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ROBUST SPECIAL ANOSOV ENDOMORPHISMS

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ABSTRACT. In this paper we introduce the notion of *"robust special Anosov endomorphisms"*, and show that Anosov endomorphisms of tori which are not neither an Anosov diffeomorphism nor an expanding map, are not robust special.

1. Introduction

Let M be a compact, connected, boundaryless finite dimensional C^{∞} manifold. The big difference between the set of all C^1 Anosov diffeomorphisms and C^1 expanding maps on M and the set of all non-invertible C^1 Anosov endomorphisms on M is that the maps in the first set are C^1 -structurally stable but the maps in the second are not. Anosov [1] proved that every Anosov diffeomorphism is C^1 -structurally stable, and Shub [10] showed the same result for expanding differentiable maps. In [10], Shub also remarked that the techniques which prove expanding maps are structurally stable should also prove Anosov endomorphisms are structurally stable. However, Mané and Pugh [6] and Przytycki [9] proved that Anosov endomorphisms which are not diffeomorphisms nor expanding do not be C^1 -structurally stable.

Przytycki [9] showed that the set of all C^1 Anosov endomorphisms is an open subset of $C^1(M, M)$, the set of all C^1 maps from M to itself. We consider C^1 special Anosov endomorphisms. The natural question is that: Is the set of all C^1 special Anosov endomorphisms an open subset of $C^1(M, M)$?

In this paper we show that the answer in general is negative. The question is equivalent to: Is specialness robust for C^1 special Anosov endomorphisms?

A property \mathcal{P} for a map f is called *robust* if there is a neighborhood \mathcal{U} of f, in the desired topology, such that the property \mathcal{P} holds for all $g \in \mathcal{U}$. In this paper, we investigate the following question:

Question. Let f be a special Anosov endomorphism. Can we perturb f such that the new perturbed map is not special any more?

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In this paper, we show that the answer for the above question is negative in general. For this we first introduce the concept of a robust special Anosov endomorphism.

Definition. Let f be a C^1 special Anosov endomorphism on a closed manifold. We say that f is a C^1 robust special Anosov endomorphism if there exists a neighborhood U_f in C^1 topology, such that for any $g \in U_f$, g is also a special Anosov endomorphism. (For the definition of special Anosov endomorphisms and details see next sections.)

Example 1.1. C^1 Anosov diffeomorphisms are invertible and then special. It is well known that if f is a C^1 Anosov diffeomorphism on a closed manifold, then f is C^1 -structurally stable, and hence it is C^1 robust special.

Firstly, we show that any TA-covering map on an infra-nil-manifold is topologically mixing and therefore topologically transitive.

Proposition 1.2. Let N/Γ be an infra-nil-manifold. If $f : N/\Gamma \to N/\Gamma$ is a TA-covering map, then f is topologically mixing and therefore topologically transitive.

In [8], we proved the following theorem which for the convenience of reader, we will bring a sketch of the proof in Section 4:

Theorem 1.3 ([8, Theorem 1.10]). Let $f : N/\Gamma \to N/\Gamma$ be a covering map of a nil-manifold and denote as $A:N/\Gamma \to N/\Gamma$ the nil-endomorphism homotopic to f. If f is a special TA-map, then A is a hyperbolic nil-endomorphism and f is topologically conjugate to A.

Secondly, as a result of Proposition 1.2 and Theorem 1.3, because a torus is a nil-manifold (and so an infra-nil-manifold), we prove the following theorem.

Theorem 1.4. Suppose $n \ge 2$. Then for generic $f \in A^*(\mathbb{T}^n)$, there exists a residual set $R \subset \mathbb{T}^n$ such that for all $x \in R$, x has infinitely many unstable directions, where

 $A(\mathbb{T}^n) = \{ f : \mathbb{T}^n \to \mathbb{T}^n : f \text{ is a } C^1 Anosov \text{ endomorphism} \}, \\ A^*(\mathbb{T}^n) = A(\mathbb{T}^n) \setminus (\{Anosov \text{ diffeomorphisms}\} \cup \{expanding \text{ maps}\}).$

Finally, we conclude the main result:

Theorem 1.5 (Main Theorem). Every $f \in A^*(\mathbb{T}^n)$ is not a robust special Anosov endomorphism.

This theorem means if $f \in A^*(\mathbb{T}^n)$, we can perturb f such that the result map is not special any more or the set of all C^1 special Anosov endomorphisms is not an open subset of $C^1(M, M)$, in general.

2. Preliminaries

Let X be a compact metric space with metric d. For a continuous surjection $f: X \to X$, we let

$$X_f = \{ \tilde{x} = (x_i) : x_i \in X \text{ and } f(x_i) = x_{i+1}, i \in \mathbb{Z} \},\$$

