# HERMITIAN POSITIVE DEFINITE SOLUTIONS OF THE MATRIX EQUATION $X^{s}+A^{*} X^{-t} A=Q$ 

Mohsen Masoudi, Mahmoud Mohseni Moghadam, and Abbas Salemi


#### Abstract

In this paper, the Hermitian positive definite solutions of the matrix equation $X^{s}+A^{*} X^{-t} A=Q$, where $Q$ is an $n \times n$ Hermitian positive definite matrix, $A$ is an $n \times n$ nonsingular complex matrix and $s, t \in[1, \infty)$ are discussed. We find a matrix interval which contains all the Hermitian positive definite solutions of this equation. Also, a necessary and sufficient condition for the existence of these solutions is presented. Iterative methods for obtaining the maximal and minimal Hermitian positive definite solutions are proposed. The theoretical results are illustrated by numerical examples.


## 1. Introduction and preliminaries

We consider Hermitian positive definite solutions of the nonlinear matrix equation

$$
\begin{equation*}
X^{s}+A^{*} X^{-t} A=Q, \tag{1.1}
\end{equation*}
$$

where, $A$ is an $n \times n$ nonsingular complex matrix, $Q$ is an $n \times n$ Hermitian positive definite matrix and $s, t \in[1, \infty)$.

This form of the nonlinear matrix equation and same configuration to them, can be appeared in control theory [11, 13], ladder networks [2, 3], dynamic programming [19], quantum mechanics [17], stochastic filtering and statistics [5]. The existence of Hermitian positive definite solutions of the matrix equation (1.1), has been investigated in some special cases. The case $s=t=1$ has been systematically investigated by several authors [2, 3, 10, 11]. The cases $s=1, t \in \mathbb{N}$ in [16], $s=1, t \in(0, \infty)$ in $[18,20], s=1, t \geq 1$ in $[9], s, t \in \mathbb{N}$ in $[6,7,8,21,22]$ and $s>0, t>0$ in [24] have been studied.

In this paper, we consider the Hermitian positive definite solutions of the matrix equation (1.1), where $s \geq 1$ and $t \geq 1$. Also, we find a matrix interval

Received June 18, 2016; Revised September 29, 2016; Accepted December 26, 2016.
2010 Mathematics Subject Classification. 65F30, 15A24, 15B48, 47H10.
Key words and phrases. iterative algoritheorem, nonlinear matrix equation, positive definite solution, fixed point theorem.

This research has been partially supported by the SBUK Center of Excellence in Linear Algebra and Optimization, Kerman, Iran.
which contains all the Hermitian positive definite solutions of the matrix equation (1.1). Indeed by using the Brouwer's fixed point theorem [1, Theorem 4.3] and the Banach's fixed point theorem [1, Theorem 1.1], we obtain sufficient conditions regarding to the existence and uniqueness of the Hermitian positive definite solutions of equation (1.1). Also, we obtain a necessary and sufficient condition for the existence of these solutions. Iterative methods for obtaining the extremal Hermitian positive definite solutions of the matrix equation (1.1) are presented. Moreover, we show that [8, Theorem 2.2], [9, Theorem 2.2], [14, Theorem 4], and [22, Theorem 2.2] are not formulated correctly, because some of the assumptions are vacuous, see Section 2. Finally, the theoretical results are illustrated by numerical examples.

The following notations are used throughout this paper. The notations $M_{n}$ denotes the algebra of $n \times n$ complex matrices. For $A \in M_{n}$, the matrices $A^{T}$ and $A^{*}$ denote the transpose and conjugate transpose of $A$, respectively. The symbol $I$ denotes the $n \times n$ identity matrix. Let $A$ be an $m \times n$ matrix and $B$ be an $p \times q$ matrix. Then the Kronecker product $A$ and $B$ denoted by $A \otimes B$ that is the $m p \times n q$ block matrix:

$$
A \otimes B=\left[\begin{array}{ccc}
a_{11} B & \cdots & a_{1 n} B \\
\cdots & \cdots & \cdots \\
a_{n 1} B & \cdots & a_{m n} B
\end{array}\right]
$$

If $m=p$ and $n=q$, then $A \circ B$ denotes Schur product $A$ and $B$ with elements given by $(A \circ B)_{i j}=(A)_{i j}(B)_{i j}$. For Hermitian matrix $A$, we write $A \geq 0$ ( $A>0$ ), if $A$ is a positive semi-definite (definite) matrix. For two Hermitian matrices $A$ and $B$, the notation $A \geq B(A>B)$ means that $A-B \geq 0$ $(A-B>0)$. We define a matrix interval by $[A, B]=\{X \mid A \leq X \leq B\}$ and $(A, B)=\{X \mid A<X<B\}$. Symbols $\|A\|$ and $\|A\|_{F}$ are used, respectively, for the spectral norm and Frobenius norm. Let $A$ be a nonsingular matrix. We indicate the condition number of $A$ with cond $(A)$. Let $\left\{\lambda_{i}(A)\right\}_{i=1}^{n}$ be the spectrum of a Hermitian matrix $A$. Then we assume that $\lambda_{n}(A) \leq \cdots \leq$ $\lambda_{2}(A) \leq \lambda_{1}(A)$. We use the notations $X_{S}$ and $X_{L}$ for the minimal and maximal Hermitian positive definite solutions of equation (1.1), respectively. By the HPD solution of Eq. (1.1), we mean the Hermitian positive definite solution of equation (1.1).

Let $A>0$ and $A=U^{*} D U$ be the spectral decomposition of the matrix $A$. We define $A^{r}:=U^{*} D^{r} U$, where $r \in \mathbb{R}$. In the following, we state inequalities between $A^{r}$ and $B^{r}$, where $0<A \leq B$ and $r \in \mathbb{R}$.

Lemma 1.1 ([23, Theorem 1.1](L%C3%B6wner-Heinz)). If $0 \leq A \leq B$ and $0 \leq r \leq 1$, then $0 \leq A^{r} \leq B^{r}$.

Lemma 1.2 ([12, Theorem 2.1]). Let $A$ and $B$ be positive operators on a Hilbert space $\mathcal{H}$ such that $M_{1} I \geq A \geq m_{1} I>0, M_{2} I \geq B \geq m_{2} I>0$ and

HERMITIAN POSITIVE DEFINITE SOLUTIONS OF THE MATRIX EQUATION 1669
$0<A \leq B$. Then, for all $r \geq 1$

$$
\begin{equation*}
A^{r} \leq\left(\frac{M_{1}}{m_{1}}\right)^{r-1} B^{r}, A^{r} \leq\left(\frac{M_{2}}{m_{2}}\right)^{r-1} B^{r} \tag{1.2}
\end{equation*}
$$

Using [4, Proposition V.1.6], we find the similar inequalities as Lemma 1.1 and Lemma 1.2 with opposite direction, for $r \in(-\infty, 0)$.

Now, we are going to find some bounds for $\left\|A^{r}-B^{r}\right\|_{F}$, where $r \in \mathbb{R}$. Let $J$ be an open interval in $\mathbb{R}$. We say that $f \in \mathcal{C}^{1}(J)$, if the real function $f$ is continuously differentiable on $J$.
Theorem 1.3. Let $f \in \mathcal{C}^{1}(J)$ and $[\alpha, \beta] \subset J$. If $A, B \in[\alpha I, \beta I]$, then

$$
\begin{equation*}
\|f(A)-f(B)\|_{F} \leq \max _{\alpha \leq c \leq \beta}\left|f^{\prime}(c)\right|\|A-B\|_{F} \tag{1.3}
\end{equation*}
$$

