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GENERIC LIGHTLIKE SUBMANIFOLDS OF AN INDEFINITE TRANS-SASAKIAN MANIFOLD WITH A NON-SYMMETRIC NON-METRIC CONNECTION OF TYPE (ℓ,m)

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ABSTRACT. Jin [7] defined a new connection on semi-Riemannian manifolds, which is a non-symmetric and non-metric connection. He said that this connection is an (ℓ,m) -type connection. Jin also studied lightlike hypersurfaces of an indefinite trans-Sasakian manifold with an (ℓ,m) -type connection in [7]. We study further the geometry of this subject. In this paper, we study generic lightlike submanifolds of an indefinite trans-Sasakian manifold endowed with an (ℓ,m) -type connection.

1. Introduction

The notion of (ℓ, m) -type connection on indefinite almost contact manifolds \bar{M} was introduced by Jin [7]. Here we quote Jin's definition as follows:

A linear connection ∇ on \bar{M} is called a non-symmetric non-metric connection of type (ℓ, m) , and abbreviate it to (ℓ, m) -type connection, if there exist smooth functions ℓ and m on \bar{M} such that $\bar{\nabla}$ and its torsion tensor \bar{T} satisfy

(1)
$$(\bar{\nabla}_{\bar{X}}\bar{g})(\bar{Y},\bar{Z}) = -\ell\{\theta(\bar{Y})\bar{g}(\bar{X},\bar{Z}) + \theta(\bar{Z})\bar{g}(\bar{X},\bar{Y})\}$$

$$-m\{\theta(\bar{Y})\bar{g}(J\bar{X},\bar{Z}) + \theta(\bar{Z})\bar{g}(J\bar{X},\bar{Y})\},$$
(2)
$$\bar{T}(\bar{X},\bar{Y}) = \ell\{\theta(\bar{Y})\bar{X} - \theta(\bar{X})\bar{Y}\} + m\{\theta(\bar{Y})J\bar{X} - \theta(\bar{X})J\bar{Y}\},$$

where J is a (1,1)-type tensor field and θ is a 1-form associated with a smooth vector field ζ by $\theta(\bar{X}) = \bar{g}(\bar{X},\zeta)$. We set $(\ell,m) \neq (0,0)$ and we denote by \bar{X}, \bar{Y} and \bar{Z} the smooth vector fields on \bar{M} . Semi-symmetric non-metric connection and non-metric ϕ -symmetric connection are important examples of this connection such that (1) $(\ell,m) = (1,0)$ and (2) $(\ell,m) = (0,1)$, respectively.

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Especially, in cases: (3) $(\ell, m) = (1, 0)$ in (1) and $(\ell, m) = (0, 1)$ in (2) (see [10] in details); (4) $(\ell, m) = (0, 0)$ in (1) and $(\ell, m) = (0, 1)$ in (2) and (5) $(\ell, m) = (0, 0)$ in (1) and $(\ell, m) = (1, 0)$ in (2), this connection ∇ reduce to quarter-symmetric non-metric connection, quarter-symmetric metric connection and semi-symmetric metric connection, respectively.

Remark 1.1. Denote by $\widetilde{\nabla}$ the Levi-Civita connection of a semi-Riemannian manifold $(\overline{M}, \overline{g})$ with respect to the metric \overline{g} . It is known [7] that a linear connection $\overline{\nabla}$ on \overline{M} is an (ℓ, m) -type connection if and only if $\overline{\nabla}$ satisfies

(3)
$$\bar{\nabla}_{\bar{X}}\bar{Y} = \tilde{\nabla}_{\bar{X}}\bar{Y} + \theta(\bar{Y})\{\ell\bar{X} + mJ\bar{X}\}.$$

A lightlike submanifold M of an indefinite almost contact manifold \bar{M} is said to be *generic* if there exists a screen distribution S(TM) on M such that

$$(4) J(S(TM)^{\perp}) \subset S(TM),$$

where $S(TM)^{\perp}$ is the orthogonal complement of S(TM) in the tangent bundle $T\bar{M}$ on \bar{M} , i.e., $T\bar{M} = S(TM) \oplus_{orth} S(TM)^{\perp}$. The notion of generic light-like submanifolds was introduced by Jin-Lee [8] and later, studied by several geometers [3,5,6,9]. Its geometry is an extension of that of lightlike hypersurfaces and half lightlike submanifolds. Much of its theory will be immediately generalized in a formal way to general lightlike submanifolds.

The subject of study in this paper is generic lightlike submanifolds of an indefinite trans-Sasakian manifold $M=(\bar{M},\zeta,\theta,J,\bar{g})$ endowed with an (ℓ,m) -type connection subject to the following two conditions that (1) the tensor field J and the 1-form θ , defined by (1) and (2), are identical with the indefinite trans-Sasakian structure tensor J and the structure 1-form θ of \bar{M} , respectively, and (2) the structure vector field ζ of \bar{M} is tangent to M.

2. (ℓ, m) -type connections

The notion of trans-Sasakian manifold \bar{M} , of type (α, β) , was introduced by Oubina [11]. Sasakian, Kenmotsu and cosymplectic manifolds are important kinds of trans-Sasakian manifolds such that

$$\alpha = 1, \quad \beta = 0; \qquad \alpha = 0, \quad \beta = 1; \qquad \alpha = \beta = 0,$$

respectively. If \bar{M} is a semi-Riemannian manifold with a trans-Sasakian structure of type (α, β) , then \bar{M} is called an indefinite trans-Sasakian manifold as follows:

An odd-dimensional semi-Riemannian manifold (\bar{M}, \bar{g}) is called an *indefinite* trans-Sasakian manifold if there exist (1) a structure set $\{J, \zeta, \theta, \bar{g}\}$, where J is a (1,1)-type tensor field, ζ is a vector field and θ is a 1-form such that

(5)
$$J^{2}\bar{X} = -\bar{X} + \theta(\bar{X})\zeta, \quad \theta(\zeta) = 1, \quad \theta(\bar{X}) = \epsilon \,\bar{g}(\bar{X},\zeta),$$
$$\theta \circ J = 0, \quad \bar{g}(J\bar{X},J\bar{Y}) = \bar{g}(\bar{X},\bar{Y}) - \epsilon \,\theta(\bar{X})\theta(\bar{Y}),$$

(2) a Levi-Civita connection $\widetilde{\nabla}$ and two smooth functions α and β such that

$$(\widetilde{\nabla}_{\bar{X}}J)\bar{Y} = \alpha\{\bar{g}(\bar{X},\bar{Y})\zeta - \epsilon\,\theta(\bar{Y})\bar{X}\} + \beta\{\bar{g}(J\bar{X},\bar{Y})\zeta - \epsilon\,\theta(\bar{Y})J\bar{X}\},$$

where ϵ denotes $\epsilon = 1$ or -1 according as ζ is spacelike or timelike respectively. $\{J, \zeta, \theta, \bar{g}\}$ is called an *indefinite trans-Sasakian structure of type* (α, β) .

In the entire discussion of this article, we shall assume that the vector field ζ is a spacelike one, *i.e.*, $\epsilon = 1$, without loss of generality.

