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JORDAN DERIVATIONS ON A LIE IDEAL OF A SEMIPRIME RING AND THEIR APPLICATIONS IN BANACH ALGEBRAS

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ABSTRACT. Let R be a 3!-torsion free noncommutative semiprime ring, U a Lie ideal of R, and let $D: R \to R$ be a Jordan derivation. If [D(x), x]D(x) = 0 for all $x \in U$, then D(x)[D(x), x]y - yD(x)[D(x), x] = 0 for all $x, y \in U$. And also, if D(x)[D(x), x] = 0 for all $x \in U$, then [D(x), x]D(x) - y[D(x), x]D(x) = 0 for all $x, y \in U$. And we shall give their applications in Banach algebras.

1. INTRODUCTION

Throughout, R represents an associative ring and A will be a complex Banach algebra. We write [x, y] for the commutator xy - yx for x, y in a ring. Let rad(R) denote the (*Jacobson*) radical of a ring R. And a ring R is said to be semisimple if its Jacobson radical rad(R) is zero.

A ring R is called n-torsion free if nx = 0 implies x = 0. Recall that R is prime if aRb = (0) implies that either a = 0 or b = 0, and is semiprime if aRa = (0) implies a = 0. On the other hand, let X be an element of a normed algebra. Then for every $a \in X$ the spectral radius of a, denoted by r(a), is defined by $r(a) = \inf\{||a^n||^{\frac{1}{n}} : n \in \mathbb{N}\}$. It is well-known that the following theorem holds: if a is an element of a normed algebra, then $r(a) = \lim_{n \to \infty} ||a^n||^{\frac{1}{n}}$ (see F.F. Bonsall and J. Duncan[1]). An additive mapping D from R to R is called a derivation if D(xy) = D(x)y +

An additive mapping D from R to R is called a *derivation* if D(xy) = D(x)y + xD(y) holds for all $x, y \in R$. And an additive mapping D from R to R is called a *Jordan derivation* if $D(x^2) = D(x)x + xD(x)$ holds for all $x \in R$.

B.E. Johnson and A.M. Sinclair[12] proved that any linear derivation on a semisimple Banach algebra is continuous. A result of I.M. Singer and J. Wermer[13] states that every continuous linear derivation on a commutative Banach algebra maps the

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algebra into its radical. From these two results, we can conclude that there are no nonzero linear derivations on a commutative semisimple Banach algebra.

M.P. Thomas[14] has proved that any linear derivation on a commutative Banach algebra maps the algebra into its radical.

J. Vukman[15] proved the following: let R be a 2-torsion free prime ring. If $D: R \longrightarrow R$ is a derivation such that [D(x), x]D(x) = 0 for all $x \in R$, then D = 0.

Moreover, using the above result, he proved that the following holds: let A be a noncommutative semisimple Banach algebra. Suppose that [D(x), x]D(x) = 0 holds for all $x \in A$. In this case, D = 0.

B.D. Kim [6] showed the following: let R be a 3!-torsion free semiprime ring. Suppose there exists a Jordan derivation $D: R \to R$ such that

$$[D(x), x]D(x)[D(x), x] = 0$$

for all $x \in R$. In this case, we have $[D(x), x]^5 = 0$ for all $x \in R$.

And, B.D. Kim[7] showed the following:let A be a noncommutative Banach algebra. Suppose there exists a continuous linear Jordan derivation $D: A \to A$ such that $D(x)[D(x), x]D(x) \in \operatorname{rad}(A)$ for all $x \in A$. In this case, we have $D(A) \subseteq \operatorname{rad}(A)$.