Proof. Suppose that $A, B \in[\alpha I, \beta I]$ and $L_{t}=t A+(1-t) B$ for all $0 \leq t \leq 1$. Then $L_{t} \in[\alpha I, \beta I]$. Using [4, Theorem X.4.5], we have

$$
\|f(A)-f(B)\|_{F} \leq \sup _{0 \leq t \leq 1}\left\|\mathcal{D} f\left(L_{t}\right)\right\|_{F}\|A-B\|_{F}
$$

where $\mathcal{D} f(A)$ is denoted the Frechet derivative of the function $f$ at $A$. Let $L_{t}=$ $U_{t} D_{t} U_{t}^{*}$ for all $0 \leq t \leq 1$, where $D_{t}$ and $U_{t}$ are diagonal and unitary matrices, respectively. Suppose that $f^{[1]}(A)$ is denoted the first divided difference of $f$ at $A[4$, p. 123]. Then, by using [4, Theorem V.3.3] and the mean value theorem,

$$
\begin{aligned}
\left\|\mathcal{D} f\left(L_{t}\right)\right\|_{F} & =\sup _{\|H\|_{F}=1}\left\|\mathcal{D} f\left(L_{t}\right)(H)\right\|_{F}=\sup _{\|H\|_{F}=1}\left\|f^{[1]}\left(D_{t}\right) \circ U_{t}^{*} H U_{t}\right\|_{F} \\
& \leq \sup _{\|H\|_{F}=1}\left(\max _{i, j}\left|\left(f^{[1]}\left(D_{t}\right)\right)_{i j}\right|\|H\|_{F}\right)=\max _{i, j}\left|\left(f^{[1]}\left(D_{t}\right)\right)_{i j}\right| \\
& \leq \max _{\lambda_{n}\left(L_{t}\right) \leq c \leq \lambda_{1}\left(L_{t}\right)}\left|f^{\prime}(c)\right| \leq \max _{\alpha \leq c \leq \beta}\left|f^{\prime}(c)\right|
\end{aligned}
$$

where $\circ$ is denoted the Schur product. Therefore,

$$
\|f(A)-f(B)\|_{F} \leq \max _{\alpha \leq c \leq \beta}\left|f^{\prime}(c)\right|\|A-B\|_{F}
$$

Corollary 1.4. Let $A, B \in[\alpha I, \beta I]$ and $\alpha>0$. Then

$$
\begin{align*}
& r \alpha^{r-1}\|A-B\|_{F} \leq\left\|A^{r}-B^{r}\right\|_{F} \leq r \beta^{r-1}\|A-B\|_{F} ; r \geq 1  \tag{1.4}\\
& r \beta^{r-1}\|A-B\|_{F} \leq\left\|A^{r}-B^{r}\right\|_{F} \leq r \alpha^{r-1}\|A-B\|_{F} ; 0<r \leq 1 \tag{1.5}
\end{align*}
$$

Proof. Let $r>0$ and $f(x)=x^{r}$ be defined on the interval $J:=(0, \infty)$. So $f \in \mathcal{C}^{1}(J)$ and is increasing on $J$. We know that $f$ is convex (concave) for $r \geq 1$ $(0<r \leq 1)$. Therefore $\max _{\alpha \leq c \leq \beta}\left|f^{\prime}(c)\right|=f^{\prime}(\beta)$ for $r \geq 1$ and $\max _{\alpha \leq x \leq \beta}\left|f^{\prime}(x)\right|=$ $f^{\prime}(\alpha)$ for $0<r \leq 1$. Using (1.3), the right hand side of (1.4) and (1.5) are derived. By replacing $A^{r} \rightarrow A, B^{r} \rightarrow B$, and $\frac{1}{r} \rightarrow r$, the left hand sides of the inequalities (1.4) and (1.5) are obtained by the right hand sides of the inequalities (1.5) and (1.4), respectively.

Corollary 1.5. Let $A, B \in[\alpha I, \beta I]$ and $\alpha>0$. Then for all $r \in(-\infty, 0)$,

$$
\begin{equation*}
-r \beta^{r-1}\|A-B\|_{F} \leq\left\|A^{r}-B^{r}\right\|_{F} \leq-r \alpha^{r-1}\|A-B\|_{F} \tag{1.6}
\end{equation*}
$$

Proof. Let $r \in(-\infty, 0)$ and $f(x)=x^{r}$ be defined on the interval $J:=(\alpha, \infty)$ with $\alpha>0$. We have, $f \in \mathcal{C}^{1}(J)$ and $f$ is convex and decreasing on $J$. Therefore, $\max _{\alpha \leq c \leq \beta}\left|f^{\prime}(c)\right|=-f^{\prime}(\alpha)=-r \alpha^{r-1}$. Hence, by using (1.3), we have

$$
\left\|A^{r}-B^{r}\right\|_{F}=\|f(A)-f(B)\|_{F} \leq-r \alpha^{r-1}\|A-B\|_{F}
$$

By replacing $A^{r} \rightarrow A, B^{r} \rightarrow B$, and $\frac{1}{r} \rightarrow r$, the left hand side of the inequality (1.6) is obtained by the right hand side of (1.6) and [4, Proposition V.1.6].

## 2. Necessary conditions and sufficient conditions

Let $X$ be an HPD solution of Eq. (1.1) and $s, t \in[1, \infty)$. It is readily seen that

$$
\begin{equation*}
X \in\left[\left(A Q^{-1} A^{*}\right)^{\frac{1}{t}}, Q^{\frac{1}{s}}\right] \tag{2.1}
\end{equation*}
$$

This interval was obtained in [22, Theorem 2.1] for $s, t \in N$. Now, we are going to obtain a better interval for HPD solutions of Eq. (1.1).
Theorem 2.1. Let $F(P)=\left(A\left(Q-\operatorname{cond}(P)^{1-s} P^{s}\right)^{-1} A^{*}\right)^{\frac{1}{t}}$ and $X$ be an HPD solution of Eq. (1.1). Then

$$
\left(A Q^{-1} A^{*}\right)^{\frac{1}{t}}<F\left(\left(A Q^{-1} A^{*}\right)^{\frac{1}{t}}\right) \leq X
$$

Proof. Let $X$ be an HPD solution of Eq. (1.1). First, we will show that for all matrix $P$ such that the conditions (i) $0<P \leq X$ and (ii) $Q<\operatorname{cond}(P)^{1-s} P^{s}+$ $A^{*} P^{-t} A$ hold, then $P<F(P) \leq X$.

Let $0<P \leq X$. Since $\lambda_{n}(P) I \leq P \leq \lambda_{1}(P) I$, by using (1.2), we obtain that

$$
\begin{aligned}
P^{s} & \leq\left(\frac{\lambda_{1}(P)}{\lambda_{n}(P)}\right)^{s-1} X^{s}=\left(\lambda_{1}(P) \lambda_{1}\left(P^{-1}\right)\right)^{s-1} X^{s} \\
& =\left(\|P\|\left\|P^{-1}\right\|\right)^{s-1} X^{s}=\operatorname{cond}(P)^{s-1} X^{s} .
\end{aligned}
$$

Since $X$ is an HPD solution of Eq. (1.1),

$$
F(P)=\left(A\left(Q-\operatorname{cond}(P)^{1-s} P^{s}\right)^{-1} A^{*}\right)^{\frac{1}{t}} \leq\left(A\left(Q-X^{s}\right)^{-1} A^{*}\right)^{\frac{1}{t}}=X
$$

Thus, $F(P) \leq X$.
Now, let $\operatorname{cond}(P)^{1-s} P^{s}+A^{*} P^{-t} A>Q$. Therefore,

$$
F(P)=\left(A\left(Q-\operatorname{cond}(P)^{1-s} P^{s}\right)^{-1} A^{*}\right)^{\frac{1}{t}}>\left(P^{t}\right)^{\frac{1}{t}}=P
$$

and so $P<F(P) \leq X$.

HERMITIAN POSITIVE DEFINITE SOLUTIONS OF THE MATRIX EQUATION 1671
Choose $P=\left(A Q^{-1} A^{*}\right)^{\frac{1}{t}}$. By using (2.1), we obtain that $0<P \leq X$. Also, we have

$$
\operatorname{cond}(P)^{1-s} P^{s}+A^{*} P^{-t} A=\operatorname{cond}(P)^{1-s} P^{s}+Q>Q
$$

Therefore, $P=\left(A Q^{-1} A^{*}\right)^{\frac{1}{t}}$ holds in conditions (i) and (ii). Hence

$$
\left(A Q^{-1} A^{*}\right)^{\frac{1}{t}}<F\left(\left(A Q^{-1} A^{*}\right)^{\frac{1}{t}}\right) \leq X
$$

The matrix $X$ is an HPD solution of Eq. (1.1) if and only if $Y:=X^{-1}$ is an HPD solution of Eq.

$$
\begin{equation*}
Y^{t}+A^{-*} Y^{-s} A^{-1}=A^{-*} Q A^{-1} \tag{2.2}
\end{equation*}
$$

Remark 2.2. We see that Eq. (2.2) is the same as Eq. (1.1) by replacing $A^{-*} Q A^{-1} \rightarrow Q, A^{-1} \rightarrow A, t \rightarrow s$, and $s \rightarrow t$.