Let ∇ be an (ℓ, m) -type connection on $(\overline{M}, \overline{g})$. By directed calculation from (3), (5) and the fact that $\theta(JY) = 0$, we obtain

(6)
$$(\bar{\nabla}_{\bar{X}}J)\bar{Y} = \alpha\{\bar{g}(\bar{X},\bar{Y})\zeta - \theta(\bar{Y})\bar{X}\} + \beta\{\bar{g}(J\bar{X},\bar{Y})\zeta - \theta(\bar{Y})J\bar{X}\}$$
$$- \theta(\bar{Y})\{\ell J\bar{X} - m\bar{X} + m\theta(\bar{X})\zeta\}.$$

Replacing \bar{Y} by ζ to (6) and using $J\zeta = 0$ and $\theta(\bar{\nabla}_X\zeta) = \ell\theta(X)$, we obtain

(7)
$$\bar{\nabla}_{\bar{X}}\zeta = (m-\alpha)J\bar{X} + (\ell+\beta)\bar{X} - \beta\theta(\bar{X})\zeta.$$

Let (M,g) be an m-dimensional lightlike submanifold of an indefinite trans-Sasakian manifold (\bar{M},\bar{g}) of dimension (m+n). Then the radical distribution $Rad(TM)=TM\cap TM^{\perp}$ on M is a subbundle of the tangent bundle TM and the normal bundle TM^{\perp} , of rank $r(1\leq r\leq \min\{m,n\})$. In case $1< r< \min\{m,n\}$, we say that M is an r-lightlike submanifold [3] of \bar{M} . In this case, there exist two complementary non-degenerate distributions S(TM) and $S(TM^{\perp})$ of Rad(TM) in TM and TM^{\perp} , respectively, which are called the screen distribution and co-screen distribution of M such that

$$TM = Rad(TM) \oplus_{orth} S(TM), TM^{\perp} = Rad(TM) \oplus_{orth} S(TM^{\perp}),$$

where \bigoplus_{orth} denotes the orthogonal direct sum. Denote by F(M) the algebra of smooth functions on M and by $\Gamma(E)$ the F(M) module of smooth sections of a vector bundle E over M. Also denote by $(5)_i$ the i-th equation of (5). We use the same notations for any others. Let X, Y, Z and W be the vector fields on M, unless otherwise specified. We use the following range of indices:

$$i, j, k, \ldots \in \{1, \ldots, r\}, \quad a, b, c, \ldots \in \{r + 1, \ldots, n\}.$$

Let tr(TM) and tr(TM) be complementary vector bundles to TM in $T\bar{M}_{|M|}$ and TM^{\perp} in $S(TM)^{\perp}$ respectively and let $\{N_1, \ldots, N_r\}$ be a lightlike basis of $tr(TM)_{|_{\mathcal{U}}}$, where \mathcal{U} is a coordinate neighborhood of M, such that

$$\bar{g}(N_i, \xi_j) = \delta_{ij}, \quad \bar{g}(N_i, N_j) = 0,$$

where $\{\xi_1, \ldots, \xi_r\}$ is a lightlike basis of $Rad(TM)_{|_{\mathcal{U}}}$. In this case,

$$T\bar{M} = TM \oplus tr(TM) = \{Rad(TM) \oplus tr(TM)\} \oplus_{orth} S(TM)$$

= $\{Rad(TM) \oplus tr(TM)\} \oplus_{orth} S(TM) \oplus_{orth} S(TM^{\perp}),$

$$\{\xi_1, \ldots, \xi_r, N_1, \ldots, N_r, F_{r+1}, \ldots, F_m, E_{r+1}, \ldots, E_n\}$$

is a quasi-orthonormal field of frames of \bar{M} , where $\{F_{r+1}, \ldots, F_m\}$ is an orthonormal basis of S(TM) and $\{E_{r+1}, \ldots, E_n\}$ is an orthonormal basis of $S(TM^{\perp})$. Denote $\epsilon_a = \bar{g}(E_a, E_a)$. Then $\epsilon_a \delta_{ab} = \bar{g}(E_a, E_b)$.

Let P be the projection morphism of TM on S(TM). Then the local Gauss-Weingarten formulae of M and S(TM) are given respectively by

(8)
$$\bar{\nabla}_X Y = \nabla_X Y + \sum_{i=1}^r h_i^{\ell}(X, Y) N_i + \sum_{a=r+1}^n h_a^{s}(X, Y) E_a,$$

(9)
$$\bar{\nabla}_X N_i = -A_{N_i} X + \sum_{j=1}^r \tau_{ij}(X) N_j + \sum_{a=r+1}^n \rho_{ia}(X) E_a,$$

(10)
$$\bar{\nabla}_X E_a = -A_{E_a} X + \sum_{i=1}^r \lambda_{ai}(X) N_i + \sum_{b=r+1}^n \sigma_{ab}(X) E_b;$$

(11)
$$\nabla_X PY = \nabla_X^* PY + \sum_{i=1}^r h_i^*(X, PY) \xi_i,$$

(12)
$$\nabla_X \xi_i = -A_{\xi_i}^* X - \sum_{j=1}^r \tau_{ji}(X) \xi_j,$$

where ∇ and ∇^* are induced linear connections on M and S(TM) respectively, h_i^ℓ and h_a^s are called the local second fundamental forms on M, h_i^* are called the local second fundamental forms on S(TM). A_{N_i} , A_{E_a} and $A_{\xi_i}^*$ are called the shape operators, and τ_{ij} , ρ_{ia} , λ_{ai} and σ_{ab} are 1-forms.

Let M be a generic lightlike submanifold of \overline{M} . From (4) we show that J(Rad(TM)), J(ltr(TM)) and $J(S(TM^{\perp}))$ are vector subbundles of S(TM). Thus there exist two non-degenerate almost complex distributions H_o and H with respect to J, i.e., $J(H_o) = H_o$ and J(H) = H, such that

$$S(TM) = \{J(Rad(TM)) \oplus J(ltr(TM))\} \oplus_{orth} J(S(TM^{\perp})) \oplus_{orth} H_o,$$

$$H = Rad(TM) \oplus_{orth} J(Rad(TM)) \oplus_{orth} H_o.$$

In this case, the tangent bundle TM on M is decomposed as follows:

(13)
$$TM = H \oplus J(ltr(TM)) \oplus_{orth} J(S(TM^{\perp})).$$

Consider local null vector fields U_i and V_i for each i, local non-null unit vector fields W_a for each a, and their 1-forms u_i , v_i and w_a defined by

(14)
$$U_i = -JN_i, V_i = -J\xi_i, W_a = -JE_a,$$

(15)
$$u_i(X) = g(X, V_i), \quad v_i(X) = g(X, U_i), \quad w_a(X) = \epsilon_a g(X, W_a).$$

Denote by S the projection morphism of TM on H and by F the tensor field of type (1,1) globally defined on M by $F = J \circ S$. Then JX is expressed as

(16)
$$JX = FX + \sum_{i=1}^{r} u_i(X)N_i + \sum_{a=r+1}^{n} w_a(X)E_a.$$

Applying J to (16) and using $(5)_1$ and (14), we have

(17)
$$F^{2}X = -X + \theta(X)\zeta + \sum_{i=1}^{r} u_{i}(X)U_{i} + \sum_{a=r+1}^{n} w_{a}(X)W_{a}.$$

3. Structure equations

Let \overline{M} be an indefinite trans-Sasakian manifold with an (ℓ, m) -type connection $\overline{\nabla}$. In the following, we shall assume that ζ is tangent to M. Călin [2] proved that if ζ is tangent to M, then it belongs to S(TM) which we assumed in this paper. Using (1), (2), (8) and (16), we see that

