Nonlinear Functional Analysis and Applications Vol. 26, No. 4 (2021), pp. 793-809 ISSN: 1229-1595(print), 2466-0973(online)

https://doi.org/10.22771/nfaa.2021.26.04.09 http://nfaa.kyungnam.ac.kr/journal-nfaa Copyright © 2021 Kyungnam University Press



EXISTENCE AND STABILITY RESULTS OF GENERALIZED FRACTIONAL INTEGRODIFFERENTIAL EQUATIONS

C. Kausika¹, K. Balachandran², N. Annapoorani³ and J. K. Kim⁴

¹Department of Mathematics Bharathiar Univerity, Coimbatore 641 046, India e-mail: kauschellamuthu3@gmail.com

²Department of Mathematics Bharathiar Univerity, Coimbatore 641 046, India e-mail: kb.maths.bu@gmail.com

³Department of Mathematics Bharathiar Univerity, Coimbatore 641 046, India e-mail: pooranimaths@gmail.com

⁴Department of Mathematics Education Kyungnam University, Changwon, Gyeongnam 51767, Korea e-mail: jongkyuk@kyungnam.ac.kr

Abstract. This paper gives sufficient conditions to ensure the existence and stability of solutions for generalized nonlinear fractional integrodifferential equations of order α ($1 < \alpha < 2$). The main theorem asserts the stability results in a weighted Banach space, employing the Krasnoselskii's fixed point technique and the existence of at least one mild solution satisfying the asymptotic stability condition. Two examples are provided to illustrate the theory.

1. INTRODUCTION

During the last decade, with the advent of fractional differential equations as a frontier area of research, different concepts of fractional derivatives and

⁰Received February 19, 2021. Revised April 5, 2021. Accepted April 9, 2021.

⁰2010 Mathematics Subject Classification: 26A33, 34A08, 34A34, 93D20.

 $^{^0{\}rm Keywords}$: Caputo generalized fractional derivative, fractional integrodifferential equation, stability theory, Krasnoselskii's fixed point theorem.

⁰Corresponding author: K. Balachandran(kb.maths.bu@gmail.com).

integrals are being introduced and used by various researchers, for example, Riemann-Lioville, Caputo, Grunwald-Letnikov, Riesz and Hadamard derivatives and integrals [18, 21]. It is known that fractional derivatives essentially capture the non-local nature of the dynamics. However, while dealing with increasingly complex systems, different types of non-locality arise and researchers try to fit in by generalizing the existing fractional derivatives. Almeida et al. [3] introduced a generalized fractional integral and derivative that interpolates the Caputo and Caputo-Hadamard fractional derivatives. Here the kernel is generalized using a parameter ρ that helps in capturing a variety of non-local phenomena and some direct applications found in the literature are image encryption and quantum mechanics related to chaos problems arising in fractional dynamical systems. For more properties of this derivative, we refer the readers to [2, 3, 13].

A variety of literature can be found in discussing the existence, uniqueness and qualitative properties of the fractional integrodifferential equations, for example, see [1, 5, 9, 14, 15]. Stability of these systems plays a crucial part in stabilizability and controllability problems. There are many notions of stability and various methods to study stability problems. We choose the fixed point method to establish stability results since it only requires conditions of averaging nature which is advantageous over other methods using pointwise conditions. Only fewer works are reported using this method, for example, see [4, 16] and references therein. Burton and Zhang [10] generalized Schaefer's and Kranoselskii's fixed point theorems suitable to study fractional differential equations (FDEs). Ge and Kou [12] adopted these fixed point theorems to study the stability of FDEs and Makhlouf et al. [7] followed a similar method to study the existence and stability of generalized FDEs. On the other hand, very recently several researchers investigated the existence of solutions of generalized FDEs and some of the works discussed various notions of stability on generalized fractional differential equations [7, 8, 17, 22, 23, 25].

Motivated by the above works, we study the existence and stability of the following generalized nonlinear fractional integrodifferential equations

$${}^{C}D_{t_{0}^{+}}^{\alpha,\rho}x(t) = f(t,x(t),\int_{t_{0}}^{t}h(t,s,x(s))ds), \quad t \ge t_{0},$$
(1.1)

$$x(t_0) = x_0, \ x'(t_0) = x_1,$$
 (1.2)

where $1 < \alpha < 2, 0 < \rho \neq 1, x_0, x_1 \in \mathbb{R}, I := [t_0, \infty)$ and the functions $f: I \times \mathbb{R} \times \mathbb{R} \to \mathbb{R}$ and $h: I \times I \times \mathbb{R} \to \mathbb{R}$ are continuous with f(t, 0, 0) = 0. The nonlinear function f of this type with integral kernel h occur in mathematical problems concerning electromagnetic waves in dielectric media [24], ruin probabilities in financial risk theory [11], among many more applications found in applied physics.

First the initial value problem (1.1)-(1.2) is converted into an equivalent integral equation which is a sum of two operators. One is a contraction and the other one is compact and hence Krasnoselskii's fixed point theorem is applied. Existence and stability results are established in a weighted Banach space.

The rest of the paper is organized as follows. In Section 2, basic notations, results, lemmas and theorems are stated. The weighted Banach space and modified compactness criterion are given in this section. In Section 3, the main results are presented. Examples are provided in section 4 to validate the theory.

2. Preliminaries

Let us recall some basic definitions from fractional calculus needed for our work. We adopt the definitions and other properties of generalized fractional integrals and derivatives from [3] and [7].

Definition 2.1. (Generalized fractional integral)

Let $f \in L^1[a, b]$. Then the generalized fractional integral of the function f is defined as

$$I_{a^+}^{\alpha,\rho}f(t) = \frac{\rho^{1-\alpha}}{\Gamma(\alpha)} \int_a^t \frac{s^{\rho-1}f(s)}{(t^{\rho}-s^{\rho})^{1-\alpha}} \mathrm{d}s,$$

where a > 0 and $\alpha, \rho > 0$.

Definition 2.2. (Generalized fractional derivative)

Let $f \in AC^{n}[a, b]$. Then the generalized fractional derivative of the function f is defined as

$${}^{C}D_{a^{+}}^{\alpha,\rho}f(t) = \frac{\rho^{\alpha-n+1}}{\Gamma(n-\alpha)} \int_{a}^{t} \frac{s^{(\rho-1)(1-n)}}{(t^{\rho}-s^{\rho})^{\alpha-n+1}} f^{(n)}(s) \mathrm{d}s,$$

where a > 0, $\alpha, \rho > 0$ and n is the smallest integer greater than α .

