# Remarks on correlated error tests<sup>†</sup>

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## Abstract

The Durbin-Watson (DW) test in regression model and the Ljung-Box (LB) test in ARMA (autoregressive moving average) model are typical examples of correlated error tests. The DW test is used for detecting autocorrelation of errors using the residuals from a regression analysis. The LB test is used for specifying the correct ARMA model using the first some sample autocorrelations based on the residuals of a fitted ARMA model. In this article, simulations with four data generating processes have been carried out to evaluate their performances as correlated error tests. Our simulations show that the DW test is severely dependent on the assumed AR(1) model but isn't sensitive enough to reject the misspecified model and that the LB test reports lackluster performance in general.

Keywords: Correlated error, Durbin-Watson test, Ljung-Box test, model specification.

### 1. Introduction

In a regression model, a basic assumption is that error terms in the regression model are independent. When this assumption-among others-is satisfied, the regression function recovery procedure such as least square method is valid and a great deal of its use has been made. In other words, it might be said that the regression function recovery procedures are eventually meant to recover the independence of residuals. Along this line of argument, whether the residuals after a given model fitting achieves independence has been regarded as a critical step for proper model specification. There have been two popular methods checking residual independence in the literatures; the Durbin-Watson (DW) test in linear regression model and the Ljung-Box (LB) test in ARMA (autoregressive moving average) model (Ljung and Box, 1978). The DW test is established in the residuals from a regression analysis. The small sample distribution of this test was derived by on Neumann (1941) under the null. Durbin and Watson (1950, 1951) applied this test to the residuals from least square regressions, and developed a bound test for the null hypothesis that the errors are serially uncorrelated against the alternative that they follow a first order autoregressive process. The LB test is commonly used in ARMA modeling. It is applied to the residuals

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of a fitted ARMA model, not the original series, and in such applications the hypothesis actually being tested is that the residuals from the ARMA model have no autocorrelation. Since autocorrelation makes the underlying model difficult to discern, various efforts have been conducted (Hwang, 2014; Ha, 2015).

The DW test calculates its asymptotic distribution under AR(1) error assumption while the LB test calculates the null distributions under the iid error. For the LB test, it has been frequently noticed that asymptotic distribution has less variance than expected. See, for instance, Pena and Rodriguez (2002).

In this article, we are mainly concerned about investigating the strength or weakness of these two tests via simulations. Section 2 discusses the DW test and the LB test separately. Section 3 provides simulation works supporting our findings.

## 2. Correlated error tests

#### 2.1. Durbin-Watson test

To derive a suitable test criterion, it is important to consider the set of alternative hypotheses against which it is desired to discriminate. The concerning alternative for DW test is the stationary Markov process

$$\epsilon_i = \rho \epsilon_{i-1} + u_i \ (i = \cdots, -1, 0, 1, \cdots) \tag{2.1}$$

where  $|\rho| < 1$  and  $u_i$  is normal with mean zero and variance  $\sigma_u^2$  and is independent of  $u_{i-1}, u_{i-2}, \cdots$ . The null hypothesis is then the hypothesis that  $\rho = 0$  in (2.1). It is known that for certain regression problems with error distributions close to that given by (2.1) tests can be obtained which are uniformly most powerful against one-sided alternatives and which give regions for two-sided alternatives. The DW is derived based on such theoretical background (Durbin and Watson, 1950; 1951).

To test for positive autocorrelation at significance level  $\alpha$ , that is  $H_0: \rho = 0$  versus  $H_1: \rho > 0$ , the test statistic which is calculated by the residuals  $\{e_i\}$ 

$$d_n = \frac{\sum_{i=2}^{n} (e_i - e_{i-1})^2}{\sum_{i=1}^{n} e_i^2}$$

is compared to lower and upper critical values  $(d_{L,\alpha}^{(n)}$  and  $d_{U,\alpha}^{(n)})$ :

- If  $d_n < d_{L,\alpha}^{(n)}$ , there is statistical evidence that the error terms are positively autocorrelated.
- If  $d_n > d_{U,\alpha}^{(n)}$ , there is no statistical evidence that the error terms are positively auto-correlated.
- If  $d_{L,\alpha}^{(n)} < d_n < d_{U,\alpha}^{(n)}$ , the test is inconclusive.

