# EXISTENCE AND UNIQUENESS RESULTS FOR SYSTEM OF FRACTIONAL DIFFERENTIAL EQUATIONS WITH INITIAL TIME DIFFERENCE 

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#### Abstract

Existence and uniqueness results for solutions of system of Riemann-Liouville (R-L) fractional differential equations with initial time difference are obtained. Monotone technique is developed to obtain existence and uniqueness of solutions of system of R-L fractional differential equations with initial time difference.


## 1. Introduction

Theory of fractional differential equations [7, 9, 17] parallel to the wellknown theory of ordinary differential equations [5, 6] has been attracted researchers. Due to wide range of applications of fractional calculus in sciences, engineering, nature and social sciences numerous methods of solving fractional differential equations are developed [11, 12]. Lakshmikantham et al. [8] studied

[^0]local and global existence results for solutions of Riemann-Liouville fractional differential equations. Monotone iterative method for Riemann-Liouville fractional differential equations with initial conditions is studied by McRae [10]. Devi obtained [1] the general monotone method for periodic boundary value problem of Caputo fractional differential equations. The Caputo fractional differential equation with periodic boundary conditions have been studied in $[2,3]$ and developed monotone method for the problem. Existence and uniqueness of solution of Riemann-Liouville fractional differential equation with integral boundary conditions is proved in $[14,15]$.

Recently, initial value problems involving Riemann-Liouville fractional derivative was studied by authors [4, 16]. Yaker et al. studied existence and uniqueness of solutions of fractional differential equations with initial time difference for locally Holder continuous functions [18]. Authors have generalized these results for the class of continuous functions [13].

Monotone iterative technique is a powerful technique to study qualitative properties of solutions such as existence and uniqueness of solutions of fractional differential equations. As population models, pharmacodynamic models and economic models etc.are governed by system of fractional differential equations many researchers attracted towards such models and studied existence and uniqueness of solutions of system of fractional differential equations. This motivates us to study system of nonlinear fractional differential equations with initial time difference.

In this paper, we consider the system of Riemann-Liouville fractional differential equations with initial time difference when the function on the right hand side is quasi-monotone non-decreasing and construct two monotone convergent sequences to obtain existence and uniqueness of solution for the nonlinear system.

The paper is organized as follows: In section 2, basic definitions and results are given. Section 3 is devoted to develop monotone technique to study existence and uniqueness results for the considered system. An example is given to validate the obtained results.

## 2. Preliminaries

Basic definitions and results required to develop monotone technique for the system are given in this section.

Definition 2.1. ([17]) The Riemann-Liouville fractional derivative of order $q(0<q<1)$ is defined as

$$
D_{a}^{q} u(t)=\frac{1}{\Gamma(n-q)}\left(\frac{d}{d t}\right)^{n} \int_{a}^{t}(t-\tau)^{n-q-1} u(\tau) d \tau, \quad \text { for } a \leq t \leq b .
$$

Lemma 2.2. ([1]) Let $m \in C_{p}(J, \mathbb{R})$ and for any $t_{1} \in\left(t_{0}, T\right]$ we have $m\left(t_{1}\right)=0$ and $m(t)<0$ for $t_{0} \leq t \leq t_{1}$. Then $D^{q} m\left(t_{1}\right) \geq 0$.

Theorem 2.3. ([14]) Let $v, w \in C_{p}\left(\left[t_{0}, T\right], \mathbb{R}\right), f \in C\left(\left[t_{0}, T\right] \times \mathbb{R}, \mathbb{R}\right)$ and

$$
D^{q} v(t) \leq f(t, v(t)), \quad D^{q} w(t) \geq f(t, w(t)), \quad t_{0}<t \leq T .
$$

Assume $f(t, u)$ satisfy one sided Lipschitz condition

$$
f(t, u)-f(t, v) \leq L(u-v), \quad u \geq v, L>0 .
$$

Then $v^{0}<w^{0}$, where $v^{0}=\left.v(t)\left(t-t_{0}\right)^{1-q}\right|_{t=t_{0}}$ and $w^{0}=\left.w(t)\left(t-t_{0}\right)^{1-q}\right|_{t=t_{0}}$, implies $v(t) \leq w(t), t \in\left[t_{0}, T\right]$.