The relationship between these two fractional operators is the following:

$$^{C}D_{a+}^{\alpha,\rho}f(t) = I_{a+}^{1-\alpha,\rho}\left(t^{1-\rho}\frac{\mathrm{d}}{\mathrm{d}t}f\right)(t).$$

Remark 2.3. ([6])

(i) (Semigroup property) For any continuous function f, the semigroup property for generalized fractional integral operators holds.

$$I_{a^{+}}^{\alpha,\rho}I_{a^{+}}^{\beta,\rho}f(t) = I_{a^{+}}^{\alpha+\beta,\rho}f(t)$$

for $\alpha, \beta > 0$ and $\rho > 0$.

C. Kausika, K. Balachandran, N. Annapoorani and J. K. Kim

(ii) If f is a constant, then the generalized fractional derivative $^{C}D_{a^{+}}^{\alpha,\rho}f(t)=0.$

Lemma 2.4. ([7]) For $1 < \alpha < 2$, the following relationship holds

$${}^{C}D_{a^{+}}^{\alpha,\rho}f(t) = {}^{C}D_{a^{+}}^{\alpha-1,\rho}\left(\int_{a}^{t}s^{1-\rho}f^{(2)}(s)\mathrm{d}s\right)$$

Lemma 2.5. ([7]) Let $u \in C(I, \mathbb{R})$, $1 < \alpha < 2$ and $0 < \rho \neq 1$. Then x is a solution of the initial value problem:

$${}^{C}D_{t_{0}^{+}}^{\alpha,\rho}x(t) = u(t), \quad t \ge t_{0},$$
(2.1)

$$x(t_0) = x_0, \quad x'(t_0) = x_1,$$
 (2.2)

if and only if

$$\begin{aligned} x(t) &= x_0 \left[\left(\frac{t}{t_0} \right)^{1-\rho} - \frac{(1-\rho)t^{1-\rho}}{t_0^{\rho}} \int_{t_0}^t \frac{1}{s^{2-2\rho}} \mathrm{d}s \right] \\ &+ x_1 (tt_0)^{1-\rho} \int_{t_0}^t \frac{1}{s^{2-2\rho}} \mathrm{d}s \\ &+ \rho (1-\rho)t^{1-\rho} \int_{t_0}^t \int_{\tau}^t \frac{1}{s^{2-2\rho}} \frac{x(\tau)}{\tau^{1+\rho}} \mathrm{d}s \ \mathrm{d}\tau \\ &+ \frac{\rho^{2-\alpha}t^{1-\rho}}{\Gamma(\alpha-1)} \int_{t_0}^t \int_{\tau}^t \frac{1}{s^{2-2\rho}} \frac{\tau^{\rho-1}}{(s^{\rho}-\tau^{\rho})^{2-\alpha}} u(\tau) \mathrm{d}s \ \mathrm{d}\tau. \end{aligned}$$
(2.3)

Using the above Lemma 2.5, we define the solution to our initial value problem (1.1)-(1.2) as follows. For simplicity we take $z_x(t) := \int_{t_0}^t h(t, s, x(s)) ds$.

Definition 2.6. The function x is defined as a mild solution of the initial value problem (1.1)-(1.2) if it satisfies

$$\begin{aligned} x(t) &= x_0 \left[\left(\frac{t}{t_0} \right)^{1-\rho} - \frac{(1-\rho)t^{1-\rho}}{t_0^{\rho}} \int_{t_0}^t \frac{1}{s^{2-2\rho}} \mathrm{d}s \right] \\ &+ x_1(tt_0)^{1-\rho} \int_{t_0}^t \frac{1}{s^{2-2\rho}} \mathrm{d}s \\ &+ \rho(1-\rho)t^{1-\rho} \int_{t_0}^t \int_{\tau}^t \frac{1}{s^{2-2\rho}} \frac{x(\tau)}{\tau^{1+\rho}} \mathrm{d}s \ \mathrm{d}\tau \\ &+ \frac{\rho^{2-\alpha}t^{1-\rho}}{\Gamma(\alpha-1)} \int_{t_0}^t \int_{\tau}^t \frac{1}{s^{2-2\rho}} \frac{\tau^{\rho-1}}{(s^{\rho}-\tau^{\rho})^{2-\alpha}} f(\tau, x(\tau), z_x(\tau)) \mathrm{d}s \mathrm{d}\tau. \end{aligned}$$
(2.4)

Definition 2.7. The generalized FDE (1.1) subject to the initial conditions (1.2) is said to be stable in a Banach space \mathbb{E} , if for every $\epsilon > 0$, there exists a $\delta > 0$ (δ depends only on ϵ) such that $|x_0| + |x_1| < \delta$ implies that there exists a mild solution x(t) defined on I which satisfies $||x|| \le \epsilon$.

Let us introduce the following weighted Banach space and establish our stability results in it. Let $0 < \rho \neq 1$, $1 < \alpha < 2$ and $g: I \to \mathbb{R}^+$ be the weight function such that $g(t) \geq t^{\alpha \rho^2 + 3}$ and $g(\frac{t}{s})g(s) \leq g(t)$ for all $t, s \geq t_0$. Let us define the weighted space as

$$\mathbb{E} := \left\{ x \in C(I, \mathbb{R}) : \sup_{t \ge t_0} \frac{|x(t)|}{g(t)} < \infty \right\}.$$

Observe that \mathbb{E} is a Banach space equipped with the norm $||x|| = \sup_{t \ge t_0} \frac{|x(t)|}{g(t)}$. For further details on this Banach space, refer [19]. For any $\epsilon > 0$, let

$$\mathcal{F}(\epsilon) = \{ x \in \mathbb{E} : \|x\| \le \epsilon \}.$$

Lemma 2.8. ([7]) Let $0 < \rho \neq 1$ and $1 < \alpha < 2$. Then for all $t \ge t_0$, there exist $M_1 := M_1(t_0, \alpha, \rho) > 0$, $0 < M_2 := M_2(\rho) < 1$, $M_3 := M_3(\alpha, \rho) > 0$ such that

$$\left|\frac{(\rho-1)t^{1-\rho}}{g(t)}\int_{t_0}^t \frac{1}{s^{2-2\rho}} \mathrm{d}s\right| \le M_1,\tag{2.5}$$

$$\left| \frac{(1-\rho)\rho t^{1-\rho}}{g(t)} \int_{t_0}^t \int_{\tau}^t \frac{1}{s^{2-2\rho}} \frac{x(\tau)}{\tau^{1+\rho}} \mathrm{d}s \, \mathrm{d}\tau \right| \le M_2 ||x||, \tag{2.6}$$

$$\frac{k(t,\tau)}{g(\frac{t}{\tau})} \le M_3 \frac{\tau^{\alpha \rho^2}}{t^{\alpha \rho^2 - \alpha \rho + 1}},\tag{2.7}$$

where

$$k(t,\tau) = \begin{cases} \frac{\rho^{2-\alpha}}{\Gamma(\alpha-1)} \left(\frac{t}{\tau}\right)^{1-\rho} \int_{\tau}^{t} \frac{1}{s^{2-2\rho}} \frac{1}{(s^{\rho}-\tau^{\rho})^{2-\alpha}} \mathrm{d}s, & t-\tau > 0, \\ 0, & t-\tau \le 0. \end{cases}$$

Lemma 2.9. ([20]) Let X be a nonempty closed convex subset of a Banach space $(Y, \|.\|)$. Suppose that A and B map X into Y such that

- (1) $Ax + By \in X$ for all $x, y \in X$,
- (2) A is continuous and AX is contained in a compact set of Y,
- (3) B is a contraction with contraction constant c < 1.