$$\sigma_f((x_i)) = (f(x_i)).$$

The map $\sigma_f : X_f \to X_f$ is called the *shift map* determined by f. We call (X_f, σ_f) the inverse limit of (X, f). A homeomorphism $f: X \to X$ is called expansive if there is a constant e > 0 (called an expansive constant) such that if x and y are any two distinct points of X, then $d(f^i(x), f^i(y)) > e$ for some integer i. A continuous surjection $f: X \to X$ is called *c-expansive* if there is a constant e > 0 such that for $\tilde{x}, \tilde{y} \in X_f$ if $d(x_i, y_i) \leq e$ for all $i \in \mathbb{Z}$, then $\tilde{x} = \tilde{y}$. In particular, if there is a constant e > 0 such that for $x, y \in X$ if $d(f^i(x), f^i(y)) \leq e$ for all $i \in \mathbb{N}$, then x = y, we say that f is positively expansive. A sequence of points $\{x_i : a < i < b\}$ of X is called a δ -pseudo orbit of f if $d(f(x_i), x_{i+1}) < \delta$ for $i \in (a, b-1)$. Given $\epsilon > 0$ a δ -pseudo orbit of $\{x_i\}$ is called to be ϵ -traced by a point $x \in X$ if $d(f^i(x), x_i) < \epsilon$ for every $i \in (a, b-1)$. Here the symbols a and b are taken as $-\infty \leq a < b \leq \infty$ if f is bijective and as $-1 \le a < b \le \infty$ if f is not bijective. f has the pseudo orbit tracing property (abbrev. POTP) if for every $\epsilon > 0$ there is $\delta > 0$ such that every δ -pseudo orbit of f can be ϵ -traced by some point of X. We say that a homeomorphism $f: X \to X$ is a topological Anosov map (abbrev. TA-map) if f is expansive and has POTP. Analogously, we say that a continuous surjection $f: X \to X$ is a topological Anosov map if f is c-expansive and has POTP, and say that f is a topological expanding map if f is positively expansive and open. We can check that every topological expanding map is a TA-map (see [2, Remark 2.3.10]).

We bring here the definitions of nil-manifolds and infra-nil-manifolds from Karel Dekimpe in [4] and [5].

Let N be a Lie group and Aut(N) be the set of all automorphisms of N. Assume that $\overline{A} \in \text{Aut}(N)$ is an automorphism of N, such that there exists a discrete and cocompact subgroup Γ of N, with $\overline{A}(\Gamma) = \Gamma$. Then the space of left cosets N/Γ is a closed manifold, and \overline{A} induces a diffeomorphism A : $N/\Gamma \to N/\Gamma$, $g\Gamma \mapsto \overline{A}(g)\Gamma$. If we want this diffeomorphism to be Anosov, \overline{A} must be hyperbolic. It is known that this can happen only when N is nilpotent. So we restrict ourselves to that case, where the resulting manifold N/Γ is said to be a *nil-manifold*. Such a diffeomorphism A induced by an automorphism \overline{A} is called a nil-automorphism and is said to be a hyperbolic nil-automorphism, when \overline{A} is hyperbolic.

All tori, $\mathbb{T}^n = \mathbb{R}^n / \mathbb{Z}^n$ are examples of nil-manifolds.

Now we give an extended definition of nil-manifolds. Let N be a connected and simply connected nilpotent Lie group and $\operatorname{Aut}(N)$ be the group of continuous automorphisms of N. Then $Aff(N) = N \rtimes \operatorname{Aut}(N)$ acts on N in the following way:

$$\forall (n, \gamma) \in Aff(N), \forall x \in N : (n, \gamma).x = n\gamma(x).$$

So an element of Aff(N) consists of a translational part $n \in N$ and a linear part $\gamma \in \operatorname{Aut}(N)$ (as a set Aff(N) is just $N \times \operatorname{Aut}(N)$) and Aff(N) acts on N by first applying the linear part and then multiplying on the left by the translational part). In this way, Aff(N) can also be seen as a subgroup of Diff(N).

Now, let C be a compact subgroup of $\operatorname{Aut}(N)$ and consider any torsion free discrete subgroup Γ of $N \rtimes C$, such that the orbit space N/Γ is compact. Note that Γ acts on N as being also a subgroup of Aff(N). The action of Γ on N will be free and properly discontinuous, so N/Γ is a manifold, which is called an *infra-nil-manifold*.

Klein bottle is an example of infra-nil-manifolds.

In what follows, we will identify N with the subgroup $N \times \{id\}$ of $N \rtimes \operatorname{Aut}(N) = Aff(N)$, F with the subgroup $\{id\} \times F$ and $\operatorname{Aut}(N)$ with the subgroup $\{id\} \times \operatorname{Aut}(N)$.

It follows from Theorem 1 of L. Auslander in [3], that $\Gamma \cap N$ is a uniform lattice of N and that $\Gamma/(\Gamma \cap N)$ is a finite group. This shows that the fundamental group of an infra-nil-manifold N/Γ is virtually nilpotent (i.e., has a nilpotent normal subgroup of finite index). In fact $\Gamma \cap N$ is a maximal nilpotent subgroup of Γ and it is the only normal subgroup of Γ with this property. (This also follows from [3]).

If we denote by $p: N \rtimes C \to C$ the natural projection on the second factor, then $p(\Gamma) = \Gamma \cap N$ is a uniform lattice of N and that $\Gamma/(\Gamma \cap N)$. Let F denote this finite group $p(\Gamma)$, then we will refer to F as being the holonomy group of Γ (or of the infra-nil-manifold N/Γ). It follows that $\Gamma \subseteq N \rtimes F$. In case $F = \{id\}$, so $\Gamma \subseteq N$, the manifold N/Γ is a nil-manifold. Hence, any infra-nil-manifold N/Γ is finitely covered by a nil-manifold $N/(\Gamma \cap N)$. This also explains the prefix "infra".

Fix an infra-nil-manifold N/Γ , so N is a connected and simply connected nilpotent Lie group and Γ is a torsion free, uniform discrete subgroup of $N \rtimes F$, where F is a finite subgroup of Aut(N). We will assume that F is the holonomy group of Γ (so for any $\mu \in F$, there exists an $n \in N$ such that $(n, \mu) \in \Gamma$).

