# NON-ZERO CONSTANT CURVATURE FACTORABLE SURFACES IN PSEUDO-GALILEAN SPACE 

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#### Abstract

Factorable surfaces, i.e. graphs associated with the product of two functions of one variable, constitute a wide class of surfaces in differential geometry. Such surfaces in the pseudo-Galilean space with zero Gaussian and mean curvature were obtained in [2]. In this study, we provide new results relating to the factorable surfaces with non-zero constant Gaussian and mean curvature.


## 1. Introduction

One of challenging problems in classical differential geometry has been obtaining surfaces with prescribed Gaussian $(K)$ and mean curvature ( $H$ ). Let $\mathbb{E}^{3}(x, y, z)$ be a Euclidean 3 -space and $z=z(x, y)$ a real-valued smooth function of two independent variables. In particular, for the immersed graph of $z$ into $\mathbb{E}^{3}$, such a problem is reduced to solve the Monge-Ampère equation given by ([25, 28])

$$
\operatorname{det}\left(\frac{\partial z}{\partial u_{i} \partial u_{j}}\right)=K\left(1+|\nabla z|^{2}\right)^{2}, u_{1}=x, u_{2}=y
$$

and the equation of mean curvature type in divergence form

$$
\operatorname{div}\left(\frac{\nabla z}{\sqrt{1+|\nabla z|^{2}}}\right)=H
$$

where $\nabla$ denotes the gradient of $\mathbb{E}^{2}([17,26,27])$. These equations are also related to the branches such as economics, meteorology, oceanography etc. $[4,5,6,7,8]$.

Recall that the graph surfaces are also known as Monge surfaces (see [14], p. 398). In this study, we deal with a special Monge surface, namely factorable surface that is graph of the form $z(x, y)=f(x) g(y)$ for smooth functions $f, g$. Such surfaces in various ambient spaces with $K, H=$ const. have been classified

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in $[3,13,15,18,19,29,32,33]$. Our purpose is to analyze the factorable surfaces in the pseudo-Galilean space $\mathbb{G}_{3}^{1}$ that is one of real Cayley-Klein spaces (for details, see $[12,16,24,30])$. As distinct from the other ambient spaces, there exist two different kinds of factorable surfaces arising from the absolute figure of $\mathbb{G}_{3}^{1}$. Explicitly, a Monge surface in $\mathbb{G}_{3}^{1}$ is said to be factorable if it is given in one of the explicit forms

$$
\Omega_{1}: z(x, y)=f(x) g(y) \text { and } \Omega_{2}: x(y, z)=f(y) g(z) .
$$

We call $\Omega_{1}$ and $\Omega_{2}$ the factorable surface of first and second kind, respectively. Note that these surfaces have different geometric structures in $\mathbb{G}_{3}^{1}$ (such as metric, curvature etc.). Flat and minimal $(K, H=0)$ factorable surfaces in $\mathbb{G}_{3}^{1}$ were presented in [2]. Still, obtaining such surfaces with $K, H=$ const. $\neq 0$ is an open problem. The present paper is devoted to solve this problem.

## 2. Preliminaries

In this section, some basics of the pseudo-Galilean geometry shall be provided from $[1,9,10,11,20,21,31]$. In particular, the local theory of immersed surfaces into a pseudo-Galilean space was well-structured in [22].

Let $P_{3}(\mathbb{R})$ denote the real projective 3 -space and ( $\left.u_{0}: u_{1}: u_{2}: u_{3}\right)$ the homogeneous coordinates in $P_{3}(\mathbb{R})$. The pseudo-Galilean 3-space $\mathbb{G}_{3}^{1}$ is a metric space constructed within $P_{3}(\mathbb{R})$ having the absolute figure $\{\sigma, l, \epsilon\}$, where $\sigma$ implies the absolute plane of $\mathbb{G}_{3}^{1}, l$ absolute line in $\sigma$ and $\epsilon$ is the hyperbolic involution of the points of $l$. These arguments are given by $\sigma: u_{0}=0$, $l: u_{0}=u_{1}=0$ and

$$
\epsilon:\left(u_{0}: u_{1}: u_{2}: u_{3}\right) \longmapsto\left(u_{0}: u_{1}: u_{3}: u_{2}\right) .
$$

The affine model of $\mathbb{G}_{3}^{1}$ can be introduced by changing homogenous coordinates with affine coordinates:

$$
\left(u_{0}: u_{1}: u_{2}: u_{3}\right)=(1: x: y: z) .
$$

In terms of the affine coordinates, the group of motions is defined by

$$
\left\{\begin{array}{l}
x^{\prime}=a_{1}+x  \tag{2.1}\\
y^{\prime}=a_{2}+a_{3} x+(\cosh \theta) y+(\sinh \theta) z \\
z^{\prime}=a_{4}+a_{5} x+(\sinh \theta) y+(\cosh \theta) z
\end{array}\right.
$$

where $a_{i}, i \in\{1, \ldots, 5\}$ and $\theta$ are some constants. The pseudo-Galilean distance is introduced with respect to the absolute figure, namely

$$
d(x, y)= \begin{cases}\left|x_{2}-x_{1}\right|, & \text { if } x_{1} \neq x_{2} \\ \sqrt{\left|\left(y_{2}-y_{1}\right)^{2}-\left(z_{2}-z_{1}\right)^{2}\right|,} & \text { if } x_{1}=x_{2}\end{cases}
$$

where $x=\left(x_{1}, y_{1}, z_{1}\right)$ and $y=\left(x_{2}, y_{2}, z_{2}\right)$. Note that this metric (also the absolute figure) is invariant under (2.1).

