Bull. Korean Math. Soc. **53** (2016), No. 2, pp. 601–614 http://dx.doi.org/10.4134/BKMS.2016.53.2.601

A FINITE PRESENTATION FOR THE TWIST SUBGROUP OF THE MAPPING CLASS GROUP OF A NONORIENTABLE SURFACE

MICHAŁ STUKOW

ABSTRACT. Let $N_{g,s}$ denote the nonorientable surface of genus g with s boundary components. Recently Paris and Szepietowski [12] obtained an explicit finite presentation for the mapping class group $\mathcal{M}(N_{g,s})$ of the surface $N_{g,s}$, where $s \in \{0, 1\}$ and g + s > 3. Following this work, we obtain a finite presentation for the subgroup $\mathcal{T}(N_{g,s})$ of $\mathcal{M}(N_{g,s})$ generated by Dehn twists.

1. Introduction

Let $N_{g,s}$ be a smooth, nonorientable, compact surface of genus g with s boundary components. If s is zero, then we omit it from the notation. If we do not want to emphasise the numbers g, s, we simply write N for a surface $N_{g,s}$. Recall that N_g is a connected sum of g projective planes and $N_{g,s}$ is obtained from N_q by removing s open disks.

Let Diff(N) be the group of all diffeomorphisms $h: N \to N$ such that h is the identity on each boundary component. By $\mathcal{M}(N)$ we denote the quotient group of Diff(N) by the subgroup consisting of maps isotopic to the identity, where we assume that isotopies are the identity on each boundary component. $\mathcal{M}(N)$ is called the *mapping class group* of N.

The mapping class group $\mathcal{M}(S_{g,s})$ of an orientable surface is defined analogously, but we consider only orientation preserving maps.

1.1. Background

One of the most important elements in mapping class groups of surfaces are Dehn twists. They were discovered by Max Dehn, who first observed that they generate the mapping class group $\mathcal{M}(S_g)$ of a closed oriented surface S_g . Twists were rediscovered by Lickorish [8, 10], who also proved that $\mathcal{M}(S_g)$ is

©2016 Korean Mathematical Society

Received April 10, 2015.

²⁰¹⁰ Mathematics Subject Classification. Primary 57N05; Secondary 20F38, 57M99.

 $Key\ words\ and\ phrases.$ mapping class group, nonorientable surface, twist subgroup, presentation.

Supported by NCN grant 2012/05/B/ST1/02171.

generated by 3g - 1 Dehn twists about nonseparating circles. Later Humphries reduced this generating set to 2g + 1 twists [4].

Since Dehn twists generate the mapping class group $\mathcal{M}(S_g)$, it is natural to ask about possible relations between them. Let us mention some results in this direction. Birman [1] observed that there is a close relation between mapping class group $\mathcal{M}(S_g)$ and the mapping class group of a punctured sphere, which in fact is a quotient of the braid group B_{2g+2} . This correspondence leads to a number of interesting relations, for example: *braid* and *chain relations*, relations with hyperelliptic involution, relations with elements of finite order. Later Johnson [5] discovered the so-called *lantern relation*, which apparently has been used by Dehn in 1920's. It turned out that this set of relations was enough to give a full presentation of $\mathcal{M}(S_g)$, which was obtained by Wajnryb [16]. Later some other relations were discovered, for example *star relations* or relations between fundamental elements in Artin groups embedded in $\mathcal{M}(S_g)$ – see [3, 11].

In the nonorientable case, Lickorish [9] first observed that Dehn twists do not generate the mapping class group $\mathcal{M}(N_g)$ for $g \geq 2$. More precisely, he proved that Dehn twists generate the so-called *twist subgroup* $\mathcal{T}(N_g)$ which is of index 2 in $\mathcal{M}(N_g)$. Later Chillingworth [2] found finite generating sets for $\mathcal{T}(N_g)$ and $\mathcal{M}(N_g)$. These generating sets were extended to the case of a surface with punctures and/or boundary components in [6, 13, 14].

As for relations, recently Paris and Szepietowski [12] obtained a finite presentations for groups $\mathcal{M}(N_{g,s})$ where $s \in \{0, 1\}$ and g + s > 3.

1.2. Main results

The main goal of this paper is to find a complete set of relations between Dehn twists on a nonorientable surface N. To be more precise, we obtain a presentation for the twist subgroup $\mathcal{T}(N_{g,s})$ of the mapping class group $\mathcal{M}(N_{g,s})$ of a nonorientable surface (Theorems 3.1 and 3.2), where $s \in \{0, 1\}$ and g+s > 3. The obtained presentations may seem to be complicated, but many relations are needed only for small genera and stably the presentations are quite simple.

Our starting point is the presentation of $\mathcal{M}(N_{g,s})$ obtained by Paris and Szepietowski [12], however their presentation has g-1 generators which are not elements of $\mathcal{T}(N_{g,s})$, hence it leads to a very complicated presentation of the twist subgroup. Therefore, we use a recent simplification of their presentation [15], which has only one generator not belonging to $\mathcal{T}(N_{g,s})$ (Theorems 2.1, 2.2 and 2.3).

2. Preliminaries

2.1. Notation

Let us represent surfaces $N_{g,0}$ and $N_{g,1}$ as respectively a sphere or a disc with g crosscaps and let $\alpha_1, \ldots, \alpha_{g-1}, \beta$ be two-sided circles indicated in Figure 1.

Small arrows in this figure indicate directions of Dehn twists a_1, \ldots, a_{g-1}, b



FIGURE 1. Surface N as a sphere/disc with crosscaps.

associated with these circles. Observe that β (hence also b) is defined only if $g \ge 4$. From now on whenever we use b, we silently assume that $g \ge 4$.

Moreover, for any unoriented one-sided circle μ and oriented two-sided circle α which intersects μ in one point (Figure 2), we define a *crosscap slide* (or Y-homeomorphism) $Y_{\mu,\alpha}$, that is the effect of pushing μ along the curve α – for precise definition see Section 2.2 of [12].



FIGURE 2. Crosscap slide.

In particular, let $y = Y_{\mu_1,\alpha_1}$, where μ_1, α_1 are curves indicated in Figure 3.



FIGURE 3. Circles μ_i and α_i .