Then there is an $x \in X$ with Ax + Bx = x.

Lemma 2.10. ([19]) Let \mathcal{F} be a subset of the Banach space \mathbb{E} . Then \mathcal{F} is relatively compact in \mathbb{E} if the following conditions are satisfied:

- (1) $\{x(t)/g(t) : x(t) \in \mathcal{F}\}$ is uniformly bounded,
- (2) $\{x(t)/g(t) : x(t) \in \mathcal{F}\}$ is equicontinuous on any compact interval of \mathbb{R}^+ ,
- (3) $\{x(t)/g(t) : x(t) \in \mathcal{F}\}$ is equiconvergent at infinity, that is, for any given $\epsilon > 0$, there exists a $T > t_0$ such that for all $x \in \mathcal{F}(\epsilon)$ and $t_1, t_2 > T$, $|x(t_2)/g(t_2) x(t_1)/g(t_1)| < \epsilon$ holds.

3. Main results

Before proving the main results, let us introduce the following hypotheses:

(H1) There exist constants $\eta_1, \eta_2 > 0$ and a continuous function $\psi : \mathbb{R}^+ \times (0, \eta_1] \times (0, \eta_2] \to \mathbb{R}^+$ such that

$$\frac{|f(t, ug(t), vg(t))|}{g(t)} \le \psi(t, |u|, |v|)$$
(3.1)

for all $t \ge t_0$, $0 < |u| \le \eta_1$, $0 < |v| \le \eta_2$.

(H2) There exists an $L^1([t_0,\infty))$ integrable function $m:[t_0,\infty)\times[t_0,\infty)\to\mathbb{R}$ such that

$$|h(t, s, x(s))| \le m(t, s)|x(s)|$$
(3.2)

and

$$\sup_{t \ge t_0} \int_{t_0}^t m(t,s) \mathrm{d}s < \infty.$$
(3.3)

(H3) There exists a constant $\beta_1 > 0$ such that

$$\sup_{t \ge t_0} \int_{t_0}^t \frac{k(t,\tau)}{g(t/\tau)} \frac{\psi(\tau, r_1, r_2)}{r} \mathrm{d}\tau \le \beta_1 < 1 - M_2$$
(3.4)

holds for every $0 < r_1 \leq \eta_1$ and $0 < r_2 \leq \eta_2$, where $r = \min(r_1, r_2)$, M_2 is as defined in (2.6), $\psi(t, r_1, r_2)$ is nondecreasing in r_1, r_2 for fixed t and $t^{\alpha \rho^2} \psi(t, r_1, r_2) \in L^1([t_0, \infty))$ in t for fixed r_1, r_2 .

Theorem 3.1. Let $1 < \alpha < 2$ and $0 < \rho \neq 1$. Suppose that hypotheses (H1) - (H3) hold. Then

 (i) the generalized nonlinear FDEs (1.1)-(1.2) is stable in the Banach space 𝔅;

(ii) there exists at least one mild solution to the generalized nonlinear FDEs
 (1.1)-(1.2) such that

$$\lim_{t \to \infty} \frac{x(t)}{g(t)} = 0.$$

Proof. (i) Let $0 < \epsilon < \eta_1, \eta_2$ and take $\delta < \frac{(1 - M_2 - \beta_1)\epsilon}{M_4 + M_1(t_0^{-\rho} + t_0^{1-\rho})}$. Let us prove that if $|x_0| + |x_1| < \delta$ then there exists a mild solution x(t) defined on $[t_0, +\infty)$ which satisfies $||x|| \le \epsilon$.

Consider the nonempty closed convex subset

$$\mathcal{F}(\epsilon) = \{ x : x \in \mathbb{E}, \|x\| \le \epsilon \} \subset \mathbb{E},$$

which is also a Banach space.

We define two mappings A, B on $\mathcal{F}(\epsilon)$ as follows:

Obviously, for $x \in \mathcal{F}(\epsilon)$, both Ax and Bx are continuous functions on $[t_0, +\infty)$. By Hypothesis (H2), we see that

$$|z_x(t)| \le \int_{t_0}^t |h(t, s, x(s))| \mathrm{d}s \le \int_{t_0}^t m(t, s) |x(s)| \mathrm{d}s \le c |x(t)|,$$

where $c := \sup_{t \ge t_0} \int_{t_0}^t m(t,s) ds < \infty$. Thus we have

$$||z_x|| \le c||x||. \tag{3.7}$$

Since $\psi(t, r_1, r_2)$ is nondecreasing in r_1, r_2 for fixed t and by (3.1)-(3.4) and (3.7), for any $t \ge t_0$ and $x \in \mathcal{F}(\epsilon)$, we have

$$\begin{aligned} \frac{|Ax(t)|}{g(t)} &= \frac{1}{g(t)} \left| \int_{t_0}^t k(t,\tau) f(\tau, x(\tau), z_x(\tau)) \mathrm{d}\tau \right| \\ &\leq \int_{t_0}^t \frac{k(t,\tau)}{g(t/\tau)} \frac{|f(\tau, x(\tau), z_x(\tau))|}{g(\tau)} \mathrm{d}\tau \\ &\leq \int_{t_0}^t \frac{k(t,\tau)}{g(t/\tau)} \psi\left(\tau, \frac{|x(\tau)|}{g(\tau)}, \frac{|z_x(\tau)|}{g(\tau)}\right) \mathrm{d}\tau \\ &\leq \int_{t_0}^t \frac{k(t,\tau)}{g(t/\tau)} \psi\left(\tau, \epsilon, c\epsilon\right) \mathrm{d}\tau \\ &\leq \beta_1 \min(\epsilon, c\epsilon) \leq \beta_1 \epsilon. \end{aligned}$$

Now,

$$\frac{|Ax(t)|}{g(t)} \le \beta_1 \epsilon < \infty.$$
(3.8)

On the other hand, there exists $M_4 = M_4(t_0, \alpha, \rho)$ such that

$$\frac{(t/t_0)^{1-\rho}}{g(t)} \le \frac{t^{1-\rho}}{t_0^{1-\rho}t^{\alpha\rho^2+3}} \le \frac{1}{t_0^{1-\rho}t^{\alpha\rho^2+\rho+2}} \le \frac{1}{t_0^{\alpha\rho^2+3}} := M_4.$$
(3.9)