A plane is said to be pseudo-Euclidean if it satisfies the equation $x=$ const. Otherwise, it is called isotropic plane. A pseudo-Euclidean plane basically has

Minkowskian metric while an isotropic plane has Galilean metric, i.e., parabolic measures of distances and angles. Contrary to its denotation, the isotropic vectors are contained in the pseudo-Euclidean plane $x=0$ and, up to the induced Minkowskian metric on this plane, such vectors are categorized by their causal characters, i.e., spacelike, timelike and lightlike. For further details of the Minkowskian geometry, see [23].

An immersed surface into $\mathbb{G}_{3}^{1}$ is given by the mapping

$$
r: D \subseteq \mathbb{R}^{2} \longrightarrow \mathbb{G}_{3}^{1}, \quad\left(u_{1}, u_{2}\right) \longmapsto\left(x\left(u_{1}, u_{2}\right), y\left(u_{1}, u_{2}\right), z\left(u_{1}, u_{2}\right)\right)
$$

and such a surface is said to be admissible (i.e., without pseudo-Euclidean tangent plane) if $x_{, i}=\frac{\partial x}{\partial u_{i}} \neq 0$ for some $i=1,2$. The first fundamental form is given by

$$
d s^{2}=\left(\mathfrak{g}_{1} d u_{1}+\mathfrak{g}_{2} d u_{2}\right)^{2}+\omega\left(\mathfrak{h}_{11} d u_{1}^{2}+2 \mathfrak{h}_{12} d u_{1} d u_{2}+\mathfrak{h}_{22} d u_{2}^{2}\right)
$$

where $\mathfrak{g}_{i}=x_{, i}, \mathfrak{h}_{i j}=y_{, i} y_{, j}+z_{, i} z_{, j}, i, j=1,2$, and

$$
\omega= \begin{cases}0, & \text { if } d u_{1}: d u_{2} \text { is non-isotropic direction } \\ 1, & \text { if } d u_{1}: d u_{2} \text { is isotropic direction. }\end{cases}
$$

A side tangent vector field in the tangent plane of the surface $r$ is of the form $x_{, 1} r_{, 2}-x_{, 2} r_{, 1}$. Its pseudo-Galilean norm corresponds to

$$
W=\sqrt{\left|\left(x_{, 1} y_{, 2}-x_{, 2} y_{, 1}\right)^{2}-\left(x_{, 1} z_{, 2}-x_{, 2} z_{, 1}\right)^{2}\right|}
$$

A surface with $W=0$ is said to be lightlike. Throughout the study, all immersed admissible surfaces shall be assumed to be non-lightlike. Then the vector given by

$$
S=\frac{x_{, 1} r_{, 2}-x_{, 2} r_{, 1}}{W}=\frac{1}{W}\left(0, x_{, 1} y_{, 2}-x_{, 2} y_{, 1}, x_{, 1} z_{, 2}-x_{, 2} z_{, 1}\right),
$$

satisfies $S \cdot S=\varepsilon=\{-1,1\}$, where "." denotes the Minkowskian scalar product. Hence a surface is said to be spacelike (timelike) if $\varepsilon=1(\varepsilon=-1)$. The normal vector field is defined as

$$
N=\frac{1}{W}\left(0, x_{, 1} z_{, 2}-x_{, 2} z, 1, x_{, 1} y_{, 2}-x_{, 2} y_{, 1}\right)
$$

such that $N \cdot N=-\varepsilon$. The second fundamental form is $I I=\sum_{i, j=1}^{2} L_{i j} d u_{i} d u_{j}$, where if $\mathfrak{g}_{1} \neq 0$

$$
L_{i j}=\frac{\varepsilon}{\mathfrak{g}_{1}}\left(\mathfrak{g}_{1}\left(0, y_{, i j}, z_{, i j}\right)-\mathfrak{g}_{i, j}\left(0, y_{, 1}, z_{, 1}\right)\right) \cdot N
$$

otherwise

$$
L_{i j}=\frac{\varepsilon}{\mathfrak{g}_{2}}\left(\mathfrak{g}_{2}\left(0, y_{, i j}, z_{, i j}\right)-\mathfrak{g}_{i, j}\left(0, y_{, 2}, z_{, 2}\right)\right) \cdot N
$$

for $y_{, i j}=\frac{\partial^{2} y}{\partial u_{i} \partial u_{j}}, 1 \leq i, j \leq 2$. Consequently, the Gaussian and mean curvature are defined as

$$
K=-\varepsilon \frac{L_{11} L_{22}-L_{12}^{2}}{W^{2}} \text { and } H=-\varepsilon \frac{\mathfrak{g}_{2}^{2} L_{11}-2 \mathfrak{g}_{1} \mathfrak{g}_{2} L_{12}+\mathfrak{g}_{1}^{2} L_{22}}{2 W^{2}}
$$

A surface is said to have constant Gaussian (resp. mean) curvature if $K$ (resp. $H)$ is a constant function identically. In particular, it is said to be flat (resp. minimal) if the constant function vanishes.