Corollary 2.4. ([14]) The function $f(t, u)=\sigma(t) u$, where $\sigma(t) \leq L$, is admissible in Theorem 2.3 to yield $u(t) \leq 0$ on $t_{0} \leq t \leq T$.

The results proved by Yakar et al. for the following problem:

$$
\begin{equation*}
D^{q} u(t)=f(t, u),\left.u(t)\left(t-t_{0}\right)^{1-q}\right|_{t=t_{0}}=u^{0}, \tag{2.1}
\end{equation*}
$$

where $0<q<1, f \in C\left[\mathbb{R}^{+} \times \mathbb{R}, \mathbb{R}\right]$, are generalized by authors [13] for the class of continuous functions $u(t)$. These results will be stated in Theorem 2.5 and Theorem 2.6.

The corresponding Volterra fractional integral equation is given by

$$
\begin{equation*}
u(t)=u^{0}(t)+\frac{1}{\Gamma(q)} \int_{t_{0}}^{t}(t-s)^{q-1} f(s, u(s)) d s \tag{2.2}
\end{equation*}
$$

where

$$
u^{0}(t)=\frac{u(t)\left(t-t_{0}\right)^{1-q}}{\Gamma(q)}
$$

and that every solution of (2.2) is a solution of (2.1).
Theorem 2.5. ([13]) Assume that
(i) $v \in C_{p}[J, \mathbb{R}], t_{0}, T>0, w \in C_{p}^{*}\left[J^{*}, \mathbb{R}\right]$ is continuous and $p=1-q$ where

$$
\begin{gathered}
C_{p}(J, \mathbb{R})=\left\{u(t) \in C(J, \mathbb{R}) \text { and } u(t)\left(t-t_{0}\right)^{p} \in C(J, \mathbb{R})\right\}, \\
C_{p}^{*}\left(J^{*}, \mathbb{R}\right)=\left\{u(t) \in C\left(J^{*}, \mathbb{R}\right) \text { and } u(t)\left(t-\tau_{0}\right)^{p} \in C\left(J^{*}, \mathbb{R}\right)\right\}, \\
f \in C\left[\left[t_{0}, \tau_{0}+T\right] \times \mathbb{R}, \mathbb{R}\right], J=\left[t_{0}, t_{0}+T\right], J^{*}=\left[\tau_{0}, \tau_{0}+T\right] \text { and } \\
D^{q} v(t) \leq f(t, v(t)), \quad t_{0} \leq t \leq t_{0}+T, \\
D^{q} w(t) \geq f(t, w(t)), \quad \tau_{0} \leq t \leq \tau_{0}+T, \\
\quad v^{0} \leq u^{0} \leq w^{0}, \\
\text { where } v^{0}=\left.v(t)\left(t-t_{0}\right)^{1-q}\right|_{t=t_{0}}, w^{0}=\left.w(t)\left(t-\tau_{0}\right)^{1-q}\right|_{t=\tau_{0}},
\end{gathered}
$$

(ii) $f(t, u)$ satisfies Lipschitz condition:

$$
f(t, u)-f(t, v) \leq L[u-v], \text { for } u \geq v, \text { and } L \geq 0
$$

(iii) $\tau_{0}>t_{0}$ and $f(t, u)$ is nondecreasing in $t$ for each $u$.

Then we have
(a) $v(t) \leq w(t+\eta), t_{0} \leq t \leq t_{0}+T$,
(b) $v(t-\eta) \leq w(t), \tau_{0} \leq t \leq \tau_{0}+T$, where $\eta=\tau_{0}-t_{0}$.

Theorem 2.6. ([13]) Assume that
(i) Assumption (i) of Theorem 2.5 holds.
(ii) $f(t, u)$ is nondecreasing in $t$ for each $u$ and $v(t) \leq w(t+\eta)$, $t_{0} \leq t \leq t_{0}+T$, where $\eta=\tau_{0}-t_{0}$.
Then there exists a solution $u(t)$ of (2.1) with $u^{0}=\left.u(t)\left(t-t_{0}\right)^{1-q}\right|_{t=t_{0}}$ satisfying $v(t) \leq u(t) \leq w(t+\eta)$ on $\left[t_{0}, t_{0}+T\right]$.

