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On the Fine Spectrum of the Lower Triangular Matrix B(r,s)over the Hahn Sequence Space

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ABSTRACT. In this article we have determined the spectrum and fine spectrum of the lower triangular matrix B(r, s) on the Hahn sequence space h. We have also determined the approximate point spectrum, the defect spectrum and the compression spectrum of the operator B(r, s) on the sequence space h.

1. Introduction

By w, we denote the space of all real or complex valued sequences. Throughout the paper $c, c_0, bv, cs, bs, \ell_1, \ell_{\infty}$ represent the spaces of all convergent, null, bounded variation, convergent series, bounded series, absolutely summable and bounded sequences respectively. Also bv_0 denotes the sequence space $bv \cap c_0$.

Fine spectra of various matrix operators on different sequence spaces have been examined by several authors. Fine spectrum of the operator $\Delta_{a,b}$ on the sequence space c was determined by Akhmedov and El-Shabrawy [1]. The fine spectra of the Cesàro operator C_1 over the sequence space bv_p , $(1 \leq p < \infty)$ was determined by Akhmedov and Başar [2]. Altay and Başar [3, 4] determined the fine spectrum of the difference operator Δ and the generalized difference operator B(r, s) on the sequence spaces c_0 and c. The spectrum and fine spectrum of the Zweier Matrix on the sequence spaces ℓ_1 and bv were studied by Altay and Karakuş [5]. Altum [6, 7] determined the fine spectra of triangular Toeplitz operators and tridiagonal symmetric matrices over some sequence spaces. Furkan, Bilgiç and Kayaduman [14] have determined the fine spectrum of the generalized difference operator B(r, s) over the sequence spaces ℓ_1 and bv. Fine spectra of operator B(r, s, t) over the sequence spaces ℓ_1 and bv. Fine spectra of operator B(r, s, t) over the sequence spaces ℓ_1 and bv and generalized difference operator B(r, s, t) over the sequence spaces ℓ_1 and bv and generalized difference operator B(r, s, t) over the sequence spaces ℓ_1 and bv and generalized difference operator B(r, s, t) over the sequence spaces ℓ_1 and bv and generalized difference operator B(r, s, t) over the sequence spaces ℓ_1 and bv and generalized difference operator B(r, s, t) over the sequence spaces ℓ_1 and bv and generalized difference operator B(r, s, t) over the sequence spaces ℓ_1 and bv and generalized difference operator B(r, s, t) over the sequence spaces spaces ℓ_1 and bv and generalized difference operator B(r, s, t) over the sequence spaces spaces ℓ_1 and bv_2 , $(1 \le p < \infty)$ were studied by Bilgiç and Furkan [11, 12]. Furkan, Bilgiç and Altay [15] have studied the fine spectrum of operator B(r, s, t) over the sequence

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spaces c_0 and c. Fine spectrum of the operator B(r, s, t) over the sequence spaces ℓ_p and bv_p , $(1 \leq p < \infty)$ were studied by Furkan, Bilgiç and Başar [16]. The spectrum of the operator D(r, 0, 0, s) over the sequence space bv_0 was investigated by Tripathy and Paul [30]. Tripathy and Paul [29, 31] also determined the spectrum of the operators D(r, 0, 0, s) and D(r, 0, s, 0, t) over the sequence spaces ℓ_p and bv_p , $(1 \leq p < \infty)$. Fine spectrum of the generalized difference operator Δ_v on the sequence space ℓ_1 was investigated by Srivastava and Kumar [26]. Panigrahi and Srivastava [23, 24] studied the spectrum and fine spectrum of the second order difference operator Δ_{uv}^2 on the sequence space c_0 and generalized second order forward difference operator Δ^2_{uvw} on the sequence space ℓ_1 . Fine spectra of upper triangular double-band matrix U(r, s) over the sequence spaces c_0 and c were studied by Karakaya and Altun [20]. Karaisa and Başar [19] have determined the spectrum and fine spectrum of the upper traiangular matrix A(r, s, t) over the sequence space ℓ_p , (0 . Dündar and Başar [13] have studied the fine spectrum of thelinear operator Δ^+ defined by an upper triangle double band matrix acting on the sequence space c_0 with respect to the Goldberg's classification. Başar, Durna and Yildirim [9] subdivided the spectra for some generalized difference operators over certain sequence spaces. Başar [10] also determined the spectrum and fine spectrum of some particular limitation matrices over some sequence spaces. Tripathy and Das [27, 28] have studied the fine spectrum of the matrix operators B(r, 0, s) and U(r, s)over the sequence space cs. The fine spectrum of the forward difference operator on the Hahn sequence space h was determined by Yeşilkayagil and Kirişci [33].