## 3. Factorable surfaces of first kind

Let us consider the factorable surface of first kind in $\mathbb{G}_{3}^{1}$ given in explicit form $\Omega_{1}: z(x, y)=f(x) g(y)$. Our purpose is to describe such a surface with $K=$ const. $\neq 0$ and $H=$ const.$\neq 0$. For this, firstly we can give the following result:

Theorem 3.1. Let a factorable surface of first kind in $\mathbb{G}_{3}^{1}$ have non-zero constant Gaussian curvature $K_{0}$. Then we have:

$$
z(x, y)=\tanh \left( \pm \sqrt{\left|K_{0}\right|} x+\lambda_{1}\right)\left(y+\lambda_{2}\right), \lambda_{1}, \lambda_{2} \in \mathbb{R}
$$

Proof. Assume that $\Omega_{1}$ has non-zero constant Gaussian curvature $K_{0}$. Hence, we get a relation as follows:

$$
\begin{equation*}
K_{0}=\frac{f g f^{\prime \prime} g^{\prime \prime}-\left(f^{\prime} g^{\prime}\right)^{2}}{\left[1-\left(f g^{\prime}\right)^{2}\right]^{2}} \tag{3.1}
\end{equation*}
$$

where $f^{\prime}=\frac{d f}{d x}, g^{\prime}=\frac{d g}{d y}$, etc. $K_{0}$ vanishes identically when $f$ or $g$ is a constant function. Then $f$ and $g$ must be non-constant functions. We distinguish two cases for the equation (3.1):
Case a. $f^{\prime}=f_{0}, f_{0} \in \mathbb{R}-\{0\}$. Thereby (3.1) turns into the following polynomial equation on $\left(g^{\prime}\right)$ :

$$
K_{0}+\left(f_{0}^{2}-2 K_{0} f^{2}\right)\left(g^{\prime}\right)^{2}+K_{0} f^{4}\left(g^{\prime}\right)^{4}=0
$$

which yields a contradiction.
Case b. $f^{\prime \prime} \neq 0$. We have again two cases:
Case b.1. $g^{\prime}=g_{0}, g_{0} \in \mathbb{R}-\{0\}$. Then (3.1) leads to

$$
\begin{equation*}
\pm \sqrt{\left|K_{0}\right|}=\frac{g_{0} f^{\prime}}{1-\left(g_{0} f\right)^{2}} \tag{3.2}
\end{equation*}
$$

After solving (3.2), we obtain

$$
f(x)=\frac{1}{g_{0}} \tanh \left( \pm \sqrt{\left|K_{0}\right|} x+\lambda_{1}\right), \quad \lambda_{1} \in \mathbb{R} .
$$

Case b.2. $g^{\prime \prime} \neq 0$. Then (3.1) can be arranged as follows:

$$
\begin{equation*}
\frac{K_{0}\left[1-\left(f g^{\prime}\right)^{2}\right]^{2}}{f f^{\prime \prime}\left(g^{\prime}\right)^{2}}=\frac{g g^{\prime \prime}}{\left(g^{\prime}\right)^{2}}-\frac{\left(f^{\prime}\right)^{2}}{f f^{\prime \prime}} \tag{3.3}
\end{equation*}
$$

The partial derivative of (3.2) with respect to $x$ and $y$ leads to a polynomial equation on $\left(g^{\prime}\right)$ :

$$
\begin{equation*}
-\left(\frac{1}{f f^{\prime \prime}}\right)^{\prime}+\left(\frac{f^{3}}{f^{\prime \prime}}\right)^{\prime}\left(g^{\prime}\right)^{4}=0 \tag{3.4}
\end{equation*}
$$

Since all coefficients must vanish in (3.4), the contradiction $f^{\prime}=0$ is obtained. Therefore the proof is completed.
Theorem 3.2. Let a factorable surface of first kind in $\mathbb{G}_{3}^{1}$ have non-zero constant mean curvature $H_{0}$. Then the following occurs:

$$
z(x, y)=f_{0} g(y)=\frac{1}{2 H_{0}} \sqrt{\left(2 H_{0} y+\lambda_{1}\right)^{2} \pm 1}+\lambda_{2}
$$

where " $\pm$ " happens plus (resp. minus) when the surface is spacelike (resp. timelike). Further, $f_{0}$ is non-zero constant and $\lambda_{1}, \lambda_{2}$ some constants.
Proof. Relating to the mean curvature, we get

$$
\begin{equation*}
H_{0}=\frac{f g^{\prime \prime}}{2\left|1-\left(f g^{\prime}\right)^{2}\right|^{\frac{3}{2}}} \tag{3.5}
\end{equation*}
$$