By (2.5), (2.6) and (3.9), we see that

$$\frac{|Bx(t)|}{g(t)} \leq \frac{|x_0|}{g(t)} \left| \left(\frac{t}{t_0}\right)^{1-\rho} + \frac{(\rho-1)t^{1-\rho}}{t_0^{\rho}} \int_{t_0}^t \frac{1}{s^{2-2\rho}} ds \right| + \frac{|x_1|}{g(t)} (tt_0)^{1-\rho} \\
\times \int_{t_0}^t \frac{1}{s^{2-2\rho}} ds + \frac{(1-\rho)\rho t^{1-\rho}}{g(t)} \int_{t_0}^t \left[\int_{\tau}^t \frac{1}{s^{2-2\rho}} \frac{|x(\tau)|}{\tau^{1+\rho}} ds \right] d\tau \\
\leq |x_0| \left(M_4 + \frac{1}{t_0^{\rho}} M_1 \right) + |x_1| t_0^{1-\rho} M_1 + M_2 \epsilon < \infty.$$
(3.10)

Then $A\mathcal{F}(\epsilon) \subseteq \mathbb{E}$ and $B\mathcal{F}(\epsilon) \subseteq \mathbb{E}$.

Next, we shall use Lemma 2.9 to prove that there exists at least one fixed point to the operator A + B in $\mathcal{F}(\epsilon)$. For clarity, let us divide the proof into three steps.

Step 1: We will prove that $Ax + By \in \mathcal{F}(\epsilon)$ for all $x, y \in \mathcal{F}(\epsilon)$. Let $x, y \in \mathcal{F}(\epsilon)$, from (3.8) and (3.10), we obtain,

$$\left| \frac{Ax(t) + By(t)}{g(t)} \right| \leq |x_0| (M_4 + t_0^{-\rho} M_1) + |x_1| t_0^{1-\rho} M_1 + M_2 \epsilon + \beta_1 \epsilon$$

$$\leq (M_4 + M_1 (t_0^{-\rho} + t_0^{1-\rho})) \delta + (M_2 + \beta_1) \epsilon \leq \epsilon,$$

which implies that $Ax + By \in \mathcal{F}(\epsilon)$ for all $x, y \in \mathcal{F}(\epsilon)$.

Step 2: We will prove that A is continuous and $A\mathcal{F}(\epsilon)$ is relatively compact in \mathbb{E} . First, we will show that A is continuous. Let $(x_n)_{n \in \mathbb{N}}$ be a sequence such that $x_n \to x$ in $\mathcal{F}(\epsilon)$.

Using (3.1), we get

$$\begin{aligned} \tau^{\alpha\rho^{2}} \frac{|f(\tau, x_{n}(\tau), z_{x_{n}}(\tau)) - f(\tau, x(\tau), z(\tau))|}{g(\tau)} \\ &\leq \tau^{\alpha\rho^{2}} \frac{|f(\tau, x_{n}(\tau), z_{x_{n}}(\tau))| + |f(\tau, x(\tau), z(\tau))|}{g(\tau)} \\ &\leq \tau^{\alpha\rho^{2}} \left(\psi\left(\tau, \frac{|x_{n}(\tau)|}{g(\tau)}, \frac{|z_{x_{n}}(\tau)|}{g(\tau)}\right) + \psi\left(\tau, \frac{|x(\tau)|}{g(\tau)}, \frac{|z(\tau)|}{g(\tau)}\right) \right) \\ &\leq 2\tau^{\alpha\rho^{2}} \psi(\tau, \epsilon, c\epsilon) \in L^{1}([t_{0}, +\infty)). \end{aligned}$$

It follows from (2.7) that for any $t \ge t_0$,

$$\begin{split} \frac{|Ax_{n}(t) - Ax(t)|}{g(t)} \\ &= \frac{1}{g(t)} \left| \int_{t_{0}}^{t} k(t,\tau) [f(\tau, x_{n}(\tau), z_{x_{n}}(\tau)) - f(\tau, x(\tau), z_{x}(\tau))] d\tau \right| \\ &\leq \int_{t_{0}}^{t} \frac{k(t,\tau)}{g(t/\tau)} \frac{|f(\tau, x_{n}(\tau), z_{x_{n}}(\tau)) - f(\tau, x(\tau), z_{x}(\tau))|}{g(\tau)} d\tau \\ &\leq \frac{M_{3}}{t_{0}^{\alpha\rho^{2} - \alpha\rho + 1}} \int_{t_{0}}^{t} \tau^{\alpha\rho^{2}} \frac{|f(\tau, x_{n}(\tau), z_{x_{n}}(\tau)) - f(\tau, x(\tau), z_{x}(\tau))|}{g(\tau)} d\tau \\ &\leq \frac{M_{3}}{t_{0}^{\alpha\rho^{2} - \alpha\rho + 1}} \int_{t_{0}}^{\infty} \tau^{\alpha\rho^{2}} \frac{|f(\tau, x_{n}(\tau), z_{x_{n}}(\tau)) - f(\tau, x(\tau), z_{x}(\tau))|}{g(\tau)} d\tau \end{split}$$

and hence

$$\|Ax_n - Ax\| \le \frac{M_3}{t_0^{\alpha \rho^2 - \alpha \rho + 1}} \int_{t_0}^{\infty} \tau^{\alpha \rho^2} \frac{|f(\tau, x_n(\tau), z_{x_n}(\tau)) - f(\tau, x(\tau), z_x(\tau))|}{g(\tau)} \mathrm{d}\tau.$$

Note that

$$\begin{aligned} |z_{x_n}(t) - z_x(t)| &= \left| \int_{t_0}^t h(t, s, x_n(s)) ds - \int_{t_0}^t h(t, s, x(s)) ds \right| \\ &\leq \int_{t_0}^t (|h(t, s, x_n(s))| - |h(t, s, x(s))|) ds \\ &\leq \int_{t_0}^t m(t, s) \left(|x_n(s)| - |x(s)| \right) ds \\ &\leq c \left(|x_n(t)| - |x(t)| \right) \leq c |x_n(t) - x(t)|. \end{aligned}$$

Hence we see that $|z_{x_n}(\tau) - z_x(\tau)| \le c|x_n(\tau) - x(\tau)|.$

Now we have for any $\tau \geq t_0$,

$$\left|\frac{x_n(\tau) - x(\tau)}{g(\tau)}\right| \le \|x_n - x\|,$$

so $\lim_{n \to \infty} |x_n(\tau) - x(\tau)| = 0$ and similarly $\lim_{n \to \infty} |z_{x_n}(\tau) - z_x(\tau)| = 0$ for all $\tau \ge t_0$. Since we know f is continuous in $[t_0, \infty) \times \mathbb{R} \times \mathbb{R}$, we have

$$\lim_{n \to \infty} \frac{|f(\tau, x_n(\tau), z_{x_n}(\tau)) - f(\tau, x(\tau), z_x(\tau))|}{g(\tau)} = 0 \text{ for all } \tau \ge t_0.$$

Then by dominated convergence theorem, it follows that $||Ax_n - Ax|| \to 0$ as $n \to \infty$. Thus, A is continuous in $\mathcal{F}(\epsilon)$.