(18)
$$(\nabla_X g)(Y, Z) = \sum_{i=1}^{7} \{ h_i^{\ell}(X, Y) \eta_i(Z) + h_i^{\ell}(X, Z) \eta_i(Y) \}$$
$$- \ell \{ \theta(Y) g(X, Z) + \theta(Z) g(X, Y) \}$$
$$- m \{ \theta(Y) \bar{g}(JX, Z) + \theta(Z) \bar{g}(JX, Y) \},$$

(19)
$$T(X,Y) = \ell\{\theta(Y)X - \theta(X)Y\} + m\{\theta(Y)FX - \theta(X)FY\},$$

(20)
$$h_i^{\ell}(X,Y) - h_i^{\ell}(Y,X) = m\{\theta(Y)u_i(X) - \theta(X)u_i(Y)\},\$$

(21)
$$h_a^s(X,Y) - h_a^s(Y,X) = m\{\theta(Y)w_a(X) - \theta(X)w_a(Y)\},\$$

for all i and a, where η_i 's are 1-forms such that $\eta_i(X) = \bar{g}(X, N_i)$.

Theorem 3.1. Let M be a lightlike hypersurface of an indefinite trans-Sasakian manifold \bar{M} with an (ℓ, m) -type connection subject such that ζ is tangent to M. Then either h_i^{ℓ} or h_a^s is symmetric if and only if m=0.

Proof. (1) If m=0, then h_i^{ℓ} are symmetric by (20). Conversely, if h_i^{ℓ} is symmetric, then, taking $X=\zeta$ and $Y=U_i$ to (20), we have m=0.

(2) If m = 0, then h_a^s are symmetric by (21). Conversely, if h_a^s is symmetric, then, taking $X = \zeta$ and $Y = W_a$ to (21), we have m = 0.

From the facts that $h_i^\ell(X,Y) = \bar{g}(\bar{\nabla}_X Y, \xi_i)$ and $\epsilon_a h_a^s(X,Y) = \bar{g}(\bar{\nabla}_X Y, E_a)$, we know that h_i^ℓ and h_a^s are independent of the choice of S(TM). Applying $\bar{\nabla}_X$ to $g(\xi_i, \xi_j) = 0$, $\bar{g}(\xi_i, E_a) = 0$, $\bar{g}(N_i, N_j) = 0$, $\bar{g}(N_i, E_a) = 0$ and $\bar{g}(E_a, E_b) = \epsilon \delta_{ab}$ by turns and using (1) and (8) \sim (10), we obtain

$$h_{i}^{\ell}(X,\xi_{j}) + h_{j}^{\ell}(X,\xi_{i}) = 0, \qquad h_{a}^{s}(X,\xi_{i}) = -\epsilon_{a}\lambda_{ai}(X),$$

$$(22) \qquad \eta_{j}(A_{N_{i}}X) + \eta_{i}(A_{N_{j}}X) = 0, \qquad \eta_{i}(A_{E_{a}}X) = \epsilon_{a}\rho_{ia}(X),$$

$$\epsilon_{b}\sigma_{ab} + \epsilon_{a}\sigma_{ba} = 0; \quad h_{i}^{\ell}(X,\xi_{i}) = 0, \quad h_{i}^{\ell}(\xi_{j},\xi_{k}) = 0, \quad A_{\xi_{i}}^{*}\xi_{i} = 0.$$

The local second fundamental forms are related to their shape operators by

(23)
$$h_i^{\ell}(X,Y) = g(A_{\xi_i}^*X,Y) + m\theta(Y)u_i(X) - \sum_{k=1}^r h_k^{\ell}(X,\xi_i)\eta_k(Y),$$

(24)
$$\epsilon_a h_a^s(X,Y) = g(A_{E_a}X,Y) + \epsilon_a m\theta(Y) w_a(X) - \sum_{k=1}^r \lambda_{ak}(X) \eta_k(Y),$$

(25)
$$h_i^*(X, PY) = g(A_{N_i}X, PY) + \{\ell \eta_i(X) + mv_i(X)\}\theta(PY).$$

Replacing Y by ζ to (8) and using (7), (16), (23) and (24), we have

(26)
$$\nabla_X \zeta = (m - \alpha) FX + (\ell + \beta) X - \beta \theta(X) \zeta,$$

(27)
$$\theta(A_{\xi_i}^*X) = -\alpha u_i(X), \qquad h_i^{\ell}(X,\zeta) = (m-\alpha)u_i(X),$$

(28)
$$\theta(A_{E_a}X) = -\epsilon_a \alpha w_a(X), \quad h_a^s(X,\zeta) = (m-\alpha)w_a(X).$$

Applying $\bar{\nabla}_X$ to $\bar{g}(\zeta, N_i) = 0$ and using (7), (9) and (25), we have

(29)
$$\theta(A_{N_i}X) = -\alpha v_i(X) + \beta \eta_i(X),$$
$$h_i^*(X,\zeta) = (\ell+\beta)\eta_i(X) + (m-\alpha)v_i(X).$$

Applying $\bar{\nabla}_X$ to $(14)_{1,2,3}$ and (16) by turns and using (6), $(8) \sim (12)$, $(14) \sim (16)$ and $(23) \sim (25)$, we have

(30)
$$h_{j}^{\ell}(X, U_{i}) = h_{i}^{*}(X, V_{j}), \qquad \epsilon_{a} h_{i}^{*}(X, W_{a}) = h_{a}^{s}(X, U_{i}), h_{j}^{\ell}(X, V_{i}) = h_{i}^{\ell}(X, V_{j}), \qquad \epsilon_{a} h_{i}^{\ell}(X, W_{a}) = h_{a}^{s}(X, V_{i}), \epsilon_{b} h_{b}^{s}(X, W_{a}) = \epsilon_{a} h_{a}^{s}(X, W_{b}),$$

(31)
$$\nabla_X U_i = F(A_{N_i} X) + \sum_{j=1}^r \tau_{ij}(X) U_j + \sum_{a=r+1}^n \rho_{ia}(X) W_a - \{\alpha \eta_i(X) + \beta v_i(X)\} \zeta,$$

(32)
$$\nabla_{X}V_{i} = F(A_{\xi_{i}}^{*}X) - \sum_{j=1}^{r} \tau_{ji}(X)V_{j} + \sum_{j=1}^{r} h_{j}^{\ell}(X,\xi_{i})U_{j} - \sum_{j=1}^{n} \epsilon_{a}\lambda_{ai}(X)W_{a} - \beta u_{i}(X)\zeta,$$

(33)
$$\nabla_X W_a = F(A_{E_a} X) + \sum_{i=1}^r \lambda_{ai}(X) U_i + \sum_{b=r+1}^n \sigma_{ab}(X) W_b - \epsilon_a \beta w_a(X) \zeta,$$

(34)
$$(\nabla_{X}F)(Y) = \sum_{i=1}^{r} u_{i}(Y)A_{N_{i}}X + \sum_{a=r+1}^{n} w_{a}(Y)A_{E_{a}}X$$

$$- \sum_{i=1}^{r} h_{i}^{\ell}(X,Y)U_{i} - \sum_{a=r+1}^{n} h_{a}^{s}(X,Y)W_{a}$$

$$+ \{\alpha g(X,Y) + \beta \bar{g}(JX,Y) - \theta(X)\theta(Y)\}\zeta$$

$$+ (m - \alpha)\theta(Y)X - (\ell + \beta)\theta(Y)FX,$$

(35)
$$(\nabla_X u_i)(Y) = -\sum_{j=1}^r u_j(Y)\tau_{ji}(X) - \sum_{a=r+1}^n w_a(Y)\lambda_{ai}(X) - h_i^{\ell}(X, FY) - (\ell + \beta)\theta(Y)u_i(X),$$

