# INVESTIGATION OF SOME FIXED POINT THEOREMS IN HYPERBOLIC SPACES FOR A THREE STEP ITERATION PROCESS

### Yunus Atalan\* and Vatan Karakaya

ABSTRACT. In the present paper, we investigate the convergence, equivalence of convergence, rate of convergence and data dependence results using a three step iteration process for mappings satisfying certain contractive condition in hyperbolic spaces. Also we give non-trivial examples for the rate of convergence and data dependence results to show effciency of three step iteration process. The results obtained in this paper may be interpreted as a refinement and improvement of the previously known results.

#### 1. Introduction and Preliminaries

The relationship between the geometric properties of a space and fixed point theory makes it possible to obtain very effective and useful results. In particular, geometric properties of a space play an important role in metric fixed point theory. Since every Banach space is a vector space, it is easier to give these spaces a convex structure. For this reason, the geometry of the Banach spaces has been worked intensively with their convex structures (see [6, 8, 9, 13, 21, 42]).

Received May 2, 2019. Revised November 7, 2019. Accepted November 16, 2019. 2010 Mathematics Subject Classification: 47H09, 47H10.

Key words and phrases: iteration process, contractive type operators, hyperbolic spaces.

<sup>\*</sup> Corresponding author.

<sup>©</sup> The Kangwon-Kyungki Mathematical Society, 2019.

This is an Open Access article distributed under the terms of the Creative commons Attribution Non-Commercial License (http://creativecommons.org/licenses/by-nc/3.0/) which permits unrestricted non-commercial use, distribution and reproduction in any medium, provided the original work is properly cited.

However, it is more difficult to gain convex structure to metric spaces. This difficulty has been overcome by Takahashi's describing convex structure in metric spaces (see [40]) and after this point, many authors have studied fixed point theory in convex metric spaces and obtained very efficient results (see [10,11,28,29]) and the references cited therein. Since many problems encountered in real life can be expressed in nonlinear form, it will be more realistic approach to study these problems in nonlinear structures instead of linear structures such as Banach spaces. At this point, hyperbolic space due to its nonlinear structure and rich geometrical properties is a good mathematical framework for metric fixed point theory in the study of these problems.

In 2004, Kohlenbach in [30] gave the definition of hyperbolic space as follows:

DEFINITION 1.1. A (H, d, W) is called a hyperbolic space if (H, d) is a metric space and  $W: H \times H \times I \to H$  satisfying

```
(H_1) \ d(u, W(x, y, \alpha)) \leq \alpha d(u, x) + (1 - \alpha) d(u, y);
(H_2) \ d(W(x, y, \alpha), W(x, y, \beta)) = |\alpha - \beta| \ d(x, y);
(H_3) \ W(x, y, \alpha) = W(y, x, 1 - \alpha);
(H_4) \ d(W(x, z, \alpha), W(y, w, \alpha)) \leq (1 - \alpha) d(x, y) + \alpha d(z, w);
for all x, y, z, w \in H and \alpha, \beta \in [0, 1].
```

If a metric space (H, d) with a mapping  $W : H \times H \times [0, 1] \to H$  satisfies only condition  $(H_1)$ , then it is a convex metric space in the sense of Takahashi [40], if (H, d) satisfies conditions  $(H_1) - (H_3)$  then it being a space of hyperbolic type in Goebel and Kirk [14]. The condition  $(H_4)$  is used in [37] to define the class of hyperbolic spaces. This class contains normed linear spaces and convex subsets therefore the open unit ball in complex Hilbert spaces. After that many authors have studied fixed point problems in hyperbolic spaces (see [2, 12, 27]) and the references cited therein.

While the existence theorems in the fixed point theory guarantee the existence of the solutions, the iterative approximation methods are significant tools for determining what is the solution. For this purpose many iteration processes have been introduced and analyzed by a great number of researches in the sense of their convergence, equivalence of convergence and rate of convergence etc. (see [1,16,18,19,24,35,38]).

In 2014, Gursoy [17] introduced the Picard-S iteration process in a Banach space as follows:

(1) 
$$\begin{cases} k_0 \in K \\ k_{n+1} = Tm_n \\ m_n = (1 - \alpha_n) Tk_n + \alpha_n Tb_n \\ b_n = (1 - \beta_n) k_n + \beta_n Tk_n \end{cases}$$

where K is a nonempty subset of a real Banach space X and T is a self-mapping on K and  $\{\alpha_n\}, \{\beta_n\}$  are real sequences in [0, 1].

The iteration process (1) can be expressed in hyperbolic as

(2) 
$$\begin{cases} k_0 \in K \\ k_{n+1} = Tm_n \\ m_n = W(Tk_n, Tb_n, \alpha_n) \\ b_n = W(k_n, Tk_n, \beta_n) \end{cases}$$

Faster and simpler iteration process have been defined to reach solution by doing less processing. In accordance with this purpose, we used the following iteration process which is defined by Karakaya et. al [24]:

(3) 
$$\begin{cases} h_0 \in K \\ h_{n+1} = Ts_n \\ s_n = (1 - \alpha_n) r_n + \alpha_n Tr_n \\ r_n = Th_n \end{cases}$$

The iteration process (3) can be expressed in hyperbolic space as

(4) 
$$\begin{cases} h_0 \in K \\ h_{n+1} = Ts_n \\ s_n = W(r_n, Tr_n, \alpha_n) \\ r_n = Th_n \end{cases}$$

DEFINITION 1.2. [22] Let T be a self operator on a metric space X. The operator T is called a contractive-like operator if there exists a constant  $\delta \in [0,1)$  and a strictly increasing and continuous function  $\varphi: [0,\infty) \to [0,\infty)$ , with  $\varphi(0) = 0$ , such that for each  $x,y \in X$ ,

(5) 
$$d(Tx, Ty) \le \delta d(x, y) + \varphi \left[ d(x, Tx) \right].$$

This definition is more general than the definitions of by Berinde [3], [4], Harder and Hicks [20], Zamfirescu [43], Osilike and Udomene [34]. Several mathematicians have established some fixed points results for this class of mappings under the assumption that this mapping has a unique fixed point (see [7, 23, 26, 31–33]). However, as we show in the

following example, this mapping need not has a fixed point even if X is a complete:

Example 1.3. Let X = [0,1] be endowed with the usual metric. Define an operator  $T: [0,1] \to [0,1]$  by

$$Tx = e^{-x} + \frac{1}{2}\sin x^2 + 0.75.$$

We have to show the operator T satisfies the condition (5). Define the function  $\varphi:[0,\infty)\to[0,\infty)$  by  $\varphi(t)=\frac{t}{40}$ . Then  $\varphi$  is increasing, continuous and  $\varphi(0)=0$ .