In this paper, we develop monotone technique coupled with lower and upper solutions for the class of continuous functions for the following system of Riemann-Liouville fractional differential equations with initial time difference and obtain existence and uniqueness of solution for the system using monotone technique.

$$
\begin{array}{ll}
D^{q} u_{1}(t)=f_{1}\left(t, u_{1}(t), u_{2}(t)\right), & \left.u_{1}(t)\left(t-t_{0}\right)^{1-q}\right|_{t=t_{0}}=u_{1}^{0}, \\
D^{q} u_{2}(t)=f_{2}\left(t, u_{1}(t), u_{2}(t)\right), & \left.u_{2}(t)\left(t-\tau_{0}\right)^{1-q}\right|_{t=t_{0}}=u_{2}^{0}, \tag{2.3}
\end{array}
$$

where $t \in J=\left[t_{0}, t_{0}+T\right] \quad f_{1}, f_{2}$ in $C\left(J \times \mathbb{R}^{2}, \mathbb{R}\right), 0<q<1$.
Definition 2.7. A pair of functions $v=\left(v_{1}, v_{2}\right)$ and $w=\left(w_{1}, w_{2}\right)$ in $C_{p}\left(J, \mathbb{R}^{2}\right)$, $p=1-q$ are said to be ordered lower and upper solutions $\left(v_{1}, v_{2}\right) \leq\left(w_{1}, w_{2}\right)$ of the problem (2.3) if

$$
D^{q} v_{i}(t) \leq f_{i}\left(t, v_{1}(t), v_{2}(t)\right),\left.\quad v_{i}(t)\left(t-t_{0}\right)^{1-q}\right|_{t=t_{0}}=v_{i}^{0}
$$

and

$$
D^{q} w_{i}(t) \geq f_{i}\left(t, w_{1}(t), w_{2}(t)\right),\left.\quad w_{i}(t)\left(t-\tau_{0}\right)^{1-q}\right|_{t=\tau_{0}}=w_{i}{ }^{0} .
$$

Definition 2.8. A function $f_{i}=f_{i}\left(t, u_{1}, u_{2}\right)$ in $C\left(J \times \mathbb{R}^{2}, \mathbb{R}\right)$ is said to be quasi-monotone non-decreasing if

$$
\begin{gathered}
f_{i}\left(t, u_{1}(t), u_{2}(t)\right) \leq f_{i}\left(t, v_{1}(t), v_{2}(t)\right) \quad \text { if } \quad u_{i}=v_{i} \quad \text { and } \quad u_{i} \leq v_{j}, \\
\\
i \neq j, i=j=1,2 .
\end{gathered}
$$

Definition 2.9. A function $f_{i}=f_{i}\left(t, u_{1}, u_{2}\right)$ in $C\left(J \times \mathbb{R}^{2}, \mathbb{R}\right)$ is said to be quasi-monotone non-increasing if

$$
\begin{gathered}
f_{i}\left(t, u_{1}(t), u_{2}(t)\right) \geq f_{i}\left(t, v_{1}(t), v_{2}(t)\right) \quad \text { if } \quad u_{i}=v_{i} \quad \text { and } \quad u_{i} \leq v_{j} \\
\\
i \neq j, \quad i=j=1,2
\end{gathered}
$$

## 3. Existence and uniqueness results

This section is devoted to develop monotone technique for system of RiemannLiouville fractional differential equations with initial time difference and obtain existence and uniqueness of solution of the problem (2.3).

Theorem 3.1. Assume that
$\left(E_{1}\right) v=\left(v_{1}, v_{2}\right) \in C_{p}[J, \mathbb{R}], t_{0}, T>0$ and $w=\left(w_{1}, w_{2}\right) \in C_{p}^{*}\left[J^{*}, \mathbb{R}\right]$ are continuous functions and $p=1-q$, where