The following three theorems are the main results of [15].

Theorem 2.1. If $g \ge 3$ is odd or g = 4, then $\mathcal{M}(N_{g,1})$ admits a presentation with generators a_1, \ldots, a_{g-1}, y and b for $g \ge 4$. The defining relations are

If $g \ge 6$ is even, then $\mathcal{M}(N_{g,1})$ admits a presentation with generators $a_1, \ldots, a_{g-1}, y, b$ and additionally $b_0, b_1, \ldots, b_{\frac{g-2}{2}}$. The defining relations are relations (A1)–(A6), (B1)–(B8) above and additionally

- (A7) $b_0 = a_1, b_1 = b,$ (A8) $b_{i+1} = (b_{i-1}a_{2i}a_{2i+1}a_{2i+2}a_{2i+3}b_i)^5(b_{i-1}a_{2i}a_{2i+1}a_{2i+2}a_{2i+3})^{-6}$ for $1 \le i \le \frac{g-4}{2},$ (A9a) $b_2b = bb_2$ for g = 6,
- (A9b) $b_{\frac{g-2}{2}}a_{g-5} = a_{g-5}b_{\frac{g-2}{2}}$ for $g \ge 8$.

Theorem 2.2. If $g \ge 4$, then the group $\mathcal{M}(N_{g,0})$ is isomorphic to the quotient of the group $\mathcal{M}(N_{g,1})$ with presentation given in Theorem 2.1 obtained by adding a generator ϱ and relations

(C1a) $(a_1a_2\cdots a_{g-1})^g = \varrho$ for g odd, (C1b) $(a_1a_2\cdots a_{g-1})^g = 1$ for g even, (C2₁) $\varrho a_1 = a_1 \varrho$, (C3) $\varrho^2 = 1$, (C4a) $(y^{-1}a_2a_3\cdots a_{g-1}ya_2a_3\cdots a_{g-1})^{\frac{g-1}{2}} = 1$ for g odd, (C4b) $(y^{-1}a_2a_3\cdots a_{g-1}ya_2a_3\cdots a_{g-1})^{\frac{g-2}{2}}y^{-1}a_2a_3\cdots a_{g-1} = \varrho$ for g even. **Theorem 2.3.** Relations (C4a), (C4b) and (C2₁) in the presentation given by

Theorem 2.3. Relations (C4a), (C4b) and (C2₁) in the presentation given by Theorem 2.2 may be replaced by

(C2) $\rho a_i = a_i \rho \text{ for } i = 1, \dots, g - 1,$ (C5) $y \rho = \rho y^{-1},$ (C4) $(y \rho a_2 a_3 \cdots a_{g-1})^{g-1} = 1.$

3. Presentation for the twist subgroup

Recall that for $s \leq 1$ and $g \geq 3$ the twist subgroup $\mathcal{T}(N_{g,s})$ has index 2 in $\mathcal{M}(N_{g,s})$ (for details see [9, 13]), hence we can obtain its presentation using Reidemeister–Schreier rewriting process. To be more precise, we define a Schreier transversal $U = \{1, y\}$ for $\mathcal{T}(N_{g,s})$ in $\mathcal{M}(N_{g,s})$ and for any $h \in \mathcal{M}(N_{g,s})$ we define

$$\overline{h} = \begin{cases} 1 & \text{if } h \in \mathcal{T}(N_{g,s}), \\ y & \text{if } h \notin \mathcal{T}(N_{g,s}). \end{cases}$$

The Reidemeister–Schreier theorem states that $\mathcal{T}(N_{g,s})$ admits a presentation with generators $ux\overline{ux}^{-1}$, where x is a generator of $\mathcal{M}(N_{g,s})$, $u \in U$ and $ux \notin U$. The set of defining relations consists of relations of the form uru^{-1} , where $u \in U$ and r is a defining relation for $\mathcal{M}(N_{g,s})$.

Theorem 3.1. If $g \ge 3$ is odd or g = 4, then $\mathcal{T}(N_{g,1})$ admits a presentation with generators $a_1, \ldots, a_{g-1}, e, f, y^2$ and b, c for $g \ge 4$. The defining relations are (A1)–(A6) and