We have the following equalities:

$$|Tx - Ty| = \left| e^{-x} - e^{-y} + \frac{1}{2} \left( \sin x^2 - \sin y^2 \right) \right|$$

and

$$\varphi[|x - Tx|] = 0.025 \left| x - e^{-x} - \frac{1}{2} (\sin x^2) - 0.75 \right|$$

If  $\delta = 0.7$ , then we have

$$\left| e^{-x} - e^{-y} + \frac{1}{2} \left( \sin x^2 - \sin y^2 \right) \right| \le 0.7 |x - y| + 0.025 \left| x - e^{-x} - \frac{1}{2} \left( \sin x^2 \right) - 0.75 \right|$$

for all  $x, y \in [0, 1]$ . That is T satisfies the condition (5). But the operator T has no fixed point in [0, 1] as shown in the following figure:

Bosede and Rhoades [5] observed that if a contractive-like operator T has a fixed point then it satisfies the following contractive condition:

(6) 
$$d(x_*, Tx) \le \delta d(x_*, x)$$

for some  $0 \le \delta < 1$  and for each  $x \in X$ .

In our opinion it is better to work with the contractive condition defined by (6) than with (5), because if we suppose that T has a fixed point, then (5) implies (6) and using (6), we avoid doing unnecessary calculations.

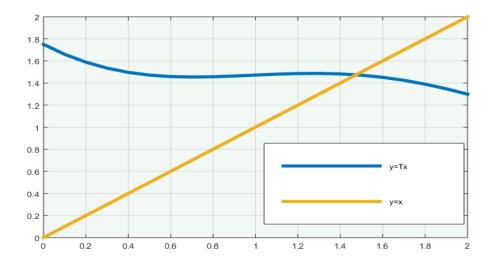


FIGURE 1. Graph of T and y = x

Also, from (6), we obtain

(7) 
$$d(Tx, Ty) \leq d(Tx, x_*) + d(x_*, Ty)$$
$$\leq \delta d(x_*, x) + \delta d(x_*, y)$$
$$\leq \delta d(x, y) + 2\delta d(x_*, y)$$

In this work, we prove that the iteration process (4) converges to fixed point  $x_*$  of a mapping, which satisfies (6), under suitable control conditions. Further, we show that there is an equivalency between iteration processes (4) and (2) in the sense of their convergence. Moreover, we prove that the iteration process (4) has a better convergence speed when compared the iteration process (2). Also, we show that a data dependence result can be obtained for the mappings which satisfy (6) by using the iteration process (4). Finally, we give numerical examples to support rate of convergence and data dependence results.

DEFINITION 1.4 ([36]). Let  $\{a_n\}_{n=0}^{\infty}$  and  $\{b_n\}_{n=0}^{\infty}$  be two sequences converging to the same point  $x_*$ . We say that  $\{a_n\}_{n=0}^{\infty}$  converges faster than  $\{b_n\}_{n=0}^{\infty}$  to  $x_*$ , if

$$\lim_{n \to \infty} \frac{d(a_n, x_*)}{d(b_n, x_*)} = 0.$$

LEMMA 1.5. [41] Let  $\{c_n\}_{n=0}^{\infty}$  and  $\{d_n\}_{n=0}^{\infty}$  be nonnegative real sequences satisfying the following inequality:

$$c_{n+1} \le \rho c_n + d_n$$

where  $\rho \in [0,1)$  and  $\lim_{n\to\infty} d_n = 0$ , then  $\lim_{n\to\infty} c_n = 0$ .

LEMMA 1.6. [41] Let  $\{c_n\}_{n=0}^{\infty}$  and  $\{d_n\}_{n=0}^{\infty}$  be nonnegative real sequences satisfying the following inequality:

$$c_{n+1} \le (1 - \xi_n) c_n + d_n,$$

where  $\xi_n \in (0,1)$  for all  $n \in \mathbb{N}$ ,  $\sum_{n=0}^{\infty} \xi_n = \infty$  and  $\frac{d_n}{\xi_n} \to 0$  as  $n \to \infty$ , then  $\lim_{n \to \infty} c_n = 0$ .

LEMMA 1.7. [39] Let  $\{c_n\}_{n=0}^{\infty}$  be a nonnegative real sequence and there exists  $n_0 \in \mathbb{N}$  such that for all  $n \geq n_0$  satisfying the following inequality

$$c_{n+1} \le (1 - \xi_n) c_n + \xi_n \mu_n.$$

where  $\xi_n \in (0,1)$  such that  $\sum_{n=0}^{\infty} \xi_n = \infty$  and  $\{\mu_n\}_{n=0}^{\infty} \geq 0$ . Then the following inequality holds:

$$0 \le \limsup_{n \to \infty} c_n \le \limsup_{n \to \infty} \mu_n.$$

Definition 1.8. [39] Let  $T, S: C \to C$  be two operators. We say that S is an approximate operator of T for all  $x \in C$  and a fixed  $\varepsilon > 0$  if  $d(Tx, Sx) \leq \varepsilon$ .

#### 2. Main Results

THEOREM 2.1. Let C be a nonempty, closed and convex subset of a hyperbolic metric space H and let  $\{h_n\}_{n=0}^{\infty}$  be the iteration process (4) with a real sequence  $\{\alpha_n\}_{n=0}^{\infty} \in [0,1]$  satisfying  $\sum_{n=0}^{\infty} \alpha_n = \infty$ . If  $T: C \to C$  is a quasi-contractive operator satisfying (6) then  $\{h_n\}_{n=0}^{\infty}$  converges to  $x_*$ .