It is clear from (3.5) that $g$ is a non-linear function. By taking partial derivative of (3.5) with respect to $x$, we deduce

$$
\begin{equation*}
f^{\prime}\left|1-\left(f g^{\prime}\right)^{2}\right|-3 f\left|f f^{\prime}\left(g^{\prime}\right)^{2}\right|=0 \tag{3.6}
\end{equation*}
$$

which yields two cases:
Case a. $f=f_{0} \neq 0, f_{0} \in \mathbb{R}$, is a solution for (3.6). If the surface is spacelike, then (3.5) turns to

$$
-2 H_{0}=\frac{f_{0} g^{\prime \prime}}{\left[1-\left(f_{0} g^{\prime}\right)^{2}\right]^{\frac{3}{2}}}
$$

By solving (3.7), we find

$$
g(y)=\frac{1}{2 f_{0} H_{0}} \sqrt{\left(2 H_{0} y+\lambda_{1}\right)^{2}+1}+\lambda_{2}
$$

where $\lambda_{1}$ and $\lambda_{2}$ are some constants. Otherwise, i.e., timelike situation yields

$$
\begin{equation*}
2 H_{0}=\frac{f_{0} g^{\prime \prime}}{\left[\left(f_{0} g^{\prime}\right)^{2}-1\right]^{\frac{3}{2}}} \tag{3.8}
\end{equation*}
$$

After solving (3.8), we obtain

$$
g(y)=\frac{1}{2 f_{0} H_{0}} \sqrt{\left(2 H_{0} y+\lambda_{3}\right)^{2}-1}+\lambda_{4}
$$

for some constants $\lambda_{3}, \lambda_{4}$.

Case b. $f^{\prime} \neq 0$. If the surface is spacelike or timelike, then (3.6) implies

$$
1+2\left(f g^{\prime}\right)^{2}=0
$$

which is not possible.

## 4. Factorable surfaces of second kind

As in previous section we try to describe the factorable graph surfaces of second kind in $\mathbb{G}_{3}^{1}$ given in explicit form $\Omega_{2}: x(y, z)=f(y) g(z)$, assuming $K=$ const.$\neq 0$ and $H=$ const.$\neq 0$. Therefore the following non-existence result can be stated:

Theorem 4.1. There does not exist a factorable surface of second kind in $\mathbb{G}_{3}^{1}$ having non-zero constant Gaussian curvature.

Proof. It is proved by contradiction. Then we suppose that $\Omega_{2}$ has the Gaussian curvature $K_{0} \neq 0$ in $\mathbb{G}_{3}^{1}$. By a calculation, relating to the Gaussian curvature, we get

$$
\begin{equation*}
K_{0}=\frac{f g f^{\prime \prime} g^{\prime \prime}-\left(f^{\prime} g^{\prime}\right)^{2}}{\left[\left(f g^{\prime}\right)^{2}-\left(f^{\prime} g\right)^{2}\right]^{2}} \tag{4.1}
\end{equation*}
$$

where $f^{\prime}=\frac{d f}{d y}, g^{\prime}=\frac{d g}{d z}$ and so on. Hereinafter $f$ and $g$ must be non-constant functions so that $K_{0}$ does not vanish. Point that the roles of $f$ and $g$ are symmetric and it is sufficient to discuss the cases depending on $f$. Thus, if $f^{\prime \prime}=0$, i.e., $f^{\prime}=f_{0} \neq 0$, then (4.1) turns to a polynomial equation on $(f)$ :

$$
\begin{equation*}
\left[K_{0}\left(g^{\prime}\right)^{4}\right] f^{4}-\left[2 K_{0}\left(f_{0} g g^{\prime}\right)^{2}\right] f^{2}+K_{0}\left(f_{0} g\right)^{4}+\left(f_{0} g^{\prime}\right)^{2}=0 \tag{4.2}
\end{equation*}
$$

The fact that the coefficients must be zero yields the contradiction $g^{\prime}=0$. Hence $f$ is a non-linear function and by symmetry, so is $g$. By dividing (4.1) with $f f^{\prime \prime}\left(g^{\prime}\right)^{2}$, we can write

$$
\begin{equation*}
K_{0}\left[\frac{f^{3}}{f^{\prime \prime}}\left(g^{\prime}\right)^{2}-2 \frac{f\left(f^{\prime}\right)^{2}}{f^{\prime \prime}} g^{2}+\frac{\left(f^{\prime}\right)^{4}}{f f^{\prime \prime}}\left(\frac{g^{2}}{g^{\prime}}\right)^{2}\right]=\frac{g g^{\prime \prime}}{\left(g^{\prime}\right)^{2}}-\frac{\left(f^{\prime}\right)^{2}}{f f^{\prime \prime}} \tag{4.3}
\end{equation*}
$$