We are using auxiliary Eq. (2.2) to find an upper bound for HPD solutions of Eq. (1.1) which is sharper than (2.1).
Theorem 2.3. Let $X$ be an HPD solution of Eq. (1.1). Then

$$
X \leq G\left(Q^{\frac{1}{s}}\right)<Q^{\frac{1}{s}}
$$

where $G(P)=\left(Q-\operatorname{cond}(P)^{1-t} A^{*} P^{-t} A\right)^{\frac{1}{s}}$.
Proof. Let $X$ be an HPD solution of Eq. (1.1). Therefore $Y:=X^{-1}$ is an HPD solution of Eq. (2.2). Using Remark 2.2 and Theorem 2.1, we have $Q^{\frac{-1}{s}}<$ $F\left(Q^{\frac{-1}{s}}\right) \leq Y$, where

$$
\begin{aligned}
F(P) & =\left(A^{-1}\left(A^{-*} Q A^{-1}-\operatorname{cond}(P)^{1-t} P^{t}\right)^{-1} A^{-*}\right)^{\frac{1}{s}} \\
& =\left(Q-\operatorname{cond}(P)^{1-t} A^{*} P^{t} A\right)^{\frac{-1}{s}}
\end{aligned}
$$

By choosing $G(P)=F^{-1}\left(P^{-1}\right)$, the proof is completed.
Corollary 2.4. Let $F$ and $G$ be the same as in Theorem 2.1 and Theorem 2.3, respectively. If $X$ is an HPD solution of Eq. (1.1), then

$$
X \in\left[F\left(\left(A Q^{-1} A^{*}\right)^{\frac{1}{t}}\right), G\left(Q^{\frac{1}{s}}\right)\right] \subset\left[\left(A Q^{-1} A^{*}\right)^{\frac{1}{t}}, Q^{\frac{1}{s}}\right] .
$$

By using Corollary 2.4, we will present an iterative method for obtaining the minimal (maximal) HPD solution of Eq. (1.1), when $t \geq s \geq 1(s \geq t \geq 1)$, in Section 3.

In the following, we study sufficient conditions for the existence of HPD solutions of Eq. (1.1). Some sufficient conditions, for various values of $s, t \in[1, \infty)$, was presented in [14, Theorem 4], [8, Theorem 2.2], [9, Theorem 2.2], and [22, Theorem 2.2]. But some of the assumptions of these theorems are vacuous, because, by choosing $X=\left(A Q^{-1} A^{*}\right)^{\frac{1}{t}}$, we obtain that $A^{*} X^{-t} A=Q>$
$Q-\left(A Q^{-1} A^{*}\right)^{\frac{s}{t}}$. Therefore, we can not assume $A^{*} X^{-t} A \leq Q-\left(A Q^{-1} A^{*}\right)^{\frac{s}{t}}$ for all $X \in\left[\left(A Q^{-1} A^{*}\right)^{\frac{1}{t}}, P\right]$. Now, in the following, we are going to improve these results.

Theorem 2.5. Let $s, t \in[1, \infty)$ and there exist $k>1$ such that

$$
\begin{equation*}
\lambda_{1}\left(Q^{-\frac{1}{2}}\left(A Q^{-1} A^{*}\right)^{\frac{s}{t}} Q^{-\frac{1}{2}}\right) \leq\left(1-k^{-1}\right) k^{\frac{-s}{t}} \tag{2.3}
\end{equation*}
$$

Then, $\left(k A Q^{-1} A^{*}\right)^{\frac{1}{t}} \leq Q^{\frac{1}{s}}$. Moreover, if $X^{t} \geq k\left(A Q^{-1} A^{*}\right)$ for all $X \in \Omega:=$ $\left[\left(k A Q^{-1} A^{*}\right)^{\frac{1}{t}}, Q^{\frac{1}{s}}\right]$, then Eq. (1.1) has an HPD solution in $\Omega$.

Proof. Using (2.3), we obtain that

$$
Q^{-\frac{1}{2}}\left(A Q^{-1} A^{*}\right)^{\frac{s}{t}} Q^{-\frac{1}{2}} \leq \lambda_{1}\left(Q^{-\frac{1}{2}}\left(A Q^{-1} A^{*}\right)^{\frac{s}{t}} Q^{-\frac{1}{2}}\right) I \leq\left(1-k^{-1}\right) k^{\frac{-s}{t}} I
$$

Since $k>1$, we have

$$
\begin{equation*}
\left(k A Q^{-1} A^{*}\right)^{\frac{s}{t}} \leq\left(1-k^{-1}\right) Q \leq Q \tag{2.4}
\end{equation*}
$$

So $\left(k A Q^{-1} A^{*}\right)^{\frac{1}{t}} \leq Q^{\frac{1}{s}}$.
Now, let $\Omega=\left[\left(k A Q^{-1} A^{*}\right)^{\frac{1}{t}}, Q^{\frac{1}{s}}\right]$ and $X^{t} \geq k\left(A Q^{-1} A^{*}\right)$ for all $X \in \Omega$. It is readily seen that $\Omega$ is a closed, convex and bounded set. We define $G(X)=$ $\left(Q-A^{*} X^{-t} A\right)^{\frac{1}{s}}$ on $\Omega$. Suppose that $X \in \Omega$. Using (2.4), we have

$$
\begin{align*}
G(X)^{s} & =Q-A^{*} X^{-t} A \geq Q-A^{*}\left(k^{-1} A^{-*} Q A^{-1}\right) A \\
& =\left(1-k^{-1}\right) Q \geq\left(k A Q^{-1} A^{*}\right)^{\frac{s}{t}} . \tag{2.5}
\end{align*}
$$

Therefore, $G(X) \geq\left(k A Q^{-1} A^{*}\right)^{\frac{1}{t}}$.
On the other hand $G(X)=\left(Q-A^{*} X^{-t} A\right)^{\frac{1}{s}} \leq Q^{\frac{1}{s}}$. So $G(\Omega) \subseteq \Omega$ and since $G$ is continuous on $(0, \infty)$, by using the Brouwer's fixed point theorem and [1, Remark 4.1], the map $G$ on $\Omega$ has a fixed point. So, the matrix Eq. (1.1) has an HPD solution in $\Omega$.

Lemma 2.6. If $A \in M_{m}, B \in M_{m \times n}$, and $C \in M_{n}$, then

$$
\begin{equation*}
\|A B C\|_{F} \leq\|A\|\|C\|\|B\|_{F} . \tag{2.6}
\end{equation*}
$$

Proof. Let $\operatorname{vec}(A):=\left[a_{1}^{T}, a_{2}^{T}, \ldots, a_{n}^{T}\right]^{T}$, where $a_{i}(1 \leq i \leq n)$ are the columns of the matrix $A$. By [15, Lemma 4.3.1], vec $(A B C)=\left(C^{T} \otimes A\right) \operatorname{vec}(B)$. So

$$
\begin{aligned}
\|A B C\|_{F} & =\|\operatorname{vec}(A B C)\|=\left\|\left(C^{T} \otimes A\right) \operatorname{vec}(B)\right\| \\
& \leq\left\|C^{T} \otimes A\right\|\|\operatorname{vec}(B)\| \leq\|A\|\|C\|\|B\|_{F} .
\end{aligned}
$$

In the following, we study uniqueness of the solutions of Eq. (1.1) in $\Omega$.