Secondly let us prove that $A\mathcal{F}(\epsilon)$ is relatively compact in \mathbb{E} . For all $t \geq t_0$, it follows from (2.7) that there exists a constant $M_3 = M_3(\alpha, \rho)$ such that

$$\frac{k(t,\tau)}{g(t/\tau)} \le M_3 \frac{\tau^{\alpha \rho^2}}{t^{\alpha \rho^2 - \alpha \rho + 1}}.$$

Moreover, for any $T \ge t_0$, the function $\frac{k(t,\tau)}{g(t/\tau)}$ is uniformly continuous on $\{(t,\tau): t_0 \le \tau \le t \le T\}.$

We have for any $x \in \mathcal{F}(\epsilon)$, $t_1, t_2 \in [t_0, T]$ and $t_1 < t_2$,

$$\begin{split} \left| \frac{Ax(t_2)}{g(t_2)} - \frac{Ax(t_1)}{g(t_1)} \right| \\ &\leq \left| \int_{t_0}^{t_2} \frac{k(t_2, \tau)}{g(t_2)} f(\tau, x(\tau), z_x(\tau)) \mathrm{d}\tau - \int_{t_0}^{t_1} \frac{k(t_1, \tau)}{g(t_1)} f(\tau, x(\tau), z_x(\tau)) \mathrm{d}\tau \right| \\ &\leq \int_{t_0}^{t_1} \left| \frac{k(t_2, \tau)}{g(t_2)} - \frac{k(t_1, \tau)}{g(t_1)} \right| |f(\tau, x(\tau), z_x(\tau))| \mathrm{d}\tau \\ &\quad + \int_{t_1}^{t_2} \left| \frac{k(t_2, \tau)}{g(t_2)} \right| |f(\tau, x(\tau), z_x(\tau))| \mathrm{d}\tau \\ &\leq \int_{t_0}^{t_1} \left| \frac{k(t_2, \tau)g(\tau)}{g(t_2)} - \frac{k(t_1, \tau)g(\tau)}{g(t_1)} \right| \psi(\tau, \epsilon, c\epsilon) \mathrm{d}\tau \\ &\quad + \int_{t_1}^{t_2} \left| \frac{k(t_2, \tau)g(\tau)}{g(t_2)} - \frac{k(t_1, \tau)g(\tau)}{g(t_1)} \right| \psi(\tau, \epsilon, c\epsilon) \mathrm{d}\tau \\ &\leq \int_{t_0}^{t_1} \left| \frac{k(t_2, \tau)g(\tau)}{g(t_2)} - \frac{k(t_1, \tau)g(\tau)}{g(t_1)} \right| \psi(\tau, \epsilon, c\epsilon) \mathrm{d}\tau \\ &\quad + \frac{M_3}{t_0^{\alpha \rho^2 - \alpha \rho + 1}} \int_{t_1}^{t_2} \tau^{\alpha \rho^2} \psi(\tau, \epsilon, c\epsilon) \mathrm{d}\tau, \end{split}$$

as $t_2 \to t_1$ which tells us that $\left\{\frac{Ax(t)}{g(t)}, x(t) \in \mathcal{F}(\epsilon)\right\}$ is equicontinuous on any compact interval of $[t_0, \infty)$. To prove that $A\mathcal{F}(\epsilon)$ is relatively compact in \mathbb{E} , by Lemma 2.9, it still remains to show that $\left\{\frac{Ax(t)}{g(t)}, x(t) \in \mathcal{F}(\epsilon)\right\}$ is equiconvergent at infinity. By (2.7), we have

$$\frac{|Ax(t)|}{g(t)} \leq \int_{t_0}^t \frac{k(t,\tau)}{g(t)} |f(\tau, x(\tau), z_x(\tau)| d\tau \leq \int_{t_0}^t \frac{k(t,\tau)}{g(t/\tau)} \psi(\tau, \epsilon, c\epsilon) d\tau \\
\leq \frac{M_3}{t^{\alpha \rho^2 - \alpha \rho + 1}} \int_{t_0}^t \tau^{\alpha \rho^2} \psi(\tau, \epsilon, c\epsilon) d\tau \\
\rightarrow 0 \text{ as } t \rightarrow \infty.$$
(3.11)

Thus, we can assert that $\left\{\frac{Ax(t)}{g(t)}, x(t) \in \mathcal{F}(\epsilon)\right\}$ is equiconvergent at infinity.

Step 3: Let us show that $B : \mathcal{F}(\epsilon) \to \mathbb{E}$ is a contraction mapping. By (2.6), for any $x_1, x_2 \in \mathcal{F}(\epsilon)$, we get that

$$\sup_{t \ge t_0} \left| \frac{Bx_1(t)}{g(t)} - \frac{Bx_2(t)}{g(t)} \right| \le \frac{(1-\rho)\rho t^{1-\rho}}{g(t)} \int_{t_0}^t \left[\int_{\tau}^t \frac{1}{s^{2-2\rho}} \frac{|x_1(\tau) - x_2(\tau)|}{\tau^{1+\rho}} \mathrm{d}s \right] \mathrm{d}\tau$$
$$\le M_2 ||x_1 - x_2||.$$

Through Lemma 2.8, we can assert that there exists at least one fixed point of the operator A + B in $\mathcal{F}(\epsilon)$, which is a mild solution of (1.1)-(1.2). Hence the generalized nonlinear FDEs (1.1)-(1.2) is stable in the Banach space \mathbb{E} .