Put $f^{\prime}=p, \dot{p}=\frac{d p}{d f}=\frac{f^{\prime \prime}}{f^{\prime}}$ and $g^{\prime}=r, \dot{r}=\frac{d r}{d g}=\frac{g^{\prime \prime}}{g^{\prime}}$ in (4.3). Then the partial derivative of (4.3) with respect to $g$ gives

$$
\begin{equation*}
K_{0}\left[2 \frac{f^{3}}{p \dot{p}} r \dot{r}-4 \frac{f p}{\dot{p}} g+2 \frac{p^{3}}{f \dot{p}}\left(\frac{g^{2}}{r}\right)\left\{\frac{d}{d g}\left(\frac{g^{2}}{r}\right)\right\}\right]=\frac{d}{d g}\left(\frac{g \dot{r}}{r}\right) . \tag{4.4}
\end{equation*}
$$

The partial derivative of (4.4) with respect to $f$ yields
(4.5) $r \dot{r}\left[\frac{d}{d f}\left(\frac{f^{3}}{p \dot{p}}\right)\right]-2 g\left[\frac{d}{d f}\left(\frac{f p}{\dot{p}}\right)\right]+\left[\frac{d}{d f}\left(\frac{p^{3}}{f \dot{p}}\right)\right]\left[\left(\frac{g^{2}}{r}\right) \frac{d}{d g}\left(\frac{g^{2}}{r}\right)\right]=0$.

By dividing (4.5) with $g$ and taking partial derivative with respect to $g$, we derive

$$
\begin{equation*}
\underbrace{\left[\frac{d}{d f}\left(\frac{f^{3}}{p \dot{p}}\right)\right]}_{F_{1}(f)} \overbrace{\left[\frac{d}{d g}\left(\frac{r \dot{r}}{g}\right)\right]}^{G_{1}(g)}+\underbrace{\left[\frac{d}{d f}\left(\frac{p^{3}}{f \dot{p}}\right)\right]}_{F_{2}(f)} \overbrace{\left[\frac{d}{d g}\left\{\left(\frac{g}{r}\right) \frac{d}{d g}\left(\frac{g^{2}}{r}\right)\right\}\right]}^{G_{2}(g)}=0 . \tag{4.6}
\end{equation*}
$$

We have to distinguish several cases:
Case a. $F_{1}=0$. Then $f^{3}=\lambda_{1} p \dot{p}, \lambda_{1} \in \mathbb{R}, \lambda_{1} \neq 0$. We have again two cases:
Case a.1. $F_{2}=0$, namely $p^{3}=\lambda_{2} f \dot{p}, \lambda_{2} \in \mathbb{R}, \lambda_{2} \neq 0$. Considering these in (4.5) implies $f p=\lambda_{3} \dot{p}, \lambda_{3} \in \mathbb{R}, \lambda_{3} \neq 0$. Substituting these into (4.3) yields

$$
K_{0}\left[\lambda_{1} r^{2}-2 \lambda_{3} g^{2}+\lambda_{2}\left(\frac{g^{2}}{r}\right)^{2}\right]-\frac{g \dot{r}}{r}=\frac{-\lambda_{2}}{p^{2}}
$$

The left side of (4.7) is either a function of $g$ or a constant, however other side is a non-constant function of $f$. This is not possible.
Case a.2. $G_{2}=0$. It implies $\frac{d}{d g}\left(\frac{g^{2}}{r}\right)=\frac{\lambda_{4} r}{g}, \lambda_{4} \in \mathbb{R}$. By considering this one into (4.5) together with the assumption of Case a, we conclude

$$
\begin{equation*}
\left[\frac{d}{d f}\left(\frac{p}{f}\right)\right]\left[1-\lambda_{4}\left(\frac{p}{f}\right)^{2}\right]=0 \tag{4.8}
\end{equation*}
$$

If $p=\lambda_{5} f, \lambda_{5} \in \mathbb{R}, \lambda_{5} \neq 0$, in (4.8) then we have $\dot{p}=\lambda_{5}$. Combining it with the assumption of Case a gives $f^{2}=\lambda_{1} \lambda_{5}^{2}$ that contradicts with $K_{0} \neq 0$.
Case b. $G_{1}=0$. Hence $r \dot{r}=\lambda_{1} g, \lambda_{1} \in \mathbb{R}, \lambda_{1} \neq 0$. We have two cases:
Case b.1. $F_{2}=0$, i.e., $p^{3}=\lambda_{2} f \dot{p}, \lambda_{2} \in \mathbb{R}, \lambda_{2} \neq 0$. Then (4.5) follows

$$
\begin{equation*}
\left[\frac{d}{d f}\left(\frac{f}{p}\right)\right]\left[\lambda_{1}\left(\frac{f}{p}\right)^{2}-1\right]=0 \tag{4.9}
\end{equation*}
$$

