$ and $x_1, x_2, \dots, x_n \in X$. Then, (X, A) is a modular A -metric space. Let M and N be two self maps defined on X by $M(x) = x^2$ and $N(x) = x^3$ for each $x \in \mathbf{R}$. Take $\{x_k\}$ such that $\{x_k\} = \frac{1}{k}$, $k = 1, 2, \dots$. In this case, the maps M and N are w -compatible maps.

Theorem 2.4. *Let (X, A) be a complete modular A -metric space. Let T and S be maps from X into itself such that*

- (1) $T(X) \subset S(X)$
- (2) T or S is continuous
- (3) $A_\lambda(Tx_1, Tx_2, \dots, Tx_k) \leq qA_\lambda(Sx_1, Sx_2, \dots, Sx_k)$ for each $x_1, x_2, \dots, x_k \in X$ and $0 \leq q < 1$
- (4) T and S are w -compatible maps.

Then, T and S have a unique common fixed point in X .

Proof. Let x_0 be an arbitrary point in X . We can choose a point x_1 in X such that $Tx_0 = Sx_1$ with $T(X) \subset S(X)$. By generalizing this situation, we can construct a sequence $\{x_{k+1}\}$ in X as follows :

$$y_k = Tx_k = Sx_{k+1}, \quad k = 0, 1, 2, \dots$$

From (3), we have

$$\begin{aligned} & A_\lambda(Tx_k, Tx_k, \dots, Tx_k, Tx_{k+1}) \\ & \leq qA_\lambda(Sx_k, Sx_k, \dots, Sx_k, Sx_{k+1}) \\ & = qA_\lambda(Tx_{k-1}, Tx_{k-1}, \dots, Tx_{k-1}, Tx_k) \\ & \leq q^2A_\lambda(Sx_{k-1}, Sx_{k-1}, \dots, Sx_{k-1}, Sx_k) \\ & = q^2A_\lambda(Tx_{k-2}, Tx_{k-2}, \dots, Tx_{k-2}, Tx_{k-1}) \\ & \quad \vdots \\ & \leq q^k A_\lambda(Sx_1, Sx_1, \dots, Sx_1, Sx_2) \\ & = q^k A_\lambda(Tx_0, Tx_0, \dots, Tx_0, Tx_1) \end{aligned}$$

Letting as $k \rightarrow \infty$, we obtain

$$\lim_{k \rightarrow \infty} A_\lambda(Tx_k, Tx_k, \dots, Tx_{k+1}) \leq \lim_{k \rightarrow \infty} q^k A_\lambda(Tx_0, Tx_0, \dots, Tx_1) = 0.$$

For all $k, m \in \mathbb{N}$ and $k < m$, we have by rectangle inequality that

$$\begin{aligned} & A_\lambda(Tx_k, Tx_k, \dots, Tx_m) \\ & \leq (n-1) \sum_{i=k}^{m-2} A_{\frac{\lambda}{n^{n-2}}} (Tx_i, \dots, Tx_{i+1}) + A_{\frac{\lambda}{n^{n-2}}} (Tx_{m-1}, \dots, Tx_m) \\ & \leq (n-1) \sum_{i=k}^{m-2} q^i A_{\frac{\lambda}{n^{n-2}}} (Tx_0, \dots, Tx_1) + q^{m-1} A_{\frac{\lambda}{n^{n-2}}} (Tx_0, \dots, Tx_1) \end{aligned}$$

$$\begin{aligned}
&\leq (n-1) \left[q^k + q^{k+1} + \dots + q^{m-2} + q^{m-1} \right] A_{\frac{\lambda}{n^{n-2}}} (Tx_0, Tx_0, \dots, Tx_1) \\
&\leq (n-1) q^k \left(\frac{1 - q^{m-k}}{1 - q} \right) A_{\frac{\lambda}{n^{n-2}}} (Tx_0, Tx_0, \dots, Tx_1) \\
&\leq (n-1) \left(\frac{q^k}{1 - q} \right) A_{\frac{\lambda}{n^{n-2}}} (Tx_0, Tx_0, \dots, Tx_1)
\end{aligned}$$

Letting as $k \rightarrow \infty$, we have

$$\lim_{k \rightarrow \infty} A_{\lambda} (Tx_k, Tx_k, \dots, Tx_m) \leq \lim_{k \rightarrow \infty} (n-1) \left(\frac{q^k}{1 - q} \right) A_{\frac{\lambda}{n^{n-2}}} (Tx_0, Tx_0, \dots, Tx_1) = 0.$$

Thus, $\{Tx_k\}$ is a Cauchy sequence in X . Since (X, A) is complete modular A -metric space, it has a limit in X such that

$$\lim_{k \rightarrow \infty} y_k = \lim_{k \rightarrow \infty} Tx_k = \lim_{k \rightarrow \infty} Sx_{k+1} = z.$$