$$
\begin{gathered}
C_{p}\left(J, \mathbb{R}^{2}\right)=\left\{u(t) \in C\left(J, \mathbb{R}^{2}\right) \text { and } u(t)\left(t-t_{0}\right)^{p} \in C\left(J, \mathbb{R}^{2}\right)\right\}, \\
C_{p}^{*}\left(J^{*}, \mathbb{R}^{2}\right)=\left\{u(t) \in C\left(J^{*}, \mathbb{R}^{2}\right) \text { and } u(t)\left(t-\tau_{0}\right)^{p} \in C\left(J^{*}, \mathbb{R}^{2}\right)\right\}, \\
f_{i} \in C\left[\left[t_{0}, t_{0}+T\right] \times \mathbb{R}^{2}, \mathbb{R}\right], \quad J=\left[t_{0}, t_{0}+T\right], J^{*}=\left[\tau_{0}, \tau_{0}+T\right] \text { and } \\
D^{q} v(t) \leq f_{i}\left(t, v_{1}(t), v_{2}(t)\right), \quad t_{0} \leq t \leq t_{0}+T, \\
D^{q} w(t) \geq f_{i}\left(t, w_{1}(t), w_{2}(t)\right), \quad \tau_{0} \leq t \leq \tau_{0}+T, \\
v^{0} \leq u^{0} \leq w^{0}, \\
\text { for } v^{0}=\left.v(t)\left(t-t_{0}\right)^{1-q}\right|_{t=t_{0}} \text { and } w^{0}=\left.w(t)\left(t-\tau_{0}\right)^{1-q}\right|_{t=\tau_{0}},
\end{gathered}
$$

$\left(E_{2}\right) f_{i}\left(t, u_{1}, u_{2}\right)$ is quasi-monotone nondecreasing in $t$ for each $u_{i}$ and $v(t) \leq w(t+\eta), t_{0} \leq t \leq t_{0}+T$, where $\eta=\tau_{0}-t_{0}$,
( $E_{3}$ ) $f_{i}$ satisfies one-sided Lipschitz condition,
$f_{i}\left(t, u_{1}, u_{2}\right)-f_{i}\left(t, \bar{u}_{1}, \bar{u}_{2}\right) \geq-M_{i}\left[u_{i}-\bar{u}_{i}\right]$, for $\bar{u}_{i} \leq u_{i}, M_{i} \geq 0$.
Then there exist monotone sequences $\left\{v^{n}(t)\right\}$ and $\left\{w^{n}(t)\right\}$ such that

$$
v^{n}(t) \rightarrow v(t)=\left(v_{1}, v_{2}\right) \quad \text { and } \quad w^{n}(t) \rightarrow w(t)=\left(w_{1}, w_{2}\right) \text { as } n \rightarrow \infty,
$$

where $v(t)$ and $w(t)$ are minimal and maximal solutions of the problem (2.3), respectively.

Proof. Let $w_{i 0}(t)=w_{i}(t+\eta)$ and $v_{i 0}(t)=v_{i}(t) i=1,2$ for $t_{0} \leq t \leq t_{0}+T$, where $\eta=\tau_{0}-t_{0}$. Since $f_{i}\left(t, u_{1}, u_{2}\right)$ is nondecreasing in $t$ for each $u_{i}$ we have

$$
D^{q} w_{i 0}(t)=D^{q} w_{i}(t+\eta) \geq f_{i}\left(t+\eta, w_{1}(t+\eta), w_{2}(t+\eta)\right) \geq f_{i}\left(t, w_{1}(t), w_{2}(t)\right)
$$

and
$w_{i 0}^{0}=\left.w_{i 0}(t)\left(t-\tau_{0}\right)^{1-q}\right|_{t=\tau_{0}}=\left.w_{i}(t+\eta)\left(t-\tau_{0}\right)^{1-q}\right|_{t=\tau_{0}}=\left.w_{i}(t)\left(t-\tau_{0}\right)^{1-q}\right|_{t=\tau_{0}}=w^{0}$.

Also,

$$
D^{q} v_{i 0}(t)=D^{q} v_{i}(t) \leq f_{i}\left(t, v_{10}(t), v_{20}(t)\right)
$$

and

$$
v_{i 0}^{0}=\left.v_{i 0}(t)\left(t-t_{0}\right)^{1-q}\right|_{t=t_{0}}=\left.v_{i}(t)\left(t-t_{0}\right)^{1-q}\right|_{t=t_{0}}=v^{0}, v^{0} \leq u^{0} \leq w^{0},
$$

which proves that $v_{0}$ and $w_{0}$ are lower and upper solutions of IVP (2.3) respectively.