In this paper, our first aim is to prove the following results in the ring theory in order to apply it to the Banach algebra theory:

Let R be a 3!-torsion free noncommutative semiprime ring, U a Lie ideal of R. And let $D: R \longrightarrow R$ be a Jordan derivation on R and U a Lie ideal of R. In this case, we show that if [D(x), x]D(x) = 0 holds for all $x \in U$, then D(x)[D(x), x]y - yD(x)[D(x), x] = 0 for all $x, y \in U$, and also, if D(x)[D(x), x] = 0 holds for all $x \in U$, then [D(x), x]D(x)y-y[D(x), x]D(x) = 0 for all $x, y \in U$. In particular, when U = R, then we conclude that [D(x), x]D(x) = 0 is equivalent to D(x)[D(x), x] = 0 for all $x \in R$.

Moreover, using the above results, we shall give their applications in Banach algebra as follows.

(i): Suppose there exists a continuous linear Jordan derivation $D: A \to A$ and U a Lie ideal of A. Then

$$[D(x), x]D(x) \in \operatorname{rad}(A) \iff D(x)[D(x), x] \in \operatorname{rad}(A)$$

for all $x \in U$.

And also, we have their applications in Banach algebras as follows. Of course, the following results are already well-known.

(ii): Suppose there exists a continuous linear Jordan derivation D on a noncommutative Banach algebra A with a Lie ideal U such that

$$[D(x), x]D(x) \in \operatorname{rad}(A)$$

for all $x \in U$.

Then we have $D(x)[D(x), x]y - yD(x)[D(x), x] \in rad(A)$ for all $x, y \in U$. And

(iii): Suppose there exists a continuous linear Jordan derivation D on a noncommutative Banach algebra A with a Lie ideal U such that

$$D(x)[D(x), x] \in \operatorname{rad}(A)$$

for all $x \in U$.

Then $[D(x), x]D(x)y - y[D(x), x]D(x) \in rad(A)$ for all $x, y \in U$. In particular, when U = A, then we see that

$$[D(x), x]D(x) \in \operatorname{rad}(A) \iff D(x)[D(x), x] \in \operatorname{rad}(A)$$

for all $x \in A$. Moreover, we have $D(A) \subseteq \operatorname{rad}(A)$.

The following lemma is due to L.O. Chung and J. Luh[4].

Lemma 1.1. Let R be a n!-torsion free ring. Suppose there exist elements $y_1, y_2, \dots, y_{n-1}, y_n$ in R such that $\sum_{k=1}^{n} t^k y_k = 0$ for all $t = 1, 2, \dots, n$. Then we have $y_k = 0$ for every positive integer k with $1 \le k \le n$.

The following theorem is due to M. Brešar[3].

Theorem 1.2. Let R be a 2-torsion free semiprime ring and let $D : R \longrightarrow R$ be a Jordan derivation. In this case, D is a derivation.

We write Q(A) for the set of all quasinilpotent elements in A. M. Brešar [2] has proved the following theorem.

Theorem 1.3. Let D be a bounded derivation of a Banach algebra A. Suppose that $[D(x), x] \in Q(A)$ for every $x \in A$. Then D maps A into rad(A).

After this, by S_m we denote the set $\{k \in \mathbb{N} \mid 1 \leq k \leq m\}$ where m is a positive integer.

We need Theorems 2.4 and 2.5 to obtain the main theorems for Banach algebra theory.

2. Main Results

Lemma 2.1. Let R be a noncommutative semiprime ring, and U a Lie ideal of R. And suppose that aya = 0 for all $y \in U$ and some $a \in R$. Then a = 0.

