

## USEFUL OPERATORS ON REPRESENTATIONS OF THE RATIONAL CHEREDNIK ALGEBRA OF TYPE $\mathfrak{sl}_n$

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**Abstract.** Let  $n$  denote an integer greater than 2 and let  $c$  denote a nonzero complex number. In this paper, we introduce a family of elements of the rational Cherednik algebra  $\mathbf{H}^{\mathfrak{sl}_n}(c)$  of type  $\mathfrak{sl}_n$ , which are analogous to the Dunkl-Cherednik elements of the rational Cherednik algebra  $\mathbf{H}^{\mathfrak{gl}_n}(c)$  of type  $\mathfrak{gl}_n$ . We also introduce the raising and lowering element of  $\mathbf{H}^{\mathfrak{sl}_n}(c)$  which are useful in the representation theory of the algebra  $\mathbf{H}^{\mathfrak{sl}_n}(c)$ , and provide simple results related to these elements.

### 1. Introduction

Throughout this paper, let  $n$  denote an integer greater than 2, and let  $c$  denote a nonzero complex number unless otherwise stated.

Roughly speaking, the rational Cherednik algebra  $\mathbf{H}^{\mathfrak{gl}_n}(c)$  of type  $\mathfrak{gl}_n$  associated with  $c$  is the algebra generated by two polynomial subalgebras  $\mathbb{C}[\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n]$ ,  $\mathbb{C}[\mathbf{y}_1, \mathbf{y}_2, \dots, \mathbf{y}_n]$ , and the symmetric group  $\mathcal{S}_n$  subject to certain relations. The algebra  $\mathbf{H}^{\mathfrak{gl}_n}(c)$  acts on the space  $\mathbb{C}[\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n]$  of all polynomials in  $n$  variables  $\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n$  in the following way. The element  $\mathbf{x}_i$  acts as multiplication by  $\mathbf{x}_i$ , and the element  $w \in \mathcal{S}_n$  permutes the variables  $\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n$  naturally. On the other hand, the element  $\mathbf{y}_i$  acts as the Dunkl operator:

$$D_i = \frac{\partial}{\partial \mathbf{x}_i} - c \sum_{j \neq i} \frac{1}{\mathbf{x}_i - \mathbf{x}_j} (1 - s_{ij}).$$

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In [3], Cherednik introduced a family of commuting elements of  $\mathbf{H}^{\mathfrak{gl}_n}(c)$ :

$$u_i = -\frac{1}{c} \mathbf{x}_i \mathbf{y}_i + \sum_{p=1}^{i-1} s_{pi} \quad (i \in \{1, 2, \dots, n\}),$$

whose actions on  $\mathbb{C}[\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n]$  are called the Dunkl-Cherednik operators. He proved that there exists a basis of the space  $\mathbb{C}[\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n]$  consisting of simultaneous eigenvectors for the Dunkl-Cherednik operators and each nontrivial eigenspace is one-dimensional for a generic  $c$ . The simultaneous eigenvectors are also called non-symmetric Jack polynomials. Furthermore, Cherednik completely classified all isomorphism classes of irreducible modules which admit a basis consisting of simultaneous eigenvectors for the actions of the elements  $u_i$  in [4]. Suzuki and Vazirani recovered his classification by combinatorial means in [6].

The rational Cherednik algebra  $\mathbf{H}^{\mathfrak{sl}_n}(c)$  of type  $\mathfrak{sl}_n$ , which is a subalgebra of  $\mathbf{H}^{\mathfrak{gl}_n}(c)$  and its representations have been studied as well. For example, when  $c = \frac{r}{n}$  with  $\gcd(r, n) = 1$ , the algebra  $\mathbf{H}^{\mathfrak{sl}_n}(c)$  admits a finite dimensional representation. However, these results on the algebra  $\mathbf{H}^{\mathfrak{sl}_n}(c)$  were obtained by totally different means from Cherednik's method for the algebra  $\mathbf{H}^{\mathfrak{gl}_n}(c)$ . Indeed, it is not possible to apply his method to the representation theory of the subalgebra  $\mathbf{H}^{\mathfrak{sl}_n}(c)$  naively. The main obstacle is that the elements  $u_i$  does not belong to the subalgebra  $\mathbf{H}^{\mathfrak{sl}_n}(c)$ .

The purpose of this paper is to introduce a family of commuting elements of  $\mathbf{H}^{\mathfrak{sl}_n}(c)$  which is analogous to the Dunkl-Cherednik operators, and to provide several relations among the elements. We expect that the elements introduced in this paper allows us to show several results on the algebra  $\mathbf{H}^{\mathfrak{sl}_n}(c)$  in a purely representation-theoretic way, which is analogous to Cherednik's method.