 $(\overline{A1}_1) \ ea_j = a_j e \ for \ g \ge 5, \ j \ge 4,$ $(\overline{A1}_2) fa_j = a_j f \text{ for } g \ge 5, \ j \ge 4,$ $(\overline{\mathbf{A2}}_1) \ a_1 e a_1 = e a_1 e,$ $(\overline{A2}_2) a_3^{-1}ea_3^{-1} = ea_3^{-1}e \text{ for } g \ge 4,$ $(\overline{A2}_3) a_1 f a_1 = f a_1 f,$ $(\overline{A3}_1) \ a_1c = ca_1 \ for \ g = 4, 5,$ $(\overline{A3}_2)$ ec = ce for g = 4, 5, $(\overline{A4}) \ ca_4c = a_4ca_4 \ for \ g = 5, 6,$ $\begin{array}{l} (\overline{\mathrm{A5}}) & (e^{-1}a_3a_4c)^{10} = (a_1^{-1}e^{-1}a_3a_4c)^6 \ for \ g = 5, 6, \\ (\overline{\mathrm{A6}}) & (e^{-1}a_3a_4a_5a_6c)^{12} = (a_1^{-1}e^{-1}a_3a_4a_5a_6c)^9 \ for \ g = 7, 8, \end{array}$ $(\overline{B1}) \ (a_2a_3a_1a_2ea_1a_3^{-1}e)(a_2a_3a_1a_2fa_1a_3^{-1}f) = 1 \ for \ g \ge 4,$ $(\overline{B2}_1) \ y^2 = a_2 a_1 e a_1 a_2 a_1 a_2 a_1 a_2 f a_1 a_2,$ $(\overline{B2}_2) \ (a_2a_1ea_1a_2a_1a_2a_1a_2fa_1a_2)(a_2a_1fa_1a_2a_1a_2a_1a_2ea_1a_2) = 1,$ ($\overline{B3}$) $y^2 a_3 = a_3 y^2$ for $g \ge 4$, $(\overline{\mathrm{B4}}_1) \ ea_2 = a_2 e,$ $(\overline{\mathrm{B4}}_2) \ fa_2 = a_2 f,$ $\begin{array}{ll} (\mathrm{B4}_2) & fa_2 = a_2 f, \\ (\overline{\mathrm{B6}}_1) & bc = [a_1 a_2 a_3 f^{-1} a_3^{-1} a_2^{-1} a_1^{-1}] [a_2^{-1} a_3^{-1} e^{-1} a_3 a_2] & for \ g \ge 4, \\ (\overline{\mathrm{B6}}_2) & c(y^2 by^{-2}) = [a_1^{-1} e^{-1} a_3 a_2 a_3^{-1} ea_1] [ea_3^{-1} (y^2 a_2 y^{-2}) a_3 e^{-1}] & for \ g = 4, 5, \\ (\overline{\mathrm{B7}}_1) & (a_4 a_5 a_3 a_4 a_2 a_3 a_1 a_2 ea_1 a_3^{-1} ea_4^{-1} a_3^{-1} a_5^{-1} a_4^{-1}) c \\ & = b(a_4 a_5 a_3 a_4 a_2 a_3 a_1 a_2 ea_1 a_3^{-1} ea_4^{-1} a_3^{-1} a_5^{-1} a_4^{-1}) & for \ g \ge 6, \\ (\overline{\mathrm{B7}}_2) & (a_2^{-1} a_1^{-1} a_3^{-1} a_2^{-1} a_4^{-1} a_3^{-1} a_5^{-1} a_4^{-1}) b(a_4 a_5 a_3 a_4 a_2 a_3 a_1 a_2) y^2 \\ & = y^2 (a_2^{-1} a_1^{-1} a_3^{-1} a_2^{-1} a_4^{-1} a_3^{-1} a_5^{-1} a_4^{-1}) b(a_4 a_5 a_3 a_4 a_2 a_3 a_1 a_2) & for \ g \ge 6, \\ (\overline{\mathrm{B8}}_1) & \left[(a_1 ea_3^{-1} a_4^{-1} a_1^{-1} a_2^{-1} a_4^{-1} a_3^{-1} a_5^{-1} a_4^{-1}) \right] \left[(a_1^{-1} a_2^{-1} a_3^{-1} a_4^{-1}) b^{-1} (a_4 a_3 a_2 a_1) \right] \\ & = a_4^{-1} \left[(a_3^{-1} a_2^{-1} e^{-1} a_3) a_4 (a_3^{-1} ea_2 a_3) \right] a_2^{-1} e^{-1} & for \ g \ge 5, \\ (\overline{\mathrm{B8}}_2) & \left[(a_1^{-1} a_2^{-1} a_3^{-1} a_4^{-1}) b(a_4 a_3 a_2 a_1) \right] \left[(a_1 fa_3^{-1} a_4^{-1}) y^{-2} c^{-1} y^2 (a_4 a_3 f^{-1} a_1^{-1}) \right] \\ & = a_4^{-1} \left[(a_2^{-1} fa_2 a_2) a_4 (a_2^{-1} a_2^{-1} f^{-1} a_2) \right] fa_2 & for \ g = 5, 6. \end{aligned}$ $= a_4^{-1} \left[(a_3^{-1} f a_2 a_3) a_4 (a_3^{-1} a_2^{-1} f a_2^{-1} a_3) \right] f a_2 \quad for \ g = 5, 6.$

$$\begin{split} &If \ g \geq 6 \ is \ even, \ then \ \mathcal{T}(N_{g,1}) \ admits \ a \ presentation \ with \ generators \ a_1, \ldots, \\ &a_{g-1}, \ e, f, y^2, b, c \ and \ additionally \ b_0, b_1, \ldots, \\ &b_{g-2}, \ \bar{b}_{g-2}, \ \bar{b}_{g-4}, \ \bar{b}_{g-2}, \ \bar{c}_{g-2}, \ \bar{c}_{g-$$

Proof. As noted before, we apply Reidemeister–Schreier theorem to the presentation given by Theorem 2.1. Hence as generators of the twist subgroup $\mathcal{T}(N_{g,1})$ we obtain $a_1, \ldots, a_{g-1}, ya_1y^{-1}, \ldots, ya_{g-1}y^{-1}, y^2$ and b, yby^{-1} for $g \geq 4$. Moreover, if $g \geq 6$ is even, we have additional generators: $b_0, b_1, \ldots, b_{\frac{g-2}{2}}, yb_0y^{-1}, yb_1y^{-1}, \ldots, yb_{\frac{g-2}{2}}y^{-1}$. Let us name some of these generators:

$$e = ya_2^{-1}y^{-1}, \ c = yby^{-1}, \ \overline{b}_i = yb_iy^{-1} \text{ for } i = 0, \dots, \frac{g-2}{2}.$$

We also add one generator $f = y^{-1}a_2^{-1}y$ with defining relation

(D1) $f = y^{-2}ey^2$ (see Figure 4).



FIGURE 4. Twists e, f, y^2, c .

(B3) Observe first that relation (B3) rewrites as

$$ya_iy^{-1} = a_i$$
 for $i = 3, 4, \dots, g - 1$

This means that we can remove generators $ya_3y^{-1}, \ldots, ya_{g-1}y^{-1}$ from the presentation, hence from now on we will silently identify ya_iy^{-1} with a_i for $i = 3, 4, \ldots, g-1$.

(B5) Similarly, (B5) allows us to identify ya_1y^{-1} with a_1^{-1} .

Observe also that conjugations of (B3) and (B5) by y give

($\overline{B3}$) $y^2 a_i = a_i y^2$ for $i = 1, 3, 4, \dots, g - 1$.

We will show later that this relation can be replaced by $(\overline{A1}_2)$ if $i \neq 3$.

