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LIGHTLIKE HYPERSURFACES OF AN INDEFINITE KAEHLER MANIFOLD WITH A NON-METRIC ϕ -SYMMETRIC CONNECTION

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ABSTRACT. We define a new connection on semi-Riemannian manifold, which is called a *non-metric* ϕ -symmetric connection. Semi-symmetric non-metric connection and quarter-symmetric non-metric connection are two impotent examples of this connection. The purpose of this paper is to study the geometry of lightlike hypersurfaces of an indefinite Kaehler manifold with a non-metric ϕ -symmetric connection.

1. Introduction

A linear connection $\overline{\nabla}$ on a semi-Riemannian manifold $(\overline{M}, \overline{g})$ is called a *non-metric* ϕ -symmetric connection if it and its torsion tensor \overline{T} satisfy

(1.1)
$$(\bar{\nabla}_{\bar{X}}\bar{g})(\bar{Y},\bar{Z}) = -\theta(\bar{Y})\phi(\bar{X},\bar{Z}) - \theta(\bar{Z})\phi(\bar{X},\bar{Y}),$$

(1.2)
$$\overline{T}(\overline{X},\overline{Y}) = \theta(\overline{Y})J\overline{X} - \theta(\overline{X})J\overline{Y},$$

where ϕ and J are tensor fields of types (0,2) and (1,1) respectively, and θ is a 1-form associated with a smooth unit vector field ζ , which is called the *characteristic vector field* of \overline{M} , by $\theta(\overline{X}) = \overline{g}(\overline{X}, \zeta)$. Throughout this paper, we denote by $\overline{X}, \overline{Y}$ and \overline{Z} the smooth vector fields on \overline{M} .

It is known [11, 12] that the induced linear connection ∇ on any 1-lightlike submanifold of an indefinite Kaehler manifold with a quarter-symmetric metric connection is an example of non-metric ϕ -symmetric connection. In case $\phi = \bar{g}$ in (1.1), the above connection $\bar{\nabla}$ is reduced to the quarter-symmetric nonmetric connection [3, 4, 8, 9, 11, 12, 14]. In case $\phi = \bar{g}$ in (1.1) and J = I in (1.2), where I is the identity tensor field of type (1, 1), the above connection $\bar{\nabla}$ is reduced to so called the semi-symmetric non-metric connection [1, 2].

The subject of this paper is to study lightlike hypersurfaces of an indefinite Kaehler manifold (\bar{M}, \bar{g}, J) with a non-metric ϕ -symmetric connection, in which the tensor field J defined by (1.2) is identical with the indefinite almost complex

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structure J of \overline{M} and the tensor field ϕ in (1.1) is identical with the fundamental 2-form associated with the indefinite almost complex structure J, *i.e.*,

(1.3)
$$\phi(\bar{X},\bar{Y}) = \bar{g}(J\bar{X},\bar{Y})$$

Remark 1.1. Denote $\widetilde{\nabla}$ by the Levi-Civita connection of $(\overline{M}, \overline{g}, J)$ with respect to the metric \overline{g} . We define a linear connection $\overline{\nabla}$ on \overline{M} given by

(1.4)
$$\bar{\nabla}_{\bar{X}}\bar{Y} = \widetilde{\nabla}_{\bar{X}}\bar{Y} + \theta(\bar{Y})J\bar{X}.$$

By directed calculations, we see that $\overline{\nabla}$ is a non-metric ϕ -symmetric connection. Conversely if $\overline{\nabla}$ is a non-metric ϕ -symmetric connection, then we can write

(1.5)
$$\bar{\nabla}_{\bar{X}}\bar{Y} = \widetilde{\nabla}_{\bar{X}}\bar{Y} + \psi(\bar{X},\bar{Y}).$$

Substituting (1.5) into (1.1) and using the fact that $\widetilde{\nabla}$ is metric, we have

(1.6)
$$\bar{g}(\psi(\bar{X},\bar{Y}),\bar{Z}) + \bar{g}(\psi(\bar{X},\bar{Z}),\bar{Y}) = \theta(\bar{Y})\phi(\bar{X},\bar{Z}) + \theta(\bar{Z})\phi(\bar{X},\bar{Y}).$$

Also, from (1.5) and the fact that $\widetilde{\nabla}$ is torsion-free, it follows that

$$\bar{T}(\bar{X},\bar{Y}) = \psi(\bar{X},\bar{Y}) - \psi(\bar{Y},\bar{X}).$$

Thus, by using (1.2), we obtain

(1.7)
$$\psi(\bar{X},\bar{Y}) - \psi(\bar{Y},\bar{X}) = \theta(\bar{Y})J\bar{X} - \theta(\bar{X})J\bar{Y}.$$

Exchanging \bar{X} with \bar{Y} and \bar{Y} with \bar{X} to (1.6), we have

$$\bar{g}(\psi(\bar{Y},\bar{X}),\bar{Z}) + \bar{g}(\psi(\bar{Y},\bar{Z}),\bar{X}) = \theta(\bar{X})\phi(\bar{Y},\bar{Z}) + \theta(\bar{Z})\phi(\bar{Y},\bar{X}).$$

Subtracting this equation from (1.6) and using (1.7), we obtain

(1.8)
$$\bar{g}(\psi(\bar{X},\bar{Z}),\bar{Y}) - \bar{g}(\psi(\bar{Y},\bar{Z}),\bar{X}) = 2\theta(\bar{Z})\phi(\bar{X},\bar{Y})$$