Since the maps T or S is continuous (assume that S is continuous), $\lim_{k \rightarrow \infty} STx_k = Sz$. Further, the maps S and T are w -compatible, therefore

$$\lim_{k \rightarrow \infty} A_{\lambda} (STx_k, \dots, STx_k, TSx_k) = 0$$

implies $\lim_{k \rightarrow \infty} TSx_k = Sz$. From (3), we have

$$\begin{aligned}
A_{\lambda} (Sz, \dots, Sz, z) &= A_{\lambda} (TSx_k, \dots, TSx_k, Tx_k) \\
&\leq qA_{\lambda} (SSx_k, \dots, SSx_k, Sx_k).
\end{aligned}$$

Proceeding limit as $k \rightarrow \infty$, we have $Sz = z$. Again by (3), we obtain

$$A_{\lambda} (Tx_k, \dots, Tx_k, Tz) \leq qA_{\lambda} (Sx_k, \dots, Sx_k, Sz)$$

and taking limit as $k \rightarrow \infty$, we have $z = Tz$. Thus, we have $Tz = Sz = z$ and z is a common fixed point of T and S .

Finally, the uniqueness of z as the common fixed point of T and S shows easily as follows :

Suppose that $z_1 (\neq z)$ be another common fixed point of T and S . Then,

$$\begin{aligned}
A_{\lambda} (z, z, \dots, z, z_1) &= A_{\lambda} (Tz, Tz, \dots, Tz, Tz_1) \leq qA_{\lambda} (Sz, Sz, \dots, Sz, Sz_1) \\
&= qA_{\lambda} (z, z, \dots, z, z_1) \\
&< A_{\lambda} (z, z, \dots, z, z_1)
\end{aligned}$$

for $0 \leq q < 1$, so this is a contradiction. Therefore, $z = z_1$. Hence, the common fixed point of T and S is unique. \square

Example 2.5. Let $X = [-1, 1]$ and define $A_\lambda : (0, \infty) \times X^n \rightarrow [0, \infty]$ as follows :

$$A_\lambda(x_1, x_2, \dots, x_n) = \frac{\lambda}{n} \sum_{i=1}^n \sum_{j=i+1}^n |x_i - x_j|$$

for all $x_1, x_2, \dots, x_n \in X$ and all $\lambda > 0$. Clearly, (X, A) is a modular A -metric space. Let T and S be maps from X into itself defined as $T(x) = \frac{x}{7}$ and $S(x) = \frac{x}{3}$ for all $x \in X$. Then,

$$T(X) = \left[-\frac{1}{7}, \frac{1}{7}\right] \subset \left[-\frac{1}{3}, \frac{1}{3}\right] = S(X)$$

and the maps T, S are continuous. Also,

$$A_\lambda(Tx_1, Tx_2, \dots, Tx_n) \leq qA_\lambda(Sx_1, Sx_2, \dots, Sx_n)$$

holds for all $\overline{x_1, x_n} \in X$ and $\frac{3}{7} \leq q < 1$. Moreover, the maps T and S are w -compatible since

$$\lim_{k \rightarrow \infty} A_\lambda(TSx_k, \dots, TSx_k, STx_k) = 0$$

where $\{x_k\} = \frac{1}{k}$ is a sequence for $k = 1, 2, \dots$ in X such that

$$\begin{aligned} \lim_{k \rightarrow \infty} Sx_k &= \lim_{k \rightarrow \infty} \frac{1}{3k} = 0 \\ \lim_{k \rightarrow \infty} Tx_k &= \lim_{k \rightarrow \infty} \frac{1}{7k} = 0 \end{aligned}$$

for $0 \in X$. Thus, 0 is the unique common fixed point of T and S .

ACKNOWLEDGMENT

The referees have reviewed the paper very carefully. The authors express their deep thanks for the comments.

REFERENCES

1. E. Aydin & S. Kutukcu: Modular A -metric spaces. *Journal of Science and Arts* **17** (2017), no. 3, 423-432.
2. V.V. Chistyakov: Modular metric spaces, I: Basic concepts. *Nonlinear Analysis: Theory, Methods and Applications* **72** (2010), no. 1, 1-14.
3. _____: Modular metric spaces, II: Application to superposition operators. *Nonlinear Analysis: Theory, Methods and Applications* **72** (2010), no. 1, 15-30.
4. G. Jungck: Compatible mappings and common fixed points. *International Journal of Mathematics and Mathematical Sciences* **9** (1986), no. 4, 771-779.
5. E. Kaplan, S. Kutukcu: w -Compatible Maps in Modular A -Metric Spaces. submitted.

^aDEPARTMENT OF MATHEMATICS, FACULTY OF SCIENCE AND ARTS, ONDOKUZ MAYIS UNIVERSITY,
SAMSUN, TURKEY

Email address: elifaydinkaplan@gmail.com

^bDEPARTMENT OF MATHEMATICS, FACULTY OF SCIENCE AND ARTS, ONDOKUZ MAYIS UNIVERSITY,
SAMSUN, TURKEY

Email address: skutukcu@omu.edu.tr