We can say that an element of Γ is of the form $n\mu$ for some $n \in N$ and some $\mu \in F$. Also, any element of Aff(N) can uniquely be written as a product $n\psi$, where $n \in N$ and $\psi \in \operatorname{Aut}(N)$. The product in Aff(N) is then given as

$$\forall n_1, n_2 \in N, \forall \psi_1, \psi_2 \in \operatorname{Aut}(N) : n_1 \psi_1 n_2 \psi_2 = n_1 \psi_1(n_2) \psi_1 \psi_2.$$

Now we can define infra-nil-endomorphisms as follows:

Let N be a connected, simply connected nilpotent Lie group and $F \subseteq \operatorname{Aut}(N)$ a finite group. Assume that Γ is a torsion free, discrete and uniform subgroup of $N \rtimes F$. Let $\overline{\mathcal{A}} : N \rtimes F \to N \rtimes F$ be an automorphism, such

that $\overline{\mathcal{A}}(F) = F$ and $\overline{\mathcal{A}}(\Gamma) \subseteq \Gamma$, then, the map

$$A: N/\Gamma \to N/\Gamma, \ \Gamma \cdot n \mapsto \Gamma \cdot \overline{\mathcal{A}}(n)$$

is the *infra-nil-endomorphism* induced by $\overline{\mathcal{A}}$. In case $\overline{\mathcal{A}}(\Gamma) = \Gamma$, we call A an *infra-nil-automorphism*.

In the definition above, $\Gamma \cdot n$ denotes the orbit of n under the action of Γ . The computation above shows that A is well defined. Note that infra-nil-automorphisms are diffeomorphisms, while in general an infra-nil-endomorphism is a self-covering map.

The following theorem shows that the only maps of an infra-nil-manifold, that lift to an automorphism of the corresponding nilpotent Lie group are exactly the infra-nil-endomorphisms defined above.

Theorem 2.1 ([5, Theorem 3.4]). Let N be a connected and simply connected nilpotent Lie group, $F \subseteq \operatorname{Aut}(N)$ a finite group and Γ a torsion free discrete and uniform subgroup of $N \rtimes F$ and assume that the holonomy group of Γ is F. If $\overline{A} : N \to N$ is an automorphism for which the map

$$A: N/\Gamma \to N/\Gamma, \ \Gamma \cdot n \mapsto \Gamma \cdot \overline{A}(n)$$

is well defined (meaning that $\Gamma \cdot \overline{A}(n) = \Gamma \cdot \overline{A}(\gamma \cdot n)$ for all $\gamma \in \Gamma$), then

$$\overline{\mathcal{A}}: N \rtimes F \to N \rtimes F: x \mapsto \phi x \phi^{-1} \ (conjugation \ in \ Aff(N))$$

is an automorphism of $N \rtimes F$, with $\overline{\mathcal{A}}(F) = F$ and $\overline{\mathcal{A}}(\Gamma) \subseteq \Gamma$. Hence, A is an infra-nil-endomorphism.

Let X and Y be metric spaces. A continuous surjection $f: X \to Y$ is called a *covering map* if for $y \in Y$ there exists an open neighborhood V_y of y in Y such that

$$f^{-1}(V_y) = \bigcup_i U_i \quad (i \neq i' \Rightarrow U_i \cap U'_i = \emptyset),$$

where each of U_i is open in X and $f_{|U_i} : U_i \to V_y$ is a homeomorphism. A covering map $f : X \to Y$ is especially called a *self-covering map* if X = Y. We say that a continuous surjection $f : X \to Y$ is a local homeomorphism if for $x \in X$ there is an open neighborhood U_x of x in X such that $f(U_x)$ is open in Y and $f_{|U_x} : U_x \to f(U_x)$ is a homeomorphism. It is clear that every covering map is a local homeomorphism. Conversely, if X is compact, then a local homeomorphism $f : X \to Y$ is a covering map (see [2, Theorem 2.1.1]).

Let X be a compact metric set and $f : X \to X$ a continuous surjection. A point $x \in X$ is said to be a *nonwandering point* if for any neighborhood U of x there is an integer n > 0 such that $f^n(U) \cap U \neq \emptyset$. The set $\Omega(f)$ of all nonwandering points is called the *nonwandering set*. Clearly $\Omega(f)$ is closed in X and invariant under f.

f is said to be topologically transitive (here X may be not necessarily compact) if there is $x_0 \in X$ such that the orbit $O^+(x_0) = \{f^i(x_0) : i \in \mathbb{Z}^{\geq 0}\}$ is dense in X. It is easy to check that if X is compact, a continuous surjection $f: X \to X$ is topologically transitive if and only if for any U, V nonempty open sets there is n > 0 such that $f^n(U) \cap V \neq \emptyset$.

A continuous surjection $f: X \to X$ of a metric space is topologically mixing if for nonempty open sets U, V there exists N > 0 such that $f^n(U) \cap V \neq \emptyset$ for all n > N. Topological mixing implies topological transitivity.

A map $f \in C^1(M, M)$ is said to be C^1 -structurally stable if there is an open neighborhood $\mathcal{N}(f)$ of f in $C^1(M, M)$ such that $g \in \mathcal{N}(f)$ implies that f and g are topologically conjugate.