Again from (1.7) we get

$$\begin{split} \bar{g}(\psi(\bar{X},\bar{Y}),\bar{Z}) &- \bar{g}(\psi(\bar{Y},\bar{X}),\bar{Z}) = \theta(\bar{Y})\phi(\bar{X},\bar{Z}) - \theta(\bar{X})\phi(\bar{Y},\bar{Z}), \\ \bar{g}(\psi(\bar{X},\bar{Z}),\bar{Y}) &- \bar{g}(\psi(\bar{Z},\bar{X}),\bar{Y}) = \theta(\bar{Z})\phi(\bar{X},\bar{Y}) - \theta(\bar{X})\phi(\bar{Z},\bar{Y}). \end{split}$$

Adding these two equations and using (1.6), we have

$$\bar{g}(\psi(\bar{Y},\bar{X}),\bar{Z}) + \bar{g}(\psi(\bar{Z},\bar{X}),\bar{Y}) = 0.$$

Using this equation, (1.8) and the fact that \bar{g} is non-degenerate, we obtain

$$\psi(\bar{X}, \bar{Y}) = \theta(\bar{Y})J\bar{X}.$$

Thus the non-metric ϕ -symmetric connection $\overline{\nabla}$ satisfies (1.4). It follows that, for a linear connection $\overline{\nabla}$ on an indefinite Kaehler manifold $(\overline{M}, \overline{g}, J), \overline{\nabla}$ is a non-metric ϕ -symmetric connection if and only if $\overline{\nabla}$ satisfies (1.4).

In this paper, we study the geometry of lightlike hypersurfaces of an indefinite Kaehler manifold with a non-metric ϕ -symmetric connection. For the rest of this paper, by saying that the non-metric ϕ -symmetric connection we shall mean the non-metric ϕ -symmetric connection given by (1.4).

2. Lightlike hypersurfaces

Let $\overline{M} = (\overline{M}, \overline{g}, J)$ be an indefinite Kaeler manifold, where \overline{g} is a semi-Riemannian metric and J is an indefinite almost complex structure satisfying

(2.1)
$$J^2 \bar{X} = -\bar{X}, \qquad \bar{g}(J\bar{X}, J\bar{Y}) = \bar{g}(\bar{X}, \bar{Y}), \qquad (\tilde{\nabla}_{\bar{X}}J)\bar{Y} = 0,$$

where $\widetilde{\nabla}$ is the Levi-Civita connection with respect to \overline{g} . Let $\overline{\nabla}$ be a non-metric ϕ -symmetric connection on \overline{M} given by (1.4). Then (2.1)₃ is reformed as follow:

(2.2)
$$(\bar{\nabla}_{\bar{X}}J)\bar{Y} = \theta(\bar{Y})\bar{X} + \theta(J\bar{Y})J\bar{X}.$$

Let (M, g) be a lightlike hypersurface of \overline{M} . The normal bundle TM^{\perp} of Mis a vector subbundle of the tangent bundle TM of M, of rank 1, and coincides with the radical distribution $Rad(TM) = TM \cap TM^{\perp}$. Denote by F(M) the algebra of smooth functions on M and by $\Gamma(E)$ the F(M) module of smooth sections of any vector bundle E over M. Also denote by $(2.1)_i$ the *i*-th equation of the three equations in (2.1). We use same notations for any others.

A complementary vector bundle S(TM) of Rad(TM) in TM is non-degenerate distribution on M, which is called a *screen distribution* on M, such that

$$TM = Rad(TM) \oplus_{orth} S(TM),$$

where \oplus_{orth} denotes the orthogonal direct sum. It is known [6] that, for any null section ξ of Rad(TM), there exists a unique null section N of a unique lightlike vector bundle tr(TM) in $S(TM)^{\perp}$ satisfying

$$\bar{g}(\xi, N) = 1, \quad \bar{g}(N, N) = \bar{g}(N, X) = 0, \quad \forall X \in \Gamma(S(TM)).$$

We call tr(TM) and N the transversal vector bundle and the null transversal vector field of M with respect to the screen distribution S(TM), respectively. The tangent bundle $T\overline{M}$ of \overline{M} is decomposed as follow:

$$TM = TM \oplus tr(TM) = \{Rad(TM) \oplus tr(TM)\} \oplus_{orth} S(TM)\}$$

In the sequel, let X, Y, Z and W be the vector fields on M, unless otherwise specified. Let P be the projection morphism of TM on S(TM). Then the local Gauss and Weingartan formulae of M and S(TM) are given respectively by

(2.3)
$$\nabla_X Y = \nabla_X Y + B(X, Y)N$$

(2.4)
$$\bar{\nabla}_X N = -A_N X + \tau(X) N t$$

(2.5)
$$\nabla_X PY = \nabla_X^* PY + C(X, PY)\xi_3$$

(2.6)
$$\nabla_X \xi = -A_{\xi}^* X - \sigma(X)\xi,$$

where ∇ and ∇^* are the induced linear connections on TM and S(TM) respectively, B and C are the local second fundamental forms on TM and S(TM) respectively, A_N and A_{ξ}^* are the shape operators on TM and S(TM) respectively, and τ and σ are 1-forms on TM.