## 2. Preliminaries

In this section, we shortly review the definitions of the rational Cherednik algebras of type  $\mathfrak{gl}_n$  and  $\mathfrak{sl}_n$ . All details skipped in this section can be found in [1] or [2].

### 2.1. Rational Cherednik algebra of type $\mathfrak{gl}_n$

Recall that  $n$  denotes an integer greater than 2 and  $c \in \mathbb{C} \setminus \{0\}$ . The rational Cherednik algebra of type  $\mathfrak{gl}_n$  associated with  $c$ , denoted

by  $\mathbf{H}^{\mathfrak{gl}_n}(c)$ , is the unital associative  $\mathbb{C}$ -algebra which has the following presentation.

**Generators:**  $x_1, \dots, x_{n-1}, x_n, s_1, \dots, s_{n-1}, y_1, \dots, y_{n-1}, y_n$   
**Relations:**  $s_i^2 = 1$  ( $i \in \{1, \dots, n-1\}$ ),  
 $s_i s_{i+1} s_i = s_{i+1} s_i s_{i+1}$  ( $i \in \{1, \dots, n-2\}$ ),  
 $s_i s_j = s_j s_i$  ( $|i-j| > 1$ ),  
 $x_i x_j = x_j x_i, \quad y_i y_j = y_j y_i$  ( $i, j \in \{1, \dots, n-1, n\}$ ),  
 $s_i x_i = x_{i+1} s_i, \quad s_i y_i = y_{i+1} s_i$  ( $i \in \{1, \dots, n-1\}$ ),  
 $s_i x_j = x_j s_i, \quad s_i y_j = y_j s_i$  ( $j \neq i, i+1$ ),  
 $x_i y_j - y_j x_i = \begin{cases} -c s_{ij} & (i \neq j) \\ -1 + c \sum_{p \neq i} s_{ip} & (i = j) \end{cases}$ ,

where  $s_{i,i+1} = s_{i+1,i} = s_i$  and  $s_{ij} = \begin{cases} s_i s_{i+1} \cdots s_{j-1} \cdots s_{i+1} s_i & (i < j) \\ s_i s_{i-1} \cdots s_{j+1} \cdots s_{i-1} s_i & (i > j) \end{cases}$   
 for  $i, j \in \{1, \dots, n-1\}$  with  $i \neq j$ .

**Remark 2.1.** Many authors provide various presentations of the rational Cherednik algebra of type  $\mathfrak{gl}_n$ . We would like to inform that our presentation is compatible with the definition given in [1].

**2.2. Rational Cherednik algebra of type  $\mathfrak{sl}_n$**

We may define the rational Cherednik algebra of type  $\mathfrak{sl}_n$  associated with  $c$  as a subalgebra of the algebra  $\mathbf{H}^{\mathfrak{gl}_n}(c)$ .

**Definition 2.2.** The **rational Cherednik algebra** (abbreviated RCA) of type  $\mathfrak{sl}_n$  associated with  $c \in \mathbb{C} - \{0\}$ , denoted by  $\mathbf{H}^{\mathfrak{sl}_n}(c)$ , is the subalgebra of the algebra  $\mathbf{H}^{\mathfrak{gl}_n}(c)$  generated by  $x_1 - x_n, \dots, x_{n-1} - x_n, s_1, \dots, s_{n-1}$ , and  $y_1 - y_n, \dots, y_{n-1} - y_n$ .

For each  $i \in \{1, \dots, n-1\}$ , we denote  $x_i - x_n$  by  $x_i$  for convenience. On the other hand, we denote by  $y_j$  the element

$$y_j - \frac{1}{n}(y_1 + \dots + y_{n-1} + y_n) \quad (j \in \{1, \dots, n-1, n\}).$$

It can be directly seen that the elements  $y_1, \dots, y_{n-1}, y_n$  belong to the subalgebra  $\mathbf{H}^{\mathfrak{sl}_n}(c)$  and the following equation holds:

(1)  $y_1 + \dots + y_{n-1} + y_n = 0.$

Let  $\mathbb{C}[X_1, \dots, X_{n-1}]$  (resp.  $\mathbb{C}[Y_1, \dots, Y_{n-1}]$ ) be the algebra of polynomials in  $X_1, \dots, X_{n-1}$  (resp.  $Y_1, \dots, Y_{n-1}$ ). For  $\mathbf{a} = (a_1, \dots, a_{n-1}) \in (\mathbb{N} \cup \{0\})^{n-1}$ , we denote  $X_1^{a_1} \cdots X_{n-1}^{a_{n-1}}$  (resp.  $Y_1^{a_1} \cdots Y_{n-1}^{a_{n-1}}$ ) by  $\mathbf{X}^{\mathbf{a}}$  (resp.  $\mathbf{Y}^{\mathbf{a}}$ ).