*Proof.* By  $(H_1)$ , (4) and (6) we have

(8) 
$$d(h_{n+1}, x_*) = d(Ts_n, x_*) \le \delta d(s_n, x_*),$$

and

$$d(s_{n}, x_{*}) = d(W(r_{n}, Tr_{n}, \alpha_{n}), x_{*})$$

$$\leq (1 - \alpha_{n}) d(r_{n}, x_{*}) + \alpha_{n} d(Tr_{n}, x_{*})$$

$$\leq (1 - \alpha_{n}) d(r_{n}, x_{*}) + \alpha_{n} \delta d(r_{n}, x_{*})$$

$$= [1 - \alpha_{n} (1 - \delta)] d(r_{n}, x_{*}).$$

and

$$(10) d(r_n, x_*) = d(Th_n, x_*) \le \delta d(h_n, x_*).$$

Substituting (10) in (9) and (9) in (8) respectively, we obtain

$$d(h_{n+1}, x_*) \le \delta^2 [1 - \alpha_n (1 - \delta)] d(h_n, x_*).$$

By repeating this process n times, we get

$$d(h_{n}, x_{*}) \leq \delta^{2} [1 - \alpha_{n-1} (1 - \delta)] d(h_{n-1}, x_{*})$$

$$d(h_{n-1}, x_{*}) \leq \delta^{2} [1 - \alpha_{n-2} (1 - \delta)] d(h_{n-2}, x_{*})$$

$$\vdots$$

$$d(h_{1}, x_{*}) \leq \delta^{2} [1 - \alpha_{0} (1 - \delta)] d(h_{0}, x_{*}).$$

From the above inequalities, we have

(11) 
$$d(h_{n+1}, x_*) \le d(h_0, x_*) \delta^{2(n+1)} \prod_{i=0}^{n} [1 - \alpha_i (1 - \delta)].$$

From classical analysis, we know that  $1-x \le e^{-x}$  for all  $x \in [0,1]$ . By using this inequality with (11), we obtain

(12) 
$$d(h_{n+1}, x_*) \leq d(h_0, x_*) \delta^{2(n+1)} \prod_{i=0}^n e^{-(1-\delta)\alpha_i}$$
$$= d(h_0, x_*) \delta^{2(n+1)} e^{-(1-\delta) \sum_{i=0}^n \alpha_i}.$$

Taking the limit in both sides of inequality (12), it can be seen that  $h_n \to x_* \text{ as } n \to \infty.$ 

THEOREM 2.2. Let C, H and T with fixed point  $x_*$  be the same as in Theorem 2.1. Let  $\{h_n\}_{n=0}^{\infty}$  be defined by the iteration process (4) for  $h_0 \in C$  and let  $\{k_n\}_{n=0}^{\infty}$  be defined by the iteration process (2) for  $k_0 \in C$ . Then the following statements are equivalent:

- (i)  $\{h_n\}_{n=0}^{\infty}$  converges to  $x_*$ (ii)  $\{k_n\}_{n=0}^{\infty}$  converges to  $x_*$

*Proof.* We will prove (i) $\Rightarrow$ (ii). Suppose that  $\{h_n\}_{n=0}^{\infty}$  converges to  $x_*$ . It follows from  $(H_1)$ , (2), (4), (7), (9) and (10) that

(13) 
$$d(s_n, x_*) \le \delta \left[1 - \alpha_n (1 - \delta)\right] d(h_n, x_*)$$

and

$$(14) d(h_n, Th_n) \leq (1+\delta) d(h_n, x_*).$$

Also

$$d(b_{n}, r_{n}) = d(W(k_{n}, Tk_{n}, \beta_{n}), Th_{n})$$

$$\leq (1 - \beta_{n}) d(k_{n}, Th_{n}) + \beta_{n} d(Tk_{n}, Th_{n})$$

$$\leq (1 - \beta_{n}) d(k_{n}, h_{n}) + (1 - \beta_{n}) d(h_{n}, Th_{n})$$

$$+ \beta_{n} \delta d(k_{n}, h_{n}) + 2\beta_{n} \delta d(x_{*}, h_{n}).$$
(15)

Substituting (14) in (15), we obtain

(16) 
$$d(b_n, r_n) = [1 - \beta_n (1 - \delta)] d(k_n, h_n) + [1 - \beta_n (1 - \delta) + \delta] d(h_n, x_*).$$

Moreover, using  $(H_4)$ , (6) and (7), we obtain

$$d(m_{n}, s_{n}) = d(W(Tk_{n}, Tb_{n}, \alpha_{n}), W(r_{n}, Tr_{n}, \alpha_{n}))$$

$$\leq (1 - \alpha_{n}) d(Tk_{n}, r_{n}) + \alpha_{n} d(Tb_{n}, Tr_{n})$$

$$\leq (1 - \alpha_{n}) d(Tk_{n}, Th_{n}) + \alpha_{n} \delta d(b_{n}, r_{n})$$

$$+2\alpha_{n} \delta d(x_{*}, r_{n})$$

$$\leq (1 - \alpha_{n}) \delta d(k_{n}, h_{n}) + 2(1 - \alpha_{n}) \delta d(x_{*}, h_{n})$$

$$+\alpha_{n} \delta d(b_{n}, r_{n}) + 2\alpha_{n} \delta d(x_{*}, r_{n}).$$

Substituting (10) and (16) in (17), and using  $\delta \in (0, 1)$  and  $[1 - \beta_n (1 - \delta)] \le 1$ , we obtain

(18) 
$$d(m_n, s_n) \leq \delta d(k_n, h_n) + \left[2 + 2\alpha_n - \alpha_n \beta_n (1 - \delta)\right] d(h_n, x_*)$$

and also using (7), we obtain

$$d(k_{n+1}, h_{n+1}) = d(Tm_n, Ts_n) \leq \delta d(m_n, s_n) + 2\delta d(x_*, s_n).$$