For a lightlike hypersurface M of an indefinite almost Hermitian manifold $(\overline{M}, \overline{g}, J)$, it is known ([6, Section 6.2], [10]) that J(Rad(TM)) and J(tr(TM)) are subbundles of S(TM), of rank 1 such that $J(Rad(TM)) \cap J(tr(TM)) = \{0\}$.

Thus there exist two non-degenerate almost complex distributions D_o and D on M with respect to J, *i.e.*, $J(D_o) = D_o$ and J(D) = D, such that

$$\begin{split} S(TM) &= J(Rad(TM)) \oplus J(tr(TM)) \oplus_{orth} D_o, \\ D &= \{Rad(TM) \oplus_{orth} J(Rad(TM))\} \oplus_{orth} D_o. \end{split}$$

In this case, the decomposition form of TM is reduced to

(2.7)
$$TM = D \oplus J(tr(TM)).$$

Consider two null vector fields U and V, and two 1-forms u and v such that

(2.8)
$$U = -JN, \quad V = -J\xi, \quad u(X) = g(X,V), \quad v(X) = g(X,U).$$

Denote by S the projection morphism of TM on D. Any vector field X of M is expressed as X = SX + u(X)U. Applying J to this form, we have

$$(2.9) JX = FX + u(X)N,$$

where F is a tensor field of type (1, 1) globally defined on M by $F = J \circ S$. Applying J to (2.9) and using (2.1) and (2.8), we have

(2.10)
$$F^2 X = -X + u(X)U.$$

As u(U) = 1 and FU = 0, the set (F, u, U) defines an indefinite almost contact structure on M and F is called the *structure tensor field* of M. But it is not an indefinite almost contact metric structure on M and satisfies

(2.11)
$$g(FX, FY) = g(X, Y) - u(X)v(Y) - u(Y)v(X).$$

3. Non-metric ϕ -symmetric connections

Let $(\overline{M}, \overline{g}, J)$ be an indefinite Kaehler manifold with a non-metric ϕ -symmetric connection $\overline{\nabla}$. Using (1.1), (1.2), (1.3), (2.3) and (2.9), we obtain

(3.1)
$$(\nabla_X g)(Y, Z) = B(X, Y)\eta(Z) + B(X, Z)\eta(Y)$$

$$-\theta(Y)\phi(X,Z) - \theta(Z)\phi(X,Y),$$

(3.2)
$$T(X,Y) = \theta(Y)FX - \theta(X)FY,$$

(3.3)
$$B(X,Y) - B(Y,X) = \theta(Y)u(X) - \theta(X)u(Y)$$

(3.4)
$$\phi(X,Y) = g(FX,Y) + u(X)\eta(Y),$$

(3.5)
$$\phi(X,\xi) = u(X), \qquad \phi(X,N) = v(X),$$

$$\phi(X, V) = 0, \qquad \phi(X, U) = -\eta(X).$$

where T is the torsion tensor with respect to ∇ and η is a 1-form such that

$$\eta(X) = \bar{g}(X, N).$$

Theorem 3.1. There exist no lightlike hypersurfaces of an indefinite Kaehler manifold with a non-metric ϕ -symmetric connection such that B is symmetric.

Proof. Assume that B is symmetric. From (3.3), we get $\theta(X)u(Y) = \theta(Y)u(X)$. Replacing Y by U to this equation, we have

$$\theta(X) = \theta(U)u(X).$$

Taking $X = \xi$ and X = V to this equation by turns, we get b = 0, *i.e.*, the characteristic vector field ζ is tangent to M, and $\theta(V) = 0$ respectively.

As ζ is tangent to M, we have

$$u(\zeta) = g(\zeta, V) = \theta(V) = 0.$$

Taking $Y = \zeta$ to $\theta(Y)u(X) = \theta(X)u(Y)$, we get $u(X) = u(\zeta)\theta(X) = 0$ for all $X \in \Gamma(TM)$. It is a contradiction to u(U) = 1. Thus there exist no lightlike hypersurfaces of an indefinite Kaehler manifold with a non-metric ϕ -connection such that B is symmetric.

Definition. A lightlike hypersurface M is called *totally umbilical* [6] if there exists a smooth function β on a coordinate neighborhood \mathcal{U} such that

$$B(X,Y) = \beta g(X,Y).$$

Corollary 3.2. There exist no totally umbilical lightlike hypersurfaces of an indefinite Kaehler manifold with a non-metric ϕ -connection.

From the fact that $B(X,Y) = \overline{g}(\overline{\nabla}_X Y,\xi)$, we know that B is independent of the choice of the screen distribution S(TM) and satisfies

(3.6)
$$B(X,\xi) = bu(X), \qquad B(\xi,X) = 0,$$

where we set $a = \theta(N)$ and $b = \theta(\xi)$. From (2.3), (2.6) and (3.6), we obtain

(3.7)
$$\bar{\nabla}_X \xi = -A_{\xi}^* X - \sigma(X)\xi + bu(X)N.$$

The local second fundamental forms are related to their shape operators by

(3.8)
$$B(X,Y) = g(A_{\xi}^*X,Y) + bg(FX,Y) + u(X)\theta(Y),$$

$$(3.9) C(X, PY) = g(A_N X, PY) + ag(FX, PY) + v(X)\theta(PY),$$

(3.10)
$$\bar{g}(A_{\xi}^*X, N) = 0, \qquad \bar{g}(A_NX, N) = -av(X),$$

(3.11) $\sigma(X) = \tau(X) - au(X) - bv(X).$

Taking $X = \xi$ to (3.8) and using (3.5)₁, (3.6)₂ and the facts that ϕ is skew-symmetric and S(TM) is non-degenerate, we obtain

