

## PERSISTENT ACTIONS ON COMPACT METRIC SPACES

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ABSTRACT. In this paper, we introduce the notion of persistent actions of finitely generated groups on compact metric spaces and give a necessary condition for a persistent dynamical system to be topologically stable.

### 1. Introduction

R. Bowen [1] introduced the concept of the pseudo-orbit-tracing-property and essentially showed that expansive homeomorphisms with this property are topologically stable. A. Morimoto [5] has proved that the topological stability implies the pseudo-orbit-tracing-property. K. Yano [6] showed that expansiveness condition is necessary in Bowen's result. Moreover J. Lewowicz [4] introduced the concept of persistence of a dynamical system which is weaker than that of topological stability.

Very recently, N. Chung and K. Lee [3] introduced the notion of topological stability for actions of finitely generated groups on compact metric spaces and proved an expansive action having the pseudo-orbit-tracing property is topologically stable. In this paper, we introduce the notion of persistent actions of finitely generated groups on compact metric spaces and give a necessary condition to be topologically stable.

Let  $X$  denote a compact metric space with a metric  $d$ . Let  $Homeo(X)$  denote the space of all homeomorphisms of  $X$  to itself topologied by the  $C^0$ -metric

$$d_0(f, g) = \sup\{d(f(x), g(x)) : x \in X\}.$$

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To explain the main theorem of our paper, we recall some definitions for group actions which are introduced very recently in [3].

Let  $G$  be a finitely generated group and  $Act(G, X)$  denote the set of all continuous actions of  $G$  on  $X$ . Let  $A$  be a finitely generating set of  $G$ . We define a metric  $d_A$  on  $Act(G, X)$  by

$$d_A(T, S) = \sup\{d(T_ax, S_ax) : x \in X, a \in A\}$$

for every  $T, S \in Act(G, X)$ .

DEFINITION 1.1. [3] An action  $T \in Act(G, X)$  is said to be *A-topologically stable* if for every  $\varepsilon > 0$ , there is  $\delta > 0$  such that if  $S$  is another continuous action of  $G$  on  $X$  with  $d_A(T, S) < \delta$  then there exists a continuous map  $f : X \rightarrow X$  with

- $T_g f = f S_g$  for every  $g \in G$ , and
- $d(f, 1_X) \leq \varepsilon$ ,

where  $1_X$  is the identity map on  $X$ . The map  $f$  is called the *semiconjugacy* from  $S$  to  $T$  with respect to  $A$ .

We can see that topological stability does not depend on the choice of a symmetric finitely generating set. And we say that  $T$  is *topologically stable* if it is *A-topologically stable* for some symmetric finitely generating set  $A$  of  $G$ .

We say that an action  $T \in Act(G, X)$  is *expansive* if there exists a constant  $\eta > 0$  such that for every  $x \neq y$ , we have

$$\sup_{g \in G} d(T_g x, T_g y) > \eta.$$

Such number  $\eta > 0$  is called an *expansive constant* of  $T$ .

Now we will introduce the definition of persistent actions of finitely generated groups by using symmetric finitely generating sets of the acting groups.

DEFINITION 1.2. Let  $A$  be a symmetric finitely generating set of  $G$ , and let  $T \in Act(G, X)$ . We say that  $T$  is  *$\alpha$ -persistent (or  $\beta$ -persistent)* with respect to  $A$  if for every  $\varepsilon > 0$ , there is  $\delta > 0$  such that if  $d_A(T, S) < \delta$  and  $x \in X$ , then there exists  $y \in X$  satisfying

$$d(T_g y, S_g x) < \varepsilon \quad (\text{or} \quad d(T_g x, S_g y) < \varepsilon)$$

for all  $g \in G$ .

We can check that a persistent action does not depend on the choice of a symmetric finitely generating set  $A$  of  $G$  as following lemma.

LEMMA 1.3. *Let  $T \in \text{Act}(G, X)$ . Let  $A$  and  $B$  be two symmetric finitely generating sets of  $G$ . If  $T$  is  $\alpha$ -persistent with respect to  $A$ , then it is also  $\alpha$ -persistent with respect to  $B$ .*

*Proof.* Let  $d$  be a compatible metric on  $X$ . By the assumption,  $T$  is  $\alpha$ -persistent with respect to  $A$ , for every  $\varepsilon > 0$  there is  $\delta > 0$  such that if  $d_A(T, S) < \delta$  and  $x \in X$ , then there exists  $y \in X$  satisfying  $d(T_g y, S_g x) < \varepsilon$  for all  $g \in G$ . To prove this lemma, it is enough to claim that there is  $\delta' > 0$  such that every  $S \in \text{Act}(G, X)$  with  $d_B(T, S) < \delta'$  satisfies  $d_A(T, S) < \delta$ .