Positive serial correlation is serial correlation in which a positive error for one observation increases the chances of a positive error for another observation.

To test for negative autocorrelation at significance  $\alpha$ , that is  $H_0: \rho = 0$  versus  $H_1: \rho < 0$ , the test statistic  $(4 - d_n)$  is compared to lower and upper critical values  $(d_{L,\alpha}^{(n)})$  and  $d_{U,\alpha}^{(n)}$ :

- If  $(4-d_n) < d_{L,\alpha}^{(n)}$ , there is statistical evidence that the error terms are negatively autocorrelated.
- If  $(4 d_n) > d_{U,\alpha}^{(n)}$ , there is no statistical evidence that the error terms are negatively autocorrelated.
- If  $d_{L,\alpha}^{(n)} < (4 d_n) < d_{U,\alpha}^{(n)}$ , the test is inconclusive.

Negative serial correlation implies that a positive error for one observation increases the chance of a negative error for another observation and a negative error for one observation increases the chances of a positive error for another.

The critical values,  $d_{L,\alpha}^{(n)}$  and  $d_{U,\alpha}^{(n)}$  vary by the level of significance  $(\alpha)$ , number of observations, and number of predictors in the regression equation. Their derivation under the null is complex and statisticians typically obtain them from the appendices of statistical texts. Actually these two significance points or bounds are obtained by quite accurate approximation to the distribution of  $d_n$ . The bounds are known to be 'best' in two senses: first they can be attained, and secondly when they are attained the test criterion adopted is uniformly most powerful against suitable alternative hypotheses.

## 2.2. Ljung-Box test

Given a discrete time series  $Z_t, Z_{t-1}, Z_{t-2}, \cdots$  and using B for the backward shift operator such that  $BZ_t = Z_{t-1}$ , a general autoregressive integrated moving average (ARIMA) model of order (p, r, q) may be written

$$\phi(B)\nabla^r Z_t = \theta(B)\epsilon_t \tag{2.2}$$

where  $\phi(B) = 1 - \phi_1 B - \dots - \phi_p B^p$  and  $\theta(B) = 1 - \theta_1 B - \dots - \theta_q B^q$ ,  $\epsilon_t$  is a sequence of independent errors with common variance  $\sigma_u^2$ , to be referred to as 'white noise', and where the roots of  $\phi(B) = 0$  and  $\theta(B) = 0$  lie outside the unit circle. In other words, if  $X_t = \nabla^r Z_t = (1 - B)^r Z_t$ , is the rth difference of the series  $Z_t$ , then  $X_t$  is a stationary, invertible, mixed autoregressive moving average process given by

$$X_t = \sum_{i=1}^p \phi_i X_{t-i} - \sum_{j=1}^q \theta_j \epsilon_{t-j} + \epsilon_t$$
(2.3)

and permitting r > 0 allows the original series to be (homogeneously) nonstationary. In some instances the model (2.2) will be appropriate after a suitable transformation is made on Z; in others Z may represent the noise structure after allowing for some systematic model (Box and Pierce, 1970).

After a model of this form has been fitted to a series  $X_1, \dots, X_n$ , it is useful to study the adequacy of the fit by examining the residuals  $e_1, \dots, e_n$ , and, in particular, their autocorrelations

$$\hat{r}_k = \sum_{t=k+1}^n e_t e_{t-k} / \sum_{t=1}^n e_t^2 \quad (k=1,2,\cdots).$$

Note that  $\hat{r}_k$  is obtained as a least square estimator of  $r_k$  from

$$e_i = r_k e_{i-k} + u_i \ (i = \dots, -1, 0, 1, \dots, k = 1, 2, \dots)$$
 (2.4)