Applying $\overline{\nabla}_X$ to (2.8) and (2.9) and using (2.2), (2.3), (2.4), (2.9), (3.1), (3.4), (3.5)_{3,4}, (3.7) and (3.9), we have

(3.13)
$$B(X,U) = u(A_N X) + \theta(U)u(X)$$
$$= C(X,V) - \theta(V)v(X) + \theta(U)u(X),$$

(3.14)
$$\nabla_X U = F(A_N X) + \tau(X)U - aX + \theta(U)FX,$$

(3.15) $\nabla_X V = F(A_{\mathcal{E}}^*X) - \sigma(X)V + bu(X)U - bX + \theta(V)FX,$

(3.16)
$$(\nabla_X F)Y = u(Y)A_N X - B(X,Y)U + \theta(Y)X + \theta(JY)FX,$$

(3.17)
$$(\nabla_X u)Y = -u(Y)\tau(X) - B(X, FY) + \theta(JY)u(X),$$

(3.18)
$$(\nabla_X v)Y = v(Y)\tau(X) - g(A_N X, FY) + \theta(Y)\eta(X)$$

$$-a\{g(X,Y)-u(Y)v(X)\}.$$

Denote by \overline{R} , R and R^* the curvature tensors of the non-metric ϕ -symmetric connection $\overline{\nabla}$ on \overline{M} , and the induced linear connections ∇ and ∇^* on M and S(TM) respectively. Using the Gauss-Weingarten formulae, we obtain two Gauss-Codazzi equations for M and S(TM) such that

$$\begin{array}{ll} (3.19) & R(X,Y)Z = R(X,Y)Z + B(X,Z)A_{N}Y - B(Y,Z)A_{N}X \\ & & + \{(\nabla_{X}B)(Y,Z) - (\nabla_{Y}B)(X,Z) + \tau(X)B(Y,Z) \\ & - \tau(Y)B(X,Z) + B(T(X,Y),Z)\}N, \\ (3.20) & \bar{R}(X,Y)N = -\nabla_{X}(A_{N}Y) + \nabla_{Y}(A_{N}X) + A_{N}[X,Y] \\ & & + \tau(X)A_{N}Y - \tau(Y)A_{N}X \\ & & + \{B(Y,A_{N}X) - B(X,A_{N}Y) + 2d\tau(X,Y)\}N, \\ (3.21) & R(X,Y)PZ = R^{*}(X,Y)PZ + C(X,PZ)A_{\xi}^{*}Y - C(Y,PZ)A_{\xi}^{*}X \\ & & + \{(\nabla_{X}C)(Y,PZ) - (\nabla_{Y}C)(X,PZ) - \sigma(X)C(Y,PZ) \\ & & + \sigma(Y)C(X,PZ) + C(T(X,Y),PZ)\}\xi, \\ (3.22) & R(X,Y)\xi = -\nabla_{X}^{*}(A_{\xi}^{*}Y) + \nabla_{Y}^{*}(A_{\xi}^{*}X) + A_{\xi}^{*}[X,Y] \\ & & - \sigma(X)A_{\xi}^{*}Y + \sigma(Y)A_{\xi}^{*}X \\ & & + \{C(Y,A_{\xi}^{*}X) - C(X,A_{\xi}^{*}Y) - 2d\sigma(X,Y)\}\xi. \end{array}$$

4. Recurrent and Lie recurrent lightlike hypersurfaces

Definition. The structure tensor field F of M is said to be *recurrent* [13] if there exists a 1-form ϖ on TM such that

$$(\nabla_X F)Y = \varpi(X)FY.$$

A lightlike hypersurface M of an indefinite Kaehler manifold \overline{M} is called *recurrent* if it admits a recurrent structure tensor field F.

Theorem 4.1. Let M be a recurrent lightlike hypersurface of an indefinite Kaehler manifold \overline{M} with a non-metric ϕ -symmetric connection. Then

- (1) the characteristic vector field ζ on \overline{M} is tangent to M, i.e., b = 0,
- (2) F is parallel with respect to the induced connection ∇ on M,
- (3) the 1-form θ vanishes, i.e., $\theta = 0$, on M,
- (4) D and J(tr(TM)) are parallel distributions on M, and
- (5) *M* is locally a product manifold $C_{U} \times M^{\sharp}$, where C_{U} is a null curve tangent to J(tr(TM)) and M^{\sharp} is a leaf of the distribution *D*.

Proof. (1) From the above definition and (3.16), we get

(4.1)
$$\varpi(X)FY = u(Y)A_NX - B(X,Y)U + \theta(Y)X + \theta(JY)FX.$$

Replacing Y by ξ and using $(3.6)_1$ and the fact that $F\xi = -V$, we get

$$\varpi(X)V = bu(X)U - bX + \theta(V)FX.$$

Taking the scalar product with N to this equation, we obtain

$$b\eta(X) - \theta(V)v(X) = 0.$$

Taking $X = \xi$ and then X = V to this equation, we have

 $b = 0, \qquad \theta(V) = 0.$

As b = 0, the characteristic vector field ζ on \overline{M} is tangent to M.