Proof. By the assumption, we have

Replacing [y, z] for y in (2.1), we obtain

(2.2) $a[y, z]a = 0, y \in U, z \in R.$

Writing zaw for z in (2.2), we get

(2.3)
$$a[y, z]awa + aza[y, w]a + az[y, a]wa = 0, y \in U, w, z \in R.$$

Combining (2.2) with (2.3),

$$(2.4) az[y,a]wa = 0, y \in U, w, z \in R$$

From (2.4), we have

$$[y,a]waz[y,a]wa = 0, y \in U, w, z \in R$$

Since R is semiprime, the relation (2.5) yields

 $[y,a]wa = 0, y \in U, w \in R.$

Substituting aw for w in (2.6),

(2.7)
$$ya^2wa - ayawa = 0, y \in U, w \in R.$$

From (2.1) and (2.7), we have

$$(2.8) ya^2wa = 0, y \in U, w \in R$$

From (2.8), we get

$$(2.9) ya^2wya^2 = 0, y \in U, w \in R$$

Since R is semiprime, the relation (2.9) yields

(2.10)
$$ya^2 = 0, y \in U.$$

Putting [x, w] instead of y in (2.10), we obtain

$$(2.11) ywa^2 - wya^2, y \in U, w \in R.$$

Combining (2.10) with (2.11),

From (2.12), we get

(2.13)
$$yw[a^2, y] = 0, y \in U, w \in R$$

From (2.13), we have

(2.14)
$$[a^2, y]w[a^2, y] = 0, y \in U, w \in R.$$

Thus by semiprimeness of R, it follows from (2.14) that

$$(2.15) [a2, y] = 0, y \in U.$$

For simplicity, we shall denote the maps $B : R \times R \longrightarrow R$, $f, g : R \longrightarrow R$ by $B(x, y) \equiv [D(x), y] + [D(y), x], f(x) \equiv [D(x), x], g(x) \equiv [f(x), x]$ for all $x, y \in R$ respectively. Then we have the basic properties:

$$\begin{split} B(x,y) &= B(y,x), \ B(x,yz) = B(x,y)z + yB(x,z) + D(y)[z,x] + [y,x]D(z), \\ B(x,x) &= 2f(x), \ B(xy,z) = B(y,z)x + zB(y,x) + D(z)[x,y] + [z,y]D(x), \\ B(x,x^2) &= 2(f(x)x + xf(x)), \ x,y,z \in R. \end{split}$$

After this, we use the above relations without specific reference.

Theorem 2.2. Let R be a 3!-torsion free noncommutative semiprime ring, U a Lie ideal of R with $[R, U] \neq \{0\}$. Then Let $D : R \longrightarrow R$ be a Jordan derivation on a semiprime ring.

(i): If
$$[D(x), x]D(x) = 0$$
 holds for all $x \in U$, then

$$D(x)[D(x), x]y - yD(x)[D(x), x] = 0$$

for all $x, y \in U$. And (ii): If D(x)[D(x), x] = 0 holds for all $x \in U$, then

$$[D(x), x]D(x)y - y[D(x), x]D(x) = 0$$

for all $x, y \in U$.

In particular, when U = R, we see that

$$[D(x), x]D(x) = 0, \ x \in R \quad \Longleftrightarrow \quad D(x)[D(x), x] = 0, \ x \in R.$$

Proof. (i)(\Longrightarrow): By Theorem 1.2, we can see that D is a derivation on R. By the assumption,

$$(2.16) f(x)D(x) = 0, \ x \in U$$

Replacing x + ty for x in (2.16), we have

(2.17)
$$[D(x+ty), x+ty]D(x+ty) \equiv +t\{B(x,y)D(x)+f(x)D(y)\} +t^{2}H(x,y)+t^{3}[D(y),y]D(y) = 0, x, y \in U, t \in S_{3}$$

where H denotes the term satisfying the identity (2.17). From (2.16) and (2.17), we obtain

(2.18)
$$t\{B(x,y)D(x) + f(x)D(y)\} + t^2H(x,y) = 0, \ x, y \in U, t \in S_3.$$

Since R is 2!-torsion free by assumption, by Lemma 2.1 the relation (2.18) yields