An informal graphical analysis of these quantities combined with overfitting is usually known to be most effective in detecting possible deficiencies in the model. Furthermore, it is known that when the p+q parameters of an appropriate model are estimated, then under the null hypothesis for the autocorrelations of  $\{\epsilon_t\}$ , that is,  $\rho_1 = \rho_2 = \cdots = \rho_m = 0$ ,

$$Q_n(\hat{r}) = n(n+2) \sum_{k=1}^m (n-k)^{-1} \hat{r}_k^2 \implies \chi_{m-p-q}^2$$
 (2.5)

yielding an approximate test for lack of fit. Note that asymptotic distribution derivation of  $Q_n(\hat{r})$  does not depend on the estimation method employed for ARIMA.

## 3. Simulation

In this section we perform simulations in order to see the behavior of the test statistics as a measure for model specification. That is, null hypothesis is the imposed model explains the DGP correctly rather than the original hypothesis of DW and LB. Our simulation results will provide useful insights into error correlation test problems. Basically we are concerned in applying and comparing two error correlation tests; DW test  $d_n$  and LB test  $Q_n$ . We set m in  $Q_n$  as a minimum of 10 and half of the sample size, which is large enough to cover the order of autocorrelation concerned.

We consider four cases and each cases are summarized in Table 3.1. (i) linear regression model is correctly imposed but data generating process (DGP) is contaminated with correlated errors (Table 3.2). (ii) linear regression model is wrongly imposed when DGP is generated by a quadratic function plus error (Table 3.3). (iii) AR(1) model is correctly imposed on the underlying DGP (Table 3.4). (iv) AR(1) model is wrongly imposed on the underlying DGP (Table 3.5).

In view of model specification we consider that (i) and (iii) are the cases when null hypothesis holds and that (ii) and (iv) are the cases when alternative hypothesis holds. From the relation with DGP and imposed model, Tables 3.2 and 3.3 report the cases where DW is expected to function and Tables 3.4 and 3.5 report the cases where LB is expected to function. We use R 3.1.2 and experimental simulations are repeated 1000 times at sample size n = 10, 30, 50 and 100 in each case.

Table 3.1 DGP and imposed model for each case.

	DGP	Imposed model
(i)	$Y_t = 1 + 2x_t + \epsilon_t \text{ with } \epsilon_t = \phi \epsilon_{t-1} + u_t$	$Y_t = a + bx_t + \epsilon_t$
(ii)	$Y_t = 1 - x_t + x_t^2 + u_t$	$Y_t = a + bx_t + \epsilon_t$
(iii)	$X_t = \phi X_{t-1} + u_t$	$X_t = a + bX_{t-1} + \epsilon_t$
(iv)	$X_t = \phi X_{t-1} + u_t + \theta u_{t-1}$	$X_t = a + bX_{t-1} + \epsilon_t$

**Table 3.2** Simulated power and size comparison of  $d_n$  and  $Q_n$  for testing correlated error at  $\alpha = 0.05$  when linear regression model is imposed for data generating process  $Y_t = 1 + 2x_t + \epsilon_t$  where  $\epsilon_t = \phi \epsilon_{t-1} + u_t$  and  $iid\ u_t \sim N(0, \sigma^2)$ .

			$d_n$	$Q_n$			
$\sigma$	n	$\phi = -0.5$	$\phi = 0$	$\phi = 0.5$	$\phi = -0.5$	$\phi = 0$	$\phi = 0.5$
	10	0.309	0.058	0.259	0.383	0.16	0.218
0.1	30	0.821	0.048	0.753	0.633	0.125	0.453
	50	0.948	0.054	0.948	0.817	0.125	0.676
	100	1	0.054	0.999	0.984	0.099	0.958
	10	0.288	0.048	0.251	0.375	0.176	0.223
1	30	0.812	0.062	0.794	0.604	0.122	0.499
	50	0.957	0.04	0.94	0.811	0.103	0.693
	100	0.999	0.055	1	0.977	0.097	0.961