The Hahn sequence space is defined as

$$h = \left\{ x = (x_n) \in w : \sum_{k=1}^{\infty} k |\Delta x_k| < \infty \quad \text{and} \quad \lim_{k \to \infty} x_k = 0 \right\},$$

where $\Delta x_k = x_k - x_{k+1}$, for all $k \in \mathbb{N}$. This space was defined and studied to some general properties by Hahn [18]. The norm $||x||_h = \sum_{k=1}^{\infty} k |\Delta x_k| + \sup_k |x_k|$ on the space h was defined by Hahn [18]. Rao ([25], Proposition 2.1) defined a new norm on h given by $||x||_h = \sum_{k=1}^{\infty} k |\Delta x_k|$. Many other authors also investigated various properties of the Hahn sequence space.

In this paper, we shall determine the spectrum and fine spectrum of the lower triangular matrix B(r, s) on the Hahn sequence space h. Also we determine the approximate point spectrum, the defect spectrum and the compression spectrum of the operator B(r, s) on the sequence space h.

2. Preliminaries and Background

Let X and Y be Banach spaces and $T: X \to Y$ be a bounded linear operator. By R(T), we denote the range of T, i.e.

$$R(T) = \{ y \in Y : y = Tx, x \in X \}.$$

By B(X), we denote the set of all bounded linear operators on X into itself. If $T \in B(X)$, then the adjoint T^* of T is a bounded linear operator on the dual X^*

of X defined by $(T^*f)(x) = f(Tx)$, for all $f \in X^*$ and $x \in X$. Let $X \neq \{\theta\}$ be a complex normed linear space, where θ is the zero element and $T: D(T) \to X$ be a linear operator with domain $D(T) \subseteq X$. With T, we associate the operator

$$T_{\lambda} = T - \lambda I,$$

where λ is a complex number and I is the identity operator on D(T). If T_{λ} has an inverse which is linear, we denote it by T_{λ}^{-1} , that is

$$T_{\lambda}^{-1} = (T - \lambda I)^{-1},$$

and call it the *resolvent* operator of T.

A regular value λ of T is a complex number such that

- (R1) T_{λ}^{-1} exists,
- (R2) T_{λ}^{-1} is bounded
- (R3) T_{λ}^{-1} is defined on a set which is dense in X i.e. $\overline{R(T_{\lambda})} = X$.

The resolvent set of T, denoted by $\rho(T, X)$, is the set of all regular values λ of T. Its complement $\sigma(T, X) = \mathbb{C} \setminus \rho(T, X)$ in the complex plane \mathbb{C} is called the *spectrum* of T. Furthermore, the spectrum $\sigma(T, X)$ is partitioned into three disjoint sets as follows:

The *point(discrete) spectrum* $\sigma_p(T, X)$ is the set of all $\lambda \in \mathbb{C}$ such that T_{λ}^{-1} does not exist. Any such $\lambda \in \sigma_p(T, X)$ is called an eigenvalue of T.

The continuous spectrum $\sigma_c(T, X)$ is the set of all $\lambda \in \mathbb{C}$ such that T_{λ}^{-1} exists and satisfies (R3), but not (R2), that is, T_{λ}^{-1} is unbounded.

The residual spectrum $\sigma_r(T, X)$ is the set of all $\lambda \in \mathbb{C}$ such that T_{λ}^{-1} exists (and may be bounded or not), but does not satisfy (R3), that is, the domain of T_{λ}^{-1} is not dense in X.

From Goldberg [17], if X is a Banach space and $T\in B(X)$, then there are three possibilities for R(T) and T^{-1} :

- (I) R(T) = X,
- (II) $R(T) \neq \overline{R(T)} = X$
- (III) $\overline{R(T)} \neq X$

and

- (1) T^{-1} exists and is continuous,
- (2) T^{-1} exists but is discontinuous,
- (3) T^{-1} does not exist.

If these possibilities are combined in all possible ways, nine different states are created which may be shown as in Table 1.

ſ		Ι	II	III
ſ	1	$\rho(T,X)$		$\sigma_r(T,X)$
	2	$\sigma_c(T,X)$	$\sigma_c(T,X)$	$\sigma_r(T,X)$
	3	$\sigma_p(T,X)$	$\sigma_p(T,X)$	$\sigma_p(T,X)$

Table 1: Subdivisions of spectrum of a linear operator

These are labeled by: I_1 , I_2 , I_3 , II_1 , II_2 , II_3 , III_1 , III_2 and III_3 . If λ is a complex number such that $T_{\lambda} \in I_1$ or $T_{\lambda} \in I_2$, then λ is in the resolvent set $\rho(T, X)$ of T. The further classification gives rise to the fine spectrum of T. If an operator is in state II_2 , then $R(T_{\lambda}) \neq \overline{R(T_{\lambda})} = X$ and T_{λ}^{-1} exists but is discontinuous and we write $\lambda \in II_2\sigma(T, X)$. The state II_1 is impossible as if T_{λ} is injective, then from Kreyszig [[22], Problem 6, p.290] T_{λ}^{-1} is bounded and hence continuous if and only if $R(T_{\lambda})$ is closed.