Substituting (13) and (18) in the above inequality, we obtain

$$d(k_{n+1}, h_{n+1}) \leq \delta^{2} d(k_{n}, h_{n}) + \{ [2\delta + 2\alpha_{n}\delta - \alpha_{n}\beta_{n}\delta(1 - \delta)] + 2\delta^{2} [1 - \alpha_{n} (1 - \delta)] \} d(h_{n}, x_{*}).$$

Denote that

(19) 
$$c_{n} = d(k_{n}, h_{n}),$$

$$\rho = \delta^{2} \in (0, 1),$$

$$d_{n} = \{ [2\delta + 2\alpha_{n}\delta - \alpha_{n}\beta_{n}\delta(1 - \delta)] + 2\delta^{2} [1 - \alpha_{n}(1 - \delta)] \} d(h_{n}, x_{*}).$$

It is clear that (19) satisfies all the conditions in Lemma 1.5 and hence it follows from its conclusion that  $\lim_{n\to\infty} d(k_n, h_n) = 0$ . Hence, we obtain  $\lim_{n\to\infty} d(k_n, x_*) = 0$ .

Secondly, we will prove (ii) $\Rightarrow$ (i). Suppose that  $\{k_n\}_{n=0}^{\infty}$  converges to  $x_*$ . It follows from (2), (4), (7), and ( $H_1$ ) that

$$d(b_{n}, x_{*}) = d(W(k_{n}, Tk_{n}, \beta_{n}), Tx_{*})$$

$$\leq (1 - \beta_{n}) d(k_{n}, x_{*}) + \beta_{n} d(Tk_{n}, Tx_{*})$$

$$\leq (1 - \beta_{n}) d(k_{n}, x_{*}) + \beta_{n} \delta d(k_{n}, x_{*})$$

$$= [1 - \beta_{n} (1 - \delta)] d(k_{n}, x_{*})$$

and

$$d(m_n, x_*) = d(W(Tk_n, Tb_n, \alpha_n), Tx_*)$$

$$\leq (1 - \alpha_n) d(Tk_n, Tx_*) + \alpha_n d(Tb_n, Tx_*)$$

$$\leq (1 - \alpha_n) \delta d(k_n, x_*) + \alpha_n \delta d(b_n, x_*).$$

Substituting (20) in (21), we obtain

(22) 
$$d(m_n, x_*) \le \delta \left[1 - \alpha_n \beta_n (1 - \delta)\right] d(k_n, x_*).$$

Also using (6) and  $(H_1)$  we get

(23) 
$$d(k_n, Tk_n) \le (1+\delta) d(k_n, x_*)$$

and

$$d(r_{n}, b_{n}) = d(Th_{n}, W(k_{n}, Tk_{n}, \beta_{n}))$$

$$\leq (1 - \beta_{n}) d(Th_{n}, k_{n}) + \beta_{n} d(Th_{n}, Tk_{n})$$

$$\leq (1 - \beta_{n}) d(Th_{n}, Tk_{n}) + (1 - \beta_{n}) d(Tk_{n}, k_{n})$$

$$+ \beta_{n} d(Th_{n}, Tk_{n})$$

$$= d(Th_{n}, Tk_{n}) + (1 - \beta_{n}) d(Tk_{n}, k_{n}).$$

Substituting (23) in the above inequality, we obtain

(24) 
$$d(r_n, b_n) \leq \delta d(h_n, k_n) + [2\delta + (1 - \beta_n) (1 + \delta)] d(k_n, x_*).$$

Moreover using (6),  $(H_4)$  and (7), we obtain

$$d(s_{n}, m_{n}) = d(W(r_{n}, Tr_{n}, \alpha_{n}), W(Tk_{n}, Tb_{n}, \alpha_{n}))$$

$$\leq (1 - \alpha_{n}) d(r_{n}, Tk_{n}) + \alpha_{n} d(Tr_{n}, Tb_{n})$$

$$\leq (1 - \alpha_{n}) d(Th_{n}, Tk_{n}) + \alpha_{n} d(Tr_{n}, Tb_{n})$$

$$\leq (1 - \alpha_{n}) \delta d(h_{n}, k_{n}) + 2(1 - \alpha_{n}) \delta d(x_{*}, k_{n})$$

$$+\alpha_{n} \delta d(r_{n}, b_{n}) + 2\alpha_{n} \delta d(x_{*}, b_{n}).$$

Substituting (20) and (24) in (25) and using  $\delta \in (0,1)$ , we obtain

$$(26)d(s_n, m_n) \leq \delta d(h_n, k_n) + \left\{ 2(1 - \alpha_n) \delta + \left[ 2\alpha_n \delta^2 + \alpha_n (1 - \beta_n) \delta (1 + \delta) \right] + 2\alpha_n \delta \left[ 1 - \beta_n (1 - \delta) \right] \right\} d(k_n, x_*)$$

and also using (7), we get

$$d(h_{n+1}, k_{n+1}) = d(Ts_n, Tm_n)$$

$$\leq \delta d(s_n, m_n) + 2\delta d(x_*, m_n).$$

Substituting (22) and (26) in the above inequality, we obtain

$$d(h_{n+1}, k_{n+1}) \leq \delta^{2} d(h_{n}, k_{n}) + \begin{cases} 2\delta^{2} (1 - \alpha_{n}) + 2\alpha_{n} \delta^{3} \\ +\alpha_{n} (1 - \beta_{n}) \delta^{2} (1 + \delta) \\ +2\alpha_{n} \delta^{2} [1 - \beta_{n} (1 - \delta)] \\ +2\delta^{2} [1 - \alpha_{n} \beta_{n} (1 - \delta)] \end{cases} d(k_{n}, x_{*})$$

Denote that

$$c_{n} = d(h_{n}, k_{n}),$$

$$\rho = \delta^{2} \in (0, 1),$$

$$d_{n} = \begin{cases} 2\delta^{2} (1 - \alpha_{n}) + 2\alpha_{n} \delta^{3} \\ +\alpha_{n} (1 - \beta_{n}) \delta^{2} (1 + \delta) \\ +2\alpha_{n} \delta^{2} [1 - \beta_{n} (1 - \delta)] \\ +2\delta^{2} [1 - \alpha_{n} \beta_{n} (1 - \delta)] \end{cases} d(k_{n}, x_{*}).$$

It is clear that the above equalities satisfies all the conditions in Lemma 1.5 and hence it follows from its conclusion that  $\lim_{n\to\infty} d(h_n, k_n) = 0$ . Hence, we obtain  $\lim_{n\to\infty} d(h_n, x_*) = 0$ .