(*ii*) For any $0 < \epsilon < \eta_1, \eta_2$, let us define

$$\mathcal{F}^*(\epsilon) = \left\{ x \in \mathcal{F}(\epsilon), \lim_{t \to \infty} \frac{x(t)}{g(t)} = 0 \right\}.$$

We show that $Ax + By \in \mathcal{F}^*(\epsilon)$ for any $x, y \in \mathcal{F}^*(\epsilon)$, that is, we need to show that $\frac{Ax(t) + By(t)}{q(t)} \to 0$ as $t \to \infty$. In fact,

$$\begin{aligned} \frac{Ax(t) + Bx(t)}{g(t)} &= \frac{1}{g(t)} \left[\int_{t_0}^t k(t,\tau) f(\tau, x(\tau), z_x(\tau)) \mathrm{d}\tau \right. \\ &+ x_0 \left(\left(\frac{t}{t_0} \right)^{1-\rho} + \frac{(\rho - 1)t^{1-\rho}}{t_0^{\rho}} \int_{t_0}^t \frac{1}{s^{2-2\rho}} \mathrm{d}s \right) \\ &+ x_1 \left((tt_0)^{1-\rho} \int_{t_0}^t \frac{1}{s^{2-2\rho}} \mathrm{d}s \right) \\ &+ (1-\rho)\rho t^{1-\rho} \int_{t_0}^t \left[\int_{\tau}^t \frac{1}{s^{2-2\rho}} \frac{x(\tau)}{\tau^{1+\rho}} \mathrm{d}s \right] \mathrm{d}\tau \right]. \end{aligned}$$

Since we know $g(t) \ge t^{\alpha \rho^2 + 3}$, we obtain

$$\frac{t^{1-\rho}}{g(t)} \le \frac{t^{1-\rho}}{t^{\alpha\rho^2+3}} = \frac{1}{t^{\alpha\rho^2+\rho+2}} \to 0 \text{ as } t \to \infty$$
(3.12)

and

$$\frac{t^{1-\rho}}{g(t)} \int_{t_0}^t \frac{1}{s^{2-2\rho}} \mathrm{d}s \to 0 \text{ as } t \to \infty.$$
(3.13)

Moreover, we see that

$$\frac{t^{1-\rho}}{g(t)} \int_{t_0}^t \left(\int_{\tau}^t \frac{1}{s^{2-2\rho}} \frac{x(\tau)}{\tau^{1+\rho}} \mathrm{d}s \right) \mathrm{d}\tau \le t^{1-\rho} \int_{t_0}^t \left(\int_{\tau}^t \frac{1}{g(t/\tau)} \frac{1}{s^{2-2\rho}} \frac{1}{\tau^{1+\rho}} \frac{x(\tau)}{g(\tau)} \mathrm{d}s \right) \mathrm{d}\tau,$$

and let us consider the following two cases. **Case 1:** For $\rho \in (0, 1)$, we have

$$t^{1-\rho} \int_{t_0}^t \left(\int_{\tau}^t \frac{1}{g(t/\tau)} \frac{1}{s^{2-2\rho}} \frac{1}{\tau^{1+\rho}} \frac{x(\tau)}{g(\tau)} \mathrm{d}s \right) \mathrm{d}\tau \leq \frac{1}{t^{\alpha\rho^2+\rho+1}} \int_{t_0}^t \tau^{\alpha\rho^2+\rho} \frac{x(\tau)}{g(\tau)} \mathrm{d}\tau.$$

Since $\lim_{\tau \to \infty} \frac{x(\tau)}{g(\tau)} = 0$, there exists $T_1 > t_0$ such that for all $t \ge T_1$,

$$\frac{|x(t)|}{g(t)} < (\alpha \rho^2 + \rho + 1)\frac{\epsilon}{2}.$$

Moreover there exists a $T_2 > T_1$, such that for all $t \ge T_2$,

$$\frac{1}{t} \int_{t_0}^{T_1} \frac{|x(\tau)|}{g(\tau)} \mathrm{d}\tau < \frac{\epsilon}{2}.$$

Then we have for $t \geq T_2$,

$$\begin{split} \frac{1}{t^{\alpha\rho^{2}+\rho+1}} & \int_{t_{0}}^{t} \tau^{\alpha\rho^{2}+\rho} \frac{|x(\tau)|}{g(\tau)} \mathrm{d}\tau \\ &= \frac{1}{t^{\alpha\rho^{2}+\rho+1}} \int_{t_{0}}^{T_{1}} \tau^{\alpha\rho^{2}+\rho} \frac{|x(\tau)|}{g(\tau)} \mathrm{d}\tau + \frac{1}{t^{\alpha\rho^{2}+\rho+1}} \int_{T_{1}}^{t} \tau^{\alpha\rho^{2}+\rho} \frac{|x(\tau)|}{g(\tau)} \mathrm{d}\tau \\ &\leq \frac{1}{t} \int_{t_{0}}^{T_{1}} \frac{|x(\tau)|}{g(\tau)} \mathrm{d}\tau + \frac{1}{t^{\alpha\rho^{2}+\rho+1}} \frac{|x(t)|}{g(t)} \int_{T_{1}}^{t} \tau^{\alpha\rho^{2}+\rho} \mathrm{d}\tau \\ &< \frac{\epsilon}{2} + (\alpha\rho^{2}+\rho+1) \frac{\epsilon}{2} \left(\frac{1}{\alpha\rho^{2}+\rho+1}\right) \\ &< \frac{\epsilon}{2} + \frac{\epsilon}{2} = \epsilon. \end{split}$$

Case 2: For $\rho \in (1, \infty)$, we have

$$t^{1-\rho} \int_{t_0}^t \left(\int_{\tau}^t \frac{1}{g(t/\tau)} \frac{1}{s^{2-2\rho}} \frac{1}{\tau^{1+\rho}} \frac{x(\tau)}{g(\tau)} \mathrm{d}s \right) \mathrm{d}\tau \le \frac{1}{t^{\alpha\rho^2-\rho+3}} \int_{t_0}^t \tau^{\alpha\rho^2-\rho+2} \frac{x(\tau)}{g(\tau)} \mathrm{d}\tau.$$

Since $\lim_{\tau \to \infty} \frac{x(\tau)}{g(\tau)} = 0$, there exists $T_1 > t_0$ such that for all $t \ge T_1$,

$$\frac{|x(t)|}{g(t)} < (\alpha \rho^2 - \rho + 3)\frac{\epsilon}{2}.$$

Moreover there exists a $T_2 > T_1$, such that for all $t \ge T_2$,

$$\frac{1}{t} \int_{t_0}^{T_1} \frac{|x(\tau)|}{g(\tau)} \mathrm{d}\tau < \frac{\epsilon}{2}.$$

Then we have for $t \geq T_2$,

$$\begin{split} \frac{1}{t^{\alpha\rho^{2}-\rho+3}} \int_{t_{0}}^{t} \tau^{\alpha\rho^{2}-\rho+2} \frac{|x(\tau)|}{g(\tau)} \mathrm{d}\tau \\ &= \frac{1}{t^{\alpha\rho^{2}-\rho+3}} \int_{t_{0}}^{T_{1}} \tau^{\alpha\rho^{2}-\rho+2} \frac{|x(\tau)|}{g(\tau)} \mathrm{d}\tau + \frac{1}{t^{\alpha\rho^{2}-\rho+3}} \int_{T_{1}}^{t} \tau^{\alpha\rho^{2}-\rho+3} \frac{|x(\tau)|}{g(\tau)} \mathrm{d}\tau \\ &\leq \frac{1}{t} \int_{t_{0}}^{T_{1}} \frac{|x(\tau)|}{g(\tau)} \mathrm{d}\tau + \frac{1}{t^{\alpha\rho^{2}-\rho+3}} \frac{|x(t)|}{g(t)} \int_{T_{1}}^{t} \tau^{\alpha\rho^{2}-\rho+2} \mathrm{d}\tau \\ &< \frac{\epsilon}{2} + (\alpha\rho^{2}-\rho+3)\frac{\epsilon}{2} \left(\frac{1}{\alpha\rho^{2}-\rho+3}\right) \\ &< \frac{\epsilon}{2} + \frac{\epsilon}{2} = \epsilon. \end{split}$$