Again, following Appell et al. [8], we define the three more subdivisions of the spectrum called as the *approximate point spectrum*, *defect spectrum* and *compression spectrum*.

Given a bounded linear operator T in a Banach space X, we call a sequence (x_k) in X as a Weyl sequence for T if $||x_k|| = 1$ and $||Tx_k|| \to 0$ as $k \to \infty$.

The $approximate\ point\ spectrum\ of\ T$, denoted by $\sigma_{ap}(T,X)$, is defined as the set

(2.1)
$$\sigma_{ap}(T,X) = \{\lambda \in \mathbb{C} : \text{there exists a Weyl sequence for } T - \lambda I\}$$

The *defect spectrum* of T, denoted by $\sigma_{\delta}(T, X)$, is defined as the set

(2.2)
$$\sigma_{\delta}(T, X) = \{\lambda \in \mathbb{C} : T - \lambda I \text{ is not surjective}\}\$$

The two subspectra given by the relations (2.1) and (2.2) form a (not necessarily disjoint) subdivisions

(2.3)
$$\sigma(T, X) = \sigma_{ap}(T, X) \cup \sigma_{\delta}(T, X)$$

of the spectrum. There is another subspectrum

$$\sigma_{co}(T, X) = \{\lambda \in \mathbb{C} : \overline{R(T - \lambda I)} \neq X\}$$

which is often called the *compression spectrum* of T. The compression spectrum gives rise to another (not necessarily disjoint) decomposition

(2.4)
$$\sigma(T,X) = \sigma_{ap}(T,X) \cup \sigma_{co}(T,X)$$

Clearly, $\sigma_p(T,X) \subseteq \sigma_{ap}(T,X)$ and $\sigma_{co}(T,X) \subseteq \sigma_{\delta}(T,X)$. Moreover, it is easy to verify that

(2.5)
$$\sigma_r(T, X) = \sigma_{co}(T, X) \setminus \sigma_p(T, X) \quad \text{and}$$

(2.6)
$$\sigma_c(T,X) = \sigma(T,X) \setminus \left[\sigma_p(T,X) \cup \sigma_{co}(T,X)\right]$$

By the definitions given above, we can illustrate the subdivisions of spectrum of a bounded linear operator in Table 2.

		1	2	3
		T_{λ}^{-1} exists	T_{λ}^{-1} exists	T_{λ}^{-1} does not exist
		and is bounded	and is not bounded	~
Ι	$R(T_{\lambda}) = X$	$\lambda \in \rho(T, X)$	• • •	$\lambda \in \sigma_p(T, X)$
				$\lambda \in \sigma_{ap}(T, X)$
			$\lambda \in \sigma_c(T, X)$	$\lambda \in \sigma_p(T, X)$
II	$\overline{R(T_{\lambda})} = X$	$\lambda \in \rho(T, X)$	$\lambda \in \sigma_{ap}(T, X)$	$\lambda \in \sigma_{ap}(T, X)$
			$\lambda \in \sigma_{\delta}(T, X)$	$\lambda \in \sigma_{\delta}(T, X)$
		$\lambda \in \sigma_r(T, X)$	$\lambda \in \sigma_r(T, X)$	$\lambda \in \sigma_p(T, X)$
III	$\overline{R(T_{\lambda})} \neq X$	$\lambda \in \sigma_{\delta}(T, X)$	$\lambda \in \sigma_{ap}(T, X)$	$\lambda \in \sigma_{ap}(T, X)$
		$\lambda \in \sigma_{co}(T, X)$	$\lambda \in \sigma_{\delta}(T,X)$	$\lambda \in \sigma_{\delta}(T, X)$
			$\lambda \in \sigma_{co}(T, X)$	$\lambda \in \sigma_{co}(T, X)$

Table 2: Subdivisions of spectrum of a linear operator

Proposition 2.1.(Appell et al. [8], Proposition 1.3, p. 28) Spectra and subspectra of an operator $T \in B(X)$ and its adjoint $T^* \in B(X^*)$ are related by the following relations:

- (a) $\sigma(T^*, X^*) = \sigma(T, X).$
- (b) $\sigma_c(T^*, X^*) \subseteq \sigma_{ap}(T, X).$
- (c) $\sigma_{ap}(T^*, X^*) = \sigma_{\delta}(T, X).$
- (d) $\sigma_{\delta}(T^*, X^*) = \sigma_{ap}(T, X).$
- (e) $\sigma_p(T^*, X^*) = \sigma_{co}(T, X).$
- (f) $\sigma_{co}(T^*, X^*) \supseteq \sigma_p(T, X).$
- (g) $\sigma(T,X) = \sigma_{ap}(T,X) \cup \sigma_p(T^*,X^*) = \sigma_p(T,X) \cup \sigma_{ap}(T^*,X^*).$

The relations (c)-(f) show that the approximate point spectrum is in a certain sense dual to defect spectrum, and the point spectrum dual to the compression spectrum. Part (g) of Proposition 2.1 implies, in particular, that $\sigma(T, X) = \sigma_{ap}(T, X)$ if X is a Hilbert space and T is normal. Roughly speaking, this shows that normal (in particular, self-adjoint) operators on Hilbert spaces are most similar to matrices in finite dimensional spaces (Appell et al. [8]).

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Let E and F be two sequence spaces and $A = (a_{nk})$ be an infinite matrix of real or complex numbers a_{nk} , where $n, k \in \mathbb{N}$. Then, we say that A defines a matrix mapping from E into F, and we denote it by $A : E \to F$, if for every sequence $x = (x_k) \in E$, the sequence $Ax = \{(Ax)_n\}$, the A-transform of x, is in F, where

(2.7)
$$(Ax)_n = \sum_{k=1}^{\infty} a_{nk} x_k, \quad n \in \mathbb{N}.$$

By (E : F), we denote the class of all matrices such that $A : E \to F$. Thus, $A \in (E : F)$ if and only if the series on the right hand side of (2.7) converges for each $n \in \mathbb{N}$ and every $x \in E$ and we have $Ax = \{(Ax)_n\}_{n \in \mathbb{N}} \in F$ for all $x \in E$.

The matrix B(r, s) is an infinite lower triangular matrix of the form

$$B(r,s) = \begin{pmatrix} r & 0 & 0 & 0 & \cdots \\ s & r & 0 & 0 & \cdots \\ 0 & s & r & 0 & \cdots \\ 0 & 0 & s & r & \cdots \\ \vdots & \vdots & \vdots & \vdots & \ddots \end{pmatrix}$$

where $s \neq 0$.

The following results will be used in order to establish the results of this article.

Lemma 2.1. (Kirişci [21], Theorem 3.5) The matrix $A = (a_{nk})$ gives rise to a bounded linear operator $T \in B(h)$ from h to itself if and only if:

(i)
$$\sum_{n=1}^{\infty} n |(a_{nk} - a_{n+1,k})|$$
 converges, for each k ,
(ii) $\sup \frac{1}{k} \sum_{k=1}^{\infty} n \left| \sum_{k=1}^{k} (a_{nv} - a_{n+1,v}) \right| < \infty$,

(ii)
$$\sup_{k} \frac{1}{k} \sum_{n=1}^{\infty} n \left| \sum_{v=1}^{\infty} (a_{nv} - a_{n+1,v}) \right| < \infty$$

(iii) $\lim_{n \to \infty} a_{nk} = 0$, for each k.

Lemma 2.2. (Goldberg [17], Page 59) T has a dense range if and only if T^* is one to one.

Lemma 2.3. (Goldberg [17], Page 60) T has a bounded inverse if and only if T^* is onto.

3. Spectrum and Fine Spectrum of the Operator ${\cal B}(r,s)$ over the Sequence Space h

Theorem 3.1. $B(r,s): h \to h$ is a bounded linear operator and

$$|| B(r,s) ||_{(h:h)} \le |r| + |s|.$$

Proof. From Lemma 2.1, $B(r,s): h \to h$ is a bounded linear operator on h if

- (i) $\sum_{n=1}^{\infty} n |(a_{nk} a_{n+1,k})|$ converges, for each k,
- (ii) $\sup_{k} \frac{1}{k} \sum_{n=1}^{\infty} n \left| \sum_{v=1}^{k} (a_{nv} a_{n+1,v}) \right| < \infty,$
- (iii) $\lim_{n \to \infty} a_{nk} = 0$, for each k,

where

$$B(r,s) = (a_{nk}) = \begin{pmatrix} r & 0 & 0 & 0 & \cdots \\ s & r & 0 & 0 & \cdots \\ 0 & s & r & 0 & \cdots \\ 0 & 0 & s & r & \cdots \\ \vdots & \vdots & \vdots & \vdots & \ddots \end{pmatrix}$$