If $p=\lambda_{3} f, \lambda_{3} \in \mathbb{R}, \lambda_{3} \neq 0$ in (4.8), then we get $\dot{p}=\lambda_{3}$. Comparing this one with the assumption of Case b. 1 gives $f^{2}=\frac{\lambda_{2}}{\lambda_{3}^{2}}$, which is no possible since $K_{0} \neq 0$.
Case b.2. $G_{2}=0$. It follows

$$
\begin{equation*}
\left(\frac{g}{r}\right) \frac{d}{d g}\left(\frac{g^{2}}{r}\right)=\lambda_{4}, \lambda_{4} \in \mathbb{R} \tag{4.10}
\end{equation*}
$$

An integration of (4.10) with respect to $g$ gives

$$
r= \pm \frac{g^{2}}{\sqrt{\lambda_{4} g^{2}+\lambda_{5}}}, \lambda_{5} \in \mathbb{R}
$$

where $\lambda_{4}$ and $\lambda_{5}$ are not equal to zero together. After taking derivative of (4.11) with respect to $g$ and producting with $r$, we conclude

$$
r \dot{r}=\frac{\lambda_{4} g^{5}+2 \lambda_{5} g^{3}}{\left(\lambda_{4} g^{2}+\lambda_{5}\right)^{2}}
$$

Due to the assumption of the Case $\mathrm{b},(4.12)$ turns to the following polynomial equation on $g$ :
$\left(\lambda_{4}-\lambda_{1} \lambda_{4}^{2}\right) g^{5}+2\left(\lambda_{5}-\lambda_{1} \lambda_{4} \lambda_{5}\right) g^{3}-\left(\lambda_{1} \lambda_{5}^{2}\right) g=0$.
Since $\lambda_{1} \neq 0$, we get $1=\lambda_{1} \lambda_{4}$ and $\lambda_{5}=0$. It follows from (4.11) that $r=\left(\lambda_{4}\right)^{\frac{-1}{2}} g$. Then by substituting it into (4.3), we obtain

$$
K_{0}\left[\frac{f^{3}}{\lambda_{4} p \dot{p}}-2 \frac{f p}{\dot{p}}+\lambda_{4} \frac{p^{3}}{f \dot{p}}\right] g^{2}+\frac{p}{f \dot{p}}-1=0
$$

This polynomial equation leads to

$$
\begin{equation*}
\frac{f^{3}}{\lambda_{4} p \dot{p}}-2 \frac{f p}{\dot{p}}+\lambda_{4} \frac{p^{3}}{f \dot{p}}=0 . \tag{4.16}
\end{equation*}
$$

Substituting (4.15) into (4.16) gives $p= \pm\left(\lambda_{4}\right)^{\frac{-1}{2}} f$ or $f(y)$ $=\lambda_{6} \exp \left( \pm\left(\lambda_{4}\right)^{\frac{-1}{2}} y\right), \lambda_{6} \in \mathbb{R}, \lambda_{6} \neq 0$. Further, since $r=$ $\left(\lambda_{4}\right)^{\frac{-1}{2}} g$, we have $g(z)=\lambda_{7} \exp \left(\left(\lambda_{4}\right)^{\frac{-1}{2}} z\right), \lambda_{7} \in \mathbb{R}, \lambda_{7} \neq 0$. However these lead the surface to be flat, i.e., $K_{0}=0$, which is not our case.
Case c. $F_{1} G_{1} \neq 0$. Then (4.6) can be rewritten as

$$
\begin{equation*}
\frac{F_{1}(f)}{F_{2}(f)}+\frac{G_{2}(g)}{G_{1}(g)}=0 \tag{4.17}
\end{equation*}
$$

which implies

$$
\begin{equation*}
\frac{f^{3}}{p \dot{p}}=\lambda_{1} \frac{p^{3}}{f \dot{p}}+\lambda_{2}, \text { and }\left(\frac{g}{r}\right) \frac{d}{d g}\left(\frac{g^{2}}{r}\right)=-\lambda_{1} \frac{r \dot{r}}{g}+\lambda_{3}, \tag{4.18}
\end{equation*}
$$

where $\lambda_{1}, \lambda_{2}, \lambda_{3} \in \mathbb{R}, \lambda_{1} \neq 0$. Substituting (4.18) into (4.5) gives

$$
2 \frac{f p}{\dot{p}}=\lambda_{3} \frac{p^{3}}{f \dot{p}}+\lambda_{4}, \lambda_{4} \in \mathbb{R}
$$

Comparing (4.19) with the first equality in (4.18) leads to

$$
\left\{\begin{array}{l}
f^{4}-\lambda_{1} p^{4}=\lambda_{2} f p \dot{p} \\
2 f^{2} p^{2}-\lambda_{3} p^{4}=\lambda_{4} f p \dot{p} .
\end{array}\right.
$$