(A1)–(A9) Relations which do not contain y, that is (A1)–(A9) does not need rewriting, however we need to add their versions conjugated by y. This gives relations (A1), (A2), (A2), (A3), (A4)–(A6) and

 $(\overline{A3}_1) \ a_i c = c a_i \text{ for } g \ge 4, i \ne 2, 4.$

If $g \ge 6$ is even, then we have additionally

- $\begin{array}{l} (\overline{A7}) \quad \overline{b}_{0} = a_{1}^{-1}, \ \overline{b}_{1} = c, \\ (\overline{A8a}) \quad \overline{b}_{2} = (\overline{b}_{0}e^{-1}a_{3}a_{4}a_{5}\overline{b}_{1})^{5}(\overline{b}_{0}e^{-1}a_{3}a_{4}a_{5})^{-6}, \\ (\overline{A8b}) \quad \overline{b}_{i+1} = (\overline{b}_{i-1}a_{2i}a_{2i+1}a_{2i+2}a_{2i+3}\overline{b}_{i})^{5}(\overline{b}_{i-1}a_{2i}a_{2i+1}a_{2i+2}a_{2i+3})^{-6} \\ \quad \text{for } 2 \leq i \leq \frac{g-4}{2}, \\ (\overline{A9a}) \quad \overline{b}_{2}c = c\overline{b}_{2} \text{ for } a = 6. \end{array}$
- $\begin{array}{l} (\overline{A9a}) \quad \overline{b}_2c = c\overline{b}_2 \ \text{for} \ g = 6, \\ (\overline{A9b}) \quad \overline{b}_{\frac{g-2}{2}}a_{g-5} = a_{g-5}\overline{b}_{\frac{g-2}{2}} \ \text{for} \ g \geq 8. \end{array}$

(B4) Relation (B4) and its conjugation by y^{-1} rewrite respectively as $(\overline{B4}_1)$ and $(\overline{B4}_2)$. It is also useful to note that relations (D1), $(\overline{B3})$, $(\overline{A2}_1)$ and $(\overline{A2}_2)$ imply that

 $\begin{array}{l} (\overline{\mathbf{A2}}_{3}) \ a_{1}fa_{1} = fa_{1}f, \\ (\overline{\mathbf{A2}}_{4}) \ a_{3}^{-1}fa_{3}^{-1} = fa_{3}^{-1}f \ \text{for } g \geq 4. \\ \textbf{(B2)} \ \text{Using (A2), } (\overline{\mathbf{A2}}_{1}), \ (\overline{\mathbf{A2}}_{2}) \ \text{and } (\overline{\mathbf{B4}}_{1}) \ \text{we rewrite (B2).} \\ & \underbrace{[y](a_{2}a_{1}\underline{y}^{-1}a_{2}^{-1}[y]a_{1}a_{2})y = a_{1}(a_{2}a_{1}y^{-1}a_{2}^{-1}ya_{1}a_{2})a_{1}, \\ & \xrightarrow{\rightarrow} & \xrightarrow{\rightarrow} \\ [e^{-1}a_{1}^{-1}a_{2}^{-1}a_{1}^{-1}e^{-1}]y^{2} = a_{1}a_{2}a_{1}f[a_{1}a_{2}a_{1}], \\ & \xrightarrow{} & \xrightarrow{} \\ y^{2} = e[a_{1}a_{2}a_{1}]ea_{1}a_{2}a_{1}fa_{2}a_{1}a_{2}, \\ & y^{2} = [e]a_{2}a_{1}a_{2}[e]a_{1}a_{2}a_{1}fa_{2}a_{1}a_{2}, \\ & y^{2} = a_{2}[ea_{1}e]a_{2}a_{1}a_{2}a_{1}a_{2}fa_{1}a_{2}, \\ & y^{2} = a_{2}a_{1}ea_{1}a_{2}a_{1}a_{2}a_{1}a_{2}fa_{1}a_{2}. \end{array}$

In the above computations we introduced the notation which should help the reader to follow our transformations. The underlined parts indicate expressions which will be reduced, and parts with small arrows indicate expressions which will be moved to the left/right.

As a conjugation of (B2) we can take

$$(a_2a_1y^{-1}a_2^{-1}ya_1a_2) = y^{-1}a_1(a_2a_1y^{-1}a_2^{-1}ya_1a_2)a_1y^{-1}.$$

By a straightforward computation this gives

$$y^{-2} = a_2 a_1 f a_1 a_2 a_1 a_2 a_1 a_2 e a_1 a_2,$$

which together with $(\overline{B2}_1)$ gives $(\overline{B2}_2)$.

Observe that $(\overline{B2}_1)$ together with (A1) and $(\overline{A1}_1)$ imply that we can replace $(\overline{B3})$ for $i \ge 4$ with $(\overline{A1}_2)$.

Observe also that $(\overline{B2}_1)$, (A2), $(\overline{B4}_1)$ and $(\overline{B4}_2)$ imply that $(\overline{B3})$ for i = 1 is superfluous.

We will now show that (D1) is superfluous – we will need here $(\overline{A2}_3)$, hence we add this relation to the statement. Using $(\overline{B2}_1)$ we substitute for y^2 .

$$f = (\underbrace{[a_2^{-1}]}_{\leftarrow} a_1^{-1} f^{-1} a_2^{-1} a_1^{-1} a_2^{-1} a_1^{-1} a_2^{-1} \underbrace{a_1^{-1}}_{\leftarrow} e^{-1} a_1^{-1} \underbrace{a_2^{-1}}_{\leftarrow})[\underline{e}]$$

$$(\underbrace{a_2 a_1 e[a_1]}_{\rightarrow} a_2 a_1 a_2 a_1 a_2 f a_1[\underline{a_2}]}_{\rightarrow}),$$

$$\underline{f} = (\underbrace{a_1^{-1} f^{-1} a_2^{-1} a_1^{-1} a_2^{-1} a_1^{-1} a_2^{-1} e^{-1} a_1^{-1})(a_1 e a_2 a_1 a_2 a_1 a_2 f a_1)f}_{\rightarrow}.$$

(B1) If we use (B1) in the form

$$(a_2a_3a_1a_2ya_2^{-1}a_1^{-1}a_3^{-1}a_2^{-1})y^{-1} = y^{-1}(a_2a_3a_1a_2ya_2^{-1}a_1^{-1}a_3^{-1}a_2^{-1}),$$

after rewriting we get $(\overline{B1})$. Conjugating this relation by y gives

$$\begin{array}{ll} (\overline{\mathrm{B1}}_2) & y(a_2a_3a_1a_2[y]a_2^{-1}a_1^{-1}a_3^{-1}a_2^{-1})[y_{\rightarrow}^{-2}] = (a_2a_3a_1a_2\underline{y}a_2^{-1}a_1^{-1}a_3^{-1}a_2^{-1})[\underline{y_{-1}}], \\ & \underset{\leftarrow}{\overset{\rightarrow}{\leftarrow}} \\ & y^2(f^{-1}a_3a_1^{-1}f^{-1}a_2^{-1}a_1^{-1}a_3^{-1}a_2^{-1}) = (a_2a_3a_1a_2ea_1a_3^{-1}e)y^2. \end{array}$$