Put  $k := \max_{a \in A} l_B(a)$ , where  $l_B$  is the word length metric on  $G$  induced by  $B$ . Choose  $\delta_1 > 0$  such that  $k\delta_1 < \delta$ . Since  $X$  is compact,  $A$  and  $B$  are finite and  $T$  is a continuous action, there exists  $\delta' > 0$  such that  $d(T_{g'} x, T_{g'} y) < \delta_1$  for any  $x$  and  $y$  with  $d(x, y) < \delta'$  and  $g' \in G$  with  $l_B(g') \leq k$ . For every  $a \in A$ , we write  $a$  as  $b_1 \cdots b_{l(a)}$ , where  $l(a) = l_B(a) \leq k, b_i \in B$ , and  $i = 1, \dots, l(a)$ . Then for every  $S \in \text{Act}(G, X)$  with  $d_B(T, S) < \delta'$ , we get the following conclusion;

$$\begin{aligned} d_A(T, S) &= d(T_a x, S_a x) \\ &= d(T_{b_1 \cdots b_{l(a)}} x, S_{b_1 \cdots b_{l(a)}} x) \\ &\leq d(T_{b_1 \cdots b_{l(a)-1}} T_{b_{l(a)}} x, T_{b_1 \cdots b_{l(a)-1}} S_{b_{l(a)}} x) \\ &\quad + d(T_{b_1 \cdots b_{l(a)-2}} T_{b_{l(a)-1}} S_{b_{l(a)}} x, T_{b_1 \cdots b_{l(a)-1}} S_{b_{l(a)-1}} S_{b_{l(a)}} x) \\ &\quad + \cdots + d(T_{b_1} T_{b_2} S_{b_3 \cdots b_{l(a)}} x, T_{b_1} S_{b_2} S_{b_3 \cdots b_{l(a)-1}} x) \\ &\quad + d(T_{b_1} S_{b_2 \cdots b_{l(a)}} x, S_{b_1 \cdots b_{l(a)}} x) \\ &\leq k\delta' < \delta. \end{aligned}$$

□

We say that  $T$  is  $\alpha$ -persistent if it is  $\alpha$ -persistent with respect to some symmetric finitely generating set  $A$  of  $G$ . Throughout this paper, a persistent action means both  $\alpha$  and  $\beta$ -persistent.

LEMMA 1.4. *A topologically stable dynamical system is persistent for group action.*

*Proof.* It is straightforward. □

The following is our main theorem which gives a necessary condition for a persistent action to be topologically stable.

**Theorem A.** A persistent action is topologically stable if it is expansive.

## 2. Proof of Theorem A

Let  $G$  and  $X$  be as before. Let  $T, S \in \text{Act}(G, X)$ . If  $d_A(T, S) < \delta$ , then each  $S$ -orbit  $\{S_g x\}$  of  $x \in X$  is nearly a  $T$ -orbit in the sense that  $d(T_a S_g x, S_{ag} x) < \delta$  for every  $a \in A, g \in G$ . To prove Theorem A, we need the following lemmas.

**LEMMA 2.1.** *Assume that an expansive action  $T$  of a finitely generated group  $G$  on a compact metric space  $(X, d)$  is  $\alpha$ -persistent with respect to some finitely generating set  $A$  of  $G$ . Let  $\varepsilon < \eta/2$  and  $\delta$  corresponds to  $\varepsilon$  as in Definition 1.2, where  $\eta$  is an expansive constant of the action  $T$ . Then for every  $S$ -orbit  $\{S_g x\}_{g \in G}$  of  $x \in X$  with  $d(T, S) < \delta$  there exists a unique point in  $X$  satisfying  $\alpha$ -persistentness.*

*Proof.* Let  $\{S_g x\}_{g \in G}$  be a  $S$ -orbit of  $x$  with  $d(T, S) < \delta$  and let  $y$  and  $z$  be two points which is  $\{T_g y\}_{g \in G}$  and  $\{T_g z\}_{g \in G}$  are two orbits such that  $d(T_g y, S_g x) < \varepsilon$  and  $d(T_g z, S_g x) < \varepsilon$  for all  $g \in G$ . Then we can certify

$$d(T_g y, T_g z) \leq d(T_g y, S_g x) + d(S_g x, T_g z) < 2\varepsilon < \eta$$

for every  $g \in G$ . This fact means  $y = z$ , since  $T$  is expansive.  $\square$

**LEMMA 2.2.** [3] *Let  $T$  be an expansive action of  $G$  on a compact metric space  $(X, d)$  and let  $\eta$  be an expansive constant of the action. Then for every  $\varepsilon > 0$  there exists a non-empty finite subset  $F$  of  $G$  such that whenever  $\sup_{g \in F} d(T_g x, T_g y) \leq \eta$ , one has  $d(x, y) < \varepsilon$ .*

*Proof.* See Lemma 1.18 in [3].  $\square$

**Proof of Theorem A.** Let  $\eta > 0$  be an expansive constant of  $T$  and  $\varepsilon < \eta/3$ . Let  $A$  be a finite generating set of  $G$ . Choose  $\delta$  corresponding to  $\varepsilon$  as in Definition 1.2. Let  $S$  be another continuous action of  $G$  on  $(X, d)$  with  $d_A(T, S) < \delta$ . Then by the persistentness, there exists  $y \in X$  such that

$$(*) \quad d(T_g y, S_g x) < \varepsilon \quad \text{and} \quad d(T_g x, S_g y) < \varepsilon$$

for all  $g \in G$  and  $x \in X$ .