Let M be a closed smooth manifold and let $C^1(M, M)$ be the set of all C^1 maps of M endowed with the C^1 topology. A map $f \in C^1(M, M)$ is called an *Anosov endomorphism* if f is a C^1 regular map and if there exist C > 0 and $0 < \lambda < 1$ such that for every $\tilde{x} = (x_i) \in M_f = \{\tilde{x} = (x_i) : x_i \in M \text{ and } f(x_i) = x_{i+1}, i \in \mathbb{Z}\}$ there is a splitting

$$T_{x_i}M = E_{x_i}^s \oplus E_{x_i}^u, \quad i \in \mathbb{Z}$$

(we show this by $T_{\tilde{x}}M = \bigcup_i (E_{x_i}^s \oplus E_{x_i}^u)$) so that for all $i \in \mathbb{Z}$:

 $(1) \ D_{x_i}f(E^{\sigma}_{x_i})=E^{\sigma}_{x_i+1} \ \text{where} \ \sigma=s,u,$

(2) for all $n \ge 0$

$$\| D_{x_i} f^n(v) \| \le C\lambda^n \| v \| \text{ if } v \in E^s_{x_i}, \\\| D_{x_i} f^n(v) \| \ge C^{-1} \lambda^{-n} \| v \| \text{ if } v \in E^u_{x_i}.$$

If, in particular, $T_{\tilde{x}}M = \bigcup_i E_{x_i}^u$ for all $\tilde{x} = (x_i) \in M_f$, then f is said to be expanding differentiable map, and if an Anosov endomorphism f is injective, then f is called an Anosov diffeomorphism. We can check that every Anosov endomorphism is a TA-map, and that every expanding differentiable map is a topological expanding map (see [2, Theorem 1.2.1]).

We define *special TA-maps* as follows. Let $f : X \to X$ be a continuous surjection of a compact metric space. Define the *stable* and *unstable* sets

$$W^{s}(x) = \{ y \in X : \lim_{n \to \infty} d(f^{n}(x), f^{n}(y)) = 0 \},\$$

$$W^{u}(\tilde{x}) = \{ y_{0} \in X : \exists \tilde{y} = (y_{i}) \in X_{f} \text{ s.t. } \lim_{i \to \infty} d(x_{-i}, y_{-i}) = 0 \}$$

for $x \in X$ and $\tilde{x} \in X_f$. A TA-map $f : X \to X$ is special if f satisfies the property that $W^u(\tilde{x}) = W^u(\tilde{y})$ for every $\tilde{x}, \tilde{y} \in X_f$ with $x_0 = y_0$. In other words, every x has only one unstable direction. Every hyperbolic nilendomorphism is a special TA-covering map (See [11, Remark 3.13]). By this and Theorem 1.3 we have the following corollary:

Corollary 2.2. A TA-covering map of a nil-manifold is special if and only if it is conjugate to a hyperbolic nil-endomorphism.

3. Proof of Proposition 1.2

To prove Proposition 1.2, we need the following lemmas and theorems:

Lemma 3.1 ([11, Lemma 1.5]). Let $f : N/\Gamma \to N/\Gamma$ be a self-covering map and let \overline{f} : $N \to N$ be a lift of f by the natural projection $\pi: N \to N/\Gamma$. If f is a TA-covering map, then \overline{f} has exactly one fixed point.

Lemma 3.2 ([11, Lemma 5.4]). If $f : N/\Gamma \to N/\Gamma$ is a TA-covering map, then $\Omega(f) = N/\Gamma$.

For continuing, we need the following theorem whose proof can be found in Theorem 3.4.4 in [2].

Theorem 3.3 (Topological decomposition theorem). Let $f : X \to X$ be a continuous surjection of a compact metric space. If $f: X \to X$ is a TA-map, then the following properties hold:

(1) (Spectral decomposition theorem due to Smale) The nonwandering set, $\Omega(f)$, contains a finite sequence B_i $(1 \leq i \leq l)$ of f-invariant closed subsets such that

(i) $\Omega(f) = \bigcup_{i=1}^{l} B_i$ (disjoint union),

- (ii) $f_{|B_i}: B_i \to B_i$ is topologically transitive.
- Such the subsets B_i are called basic sets.
- (2) (Decomposition theorem due to Bowen) For a basic set B there exist a > 0 and a finite sequence C_i $(0 \le i \le a - 1)$ of closed subsets such that
 - (i) $C_i \cap C_j = \emptyset \ (i \neq j), \ f(C_i) = C_{i+1} \ and \ f^a(C_i) = C_i,$

 - (ii) $B = \bigcup_{i=0}^{a-1} C_i$, (iii) $f^a_{|C_i|} : C_i \to C_i$ is topologically mixing,

Such the subsets C_i are called elementary sets.

Proposition 3.4. If $f : N/\Gamma \to N/\Gamma$ is a TA-covering map, then N/Γ is indeed an elementary set.

Proof. By Lemma 3.1, let $\overline{f}: N \to N$ be the lift of f such that $\overline{f}(e) = e$. By the commuting diagram:

$$\begin{array}{c} N \xrightarrow{f} N \\ \pi \downarrow & \downarrow \pi \\ N/\Gamma \xrightarrow{f} N/\Gamma \end{array}$$

we have,

$$f([e]) = f(\pi(e)) = \pi(f(e)) = \pi(e) = [e].$$

Therefore, [e] is a fixed point of f. By Lemma 3.2, $\Omega(f) = N/\Gamma$. As N is connected and π is a continuous surjection then N/Γ is connected. In the proof of part (1) of spectral decomposition theorem, they prove that basic sets are close and open. Hence by connectedness of $\Omega(f) = N/\Gamma$, it consists of only one basic set, say B. On the other hand, by part (2) of spectral decomposition theorem, $N/\Gamma = B$ is the union of elementary sets. There is an elementary set, say C, such that $[e] \in C$. Since elementary sets are disjoint, by condition $f(C_i) = C_{i+1}, N/\Gamma = B$ consists of only one elementary set. \Box

Proof. (Proof of Proposition 1.2) By Theorem 3.4, N/Γ is an elementary set and the "a" in item (i) of part (2) of Theorem 3.3 must be equal to 1 and by item (iii) of part (2), f is topologically mixing on N/Γ . Of course, by this result f is topologically transitive on N/Γ .