Now we will show that this relation is superfluous – it is a consequence of relations (A1), (A2), $(\overline{A2}_1)-(\overline{A2}_4)$, $(\overline{B1})$, $(\overline{B2}_1)$, $(\overline{B2}_2)$, $(\overline{B4}_1)$, $(\overline{B4}_2)$. We substitute for y^2 using $(\overline{B2}_1)$ and $(\overline{B2}_2)$.

$$\begin{split} &(\underline{a_{2}a_{1}}ea_{1}a_{2}a_{1}\underline{a_{2}}fa_{1}a_{2})([\underbrace{f^{-1}}_{\leftarrow}]a_{3}a_{1}^{-1}f^{-1}a_{2}^{-1}\underline{a_{1}^{-1}}a_{3}^{-1}\underline{a_{2}^{-1}})\\ &=(\underbrace{a_{2}a_{3}\underline{a_{1}}a_{2}ea_{1}a_{3}^{-1}}_{\rightarrow}](a_{2}^{-1}a_{1}^{-1}e^{-1}\underline{a_{1}^{-1}}a_{2}^{-1}a_{1}^{-1}a_{2}^{-1}a_{1}^{-1}a_{2}^{-1}f^{-1}\underline{a_{1}^{-1}}a_{2}^{-1}),\\ &(ea_{1}a_{2}[a_{1}][a_{1}]\underline{a_{2}}fa_{1}a_{2})(a_{3}[\underline{a_{1}^{-1}}]f^{-1}a_{2}^{-1}a_{3}^{-1})\\ &\leftarrow \rightarrow \\ &=(a_{3}a_{2}e[\underline{a_{1}}]a_{3}^{-1})(a_{2}^{-1}a_{1}^{-1}e^{-1}\underline{a_{2}^{-1}}[a_{1}^{-1}]a_{2}^{-1}a_{1}^{-1}[a_{2}^{-1}]f^{-1}),\\ &([e]a_{1}a_{2}fa_{1}a_{2})(\underline{f}a_{3}f^{-1}a_{2}^{-1}a_{3}^{-1})[\underline{a_{2}}]\\ &\leftarrow \\ &=[\underline{a_{2}^{-1}}](a_{3}a_{2}ea_{3}^{-1})(\underline{e^{-1}}a_{2}^{-1}a_{1}^{-1}e^{-1}a_{2}^{-1}a_{1}^{-1}[f^{-1}]),\\ &(a_{1}a_{2}fa_{1}a_{2})(\underline{a_{3}}[f^{-1}][a_{2}^{-1}]\underline{a_{3}^{-1}}f) =(e^{-1}\underline{a_{3}}[a_{2}][e]\underline{a_{3}^{-1}})(a_{2}^{-1}a_{1}^{-1}e^{-1}a_{2}^{-1}a_{1}^{-1}),\\ &a_{1}a_{2}fa_{1}a_{3}^{-1}[a_{2}]f[a_{3}] =[a_{3}^{-1}]e^{-1}[a_{2}^{-1}]a_{3}a_{1}^{-1}e^{-1}a_{2}^{-1}a_{1}^{-1}],\\ &a_{2}a_{3}a_{1}a_{2}fa_{1}a_{3}^{-1}f =e^{-1}a_{3}a_{1}^{-1}e^{-1}a_{2}^{-1}a_{1}^{-1}a_{3}^{-1}a_{2}^{-1}. \end{split}$$

What we get is $(\overline{B1})$.

(B6) If we rewrite (B6) we get $(\overline{B6}_1)$, and (B6) conjugated by y gives $(\overline{B6}_2)$.

(B7) If we use (B7) in the form

$$a_4a_5a_3a_4a_2a_3a_1a_2ya_2^{-1}a_1^{-1}a_3^{-1}a_2^{-1}a_4^{-1}a_3^{-1}a_5^{-1}a_4^{-1}by^{-1}$$

= $ba_4a_5a_3a_4a_2a_3a_1a_2ya_2^{-1}a_1^{-1}a_3^{-1}a_2^{-1}a_4^{-1}a_3^{-1}a_5^{-1}a_4^{-1}y^{-1},$

after rewriting we get $(\overline{\text{B7}}_1)$. By conjugating this relation by y^{-1} , taking inverses of both sides and using (D1), we get

$$\begin{array}{l} ([a_4a_5a_3a_4a_2a_3a_1a_2]fa_1a_3^{-1}fa_4^{-1}a_3^{-1}a_5^{-1}a_4^{-1})[y^{-2}]cy^2 \\ \leftarrow \\ = b(a_4a_5a_3a_4a_2a_3a_1a_2[fa_1a_3^{-1}fa_4^{-1}a_3^{-1}a_5^{-1}a_4^{-1}]), \\ \to \\ y^{-2}(ea_1a_3^{-1}ea_4^{-1}a_3^{-1}a_5^{-1}a_4^{-1})c(a_4a_5a_3a_4e^{-1}a_3a_1^{-1}e^{-1})y^2 \\ = (a_2^{-1}a_1^{-1}a_3^{-1}a_2^{-1}a_4^{-1}a_3^{-1}a_5^{-1}a_4^{-1})b(a_4a_5a_3a_4a_2a_3a_1a_2). \end{array}$$

This together with $(\overline{B7}_1)$ gives $(\overline{B7}_2)$. For further reference observe that using $(\overline{B1})$ the above relation can be also rewritten as

$$(\overline{\mathbf{B7}}_3) \qquad (a_4 a_5 a_3 a_4 e^{-1} a_3 a_1^{-1} e^{-1}) (a_2^{-1} a_1^{-1} a_3^{-1} a_2^{-1} a_4^{-1} a_3^{-1} a_5^{-1} a_4^{-1}) y^{-2} c y^2 = b (a_4 a_5 a_3 a_4 e^{-1} a_3 a_1^{-1} e^{-1}) (a_2^{-1} a_1^{-1} a_3^{-1} a_2^{-1} a_4^{-1} a_3^{-1} a_5^{-1} a_4^{-1}).$$

Observe that we can use $(\overline{B7}_1)$ and $(\overline{B6}_1)$ as definitions of c. It is straightforward to check that the first of these relations imply $(\overline{A3}_2)$ and $(\overline{A3}_1)$ for i = 1. The second one imply $(\overline{A3}_1)$ for i = 3 and $i \ge 5$.