We may regard the algebra  $\mathbf{H}^{\text{sl}_n}(c)$  as a (infinite dimensional) vector space over  $\mathbb{C}$ . The following theorem, which is also known as the PBW theorem for the rational Cherednik algebra, gives a basis of the vector space  $\mathbf{H}^{\text{sl}_n}(c)$  over  $\mathbb{C}$ . The proof can be found in [2].

**Theorem 2.3** (PBW theorem for the rational Cherednik algebra). *Let  $\mathcal{X}$  (resp.  $\mathcal{Y}$ ) denote the polynomial algebra  $\mathbb{C}[X_1, \dots, X_{n-1}]$  (resp.  $\mathbb{C}[Y_1, \dots, Y_{n-1}]$ ), and let  $\mathbb{C}\mathcal{S}_n$  denote the group algebra of the symmetric group  $\mathcal{S}_n$ . As a vector space over  $\mathbb{C}$ , the rational Cherednik algebra  $\mathbf{H}^{\text{sl}_n}(c)$  is isomorphic to the tensor product  $\mathcal{X} \otimes \mathbb{C}\mathcal{S}_n \otimes \mathcal{Y}$  of the vector spaces  $\mathcal{X}$ ,  $\mathbb{C}\mathcal{S}_n$  and  $\mathcal{Y}$ . More precisely, the linear map*

$$\iota: \mathcal{X} \otimes \mathbb{C}\mathcal{S}_n \otimes \mathcal{Y} \longrightarrow \mathbf{H}^{\text{sl}_n}(c)$$

given by

$$(2) \quad \iota(\mathbf{X}^{\mathbf{a}} \otimes w \otimes \mathbf{Y}^{\mathbf{b}}) = x_1^{a_1} \cdots x_{n-1}^{a_{n-1}} s_{i_1} s_{i_2} \cdots s_{i_k} y_1^{b_1} \cdots y_{n-1}^{b_{n-1}}$$

for  $\mathbf{a} = (a_1, \dots, a_{n-1})$ ,  $\mathbf{b} = (b_1, \dots, b_{n-1}) \in (\mathbb{N} \cup \{0\})^{n-1}$  and  $w \in \mathcal{S}_n$ , where  $w$  is represented as a product of the transpositions

$$(3) \quad w = (i_1 \ i_1 + 1)(i_2 \ i_2 + 1) \cdots (i_k \ i_k + 1),$$

is an isomorphism of vector spaces over  $\mathbb{C}$ .

**Remark 2.4.** *Due to the PBW theorem, we directly see that the group algebra  $\mathbb{C}\mathcal{S}_n$  is embedded in the algebra  $\mathbf{H}^{\text{sl}_n}(c)$ . In this sense, if a permutation  $w \in \mathcal{S}_n$  can be represented as in the equation (3), we will identify  $w$  with the element  $s_{i_1} s_{i_2} \cdots s_{i_k}$  in the algebra  $\mathbf{H}^{\text{sl}_n}(c)$  in the paper.*

### 3. Useful Elements

In this section, we introduce a family of elements of the algebra  $\mathbf{H}^{\text{sl}_n}(c)$ , which are analogous to the Dunkl-Cherednik elements of the algebra  $\mathbf{H}^{\text{gl}_n}(c)$ , introduce auxiliary elements (intertwining elements, raising element and lowering element), and prove that several relations among these elements hold. These elements are obtained from the corresponding elements of the algebra  $\mathbf{H}^{\text{gl}_n}(c)$  by modifying slightly.

#### 3.1. Modified Dunkl-Cherednik elements

By modifying Dunkl-Cherednik operators slightly, we introduce a family of elements in the algebra  $\mathbf{H}^{\text{sl}_n}(c)$ .

**Definition 3.1.** For each  $i \in \{1, 2, \dots, n - 1\}$ , we define the **modified Dunkl-Cherednik element**  $g_i$  to be

$$(4) \quad g_i = -\frac{1}{c}x_i y_i + \left( \sum_{j=1}^{i-1} s_{ji} \right) + s_{in} \in \mathbf{H}^{\mathfrak{sl}_n}(c).$$

The first property of the modified Dunkl-Cherednik elements we show here is that the elements  $g_1, \dots, g_{n-1}$  with  $s_1, \dots, s_{n-2}$  in  $\mathbf{H}^{\mathfrak{sl}_n}(c)$  satisfy the defining relations for the degenerate affine Hecke algebra of type  $\mathbf{A}_{n-2}$ . We prove this property in Lemma 3.2 and Proposition 3.4.