THEOREM 2.3. Let C, H, and T with fixed point  $x_*$  be the same as in Theorem 2.1. Let  $\{\alpha_n\}_{n=0}^{\infty}$  and  $\{\beta_n\}_{n=0}^{\infty}$  be real sequences in [0,1] satisfying  $\alpha_1 < \alpha_n \leq 1$ , and  $\beta_1 < \beta_n \leq 1$  for all  $n \in \mathbb{N}$ . For given  $h_0 = k_0 \in C$ , consider the iterative sequences  $\{h_n\}_{n=0}^{\infty}$  and  $\{k_n\}_{n=0}^{\infty}$  defined by (4) and (2) respectively. Then,  $\{h_n\}_{n=0}^{\infty}$  converges to  $x_*$  faster than  $\{k_n\}_{n=0}^{\infty}$ .

*Proof.* From (22), we have

(27) 
$$d(m_n, x_*) \leq \delta \left[1 - \alpha_n \beta_n (1 - \delta)\right] d(k_n, x_*).$$

Also, using (2) and (6) we get

(28) 
$$d(k_{n+1}, x_*) = d(Tm_n, x_*)$$
$$\leq \delta d(m_n, x_*).$$

Substituting (27) in (28), we obtain

(29) 
$$d(k_{n+1}, x_*) \le \delta^2 \left[ 1 - \alpha_n \beta_n (1 - \delta) \right] d(k_n, x_*).$$

By repeating this process n times, we get

$$d(k_{n}, x_{*}) \leq \delta^{2} \left[1 - \alpha_{n-1}\beta_{n-1} (1 - \delta)\right] d(k_{n-1}, x_{*})$$

$$d(k_{n-1}, x_{*}) \leq \delta^{2} \left[1 - \alpha_{n-2}\beta_{n-2} (1 - \delta)\right] d(k_{n-2}, x_{*})$$

$$\vdots$$

$$d(k_{1}, x_{*}) \leq \delta^{2} \left[1 - \alpha_{0}\beta_{0} (1 - \delta)\right] d(k_{0}, x_{*}).$$

From the above inequalities, we have

(30) 
$$d(k_{n+1}, x_*) \le d(k_0, x_*) \delta^{2(n+1)} \prod_{i=0}^{n} [1 - \alpha_i \beta_i (1 - \delta)].$$

Also, from Theorem 2.1, we have

(31) 
$$d(h_{n+1}, x_*) \le d(h_0, x_*) \delta^{2(n+1)} \prod_{i=0}^{n} [1 - \alpha_i (1 - \delta)].$$

Applying assumptions  $\alpha_1 < \alpha_n \le 1$ , and  $\beta_1 < \beta_n \le 1$  to (30) and (31) respectively, we obtain

$$d(k_{n+1}, x_*) \leq d(k_0, x_*) \delta^{2(n+1)} \left[1 - \alpha_1 \beta_1 (1 - \delta)\right]^{n+1} d(h_{n+1}, x_*) \leq d(h_0, x_*) \delta^{2(n+1)} \left[1 - \alpha_1 (1 - \delta)\right]^{n+1}.$$

Define

$$a_n = d(h_0, x_*) \delta^{2(n+1)} [1 - \alpha_1 (1 - \delta)]^{n+1}$$
  

$$b_n = d(k_0, x_*) \delta^{2(n+1)} [1 - \alpha_1 \beta_1 (1 - \delta)]^{n+1}$$

and

$$\Delta_n = \frac{a_n}{b_n} = \frac{d(h_0, x_*) \, \delta^{2(n+1)} \left[ 1 - \alpha_1 (1 - \delta) \right]^{n+1}}{d(k_0, x_*) \, \delta^{2(n+1)} \left[ 1 - \alpha_1 \beta_1 (1 - \delta) \right]^{n+1}}$$
$$= \left[ \frac{1 - \alpha_1 (1 - \delta)}{1 - \alpha_1 \beta_1 (1 - \delta)} \right]^{n+1}.$$

Since  $\delta$  and  $\beta_1 \in (0,1)$ , we have

$$\beta_1 < 1$$

$$\Rightarrow \alpha_1 \beta_1 < \alpha_1$$

$$\Rightarrow \alpha_1 \beta_1 (1 - \delta) < \alpha_1 (1 - \delta)$$

$$\Rightarrow \frac{[1 - \alpha_1 (1 - \delta)]}{[1 - \alpha_1 \beta_1 (1 - \delta)]} < 1.$$

Therefore,  $\lim_{n\to\infty} \Delta_n = 0$ . Hence from Definition 1.4, we obtain that  $\{h_n\}_{n=1}^{\infty}$  converges faster than  $\{k_n\}_{n=1}^{\infty}$ .

In the following we give a non-trivial example to show iteration process (4) has higher convergence speed when compared to iteration process (2):

EXAMPLE 2.4. Let H = [0, 1] be endowed with the usual metric. Define operator  $T: H \to H$  by  $Tx = \frac{1}{4} \exp(0.025 - x^2) - \frac{1}{2} \sin x$  with a unique fixed point  $x_* = 0.166471116$ . The operator T satisfies the condition (6) with  $\delta \in [0.75, 1)$ . For  $h_0 = k_0 = 1$  and  $\alpha_n = 0.40$ ,  $\beta_n = 0.30$ , the following table shows that iteration process (4) converges to  $x_* = 0.166471116$  faster than iteration process (2).