(B8) If we rewrite (B8) we get $(\overline{B8}_1)$ and (B8) conjugated by y^{-1} gives $(\overline{B8}_2)$.

Further reductions. For any $3 \le k \le g - 1$ define

$$z_{k} = (a_{k-1}a_{k}a_{k-2}a_{k-1}\cdots a_{3}a_{4}e^{-1}a_{3}a_{1}^{-1}e^{-1})(a_{2}^{-1}a_{1}^{-1}\cdots a_{k-1}^{-1}a_{k-2}^{-1}a_{k}^{-1}a_{k-1}^{-1}).$$

Geometrically z_k is the product of crosscap slides $yY_{\mu_k,\alpha_k}^{\pm 1}$, where μ_k and α_k are circles indicated in Figure 3 (see Section 4 of [15]), hence on the left of μ_k , conjugation by z_k has the same effect as conjugation by y. More precisely,

(D2)
$$z_k a_1 z_k^{-1} = a_1^{-1}$$
,
(D3) $z_k a_2 z_k^{-1} = e^{-1}$ for $k \ge 4$,
(D4) $z_k a_i z_k^{-1} = a_i$ for $3 \le i \le k-2$,
(D5) $z_k b z_k^{-1} = c$ for $k \ge 5$,
(D6) $z_k y^2 z_k^{-1} = y^2$,
(D7) $z_k f z_k^{-1} = a_2^{-1}$ for $k \ge 4$,
(D8) $z_k e z_k^{-1} = y^2 a_2^{-1} y^{-2}$ for $k \ge 4$,
(D9) $z_k c z_k^{-1} = y^2 b y^{-2}$ for $k \ge 5$.

Relations (D2)–(D4) are straightforward consequences of (A1), (A2), ($\overline{A1}_1$), ($\overline{A2}_1$), ($\overline{A2}_2$). For (D5) we need additionally (A3), ($\overline{A3}_1$) and ($\overline{B7}_1$).

Let us prove (D6) – we will use (A1), $(\overline{A1}_1)$, $(\overline{B1})$, $(\overline{B3})$ and $(\overline{B1}_2)$ (hence we need all relations that we used to reduce $(\overline{B1}_2)$).

$$z_k y^2 = (a_{k-1}a_k a_{k-2}a_{k-1} \cdots a_3 a_4 e^{-1}a_3 a_1^{-1} e^{-1})(a_2^{-1}a_1^{-1} \cdots a_{k-1}^{-1}a_{k-2}^{-1}a_k^{-1}a_{k-1}^{-1})y^2$$

MICHAŁ STUKOW

$$= (a_{k-1}a_k \cdots a_3a_4)[e^{-1}a_3a_1^{-1}e^{-1}a_2^{-1}a_1^{-1}a_3^{-1}a_2^{-1}]y^2(a_4^{-1}a_3^{-1}\cdots a_k^{-1}a_{k-1}^{-1})$$

= $(a_{k-1}a_k \cdots a_3a_4)y^2[e^{-1}a_3a_1^{-1}e^{-1}a_2^{-1}a_1^{-1}a_3^{-1}a_2^{-1}](a_4^{-1}a_3^{-1}\cdots a_k^{-1}a_{k-1}^{-1})$
= y^2z_k .

Now we will prove (D7) – we will use (A1), (A2), $(\overline{A1}_2)$, $(\overline{A2}_4)$, $(\overline{B1})$.

$$\begin{split} z_k f &= (a_{k-1}a_k \cdots a_4 a_5) a_3 a_4 [e^{-1}a_3 a_1^{-1} e^{-1} a_2^{-1} a_1^{-1} a_3^{-1} a_2^{-1}] a_4^{-1} a_3^{-1} \\ & (a_5^{-1} a_4^{-1} \cdots a_k^{-1} a_{k-1}^{-1}) f \\ &= (a_{k-1}a_k \cdots a_4 a_5) a_3 a_4 [a_2 a_3 a_1 a_2 f a_1 a_3^{-1} f] a_4^{-1} a_3^{-1} [f] (a_5^{-1} a_4^{-1} \cdots a_k^{-1} a_{k-1}^{-1}) \\ & \leftarrow \\ & (a_{k-1}a_k \cdots a_4 a_5) a_2^{-1} a_3 a_4 [a_2 a_3 a_1 a_2 f a_1 a_3^{-1} f] a_4^{-1} a_3^{-1} (a_5^{-1} a_4^{-1} \cdots a_k^{-1} a_{k-1}^{-1}) \\ & = (a_{k-1}a_k \cdots a_4 a_5) a_2^{-1} a_3 a_4 [a_2 a_3 a_1 a_2 f a_1 a_3^{-1} f] a_4^{-1} a_3^{-1} (a_5^{-1} a_4^{-1} \cdots a_k^{-1} a_{k-1}^{-1}) \\ & = a_2^{-1} (a_{k-1}a_k \cdots a_3 a_4) [e^{-1}a_3 a_1^{-1} e^{-1} a_2^{-1} a_1^{-1} a_3^{-1} a_2^{-1}] (a_4^{-1} a_3^{-1} \cdots a_k^{-1} a_{k-1}^{-1}) \\ & = a_2^{-1} z_k. \end{split}$$

Relation (D8) is a consequence of (D6), (D7) and (D1). Finally, (D9) is a consequence of $(\overline{B7}_3)$ and (D6) (hence we need $(\overline{B7}_2)$).

Relations (D2)-(D9) imply that

- $(\overline{A4})$ is superfluous if $g \ge 7$,
- $(\overline{A5})$ is superfluous if $g \ge 7$,
- $(\overline{A6})$ is superfluous if $g \ge 9$,
- $(\overline{B6}_2)$ is superfluous if $g \ge 6$,
- $(\overline{B8}_2)$ is superfluous if $g \ge 7$.