(2) As b = 0 and $\theta(V) = 0$, we see that $\varpi(X)V = 0$. Taking the scalar product with U to this result, we get $\varpi = 0$. It follows that $\nabla_X F = 0$. Thus F is parallel with respect to the induced connection ∇ on M.

(3) Taking the scalar product with N to (4.1) and using $(3.10)_2$, we have

$$- au(Y)v(X) + \theta(Y)\eta(X) + \theta(JY)v(X) = 0.$$

Replacing X by ξ to this equation, we obtain

(4.2)
$$\theta(X) = 0, \quad \forall X \in \Gamma(TM).$$

(4) Taking the scalar product with V to (4.1) and using (4.2), we get

$$B(X,Y)=u(Y)u(A_{\scriptscriptstyle N}X)$$

Taking Y = V and Y = FZ, $Z \in \Gamma(D_o)$ to this equation by turns and using the fact that u(FZ) = 0 as $FZ = JZ \in \Gamma(D_o)$, we have

(4.3)
$$B(X,V) = 0, \qquad B(X,FZ) = 0.$$

In general, by using (2.11), (3.1), (3.4), $(3.5)_{1,3}$, (3.8) and (3.15), we derive

$$\begin{split} g(\nabla_X \xi, V) &= -B(X, V) + \theta(V)u(X), \qquad g(\nabla_X V, V) = 0\\ g(\nabla_X Z, V) &= B(X, FZ) - \theta(FZ)u(X), \qquad \forall Z \in \Gamma(D_o), \end{split}$$

due to u(Z) = v(Z) = 0. From these equations, (4.2) and (4.3), we see that

$$\nabla_X Y \in \Gamma(D), \quad \forall X \in \Gamma(TM), \quad \forall Y \in \Gamma(D)$$

It follows that D is a parallel distribution on M.

On the other hand, taking Y = U to (4.1) and using (4.2), we have

Applying F to (4.4) and using the facts that FU = 0 and $\theta(U) = 0$, we get

$$F(A_N X) = aX - au(X)U.$$

Using this, (3.11) and the fact that $\theta = 0$, (3.14) is reduced to

(4.5)
$$\nabla_X U = \sigma(X) U$$

It follows that J(tr(TM)) is also a parallel distribution on M, *i.e.*,

$$\nabla_X U \in \Gamma(J(tr(TM))), \quad \forall X \in \Gamma(TM).$$

(5) As D and J(tr(TM)) are parallel distributions satisfying (2.7), by the decomposition theorem [5], M is locally a product manifold $\mathcal{C}_U \times M^{\sharp}$, where \mathcal{C}_U is a null curve tangent to J(tr(TM)) and M^{\sharp} is a leaf of D.

Definition. The structure tensor field F of M is said to be *Lie recurrent* [13] if there exists a 1-form ϑ on M such that

$$(\mathcal{L}_{x}F)Y = \vartheta(X)FY,$$

where \mathcal{L}_{X} denotes the Lie derivative on M with respect to X, that is,

(4.6)
$$(\mathcal{L}_X F)Y = [X, FY] - F[X, Y].$$

The structure tensor field F is called *Lie parallel* if $\mathcal{L}_{X}F = 0$. A lightlike hypersurface M of an indefinite Kaehler manifold \overline{M} is called *Lie recurrent* if it admits a Lie recurrent structure tensor field F.

Theorem 4.2. Let M be a Lie recurrent lightlike hypersurface of an indefinite Kaehler manifold \overline{M} with a non-metric ϕ -symmetric connection. Then

- (1) F is Lie parallel,
- (2) the 1-forms τ and σ satisfy $\tau = au$ and $\sigma = -bv$, and
- (3) the shape operator A_{ξ}^* satisfies $A_{\xi}^*U = A_{\xi}^*V = 0$.

Proof. (1) Using the above definition, (2.9), (2.10), (3.2) and (3.16), we get

(4.7)
$$\vartheta(X)FY = -\nabla_{FY}X + F\nabla_YX + u(Y)A_NX - B(X,Y)U + au(Y)FX + \theta(Y)u(X)U.$$

Taking $Y = \xi$ to (4.7) and using (3.6)₁ and the fact that $F\xi = -V$, we have (4.8) $-\vartheta(X)V = \nabla_V X + F\nabla_{\xi} X.$

Taking the scalar product with V to (4.8) and using g(FX, V) = 0, we have

(4.9)
$$u(\nabla_V X) = g(\nabla_V X, V) = 0.$$

Replacing Y by V to (4.7) and using the fact that $FV = \xi$, we have

$$\vartheta(X)\xi = -\nabla_{\xi}X + F\nabla_{V}X - B(X,V)U + \theta(V)u(X)U.$$

Applying F to this equation and using (3.11) and (4.9), we obtain

$$\vartheta(X)V = \nabla_V X + F\nabla_\xi X$$

Comparing this equation with (4.8), we get $\vartheta = 0$. Thus F is Lie parallel.

(2) Taking the scalar product with N to (4.7) and using $(3.10)_2$, we have

(4.10)
$$-\bar{g}(\nabla_{FY}X,N) + \bar{g}(F\nabla_{Y}X,N) = 0$$

Replacing X by V to (4.10) and using (2.10) and (3.15), we have

$$g(A_{\varepsilon}^*FY, U) + \sigma(Y) = 0.$$

Taking X = FY and Y = U to (3.8) and using (3.5)₄ and (3.11), we have $B(FY, U) = -\tau(Y) + au(Y).$

Replacing Y by U to this and using the fact that FU = 0, we obtain (4.11) $\tau(U) = a$.