Corollary 2.7. Let the assumptions of Theorem 2.5 hold and

$$
a=\frac{t}{s} \frac{\lambda_{1}\left(A^{*} A\right)}{\left(\left(1-k^{-1}\right) \lambda_{n}(Q)\right)^{1-\frac{1}{s}}\left(k \lambda_{n}\left(A Q^{-1} A^{*}\right)\right)^{1+\frac{1}{t}}}<1 .
$$

Then, the matrix $X_{L}$ is the unique HPD solution of $E q$. (1.1) in $\Omega$ and the sequence

$$
X_{k+1}=\left(Q-A^{*} X_{k}^{-t} A\right)^{\frac{1}{s}}, \quad k \geq 1
$$

for any $X_{1} \in \Omega$, is convergent to the $X_{L}$. Also, for all $k \geq 1$,

$$
\begin{aligned}
& \left\|X_{k+1}-X_{L}\right\| \leq \frac{a^{k}}{1-a}\left\|X_{2}-X_{1}\right\|, \\
& \left\|X_{k+1}-X_{L}\right\| \leq a^{k}\left\|X_{1}-X_{L}\right\|
\end{aligned}
$$

Proof. Let $G(X)=\left(Q-A^{*} X^{-t} A\right)^{\frac{1}{s}}$ on $\Omega$. Suppose that $G(X)^{s}, G(Y)^{s} \geq \beta I$ and $X, Y \geq \alpha I$. Using (1.5), (2.6) and (1.6), respectively, we have

$$
\begin{align*}
\|G(X)-G(Y)\|_{F} & =\left\|\left(G(X)^{s}\right)^{\frac{1}{s}}-\left(G(Y)^{s}\right)^{\frac{1}{s}}\right\|_{F} \\
& \leq \frac{1}{s} \beta^{\frac{1}{s}-1}\left\|G(X)^{s}-G(Y)^{s}\right\|_{F} \\
& =\frac{1}{s} \beta^{\frac{1}{s}-1}\left\|A^{*}\left(X^{-t}-Y^{-t}\right) A\right\|_{F} \\
& \leq \frac{1}{s} \beta^{\frac{1}{s}-1}\|A\|^{2}\left\|X^{-t}-Y^{-t}\right\|_{F} \\
& \leq \frac{1}{s} \beta^{\frac{1}{s}-1} \lambda_{1}\left(A^{*} A\right)\left(t \alpha^{-t-1}\|X-Y\|_{F}\right) . \tag{2.7}
\end{align*}
$$

Since $X, Y \in \Omega$, we have

$$
X, Y \geq\left(k A Q^{-1} A^{*}\right)^{\frac{1}{t}} \geq\left(k \lambda_{n}\left(A Q^{-1} A^{*}\right)\right)^{\frac{1}{t}} I
$$

and by using (2.5), we obtain that

$$
G(X)^{s}, G(Y)^{s} \geq\left(1-k^{-1}\right) Q \geq\left(1-k^{-1}\right) \lambda_{n}(Q) I
$$

Let $\alpha:=\left(k \lambda_{n}\left(A Q^{-1} A^{*}\right)\right)^{\frac{1}{t}}$ and $\beta:=\left(1-k^{-1}\right) \lambda_{n}(Q)$. By replacing $\alpha, \beta$ in (2.7), we have $\|G(X)-G(Y)\|_{F} \leq a\|X-Y\|_{F}$, where $a<1$. Hence, $G$ is a contraction map on $\Omega$. Since $G(\Omega) \subseteq \Omega$, by Banach's fixed point theorem, $G$ has the unique fixed point $\bar{X}$ in $\Omega$ and so Eq. (1.1) has the unique HPD solution $\bar{X} \in \Omega$. Also, for any $X_{1} \in \Omega$, sequence

$$
X_{k+1}=G\left(X_{k}\right)=\left(Q-A^{*} X_{k}^{-t} A\right)^{\frac{1}{s}} ; k \geq 1,
$$

is convergent to the $\bar{X}$ and for all $k \geq 1$,

$$
\begin{aligned}
& \left\|X_{k+1}-\bar{X}\right\| \leq \frac{a^{k}}{1-a}\left\|X_{2}-X_{1}\right\|, \\
& \left\|X_{k+1}-\bar{X}\right\| \leq a^{k}\left\|X_{1}-\bar{X}\right\|
\end{aligned}
$$

Now, let $X$ be an HPD solution of Eq. (1.1) and $\bar{X} \leq X$. By using (2.1), we obtain that $\bar{X} \leq X \leq Q^{\frac{1}{s}}$ and so $X \in \Omega$. Since $\bar{X}$ is the unique HPD solution of Eq. (1.1) in $\Omega$, we have $\bar{X}=X$ and hence $\bar{X}$ is the maximal HPD solution of Eq. (1.1).

Using Remark 2.2, Theorem 2.5, and choosing $l=k^{-1}$, we obtain the following:

Corollary 2.8. Let $s, t \in[1, \infty)$ and there exist $0<l<1$ such that

$$
\begin{equation*}
\lambda_{1}\left(Q^{-\frac{t}{2 s}} A Q^{-1} A^{*} Q^{-\frac{t}{2 s}}\right) \leq(1-l) l^{\frac{t}{s}} \tag{2.8}
\end{equation*}
$$

Then $\left(A Q^{-1} A^{*}\right)^{\frac{1}{t}} \leq(l Q)^{\frac{1}{s}}$. Moreover, if for all $X \in \Lambda=\left[\left(A Q^{-1} A^{*}\right)^{\frac{1}{t}},(l Q)^{\frac{1}{s}}\right]$ we have $X^{s} \leq l Q$, then Eq. (1.1) has an HPD solution in $\Lambda$.

Corollary 2.9. Let the assumptions of Corollary 2.8 hold and

$$
b=\frac{s}{t} \frac{\left((1-l)^{-1} \lambda_{1}\left(A Q^{-1} A^{*}\right)\right)^{1-\frac{1}{t}}\left(l \lambda_{1}(Q)\right)^{1+\frac{1}{s}}}{\lambda_{n}\left(A^{*} A\right)}<1 .
$$

Then, the matrix $X_{S}$ is the unique HPD solution of Eq. (1.1) in $\Lambda$. Also, the sequence

$$
X_{k+1}=\left(A\left(Q-X_{k}^{s}\right)^{-1} A^{*}\right)^{\frac{1}{t}} ; k \geq 1
$$

for any $X_{1} \in \Lambda$, is convergent to the $X_{S}$ and for all $k \geq 1$, we have

$$
\begin{aligned}
& \left\|X_{k+1}-X_{S}\right\| \leq \frac{b^{k}}{1-b}\left\|X_{2}-X_{1}\right\| \\
& \left\|X_{k+1}-X_{S}\right\| \leq b^{k}\left\|X_{1}-X_{S}\right\|
\end{aligned}
$$

Proof. Let $F(X)=\left(A\left(Q-X^{s}\right)^{-1} A^{*}\right)^{\frac{1}{t}}$ on $\Lambda$. Suppose that $F(X), F(Y) \leq$ $\beta I$ and $X, Y \leq \alpha I$. Therefore, by using (2.6) and (1.4), we have

$$
\begin{aligned}
\|F(X)-F(Y)\|_{F} & =\left\|F(X)\left(F(X)^{-1}-F(Y)^{-1}\right) F(Y)\right\|_{F} \\
& \leq\|F(X)\|\|F(Y)\|\left\|F(X)^{-1}-F(Y)^{-1}\right\|_{F} \\
& \leq \beta^{2}\left\|F(X)^{-1}-F(Y)^{-1}\right\|_{F} \\
& \leq \frac{1}{t} \beta^{1+t}\left\|F(X)^{-t}-F(Y)^{-t}\right\|_{F} \\
& =\frac{1}{t} \beta^{1+t}\left\|A^{-*}\left(X^{s}-Y^{s}\right) A^{-1}\right\|_{F} \\
& \leq \frac{1}{t} \beta^{1+t}\left\|A^{-1}\right\|^{2}\left\|X^{s}-Y^{s}\right\|_{F} \\
& \leq \frac{s}{t} \beta^{1+t} \alpha^{s-1} \lambda_{1}\left(A^{-*} A^{-1}\right)\|X-Y\|_{F}
\end{aligned}
$$