TABLE 1. Comparison the convergence speed of iteration process (4) and iteration process (2).

Number of iter.	iteration (4)	iteration (2)
$x_0$	1	1
$x_1$	0,275703121	0,275703121
$x_2$	0, 180394601	0,218930031
<u>:</u>	:	:
$x_{10}$	0, 166471117	0,166472569
$x_{11}$	0, 166471116	0,166471222
:	<u>:</u>	<u>:</u>
$x_{17}$		0,166471117
$x_{18}$		0, 166471116

THEOREM 2.5. Let S be an approximate operator of T. Let  $\{h_n\}_{n=1}^{\infty}$  be an iterative sequence generated by (4) for T and define an iterative sequence  $\{u_n\}_{n=1}^{\infty}$  as follows:

(32) 
$$\begin{cases} u_0 \in C, \\ u_{n+1} = Sv_n \\ v_n = W(w_n, Tw_n, \alpha_n) \\ w_n = Su_n. \end{cases}$$

where  $\{\alpha_n\}_{n=1}^{\infty}$  is a real sequence in [0,1] satisfying  $\frac{1}{2} \leq \alpha_n$  for all  $n \in \mathbb{N}$ . If  $Tx_* = x_*$  and  $Su_* = u_*$  such that  $u_n \to u_*$  as  $n \to \infty$ , then we have

$$d\left(x_{*}, u_{*}\right) \leq \frac{5\varepsilon}{1 - \delta}$$

where  $\varepsilon > 0$  is a fixed number.

*Proof.* It follows from (H4),(4),(6),(9),(10) and (32), that

$$(33) d(r_n, x_*) \le \delta d(h_n, x_*)$$

and

(34) 
$$d(s_n, x_*) \le \delta [1 - \alpha_n (1 - \delta)] d(h_n, x_*)$$

and

(35) 
$$d(w_n, r_n) = d(Su_n, Th_n)$$

$$\leq d(Su_n, Tu_n) + d(Tu_n, Th_n)$$

$$\varepsilon + \delta d(u_n, h_n) + 2\delta d(x_*, h_n).$$

Also

$$d(v_{n}, s_{n}) = d(W(w_{n}, Sw_{n}, \alpha_{n}), W(r_{n}, Tr_{n}, \alpha_{n}))$$

$$\leq (1 - \alpha_{n}) d(w_{n}, r_{n}) + \alpha_{n} d(Sw_{n}, Tr_{n})$$

$$\leq (1 - \alpha_{n}) d(w_{n}, r_{n}) + \alpha_{n} d(Sw_{n}, Tw_{n})$$

$$+\alpha_{n} d(Tw_{n}, Tr_{n})$$

$$\leq (1 - \alpha_{n}) d(w_{n}, r_{n}) + \alpha_{n} \varepsilon$$

$$+\alpha_{n} \delta d(w_{n}, r_{n}) + 2\alpha_{n} \delta d(x_{*}, r_{n})$$

$$= [1 - \alpha_{n} (1 - \delta)] d(w_{n}, r_{n})$$

$$+2\alpha_{n} \delta d(r_{n}, x_{*}) + \alpha_{n} \varepsilon.$$

Substituting (33) and (35) in (36), we obtain

$$d(v_n, s_n) \leq [1 - \alpha_n (1 - \delta)] \varepsilon$$

$$+ \delta [1 - \alpha_n (1 - \delta)] d(u_n, h_n)$$

$$+ 2\delta [1 - \alpha_n (1 - \delta)] d(h_n, x_*)$$

$$+ 2\alpha_n \delta^2 d(h_n, x_*) + \alpha_n \varepsilon.$$

Using  $\delta \in (0,1)$  and the above inequality, we obtain

(37) 
$$d(v_{n}, s_{n}) \leq [1 - \alpha_{n} (1 - \delta)] d(u_{n}, h_{n}) + \{2\delta [1 - \alpha_{n} (1 - \delta)] + 2\alpha_{n} \delta^{2}\} d(h_{n}, x_{*}) + \{[1 - \alpha_{n} (1 - \delta)] + \alpha_{n}\} \varepsilon.$$

Moreover

(38) 
$$d(u_{n+1}, h_{n+1}) = d(Sv_n, Ts_n)$$

$$\leq d(Sv_n, Tv_n) + d(Tv_n, Ts_n)$$

$$\leq \varepsilon + \delta d(v_n, s_n) + 2\delta d(x_*, s_n).$$

Substituting (34) and (37) in (38) and using  $\delta \in (0,1)$ , we obtain

(39) 
$$d(u_{n+1}, h_{n+1}) \leq [1 - \alpha_n (1 - \delta)] d(u_n, h_n) + \{4\delta^2 + 2\alpha_n \delta^2\} d(h_n, x_*) + (2 + \alpha_n)\varepsilon.$$

From hypothesis, we obtain

$$1 - \alpha_n \le \alpha_n.$$

Applying the above inequality to (39), we get

$$d(u_{n+1}, h_{n+1}) \leq \left[1 - \alpha_n (1 - \delta)\right] d(u_n, h_n)$$

$$\alpha_n (1 - \delta) \left[\frac{10\delta^2 d(h_n, x_*) + 5\varepsilon}{(1 - \delta)}\right].$$

Denote

$$c_n = d(u_n, h_n)$$
  

$$\xi_n = \alpha_n (1 - \delta) \in (0, 1),$$
  

$$\mu_n = \frac{10\delta^2 d(h_n, x_*) + 5\varepsilon}{(1 - \delta)}.$$

Hence, all conditions in Lemma 1.7 are satisfied. Therefore,

$$0 \le \limsup_{n \to \infty} d(u_n, h_n) \le \limsup_{n \to \infty} \frac{10\delta^2 d(h_n, x_*) + 5\varepsilon}{(1 - \delta)}.$$