For each k, it is clear that $\lim_{n\to\infty} a_{nk} = 0$. Also for each k, $\sum_{n=1}^{\infty} n |(a_{nk} - a_{n+1,k})|$ is finite and so is convergent. It is easy to show that, for each k

$$\frac{1}{k}\sum_{n=1}^{\infty} n \left| \sum_{v=1}^{k} (a_{nv} - a_{n+1,v}) \right| \le |r| + \left(1 + \frac{2}{k}\right) |s|$$

and so

$$\sup_{k} \frac{1}{k} \sum_{n=1}^{\infty} n \left| \sum_{v=1}^{k} (a_{nv} - a_{n+1,v}) \right| \le |r| + 3|s| < \infty.$$

Now,

$$||B(r,s)(x)||_{h} = \sum_{k=1}^{\infty} k |(sx_{k} + rx_{k+1}) - (sx_{k+1} + rx_{k+2})|$$

$$= \sum_{k=1}^{\infty} k |s(x_{k} - x_{k+1}) + r(x_{k+1} - x_{k+2})|$$

$$\leq |s| \sum_{k=1}^{\infty} k |(x_{k} - x_{k+1})| + |r| \sum_{k=1}^{\infty} k |(x_{k+1} - x_{k+2})|$$

$$\leq (|s| + |r|) ||x||_{h}$$

and hence, $|| B(r,s) ||_{(h:h)} \leq |r| + |s|$. Hence the result. **Theorem 3.2.** The spectrum of the operator B(r,s) over h is given by

$$\sigma(B(r,s),h) = \{ \alpha \in \mathbb{C} : |\alpha - r| \le |s| \}.$$

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Proof. We prove this theorem by showing that $(B(r,s) - \alpha I)^{-1}$ exists and is in (h:h) for $|\alpha - r| > |s|$, and then show that the operator $B(r,s) - \alpha I$ is not invertible for $|\alpha - r| \le |s|$.

Let α be such that $|\alpha - r| > |s|$. Since $s \neq 0$ we have $\alpha \neq r$ and so $B(r, s) - \alpha I$ is a triangle, therefore $(B(r, s) - \alpha I)^{-1}$ exists. Let $y = (y_n) \in h$. On solving $(B(r, s) - \alpha I)x = y$ for x in terms of y we get

$$(B(r,s) - \alpha I)^{-1} = (b_{nk})$$

$$= \begin{pmatrix} \frac{1}{r-\alpha} & 0 & 0 & 0 & \cdots \\ -\frac{s}{(r-\alpha)^2} & \frac{1}{r-\alpha} & 0 & 0 & \cdots \\ \frac{s^2}{(r-\alpha)^3} & -\frac{s}{(r-\alpha)^2} & \frac{1}{r-\alpha} & 0 & \cdots \\ -\frac{s^3}{(r-\alpha)^4} & \frac{s^2}{(r-\alpha)^3} & -\frac{s}{(r-\alpha)^2} & \frac{1}{r-\alpha} & \cdots \\ \vdots & \vdots & \vdots & \vdots & \ddots \end{pmatrix}$$

From Lemma 2.1, $(B(r,s) - \alpha I)^{-1}$ will be a bounded linear operator on h if

- (i) $\sum_{n=1}^{\infty} n |(b_{nk} b_{n+1,k})|$ converges, for each k,
- (ii) $\sup_{k} \frac{1}{k} \sum_{n=1}^{\infty} n \left| \sum_{v=1}^{k} (b_{nv} b_{n+1,v}) \right| < \infty,$ (iii) line h of for each h
- (iii) $\lim_{n \to \infty} b_{nk} = 0$, for each k.

For each k, we get

$$b_{nk} = \frac{(-s)^{n-k}}{(r-\alpha)^{n-k+1}} = \frac{1}{r-\alpha} \left(\frac{-s}{r-\alpha}\right)^{n-k}$$

Since $|\alpha - r| > |s|$, so for each k, $\lim_{n \to \infty} b_{nk} = 0$. For each k, it is easy to show that

$$\sum_{n=1}^{\infty} n |(b_{nk} - b_{n+1,k})| \le (2k-1) \frac{1}{|r-\alpha|} + (2k+1) \frac{|s|}{|r-\alpha|^2} + (2k+3) \frac{|s|^2}{|r-\alpha|^3} + \cdots$$

Now for a fixed k, considering 2k - 1 = a, from above we get

$$\sum_{n=1}^{\infty} n |(b_{nk} - b_{n+1,k})| \leq a \frac{1}{|r-\alpha|} + (a+2) \frac{|s|}{|r-\alpha|^2} + (a+4) \frac{|s|^2}{|r-\alpha|^3} + \cdots$$
$$= \frac{a}{|r-\alpha|} \left(1 + \frac{|s|}{|r-\alpha|} + \frac{|s|^2}{|r-\alpha|^2} + \cdots \right) + \frac{2}{|r-\alpha|} \left(\frac{|s|}{|r-\alpha|} + \frac{2|s|^2}{|r-\alpha|^2} + \frac{3|s|^3}{|r-\alpha|^3} + \cdots \right)$$