4. Proof of Theorem 1.3

Here we give a brief outline proof of Theorem 1.3:

Proof. Suppose that $f: N/\Gamma \to N/\Gamma$ is a special *TA*-covering map of an infra-nil-manifold. Sumi [11] proved that if f is injective (or expanding), then f conjugates to a hyperbolic infra-nil-automorphism (or an expanding infra-nil-endomorphism). By Dekimpe [5], the main results of [11] are incorrect for infranil-manifolds. But if we consider nil-manifolds instead of infra-nil-manifolds, we can repair main results. So, we consider them for nil-manifolds. So consider the case f is not injective nor expanding, and $A: N/\Gamma \to N/\Gamma$ is the unique nil-endomorphism homotopic to f (see [8], for details), and let $\overline{f}, \overline{A}: N \to N$ be the automorphisms which are lifts of f and A, respectively, by the natural projection π . Sumi [11] proved that there is a unique continuous surjective map $\overline{h}: N \to N$ such that

$$\overline{A} \circ \overline{h} = \overline{h} \circ \overline{f}.$$

So \overline{h} is a so-called *semi-conjugacy* between \overline{f} and \overline{A} . We should find a conjugacy between f and A.

For continuous maps f and g of N we define $D(f,g) = \sup\{D(f(x), g(x)) : x \in N\}$ where D denotes a left invariant, Γ -invariant Riemannian distance for N. Notice that D(f,g) is not necessary finite. Since $D_e\overline{A}$ is hyperbolic, the Lie algebra Lie(N) of N splits into the direct sum $Lie(N) = E_e^s \oplus E_e^u$ of subspaces E_e^s and E_e^u such that $D_e\overline{A}(E_e^s) = E_e^s$, $D_e\overline{A}(E_e^u) = E_e^u$ and there are $c > 1, 0 < \lambda < 1$ so that for all $n \ge 0$

$$\begin{split} ||D_e A^n(v)|| &\leq c\lambda^n ||v|| \quad (v \in E_e^s), \\ ||D_e \overline{A}^{-n}(v)|| &\leq c\lambda^n ||v|| \quad (v \in E_e^u), \end{split}$$

where $||\cdot||$ is the Riemannian metric. Let $\overline{L}^{\sigma}(e) = \exp(E_e^{\sigma})$ ($\sigma = s, u$) and let $\overline{L}^{\sigma}(x) = x \cdot \overline{L}^{\sigma}(e)(\sigma = s, u)$ for $x \in N$. Since left translations are isometries under the metric D, it follows that for all $x \in N$

$$\overline{L}^{s}(x) = \{ y \in N : D(\overline{A}^{i}(x), \overline{A}^{i}(y)) \to 0 \ (i \to \infty) \},\$$
$$\overline{L}^{u}(x) = \{ y \in N : D(\overline{A}^{i}(x), \overline{A}^{i}(y)) \to 0 \ (i \to -\infty) \}.$$

Let $x \in N$, we define the stable set and unstable sets of x for f and A as follow (for more details see [2]):

$$\overline{W}^{s}(x) = \{ y \in N : \lim_{i \to \infty} D(\overline{f}^{i}(x), \overline{f}^{i}(y)) = 0 \},\$$
$$\overline{W}^{u}(x, \mathbf{e}) = \{ y \in N : \lim_{i \to -\infty} D(\overline{f}^{i}(x), \overline{f}^{i}(y)) = 0 \},\$$

where e = (..., e, e, e, ...).

Lemma 4.1 ([11, Lemma 2.4]). For the semi-conjugacy \overline{h} , we have the following properties:

- (1) There exists K > 0 such that $D(\overline{h} \circ \gamma(x), \gamma \circ \overline{h}(x)) < K$ for $x \in \mathbb{N}$ and $\gamma \in \Gamma$.
- (2) For any $\lambda > 0$, there exists $L \in \mathbb{N}$ such that $D(\overline{h} \circ \gamma(x), \gamma \circ \overline{h}(x)) < \lambda$ for $x \in N$ and $\gamma \in \overline{A}^L_*(\Gamma)$.
- (3) For $x \in N$ and $\gamma \in \bigcap_{i=0}^{\infty} \overline{A}_*^i(\Gamma)$, we have $\overline{h} \circ \gamma(x) = \gamma \circ \overline{h}(x)$. (4) For $x \in N$ and $\gamma \in \Gamma$, we have $\overline{h} \circ \gamma(x) \in \overline{L}^s(\gamma \circ \overline{h}(x))$.

Remark 4.2. Since \overline{h} is *D*-uniformly continuous then $\overline{h}(\overline{W}^s(x)) = \overline{L}^s(\overline{h}(x))$ and $\overline{h}(\overline{W}^{u}(x;\mathbf{e})) = \overline{L}^{u}(\overline{h}(x)).$

Lemma 4.3. The following statements hold:

- (1) $\gamma(\overline{W}^{s}(x)) = \overline{W}^{s}(\gamma(x))$ for $\gamma \in \Gamma$ and $x \in N$,
- (2) $\gamma(\overline{W}^{u}(x; e)) = \overline{W}^{u}(\gamma(x); e)$ for $\gamma \in \Gamma$ and $x \in N$,
- (3) $\gamma(\overline{L}^{s}(x)) = \overline{L}^{s}(\gamma(x))$ for $\gamma \in \Gamma$ and $x \in N$,
- (4) $\gamma(\overline{L}^{u}(x)) = \overline{L}^{u}(\gamma(x))$ for $\gamma \in \Gamma$ and $x \in N$,
- (5) If $x \in \overline{W}^{u}(e; e)$, then $\overline{W}^{u}(x; e) = \overline{W}^{u}(e; e)$,
- (6) If $x \in \overline{L}^u(e)$, then $\overline{L}^u(x) = \overline{L}^u(e)$.