HERMITIAN POSITIVE DEFINITE SOLUTIONS OF THE MATRIX EQUATION 1675

$$
\begin{equation*}
=\frac{s}{t} \frac{\beta^{1+t} \alpha^{s-1}}{\lambda_{n}\left(A^{*} A\right)}\|X-Y\|_{F} . \tag{2.9}
\end{equation*}
$$

Since $X, Y \in \Lambda$, we have

$$
X, Y \leq(l Q)^{\frac{1}{s}} \leq\left(l \lambda_{1}(Q)\right)^{\frac{1}{s}} I
$$

and the same as (2.6), we obtain that

$$
F(X), F(Y) \leq\left((1-l)^{-1}\left(A Q^{-1} A^{*}\right)\right)^{\frac{1}{t}} \leq\left((1-l)^{-1} \lambda_{1}\left(A Q^{-1} A^{*}\right)\right)^{\frac{1}{t}} I
$$

Let $\alpha:=\left(l \lambda_{1}(Q)\right)^{\frac{1}{s}}$ and $\beta:=\left((1-l)^{-1} \lambda_{1}\left(A Q^{-1} A^{*}\right)\right)^{\frac{1}{t}}$. By replacing $\alpha, \beta$ in (2.9), we have $\|F(X)-F(Y)\|_{F} \leq b\|X-Y\|_{F}$, where $b<1$. The same as the proof of Corollary 2.7, proof is completed.

Let $\gamma \in \mathbb{R}, \theta>0$. Consider $f_{\theta, \gamma}(x)=x^{s+t}-\theta x^{t}+\gamma$ on $(0, \infty)$. Then $f_{\theta, \gamma}$ on $\left[\left(\frac{t}{s+t} \theta\right)^{\frac{1}{s}}, \infty\right)$ is increasing and $\min f_{\theta, \gamma}(x)=\gamma-\frac{s}{s+t}\left(\frac{t}{s+t}\right)^{\frac{t}{s}} \theta^{1+\frac{t}{s}}$. If $\min f_{\theta, \gamma}(x)=\gamma-\frac{s}{s+t}\left(\frac{t}{s+t}\right)^{\frac{t}{s}} \theta^{1+\frac{t}{s}} \leq 0$, then equation $f_{\theta, \gamma}(x)=0$ has a unique solution $\alpha$ in $\left[\left(\frac{t}{s+t} \theta\right)^{\frac{1}{s}}, \infty\right)$. Consider the following functions on $(0, \infty)$.

$$
\begin{gathered}
f(x)=x^{s+t}-\lambda_{n}(Q) x^{t}+\lambda_{1}\left(A^{*} A\right) \\
g(x)=x^{s+t}-\lambda_{1}(Q) x^{t}+\lambda_{n}\left(A^{*} A\right)
\end{gathered}
$$

Let $\lambda_{1}\left(A^{*} A\right) \leq \frac{s}{s+t}\left(\frac{t}{s+t}\right)^{\frac{t}{s}} \lambda_{n}^{1+\frac{t}{s}}(Q)$. Therefore

$$
\lambda_{n}\left(A^{*} A\right) \leq \frac{s}{s+t}\left(\frac{t}{s+t}\right)^{\frac{t}{s}} \lambda_{1}^{1+\frac{t}{s}}(Q)
$$

So we have $\min f(x) \leq 0$ and $\min g(x) \leq 0$. Therefore equations $f(x)=0$ and $g(x)=0$ have a unique solution $\alpha$ and $\beta$ in $\left[\left(\frac{t}{s+t} \theta\right)^{\frac{1}{s}}, \infty\right)$, respectively. Since $f(x) \geq g(x)$, we have $\left(\frac{t}{s+t} \lambda_{n}(Q)\right)^{\frac{1}{s}} \leq \alpha \leq \beta$. Consider the matrix interval $\Omega:=[\alpha I, \beta I]$.
Theorem 2.10. If one of the following inequalities hold, then Eq. (1.1) has an HPD solution.
(1) $\lambda_{1}\left(A^{*} A\right) \leq \frac{s}{s+t}\left(\frac{t}{s+t}\right)^{\frac{t}{s}} \lambda_{n}^{1+\frac{t}{s}}(Q)$.
(2) $\lambda_{1}\left(A Q^{-1} A^{*}\right) \leq\left(\frac{t}{s+t}\right)^{\frac{t}{s+t}}\left(\frac{s}{s+t}\right)^{\frac{s}{s+t}} \lambda_{n}^{\frac{t}{s+t}}\left(A A^{*}\right)$.

Proof. Let inequality (1) be holds and $G(X)=\left(Q-A^{*} X^{-t} A\right)^{\frac{1}{s}}$ on $\Omega=$ $[\alpha I, \beta I]$. If $X \in \Omega$, then

$$
\begin{aligned}
\lambda_{n}\left(G^{s}(X)\right) & =\lambda_{n}\left(Q-A^{*} X^{-t} A\right) \geq \lambda_{n}\left(Q-A^{*} \alpha^{-t} A\right) \\
& \geq \lambda_{n}(Q)-\lambda_{1}\left(A^{*} A\right) \alpha^{-t}=\alpha^{s} \\
\lambda_{1}\left(G^{s}(X)\right) & =\lambda_{1}\left(Q-A^{*} X^{-t} A\right) \leq \lambda_{1}\left(Q-A^{*} \beta^{-t} A\right) \\
& \leq \lambda_{1}(Q)-\lambda_{n}\left(A^{*} A\right) \beta^{-t}=\beta^{s} .
\end{aligned}
$$

Hence $G(\Omega) \subseteq \Omega$. By using Brouwer's fixed point theorem, the map $G$ on $\Omega$ has a fixed point and so Eq. (1.1) has an HPD solution.

For the second one, we know that Eq. (1.1) has an HPD solution if and only if Eq. (2.2) has an HPD solution. Let inequality (2) be holds. Therefore

$$
\begin{aligned}
\lambda_{1}\left(A^{-*} A^{-1}\right) & =\frac{1}{\lambda_{n}\left(A A^{*}\right)} \leq\left(\left(\frac{t}{s+t}\right)^{\frac{t}{s+t}}\left(\frac{s}{s+t}\right)^{\frac{s}{s+t}} \frac{1}{\lambda_{1}\left(A Q^{-1} A^{*}\right)}\right)^{\frac{s+t}{t}} \\
& =\frac{t}{s+t}\left(\frac{s}{s+t}\right)^{\frac{s}{t}} \lambda_{n}^{1+\frac{s}{t}}\left(A^{-*} Q A^{-1}\right)
\end{aligned}
$$

Now, by using Remark 2.2 and inequality (1), Eq. (2.2) has an HPD solution $Y$. Therefore, the matrix $X:=Y^{-1}$ is an HPD solution of Eq. (1.1).
Corollary 2.11. If $\lambda_{1}\left(A^{*} A\right)<\frac{s}{s+t}\left(\frac{t}{s+t}\right)^{\frac{t}{s}} \lambda_{n}^{1+\frac{t}{s}}(Q)$, then Eq. (1.1) has the unique HPD solution in $\Omega$.

Proof. Let $G$ be the same as in the proof of Theorem 2.10. By the proof of this Theorem, we see that $G(\Omega) \subseteq \Omega$. Let $X, Y \in \Omega$. Therefore $G^{s}(X), G^{s}(Y) \geq$ $\alpha^{s} I$ and $X, Y \geq \alpha I$. Using (2.7), we have

$$
\|G(X)-G(Y)\|_{F} \leq \frac{t}{s} \frac{\lambda_{1}\left(A^{*} A\right)}{\alpha^{s+t}}\|X-Y\|_{F} .
$$

Since $\alpha \geq\left(\frac{t}{s+t} \lambda_{n}(Q)\right)^{\frac{1}{s}}$, we have

$$
\|G(X)-G(Y)\|_{F} \leq \frac{\lambda_{1}\left(A^{*} A\right)}{\frac{s}{s+t}\left(\frac{t}{s+t}\right)^{\frac{t}{s}} \lambda_{n}^{1+\frac{t}{s}}(Q)}\|X-Y\|_{F}
$$

Hence, $G$ is contraction on the set $\Omega$ and by Banach's fixed point theorem, $G$ has the unique fixed point on $\Omega$. So Eq. (1.1) has the unique HPD solution in $\Omega$.