For any $\theta(t)=\left(\theta_{1}, \theta_{2}\right)$ in $C_{p}\left(J, \mathbb{R}^{2}\right)$ such that for $\alpha_{10} \leq \theta_{1} \leq \beta_{10}, \alpha_{20} \leq$ $\theta_{2} \leq \beta_{20}$ on $J$, consider the following linear system of fractional differential equations:

$$
\begin{align*}
D^{q} u_{i}(t) & =f_{i}\left(t, \theta_{1}(t), \theta_{2}(t)\right)-M_{i}\left[u_{i}(t)-\theta_{i}(t)\right], \\
u_{i}^{0} & =\left.u_{i}(t)\left(t-t_{0}\right)^{1-q}\right|_{t=t_{0}} . \tag{3.1}
\end{align*}
$$

Since the right hand side of IVP (3.1) satisfies Lipschitz condition, unique solution of IVP (3.1) exists on $J$.

For each $\eta(t)$ and $\mu(t)$ in $C_{p}\left(J, \mathbb{R}^{2}\right)$ such that $v_{i}^{0}(0) \leq \eta_{i}(t), w_{i}^{0}(0) \leq \mu_{i}(t)$, define a mapping $A$ by $A[\eta, \mu]=u(t)$ where $u(t)$ is the unique solution of the problem (3.1).

Firstly, we prove that
$\left(A_{1}\right) v^{0} \leq A\left[v^{0}, w^{0}\right], \quad w^{0} \geq A\left[w^{0}, v^{0}\right]$,
$\left(A_{2}\right) A$ possesses the monotone property on the segment

$$
\left[v^{0}, w^{0}\right]=\left\{(t, u) \in C\left(J, \mathbb{R}^{2}\right): v_{1}^{0} \leq u_{1} \leq w_{1}^{0}, v_{2}^{0} \leq u_{2} \leq w_{2}^{0}\right\} .
$$

Set $A\left[v^{0}, w^{0}\right]=v_{i}^{1}$, where $v_{i}^{1}=\left(v_{1}^{1}, v_{2}^{1}\right)$ is the unique solution of system (3.1) with $\eta_{i}=v_{i}^{0}(t)$. Setting $p_{i}(t)=v_{i}^{0}(t)-v_{i}^{1}(t)$, then we see that

$$
\begin{aligned}
D^{q} p_{i}(t) & =D^{q} v_{i}^{0}(t)-D^{q} v_{i}^{1}(t) \\
& =f_{i}\left(t, v_{1}^{0}(t), v_{2}^{0}(t)\right)-f_{i}\left(t, \theta_{1}^{1}(t), \theta_{2}^{1}(t)\right)+M_{i}\left(v_{i}^{1}(t)-\theta_{i}(t)\right) \\
& \leq-M_{i}\left(v_{i}^{0}(t)-v_{i}^{1}(t)\right)+M_{i}\left(v_{i}^{1}(t)-\theta_{i}(t)\right) \\
& \leq-M_{i}\left[v_{i}^{0}(t)-v_{i}^{1}(t)\right] \\
& \leq-M_{i} p_{i}(t) .
\end{aligned}
$$

By Corollary 2.4, we get $p_{i}(t) \leq 0$ on $0 \leq t \leq T$ and hence $v_{i}^{0}(t)-v_{i}^{1}(t) \leq 0$ which implies $v_{i}^{0} \leq A\left[v^{0}, w^{0}\right]$. Set $A\left[v^{0}, w^{0}\right]=w_{i}^{1}$, where $w_{i}^{1}=\left(w_{1}^{1}, w_{2}^{1}\right)$ is the unique solution of the problem (3.1) with $\mu_{i}=w_{i}^{0}(t)$.