Since  $h_n \to x_*$  and  $u_n \to u_*$  as  $n \to \infty$ , then we have

$$d\left(x_{*}, u_{*}\right) \leq \frac{5\varepsilon}{1 - \delta}.$$

EXAMPLE 2.6. Let H = [0,1] be endowed with the usual metric. Define operator  $T: H \to H$  by  $Tx = \frac{1}{3}\cos{(2x)}$  with a unique fixed point  $x_* = 0.2818$ . It is easy to check that T satisfies (6) with  $\delta \in [0.50, 1)$ . Define operator  $S: H \to H$  by

(40) 
$$Su = \frac{1}{2} - \frac{2}{3}(u - 0.01)^3 + \frac{2}{15}(u - 0.05)^5 - \frac{4}{283}(u + 0.02)^8$$

By utilizing Wolfram Mathematica 9 software package, we get  $\max_{x \in H} |T - S| = 0.1667$ . Hence for all  $x \in H$  and for a fixed  $\varepsilon = 0.1667 > 0$ , we have  $|Tx - Sx| \leq 0.1667$ . Thus S is an approximate operator of T in the sense of Definition 1.8. Also  $u_* = 0.446009101$  is the unique fixed point for the operator S in H = [0,1]. Therefore  $|x_* - u_*| = 0.178$ . If we put

 $\alpha_n = 0.15$  in (32) for the approximate operator S (40), we obtain

$$\begin{cases} u_{n+1} = \frac{1}{2} - \frac{2}{3}(v_n - 0.01)^3 \\ + \frac{2}{15}(v_n - 0.05)^5 - \frac{4}{283}(v_n + 0.02)^8 \\ v_n = (0.85) w_n \\ + (0.15) \left[ \frac{1}{2} - \frac{2}{3}(w_n - 0.01)^3 + \frac{2}{15}(w_n - 0.05)^5 - \frac{4}{283}(w_n + 0.02)^8 \right] \\ w_n = \frac{1}{2} - \frac{2}{3}(u_n - 0.01)^3 + \frac{2}{15}(u_n - 0.05)^5 - \frac{4}{283}(u_n + 0.02)^8 \end{cases}$$

The following table shows that the sequence  $\{u_n\}_{n=0}^{\infty}$  generated by (41) converges to the fixed point  $u_* = 0.446009101$ .

Table 2. Convergence of iteration process (41)

Number of iter.	iteration (41)
$x_0$	1
$x_1$	0,499998240
$x_2$	0,452178384
:	i :
$x_9$	0,446009102
$x_{10}$	0,446009101

Then we can find the following estimate

$$|x_* - u_*| = 0.178 \le \frac{5(0.1667)}{1 - 0.50} = 1.667.$$

## References

- R. Agarwal, D. O'Regan and D.Sahu, Iterative Construction of Fixed Points of Nearly Asymptotically Nonexpansive Mappings, J. Nonlinear Convex Anal. 8 (2007), 61–79.
- [2] M.R. Alfuraidan and M.A. Khamsi, Fixed points of monotone nonexpansive mappings on a hyperbolic metric space with a graph, Fixed Point Theory Appl. 44 (2015), 1–10.

- [3] V. Berinde, On The Stability of Some Fixed Point Procedures, Bul. Stiintc. Univ. Baia Mare, Ser. B, Mat.-Inform. 18 (2002), 7–14.
- [4] V. Berinde, On The Convergence of The Ishikawa Iteration in The Class of Quasi Contractive Operators, Acta Math. Univ. Comen. 73 (2004), 119–126.
- [5] A.O.Bosede and B.E. Rhoades, Stability of Picard and Mann iteration for a General Class of Functions, J. Adv. Math. Stud. 3 (2010), 23–26.
- [6] L. Chen, Y. Cui, H. Hudzik and R. Kaczmarek, Ellipsoidal geometry of Banach spaces and applications, J. Nonlinear Convex Anal. 18 (2017), 279–308.
- [7] R. Chugh and V. Kumar, Data Dependence of Noor and SP iterative Schemes When Dealing with Quasi-Contractive Operators, Int. J. Comput. Appl. 40 (2011), 41–46.
- [8] Y. Cui, H. Hudzik, R. Kaczmarek, H. Ma, Y. Wang and M. Zhang, On Some Applications of Geometry of Banach Spaces and Some New Results Related to the Fixed Point Theory in Orlicz Sequence Spaces, J. Math. Study, 49 (2016) 325-378.
- [9] S. Dilworth, D. Kutzarova, G. Lancien and N. Randrianarivony, *Asymptotic geometry of Banach spaces and uniform quotient maps*, Proc. Amer. Math. Soc., **142** (2014), 2747–2762.
- [10] H. Fukhar-ud-din, One Step Iterative Scheme for a Pair of Nonexpansive Mappings in a Convex Metric Space, Hacet. J. Math. Stat. 44 (2015), 1023–1031.
- [11] H. Fukhar-ud-din and V. Berinde, Iterative Methods for the Class of Quasi-Contractive Type Operators and Comparsion of Their Rate of Convergence in Convex Metric Spaces, Filomat, **30** (2016), 223–230.
- [12] H. Fukhar-ud-din and M. Khan, Convergence Analysis of a General Iteration Schema of Non-Linear Mappings in Hyperbolic Spaces, Fixed Point Theory Appl. 2013 (2013), 1–18.
- [13] G. Godefroy, G. Lancien and V. Zizler, *The non-linear geometry of Banach spaces after Nigel Kalton*, Rocky Mountain J. Math. 44 (2014), 1529–1583.
- [14] K. Goebel and W.A.Kirk, *Iteration Processes for Nonexpansive Mappings*, Topol. Methods Nonlinear Anal. **21** (1983) 115–123.
- [15] F. Gursoy, V. Karakaya and B.E. Rhoades, Data Dependence Results of New Multi-step and S-Iterative Schemes for Contractive-like Operators, Fixed Point Theory Appl. 2013 (2013), 1–12.
- [16] F. Gursoy, A.R. Khan and H. Fukhar-ud-din, Convergence and data dependence results for quasi-contractive type operators in hyperbolic spaces, Hacet. J. Math. Stat. 46 (2017), 377–388.
- [17] F. Gursoy, A Picard-S Iterative Method for Approximating Fixed Point of Weak-Contraction Mappings, Filomat, 30 (2016), 2829–2845.
- [18] E. Hacioglu and V. Karakaya, Existence and convergence for a new multivalued hybrid mapping in  $CAT(\kappa)$  spaces, Carpathian J. Math. **33** (2017), 319-326.
- [19] E. Hacioglu and V. Karakaya, Some Fixed Point Results for A Multivalued Generalization of Generalized Hybrid Mappings in CAT(κ)-Spaces, Konuralp J. Math. 6 (2018), 26-34.
- [20] A.M. Harder and T.L. Hicks, Stability Results for Fixed Point Iteration Procedures, Math. Japonica, 33 (1988), 693–706.