Replacing X by ξ to (4.10) and using (2.6), (2.8) and (2.10), we have

$$g(A_{\varepsilon}^*X, U) = \sigma(FX).$$

Taking Y = U to (3.8) and using the last equation, (3.5)₄, (3.11), (4.11) and the facts that $v(FX) = -\eta(X)$ and u(FX) = 0, we have

(4.12)
$$B(X,U) = \tau(FX) + \theta(U)u(X).$$

From this equation and (3.13), we see that

(4.13)
$$u(A_N X) = \tau(FX)$$

Replacing X by U to (4.7) and using (2.10), (3.3) and (3.14), we get

$$u(Y)A_{N}U - F(A_{N}FY) - A_{N}Y - \tau(FY)U = 0.$$

Taking the scalar product with V and using (4.13), we get

$$\tau(FY) = 0.$$

Taking Y = FX to this and using (2.10), (4.11) and then, (3.11), we have

$$\tau(X) = au(X), \qquad \sigma(X) = -bv(X).$$

(3) Replacing Y by U to (3.3) and using (4.12), we have

$$(4.14) B(U,X) = \theta(X)$$

Taking X = U to (3.8) and using (4.14), we have $g(A_{\xi}^*U, X) = 0$, As S(TM) is non-degenerate, we get $A_{\xi}^*U = 0$. Replacing X by ξ to (4.8) and using (2.6), (3.12) and the facts that $F\xi = V$ and $\sigma(X) = -bv(X)$, we obtain $A_{\xi}^*V = 0$. \Box

5. Indefinite complex space forms

An indefinite complex space form $\overline{M}(c)$ is a connected indefinite Kaehler manifold of constant holomorphic sectional curvature c such that

(5.1)
$$\bar{R}(\bar{X},\bar{Y})\bar{Z} = \frac{c}{4} \{ \bar{g}(\bar{Y},\bar{Z})\bar{X} - \bar{g}(\bar{X},\bar{Z})\bar{Y} + \bar{g}(J\bar{Y},\bar{Z})J\bar{X} - \bar{g}(J\bar{X},\bar{Z})J\bar{Y} + 2\bar{g}(\bar{X},J\bar{Y})J\bar{Z} \}.$$

Comparing the tangential and transversal components of the two equations (3.19) and (5.1), and using (2.9) and (3.2), we get

(5.2)
$$R(X,Y)Z = B(Y,Z)A_{N}X - B(X,Z)A_{N}Y + \frac{c}{4}\{g(Y,Z)X - g(X,Z)Y + \bar{g}(JY,Z)FX - \bar{g}(JX,Z)FY + 2\bar{g}(X,JY)FZ\},$$

(5.3)
$$(\nabla_X B)(Y,Z) - (\nabla_Y B)(X,Z) + \tau(X)B(Y,Z) - \tau(Y)B(X,Z) - \theta(X)B(FY,Z) + \theta(Y)B(FX,Z)$$

$$= \frac{c}{4} \{ u(X)g(FY,Z) - u(Y)g(FX,Z) + 2u(Z)\bar{g}(X,JY) \}.$$

Taking the scalar product with N to (3.21) and then, substituting (5.2) into the resulting equation and using (2.9), (3.2) and $(3.10)_2$, we obtain

$$(5.4) \qquad (\nabla_X C)(Y, PZ) - (\nabla_Y C)(X, PZ) - \sigma(X)C(Y, PZ) + \sigma(Y)C(X, PZ) - \theta(X)C(FY, PZ) + \theta(Y)C(FX, PZ) + a\{v(X)B(Y, PZ) - v(Y)B(X, PZ)\} = \frac{c}{4}\{\eta(X)g(Y, PZ) - \eta(Y)g(X, PZ) + v(X)g(FY, PZ) - v(Y)g(FX, PZ) + 2v(PZ)\bar{g}(X, JY)\}.$$

Theorem 5.1. Let M be a recurrent lightlike hypersurface of an indefinite complex space form $\overline{M}(c)$ with a non-metric ϕ -connection. Then $\overline{M}(c)$ is flat, i.e., c = 0, and the 1-form σ is closed, i.e., $d\sigma = 0$ on M. Moreover, there exists a null pair $\{\xi, N\}$ on a coordinate neighborhood \mathcal{U} such that the corresponding 1-forms σ and τ satisfy $\sigma = 0$ and $\tau = au$.

Proof. Taking the scalar product with U to (4.4) and using (3.9), we have

$$C(X,U) = 0,$$

due to $(3.5)_4$ and $\theta = 0$. Applying ∇_Y to this and using (4.5), we get

$$(\nabla_X C)(Y,U) = 0.$$

Replacing PZ by U to (5.4) and using the last two equations, we obtain

(5.5)
$$a\{B(Y,U)v(X) - B(X,U)v(Y)\} = \frac{c}{2}\{v(Y)\eta(X) - v(X)\eta(Y)\}.$$

Taking Y = V to (3.3) and using (4.3)₁ and the fact that $\theta = 0$, we have (5.6) B(V, X) = 0.