By (4.20), we derive an equation as follows:

$$
\begin{equation*}
\lambda_{4} f^{4}-2 \lambda_{2} f^{2} p^{2}+\left(\lambda_{2} \lambda_{3}-\lambda_{1} \lambda_{4}\right) p^{4}=0 \tag{4.21}
\end{equation*}
$$

or

$$
\begin{equation*}
\lambda_{4}\left(\frac{f}{p}\right)^{2}+\left(\lambda_{2} \lambda_{3}-\lambda_{1} \lambda_{4}\right)\left(\frac{f}{p}\right)^{-2}=2 \lambda_{2} \tag{4.22}
\end{equation*}
$$

Taking derivative of (4.22) with respect to $f$ leads to

$$
\begin{equation*}
\frac{d}{d f}\left(\frac{f}{p}\right)\left[1-\left(\lambda_{2} \lambda_{3}-\lambda_{1}\right)\left(\frac{f}{p}\right)^{-4}\right]=0 \tag{4.23}
\end{equation*}
$$

which yields that the ratio $f / p$ is constant, i.e., $p=\lambda_{5} f, \lambda_{5} \in \mathbb{R}$, $\lambda_{5} \neq 0$. Substituting this one into (4.3) gives the following polynomial equation on $(f)$ :

$$
K_{0}\left[\frac{r^{2}}{\lambda_{5}^{2}}-2 g^{2}+\lambda_{5}^{2}\left(\frac{g^{2}}{r}\right)^{2}\right] f^{2}-\frac{g \dot{r}}{r}+1=0
$$

which implies

$$
\frac{r^{2}}{\lambda_{5}^{2}}-2 g^{2}+\lambda_{5}^{2}\left(\frac{g^{2}}{r}\right)^{2}=0
$$

and $r=g \dot{r}$. Solving this one leads to $r=\lambda_{6} g, \lambda_{6} \in \mathbb{R}, \lambda_{6} \neq 0$. However, this is not possible since $K_{0} \neq 0$. This completes the proof.

Theorem 4.2. Let a factorable surface of second kind in $\mathbb{G}_{3}^{1}$ have non-zero constant mean curvature $H_{0}$. Then we have:

$$
x(y, z)=\lambda_{1} \exp \left(\lambda_{2} y+\frac{\lambda_{2}}{2 H_{0}} \sqrt{\left(2 H_{0} z+\lambda_{3}\right)^{2} \pm 1}\right)
$$

where " $\pm$ " happens plus (resp. minus) when the surface is timelike (resp. spacelike). Further, $\lambda_{1}, \lambda_{2}$ are non-zero constants and $\lambda_{3}$ some constant.

Proof. It is only proved for spacelike situation since the calculations are almost same for other situation. Then we have

$$
\left(f g^{\prime}\right)^{2}-\left(f^{\prime} g\right)^{2}>0
$$

for all pairs $(y, z)$. Since the mean curvature is constant $H_{0} \neq 0$, by a calculation, we deduce

$$
\begin{equation*}
2 H_{0}\left[\left(f g^{\prime}\right)^{2}-\left(f^{\prime} g\right)^{2}\right]^{\frac{3}{2}}=\left(f g^{\prime}\right)^{2} f^{\prime \prime} g-2 f g\left(f^{\prime} g^{\prime}\right)^{2}+\left(f^{\prime} g\right)^{2} f g^{\prime \prime} \tag{4.24}
\end{equation*}
$$

Note that $f$ is not a constant function since $H_{0} \neq 0$ and, by symmetry, neither is $g$. Then dividing (4.24) with $f g\left(f^{\prime} g^{\prime}\right)^{2}$ yields

$$
\begin{equation*}
2 H_{0}\left[\left(\frac{f}{f^{\prime}}\right)^{\frac{4}{3}}\left(\frac{g^{\prime}}{g}\right)^{\frac{2}{3}}-\left(\frac{f^{\prime}}{f}\right)^{\frac{2}{3}}\left(\frac{g}{g^{\prime}}\right)^{\frac{4}{3}}\right]^{\frac{3}{2}}=\frac{f f^{\prime \prime}}{\left(f^{\prime}\right)^{2}}+\frac{g g^{\prime \prime}}{\left(g^{\prime}\right)^{2}}-2 . \tag{4.25}
\end{equation*}
$$

Let us put $f^{\prime}=p, \dot{p}=\frac{d p}{d f}=\frac{f^{\prime \prime}}{f^{\prime}}$ and $g^{\prime}=r, \dot{r}=\frac{d r}{d g}=\frac{g^{\prime \prime}}{g^{\prime}}$ in (4.25). Thus (4.25) can be rewritten as

$$
\begin{equation*}
2 H_{0}\left[\left(\frac{f}{p}\right)^{\frac{4}{3}}\left(\frac{r}{g}\right)^{\frac{2}{3}}-\left(\frac{p}{f}\right)^{\frac{2}{3}}\left(\frac{g}{r}\right)^{\frac{4}{3}}\right]^{\frac{3}{2}}=\frac{f \dot{p}}{p}+\frac{g \dot{r}}{r}-2 . \tag{4.26}
\end{equation*}
$$