Similarly, by Corollary 2.4, setting $p_{i}(t)=w_{i}^{0}(t)-w_{i}^{1}(t)$, we have $w_{i}^{0} \geq w_{i}^{1}$. Hence $w^{0} \geq A\left[w^{0}, v^{0}\right]$. This proves $\left(A_{1}\right)$. Let $\eta, \beta, \mu \in\left[v^{0}, w^{0}\right]$ with $\eta \leq \beta$. Suppose that $A[\eta, \mu]=u(t), A[\beta, \mu]=v(t)$. Then setting $p_{i}(t)=u_{i}(t)-v_{i},(t)$
we find that $p_{i}(t) \leq 0$ and

$$
\begin{aligned}
D^{q} p_{i}(t)= & D^{q} u_{i}(t)-D^{q} v_{i}(t) \\
= & f_{i}\left(t, \eta_{1}, \eta_{2}\right)-M_{i}\left[u_{i}(t)-\eta_{i}(t)\right]-f_{i}\left(t, \beta_{1}, \beta_{2}\right) \\
& +M_{i}\left[v_{i}(t)-\beta_{i}(t)\right] \\
\leq & -M_{i} p_{i}(t) .
\end{aligned}
$$

As before in $\left(A_{1}\right)$, we have $A[\eta, \mu] \leq A[\beta, \mu]$.
Similarly, if $\eta(t), \gamma(t), \mu(t) \in\left[v^{0}, w^{0}\right]$ satisfying $\gamma(t) \leq \mu(t)$ and $A[\eta, \gamma]=$ $u(t), A[\eta, \mu]=v(t)$ we can prove that $A[\eta, \gamma] \geq A[\eta, \mu]$. Thus the mapping $A$ possesses monotone property on $\left[v^{0}, w^{0}\right]$. Define the sequences

$$
v_{i}^{n}(t)=A\left[v_{i}^{n-1}, w_{i}^{n-1}\right], \quad w_{i}^{n}(t)=A\left[w_{i}^{n-1}, v_{i}^{n-1}\right],
$$

on the segment $\left[v^{0}, w^{0}\right]$ by

$$
\begin{aligned}
D^{q} v_{i}^{n}(t) & =f_{i}\left(t, v_{1}^{n-1}, v_{2}^{n-1}\right)-M_{i}\left[v_{i}^{n}-v_{i}^{n-1}\right],\left.\quad v_{i}^{n}(t)\left(t-t_{0}\right)^{1-q}\right|_{t=t_{0}}=v_{i}^{n 0}, \\
D^{q} w_{i}^{n}(t) & =f_{i}\left(t, w_{1}^{n-1}, w_{2}^{n-1}\right)-M_{i}\left[w_{i}^{n}-w_{i}^{n-1}\right],\left.\quad w_{i}^{n}(t)\left(t-\tau_{0}\right)^{1-q}\right|_{t=\tau_{0}}=w_{i}^{n 0} .
\end{aligned}
$$

From $\left(A_{1}\right)$, we have $v_{i}^{0} \leq v_{i}^{1}, w_{i}^{0} \geq w_{i}^{1}$. To prove $v_{i}^{k} \leq v_{i}^{k+1}, w_{i}^{k} \geq w_{i}^{k+1}$ and $v_{i}^{k} \geq w_{i}^{k}$, define $p_{i}(t)=v_{i}^{k}(t)-v_{i}^{k+1}(t)$ and assume $v_{i}^{k-1} \leq v_{i}^{k}, w_{i}^{k-1} \geq w_{i}^{k}$. Thus

$$
\begin{aligned}
D^{q} p_{i}(t)= & f_{i}\left(t, v_{1}^{k-1}, v_{2}^{k-1}\right)-M_{i}\left[v_{i}^{k}-v_{i}^{k-1}\right] \\
& -\left\{f_{i}\left(t, v_{1}^{k}(t), v_{2}^{k}(t)\right)-M_{i}\left[v_{i}^{k+1}(t)-v_{i}^{k}(t)\right]\right\} \\
\leq & -M_{i}\left[v_{i}^{k-1}-v_{i}^{k}\right]-M_{i}\left[v_{i}^{k}-v_{i}^{k-1}\right]+M_{i}\left[v_{i}^{k+1}(t)-v_{i}^{k}(t)\right] \\
\leq & -M_{i}\left[v_{i}^{k}(t)-v_{i}^{k+1}(t)\right] \\
\leq & -M_{i} p_{i}(t) .
\end{aligned}
$$