(2.19)
$$B(x,y)D(x) + f(x)D(y) = 0, x, y \in U.$$

Let $y = x^2$ in (2.19). Then using (2.16), we have

(2.20)
$$2(f(x)x + xf(x))D(x) + f(x)(D(x)x + xD(x)) = 0, x \in U.$$

From (2.16) and (2.20),

(2.21)
$$3f(x)xD(x) + 2xf(x)D(x) + f(x)D(x)x = 3f(x)^2 = 0, x \in U.$$

Since R is 3!-torsion free, it follows from (2.21) that

(2.22)
$$f(x)^2 = 0, x \in U.$$

From (2.16), we obtain

(2.23)
$$0 = [f(x)D(x), x] = g(x)D(x) + f(x)^2, x \in U.$$

From (2.22) and (2.23), we have

$$(2.24) g(x)D(x) = 0, x \in U.$$

Writing yx for y in (2.19), we get

$$(2.25)(B(x,y)x + 2yf(x) + [y,x]D(x))D(x) + f(x)(D(y)x + yD(x)) = 0, x, y \in U.$$

Right multiplication of (2.19) by x leads to

(2.26)
$$B(x,y)D(x)x + f(x)D(y)x = 0, x \in U.$$

Combining (2.25) with (2.26),

$$(2.27) -B(x,y)f(x) + 2yf(x)D(x) + [y,x]D(x)^2 + f(x)yD(x) = 0, x, y \in U.$$

From (2.16) and (2.27), we have

(2.28)
$$-B(x,y)f(x) + [y,x]D(x)^2 + f(x)yD(x) = 0, x, y \in U.$$

Substituting x^2 for y in (2.28), we get

(2.29)
$$-2(f(x)x + xf(x))f(x) + f(x)x^2D(x) = 0, x \in U.$$

Comparing (2.22) and (2.24), we obtain

(2.30)
$$\begin{aligned} -2f(x)xf(x) - xf(x)^2 - f(x)(f(x)x + xf(x)) \\ = -3f(x)xf(x) = -3g(x)f(x) = 3f(x)g(x) = 0, x \in R. \end{aligned}$$

Since R is 3!-torsion free by assumption, the relation (2.30) yields

(2.31)
$$g(x)f(x) = f(x)g(x) = 0, x \in R.$$

Right multiplication of (2.28) by D(x) leads to

(2.32)
$$-B(x,y)f(x)^{2} + [y,x]D(x)^{2}f(x) + f(x)yD(x)f(x) = 0, x, y \in \mathbb{R}$$

From (2.22) and (2.32), we have

(2.33)
$$[y,x]D(x)^2f(x) + f(x)yD(x)f(x) = 0, x, y \in R.$$

Substituting xy for y in (2.33), we get

(2.34)
$$x[y,x]D(x)^{2}f(x) + f(x)xyD(x)f(x) = 0, x, y \in \mathbb{R}$$

Left multiplication of (2.34) by D(x) leads to

(2.35)
$$-x[y,x]D(x)^{2}f(x) + xf(x)yD(x)f(x) = 0, x, y \in R.$$

From (2.34) and (2.35), we have

(2.36)
$$g(x)yD(x)f(x) = 0, x, y \in R.$$

Replacing yx for y in (2.36), we obtain

$$(2.37) g(x)yxD(x)f(x) = 0, x, y \in R$$

Right multiplication of (2.36) by x leads to

(2.38)
$$g(x)yD(x)f(x)x = 0, x, y \in R.$$

From (2.22), (2.37) and (2.38), we have

(2.39) $g(x)yD(x)g(x) = 0, x, y \in R.$

Left multiplication of (2.39) by D(x) leads to

$$(2.40) D(x)g(x)yD(x)g(x) = 0, x, y \in R.$$

Thus by semiprimeness of R, it is clear that

(2.41)
$$D(x)g(x) = 0, x \in R.$$

Putting xy instead of y in (2.28), we get

$$-(xB(x,y) + 2f(x)y + D(x)[y,x])f(x) + x[y,x]D(x)^{2} + f(x)xyD(x)$$

$$(2.42) = 0, x, y \in R.$$

Left multiplication of (2.28) by x leads to

(2.43)
$$-xB(x,y)f(x) + x[y,x]D(x)^2 + xf(x)yD(x) = 0, x \in \mathbb{R}$$

Combining (2.42) with (2.43),

(2.44)
$$-2f(x)yf(x) - D(x)[y,x]f(x) + g(x)yD(x) = 0, x, y \in R.$$

Right multiplication of (2.44) by D(x) yields

(2.45)
$$-2f(x)yf(x)D(x) - D(x)[y,x]f(x)D(x) + g(x)yD(x)^2 = 0, x \in \mathbb{R}.$$