(36)
$$(\nabla_X v_i)(Y) = \sum_{j=1}^r v_j(Y) \tau_{ij}(X) + \sum_{a=r+1}^n \epsilon_a w_a(Y) \rho_{ia}(X)$$

$$+ \sum_{j=r+1}^r u_j(Y) \eta_i(A_{N_j} X) - g(A_{N_i} X, FY)$$

$$+ (m - \alpha) \theta(Y) \eta_i(X) - (\ell + \beta) \theta(Y) v_i(X).$$

Theorem 3.2. There exist no generic lightlike submanifolds of an indefinite trans-Sasakian manifold with an (ℓ, m) -type connection subject such that ζ is tangent to M and F satisfies the following equation:

$$(\nabla_X F)Y = (\nabla_Y F)X, \quad \forall X, Y \in \Gamma(TM).$$

Proof. Let $(\nabla_X F)Y = (\nabla_Y F)X$. Using (20), (21) and (34), we obtain

$$(37) \qquad \sum_{i=1}^{r} \{u_{i}(Y)A_{N_{i}}X - u_{i}(X)A_{N_{i}}Y\}$$

$$+ \sum_{a=r+1}^{n} \{w_{a}(Y)A_{E_{a}}X - w_{a}(X)A_{E_{a}}Y\} - 2\beta\bar{g}(X,JY)\zeta$$

$$+ \{\theta(X)u_{i}(Y) - \theta(Y)u_{i}(X)\}U_{i} + \{\theta(X)w_{a}(Y) - \theta(Y)w_{a}(X)\}W_{a}$$

$$+ (m - \alpha)\{\theta(Y)X - \theta(X)Y\} - (\ell + \beta)\{\theta(Y)FX - \theta(X)FY\} = 0.$$

Taking the scalar product with ζ and using $(28)_1$ and $(29)_1$, we have

$$\alpha \sum_{i=1}^{r} \{u_i(Y)v_i(X) - u_i(X)v_i(Y)\}$$

$$= \beta \sum_{i=1}^{r} \{u_i(Y)\eta_i(X) - u_i(X)\eta_i(Y)\} - 2\beta \bar{g}(X, JY).$$

Taking $X = V_j$, $Y = U_j$ and $X = \xi_j$, $Y = U_j$ to this equation by turns, we obtain $\alpha = 0$ and $\beta = 0$, respectively. Taking $X = \xi_j$ to (37), we have

$$\theta(X)\{m\xi_i + \ell V_i\} + \sum_{i=1}^r u_j(X)A_{N_j}\xi_i + \sum_{a=r+1}^n w_a(X)A_{E_a}\xi_i = 0.$$

Taking $X = \zeta$ to this, we have $m\xi_i + \ell V_i = 0$. It follows that $\ell = m = 0$. It is a contradiction to $(\ell, m) \neq (0, 0)$. Thus we have our theorem.

Corollary 3.3. There exist no generic lightlike submanifolds of an indefinite trans-Sasakian manifold with an (ℓ, m) -type connection subject such that ζ is tangent to M and F is parallel with respect to the connection ∇ .

Theorem 3.4. Let M be a generic lightlike submanifold of an indefinite trans-Sasakian manifold \bar{M} with an (ℓ, m) -type connection such that ζ is tangent to M. If U_i 's or V_i 's are parallel with respect to ∇ , then $\tau_{ij} = 0$ and $\alpha = \beta = 0$, i.e., \bar{M} is an indefinite cosymplectic manifold. *Proof.* (1) If U_i is parallel with respect to ∇ , then, taking the scalar product with ζ , V_j , W_a , U_j and N_j to (31) such that $\nabla_X U_i = 0$ respectively, we get

(38)
$$\alpha = \beta = 0$$
, $\tau_{ij} = 0$, $\rho_{ia} = 0$, $\eta_j(A_{N_i}X) = 0$, $h_i^*(X, U_j) = 0$.

As $\alpha = \beta = 0$, \bar{M} is an indefinite cosymplectic manifold.

(2) If V_i is parallel with respect to ∇ , then, taking the scalar product with ζ , U_i , V_i , W_a and N_i to (32) with $\nabla_X V_i = 0$ respectively, we get

(39)
$$\beta = 0$$
, $\tau_{ji} = 0$, $h_i^{\ell}(X, \xi_i) = 0$, $\lambda_{ai} = 0$, $h_i^{\ell}(X, U_j) = 0$.

As $h_i^{\ell}(X, U_j) = 0$, we get $h_i^{\ell}(\zeta, U_j) = 0$. Taking $X = U_j$ and $Y = \zeta$ to (20), we get $h_i^{\ell}(U_j, \zeta) = m\delta_{ij}$. On the other hand, replacing X by U to (27)₂, we have $h_i^{\ell}(U_j, \zeta) = (m - \alpha)\delta_{ij}$. It follows that $\alpha = 0$. Since $\alpha = \beta = 0$, \bar{M} is an indefinite cosymplectic manifold.

4. Indefinite generalized Sasakian space forms

Definition. An indefinite trans-Sasakian manifold \bar{M} is said to be an *indefinite* generalized Sasakian space form and denote it by $\bar{M}(f_1, f_2, f_3)$ if there exist three smooth functions f_1 , f_2 and f_3 on \bar{M} such that

$$(40) \qquad \widetilde{R}(\bar{X}, \bar{Y})\bar{Z} = f_1\{\bar{g}(\bar{Y}, \bar{Z})\bar{X} - \bar{g}(\bar{X}, \bar{Z})\bar{Y}\}$$

$$+ f_2\{\bar{g}(\bar{X}, J\bar{Z})J\bar{Y} - \bar{g}(\bar{Y}, J\bar{Z})J\bar{X} + 2\bar{g}(\bar{X}, J\bar{Y})J\bar{Z}\}$$

$$+ f_3\{\theta(\bar{X})\theta(\bar{Z})\bar{Y} - \theta(\bar{Y})\theta(\bar{Z})\bar{X}$$

$$+ \bar{g}(\bar{X}, \bar{Z})\theta(\bar{Y})\zeta - \bar{g}(\bar{Y}, \bar{Z})\theta(\bar{X})\zeta\},$$

where \widetilde{R} is the curvature tensor of the Levi-Civita connection $\overline{\nabla}$.

The notion of generalized Sasakian space form was introduced by Alegre et al. [1], while the indefinite generalized Sasakian space forms were introduced by Jin [4]. Sasakian space form, Kenmotsu space form and cosymplectic space form are important kinds of generalized Sasakian space forms such that

$$f_1=\frac{c+3}{4},\ f_2=f_3=\frac{c-1}{4};$$
 $f_1=\frac{c-3}{4},\ f_2=f_3=\frac{c+1}{4};$ $f_1=f_2=f_3=\frac{c}{4}$ respectively, where c is a constant J-sectional curvature of each space forms.