Define a map  $f : X \rightarrow X$  by  $f(x) = y$ . By Lemma 2.1,  $f$  is well-defined. In particular, we have  $d(f(x), x) < \varepsilon$  for every  $x \in X$ , and hence  $d(f, Id_X) \leq \varepsilon$ .

Now we will prove that  $f$  is continuous. Let  $\varepsilon_1 > 0$ . By Lemma 2.2, there is a non-empty finite subset  $F$  of  $G$  such that whenever  $\sup_{g \in F} d(T_g x, T_g y) \leq \eta$  one has  $d(x, y) < \varepsilon_1$ . Choose  $\delta_1 > 0$  such that

for every  $x, y \in X$  with  $d(x, y) < \delta_1$ , one has  $d(S_g x, S_g y) < \eta/3$  for any  $g \in F$ . Then, for every  $x, y \in X$  with  $d(x, y) < \delta_1$  and for every  $g \in F$ , we get

$$\begin{aligned} d(T_g f(x), T_g f(y)) &= d(f S_g(x), f S_g(y)) \\ &\leq d(f S_g(x), S_g(x)) + d(S_g(x), S_g(y)) + d(S_g(y), f S_g(y)) \\ &< \varepsilon + \eta/3 + \varepsilon < \eta. \end{aligned}$$

Thus  $d(f(x), f(y)) < \varepsilon_1$  for every  $x, y \in X$  with  $d(x, y) < \delta_1$  and hence  $f$  is continuous.

Next we will show that  $T_g f(x) = f S_g(x)$  for every  $x \in X$  and  $g \in G$ . Then

$$d(T_{g'} f(S_g x), S_{g'} S_g x) = d(T_{g'} f(S_g x), S_{g'} S_g x) < \varepsilon$$

for every  $g' \in G$ . On the other hand, applying (\*), we obtain

$$d(T_{g'} T_g f(x), S_{g'} S_g x) = d(T_{g'} f(x), S_{g'} S_g x) < \varepsilon.$$

Then by Lemma 2.1, we get  $T_g f(x) = f S_g(x)$ . This completes the proof of Theorem A.  $\square$

Let  $T, S \in \text{Act}(G, X)$ . We say that  $T$  is topologically conjugate to  $S$  if there exists  $h \in \text{Homeo}(X)$  satisfying  $hS = Th$ , and the homeomorphism  $h$  is called a *topological conjugacy* between  $T$  and  $S$ . We can see that a persistence action is invariant under a topological conjugacy.

**THEOREM 2.3.** *A dynamical system which is topologically conjugate to a persistent action is persistent.*

*Proof.* Suppose that a persistent action  $T \in \text{Act}(G, X)$  is topologically conjugate to a dynamical system  $S$ . Then we have a topological conjugacy  $f \in \text{Homeo}(X)$  between  $T$  and  $S$ . Let  $\varepsilon > 0$  be given, and choose  $0 < \varepsilon' < \varepsilon$  such that if  $d(a, b) < \varepsilon'$  then  $d(f^{-1}(a), f^{-1}(b)) < \varepsilon$  for  $a, b \in X$ .

Since  $T$  is persistent, there is  $\delta' > 0$  such that if  $d_A(T, T') < \delta'$  for some symmetric finitely generating set  $A$  of  $G$  then for any  $x \in X$ , there exists  $y \in X$  satisfying

$$d(T_g(y), T'_g(x)) < \varepsilon'$$

for all  $g \in G$ .

We can choose  $0 < \delta < \delta'$  such that if  $d(a, b) < \delta$ , then

$$d(f(a), f(b)) < \delta'.$$

Let  $S_0 \in \text{Act}(G, X)$  be such that  $d_A(S, S_0) < \delta$ , and put  $T_0 = f \circ S_0 \circ f^{-1}$ . Since

$$d(f(S(x)), f(S_0(x))) = d(T(f(x)), T_0(f(x))) < \delta'$$

for any  $x \in X$ , we have  $d_A(T, T_0) < \delta'$ . Since  $T$  is persistent, there is  $f(y) \in X$  such that

$$d(T_g(f(y)), T'_g(f(x))) = d(f(S_g(y)), f(S'_g(x))) < \varepsilon'$$

for all  $g \in G$ . Therefore we have  $d(S_g(y), S'_g(x)) < \varepsilon'$  for all  $g \in G$ . This completes the proof.  $\square$

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