Since $|\alpha - r| > |s|$, therefore the two series

$$1 + \frac{|s|}{|r-\alpha|} + \frac{|s|^2}{|r-\alpha|^2} + \cdots \text{ and } \frac{|s|}{|r-\alpha|} + \frac{2|s|^2}{|r-\alpha|^2} + \frac{3|s|^3}{|r-\alpha|^3} + \cdots$$

are convergent and converge to $\frac{1}{1-\frac{|s|}{|r-\alpha|}}$ and $\frac{\frac{|s|}{|r-\alpha|}}{(1-\frac{|s|}{|r-\alpha|})^2}$ respectively. Therefore, $\sum_{n=1}^{\infty} n |(b_{nk} - b_{n+1,k})|$ converges, for each k. Also, for each k, it is easy to show that $\frac{1}{k} \sum_{n=1}^{\infty} n \left| \sum_{v=1}^{k} (b_{nv} - b_{n+1,v}) \right| \leq \frac{1}{|r-\alpha|} + \left(1 + \frac{2}{k}\right) \frac{|s|}{|r-\alpha|^2} + \left(1 + \frac{4}{k}\right) \frac{|s|^2}{|r-\alpha|^3} + \cdots$ $\leq \frac{1}{|r-\alpha|} + 3 \frac{|s|}{|r-\alpha|^2} + 5 \frac{|s|^2}{|r-\alpha|^3} + \cdots$

Since $|\alpha - r| > |s|$, so by D'Alembert's ratio test it is easy to show that the series $\frac{1}{|r-\alpha|} + 3\frac{|s|}{|r-\alpha|^2} + 5\frac{|s|^2}{|r-\alpha|^3} + \cdots$ is convergent and therefore we have,

$$\sup_{k} \frac{1}{k} \sum_{n=1}^{\infty} n \left| \sum_{v=1}^{k} (b_{nv} - b_{n+1,v}) \right| < \infty.$$

So, by Lemma 2.1, $(B(r,s) - \alpha I)^{-1}$ is in (h : h). This shows that $\sigma(B(r,s),h) \subseteq \{\alpha \in \mathbb{C} : |\alpha - r| \leq |s|\}.$

Now, let $\alpha \in \mathbb{C}$ be such that $|\alpha - r| \leq |s|$. If $\alpha \neq r$, then $B(r,s) - \alpha I$ is a triangle and hence, $(B(r,s) - \alpha I)^{-1}$ exists. Let y = (1,0,0,0,...). Then $y \in h$. Now, $(B(r,s) - \alpha I)^{-1}y = x$ gives

$$x_n = \frac{(-s)^{n-1}}{(r-\alpha)^n}.$$

Since $|\alpha - r| \leq |s|$, so the sequence (x_n) does not converge to 0 and so, $x = (x_n) \notin h$. Therefore, $(B(r, s) - \alpha I)^{-1}$ is not in (h : h) and so $\alpha \in \sigma(B(r, s), h)$. If $\alpha = r$, then the operator $B(r, s) - \alpha I$ is represented by the matrix

$$B(r,s) - \alpha I = \begin{pmatrix} 0 & 0 & 0 & 0 & \cdots \\ s & 0 & 0 & 0 & \cdots \\ 0 & s & 0 & 0 & \cdots \\ 0 & 0 & s & 0 & \cdots \\ \vdots & \vdots & \vdots & \vdots & \ddots \end{pmatrix}$$

Since, the range of $B(r,s) - \alpha I$ is not dense, so $\alpha \in \sigma(B(r,s),h)$. Hence,

$$\{\alpha \in \mathbb{C} : |\alpha - r| \le |s|\} \subseteq \sigma(B(r, s), h)$$

This completes the proof.

Theorem 3.3. The point spectrum of the operator B(r, s) over h is given by

$$\sigma_p(B(r,s),h) = \emptyset$$

Proof. Let α be an eigenvalue of the operator B(r,s). Then there exists $x \neq \theta = (0,0,0,...)$ in h such that $B(r,s)x = \alpha x$. Then, we have

$$\begin{aligned} rx_1 &= \alpha x_1 \\ sx_1 + rx_2 &= \alpha x_2 \\ sx_2 + rx_3 &= \alpha x_3 \\ \vdots \\ x_n + rx_{n+1} &= \alpha x_{n+1} \end{aligned} \right\},$$

where $n \geq 1$. If x_k is the first non-zero entry of the sequence (x_n) , then $\alpha = r$. Then from the relation $sx_k + rx_{k+1} = \alpha x_{k+1}$, we have $sx_k = 0$. But $s \neq 0$ and hence, $x_k = 0$, a contradiction. Hence, $\sigma_p(B(r,s),h) = \emptyset$.