Denote by \bar{R} the curvature tensors of the non-metric ϕ -symmetric connection $\bar{\nabla}$ on \bar{M} . By directed calculations from (2), (3) and (5), we see that

$$(41) \quad \bar{R}(\bar{X}, \bar{Y})\bar{Z} = \tilde{R}(\bar{X}, \bar{Y})\bar{Z}$$

$$+ (\bar{\nabla}_{\bar{X}}\theta)(\bar{Z})\{\ell\bar{Y} + mJ\bar{Y}\} - (\bar{\nabla}_{\bar{Y}}\theta)(\bar{Z})\{\ell\bar{X} + mJ\bar{X}\}$$

$$+ \theta(\bar{Z})\{(\bar{X}\ell)\bar{Y} - (\bar{Y}\ell)\bar{X} + (\bar{X}m)J\bar{Y} - (\bar{Y}m)J\bar{X}$$

$$- m\alpha[\theta(\bar{Y})\bar{X} - \theta(\bar{X})\bar{Y}] - m\beta[\theta(\bar{Y})J\bar{X} - \theta(\bar{X})J\bar{Y}]$$

$$- 2m\beta\bar{g}(\bar{X}, J\bar{Y})\zeta\}.$$

Taking the scalar product with ξ_i and N_i to (41) by turns and, then denote by R and R^* the curvature tensors of the induced linear connections ∇ and

 ∇^* on M and S(TM) respectively. Using the Gauss-Weingarten formulae, we obtain Gauss equations for M and S(TM), respectively:

$$\begin{split} \bar{R}(X,Y)Z &= R(X,Y)Z \\ &+ \sum_{i=1}^{r} \{h_{i}^{\ell}(X,Z)A_{N_{i}}Y - h_{i}^{\ell}(Y,Z)A_{N_{i}}X\} \\ &+ \sum_{a=r+1}^{n} \{h_{a}^{s}(X,Z)A_{E_{a}}Y - h_{a}^{s}(Y,Z)A_{E_{a}}X\} \\ &+ \sum_{i=1}^{r} \{(\nabla_{X}h_{i}^{\ell})(Y,Z) - (\nabla_{Y}h_{i}^{\ell})(X,Z) \\ &+ \sum_{j=1}^{r} [\tau_{ji}(X)h_{j}^{\ell}(Y,Z) - \tau_{ji}(Y)h_{j}^{\ell}(X,Z)] \\ &+ \sum_{a=r+1}^{n} [\lambda_{ai}(X)h_{a}^{s}(Y,Z) - \lambda_{ai}(Y)h_{a}^{s}(X,Z)] \\ &- \ell[\theta(X)h_{i}^{\ell}(Y,Z) - \theta(Y)h_{i}^{\ell}(X,Z)] \\ &- m[\theta(X)h_{i}^{\ell}(FY,Z) - \theta(Y)h_{i}^{\ell}(FX,Z)]\}N_{i} \\ &+ \sum_{a=r+1}^{n} \{(\nabla_{X}h_{a}^{s})(Y,Z) - (\nabla_{Y}h_{a}^{s})(X,Z) \\ &+ \sum_{i=1}^{r} [\rho_{ia}(X)h_{i}^{\ell}(Y,Z) - \rho_{ia}(Y)h_{i}^{\ell}(X,Z)] \\ &- \ell[\theta(X)h_{a}^{s}(Y,Z) - \theta(Y)h_{a}^{s}(X,Z)] \\ &- m[\theta(X)h_{a}^{s}(FY,Z) - \theta(Y)h_{a}^{s}(FX,Z)]\}E_{a}, \end{split}$$

$$(43) \quad R(X,Y)PZ = R^{*}(X,Y)PZ \\ &+ \sum_{i=1}^{r} \{h_{i}^{*}(X,PZ)A_{\xi_{i}}^{*}Y - h_{i}^{*}(Y,PZ)A_{\xi_{i}}X\} \\ &+ \sum_{i=1}^{r} \{h_{i}^{*}(X,PZ)A_{\xi_{i}}^{*}Y - h_{i}^{*}(Y,PZ)A_{\xi_{i}}X\} \\ &+ \sum_{i=1}^{r} [\tau_{ik}(Y)h_{k}^{*}(X,PZ) - \tau_{ik}(X)h_{k}^{*}(Y,PZ)] \\ &- \ell[\theta(X)h_{i}^{*}(Y,PZ) - \theta(Y)h_{i}^{*}(FX,PZ)]\}\xi_{i}. \end{split}$$

substituting (42) and (40) and using $(22)_4$ and (43), we get

$$(44) \quad (\nabla_{X}h_{i}^{\ell})(Y,Z) - (\nabla_{Y}h_{i}^{\ell})(X,Z) \\ + \sum_{j=1}^{r} \{\tau_{ji}(X)h_{j}^{\ell}(Y,Z) - \tau_{ji}(Y)h_{j}^{\ell}(X,Z)\} \\ + \sum_{a=r+1}^{n} \{\lambda_{ai}(X)h_{a}^{s}(Y,Z) - \lambda_{ai}(Y)h_{a}^{s}(X,Z)\} \\ - \ell\{\theta(X)h_{i}^{\ell}(Y,Z) - \theta(Y)h_{i}^{\ell}(X,Z)\} \\ - m\{\theta(X)h_{i}^{\ell}(FY,Z) - \theta(Y)h_{i}^{\ell}(FX,Z)\} \\ - m\{(\bar{\nabla}_{X}\theta)(Z)u_{i}(Y) - (\bar{\nabla}_{Y}\theta)(Z)u_{i}(X)\} \\ - \theta(Z)\{[Xm + m\beta\theta(X)]u_{i}(Y) - [Ym + m\beta\theta(Y)]u_{i}(X)\} \\ = f_{2}\{u_{i}(Y)\bar{g}(X,JZ) - u_{i}(X)\bar{g}(Y,JZ) + 2u_{i}(Z)\bar{g}(X,JY)\}, \\ (45) \quad (\nabla_{X}h_{i}^{*})(Y,PZ) - (\nabla_{Y}h_{i}^{*})(X,PZ) \\ - \sum_{j=1}^{r} \{\tau_{ij}(X)h_{j}^{*}(Y,PZ) - \tau_{ij}(Y)h_{j}^{*}(X,PZ)\} \\ - \sum_{n}^{r} \{h_{j}^{\ell}(X,PZ)\eta_{i}(A_{N_{j}}Y) - h_{j}^{\ell}(Y,PZ)\eta_{i}(A_{N_{j}}X)\} \\ - \ell\{\theta(X)h_{i}^{*}(Y,PZ) - \theta(Y)h_{i}^{*}(X,PZ)\} \\ - m\{\theta(X)h_{i}^{*}(FY,PZ) - \theta(Y)h_{i}^{*}(FX,PZ)\} \\ - m\{\theta(X)h_{i}^{*}(FY,PZ) - \theta(Y)h_{i}^{*}(FX,PZ)\} \\ - (\bar{\nabla}_{X}\theta)(PZ)\{\ell\eta_{i}(Y) + mv_{i}(Y)\} + (\bar{\nabla}_{Y}\theta)(PZ)\{\ell\eta_{i}(X) + mv_{i}(X)\} \\ - \theta(PZ)\{[X\ell + m\alpha\theta(X)]\eta_{i}(Y) - [Y\ell + m\alpha\theta(Y)]\eta_{i}(X) \\ + [Xm + m\beta\theta(X)]v_{i}(Y) - [Ym + m\beta\theta(Y)]v_{i}(X)\} \\ = f_{1}\{g(Y,PZ)\eta_{i}(X) - g(X,PZ)\eta_{i}(Y)\} \\ + f_{2}\{v_{i}(Y)\bar{g}(X,JPZ) - v_{i}(X)\bar{g}(Y,JPZ) + 2v_{i}(PZ)\bar{g}(X,JY)\} \\ + f_{3}\{\theta(X)\eta_{i}(Y) - \theta(Y)\eta_{i}(X)\}\theta(PZ).$$

Theorem 4.1. Let M be a generic lightlike submanifold of an indefinite generalized Sasakian space form $\bar{M}(f_1, f_2, f_3)$ with an (ℓ, m) -type connection such that ζ is tangent to M. Then the functions α , β , f_1 , f_2 and f_3 satisfy

- (1) α is a constant on M,
- (2) $\alpha\beta = 0$, and
- (3) $f_1 f_2 = \alpha^2 \beta^2$ and $f_1 f_3 = \alpha^2 \beta^2 \zeta\beta$.