**Lemma 3.2.** *The following relations hold in the algebra  $\mathbf{H}^{\mathfrak{sl}_n}(c)$  for all  $i, j \in \{1, \dots, n - 2\}$ :*

$$(5) \quad s_i g_i s_i = g_{i+1} - s_i,$$

$$(6) \quad s_i g_j s_i = g_j \quad (j \neq i, i + 1).$$

*Proof.* Let  $i \in \{1, \dots, n - 2\}$ . Then we have

$$\begin{aligned} s_i g_i s_i &= s_i \left( -\frac{1}{c}x_i y_i + \left( \sum_{j=1}^{i-1} s_{ji} \right) + s_{in} \right) s_i \\ &= -\frac{1}{c}x_{i+1} y_{i+1} + \left( \sum_{j=1}^{i-1} s_{j,i+1} \right) + s_{i+1,n} \\ &= g_{i+1} - s_{i,i+1} = g_{i+1} - s_i. \end{aligned}$$

In the case of  $j < i$ , we directly see that the equation  $s_i g_j = g_j s_i$  holds because  $s_i$  commutes with  $x_j, y_j, s_{1j}, \dots, s_{j-1,j}$ , and  $s_{jn}$ .

Now assume  $i + 1 < j \leq n - 2$ . Then we have

$$\begin{aligned} s_i g_j s_i &= s_i \left( -\frac{1}{c}x_j y_j + s_{1j} + \dots + s_{ij} + s_{i+1,j} + \dots + s_{j-1,j} + s_{jn} \right) s_i \\ &= -\frac{1}{c}x_j y_j + s_{1j} + \dots + s_{i+1,j} + s_{ij} + \dots + s_{j-1,j} + s_{jn} = g_j. \end{aligned}$$

□

**Remark 3.3.** *From (5), one can easily show that the following relation holds:*

$$s_i g_{i+1} s_i = g_i + s_i$$

for all  $i, j \in \{1, \dots, n - 2\}$ .

**Proposition 3.4.** *The modified Dunkl-Cherednik elements  $g_1, g_2, \dots, g_{n-1}$  commute with each other in the algebra  $\mathbf{H}^{\mathfrak{sl}_n}(c)$ ; that is, the equation  $g_i g_j = g_j g_i$  holds for every  $i, j \in \{1, 2, \dots, n - 1\}$ .*

*Proof.* Without loss of generality, we may assume  $i < j$ . We first show a special case directly:  $g_1g_2 = g_2g_1$ .

$$\begin{aligned}
g_1g_2 &= \frac{1}{c^2}x_1y_1x_2y_2 - \frac{1}{c}x_1y_1s_{12} - \frac{1}{c}x_1y_1s_{2n} \\
&\quad - \frac{1}{c}s_{1n}x_2y_2 + s_{1n}s_{12} + s_{1n}s_{2n} \\
&= \frac{1}{c^2}x_1(x_2y_1 + cs_{12} - cs_{1n})y_2 - \frac{1}{c}x_1s_{12}y_2 - \frac{1}{c}x_1s_{2n}y_1 \\
&\quad - \frac{1}{c}(x_2 - x_1)s_{1n}y_2 + s_{1n}s_{12} + s_{1n}s_{2n} \\
&= \frac{1}{c^2}x_1x_2y_1y_2 + \frac{1}{c}x_1s_{12}y_2 - \frac{1}{c}x_1s_{1n}y_2 \\
&\quad - \frac{1}{c}x_1s_{12}y_2 - \frac{1}{c}x_1s_{2n}y_1 - \frac{1}{c}x_2s_{12}y_2 \\
&\quad + \frac{1}{c}x_1s_{1n}y_2 + s_{1n}s_{12} + s_{1n}s_{2n} \\
&= \frac{1}{c^2}x_1x_2y_1y_2 - \frac{1}{c}x_1s_{2n}y_1 - \frac{1}{c}x_2s_{1n}y_2 + s_{2n}s_{1n} + s_{1n}s_{2n} \\
g_2g_1 &= \frac{1}{c^2}x_2y_2x_1y_1 - \frac{1}{c}x_2y_2s_{1n} - \frac{1}{c}s_{12}x_1y_1 \\
&\quad + s_{12}s_{1n} - \frac{1}{c}s_{2n}x_1y_1 + s_{2n}s_{1n} \\
&= \frac{1}{c^2}x_2(x_1y_2 + cs_{12} - cs_{2n})y_1 - \frac{1}{c}x_2s_{1n}y_2 - \frac{1}{c}x_2s_{12}y_1 \\
&\quad + s_{12}s_{1n} - \frac{1}{c}(x_1 - x_2)s_{2n}y_1 + s_{2n}s_{1n} \\
&= \frac{1}{c^2}x_1x_2y_1y_2 + \frac{1}{c}s_2s_{12}y_1 - \frac{1}{c}x_2s_{2n}y_1 \\
&\quad - \frac{1}{c}x_2s_{1n}y_2 - \frac{1}{c}x_2s_{12}y_1 + s_{12}s_{1n} \\
&\quad - \frac{1}{c}x_1s_{2n}y_1 + \frac{1}{c}x_2s_{2n}y_1 + s_{2n}s_{1n} \\
&= \frac{1}{c^2}x_1x_2y_1y_2 - \frac{1}{c}x_2s_{1n}y_2 - \frac{1}{c}x_1s_{2n}y_1 + s_{1n}s_{2n} + s_{2n}s_{1n}
\end{aligned}$$