Theorem 2.12. If Eq. (1.1) has an HPD solution, then for $s, t \in[1, \infty)$ we have
(1) $\lambda_{n}\left(A^{*} A\right) \leq \frac{s}{s+t}\left(\frac{t}{s+t}\right)^{\frac{t}{s}} \lambda_{1}^{1+\frac{t}{s}}(Q)$,
(2) $\lambda_{n}\left(A Q^{-1} A^{*}\right) \leq\left(\frac{t}{s+t}\right)^{\frac{t}{s+t}}\left(\frac{s}{s+t}\right)^{\frac{s}{s+t}} \lambda_{1}^{\frac{t}{s+t}}\left(A^{*} A\right)$.

Proof. The first inequality is obtained by the same method as in [8, Theorem 3.3]. For the second one, let $X$ be an HPD solution of Eq. (1.1). Then $Y:=X^{-1}$ is an HPD solution of Eq. (2.2). Now, by using Remark 2.2 and inequality (1), we have

$$
\lambda_{n}\left(A^{-*} A^{-1}\right) \leq \frac{t}{s+t}\left(\frac{s}{s+t}\right)^{\frac{s}{t}} \lambda_{1}^{1+\frac{s}{t}}\left(A^{-*} Q A^{-1}\right)
$$

Therefore,

$$
\lambda_{n}\left(A Q^{-1} A^{*}\right)=\frac{1}{\lambda_{1}\left(A^{-*} Q A^{-1}\right)} \leq\left(\frac{t}{s+t}\left(\frac{s}{s+t}\right)^{\frac{s}{t}} \frac{1}{\lambda_{n}\left(A^{-*} A^{-1}\right)}\right)^{\frac{t}{s+t}}
$$

$$
=\left(\frac{t}{s+t}\right)^{\frac{t}{s+t}}\left(\frac{s}{s+t}\right)^{\frac{s}{s+t}} \lambda_{1}^{\frac{t}{s+t}}\left(A^{*} A\right)
$$

## 3. Iterative methods

In this section, we will present iterative methods for obtaining the extremal HPD solution of Eq. (1.1). Let $F$ be an operator on $\Lambda$ and $A, B \in \Lambda$. We say that $F$ is an operator monotone on $\Lambda$, if $F(A) \geq F(B)$, whenever $A \geq B$.

Theorem 3.1. Let $t=1, s \geq 1$ and Eq. (1.1) has an HPD solution. Then the sequence

$$
\begin{equation*}
P_{1}=Q^{\frac{1}{s}}, \quad P_{k+1}=\left(Q-A^{*} P_{k}^{-1} A\right)^{\frac{1}{s}} ; k \geq 1, \tag{3.1}
\end{equation*}
$$

is monotonically decreasing and converges to the matrix $X_{L}$.
Proof. Let $X$ be an HPD solution of Eq. (1.1). By considering $t=1$ in Theorem 2.3, we have $G(P)=\left(Q-A^{*} P^{-1} A\right)^{\frac{1}{s}}$. In this case, we see that $G$ is an operator monotone on $(0, \infty)$. By induction, we will show that $X \leq P_{k+1}<P_{k}$, for $k \in \mathbb{N}$. Using Theorem 2.3, we have $X \leq P_{2}=G\left(P_{1}\right)<P_{1}$. Now, let $X \leq P_{k}<P_{k-1}$. Since $G$ is an operator monotone map, we obtain that

$$
X=G(X) \leq P_{k+1}=G\left(P_{k}\right)<P_{k}=G\left(P_{k-1}\right)
$$

Thus, $X \leq P_{k+1}<P_{k}$ for $k \in \mathbb{N}$. Therefore, the sequence $\left\{P_{k}\right\}$ is decreasing and bounded sequence and hence it is convergent. Let $\lim P_{k}=P$. Since $G$ is continuous on $(0, \infty)$, we have $G(P)=P$ and $P \geq X$. Therefore, $P$ is a solution of Eq. (1.1) and $P \geq X$. Hence $P=X_{L}$.

Theorem 3.2. Let $s \geq t \geq 1$ and Eq. (1.1) has an HPD solution. Then the sequence

$$
\begin{equation*}
P_{1}=Q^{\frac{1}{s}}, \quad P_{k+1}=\left(Q-A^{*} P_{k}^{-t} A\right)^{\frac{1}{s}} ; k \geq 1 \tag{3.2}
\end{equation*}
$$

is monotonically decreasing and converges to the matrix $X_{L}$. Moreover, for all $k \in \mathbb{N}$,

$$
\begin{equation*}
\left\|P_{k+1}-X_{L}\right\|_{F} \leq \frac{t}{s} \frac{\lambda_{1}\left(A^{*} A\right)}{\lambda_{n}^{s+t}\left(X_{L}\right)}\left\|P_{k}-X_{L}\right\|_{F} \tag{3.3}
\end{equation*}
$$

Proof. Let $X$ be an HPD solution of Eq. (1.1). Therefore $Y=X^{t}$ is an HPD solution of equation

$$
\begin{equation*}
Y^{\frac{s}{t}}+A^{*} Y^{-1} A=Q \tag{3.4}
\end{equation*}
$$

Since $\frac{s}{t} \geq 1$, by Theorem 3.1, the sequence $\left\{P_{k}^{t}\right\}$ is monotonically decreasing and converges to the matrix $Y_{L}$, where $Y_{L}$ is the maximal HPD solution of Eq. (3.4). Let $X$ be an arbitrary HPD solution of Eq. (1.1). So $Y=X^{t}$ is an HPD solution of Eq. (3.4). Since $Y_{L}$ is the maximal HPD solution of Eq. (3.4), we have $Y_{L} \geq Y=X^{t}$. So $Y_{L}^{\frac{1}{t}} \geq X$. Therefore $X_{L}=Y_{L}^{\frac{1}{t}}$ and the sequence (3.2) is monotonically decreasing and converges to the matrix $X_{L}$.

Let $G(P)=\left(Q-A^{*} P^{-t} A\right)^{\frac{1}{s}}$ on $(0, \infty)$. Therefore $P_{k+1}=G\left(P_{k}\right)$ and $X_{L}=$ $G\left(X_{L}\right)$. By using (2.7), for all $k \in \mathbb{N}$, we obtain that

$$
\begin{align*}
\left\|P_{k+1}-X_{L}\right\|_{F} & =\left\|G\left(P_{k}\right)-G\left(X_{L}\right)\right\|_{F} \\
& \leq \frac{t}{s} \beta^{\frac{1}{s}-1} \alpha^{-t-1} \lambda_{1}\left(A^{*} A\right)\left\|P_{k}-X_{L}\right\|_{F}, \tag{3.5}
\end{align*}
$$

where $P_{k}, X_{L} \geq \alpha I$ and $G\left(P_{k}\right)^{s}, G\left(X_{L}\right)^{s} \geq \beta I$. But $G\left(P_{k}\right)^{s}, G\left(X_{L}\right)^{s} \geq$ $\lambda_{n}^{s}\left(X_{L}\right) I$ and $P_{k} \geq X_{L} \geq \lambda_{n}\left(X_{L}\right) I$ for all $k \in \mathbb{N}$. Therefore, by replacing $\alpha=\lambda_{n}\left(X_{L}\right)$ and $\beta=\lambda_{n}^{s}\left(X_{L}\right)$ in (3.5),

$$
\left\|P_{k+1}-X_{L}\right\|_{F} \leq \frac{t}{s} \frac{\lambda_{1}\left(A^{*} A\right)}{\lambda_{n}^{s+t}\left(X_{L}\right)}\left\|P_{k}-X_{L}\right\|_{F}
$$

Theorem 3.3. Let $t \geq s \geq 1$ and Eq. (1.1) has an HPD solution. Then the sequence

$$
\begin{equation*}
P_{1}=\left(A Q^{-1} A^{*}\right)^{\frac{1}{t}}, \quad P_{k+1}=\left(A\left(Q-P_{k}^{s}\right)^{-1} A^{*}\right)^{\frac{1}{t}} ; k \geq 1 \tag{3.6}
\end{equation*}
$$

is monotonically increasing and converges to the matrix $X_{S}$. Moreover, for all $k \in \mathbb{N}$, we have

$$
\left\|P_{k+1}-X_{S}\right\|_{F} \leq \frac{s}{t} \frac{\lambda_{1}^{s+t}\left(X_{S}\right)}{\lambda_{n}\left(A^{*} A\right)}\left\|P_{k}-X_{S}\right\|_{F} .
$$

Proof. Let $X$ be an HPD solution of Eq. (1.1). So, the matrix $Y:=X^{-1}$ is an HPD solution of Eq. (2.2). Using Remark 2.2 and Theorem 3.2, the sequence $\left\{P_{k}^{-1}\right\}$ is monotonically decreasing and converges to the matrix $Y_{L}$, where $Y_{L}$ is the maximal HPD solution of Eq. (2.2). Therefore, the sequence $\left\{P_{k}\right\}$ is monotonically increasing and converges to the matrix $X_{S}=Y_{L}^{-1}$.