- [21] H. Hudzik, V. Karakaya, M. Mursaleen and N. Simsek, Banach-Saks Type and Gurarii Modulus of Convexity of Some Banach Sequence Spaces, Abstr. Appl. Anal. 2014 (2014) 1–9.
- [22] C.O.Imoru and M.O.Olantiwo, On The Stability of Picard and Mann Iteration Processes, Carpath. J. Math. 19 (2003), 155–160.
- [23] Z.Z. Jamil and B.A. Ahmed, Convergence and Data Dependence Result for Picard S-Iterative Scheme Using Contractive-Like operators, Amer. Rev. Math. Stat. 3 (2015), 83–86.
- [24] V.Karakaya, Y. Atalan, K. Dogan and NEH. Bouzara, Some Fixed Point Results for a New Three Steps Iteration Process in Banach Spaces, Fixed Point Theory, 18 (2017), 625–640.
- [25] V. Karakaya, F. Gursoy, K. Dogan and M.Erturk, Data Dependence Results for Multistep and CR Iterative Schemes in the Class of Contractive-Like Operators, Abstr. Appl. Anal. 2013 (2013) 1–7.
- [26] S.H. Khan, Fixed Points of Contractive-Like Operators by a Faster Iterative Process, Int. J. Math. Comput. Sci. Eng. 7 (2013), 57–59.
- [27] A.R. Khan, H. Fukhar-ud-din and M.A.A. Khan, An Implicit Algorithm for Two Finite Families of Nonexpansive Maps in Hyperbolic spaces, Fixed Point Theory Appl. 54 (2012), 1–12.
- [28] JK. Kim, KS. Kim and YM. Nam, Convergence of Stability of Iterative Processes for a Pair of Simultaneously Asymptotically Quasi-Nonexpansive Type Mappings in Convex Metric Spaces, J. Comput. Anal. Appl. 9 (2007), 159–172.
- [29] JK. Kim, SA. Chun and YM. Nam, Convergence Theorems of Iterative Sequences for Generalized pp-Quasicontractive Mappings in pp-Convex Metric Spaces, J. Comput. Anal. Appl. 10 (2008), 147–162.
- [30] U. Kohlenbach, Some Logical Metatheorems with Applications in Functional Analysis, Trans. Amer. Math. Soc. **357** (2004), 89–128.
- [31] J.O. Olaleru and H. Akewe, On Multistep Iterative Scheme for Approximating the Common Fixed Points of Contractive-like Operators, Int. J. Math. Math. Sci. 2010 (2010) 1–11.
- [32] M.O. Olatinwo, O.O. Owojori and C.O.Imoru, On Some Stability Results for Fixed Point Iteration Procedure, J. Math. Stat. Sci. 2 (2006), 339–342.
- [33] M.O. Olatinwo, Some Stability Results for Nonexpansive and Quasi-Nonexpansive Operators in Uniformly Convex Banach Space Using Two New Iterative Processes of Kirk-Type, Fasc. Math. 43 (2010) 101–114.
- [34] M.O. Osilike and A. Udomene, Short Proofs of Stability Results for Fixed Point Iteration Procedures for a Class of Contractive-Type Mappings, Indian J. Pure Appl. Math. 30 (1999), 1229–1234.
- [35] W. Pheungrattana and S. Suantai, On the Rate of Convergence of Mann, Ishikawa, Noor and SP Iterations for Continuous on an Arbitrary Interval, J. Comput. Appl. Math. 235 (2011), 3006-3914.
- [36] W. Phuengrattana and S. Suantai, Comparison of The Rate of Convergence of Various Iterative Methods for the Class of Weak Contractions in Banach Spaces, Thai J. Math. 11 (2012), 217–226.

- [37] S. Reich and I. Shafrir, *Nonexpansive Iterations in Hyperbolic Spaces*, Nonlinear Anal. Theory Methods Appl. **15** (1990), 537–558.
- [38] B. Rhoades and S.M. Soltuz, The Equivalence Between Mann-Ishikawa Iterations and Multistep Iteration, Nonlinear Anal. 58 (2004), 219–228.
- [39] S.M. Soltuz and T. Grosan, Data Dependence for Ishikawa Iteration When Dealing with Contractive-Like Operators, Fixed Point Theory Appl. 2008 (2008) 1–7.
- [40] W.A.Takahashi, Convexity in Metric Space and Nonexpansive Mappings, Kodai Math. Sem Rep. 22 (1970), 142–149.
- [41] X. Weng, Fixed Point Iteration for Local Strictly Pseudo-Contractive Mapping, Proc. Amer. Math. Soc. 113 (1991), 727–731.
- [42] Q. I. N. Xiaolong and S. Y. Cho, Convergence analysis of a monotone projection algorithm in reflexive Banach spaces, Acta Math. Sci. 37 (2017), 488-502.
- [43] T. Zamfirescu, Fix Point Theorems in Metric Spaces, Arch. Math. 23 (1972), 292–298.

#### Yunus Atalan

Department of Mathematics Aksaray University Aksaray 68100, Turkey E-mail: yunusatalan@aksaray.edu.tr

## Vatan Karakaya

Department of Mathematical Engineering Yildiz Technical University Istanbul 34210, Turkey E-mail: vkkaya@yahoo.com