Taking $X = \xi$ and Y = V to (5.5) and using (3.6)₂ and (5.6), we get c = 0. As c = 0, taking Y = V to (5.5) and using (5.6), we have

$$aB(X,U) = 0.$$

Substituting (4.4) into (5.2) and using (4.2) and the last equation, we get

$$R(X, Y)U = 0.$$

On the other hand, by directed calculations from (4.5), we obtain

$$R(X,Y)U = 2d\sigma(X,Y)U.$$

Comparing the last two equations, we have $d\sigma = 0$.

As $d\sigma = 0$, there exists a smooth function f on \mathcal{U} such that $\sigma = df$. Thus $\sigma(X) = X(f)$. If we take $\bar{\xi} = \alpha\xi$, then $\bar{N} = (1/\alpha)N$ and $\sigma(X) = \bar{\sigma}(X) + X(\ln \alpha)$. Setting $\alpha = \exp(f)$ in this equation, we get $\bar{\sigma} = 0$. Therefore, there exists a null pair $\{\xi, N\}$ on \mathcal{U} such that $\sigma = 0$ and τ satisfies $\tau = au$.

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Theorem 5.2. Let M be a Lie recurrent lightlike hypersurface of an indefinite complex space form $\overline{M}(c)$ with a non-metric ϕ -symmetric connection. Then $c = 4\{ab - Ub\}.$

Proof. Replacing Z by
$$\xi$$
 to (5.2) and then, comparing with (3.22), we have

$$\begin{split} &-\nabla_X^*(A_{\xi}^*Y) + \nabla_Y^*(A_{\xi}^*X) + A_{\xi}^*[X,Y] - \sigma(X)A_{\xi}^*Y + \sigma(Y)A_{\xi}^*X \\ &+ \{C(Y,A_{\xi}^*X) - C(X,A_{\xi}^*Y) - 2d\sigma(X,Y)\}\xi \\ &= b\{u(Y)A_{_N}X - u(X)A_{_N}Y\} + \frac{c}{4}\{u(Y)FX - u(X)FY - 2\bar{g}(X,JY)V\}, \end{split}$$

due to $(3.6)_1$. Taking the scaler product with N, we obtain $C(Y, A_{\xi}^*X) - C(X, A_{\xi}^*Y) - 2d\sigma(X, Y) = \{ab - c/4\}\{u(X)v(Y) - u(Y)v(X)\}.$ Taking X = U and Y = V to this and using (3) of Theorem 4.2, we get $2d\sigma(U, V) = -ab + c/4.$

By directed calculation from $\sigma(X) = -bv(X)$, (3.2) and (3.18), we derive

$$\begin{split} 2d\sigma(X,Y) &= -(Xb)v(Y) + (Yb)v(X) + ab\{u(X)v(Y) - u(Y)v(X)\} \\ &+ b\{v(X)\tau(Y) - v(Y)\tau(X) + g(A_{_N}X,FY) - g(A_{_N}Y,FX)\}. \end{split}$$

Taking X = U and Y = V to this equation and using (4.11), we get

$$2d\sigma(U,V) = -Ub,$$

due to $FV = \xi$ and FU = 0. Thus we have $c = 4\{ab - Ub\}$.

Corollary 5.3. Let M be a Lie recurrent lightlike hypersurface of $\overline{M}(c)$ with a non-metric ϕ -symmetric connection. If b = 0, then c = 0 and $\overline{M}(c)$ is flat.

Definition. A screen distribution S(TM) is called *totally umbilical* [6] in M if there exists a smooth function γ on a coordinate neighborhood \mathcal{U} such that

$$C(X, PY) = \gamma g(X, Y).$$

In case $\gamma = 0$, we say that S(TM) is totally geodesic in M.

Theorem 5.4. Let M be a lightlike hypersurface of an indefinite complex space form $\overline{M}(c)$ with a non-metric ϕ -connection. If S(TM) is totally umbilical, then

 $c = 4\gamma \theta(V).$

Moreover, if S(TM) is totally geodesic in M, then c = 0.

Proof. From (3.3) and (3.13), we see that

(5.7)
$$B(U,V) = 0, \qquad B(V,U) = -\theta(V).$$

Applying ∇_X to $C(Y, PZ) = \gamma g(Y, PZ)$ and using (3.1) and (3.4), we get $(\nabla_X C)(Y, PZ) = (X\gamma)g(Y, PZ)$

$$+\gamma\{B(X, PZ)\eta(Y) - \theta(Y)g(FX, PZ) - \theta(PZ)\phi(X, Y)\}.$$

Substituting this equation into (5.4), we obtain

$$\begin{split} &\{X\gamma - \gamma\sigma(X)\}g(Y,PZ) - \{Y\gamma - \gamma\sigma(Y)\}g(X,PZ) \\ &+ \{\gamma\eta(Y) - av(Y)\}B(X,PZ) - \{\gamma\eta(X) - av(X)\}B(Y,PZ) \\ &- 2\gamma\theta(PZ)\phi(X,Y) \\ &= \frac{c}{4}\{\eta(X)g(Y,PZ) - \eta(Y)g(X,PZ) + v(X)g(FY,PZ) \\ &- v(Y)g(FX,PZ) + 2v(PZ)\bar{g}(X,JY)\}. \end{split}$$

Replacing X by ξ to this and using $(3.5)_1$ and $(3.6)_2$, we have

$$\{\xi\gamma - \gamma\sigma(\xi)\}g(Y, PZ) - \gamma B(Y, PZ) + 2\gamma\theta(PZ)u(Y)$$
$$= \frac{c}{4}\{g(Y, PZ) + v(Y)u(PZ) + 2u(Y)v(PZ)\}.$$

Taking Y = U, PZ = V and Y = V, PZ = U by turns and using (5.7), we get

$$\xi\gamma - \gamma\sigma(\xi) = -2\gamma\theta(V) + \frac{3}{4}c, \qquad \xi\gamma - \gamma\sigma(\xi) = -\gamma\theta(V) + \frac{2}{4}c.$$

From these two equations, we have $c = 4\gamma\theta(V)$.