At Table 3.2, DGP is  $Y_t = 1 + 2x_t + \epsilon_t$  where  $x_t = t/n$ ,  $\epsilon_t = \phi \epsilon_{t-1} + u_t$  and  $u_t \sim N(0, \sigma^2)$  is iid. We generate  $Y_t$  for  $\phi = -0.5, 0, 0.5$  and  $\sigma = 0.1, 1$ . Note here that  $\phi = 0$  corresponds to iid error. A classical linear regression analysis is done for practicing DW  $d_n$  and LB  $Q_n$  in checking correlated error with significance level  $\alpha = 0.05$ . Table 3.2 shows that DW is very sensitive to correlated error ( $\phi = -0.5, 0.5$ ) and rejects the correctly imposed model whenever it is contaminated with the correlated error, which is normal in the ordinary hypothesis of DW. In other words, DW accepts the correctly imposed model only when the true DGP is with iid error ( $\phi = 0$ ). LB reports similar results but its level of performance is not so precise as DW.

**Table 3.3** Simulated power comparison of  $d_n$  and  $Q_n$  for testing correlated error at  $\alpha = 0.05$  when linear regression model is imposed and data generating process is  $Y_t = 1 - x_t + x_t^2 + u_t$  with  $iid\ u_t \sim N(0, \sigma^2)$ .

$d_n$				$Q_n$			
n	$\sigma = 0.1$	$\sigma = 1$	$\sigma = 2$	$\sigma = 0.1$	$\sigma = 1$	$\sigma = 2$	
10	0.361	0.047	0.048	0.182	0.171	0.188	
30	0.674	0.06	0.048	0.255	0.125	0.118	
50	0.834	0.05	0.037	0.66	0.096	0.117	
100	0.975	0.075	0.047	0.995	0.105	0.097	

At Table 3.3, DGP is  $Y_t = 1 - x_t + x_t^2 + u_t$  where  $x_t = t/n$  and  $u_t \sim N(0, \sigma^2)$  is iid. We generate  $Y_t$  for  $\sigma = 0.1, 1, 2$ . Note here that correlated error is not considered. Again, a classical linear regression analysis is done for practicing DW  $d_n$  and LB  $Q_n$  with significance level  $\alpha = 0.05$ . Table 3.3 shows that DW is not sensitive enough to reject the wrongly imposed model particularly when error variance  $\sigma^2$  is relatively large ( $\sigma^2 = 1, 4$ ). LB reports similar results but its performance is relatively less misleading (accurate) than DW when  $\sigma^2$  is large (small). This shows that checking error correlatedness would not be a good measure for model specification.

**Table 3.4** Simulated power comparison of  $d_n$  and  $Q_n$  for testing correlated error at  $\alpha = 0.05$  when AR(1) model is imposed and data generating process is  $X_t = \phi X_{t-1} + u_t$  with  $iid\ u_t \sim N(0, \sigma^2)$ .

	$d_n$				$Q_n$				
$\sigma$	n	$\phi = -0.5$	$\phi = -0.1$	$\phi = 0.1$	$\phi = 0.5$	$\phi = -0.5$	$\phi = -0.1$	$\phi = 0.1$	$\phi = 0.5$
	10	0.01	0.012	0.002	0.02	0.057	0.038	0.054	0.055
0.1	30	0.006	0	0	0.008	0.052	0.044	0.044	0.059
	50	0.005	0	0	0.001	0.062	0.045	0.054	0.052
	100	0.002	0	0	0.002	0.053	0.051	0.049	0.053
	10	0.008	0.002	0.006	0.015	0.04	0.059	0.041	0.044
1	30	0.004	0	0.001	0.008	0.049	0.074	0.057	0.064
	50	0.001	0	0	0.001	0.058	0.047	0.05	0.044
	100	0	0	0	0.001	0.041	0.059	0.058	0.06

At Table 3.4, DGP is  $X_t = \phi X_{t-1} + u_t$  with  $iid\ u_t \sim N(0, \sigma^2)$ . We generate  $X_t$  for  $\phi = -0.5, -0.1, 0.1, 0.5$  and  $\sigma = 0.1, 1$ . Note here that  $\phi = 0$  (iid error, equivalently) is not considered. A classical least square parameter estimation for the imposed AR(1) model is done for practicing DW  $d_n$  and LB  $Q_n$  in checking correlated error with significance level  $\alpha = 0.05$ . Table 3.4 shows that LB performs reasonably well in accepting the correctly imposed model across various values of  $\phi$  and  $\sigma^2$ . DW almost always accepts the correctly imposed model regardless of value of  $\phi$  and  $\sigma^2$ .