Proof. Applying $\bar{\nabla}_X$ to $\theta(U_i) = 0$ and $\theta(V_i) = 0$ by turns and using (8), (31), (32) and the facts that $g(FX, \zeta) = 0$ and $\zeta \in \Gamma(S(TM))$, we get

(46)
$$(\bar{\nabla}_X \theta)(U_i) = \alpha \eta_i(X) + \beta v_i(X), \qquad (\bar{\nabla}_X \theta)(V_i) = \beta u_i(X).$$

Applying ∇_X to $(30)_1$: $h_j^{\ell}(Y, U_i) = h_i^*(Y, V_j)$ and using (5), (16), (23), (25), (27)₂, (29)₂, (30)_{1,2,4}, (31) and (32), we obtain

$$\begin{split} (\nabla_{X}h_{j}^{\ell})(Y,U_{i}) &= (\nabla_{X}h_{i}^{*})(Y,V_{j}) \\ &- \sum_{k=1}^{r} \{\tau_{kj}(X)h_{k}^{\ell}(Y,U_{i}) + \tau_{ik}(X)h_{k}^{*}(Y,V_{j})\} \\ &- \sum_{a=r+1}^{n} \{\lambda_{aj}(X)h_{a}^{s}(Y,U_{i}) + \epsilon_{a}\rho_{ia}(X)h_{a}^{s}(Y,V_{j})\} \\ &+ \sum_{k=1}^{r} \{h_{i}^{*}(Y,U_{k})h_{k}^{\ell}(X,\xi_{j}) + h_{i}^{*}(X,U_{k})h_{k}^{\ell}(Y,\xi_{j})\} \\ &- g(A_{\xi_{j}}^{*}X,F(A_{N_{i}}Y)) - g(A_{\xi_{j}}^{*}Y,F(A_{N_{i}}X)) \\ &- \sum_{k=1}^{r} h_{j}^{\ell}(X,V_{k})\eta_{k}(A_{N_{i}}Y) \\ &+ \beta(m-\alpha)\{u_{j}(Y)v_{i}(X) - u_{j}(X)v_{i}(Y)\} \\ &+ \alpha(m-\alpha)u_{i}(Y)\eta_{i}(X) - \beta(\ell+\beta)u_{i}(X)\eta_{i}(Y). \end{split}$$

Substituting this and (29) into the modified equation (44) which is change i with j and Z with U_i , and using $(22)_3$, $(30)_3$ and $(46)_1$, we have

$$\begin{split} &(\nabla_{X}h_{i}^{*})(Y,V_{j})-(\nabla_{Y}h_{i}^{*})(X,V_{j})\\ &-\sum_{k=1}^{r}\{\tau_{ik}(X)h_{k}^{*}(Y,V_{j})-\tau_{ik}(Y)h_{k}^{*}(X,V_{j})\}\\ &-\sum_{a=r+1}^{n}\epsilon_{a}\{\rho_{ia}(X)h_{a}^{s}(Y,V_{j})-\rho_{ia}(Y)h_{a}^{s}(X,V_{j})\}\\ &+\sum_{k=1}^{r}\{h_{k}^{\ell}(X,V_{j})\eta_{i}(A_{N_{k}}Y)-h_{k}^{\ell}(Y,V_{j})\eta_{i}(A_{N_{k}}X)\}\\ &-\theta(X)h_{i}^{*}(FY,V_{j})+\theta(Y)h_{i}^{*}(FX,V_{j})\\ &+\beta(m-2\alpha)\{u_{j}(Y)v_{i}(X)-u_{j}(X)v_{i}(Y)\}\\ &+(\ell\beta-\alpha^{2}+\beta^{2})\{u_{j}(Y)\eta_{i}(X)-u_{j}(X)\eta_{i}(Y)\}\\ &=f_{2}\{u_{j}(Y)\eta_{i}(X)-u_{j}(X)\eta_{i}(Y)+2\delta_{ij}\bar{g}(X,JY)\}. \end{split}$$

Comparing this with (45) such that $PZ = V_i$ and using (46)₂, we obtain

$$\{f_1 - f_2 - \alpha^2 + \beta^2\}\{u_j(Y)\eta_i(X) - u_j(X)\eta_i(Y)\}\$$

= $2\alpha\beta\{u_j(Y)v_i(X) - u_{(j}X)v_i(Y)\}.$

Taking $Y = U_j$, $X = \xi_i$ and $Y = U_j$, $X = V_i$ to this by turns, we have

$$f_1 - f_2 = \alpha^2 - \beta^2, \qquad \alpha\beta = 0.$$

Applying $\bar{\nabla}_X$ to $\theta(\zeta) = 1$ and using (7) and the fact: $\theta \circ J = 0$, we get

(47)
$$(\bar{\nabla}_X \theta)(\zeta) = -\ell \theta(X).$$

Applying $\bar{\nabla}_X$ to $\eta_i(Y) = \bar{g}(Y, N_i)$ and using (1) and (9), we have

(48)
$$(\nabla_X \eta_i)(Y) = -g(A_{N_i} X, Y) + \sum_{j=1}^r \tau_{ij}(X) \eta_j(Y)$$
$$- \{\ell \eta_i(X) + m v_i(X)\} \theta(Y).$$

Applying ∇_X to $h_i^*(Y,\zeta) = (\ell + \beta)\eta_i(Y) + (m - \alpha)v_i(Y)$ and using (25), (26), (36), (48) and the fact that $\alpha\beta = 0$, we get

$$\begin{split} (\nabla_{X}h_{i}^{*})(Y,\zeta) &= X(\ell+\beta)\eta_{i}(Y) + X(m-\alpha)v_{i}(Y) \\ &+ (\ell+\beta)\{-g(A_{N_{i}}X,Y) - g(A_{N_{i}}Y,X) + \sum_{j=1}^{r}\tau_{ij}(X)\eta_{j}(Y) \\ &+ \beta\theta(X)\eta_{i}(Y) - \ell[\theta(Y)\eta_{i}(X) + \theta(X)\eta_{i}(Y)] \\ &- m[\theta(Y)v_{i}(X) + \theta(X)v_{i}(Y)]\} \\ &+ (m-\alpha)\{-g(A_{N_{i}}X,FY) - g(A_{N_{i}}Y,FX) \\ &+ \sum_{j=1}^{r}v_{j}(Y)\tau_{ij}(X) + \sum_{a=r+1}^{n}\epsilon_{a}w_{a}(Y)\rho_{ia}(X) \\ &+ \sum_{j=1}^{r}u_{j}(Y)\eta_{i}(A_{N_{j}}X) + (m-\alpha)\theta(Y)\eta_{i}(X) \\ &+ \beta\theta(X)v_{i}(Y) - (\ell+\beta)\theta(Y)v_{i}(X)\}. \end{split}$$