Now assume  $j \geq 3$ . Then by applying Lemma 3.2 repeatedly, we have

$$g_j = s_{j-1} \cdots s_2g_2s_2 \cdots s_{j-1} + \sum_{k=2}^{j-1} s_{kj}.$$

Since the element  $g_1$  commutes with the element  $g_2$  and  $s_2, \dots, s_{n-1}$ , we obtain  $g_1g_j = g_jg_1$ .

Let us assume  $1 < i < j$  additionally. Then we also express  $g_i$  as

$$g_i = s_{i-1} \cdots s_1g_1s_1 \cdots s_{i-1} + \sum_{k=1}^{i-1} s_{ki},$$

from which it follows that the equation  $g_i g_j = g_j g_i$  holds because the element  $g_j$  commutes with  $g_1$  and  $s_1, \dots, s_i$ .  $\square$

Let  $\mathcal{G}$  denote the subalgebra of  $\mathbf{H}^{s^n}(c)$  generated by the elements  $g_1, g_2, \dots, g_{n-1}$ . Note that it follows from the previous proposition that the subalgebra  $\mathcal{G}$  is a commutative algebra.

### 3.2. Intertwing elements

Here we introduce auxiliary elements of the algebra  $\mathbf{H}^{\mathfrak{sl}_n}(c)$ , and give relations between these elements and the elements  $g_i$ . In Section 4, we will see that these auxiliary elements are useful in the representation theory of the algebra  $\mathbf{H}^{\mathfrak{sl}_n}(c)$ .

**Definition 3.5.** For each  $i \in \{1, \dots, n-2\}$ , we define the **intertwining element**  $\varphi_i$  to be the element

$$(7) \quad \varphi_i = 1 + s_i(g_i - g_{i+1}) \in \mathbf{H}^{\mathfrak{sl}_n}(c).$$

The next proposition shows how well the intertwining elements behave with the elements  $g_1, g_2, \dots, g_{n-1}$ .

**Proposition 3.6.** The following relation holds in the algebra  $\mathbf{H}^{\mathfrak{sl}_n}(c)$ :

$$g_j \varphi_i = \varphi_i g_{s_i(j)}$$

for  $i \in \{1, \dots, n-2\}$  and  $j \in \{1, \dots, n-1\}$ .

*Proof.* Let  $i \in \{1, \dots, n-2\}$ . From Lemma 3.2, we directly see that the following equations hold:

$$(8) \quad g_i s_i = s_i s_i g_i s_i = s_i(g_{i+1} - s_i) = s_i g_{i+1} - 1,$$

$$(9) \quad g_{i+1} s_i = (s_i g_i s_i + s_i) s_i = s_i g_i + 1.$$

Thus, we obtain

$$\begin{aligned} g_i \varphi_i &= g_i(1 + s_i(g_i - g_{i+1})) \\ &= g_i + g_i s_i(g_i - g_{i+1}) \\ &= g_i + (s_i g_{i+1} - 1)(g_i - g_{i+1}) \\ &= g_i + s_i g_{i+1}(g_i - g_{i+1}) - (g_i - g_{i+1}) \\ &= s_i(g_i - g_{i+1})g_{i+1} + g_{i+1} \\ &= (s_i(g_i - g_{i+1}) + 1)g_{i+1} = \varphi_i g_{i+1}. \end{aligned}$$

Similarly, one can easily check the relation  $g_{i+1} \varphi_i = \varphi_i g_i$  holds.

For  $j \in \{1, \dots, n-1\}$  with  $j \neq i, i+1$ , note that the element  $g_j$  commutes with  $s_i$  as well as  $g_i - g_{i+1}$ , from which it follows that the relation  $g_j \varphi_i = \varphi_i g_j$  holds.  $\square$

From the following proposition, we see  $\varphi_i \in \mathcal{G}$  for each  $i \in \{1, \dots, n-2\}$ . In particular,  $\varphi_i^2$  commutes with the elements  $g_1, g_2, \dots, g_{n-1}$ .