Moreover, if $g \ge 8$, relations (A8a) and (A8b) for $i < \frac{g-4}{2}$ are consequences of relation (A8). Hence we can remove all these relations together with generators $\overline{b}_0, \ldots, \overline{b}_{\frac{g-8}{2}}$ and instead add the relation

$$\overline{b}_i = z_{g-1} b_i z_{g-1}^{-1}$$
 for $i = \frac{g-6}{2}, \ \frac{g-4}{2}.$

This is exactly $(\overline{A7c})$.

Theorem 3.2. If $g \ge 5$ is odd, then the group $\mathcal{T}(N_{g,0})$ is isomorphic to the quotient of the group $\mathcal{T}(N_{g,1})$ with presentation given in Theorem 3.1 obtained by adding a generator ϱ and relations

 $\begin{array}{ll} (C1a) & (a_1a_2\cdots a_{g-1})^g = \varrho, \\ (\overline{C1a}) & (a_1^{-1}e^{-1}a_3\cdots a_{g-1})^g = y^2\varrho, \\ (C2) & a_i\varrho = \varrho a_i \quad for \ i = 1, 2, \dots, g-1, \\ (\overline{C2}) & \varrho e = f\varrho, \\ (\overline{C5}) & \varrho y^2 = y^{-2}\varrho, \\ (C3) & \varrho^2 = 1, \\ (\overline{C4a}) & (a_2a_3\cdots a_{g-1}e^{-1}a_3\cdots a_{g-1})^{\frac{g-1}{2}} = 1. \end{array}$

Moreover, relations $(\overline{A1}_2)$, $(\overline{B2}_2)$, $(\overline{B4}_2)$ are superfluous.

If $g \geq 4$ is even, then the group $\mathcal{T}(N_{g,0})$ is isomorphic to the quotient of the group $\mathcal{T}(N_{g,1})$ with presentation given in Theorem 3.1 obtained by adding a generator $\overline{\varrho}$ and relations

 $(C1b) (a_1a_2\cdots a_{g-1})^g = 1,$ $(\overline{C2}_1) \overline{\varrho}a_1 = a_1^{-1}\overline{\varrho},$ $(\overline{C2}_2) \overline{\varrho}a_i = a_i\overline{\varrho} \text{ for } i = 3, \dots, g-1,$ $(\overline{C2}_3) \overline{\varrho}a_2 = e^{-1}\overline{\varrho},$ $(\overline{C3}) \overline{\varrho}y^2 = y^{-2}\overline{\varrho},$ $(\overline{C3}) \overline{\varrho}^2 = 1,$ $(\overline{C4}) (\overline{\varrho}a_2a_3\cdots a_{g-1})^{g-1} = 1.$

Moreover, relations $(\overline{A1}_1)$, $(\overline{A2}_1)$, $(\overline{A2}_2)$ are superfluous.

Proof. We follow the lines of the proof of Theorem 3.1, but as a starting point we now have Theorem 2.2. Moreover, it is convenient to add relations (C2) and (C5), so in particular (C4a) and (C4b) are equivalent to (C4) (see Theorem 2.3). Generator ϱ yields two additional generators for $\mathcal{T}(N_{g,0})$, namely $\varrho, y \varrho y^{-1}$ if g is odd and $\overline{\varrho} = y \varrho, \varrho y^{-1}$ if g is even.

Suppose first that g is odd. Then (C5) and its conjugate by y^{-1} rewrite as

$$y^{2}\varrho = y\varrho y^{-1}$$
$$y^{2}\varrho y^{2} = \varrho.$$

The first relation implies that we can remove generator $y \varrho y^{-1}$ – we will do this silently from now on. The second one gives ($\overline{C5}$).

Relations (C1a), (C2), (C3) does not need rewriting, and if we conjugate them by y we get respectively ($\overline{C1a}$), ($\overline{C2}$) (we use here ($\overline{D1}$), hence also ($\overline{A2}_3$)) and relation equivalent to ($\overline{C5}$).

Relation (C4a) and its conjugate by y rewrite respectively as

$$(f^{-1}a_3\cdots a_{g-1}a_2a_3\cdots a_{g-1})^{\frac{g-1}{2}} = 1,$$

$$(a_2a_3\cdots a_{g-1}e^{-1}a_3\cdots a_{g-1})^{\frac{g-1}{2}} = 1.$$

The second relation is $(\overline{C4a})$, and if we conjugate it by ρ , by (C2) and $(\overline{C2})$ we get the first one.

Finally, observe that if we conjugate relations $(\overline{A1}_1)$, $(\overline{B2}_1)$, $(\overline{B4}_1)$ by ρ we get respectively $(\overline{A1}_2)$, $(\overline{B2}_2)$, $(\overline{B4}_2)$.

Now assume that g is even, hence $\overline{\varrho} = y \varrho \in \mathcal{T}(N_{g,0})$. Relation (C5) and its conjugate by y rewrite as

$$y\varrho = \varrho y^{-1},$$

$$y^2(y\varrho) = (y\varrho)y^{-2}.$$

The first relation implies that we can remove generator ρy^{-1} – we will do this silently from now on. The second one gives ($\overline{C5}$).

If we rewrite relation (C2) we get relations $(\overline{C2}_1) - (\overline{C2}_3)$.

Relations (C1b), (C3) and (C4) rewrite respectively as (C1b), ($\overline{C3}$) and ($\overline{C4}$). Their conjugates by $y^{\pm 1}$ are superfluous since, by ($\overline{C2}_1$)–($\overline{C2}_3$), they are the same as conjugates by $\overline{\varrho}$.

Finally, observe that if we conjugate relations (A1), (A2) by $\overline{\varrho}$ we get respectively $(\overline{A1}_1), (\overline{A2}_1)-(\overline{A2}_2)$.

Remark 3.3. Observe that relations $(\overline{B2}_1)$ and (C1a), $(\overline{C4})$ allows to remove y^2 and $\varrho, \overline{\varrho}$ from the generating sets, hence the generating sets of the presentations given by Theorems 3.1 and 3.2 are really Dehn twists about nonseparating circles.