Substituting this and $(29)_2$ into (45) with $PZ = \zeta$ and using (47), we get

$$\{X\beta + (f_1 - f_3 - \alpha^2 + \beta^2)\theta(X)\}\eta_i(Y) - \{Y\beta + (f_1 - f_3 - \alpha^2 + \beta^2)\theta(Y)\}\eta_i(X)$$

= $(X\alpha)v_i(Y) - (Y\alpha)v_i(X).$

Taking $X = \zeta$, $Y = \xi_i$ and $X = U_j$, $Y = V_i$ to this by turns, we have

$$f_1 - f_3 = \alpha^2 - \beta^2 - \zeta \beta, \qquad U_j \alpha = 0.$$

Applying ∇_X to $h_i^{\ell}(Y,\zeta) = (m-\alpha)u_i(Y)$ and using (26) and (35), we get

$$(\nabla_{X} h_{i}^{\ell})(Y, \zeta) = X(m - \alpha)u_{i}(Y) - (\ell + \beta)h_{i}^{\ell}(Y, X)$$

$$- (m - \alpha)\{\sum_{j=1}^{r} u_{j}(Y)\tau_{ji}(X) + \sum_{a=r+1}^{n} \epsilon_{a}w_{a}(Y)\lambda_{ai}(X) + h_{i}^{\ell}(X, FY) + h_{i}^{\ell}(Y, FX) + \ell\theta(Y)u_{i}(X)$$

+
$$\beta[\theta(Y)u_i(X) - \theta(X)u_i(Y)]$$
.

Substituting this into (44) with $Z = \zeta$ and using (20) and (47), we have

$$(X\alpha)u_i(Y) = (Y\alpha)u_i(X).$$

Taking $Y = U_i$ to this result and using the fact that $U_i \alpha = 0$, we have $X \alpha = 0$. Therefore α is a constant. This completes the proof of the theorem.

Definition. (1) A screen distribution S(TM) is said to be totally umbilical [3] in M if there exist smooth functions γ_i on a neighborhood \mathcal{U} such that

$$h_i^*(X, PY) = \gamma_i g(X, PY).$$

In case $\gamma_i = 0$, we say that S(TM) is totally geodesic in M.

(2) An r-lightlike submanifold M is said to be screen conformal [4] if there exist non-vanishing smooth functions φ_i on \mathcal{U} such that

$$h_i^*(X, PY) = \varphi_i h_i^{\ell}(X, PY).$$

Theorem 4.2. Let M be a generic lightlike submanifold of an indefinite generalized Sasakian space form $\overline{M}(f_1, f_2, f_3)$ with an (ℓ, m) -type connection subject such that ζ is tangent to M. If

- (1) S(TM) is totally umbilical, or
- (2) M is screen conformal,

then $\bar{M}(f_1, f_2, f_3)$ is an indefinite β -Kenmotsu manifold with a semi-symmetric non-metric connection such that

$$\alpha = m = 0, \quad \beta = -\ell \neq 0, \qquad f_1 = -\beta^2, \quad f_2 = 0, \quad f_3 = -\zeta\beta.$$

Proof. (1) If S(TM) is totally umbilical, then $(29)_2$ is reduced to

$$\gamma_i \theta(X) = (\ell + \beta) \eta_i(X) + (m - \alpha) v_i(X).$$

Taking $X = \zeta$, $X = \xi_i$ and $X = V_i$ to this equation by turns, we have

(50)
$$\gamma_i = 0, \qquad \ell = -\beta, \qquad m = \alpha,$$

respectively. As $\gamma_i = 0$, we obtain $h_i^* = 0$. Thus. from $(30)_{1,2}$, we have

(51)
$$h_i^{\ell}(X, U_i) = 0, \qquad h_a^{s}(X, U_i) = 0.$$

Replacing Y by U_j to (20) and using (50)₁ and the result: $m = \alpha$, we get

$$h_i^{\ell}(U_i, X) = \alpha \theta(X) \delta_{ij}.$$

Taking $X = \zeta$ to this and using $(27)_2$ such that $m = \alpha$, we have $\alpha = 0$.

As $\alpha = m = 0$ and $\beta = -\ell \neq 0$, \bar{M} is an indefinite β -Kenmotsu manifold with a semi-symmetric non-metric connection and $f_1 + \beta^2 = f_2$ by Theorem 4.1. Taking $PZ = U_i$ to (45) and using (46)₁, (50) and (51), we have

$$f_2\{[v_i(Y)\eta_i(X) - v_i(X)\eta_i(Y)] + [v_i(Y)\eta_i(X) - v_i(X)\eta_i(Y)]\} = 0.$$

Taking $X = \xi_i$ and $Y = U_j$, we get $f_2 = 0$. Thus $f_1 = -\beta^2$ and $f_3 = -\zeta\beta$.

(2) If M is screen conformal, then, from $(28)_2$, $(29)_2$ and (49), we have

$$(\ell + \beta)\eta_i(X) + (m - \alpha)v_i(X) = \varphi_i(m - \alpha)u_i(X)\}.$$

Taking $X = \xi_i$ and $X = V_i$ to this equation by turns, we see that $\ell = -\beta$ and $m = \alpha$, respectively. As $\alpha\beta = 0$, it follows that

(52)
$$\ell m = \ell \alpha = m\beta = 0, \qquad \ell \beta = -\beta^2, \qquad m\alpha = \alpha^2.$$

Denote by μ_i the r-th vector fields on S(TM) such that $\mu_i = U_i - \varphi_i V_i$. Using $(30)_{1,2,3,4}$ and (49), we see that

(53)
$$h_j^{\ell}(X,\mu_i) = 0, \qquad h_a^{s}(X,\mu_i) = 0,$$
$$q(\mu_i,\mu_i) = -(\varphi_i + \varphi_i)\delta_{i,i}, \qquad J\mu_i = N_i - \varphi_i\xi_i.$$

Applying ∇_X to $\mu_i = U_i - \varphi_i V_i$ and then, taking the scalar product with ζ to the resulting equation and using (31) and (32), we obtain

$$g(\nabla_X \mu_i, \zeta) = -\{\alpha \eta_i(X) + \beta v_i(X) - \varphi_i \beta u_i(X)\}.$$

Applying $\bar{\nabla}_X$ to $\theta(\mu_i) = 0$ and using (8) and the last equation, we get

$$(54) \qquad (\bar{\nabla}_X \theta)(\mu_i) = \alpha \eta_i(X) + \beta v_i(X) - \varphi_i \beta u_i(X).$$

Applying ∇_Y to (49), we have

$$(\nabla_X h_i^*)(Y, PZ) = (X\varphi_i)h_i^{\ell}(Y, PZ) + \varphi_i(\nabla_X h_i^{\ell})(Y, PZ).$$