Proof. For proof, see [8], Lemmas 3.13, 3.14 and 4.2.

Lemma 4.4 ([2, Lemma 8.6.2]). For $\epsilon > 0$ there is $\delta > 0$ such that if D(x, y) < 0 $\delta, x, y \in N$, then $\overline{W}^{s}(x) \subset U_{\epsilon}(\overline{W}^{s}(y))$ and $\overline{W}^{u}(x; e) \subset U_{\epsilon}(\overline{W}^{u}(y; e))$. Where for a set S, $U_{\epsilon}(S) = \{y \in N : D(y, S) < \epsilon\}$.

Remark 4.5. There is a $\delta_K > 0$ such that $D(\overline{h}(x), x) < \delta_K$ for $x \in N$, we have (see [2] page 270 (8.5))

 $\overline{W}^{s}(x) \subset U_{\delta_{K}}(\overline{L}^{s}(\overline{h}(x))) \quad \text{and} \quad \overline{W}^{u}(x; \mathbf{e}) \subset U_{\delta_{K}}(\overline{L}^{u}(\overline{h}(x))).$

For simplicity, let $\Gamma_{\overline{f}} = (\overline{W}^u(e; \mathbf{e}) \rtimes \{id_{\operatorname{Aut}(N)}\}) \cap \Gamma$ and $\Gamma_{\overline{A}} = (\overline{L}^u(e) \rtimes I)$ $\{id_{\operatorname{Aut}(N)}\})\cap\Gamma.$

Lemma 4.6. The following statements hold:

(1) $\Gamma_{\overline{A}}$ and $\Gamma_{\overline{f}}$ are subgroups of Γ . (2) $\Gamma_{\overline{f}} \subset \Gamma_{\overline{A}}$. (3) $\overline{h}(\gamma(v)) = \gamma(\overline{h}(v))$ for each $\gamma \in \Gamma_{\overline{f}}$ and $v \in \overline{W}^u(e; e)$.

(4) If
$$\overline{W}^{u}(\gamma_{1}(e); e) = \overline{W}^{u}(\gamma_{2}(e); e)$$
 for some $\gamma_{1}, \gamma_{2} \in \Gamma$, then we have
 $\gamma_{1}(\overline{h}(\gamma_{1}^{-1}(x))) = \gamma_{2}(\overline{h}(\gamma_{2}^{-1}(x)))$ for $x \in \overline{W}^{u}(\gamma_{1}(e); e)$.

Proof. (1) Let $x, y \in \overline{L}^u(e)$, since $A^i(e) = e$ for all i, then by definition,

$$\lim_{i \to -\infty} D(A^i(x), e) = \lim_{i \to -\infty} D(A^i(x), A^i(e)) = 0,$$

(4.1)
$$\lim_{i \to -\infty} D(A^i(y), e) = \lim_{i \to -\infty} D(A^i(y), A^i(e)) = 0.$$

As D is left invariant we have

$$0 \leq \lim_{i \to -\infty} D(A^{i}(xy^{-1}), A^{i}(e)) = \lim_{i \to -\infty} D(A^{i}(x)A^{i}(y^{-1}), e)$$

=
$$\lim_{i \to -\infty} D(A^{i}(x)A^{-i}(y), A^{i}(x)A^{-i}(x))$$

(D is left invariant) =
$$\lim_{i \to -\infty} D(A^{-i}(y), A^{-i}(x))$$

$$\leq \lim_{i \to -\infty} D(A^{-i}(y), e) + D(e, A^{-i}(x))$$

(equation (4.1)) =
$$\lim_{i \to -\infty} D(A^{i}(y), e) + D(A^{i}(x), e) = 0.$$

Thus $xy^{-1} \in \overline{L}^u(e)$ and $\overline{L}^u(e)$ is a subgroup of N. So $(\overline{L}^u(e) \rtimes \{id_{\operatorname{Aut}(N)}\}) \cap \Gamma$ is a subgroup of Γ .

For the second part, let $\gamma_1, \gamma_2 \in \Gamma_{\overline{f}}$. Since Γ is a group we have $\gamma_1 \gamma_2^{-1} \in \Gamma$. Now consider that $\gamma_1, \gamma_2 \in (\overline{W}^u(e; \mathbf{e}) \rtimes \{id_{\operatorname{Aut}(N)}\})$. There exist $x_1, x_2 \in \overline{W}^u(e; \mathbf{e})$ such that $\gamma_1 = (x_1, id_N)$ and $\gamma_2 = (x_2, id_N)$. Therefore,

$$x_1 \overline{W}^u(e; \mathbf{e}) = \gamma_1(\overline{W}^u(e; \mathbf{e}))$$

(Lemma 4.3, part (2))
$$= \overline{W}^u(\gamma_1(e); \mathbf{e})$$
$$= \overline{W}^u(x_1; \mathbf{e})$$

(Lemma 4.3, part (5))
$$= \overline{W}^u(e; \mathbf{e}).$$

Similarly, $x_2 \overline{W}^u(e; \mathbf{e}) = \overline{W}^u(e; \mathbf{e})$. So we have $x_1 \overline{W}^u(e; \mathbf{e}) = x_2 \overline{W}^u(e; \mathbf{e})$ and then $x_1 x_2^{-1} \in \overline{W}^u(e; \mathbf{e})$. Finally,

$$\begin{split} \gamma_1 \gamma_2^{-1} &= (x_1, id_N)(x_2, id_N)^{-1} \\ &= (x_1, id_N)(x_2^{-1}, id_N) \\ &= (x_1 x_2^{-1}, id_N) \in \overline{W}^u(e; \mathbf{e}) \rtimes \{ id_{\operatorname{Aut}(N)} \}, \end{split}$$

and we have the result.