Definition. A lightlike hypersurface M is called *screen conformal* [10] if there exists a non-vanishing smooth function φ on a neighborhood \mathcal{U} such that

$$C(X, PY) = \varphi B(X, Y).$$

Theorem 5.5. Let M be a screen conformal lightlike hypersurface of an indefinite complex space form $\overline{M}(c)$ with a non-metric ϕ -connection. Then c = 0.

Proof. Applying ∇_X to $C(Y, PZ) = \varphi B(Y, PZ)$, we have

$$(\nabla_X C)(Y, PZ) = (X\varphi)B(Y, PZ) + \varphi(\nabla_X B)(Y, PZ).$$

Substituting this equation into (5.4) and using (5.3), we obtain

$$\begin{split} &\{X\varphi - \varphi\tau(X) - \varphi\sigma(X) + av(X)\}B(Y,PZ) \\ &- \{Y\varphi - \varphi\tau(Y) - \varphi\sigma(Y) + av(Y)\}B(X,PZ) \\ &= \frac{c}{4}\{\eta(X)g(Y,PZ) - \eta(Y)g(X,PZ) \\ &+ [v(X) - \varphi u(X)]g(FY,PZ) - [v(Y) - \varphi u(Y)]g(FX,PZ) \\ &+ 2[v(PZ) - \varphi u(PZ)]\bar{g}(X,JY)\}. \end{split}$$

Replacing X by ξ to this equation and using (3.6)₂ and (3.11), we have

(5.8)
$$\{\xi\varphi - 2\varphi\tau(\xi)\}B(Y, PZ)$$

= $\frac{c}{4}\{g(Y, PZ) + [v(Y) - \varphi u(Y)]u(PZ) + 2[v(PZ) - \varphi u(PZ)]u(Y)\}.$

Taking Y = U, PZ = V and Y = V, PZ = U to this by turns, we get

$$\{\xi\varphi - 2\varphi\tau(\xi)\}B(U,V) = 3c/4, \qquad \{\xi\varphi - 2\varphi\tau(\xi)\}B(V,U) = 2c/4.$$

As $B(U, V) = B(V, U) + \theta(V)$ by (3.3), we have

(5.9)
$$\{\xi\varphi - 2\varphi\tau(\xi)\}\theta(V) = c/4.$$

Now we set $\mu = U - \varphi V$. From (3.13), we see that

$$B(X,\mu) = \theta(U)u(X) - \theta(V)v(X).$$

Taking X = V to this equation, we obtain

$$B(V,\mu) = -\theta(V).$$

Taking Y = V and $PZ = \mu$ to (5.8) and using the last equation, we have

$$\{\xi\varphi - 2\varphi\tau(\xi)\}\theta(V) = -2c/4.$$

From this equation and (5.9), we obtain c = 0.

Theorem 5.6. Let M be a lightlike hypersurface of an indefinite complex space form $\overline{M}(c)$ with a non-metric ϕ -symmetric connection. If V or U is parallel with respect to the induced connection ∇ on M, then c = 0.

Proof. (1) If U is parallel with respect to ∇ , then, from (3.14), we have

$$F(A_N X) + \tau(X)U - aX + \theta(U)FX = 0.$$

Taking the scalar product with N to this equation and using (3.9), we get

$$C(X,U) = 0.$$

Applying ∇_X to C(Y, U) = 0 and using the fact that $\nabla_X U = 0$, we have

$$(\nabla_X C)(Y, U) = 0.$$

Replacing PZ by U to (5.4) and using the last two equations, we obtain

$$a\{B(Y,U)v(X) - B(X,U)v(Y)\} = \frac{c}{2}\{v(Y)\eta(X) - v(X)\eta(Y)\}.$$

Taking $X = \xi$ and Y = V and using $(3.6)_2$, we have c = 0.

(2) If V is parallel with respect to ∇ , then, from (3.15), we have

$$F(A_{\xi}^*X) - \sigma(X)V + bu(X)U - bX + \theta(V)FX = 0.$$

Taking the scalar product with N to this and using (3.8) and (3.13), we have

$$C(X,V) = 0$$

Applying ∇_X to C(Y, V) = 0 and using the fact that $\nabla_X V = 0$, we have $(\nabla_X C)(Y, V) = 0.$

Replacing PZ by V to (5.4) and using the last two equations, we obtain

$$a\{B(Y,V)v(X) - B(X,V)v(Y)\} = \frac{c}{4}\{u(Y)\eta(X) - u(X)\eta(Y) + 2\bar{g}(X,JY)\}.$$

Taking $X = \xi$ and $Y = U$ and using (3.6)₂, we have $c = 0$.

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