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If $T: h \to h$ is a bounded linear operator represented by a matrix A, then it is known that the adjoint operator $T^*: h^* \to h^*$ is defined by the transpose A^t of the matrix A. It should be noted that the dual space h^* of h is isometrically isomorphic to the Banach space $\sigma_{\infty} = \left\{ x = (x_k) \in w : \sup_n \frac{1}{n} \left| \sum_{k=1}^n x_k \right| < \infty \right\}.$

Theorem 3.4. The point spectrum of the operator $B(r, s)^*$ over h^* is given by

$$\sigma_p(B(r,s)^*, h^* \cong \sigma_\infty) = \{ \alpha \in \mathbb{C} : |\alpha - r| < |s| \}.$$

Proof. Let α be an eigenvalue of the operator $B(r, s)^*$. Then there exists $x \neq \theta = (0, 0, 0, ...)$ in σ_{∞} such that $B(r, s)^* x = \alpha x$. Then, we have

$$B(r,s)^{t}x = \alpha x$$

$$\Rightarrow rx_{1} + sx_{2} = \alpha x_{1}$$

$$rx_{2} + sx_{3} = \alpha x_{2}$$

$$\vdots$$

$$rx_{n} + sx_{n+1} = \alpha x_{n}$$

where $n \ge 1$. Solving, we get

$$x_n = \left(\frac{\alpha - r}{s}\right)^{n-1} x_1, \quad n \ge 1.$$

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and so,
$$\sup_{n} \frac{1}{n} \left| \sum_{k=1}^{n} x_{k} \right| < \infty$$
 if and only if $|\alpha - r| < |s|$. Hence, $\sigma_{p}(B(r,s)^{*}, h^{*} \cong \sigma_{\infty}) = \{\alpha \in \mathbb{C} : |\alpha - r| < |s|\}.$

Theorem 3.5. The residual spectrum of the operator B(r, s) over h is given by

$$\sigma_r(B(r,s),h) = \{ \alpha \in \mathbb{C} : |\alpha - r| < |s| \}.$$

Proof. From part (e) of Proposition 2.1 and relation (2.5), we get

$$\sigma_r(B(r,s),h) = \sigma_p(B(r,s)^*,h^*) \setminus \sigma_p(B(r,s),h).$$

So we get the required result by using Theorem 3.3 and Theorem 3.4. \Box

Theorem 3.6. The continuous spectrum of the operator B(r,s) over h is given by

$$\sigma_c(B(r,s),h) = \{ \alpha \in \mathbb{C} : |\alpha - r| = |s| \}.$$

Proof. Since, $\sigma(B(r, s), h)$ is the disjoint union of $\sigma_p(B(r, s), h)$, $\sigma_r(B(r, s), h)$ and $\sigma_c(B(r, s), h)$, therefore, by Theorem 3.2, Theorem 3.3 and Theorem 3.5, we get $\sigma_c(B(r, s), h) = \{\alpha \in \mathbb{C} : |\alpha - r| = |s|\}.$

Theorem 3.7. If $\alpha = r$, then $\alpha \in III_1\sigma(B(r,s),h)$.

Proof. If $\alpha = r$, the range of $B(r, s) - \alpha I$ is not dense. So, from Table 2 and Theorem 3.3, we have $\alpha \in \sigma_r(B(r, s), h)$. From Table 2,

$$\sigma_r(B(r,s),h) = III_1 \sigma(B(r,s),h) \cup III_2 \sigma(B(r,s),h).$$

Therefore, $\alpha \in III_1\sigma(B(r,s),h)$ or $\alpha \in III_2\sigma(B(r,s),h)$. Also for $\alpha = r$,

$$B(r,s) - \alpha I = \begin{pmatrix} 0 & 0 & 0 & 0 & \cdots \\ s & 0 & 0 & 0 & \cdots \\ 0 & s & 0 & 0 & \cdots \\ 0 & 0 & s & 0 & \cdots \\ \vdots & \vdots & \vdots & \vdots & \ddots \end{pmatrix}$$

It is easy to show that the operator $(B(r,s) - \alpha I)^* : \sigma_{\infty} \to \sigma_{\infty}$ is onto. So by Lemma 2.3 we get the operator $B(r,s) - \alpha I$ has a bounded inverse. This completes the theorem.