4. Geometric interpretation

We devote this last section to the geometric interpretation of relations obtained in Theorem 3.1.

Relations (A1), (A3), (A9a), (A9b), $(\overline{A1}_1)$, $(\overline{A1}_2)$, $(\overline{A3}_1)$, $(\overline{A3}_2)$, $(\overline{B3})$, $(\overline{B4}_1)$, $(\overline{B4}_2)$, $(\overline{B7}_2)$, $(\overline{A9a})$, $(\overline{A9b})$ are standard commutativity relations between Dehn twists with disjoint supports.

Relations (A2), (A4), (A2₁)–(A2₃), (A4) are standard braid relations between Dehn twists about circles intersecting in one point.

Relations (A5), (A6), (A8), ($\overline{A5}$), ($\overline{A6}$), ($\overline{A8a}$), ($\overline{A8b}$) came from Matsumoto [11] presentation of mapping class group of an orientable surface. They have simple interpretation as relations between fundamental elements of Artin groups – for details see [11] and [7].

Relations $(\overline{B7}_1)$ and $(\overline{A7c})$ are simple conjugation relations of the form $t_{f(\alpha)} = ft_{\alpha}f^{-1}$, where t_{α} is the twist about a circle α .

Relations $(\overline{B6}_2)$ and $(\overline{B8}_2)$ are conjugates (by $y^{\pm 1}$) of $(\overline{B6}_1)$ and $(\overline{B8}_1)$ respectively, and $(\overline{B2}_2)$ is equivalent to the conjugation of $(\overline{B2}_1)$, hence we are left with four interesting relations: $(\overline{B1})$, $(\overline{B2}_1)$, $(\overline{B6}_1)$ and $(\overline{B8}_1)$.

Relation $(\overline{B1})$ can be rewritten in a slightly more symmetric form

$$(a_2ea_1)a_3^{-1}(a_2ea_1)a_3(a_2fa_1)a_3^{-1}(a_2fa_1)a_3 = 1.$$

This is a relation between five Dehn twists a_1, a_2, a_3, e, f illustrated in Figures 1 and 4.

Relation $(\overline{B2}_1)$ can be rewritten as

$$y^2 = (a_2 e a_1)^2 (a_2 f a_1)^2.$$

This is a relation between five twists a_1, a_2, e, f, y^2 illustrated in Figures 1 and 4.

Relation $(\overline{B6}_1)$ is a relation between four Dehn twists

b, c,
$$f' = (a_1 a_2 a_3) f^{-1} (a_1 a_2 a_3)^{-1}$$
, $e' = (a_3 a_2)^{-1} e^{-1} (a_3 a_2)$,

illustrated in Figures 1, 4 and 5.



FIGURE 5. Dehn twists e' and f'.

Finally, relation $(\overline{B8}_1)$ is a relation between six Dehn twists

 $c' = (a_1 e a_3^{-1} a_4^{-1}) c(a_1 e a_3^{-1} a_4^{-1})^{-1}, \ b' = (a_4 a_3 a_2 a_1)^{-1} b^{-1} (a_4 a_3 a_2 a_1),$ $a_4, \ a' = (a_3^{-1} e a_2 a_3)^{-1} a_4 (a_3^{-1} e a_2 a_3), \ a_2, \ e.$

illustrated in Figures 1, 4 and 6.



FIGURE 6. Dehn twists a', b' and c'.

References

- J. S. Birman, Automorphisms of the fundamental group of a closed, orientable 2manifold, Proc. Amer. Math. Soc. 21 (1969), no. 2, 351–354.
- [2] D. R. J. Chillingworth, A finite set of generators for the homeotopy group of a nonorientable surface, Math. Proc. Cambridge Philos. Soc. 65 (1969), 409–430.
- [3] S. Gervais, A finite presentation of the mapping class group of a punctured surface, Topology **40** (2001), no. 4, 703–725.
- [4] S. P. Humphries, Generators for the mapping class group, In Topology of lowdimensional manifolds (Proc. Second Sussex Conf., Chelwood Gate, 1977), pp. 44–47, Lecture Notes in Math., 722, Springer, Berlin, 1979.
- [5] D. L. Johnson, Homeomorphisms of a surface which act trivially on homology, Proc. Amer. Math. Soc. 75 (1979), no. 1, 119–125.
- [6] M. Korkmaz, Mapping class groups of nonorientable surfaces, Geom. Dedicata 89 (2002), 109–133.
- [7] C. Labruère and L. Paris, Presentations for the punctured mapping class groups in terms of Artin groups, Algebr. Geom. Topol. 1 (2001), 73–114.
- W. B. R. Lickorish, A representation of orientable combinatorial 3-manifolds, Ann. of Math. 76 (1962), 531–540.

MICHAŁ STUKOW

- [9] _____, Homeomorphisms of non-orientable two-manifolds, Math. Proc. Cambridge Philos. Soc. 59 (1963), 307–317.
- [10] _____, A finite set of generators for the homeotopy group of a 2-manifold, Math. Proc. Cambridge Philos. Soc. **60** (1964), 769–778.
- [11] M. Matsumoto, A presentation of mapping class groups in terms of Artin groups and geometric monodromy of singularities, Math. Ann. 316 (2000), no. 3, 401–418.
- [12] L. Paris and B. Szepietowski, A presentation for the mapping class group of a nonorientable surface, arXiv:1308.5856v1 [math.GT], 2013.
- M. Stukow, The twist subgroup of the mapping class group of a nonorientable surface, Osaka J. Math. 46 (2009), no. 3, 717–738.
- [14] _____, Generating mapping class groups of nonorientable surfaces with boundary, Adv. Geom. 10 (2010), no. 2, 249–273.
- [15] _____, A finite presentation for the mapping class group of a nonorientable surface with Dehn twists and one crosscap slide as generators, J. Pure Appl. Algebra 218 (2014), no. 12, 2226–2239.
- [16] B. Wajnryb, A simple presentation for the mapping class group of an orientable surface, Israel J. Math. 45 (1983), no. 2-3, 157–174.

INSTITUTE OF MATHEMATICS UNIVERSITY OF GDAŃSK WITA STWOSZA 57, 80-952 GDAŃSK, POLAND *E-mail address*: trojkat@mat.ug.edu.pl