(2) Take $(x, \alpha) = \gamma \in \Gamma_{\overline{f}}$ $(x \in N, \alpha \in C)$, such that $\gamma \notin \Gamma_{\overline{A}}$. So, $x \notin \overline{L}^{u}(e)$ and for each $n \in \mathbb{Z}$, $n \neq 0$, $x^{n} \notin \overline{L}^{u}(e)$. By part (1), Remark 4.5 and the fact that $\overline{h}(e) = e$ for all $n \in \mathbb{Z}$, we have $x^{n} \in \overline{W}^{u}(e; \mathbf{e}) \subset U_{\delta_{K}}(\overline{L}^{u}(e))$, which is impossible.

(3) Let $\gamma = (x, id_N)$ for some $x \in N$ and $v \in \overline{W}^u(e; \mathbf{e})$. We have $\gamma(v) \in \gamma(\overline{W}^u(e; \mathbf{e}))$ (Lemma 4.3, part (2)) $= \overline{W}^u(\gamma(e); \mathbf{e})$ $= \overline{W}^u(x; \mathbf{e})$ (Lemma 4.3, part (5)) $= \overline{W}^u(e; \mathbf{e}),$

so,

$$\overline{h}(\gamma(v)) \in \overline{h}(\overline{W}^u(e; \mathbf{e}))$$
(Remark 4.2) = $\overline{L}^u(e)$.

By part (2), $\gamma \in \Gamma_{\overline{A}}$. Thus

$$\gamma(\overline{h}(v)) \in \gamma(\overline{h}(\overline{W}^{u}(e; \mathbf{e}))$$
(Remark 4.2) = $\gamma(\overline{L}^{u}(e))$
(Lemma 4.3, part (4)) = $(\overline{L}^{u}(\gamma(e)))$
= $\overline{L}^{u}(x)$
(Lemma 4.3, part (6)) = $\overline{L}^{u}(e)$.

Again by Lemma 4.3 and last part of the above relation, $\overline{L}^u(\gamma(\overline{h}(v))) = \overline{L}^u(e)$, and

$$\overline{h}(\gamma(v)) \in \overline{L}^u(e) = \overline{L}^u(\gamma(\overline{h}(v))).$$

On the other hand, by part (4) of Lemma 4.1, $\overline{h}(\gamma(v)) \in \overline{L}^s(\gamma(\overline{h}(v)))$. Since $\overline{L}^u(\gamma(\overline{h}(v))) \cap \overline{L}^s(\gamma(\overline{h}(v))) = \{\gamma(\overline{h}(v))\}$ (see [11, Lemma 2.1]), then $\overline{h}(\gamma(v)) = \gamma(\overline{h}(v))$.

(4) We have $x \in \overline{W}^{u}(\gamma_{1}(e); \mathbf{e}) = \gamma_{1}(\overline{W}^{u}(e; \mathbf{e}))$. Thus, $\gamma_{1}^{-1}(x) \in \overline{W}^{u}(e; \mathbf{e})$. Similarly, $\gamma_{2}^{-1}(x) \in \overline{W}^{u}(e; \mathbf{e})$. Now, by part (3),

$$\gamma_1(\overline{h}(\gamma_1^{-1}(x))) = \overline{h}(\gamma_1(\gamma_1^{-1}(x)))$$
$$= \overline{h}(x)$$
$$= \overline{h}(\gamma_2(\gamma_2^{-1}(x)))$$
$$= \gamma_2(\overline{h}(\gamma_2^{-1}(x))).$$

According to part (4) of Lemma 4.6, we can define a map

$$\overline{h}': \bigcup_{\gamma \in \Gamma} \overline{W}^u(\gamma(e); \mathbf{e}) \to \bigcup_{\gamma \in \Gamma} \overline{L}^u(\gamma(e))$$

by

$$\overline{h}'(x) = \gamma(\overline{h}(\gamma^{-1}(x))) \quad x \in \overline{W}^u(\gamma(e); \mathbf{e}) \ (\gamma \in \Gamma).$$

Next lemma shows some properties of \overline{h}' :

Lemma 4.7. The following statements hold:

 $\begin{array}{ll} (1) \ \overline{A} \circ \overline{h}' = \overline{h}' \circ \overline{f} \ on \bigcup_{\gamma \in \Gamma} \overline{W}^u(\gamma(e); \boldsymbol{e}), \\ (2) \ D(\overline{h}', id_{|\bigcup_{\gamma \in \Gamma} \overline{W}^u(\gamma(e); \boldsymbol{e})}) < \infty, \\ (3) \ \overline{h}'(\gamma(e)) = \gamma(e) \ for \ \gamma \in \Gamma, \\ (4) \ if \ x \in \overline{W}^u(\gamma(e); \boldsymbol{e})(\gamma \in \Gamma), \ then \ \overline{h}'(x) \in \overline{L}^u(\gamma(e)) \ and \ \overline{h}'(x) \in \overline{L}^s(\overline{h}(x)), \\ (5) \ if \ y \in \overline{W}^s(x) \ for \ x, \ y \in \bigcup_{\gamma \in \Gamma} \overline{W}^u(\gamma(e); \boldsymbol{e}), \ then \ \overline{h}'(y) \in \overline{L}^s(\overline{h}'(x)). \end{array}$

Proof. For proof, see [8], Lemma 4.4.

Lemma 4.8. \overline{h}' is *D*-uniformly continuous.

Proof. For proof, see [8], Lemma 4.7.

