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## 이중 배경 모델을 이용한 급격한 조명 변화에서의 전경 객체 검출

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# Detecting Foreground Objects Under Sudden Illumination Change Using Double Background Models

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### 요 약

배경 모델과 배경 차분화로 구성되어 있는 전경객체 추출은 다양한 컴퓨터 비전 응용에서 중요한 기능이다. 조명 변화를 고려하지 않은 기존 방법들은 급격한 조명 변화에서는 성능이 저하된다. 본 레터에서는 이 문제를 해결할 수 있는 조명 변화에 강인한 배경 모델링 방법을 제안한다. 제안 방법은 다른 적응률을 가진 두 개의 배경 모델을 사용함으로써 조명 조건에 신속하게 적응할 수 있다. 본 논문의 제안 방법은 non-parametric 기법으로서 실험에서는 기존 non-parametric 기법들보다 우수한 성능 및 낮은 복잡도를 보여줌을 증명하였다.

### Abstract

In video sequences, foreground object detection being composed of a background model and a background subtraction is an important part of diverse computer vision applications. However, object detection might fail in sudden illumination changes. In this letter, an illumination-robust background detection is proposed to address this problem. The method can provide quick adaption to current illumination condition using two background models with different adaption rates. Since the proposed method is a non-parametric approach, experimental results show that the proposed algorithm outperforms several state-of-art non-parametric approaches and provides low computational cost.

Keyword : background modeling, foreground detection, illumination change, double backgrounds

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## I . Introduction

In general, foreground object detection consists of a background modeling as well as a background subtraction in video frames. A major challenge to accurate foreground detection is a sudden illumination change in the scene. In these situations, the background is no longer stable and

could be mistakenly classified as the foreground yielding false positives. Conventional background modeling belongs to either parametric or non-parametric approach. In both, current pixels varying significantly from the background image are chosen as foreground pixels<sup>[1-4]</sup>.

The performance of a foreground detection highly depends on a reliable background model. The state-of-art methods<sup>[5-11]</sup> are mostly devised for gradual illumination changes and fail to handle sudden changes such as light on/off. Illumination change condition (ICC) can affect the performance of the foreground object detection due to many false alarms and may lead to a system malfunction.

In this letter, a non-parametric background modeling employing double backgrounds as well as illumination compensation is proposed. Two main functionalities are the utilization of double backgrounds as well as the fast compensation of them to new illumination condition. Fig. 1 shows the overall flow of the proposed method.

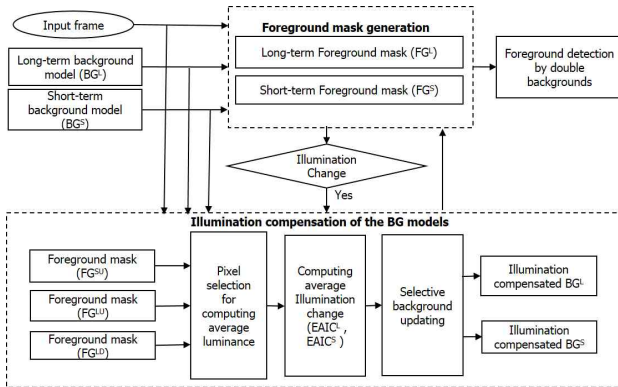


그림 1. 제안방법의 전체 블록도  
 Fig. 1. The overall block diagram of the proposed method.

## II. Proposed Method

The illumination-robust foreground detection uses two background models with slow and fast adaption speeds. Let  $BG_t^L$  and  $BG_t^S$  denote long-term background model

(LTBM) and short-term background model (STBM), respectively. Comparing  $i$ th pixel of  $t$ -th frame  $I_t(i)$  with the LTBM, a foreground binary mask  $FG_t^L$  is obtained as

$$FG_t^L(i) = \begin{cases} 1, & \text{if } |I_t(i) - BG_t^L(i)| > T_L \\ 0, & \text{otherwise} \end{cases} \quad (1)$$

where  $T_L$  is the long-term background threshold. Similar thresholding method is performed for the STBM  $BG_t^S$  with a threshold  $T_S$  resulting in a binary mask  $FG_t^S$ . Since  $BG_t^S$  is used to extract all pixels with significant temporal activities, a smaller threshold is chosen ( $T_S=0.4T_L$ ).  $T_L=50$ ,  $T_S=20$  are used in experiments.

Current LTBM is updated by integrating a current frame  $I_t(i)$  into a previous model  $BG_{t-1}^L$  and is computed by

$$BG_t^L(i) = \alpha_L I_t(i) + (1 - \alpha_L) BG_{t-1}^L(i) \quad (2)$$

where  $\alpha_L$  is an adaption parameter. Similarly, a STBM is computed using an adaption parameter  $\alpha_S$ .

Double backgrounds are utilized for ICC. The proposed method evaluates the responses of STBM and LTBM using the following thresholds:

- 1)  $T_{LU}=2T_L$ : Using this threshold, pixels that are changed drastically from the LTBM are extracted as foreground pixels whose binary mask is  $FG_t^{LU}$ .
- 2)  $T_{SU}=2T_S$ : This threshold is used to obtain a foreground mask  $FG_t^{SU}$  from STBM with less false detection than  $FG_t^S$ .

The proposed updating strategy is used only in ICC, where the ratio of the number of foreground and background pixels of  $FG_t^S$  is higher than a threshold  $T_R$ . The updating process consists of computing average illumination change followed by illumination compensation of background models.