Now, let $F(P)=\left(A\left(Q-P^{s}\right)^{-1} A^{*}\right)^{\frac{1}{t}}$ on $\left(0, Q^{\frac{1}{s}}\right)$. Hence $P_{k+1}=F\left(P_{k}\right)$ and $X_{S}=F\left(X_{S}\right)$. By using (2.9), for all $k \in \mathbb{N}$, we obtain that

$$
\begin{equation*}
\left\|P_{k+1}-X_{S}\right\|_{F}=\left\|F\left(P_{k}\right)-F\left(X_{S}\right)\right\|_{F} \leq \frac{s}{t} \frac{\beta^{1+t} \alpha^{s-1}}{\lambda_{n}\left(A^{*} A\right)}\left\|P_{k}-X_{S}\right\|_{F} \tag{3.7}
\end{equation*}
$$

where $P_{k}, X_{S} \leq \alpha I$ and $F\left(P_{k}\right), F\left(X_{S}\right) \leq \beta I$. For all $k \in \mathbb{N}$, we have $P_{k} \leq$ $X_{S} \leq \lambda_{1}\left(X_{S}\right) I$ and $F\left(P_{k}\right) \leq F\left(X_{S}\right) \leq \lambda_{1}\left(X_{S}\right) I$. So, by replacing $\alpha=\lambda_{1}\left(X_{S}\right)$ and $\beta=\lambda_{1}\left(X_{S}\right)$ in (3.7),

$$
\left\|P_{k+1}-X_{S}\right\|_{F} \leq \frac{s}{t} \frac{\lambda_{1}\left(X_{S}\right)^{s+t}}{\lambda_{n}\left(A^{*} A\right)}\left\|P_{k}-X_{S}\right\|_{F}
$$

In the following, we present a necessary and sufficient condition for the existence of HPD solutions of Eq. (1.1), when $s, t \in[1, \infty)$.

Proposition 3.4. If $s \geq t \geq 1$, then Eq. (1.1) has an HPD solution if and only if the sequence (3.2) is convergent to the Hermitian positive definite matrix $P$. (In this case, by Theorem 3.2, the sequence (3.2) is monotonically decreasing and converges to the maximal HPD solution $X_{L}$.)

Also, if $t \geq s \geq 1$, then Eq. (1.1) has an HPD solution if and only if the sequence (3.6) is convergent to the Hermitian positive definite matrix P. (In this case, by Theorem 3.3, the sequence (3.6) is monotonically increasing and converges to the minimal HPD solution $X_{S}$.)
Remark 3.5. By Proposition 3.4, if $s \geq t \geq 1(t \geq s \geq 1)$ and the sequence (3.2) (sequence (3.6)) is not decreasing (not increasing) sequence or there exists $k \in \mathbb{N}$ such that $P_{k}$ is not an Hermitian positive definite, then Eq. (1.1) has not HPD solution.
Proposition 3.6. Let $s=t \geq 1$. Then Eq. (1.1) has an HPD solution if and only if the sequence (3.2) is monotonically decreasing and converges to the matrix $X_{L}$ if and only if the sequence (3.6) is monotonically increasing and converges to the matrix $X_{S}$.

## 4. Numerical examples

In this section, by some numerical examples, the convergence of the above iterative sequences are studied. All the tests are performed by MATLAB with machine precision around $10^{-10}$. We continue the iterative sequences up to step $k$, where $\left\|P_{k+1}-P_{k}\right\|_{F} \leq 1.0 e-10$.
Example 4.1. Consider Eq. (1.1) with $s=\frac{5}{3}, t=1$,
$A=\left[\begin{array}{cccc}0.75 & -0.75 & 0 & 0 \\ 0.80 & 0.80 & 0 & 0 \\ 0 & 0 & 0.85 & 0.85 \\ 0 & 0 & -0.90 & 0.90\end{array}\right], Q=\left[\begin{array}{cccc}2.405 & 0.155 & 0 & 0 \\ 0.155 & 2.405 & 0 & 0 \\ 0 & 0 & 3.065 & -0.175 \\ 0 & 0 & -0.175 & 3.065\end{array}\right]$.
The matrix $A$ is a nonsingular and $Q$ is a Hermitian positive definite matrix. By choosing $k=2$, we obtain that

$$
\lambda_{1}\left(Q^{-\frac{1}{2}}\left(A Q^{-1} A^{*}\right)^{\frac{s}{t}} Q^{-\frac{1}{2}}\right)=0.1400 \leq 0.1575=\frac{k-1}{k^{\frac{s+t}{t}}}
$$

So, by Theorem 2.5, $2 A Q^{-1} A^{*} \leq Q^{\frac{3}{5}}$. Moreover if $\Omega:=\left[2 A Q^{-1} A^{*}, Q^{\frac{3}{5}}\right]$, Eq. (1.1) has an HPD solution in $\Omega$. Since

$$
a=\frac{t}{s} \frac{\lambda_{1}\left(A^{*} A\right)}{\left(\left(1-k^{-1}\right) \lambda_{n}(Q)\right)^{1-\frac{1}{s}}\left(k \lambda_{n}\left(A Q^{-1} A^{*}\right)\right)^{1+\frac{1}{t}}}=0.9273<1
$$

by Corollary 2.7, Eq. (1.1) has the unique HPD solution $X_{L}$ in $\Omega$ and sequence

$$
P_{k+1}=\left(Q-A^{*} P^{-t} A\right)^{\frac{1}{s}}, P_{1}=\frac{1}{2}\left(\left(k A Q^{-1} A^{*}\right)^{\frac{1}{t}}+Q^{\frac{1}{s}}\right) \in \Omega
$$

is convergent to the $X_{L}$. After $k=25$ step, we see that $\left\|P_{25}-P_{24}\right\|_{F}=$ $7.7435 e-011$. Therefore

$$
X_{L} \simeq P_{25}=\left[\begin{array}{cccc}
1.2575 & 0.0412 & 0 & 0 \\
0.0412 & 1.2241 & 0 & 0 \\
0 & 0 & 1.5625 & -0.0491 \\
0 & 0 & -0.0491 & 1.5344
\end{array}\right]
$$

Example 4.2. Consider the matrix Eq. (1.1) with $s=\sqrt{3}, t=\sqrt{2}$,

$$
A=\left[\begin{array}{llll}
4 & 1 & 9 & 4 \\
5 & 6 & 9 & 8 \\
0 & 4 & 1 & 5 \\
2 & 7 & 5 & 1
\end{array}\right], Q=\left[\begin{array}{cccc}
686 & 441 & 392 & 441 \\
441 & 931 & 588 & 686 \\
392 & 588 & 686 & 392 \\
441 & 686 & 392 & 735
\end{array}\right]
$$

Since

$$
\lambda_{1}\left(A^{*} A\right)-\frac{s}{s+t}\left(\frac{t}{s+t}\right)^{\frac{t}{s}} \lambda_{n}^{1+\frac{t}{s}}(Q)=-627.6697 \leq 0
$$

by Theorem 2.10 (1), Eq. (1.1) has an HPD solution and so by using Theorem 3.2 , the iterative sequence (3.2) is convergent to the maximal HPD solution of Eq. (1.1). For $k=6$, we have $\left\|P_{6}-P_{5}\right\|_{F}=6.7641 e-12$. Hence

$$
X_{L} \simeq P_{6}=\left[\begin{array}{cccc}
39.1792 & 11.8409 & 12.4479 & 14.1989 \\
11.8409 & 43.2579 & 19.6539 & 23.7551 \\
12.4479 & 19.6539 & 37.7836 & 9.9658 \\
14.1989 & 23.7551 & 9.9658 & 37.6148
\end{array}\right]
$$