Substituting this and (49) into (45) and using (44), we have

$$\begin{split} &\sum_{j=1}^{r} \{ (X\varphi_{i})\delta_{ij} - \varphi_{i}\tau_{ji}(X) - \varphi_{j}\tau_{ij}(X) - \eta_{i}(A_{N_{j}}X) \} h_{j}^{\ell}(Y,PZ) \\ &- \sum_{j=1}^{r} \{ (Y\varphi_{i})\delta_{ij} - \varphi_{i}\tau_{ji}(Y) - \varphi_{j}\tau_{ij}(Y) - \eta_{i}(A_{N_{j}}Y) \} h_{j}^{\ell}(X,PZ) \\ &- \sum_{a=r+1}^{n} \{ \epsilon_{a}\rho_{ia}(X) + \varphi_{i}\lambda_{ai}(X) \} h_{a}^{s}(Y,PZ) \\ &+ \sum_{a=r+1}^{n} \{ \epsilon_{a}\rho_{ia}(Y) + \varphi_{i}\lambda_{ai}(Y) \} h_{a}^{s}(X,PZ) \\ &- (\bar{\nabla}_{X}\theta)(PZ) \{ \ell\eta_{i}(Y) + mv_{i}(Y) - \varphi_{i}mu_{i}(Y) \} \\ &+ (\bar{\nabla}_{Y}\theta)(PZ) \{ \ell\eta_{i}(X) + mv_{i}(X) - \varphi_{i}mu_{i}(X) \} \\ &- \theta(PZ) \{ [X\ell + \alpha^{2}\theta(X)]\eta_{i}(Y) - [Y\ell + \alpha^{2}\theta(Y)]\eta_{i}(X) \\ &+ (Xm)g(\mu_{i}, Y) - (Ym)g(\mu_{i}, X) \} \\ &= f_{1} \{ g(Y, PZ)\eta_{i}(X) - g(X, PZ)\eta_{i}(Y) \} \\ &+ f_{2} \{ g(\mu_{i}, Y)\bar{g}(X, JPZ) - g(\mu_{i}, X)\bar{g}(Y, JPZ) + 2g(\mu_{i}, PZ)\bar{g}(X, JY) \} \\ &+ f_{3} \{ \theta(X)\eta_{i}(Y) - \theta(Y)\eta_{i}(X) \} \theta(PZ). \end{split}$$

Replacing PZ by μ_i to this and using (46) and (52) \sim (54), we obtain

(55)
$$(f_{1} + \beta^{2})\{v_{j}(Y)\eta_{i}(X) - v_{j}(X)\eta_{i}(Y)\}$$

$$- \varphi_{j}(f_{1} + \beta^{2})\{u_{j}(Y)\eta_{i}(X) - u_{j}(X)\eta_{i}(Y)\}$$

$$+ (f_{2} + \alpha^{2})\{v_{i}(Y)\eta_{j}(X) - v_{i}(X)\eta_{j}(Y)\}$$

$$- \varphi_{i}(f_{2} + \alpha^{2})\{u_{i}(Y)\eta_{j}(X) - u_{i}(X)\eta_{j}(Y)\}$$

$$= 2f_{2}\delta_{ij}(\varphi_{j} + \varphi_{i})\bar{g}(X, JY).$$

Taking $X = \xi_i$ and $Y = V_j$ to this equation, we obtain

$$f_1 + f_2 = -(\alpha^2 + \beta^2).$$

From this result and Theorem 5.1, we see that $\alpha=0$. As $\alpha=m=0$ and $\beta=-\ell\neq 0$, $\bar{M}(f_1,f_2,f_3)$ is an indefinite β -Kenmotsu manifold with a semi-symmetric non-metric connection. Taking $X=\xi_j$ and $Y=U_j$ to the modified equation (55) which is change j with i, we obtain $f_2\varphi_i=0$. As all φ_i are non-vanishing functions, we get $f_2=0$. Thus $f_1=-\beta^2$ and $f_3=-\zeta\beta$.

Theorem 4.3. Let M be a generic lightlike submanifold of an indefinite generalized Sasakian space form $\bar{M}(f_1, f_2, f_3)$ with an (ℓ, m) -type connection such that ζ is tangent to M. If U_i 's or V_i 's are parallel with respect to ∇ , then $\bar{M}(f_1, f_2, f_3)$ is a flat manifold with an indefinite cosymplectic structure;

$$\alpha = \beta = 0,$$
 $f_1 = f_2 = f_3 = 0.$

Proof. (1) If U_i 's are parallel with respect to the connection ∇ , then we have the equations of (38). As $\alpha = \beta = 0$, we get $f_1 = f_2 = f_3$ by Theorem 4.1. Applying ∇_Y to (38)₅ and using the fact that $\nabla_Y U_j = 0$, we obtain

$$(\nabla_X h_i^*)(Y, U_j) = 0.$$

Substituting this equation and (38) into (45) with $PZ = U_i$, we have

$$f_1\{v_i(Y)\eta_i(X) - v_i(X)\eta_i(Y)\} + f_2\{v_i(Y)\eta_i(X) - v_i(X)\eta_i(Y)\} = 0.$$

Taking $X = \xi_i$ and $Y = V_j$ to this equation, we get $f_1 + f_2 = 0$. Thus we see that $f_1 = f_2 = f_3 = 0$ and \bar{M} is flat.

(2) If V_i 's are parallel with respect to the connection ∇ , then we have the equations in (39). As $\alpha = \beta = 0$, $f_1 = f_2 = f_3$ by Theorem 4.1. Taking $Y = \xi_j$ and $Y = U_j$ to (20) by turns and using (39)_{3,5}, we have

$$h_i^{\ell}(\xi_j, X) = 0,$$
 $h_i^{\ell}(U_j, X) = m\theta(X)\delta_{ij}.$

Using these two equations and (30), we see that

(56)
$$h_k^{\ell}(\xi_i, V_j) = 0, \qquad h_a^{s}(\xi_i, V_j) = \epsilon_a h_j^{\ell}(\xi_i, W_a) = 0, h_k^{\ell}(U_j, V_j) = 0, \qquad h_a^{s}(U_j, V_j) = \epsilon_a h_j^{\ell}(U_j, W_a) = 0.$$

From $(30)_1$ and $(39)_5$ and using the fact that $\nabla_X V_i = 0$, we have

$$h_i^*(Y, V_i) = 0.$$

Applying ∇_X to this equation and using the fact that $\nabla_X V_j = 0$, we have $(\nabla_X h_i^*)(Y, V_i) = 0$.

Substituting the last two equations into (45) such that $PZ = V_j$, we get

$$\begin{split} & \sum_{a=r+1}^{n} \epsilon_{a} \{ \rho_{ia}(Y) h_{a}^{s}(X, V_{j}) - \rho_{ia}(X) h_{a}^{s}(Y, V_{j}) \} \\ & + \sum_{k=1}^{r} \{ h_{k}^{\ell}(X, V_{j}) \eta_{i}(A_{N_{k}}Y) - h_{k}^{\ell}(Y, V_{j}) \eta_{i}(A_{N_{k}}X) \} \\ & = f_{1} \{ u_{j}(Y) \eta_{i}(X) - u_{j}(X) \eta_{i}(Y) \} + 2 f_{2} \delta_{ij} \bar{g}(X, JY). \end{split}$$

Taking $X = \xi_i$ and $Y = U_j$ to this equation and using (56), we obtain $f_1 + 2f_2 = 0$. It follows that $f_1 = f_2 = f_3 = 0$ and \bar{M} is flat.

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GENERIC LIGHTLIKE SUBMANIFOLDS OF A TRANS-SASAKIAN MANIFOLD $1219\,$

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