Based on the previous calculations, we get

$$\frac{t^{1-\rho}}{g(t)} \int_{t_0}^t \left(\int_{\tau}^t \frac{1}{s^{2-2\rho}} \frac{x(\tau)}{\tau^{1+\rho}} \mathrm{d}s \right) \mathrm{d}\tau \to 0 \text{ as } t \to \infty.$$
(3.14)

Also by (3.11) we obtain

$$\frac{Ax(t)}{g(t)} = \int_{t_0}^t k(t,\tau) f(\tau, x(\tau), z_x(\tau)) \mathrm{d}\tau \to 0 \text{ as } t \to \infty.$$
(3.15)

Then by using (3.12)-(3.15), we assert that

$$\frac{Ax(t) + By(t)}{g(t)} \to 0 \text{ as } t \to \infty.$$
(3.16)

Hence we proved that there exists at least one mild solution to (1.1)-(1.2) such that

$$\lim_{t \to \infty} \frac{x(t)}{g(t)} = 0.$$

4. Examples

Example 4.1. Consider the nonlinear fractional initial value problem:

$${}^{C}D^{\frac{3}{2},\frac{1}{2}}x(t) = \frac{1}{10} \left[\frac{x}{t^{6}} + \frac{x^{3}}{1+t^{12}} + \frac{1}{1+t^{8}} \left(\int_{1}^{t} \frac{x(s)}{e^{t+s}} \mathrm{d}s \right)^{2} \right], \quad (4.1)$$
$$x(1) = x_{0}, \ x'(1) = x_{1}. \quad (4.2)$$

Let us choose $g(t) = t^4$ and let

$$\mathbb{E} = \left\{ x \in C([1,\infty),\mathbb{R}) : \sup_{t \ge 1} \frac{|x(t)|}{t^4} < \infty \right\}.$$

 Set

$$f(t, x, z_x) = \frac{1}{10} \left(\frac{x}{t^6} + \frac{x^3}{1 + t^{12}} + \frac{z_x^2}{1 + t^8} \right)$$

where $z_x := \int_1^t \frac{x(s)}{e^{t+s}} ds$. Then we have $|z_x(t)| \le \frac{1}{e^2} |x(t)|$ and observe that

$$\frac{|f(t, ug(t), z_ug(t))|}{g(t)} = \frac{1}{10} \frac{\left|\frac{ut^4}{t^6} + \frac{(ut^4)^3}{1+t^{12}} + \frac{(z_ut^4)^2}{1+t^8}\right|}{t^4} \le \frac{1}{10} \left(\frac{|u|}{t^6} + \frac{|u|^3}{t^4} + \frac{|z_u|^2}{t^4}\right).$$

So let us take

$$\psi(t, r_1, r_2) = \frac{1}{10} \left(\frac{r_1}{t^6} + \frac{r_1^3}{t^4} + \frac{r_2^2}{t^4} \right)$$

and further

$$\int_{1}^{\infty} t^{3/8} \psi(t, r_1, r_2) \mathrm{d}t \le \frac{1}{10} \left(\frac{r_1}{4} + \frac{r_1^3}{2} + \frac{r_2^2}{2} \right)$$

for fixed r_1, r_2 and hence $t^{3/8}\psi(t, r_1, r_2) \in L^1([1, \infty))$. We see that

$$\sup_{t \ge 1} \int_1^t \frac{k(t,\tau)}{g(t/\tau)} \frac{\psi(t,r_1,r_2)}{r} \mathrm{d}\tau \le \frac{2\sqrt{2}}{\sqrt{\pi}} \left(\frac{r_1}{5r} + \frac{r_1^3}{3r} + \frac{r_2^2}{3r}\right),$$

where $r := \min(r_1, r_2)$.

Then there exist $\eta_1, \eta_2 > 0$ such that

$$\sup_{t \ge 1} \int_{1}^{t} \frac{k(t,\tau)}{g(t/\tau)} \frac{\psi(t,r_{1},r_{2})}{r} \mathrm{d}\tau \le \frac{4}{5} < 1 - \frac{2}{15} = \frac{13}{15},$$

for all $0 < r_1 \le \eta_1$ and $0 < r_2 \le \eta_2$. Hence by Theorem 3.1, we conclude that the nonlinear fractional integrodifferential equation (4.1)-(4.2) is stable in the Banach space \mathbb{E} and there exists at least one mild solution which satisfies $\lim_{t\to\infty} \frac{x(t)}{g(t)} = 0.$

Example 4.2. Consider the nonlinear fractional initial value problem:

$${}^{C}D^{\frac{4}{3},3}x(t) = \frac{1}{t^{5}}\arctan\left(t^{3} + x^{1/3} + \left(\int_{1}^{t}\frac{\sin(x(s))}{(t-s)^{2}}\mathrm{d}s\right)^{1/3}\right), \quad (4.3)$$
$$x(1) = x_{0}, \ x'(1) = x_{1}. \quad (4.4)$$

Let us choose $g(t) = t^{15}$ and let

$$\mathbb{E} = \left\{ x \in C([1,\infty),\mathbb{R}) : \sup_{t \ge 1} \frac{|x(t)|}{t^{15}} < \infty \right\}.$$

Take

$$f(t, x, z_x) = \frac{1}{t^5} \arctan(t^3 + x^{1/3} + z_x^{1/3})$$
where $z_x := \int_1^t \frac{\sin(x(s))}{(t-s)^2} ds$. Note that $|z_x(t)| \le \frac{1}{4} |x(t)|$ and
$$\frac{|f(t, ug(t), z_ug(t))|}{g(t)} = \frac{1}{t^5} \frac{|\arctan(t^3 + (ut^{15})^{1/3} + (z_ut^{15})^{1/3})|}{t^{15}}$$

$$\le \frac{\left(\frac{t^3}{t^5} + \frac{|u^{1/3}|t^5}{t^5} + \frac{|z_u|^{1/3}t^5}{t^5}\right)}{t^{15}} \le \frac{1}{t^{17}} + \frac{|u|^{1/3}}{t^{15}} + \frac{|z_u|^{1/3}}{t^{15}}$$