$Art(t)$ model is imposed and data generating process is $At = \varphi At_{t-1} + at + \varphi at_{t-1}$ with the $at = Ar(0, \varphi)$ .									
			$d_n(\phi, \theta)$				$Q_n(\phi, \theta)$		
$\sigma$	n	(-0.5, -0.3)	(-0.5, 0.3)	(-0.1, -0.3)	(-0.1,0.3)	(-0.5, -0.3)	(-0.5, 0.3)	(-0.1, -0.3)	(-0.1,0.3)
	10	0.02	0.011	0.005	0.005	0.082	0.042	0.064	0.069
0.1	30	0.063	0.001	0.001	0.008	0.131	0.059	0.074	0.082
	50	0.116	0.001	0.002	0.001	0.16	0.045	0.08	0.095
	100	0.238	0	0	0	0.221	0.063	0.068	0.083
	10	0.061	0.029	0.005	0.011	0.089	0.086	0.047	0.072
1	30	0.108	0.045	0.002	0	0.122	0.134	0.069	0.114
	50	0.168	0.113	0.001	0	0.152	0.164	0.054	0.106
	100	0.334	0.268	0.001	0	0.253	0.261	0.061	0.119
$\sigma$	n	(0.1, -0.3)	(0.1,0.3)	(0.5, -0.3)	(0.5,0.3)	(0.1, -0.3)	(0.1,0.3)	(0.5, -0.3)	(0.5,0.3)
	10	0.001	0.019	0.001	0.066	0.053	0.056	0.039	0.106
0.1	30	0	0.006	0	0.119	0.078	0.082	0.044	0.12
	50	0	0.003	0	0.174	0.073	0.096	0.053	0.156
	100	0	0.003	0	0.348	0.077	0.133	0.048	0.241
	10	0.002	0.013	0.01	0	0.061	0.053	0.035	0.047
1	30	0	0.004	0.002	0	0.079	0.071	0.052	0.049
	50	0	0.004	0	0	0.063	0.099	0.047	0.052

**Table 3.5** Simulated power comparison of  $d_n$  and  $Q_n$  for testing correlated error at size  $\alpha = 0.05$  when AR(1) model is imposed and data generating process is  $X_t = \phi X_{t-1} + u_t + \theta u_{t-1}$  with iid  $u_t \sim N(0, \sigma^2)$ .

At Table 3.5, DGP is  $X_t = \phi X_{t-1} + u_t + \theta u_{t-1}$  with  $iid\ u_t \sim N(0, \sigma^2)$ . We generate  $X_t$  for  $\phi = -0.5, -0.1, 0.1, 0.5, \theta = -0.3, 0.3$  and  $\sigma = 0.1, 1$ . A classical least square parameter estimation for the imposed AR(1) model is done for practicing DW  $d_n$  and LB  $Q_n$  in checking correlated error with significance level  $\alpha = 0.05$ . Table 3.5 shows that both LB and DW fail to perform properly in rejecting the null hypothesis.

0.044

In view of model specification our simulation results is summarized as follows. (a) DW is very sensitive to correlated error as long as the underlying correlated error is restricted to AR(1). (b) DW doesn't tend to be sensitive enough to reject the wrongly imposed linear regression model. (c) LB performs reasonably well when correct ARMA model is specified but does not have enough sensitivity when ARMA model is wrongly specified.

The DW test only works when errors are correlated via AR(1) model and the LB test needs to improve its level of performance. Both of them need some modifications and it will be done in separate papers.

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