Theorem 3.8. If $\alpha \neq r$ and $\alpha \in \sigma_r(B(r,s),h)$, then $\alpha \in III_2\sigma(B(r,s),h)$. Proof. Let $\alpha \neq r$. Since, $\alpha \in \sigma_r(B(r,s),h)$, therefore, from Table 2,

$$\alpha \in III_1 \sigma(B(r,s),h)$$
 or $\alpha \in III_2 \sigma(B(r,s),h)$

Now, $\alpha \in \sigma_r(B(r,s),h)$ implies that $|\alpha - r| < |s|$. Therefore, for each k, the sequence $(b_{nk})_n$ in Theorem 3.2 does not converge to 0 as $n \to \infty$ and hence, the operator $B(r,s) - \alpha I$ has no bounded inverse. Therefore, $\alpha \in III_2\sigma(B(r,s),h)$. \Box

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Theorem 3.9. If $\alpha \in \sigma_c(B(r,s),h)$, then $\alpha \in II_2\sigma(B(r,s),h)$.

Proof. If $\alpha \in \sigma_c(B(r,s), h)$, then $|\alpha - r| = |s|$. Therefore, for each k, the sequence $(b_{nk})_n$ in Theorem 3.2 does not converge to 0 as $n \to \infty$ and hence, the operator $B(r,s) - \alpha I$ has no bounded inverse. So, α satisfies Goldberg's condition 2.

Now we shall show that the operator $B(r,s) - \alpha I$ is not onto. Let $y = (y_n) = (1,0,0,0,...)$. Clearly, $(y_n) \in h$. Let $x = (x_n)$ be a sequence such that $(B(r,s) - \alpha I)x = y$. On solving, we get

$$x_n = \frac{(-s)^{n-1}}{(r-\alpha)^n}.$$

Since, $|\alpha - r| = |s|$ so the sequence $\{x_n\}$ does not converge to 0 as $n \to \infty$ and so, $x = (x_n) \notin h$. Hence the operator $B(r, s) - \alpha I$ is not onto. So, α satisfies Goldberg's condition II. This completes the proof. \Box

Theorem 3.10. The approximate point spectrum of the operator B(r, s) over h is given by

$$\sigma_{ap}(B(r,s),h) = \{ \alpha \in \mathbb{C} : |\alpha - r| \le |s| \} \setminus \{r\}.$$

Proof. From Table 2,

$$\sigma_{ap}(B(r,s),h) = \sigma(B(r,s),h) \setminus III_1 \sigma(B(r,s),h).$$

By Theorem 3.7, $III_1\sigma(B(r,s),h) = \{r\}$. This completes the proof.

Theorem 3.11. The compression spectrum of the operator B(r,s) over h is given by

$$\sigma_{co}(B(r,s),h) = \{ \alpha \in \mathbb{C} : |\alpha - r| < |s| \}.$$

Proof. From part (e) of Proposition 2.1, we get

$$\sigma_p(B(r,s)^*,h^*) = \sigma_{co}(B(r,s),h).$$

Using Theorem 3.4, we get the required result.

Theorem 3.12. The defect spectrum of the operator B(r,s) over h is given by

$$\sigma_{\delta}(B(r,s),h) = \{ \alpha \in \mathbb{C} : |\alpha - r| \le |s| \}$$

Proof. From Table 2, we have

$$\sigma_{\delta}(B(r,s),h) = \sigma(B(r,s),h) \setminus I_3 \sigma(B(r,s),h).$$

Also,

$$\sigma_p(B(r,s),h) = I_3 \sigma(B(r,s),h) \cup II_3 \sigma(B(r,s),h) \cup III_3 \sigma(B(r,s),h).$$

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By Theorem 3.3, we have $\sigma_p(B(r,s),h) = \emptyset$ and so $I_3\sigma(B(r,s),h) = \emptyset$. Hence, $\sigma_{\delta}(B(r,s),h) = \{\alpha \in \mathbb{C} : |\alpha - r| \le |s|\}.$

Theorem 3.13. The following statements hold:

- (i) $\sigma_{ap}(B(r,s)^*, h^* \cong \sigma_{\infty}) = \{\alpha \in \mathbb{C} : |\alpha r| \le |s|\}.$
- (ii) $\sigma_{\delta}(B(r,s)^*, h^* \cong \sigma_{\infty}) = \{ \alpha \in \mathbb{C} : |\alpha r| \le |s| \} \setminus \{r\}.$

Proof. From parts (c) and (d) of Proposition 2.1, we get

$$\sigma_{ap}(B(r,s)^*, h^* \cong \sigma_{\infty}) = \sigma_{\delta}(B(r,s), h)$$

and

$$\sigma_{\delta}(B(r,s)^*, h^* \cong \sigma_{\infty}) = \sigma_{ap}(B(r,s), h).$$

Using Theorem 3.10 and Theorem 3.12, we get the required results.

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