(a) Average illumination change: In order to estimate the amount of illumination change, the difference between  $m(BG_t^L)$  and  $m(BG_t^S)$  is computed using some selected pixels, where  $m(\bullet)$  is a mean value of  $(\bullet)$ . Based on the responses of them, we exclude two pixel groups that are not suitable for average computation. *Estimated average illumination change* (EAIC) of the current frame from the STBM and LTBM are calculated by

$$\begin{aligned} EAIC_t^L &= m(I_t) - m(BG_t^L) \\ EAIC_t^S &= m(I_t) - m(BG_t^S) \end{aligned} \quad (3)$$

(b) Illumination compensation: The aim of per-pixel illumination compensation is to update the pixel values by using EAIC as a gain value, however, some pixels may not show a considerable change. Thus, the pixels are divided into two categories for updating:

- $|I_t(i) - BG_{t-1}(i)| < EAIC$ : The current pixels that are changed by less than average or remained unchanged are not updated. For this, an adaptive parameter  $\beta_d$  is computed for each pixel according to the distance of the current pixel from its co-located background pixel ( $I_t(i) - BG_{t-1}(i)$ ). Using  $\beta_d$ , the LTBM is updated by

$$\begin{aligned} BG_t^L(i) &= BG_{t-1}^L(i) + \beta_d(i)(I_t(i) - BG_{t-1}^L(i)) \\ \beta_d(i) &= (\beta_{EAIC} - 1) \left| \frac{I_t(i) - BG_{t-1}^L(i)}{EAIC_t^L} \right| + \beta_0 \end{aligned} \quad (4)$$

where  $\beta_0$  is set to 1 and  $\beta_{EAIC}$  to 0.5 in experiments.

- $|I_t(i) - BG_{t-1}(i)| \geq EAIC$ : For pixels changed more than EAIC, the LTBM is updated by a constant gain by

$$\begin{aligned} &BG_t^L(i) \\ &= \begin{cases} BG_{t-1}^L(i) + \beta_{EAIC} \cdot EAIC_t^L, & \text{if } BG_{t-1}^L(i) < I_t(i) \\ BG_{t-1}^L(i) - \beta_{EAIC} \cdot EAIC_t^L, & \text{if } BG_{t-1}^L(i) > I_t(i) \end{cases} \end{aligned} \quad (5)$$

The selective updating methodology is similarly performed for STBM. From the updated background, a final foreground

mask  $FG_t(i)$  is obtained by  $FG_t^L(i) \cdot FG_t^S(i)$ .

### III. Experimental Results

The performance of the proposed system is compared with five foreground detections methods; Double backgrounds (DBG)<sup>[9]</sup>, Eigen background<sup>[4]</sup>, MoG<sup>[5]</sup>, KDE<sup>[2]</sup> and ViBe<sup>[6]</sup>. In *Seq1*, there are no moving objects during illumination change and humans enter a room after sudden changes while in two other sequences, moving humans exist during subsequent illumination changes. First we examined the performance of the algorithms during sudden illumination change in terms of FP (false positive) and TP (true positive) rates. The accuracy of foreground binary mask is evaluated through use of Recall=TP/(TP+FN) and Precision=TP/(TP+FP). F-score compares the binary masks with ground truth (GT).

표 1. 비교 방법들과의 성능 비교

Table 1. Performance comparison of different methods

Method	F-score		
	Seq1	Seq2	Seq3
Eigen	0.509	0.280	0.150
MoG	0.647	0.414	0.313
KDE	0.203	0.113	0.096
ViBe	0.276	0.229	0.158
DBG	0.614	0.508	0.480
Proposed	0.896	0.754	0.719

Table 1 compares the overall performance of the proposed algorithm with other methods in three sequences. As shown in the Table, our proposed approach significantly outperforms five methods in all sequences. The proposed method is able to detect the moving objects with high accuracy in three sequences and shows an acceptable performance. Fig. 2 shows the resulting foreground objects detected by five comparative methods and the proposed. The results show that our method outperforms other methods. The processing speed of the proposed method is

faster than that of other approaches except DBG (with 218 fps vs. 145 fps of Eigen BG, 71 fps of MoG, 66 fps of ViBe, 42 fps of KDE and 296 fps of DBG for Seq3).

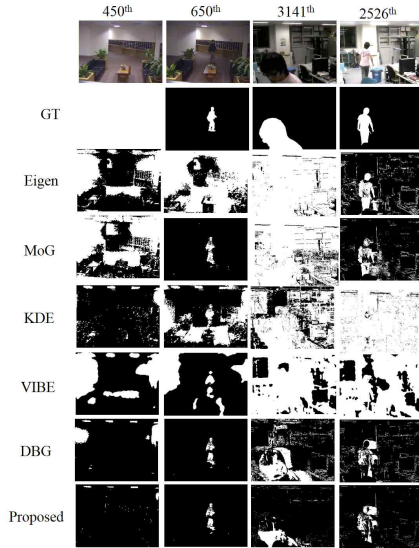


그림 2. 5개의 비교방법과 제안방법으로 추출된 전경객체. GT는 ground truth  
 Fig. 2. Foreground objects extracted by five comparative methods and the proposed method. GT=ground truth

Algorithms such as Eigen background and ViBe cannot adapt as fast as other methods like MoG to new illumination condition due to their updating methodology. Our method can be adapted to the background models to the new illumination condition right after the illumination has occurred. The most important part is the illumination compensation of the background models with an appropriate gain value of EAIC. First, we compute the amount of illumination change with high accuracy by choosing the effective pixels. Then a pixel-selective background updating is performed. For updating, a correct gain value is assigned to each pixel. The fast background compensation by assigning a correct compensation gain value to each pixel of the background model is very important.

## V. Conclusion

A novel foreground detection was proposed that can address the illumination change problem. The algorithm utilizes two background models with slow and fast adaptation rates for accurate illumination compensation. The proposed method delivers promising detection results in sudden illumination change and outperforms several state-of-art methods.

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