Lemma 4.9. $\bigcup_{\gamma \in \Gamma} \overline{W}^u(\gamma(e); e)$ is dense in N.

Proof. For proof, see [8], Lemma 4.13.

By Lemma 4.8, \overline{h}' is extended to a continuous map $\tilde{h} : N \to N$. From Lemma 4.7(1), (2) and (3), and uniqueness of \overline{h} , we have $\overline{h} = \tilde{h}$ and $\overline{h}(\gamma(e)) = \gamma(e)$ for all $\gamma \in \Gamma$.

Lemma 4.10. For all $\gamma \in \Gamma$ and $x \in N$, $\overline{h}(\gamma(x)) = \gamma(\overline{h}(x))$.

Proof. According to Lemma 4.1(4), we have

(4.2)
$$\overline{h}(\gamma(x)) \in \overline{L}^{*}(\gamma(\overline{h}(x))).$$

Suppose that $x \in \bigcup_{\gamma \in \Gamma} \overline{W}^u(\gamma(e); \mathbf{e})$. Then there is $\gamma_x \in \Gamma$ such that $x \in \overline{W}^u(\gamma_x(e); \mathbf{e})$. For each $\gamma \in \Gamma$ we have

$$\gamma(x) \in \overline{h}(\overline{W}^u(\gamma_x(e); \mathbf{e})) = \overline{W}^u(\gamma(\gamma_x(e)); \mathbf{e}).$$

Thus

(4.3)
$$\overline{h}(\gamma(x)) \in \overline{h}\left(\overline{W}^{u}(\gamma(\gamma_{x}(e)); \mathbf{e})\right)$$
$$(= \overline{L}^{u}(\overline{h}(\gamma(\gamma_{x}(e))))$$
$$= \overline{L}^{u}(\gamma(\gamma_{x}(e))).$$

On the other hand,

(4.4)

$$\gamma(\overline{h}(x)) \in \gamma(\overline{h}(\overline{W}^{u}(\gamma_{x}(e); \mathbf{e})))$$

$$(by \text{ Remark } 4.2) = \gamma(\overline{L}^{u}(\overline{h}(\gamma_{x}(e))))$$

$$= \gamma(\overline{L}^{u}(\gamma_{x}(e)))$$

$$(by \text{ Lemma } 4.3, \text{ part } (4)) = \overline{L}^{u}(\gamma(\gamma_{x}(e))).$$

By (4.4), we have $\overline{L}^{u}(\gamma(\gamma_{x}(e))) = \overline{L}^{u}(\gamma(\overline{h}(x)))$. Therefore, by (4.3) we have (4.5) $\overline{h}(\gamma(x)) \in \overline{L}^{u}(\gamma(\overline{h}(x))).$

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By (4.2) and (4.5) we have

(4.6)
$$\overline{h}(\gamma(x)) \in \overline{L}^u(\gamma(\overline{h}(x))) \cap \overline{L}^s(\gamma(\overline{h}(x))) = \{\gamma(\overline{h}(x))\}.$$

Thus for each $x \in \bigcup_{\gamma \in \Gamma} \overline{W}^u(\gamma(e); \mathbf{e})$ we have $\overline{h}(\gamma(x)) = \gamma(\overline{h}(x))$. Since \overline{h} is continuous and $\bigcup_{\gamma \in \Gamma} \overline{W}^u(\gamma(e); \mathbf{e})$ is dense in N, we have the desired result. \Box

Hence, \overline{h} induces a homeomorphism $h: N/\Gamma \to N/\Gamma$ such that $h \circ \pi = \pi \circ \overline{h}$, i.e., the following diagram commutes:



Now, it is easy to see that h is the desired conjugacy between f and A.

5. Proof of Theorems 1.4 and 1.5

From now on suppose that $f \in C^1(\mathbb{T}^n, \mathbb{T}^n)$. To prove Theorem 1.4, we need the following theorems:

Zhang [12], by use of the fact that C^1 Anosov endomorphisms, which are not injective nor expanding, are not C^1 -structurally stable, showed that:

Theorem 5.1 ([12], Main Theorem). Suppose $n \ge 2$. Then for generic $f \in A^*(\mathbb{T}^n)$, f is not topologically conjugate to any hyperbolic toral endomorphism.

Micena and Tahzibi [7], proved that:

Theorem 5.2 ([7], Theorem 1.4). Let M be a closed manifold and $f: M \to M$ topologically transitive endomorphism. Then

- (1) either f is a special Anosov endomorphism
- (2) or there exists a residual subset $R \subset M$ such that for every $x \in R$, x has infinitely many unstable directions.

Proof. (Proof of Theorem 1.4) We know that \mathbb{T}^n is a case of nil-manifold. Clearly, every C^1 Anosov endomorphism on a closed manifold is a *TA*-covering map.

According to Theorem 5.1, for generic $f \in A^*(\mathbb{T}^n)$, f is not topologically conjugate to any hyperbolic toral endomorphism. Hence by Theorem 1.3 for \mathbb{T}^n $(n \geq 2)$, f is not special.

On the other hand Proposition 1.2 says that f is topologically transitive. Finally, by Theorem 5.2 and the fact that f is not special, there exists a residual subset $R \subset \mathbb{T}^n$ such that for every $x \in R$, x has infinitely many unstable directions with respect to f. End of the proof of Theorem 1.5 (Main Theorem). Let $\Lambda \subset A^*(\mathbb{T}^n)$ be the generic set gotten in Theorem 1.4. According to Baire category theorem, Λ is dense in $A^*(\mathbb{T}^n)$. Thus if $f \in A^*(\mathbb{T}^n)$, then for every neighborhood U of f there is at least one $f \in \Lambda$ which is not special.

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