The partial derivative of (4.26) with respect to $f$ gives
(4.27)

$$
\begin{aligned}
& 2 H_{0}\left[\left(\frac{f}{p}\right)^{\frac{4}{3}}\left(\frac{r}{g}\right)^{\frac{2}{3}}-\left(\frac{p}{f}\right)^{\frac{2}{3}}\left(\frac{g}{r}\right)^{\frac{4}{3}}\right]^{\frac{1}{2}}\left[2\left(\frac{r}{g}\right)^{\frac{2}{3}}+\left(\frac{p}{f}\right)^{2}\left(\frac{g}{r}\right)^{\frac{4}{3}}\right] \frac{d}{d f}\left(\frac{f}{p}\right) \\
= & \frac{d}{d f}\left(\frac{f \dot{p}}{p}\right)\left(\frac{p}{f}\right)^{\frac{1}{3}} .
\end{aligned}
$$

If $\dot{p}=0$, then (4.27) reduces to

$$
2+\left(\frac{p}{f}\right)^{2}\left(\frac{g}{r}\right)^{2}=0
$$

which is not possible. Thus $p$ is not constant function and, by symmetry, so is $r$. In addition, we have to consider two cases in order to solve (4.27):
Case a. $p=\lambda_{1} f, \lambda_{1} \neq 0$, is a solution for (4.27). Substituting this one into (4.26) gives

$$
2 H_{0}\left[\lambda_{1}^{-\frac{4}{3}}\left(\frac{r}{g}\right)^{\frac{2}{3}}-\lambda_{1}^{\frac{2}{3}}\left(\frac{g}{r}\right)^{\frac{4}{3}}\right]^{\frac{3}{2}}=\frac{g \dot{r}}{r}-1
$$

or

$$
2 H_{0}\left[\left(\frac{r}{g}\right)^{2}-\lambda_{1}^{2}\right]^{\frac{3}{2}}=\lambda_{1}^{2}\left[\frac{r \dot{r}}{g}-\left(\frac{r}{g}\right)^{2}\right] .
$$

The last equality can be rearranged as

$$
\begin{equation*}
2 H_{0}=\frac{\lambda_{1}^{2}\left(\frac{g^{\prime}}{g}\right)^{\prime}}{\left[\left(\frac{g^{\prime}}{g}\right)^{2}-\lambda_{1}^{2}\right]^{\frac{3}{2}}} . \tag{4.28}
\end{equation*}
$$

An integration of (4.28) with respect to $z$ yields

$$
2 H_{0} z+\lambda_{2}=\frac{-\frac{g^{\prime}}{g}}{\sqrt{\left(\frac{g^{\prime}}{g}\right)^{2}-\lambda_{1}^{2}}}
$$

or

$$
\begin{equation*}
\frac{g^{\prime}}{g}=\frac{\lambda_{1}\left(2 H_{0} z+\lambda_{2}\right)}{\sqrt{\left(2 H_{0} z+\lambda_{2}\right)^{2}-1}} . \tag{4.29}
\end{equation*}
$$

An again integration of (4.29) with respect to $z$ leads to

$$
g(z)=\lambda_{3} \exp \left(\frac{\lambda_{1}}{2 H_{0}} \sqrt{\left(2 H_{0} z+\lambda_{2}\right)^{2}-1}\right), \lambda_{3} \neq 0
$$

Due to the assumption of Case a, we conclude $f(y)=\lambda_{4} \exp \left(\lambda_{1} y\right)$, $\lambda_{4} \neq 0$, which gives the assertion of the theorem.
Case b. $\frac{d}{d f}\left(\frac{f}{p}\right) \neq 0$. By symmetry, we deduce $\frac{d}{d g}\left(\frac{g}{r}\right) \neq 0$. Then (4.27) can be rewritten as

$$
\begin{equation*}
\left[\left(\frac{r}{g}\right)^{2}-\left(\frac{p}{f}\right)^{2}\right]^{\frac{1}{2}}\left[2+\left(\frac{p}{f}\right)^{2}\left(\frac{r}{g}\right)^{-2}\right]=\frac{\frac{d}{d f}\left(\frac{f \dot{p}}{p}\right)\left(\frac{p}{f}\right)}{2 H_{0} \frac{d}{d f}\left(\frac{f}{p}\right)} \tag{4.30}
\end{equation*}
$$

The partial derivative of (4.30) with respect to $g$ leads to

$$
2\left(\frac{r}{g}\right)^{4}-\left(\frac{r}{g}\right)^{2}\left(\frac{p}{f}\right)^{2}+2\left(\frac{p}{f}\right)^{4}=0
$$

or

$$
\left[\left(\frac{r}{g}\right)^{2}-\left(\frac{p}{f}\right)^{2}\right]^{2}+\frac{3}{2}\left(\frac{r}{g}\right)^{2}\left(\frac{p}{f}\right)^{2}=0
$$

which yields a contradiction. Therefore the proof is completed.

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