**Proposition 3.7.** For each  $i \in \{1, \dots, n-2\}$ , the following equation holds in the algebra  $\mathbf{H}^{\mathfrak{sl}_n}(c)$ :

$$(10) \quad \varphi_i^2 = (1 + g_i - g_{i+1})(1 - g_i + g_{i+1}).$$

*Proof.* It is straightforward. Indeed, by proposition 3.6 and equation (7), we obtain

$$\begin{aligned}
 \varphi_i^2 &= (1 + s_i(g_i - g_{i+1}))\varphi_i \\
 &= \varphi_i + s_i\varphi_i(g_{i+1} - g_i) \\
 &= \varphi_i - s_i(1 + s_i(g_i - g_{i+1}))(g_i - g_{i+1}) \\
 &= \varphi_i - s_i(g_i - g_{i+1}) - (g_i - g_{i+1})^2 \\
 &= 1 - (g_i - g_{i+1})^2 \\
 &= (1 + g_i - g_{i+1})(1 - g_i + g_{i+1}).
 \end{aligned}$$

□

### 3.3. Raising element

Together with the intertwining elements, we introduce two more auxiliary elements in this paper. One is the raising element and the other is the lowering element.

**Definition 3.8.** *The element*

$$(11) \quad r = x_1 s_1 \cdots s_{n-2} \in \mathbf{H}^{\text{sl}_n}(c).$$

is said to be the **raising element**.

**Remark 3.9.** *The element  $x_1$  is not a zero-divisor in  $\mathbf{H}^{\text{sl}_n}(c)$  by the PBW theorem, and  $s_1, \dots, s_{n-2}$  are all invertible elements in  $\mathbf{H}^{\text{sl}_n}(c)$ . Hence, the raising element  $r = x_1 s_1 \cdots s_{n-2}$  is not a zero-divisor.*

The following lemma gives relations between the raising element  $r$  and the elements  $g_i$  in the algebra  $\mathbf{H}^{\text{sl}_n}(c)$ .

**Proposition 3.10.** *The raising element  $r$  with the  $n - 1$  elements  $g_1, g_2, \dots, g_{n-1}$  satisfies the following relations in the algebra  $\mathbf{H}^{\text{sl}_n}(c)$ .*

$$\begin{aligned}
 g_1 r &= r \left( g_{n-1} - \frac{1}{c} \right), \\
 g_i r &= r g_{i-1} \quad (i \in \{2, \dots, n-1\})
 \end{aligned}$$

*Proof.* Let  $w = s_1 \cdots s_{n-2}$ . Note  $x_1 w = w x_{n-1}$  and  $y_1 w = w y_{n-1}$ . Hence, we see that the first relation holds by a direct computation as



follows.

$$\begin{aligned}
g_1 r &= \left(-\frac{1}{c}x_1 y_1 + s_{1n}\right) x_1 w \\
&= \left(-\frac{1}{c}x_1 \left(x_1 y_1 + 1 - c \sum_{j=2}^n s_{1j} - cs_{1n}\right) + s_{1n}x_1\right) w \\
&= \left(-\frac{1}{c}x_1^2 y_1 - \frac{1}{c}x_1 + x_1 \sum_{j=2}^n s_{1j} + x_1 s_{1n} - x_1 s_{1n}\right) w \\
&= x_1 \left(-\frac{1}{c}x_1 y_1 - \frac{1}{c} + \sum_{j=2}^n s_{1j}\right) w \\
&= x_1 w \left(-\frac{1}{c}x_{n-1} y_{n-1} - \frac{1}{c} + \sum_{j=1}^{n-2} s_{j,n-1} + s_{n-1,n}\right) \\
&= r \left(g_{n-1} - \frac{1}{c}\right)
\end{aligned}$$

We now suppose  $i \in \{2, \dots, n-1\}$ . Since  $x_i w = w x_{i-1}$  and  $y_i w = w y_{i-1}$ , we obtain

$$\begin{aligned}
g_i r &= \left(-\frac{1}{c}x_i y_i + s_{1i} + \left(\sum_{j=2}^{i-1} s_{ji}\right) + s_{in}\right) x_1 w \\
&= \left(-\frac{1}{c}x_i (x_1 y_i + cs_{1i}) + x_i s_{1i} + x_1 \left(\sum_{j=2}^{i-1} s_{ji}\right) + x_1 s_{in}\right) w \\
&= x_1 \left(-\frac{1}{c}x_i y_i + \left(\sum_{j=2}^{i-1} s_{ji}\right) + s_{in}\right) w \\
&= x_1 w \left(-\frac{1}{c}x_{i-1} y_{i-1} + \left(\sum_{j=1}^{i-2} s_{j,i-1}\right) + s_{i-1,n}\right) = r g_{i-1}.
\end{aligned}$$

□

### 3.4. Lowering operator

**Definition 3.11.** *The element*

$$(12) \quad \ell = -\frac{1}{c}(s_{n-1} \cdots s_2 s_1 y_1 - s_{n-2} \cdots s_2 s_1 y_1 g_1) \in \mathbf{H}^{\mathfrak{sl}_n}(c).$$

*is said to be the lowering element.*

We will see that both  $r\ell$  and  $\ell r$  belong to  $\mathcal{G}$ . In particular, the products  $r\ell$ ,  $\ell r$  commute with the elements  $g_1, g_2, \dots, g_{n-1}$ .