It follows from Corollary 2.4 that $p_{i}(t) \leq 0$, which gives $v_{i}^{k}(t) \leq v_{i}^{k+1}(t)$.
Similarly we can prove $w_{i}^{k}(t) \geq w_{i}^{k+1}(t)$ and $v_{i}^{k}(t) \geq w_{i}^{k}(t)$. By induction, it follows that

$$
v_{i}^{0}(t) \leq v_{i}^{1}(t) \leq v_{i}^{2}(t) \leq \ldots \leq v_{i}^{n}(t) \leq w_{i}^{n}(t) \leq w_{i}^{n-1}(t) \leq \ldots \leq w_{i}^{1}(t) \leq w_{i}^{0}(t)
$$

Thus the sequences $\left\{v^{n}(t)\right\}$ and $\left\{w^{n}(t)\right\}$ are bounded from below and bounded from above respectively and monotonically nondecreasing and monotonically nonincreasing on $J$. Hence point-wise limit exist and are given by

$$
\lim _{n \rightarrow \infty} v_{i}^{n}(t)=v_{i}(t), \quad \lim _{n \rightarrow \infty} w_{i}^{n}(t)=w_{i}(t) \text { on } J .
$$

Using corresponding Volterra fractional integral equations

$$
\begin{aligned}
& v_{i}^{n}(t)=v_{i}^{0}+\frac{1}{\Gamma(q)} \int_{0}^{T}(t-s)^{q-1}\left\{f_{i}\left(s, v_{1}^{n}(s), v_{2}^{n}(s)\right)-M_{i}\left[v_{i}^{n}-v_{i}^{n-1}\right]\right\} d s \\
& w_{i}^{n}(t)=w_{i}^{0}+\frac{1}{\Gamma(q)} \int_{0}^{T}(t-s)^{q-1}\left\{f_{i}\left(s, w_{1}^{n}(s), w_{2}^{n}(s)\right)-M_{i}\left[w_{1}^{n}-w_{1}^{n-1}\right]\right\} d s
\end{aligned}
$$

as $n \rightarrow \infty$, we get

$$
\begin{aligned}
& v_{i}(t)=\frac{v_{i}^{0}\left(t-t_{0}\right)^{q-1}}{\Gamma(q)}+\frac{1}{\Gamma(q)} \int_{t_{0}}^{T}(t-s)^{q-1} f_{i}\left(s, v_{1}^{n}(s), v_{2}^{n}(s)\right) d s \\
& w_{i}(t)=\frac{w_{i}^{0}\left(t-\tau_{0}\right)^{q-1}}{\Gamma(q)}+\frac{1}{\Gamma(q)} \int_{\tau_{0}}^{T}(t-s)^{q-1} f_{i}\left(s, w_{1}^{n}(s), w_{2}^{n}(s)\right) d s
\end{aligned}
$$

where $v_{i}^{0}=\left.v_{i}(t)\left(t-t_{0}\right)^{1-q}\right|_{t=t_{0}}, \quad w_{i}^{0}=\left.w_{i}(t)\left(t-\tau_{0}\right)^{1-q}\right|_{t=\tau_{0}}$. It follows that $v(t)$ and $w(t)$ are solutions of system (2.3).

Lastly, we prove $v(t)$ and $w(t)$ are the minimal and maximal solutions of the problem (2.3). Let $u(t)=\left(u_{1}, u_{2}\right)$ be any solution of (2.3) other than $v(t)$ and $w(t)$, so that there exists $k$ such that $v_{i}^{k}(t) \leq u_{i}(t) \leq w_{i}^{k}(t)$ on $J$ and setting $p_{i}(t)=v_{i}^{k+1}(t)-u_{i}(t)$, then we have $p_{i}(t) \leq 0$ and

$$
\begin{aligned}
D^{q} p_{i}(t) & =f_{i}\left(t, v_{1}^{k}, v_{2}^{k}\right)-M_{i}\left[v_{i}^{k+1}-v_{i}^{k}\right]-f_{i}\left(t, u_{1}, u_{2}\right) \\
& \leq-M_{i} p_{i}(t)
\end{aligned}
$$

Thus $v_{i}^{k+1}(t) \leq u_{i}(t)$ on $J$. Since $v_{i}^{0}(t) \leq u_{i}(t)$ on $J$, by induction it follows that $v_{i}^{k}(t) \leq u_{i}(t)$ for all $k$. Similarly, we can prove $u_{i} \leq w_{i}^{k}$ for all $k$ on $J$. Hence $v_{i}^{k}(t) \leq u_{i}(t) \leq w_{i}^{k}(t)$ on $J$. Taking limit as $n \rightarrow \infty$, it follows that $v_{i}(t) \leq u_{i}(t) \leq w_{i}(t)$ on $J$.