So let us take

$$\psi(t, r_1, r_2) = \left(\frac{1}{t^{17}} + \frac{r_1^{1/3}}{t^{15}} + \frac{r_2^{1/3}}{t^{15}}\right)$$

and further

$$\int_{1}^{\infty} t^{12} \psi(t, r_1, r_2) \mathrm{d}t \le \frac{1}{4} + \frac{r_1^{1/3}}{2} + \frac{r_2^{1/3}}{2}$$

for fixed r_1, r_2 and hence $t^{12}\psi(t, r_1, r_2) \in L^1([1, \infty))$. We see that

$$\sup_{t\geq 1} \int_{1}^{t} \frac{k(t,\tau)}{g(t/\tau)} \frac{\psi(t,r_{1},r_{2})}{r} \mathrm{d}\tau \leq \frac{1}{3^{1/3}\Gamma(4/3)} \left(\frac{1}{16r} + \frac{r_{1}^{1/3}}{14r} + \frac{r_{2}^{1/3}}{14r} \right),$$

where $r := \min(r_1, r_2)$. Then there exist $\eta_1, \eta_2 > 0$ such that

$$\sup_{t \ge 1} \int_1^t \frac{k(t,\tau)}{g(t/\tau)} \frac{\psi(t,r_1,r_2)}{r} \mathrm{d}\tau \le \frac{1}{5} < 1 - \frac{1}{2} = \frac{1}{2},$$

for all $0 < r_1 \le \eta_1$ and $0 < r_2 \le \eta_2$. Hence by Theorem 3.1, we conclude that the nonlinear fractional integrodifferential equation (4.3)-(4.4) is stable in the Banach space \mathbb{E} and there exists at least one mild solution which satisfies $\lim_{t\to\infty} \frac{x(t)}{g(t)} = 0.$

Acknowledgments: The work of first author is supported by the Department of Science and Technology, Government of India, Grant No: SR/WOS-A/PM-34/2019(G).

References

- N. Abdellouahab, B. Tellab and K. Zennir, Existence and stability results of a nonlinear fractional integro-differential equation with integral boundary conditions, Kragujev. J. Math., 46 (2022), 685–699.
- [2] R. Almeida, A Caputo fractional derivative of a function with respect to another function, Commun. Nonlinear Sci. Numer. Simul., 44 (2017), 460–481.
- [3] R. Almeida, A.B. Malinowska and T. Odzijewicz, Fractional differential equations with dependence on the Caputo-Katugampola derivative, J. Comput. Nonlinear Dyn., 11 (2016), 061017, 11 pages.
- [4] A. Ardjouni, H. Boulares and Y. Laskri, Stability in higher-order nonlinear fractional differential equations, Acta et Comment. Univ. Tartu. de Math., 22 (2018), 37–47.
- [5] K. Balachandran and S. Divya, Controllability of nonlinear neutral fractional integrodifferential systems with infinite delay, J. Appl. Nonlinear Dyn., 6 (2017), 333–344.
- [6] D. Baleanu, G.C. Wu and S.D. Zeng, Chaos analysis and asymptotic stability of generalized Caputo fractional differential equations, Chaos Soliton Fract., 102 (2017), 99–105.
- [7] A. Ben Makhlouf, D. Boucenna and M.A. Hammami, Existence and stability results for generalized fractional differential equations, Acta Math. Sci., 40B (2020), 141–154.
- [8] A. Ben Makhlouf and A.M. Nagy, Finite-time stability of linear Caputo-Katugampola fractional-order time delay systems, Asian J. Control, 22 (2020), 297–306.
- [9] A. Boulfoul, B. Tellab, N. Abdellouahab and K. Zennir, Existence and uniqueness results for initial value problem of nonlinear fractional integro-differential equation on an unbounded domain in a weighted Banach space, Math. Methods Appl. Sci., 2020 (2020), 1–12.
- [10] T.A. Burton and B. Zhang, Fractional differential equations and generalizations of Schaefer's and Krasnoselskii's fixed point theorems, Nonlinear Anal., 75 (2012), 6485– 6495.
- [11] C.D. Constantinescu, J.M. Ramirez and W.R. Zhu, An application of fractional differential equations to risk theory, Financ. Stoch., 23 (2019), 1001–1024.
- [12] F. Ge and C. Kou, Stability analysis by Krasnoselskii's fixed point theorem for nonlinear fractional differential equations, Appl. Math. Comput., 257 (2015), 308–316.
- [13] F. Jarada, T. Abdeljawad and C. Baleanua, On the generalized fractional derivatives and their Caputo modification, J. Nonlinear Sci. Appl., 10 (2017), 2607–2619.
- [14] B. Kamalapriya, K. Balachandran and N. Annapoorani, Existence results for fractional integrodifferential equations, Nonlinear Funct. Anal. Appl., 22(3) (2017), 641–653.
- [15] B. Kamalapriya, K. Balachandran and N. Annapoorani, Existence results of fractional neutral integrodifferential equations with deviating arguments, Discontinuity, Nonlinearity, Complex., 9 (2020), 277–287.
- [16] C. Kausika, Stability of higher order nonlinear implicit fractional differential equations by fixed point technique, J. Vib. Test. Syst. Dyn., 5 (2021), 169–180.
- [17] C. Kausika, K. Balachandran and N. Annapoorani, *Linearized asymptotic stability* of *Caputo-Katugampola fractional integro differential equations*, Indian J. Ind. Appl. Math., **10** (2019), 217–230.

- [18] A.A. Kilbas, H.M. Srivastava and J.J. Trujillo, Theory and Applications of Fractional Differential Equations, Elsevier, Amsterdam, 2006.
- [19] C. Kou, H. Zhou and Y. Yan, Existence of solutions of initial value problems for nonlinear fractional differential equations on the half-axis, Nonlinear Anal., 74 (2011), 5975– 5986.
- [20] M.A. Krasnoselskii, Some problems of nonlinear analysis, Amer. Math. Soc. Transl., 10 (1958), 345–409.
- [21] J.T. Machado, V. Kiryakova and F. Mainardi, *Recent history of fractional calculus*, Commun. Nonlinear Sci. Numer. Simul., 16 (2011), 1140–1153.
- [22] N. Sene, Stability analysis of the generalized fractional differential equations with and without exogenous inputs, J. Nonlinear Sci. Appl., 12 (2019), 562–572.
- [23] N. Sene and G. Srivastava, Generalized Mittag-Leffler input stability of the fractional differential equations, Symmetry, 11 (2019), 608.
- [24] V.E. Tarasov, Fractional integro-differential equations for electromagnetic waves in dielectric media, Theor. Math. Phys., 158 (2009), 355–359.
- [25] M.D. Tran, V. Ho and H.N. Van, On the stability of fractional differential equations involving generalized Caputo fractional derivative, Math. Probl. Eng., 2020 (2020), Article ID 1680761, 14 pages.