**Lemma 3.12.** *The raising element  $r$  and the lowering element  $\ell$  satisfy the relations:*

$$\begin{aligned} r\ell &= (1 + g_1)(1 - g_1), \\ \ell r &= (1 + g_{n-1} - \frac{1}{c})(1 - g_{n-1} + \frac{1}{c}). \end{aligned}$$

*Proof.* Recall that we denote by  $s_{1n}$  the element

$$s_1 \cdots s_{n-2} s_{n-1} s_{n-2} \cdots s_1 \in \mathbf{H}^{\text{sl}_n}(c).$$

Thus, we obtain

$$\begin{aligned} r\ell &= -\frac{1}{c}(x_1 s_{1n} y_1 - x_1 y_1 g_1) \\ &= -\frac{1}{c}(-s_{1n} x_1 y_1 - x_1 y_1 g_1) \\ &= -\frac{1}{c}(c s_{1n}(g_1 - s_{1n}) + c(g_1 - s_{1n})g_1) \\ &= 1 - g_1^2 = (1 + g_1)(1 - g_1). \end{aligned}$$

On the other hand, together with Proposition 3.10, the relation

$$r\ell = (1 + g_1)(1 - g_1)$$

implies

$$\begin{aligned} r\ell r &= (1 + g_1)(1 - g_1)r \\ &= r(1 + g_{n-1} - \frac{1}{c})(1 - g_{n-1} + \frac{1}{c}). \end{aligned}$$

Hence, it follows that the relation

$$\ell r = (1 + g_{n-1} - \frac{1}{c})(1 - g_{n-1} + \frac{1}{c})$$

holds because the raising element  $r$  is not a zero-divisor in the algebra  $\mathbf{H}^{\text{sl}_n}(c)$  as we have seen in Remark 3.9.  $\square$

From the previous lemma, we obtain a relation between the lowering element  $\ell$  and the elements  $g_i$ .

**Proposition 3.13.** *The lowering element  $\ell$  with the  $n - 1$  elements  $g_1, g_2, \dots, g_{n-1}$  satisfies the following relations in the algebra  $\mathbf{H}^{\text{sl}_n}(c)$ .*

$$\begin{aligned} g_i \ell &= \ell g_{i+1}, \quad (i \in \{1, \dots, n-2\}) \\ g_{n-1} \ell &= \ell(g_1 + \frac{1}{c}) \end{aligned}$$

*Proof.* Note that  $lr = (1 + g_{n-1} - \frac{1}{c})(1 - g_{n-1} + \frac{1}{c})$  commutes with all the elements  $g_1, g_2, \dots, g_{n-1}$ . By Proposition 3.10, we obtain

$$g_i \ell r = lr g_i = \begin{cases} \ell g_{i+1} r & (i \in \{1, \dots, n-2\}), \\ \ell(g_1 + \frac{1}{c})r. \end{cases}$$

Since the raising element  $r$  is not a zero-divisor in the algebra  $\mathbf{H}^{\mathfrak{sl}_n}(c)$  (Remark 3.9), we have

$$g_i \ell = \begin{cases} \ell g_{i+1} & (i \in \{1, \dots, n-2\}), \\ \ell(g_1 + \frac{1}{c}). \end{cases}$$

□

#### 4. Applications and Outlook

As we mentioned in Section 1, we may use the elements we introduce in Section 3 in order to study a structure of a given  $\mathbf{H}^{\mathfrak{sl}_n}(c)$ -module. Here we provide simple applications and discuss what we expect to be able to do with these elements.

##### 4.1. Applications: representation theory of $\mathbf{H}^{\mathfrak{sl}_n}(c)$

Recall that  $\mathcal{G}$  denotes the commutative subalgebra of  $\mathbf{H}^{\mathfrak{sl}_n}(c)$  generated by the elements  $g_1, g_2, \dots, g_{n-1}$ . Hence, when we have an  $\mathbf{H}^{\mathfrak{sl}_n}(c)$ -module, it is natural to consider simultaneous eigenvectors in the module  $M$  for the actions of all elements of  $\mathcal{G}$ .