Now, we obtain the uniqueness of solution of the problem (2.3) in the following:

Theorem 3.2. Assume that
$\left(U_{1}\right)$ Assumptions $\left(E_{1}\right)$ and $\left(E_{3}\right)$ of Theorem 3.1 hold.
$\left(U_{2}\right) f_{i}=f_{i}\left(t, u_{1}, u_{2}\right)$ satisfies Lipschitz condition (two-sided),

$$
\left|f_{i}\left(t, u_{1}, u_{2}\right)-f_{i}\left(t, \bar{u}_{1}, \bar{u}_{2}\right)\right| \geq-M_{i}\left|u_{i}-\bar{u}_{i}\right|, M_{i} \geq 0
$$

Then the solution of the problem (2.3) is unique.

Proof. It is sufficient to prove $v(t) \geq w(t)$. If $p_{i}(t)=w_{i}(t)-v_{i}(t)$, then $p_{i}(t)=0$ and

$$
\begin{aligned}
D^{q} p_{i}(t) & =D^{q} w_{i}(t)-D^{q} v_{i}(t) \\
& =f_{i}\left(t, w_{1}(t), w_{2}(t)\right)-f_{i}\left(t, v_{1}(t), v_{2}(t)\right) \\
& \leq-M_{i}\left(w_{i}(t)-v_{i}(t)\right) \\
& \leq-M_{i} p_{i}(t) .
\end{aligned}
$$

Thus, by Corollary 2.4, we get $p_{i}(t) \leq 0$ implies $w_{i}(t) \leq v_{i}(t)$. Hence $v(t)=$ $u(t)=w(t)$ is the unique solution of (2.3) on $\left[t_{0}, t_{0}+T\right]$.

Example 3.3. We validate obtained results for the following system of R-L fractional differential equations with initial time difference:

$$
\begin{array}{ll}
D^{q} u_{1}(t)=2 t^{q}(1-t)^{\frac{1}{2}}-\frac{1}{4} u_{1}^{3}+u_{2}, & \left.u_{1}(t)\left(t-t_{0}\right)^{1-q}\right|_{t=t_{0}}=0, \\
D^{q} u_{2}(t)=5 t^{q}(1-t)^{\frac{1}{3}}+u_{1}-\frac{1}{2} u_{2}^{2}, & \left.u_{2}(t)\left(t-t_{0}\right)^{1-q}\right|_{t=t_{0}}=1, \tag{3.2}
\end{array}
$$

where $t \in J=\left[t_{0}, t_{0}+T\right]$. We have

$$
\begin{aligned}
\left|f_{1}\left(t, u_{1}, u_{2}\right)-f_{1}\left(t, \overline{u_{1}}, \overline{u_{2}}\right)\right| & =\left|-\frac{1}{4} u_{1}^{3}+u_{2}-\frac{1}{4}{\overline{u_{1}}}^{3}-\overline{u_{2}}\right| \\
& \leq \frac{1}{4}\left|u_{1}-\overline{u_{1}}\right|
\end{aligned}
$$

and

$$
\begin{aligned}
\left|f_{2}\left(t, u_{1}, u_{2}\right)-f_{2}\left(t, \overline{u_{1}}, \overline{u_{2}}\right)\right| & =\left|u_{1}-\frac{1}{2} u_{2}^{2}-\overline{u_{1}}+\frac{1}{2}{\overline{u_{2}}}^{2}\right| \\
& \leq \frac{1}{2}\left|u_{2}-\overline{u_{2}}\right|
\end{aligned}
$$

Thus, assumptions of the Theorem 3.1 hold with Lipschitz constants $\frac{1}{4}$ and $\frac{1}{2}$. The unique solution $u(t)=\left(u_{1}, u_{2}\right)$ of the system (3.2) exists satisfying $v(t) \leq$ $u(t) \leq w(t)$ where $v(t)=(0,0)$ is lower solution and $w(t)=\left(2 t^{q-1}, 5 t^{q-1}\right)$ is upper solution of the system (3.2).
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