Example 4.3. Consider the matrix Eq. (1.1) with $s=\frac{3}{2}, t=3$,

$$
A=\left[\begin{array}{ccccc}
4 & 2 & -2 & 0 & 1 \\
1 & 5 & -1 & 0 & 3 \\
2 & 0 & 5 & 1 & 0 \\
-3 & 1 & 5 & -7 & 5 \\
0 & 0 & -4 & 1 & 8
\end{array}\right], Q=\left[\begin{array}{ccccc}
32 & 10 & -14 & 23 & -8 \\
10 & 32 & -4 & -7 & 22 \\
-14 & -4 & 73 & -34 & -12 \\
23 & -7 & -34 & 53 & -27 \\
-8 & 22 & -12 & -27 & 101
\end{array}\right]
$$

Since

$$
\lambda_{1}\left(A Q^{-1} A^{*}\right)-\left(\frac{t}{s+t}\right)^{\frac{t}{s+t}}\left(\frac{s}{s+t}\right)^{\frac{s}{s+t}} \lambda_{n}\left(A^{*} A\right)^{\frac{t}{s+t}}=-0.9199 \leq 0
$$

by Theorem 2.10(2), Eq. (1.1) has an HPD solution and so by Theorem 3.3, the iterative sequence (3.6) is convergent to the minimal HPD solution of Eq. (1.1). For $k=9$, we have $\left\|P_{9}-P_{8}\right\|_{F}=5.3450 e-011$. Therefore

$$
X_{S} \simeq P_{9}=\left[\begin{array}{ccccc}
0.9692 & 0.0170 & 0.0033 & -0.0065 & 0.0020 \\
0.0170 & 0.9776 & -0.0003 & 0.0042 & 0.0036 \\
0.0033 & -0.0003 & 0.9853 & 0.0026 & -0.0044 \\
-0.0065 & 0.0042 & 0.0026 & 0.9951 & 0.0012 \\
0.0020 & 0.0036 & -0.0044 & 0.0012 & 0.9930
\end{array}\right]
$$

Example 4.4. Let $s=3, t=2$ and $A, Q$ be the same as in Example 4.3. Replacing $2 A \rightarrow A$ and consider the sequence (3.2). Since $P_{3}$ is not an Hermitian positive definite, by using Remark 3.5, the Eq. (1.1) has not HPD solution.

Acknowledgement. We would like to thank the anonymous referees for the careful reading and the helpful comments and suggestions to improving this paper.

## References

[1] R. P. Agarwal, M. Meehan, and D. O'Regan, Fixed Point Theory and Applications, Cambridge University, 2001.
[2] W. N. Anderson, T. D. Morley, and G. E. Trapp, Ladder networks, fixed points, and the geometric mean, Circuits Systems Signal Process. 2 (1983), no. 3, 259-268.
[3] T. Ando, Limit of iterates of cascade addition of matrices, Numer. Funct. Anal. Optim. 2 (1980), no. 7-8, 579-589.
[4] R. Bhatia, Matrix Analysis, Graduate Text in Mathematics, Springer-Verlag New York, 1997.
[5] R. S. Bucy, A priori bound for the Riccati equation, in: Proceedings of the Sixth Berkeley Symposium on Mathematical Statistics and Probability, Vol. 111, 645-656, Probability Theory, University of California Press, Berkeley, 1972.
[6] J. Cai and G. Chen, Some investigation on Hermitian positive definite solutions of the matrix equation $X^{s}+A^{*} X^{-t} A=Q$, Linear Algebra Appl. 430 (2009), no. 8-9, 2448-2456.
[7] Sh. Du and J. Hou, Positive definite solutions of operator equations $X^{m}+A^{*} X^{-n} A=I$, Linear Multilinear Algebra 51 (2003), no. 2, 163-173.
[8] X. F. Duan and A. P. Liao, On the existence of Hermitian positive definite solutions of the matrix equation $X^{s}+A^{*} X^{-t} A=Q$, Linear Algebra Appl. 429 (2008), no. 4, 673-687.
$\qquad$ , On the nonlinear matrix equation $X+A^{*} X^{-q} A=Q(q \geq 1)$, Math. Comput. Modelling 49 (2009), no. 5-6, 936-945.
[10] S. M. El-Sayed and A. M. Al-Dbiban, A new inversion free iteration for solving the equation $X+A^{*} X^{-1} A=Q$, J. Comput. Appl. Math. 181 (2005), no. 1, 148-156.
[11] J. C. Engwerda, On the existence of a positive definite solution of the matrix equation $X+A^{T} X^{-1} A=I$, Linear Algebra Appl. 194 (1993), 91-108.
[12] T. Furuta, Operator inequalities associated with Hölder-McCarthy and Kantorovich inequalities, J. Inequal. Appl. 2 (1998), no. 2, 137-148.
[13] W. L. Green and E. W. Kamen, Stabilization of linear systems over a commutative normed algebra with applications to spatially distributed parameter dependent systems, SIAM J. Control Optim. 23 (1985), 1-18.
[14] V. I. Hasanov and I. G. Ivanov, Solutions and perturbation estimates for the matrix equations $X \pm A^{*} X^{-n} A=Q$, Appl. Math. Comput. 156 (2004), no. 2, 513-525.
[15] R. A. Horn and C. R. Johnson, Topics in Matrix Analysis, Cambridge University Press, 1991.
[16] I. G. Ivanov, On positive definite solutions of the family of matrix equations $X+$ $A^{*} X^{-n} A=Q$, J. Comput. Appl. Math. 193 (2006), no. 1, 277-301.
[17] M. Parodi, La localisation des valeurs caractérisiques des matrices et ses applications, Gauthier-Villars, Paris, 1959.
[18] Z. Y. Peng, S. M. El-Sayed, and X. L. Zhang, Iterative methods for the extremal positive definite solution of the matrix equation $X+A^{*} X^{-\alpha} A=Q$, J. Comput. Appl. Math. 200 (2007), no. 2, 520-527.
[19] W. Pusz and S. L. Woronowitz, Functional calculus for sesquilinear forms and the purification map, Rep. Mathematical Phys. 8 (1975), no. 2,159-170.
[20] X. T. Wang and Y. M. Li, On equations that are equivalent to the nonlinear matrix equation $X+A^{*} X^{-\alpha} A=Q$, J. Comput. Appl. Math. 234 (2010), no. 8, 2441-2449.
[21] X. Y. Yin, S. Y. Liu, and L. Fang, Solutions and perturbation estimates for the matrix equation $X^{s}+A^{*} X^{-t} A=Q$, Linear Algebra Appl. 431 (2009), no. 9, 1409-1421.
[22] Y. Yueting, The iterative method for solving nonlinear matrix equation $X^{s}+A^{*} X^{-t} A=$ $Q$, Appl. Math. Comput. 188 (2007), no. 1, 46-53.
[23] X. Zhan, Matrix Inequalities, Springer-Verlag Berlin Heidelberg, 2002.
[24] D. Zhou, G. Chen, G. Wu, and X. Zhang, Some properties of the nonlinear matrix equation $X^{s}+A^{*} X^{-t} A=Q$, J. Math. Anal. Appl. 392 (2012), no. 1, 75-82.

Mohsen Masoudi
Department of Mathematics
Shahid Bahonar University of Kerman
Kerman, Iran
E-mail address: masoudi.mohsen.math@gmail.com
Mahmoud Mohseni Moghadam
Department of Mathematics
Shahid Bahonar University of Kerman
Kerman, Iran
E-mail address: mohseni@mail.uk.ac.ir
Abbas Salemi
Department of Mathematics
Shahid Bahonar University of Kerman
Kerman, Iran
E-mail address: salemi@mail.uk.ac.ir