**Definition 4.1.** Let  $M$  be an  $\mathbf{H}^{\mathfrak{sl}_n}(c)$ -module. An  $(n-1)$ -tuple  $\mathbf{a} = (a_1, a_2, \dots, a_{n-1}) \in \mathbb{C}^{n-1}$  is called a **weight** of  $M$  if there exists a nonzero vector  $v \in M$  such that  $g_i \cdot v = a_i v$  for all  $i \in \{1, 2, \dots, n-1\}$ , and such a vector  $v$  is called a **weight vector** of weight  $\mathbf{a}$ .

Given a weight vector  $v$  in an  $\mathbf{H}^{\mathfrak{sl}_n}(c)$  module, we can produce several weight vectors from the given weight vector  $v$  using the auxiliary elements defined in Section 3. To be precise, we consider the actions of the intertwining elements  $\varphi_i$  on a module, which send weight vectors to weight vectors or zero.

**Theorem 4.2.** Let  $M$  be an  $\mathbf{H}^{\mathfrak{sl}_n}(c)$ -module. If a vector  $v \in M$  is a weight vector of weight  $\mathbf{a} = (a_1, a_2, \dots, a_{n-1}) \in \mathbb{C}^{n-1}$ , then  $\varphi_i \cdot v$  is either a weight vector of weight  $(a_1, \dots, a_{i+1}, a_i, \dots, a_{n-1})$  or zero. Furthermore,  $\varphi_i \cdot v = 0$  happens only if  $a_i - a_{i+1} \in \{-1, 1\}$ .

*Proof.* Let  $v \in M$  be a weight vector of weight  $(a_1, a_2, \dots, a_{n-1}) \in \mathbb{C}^{n-1}$ . Then by Proposition 3.6, we directly see

$$g_j \cdot (\varphi_i \cdot v) = \varphi_i \cdot (g_{s_i(j)} \cdot v) = a_{s_i(j)} v$$

from which it follows that  $\varphi_i \cdot v$  is either a weight vector of weight

$$(a_1, \dots, a_{i+1}, a_i, \dots, a_{n-1}) \in \mathbb{C}^{n-1}$$

or zero.

Now assume  $a_i - a_{i+1} \notin \{-1, 1\}$  additionally. Then by Proposition 3.7, we obtain

$$\varphi_i \cdot (\varphi_i \cdot v) = (1 + a_i - a_{i+1})(1 - a_i + a_{i+1})v \neq 0;$$

hence, we have  $\varphi_i \cdot v \neq 0$ . □

We may also apply the results in Proposition 3.10 and Proposition 3.13 to the representation theory of the algebra  $\mathbf{H}^{sl_n}(c)$ . Indeed, we directly prove the following theorem using Proposition 3.10 and Proposition 3.13 in a similar way to the proof of Theorem 4.2.

**Theorem 4.3.** *Let  $M$  be an  $\mathbf{H}^{sl_n}(c)$ -module and let  $v \in M$  be a weight vector of weight  $\mathbf{a} = (a_1, a_2, \dots, a_{n-1}) \in \mathbb{C}^{n-1}$ . Then  $r \cdot v$  is either a weight vector of weight  $(a_{n-1} - \frac{1}{c}, a_1, a_2, \dots, a_{n-2})$  or zero, and  $r \cdot v = 0$  happens only if  $a_{n-1} - \frac{1}{c} \in \{-1, 1\}$ . Also,  $\ell \cdot v$  is either a weight vector of weight  $(a_2, \dots, a_{n-1}, a_1 + \frac{1}{c})$  or zero, and  $\ell \cdot v = 0$  happens only if  $a_1 \in \{-1, 1\}$ .*

### 4.2. Outlook

Theorem 4.2 and theorem 4.3 suggest a combinatorial approach to the representation theory of the algebra  $\mathbf{H}^{sl_n}(c)$  in terms of weights of a given  $\mathbf{H}^{sl_n}(c)$ -module as in [6] for the algebra  $\mathbf{H}^{sl_n}(c)$ . For example, we may apply Suzuki’s proof of Theorem 7.2 in [5] in order to prove the fact that for a generic  $c$ , the polynomial representation of the algebra  $\mathbf{H}^{sl_n}(c)$  admits a basis consisting of weight vectors.

Furthermore, we expect various results on the algebra  $\mathbf{H}^{sl_n}(c)$  to be proved or explained in terms of the modified Dunkl-Cherednik elements by using the elementary representation theory or combinatorics. One of the interesting results on the algebra  $\mathbf{H}^{sl_n}(c)$  is that there exists a  $r^{n-1}$ -dimensional representation when  $c = \frac{r}{n}$  with  $\gcd(r, n) = 1$ . On the other hand, there is the notion of the  $(r, n)$ -rational parking functions in combinatorics, and it is well known that there are exactly  $r^{n-1}$  parking functions. We expect the notion of weights we defined in this paper to

be a bridge between representation-theoretic values and combinatorial statistic of parking functions.

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