Combining (2.16) with (2.45),

(2.46)
$$g(x)yD(x)^2 = 0, x, y \in R$$

Replacing yD(x) for y in (2.45), we get

(2.47)
$$\begin{aligned} -2f(x)yD(x)f(x) - D(x)[y,x]D(x)f(x) - D(x)yf(x)^2 \\ +g(x)yD(x)^2 &= 0, x \in R. \end{aligned}$$

From (2.22) and (2.47), we have

(2.48)
$$-2f(x)yD(x)f(x) - D(x)[y,x]D(x)f(x) + g(x)yD(x)^2 = 0, x \in \mathbb{R}$$

Comparing (2.46) and (2.48),

(2.49)
$$2f(x)yD(x)f(x) + D(x)[y,x]D(x)f(x) = 0, x \in R.$$

Left multiplication of (2.49) by D(x) leads to

(2.50)
$$2D(x)f(x)yD(x)f(x) + D(x)^{2}[y,x]D(x)f(x) = 0, x, y \in \mathbb{R}.$$

Substituting f(x)y for y in (2.49), we obtain

(2.51) $2f(x)^2 y D(x) f(x) + D(x) f(x) [y, x] D(x) f(x) + D(x) g(x) y D(x) f(x) = 0, x \in R.$

Combining (2.22), (2.41) with (2.51), we obtain

(2.52)
$$D(x)f(x)[y,x]D(x)f(x) = 0, x \in R.$$

Substituting $yD(x)^2z$ for y in (2.52), we get

(2.53)
$$D(x)f(x)[y,x]D(x)^{2}zD(x)f(x) + D(x)f(x)y[D(x)^{2},x]zD(x)f(x) + D(x)f(x)yD(x)^{2}[z,x]D(x)f(x) = 0, x, y \in R.$$

From (2.16) and (2.53), we have

(2.54)
$$D(x)f(x)[y,x]D(x)^{2}zD(x)f(x) + D(x)f(x)yD(x)f(x)zD(x)f(x) + D(x)f(x)yD(x)^{2}[z,x]D(x)f(x) = 0, x, y \in R.$$

Comparing (2.50) and (2.54),

$$D(x)f(x)[y,x]D(x)^{2}zD(x)f(x) + D(x)f(x)yD(x)f(x)zD(x)f(x) -2D(x)f(x)yD(x)f(x)zD(x)f(x) = D(x)f(x)[y,x]D(x)^{2}zD(x)f(x) - D(x)f(x)yD(x)f(x)zD(x)f(x) (2.55) = (D(x)f(x)[y,x]D(x)^{2} - D(x)f(x)yD(x)f(x))zD(x)f(x) = 0, x, y \in \mathbb{R}.$$

From (2.55), we obtain

$$(D(x)f(x)[y,x]D(x)^{2} - D(x)f(x)yD(x)f(x))z(D(x)f(x)[y,x]D(x)^{2}$$

$$(2.56) \quad -D(x)f(x)yD(x)f(x)) = 0, x, y \in R.$$

Thus by semiprimeness of R, it is obvious that

(2.57)
$$D(x)f(x)[y,x]D(x)^2 - D(x)f(x)yD(x)f(x) = 0, x, y \in R.$$

Replacing x + tz for x in (2.46), we have

$$g(x+tz)yD(x+tz)^{2} \equiv g(x)yD(x)^{2} + t\{([B(x,z),x] + [f(x),z])yD(x)^{2} + g(x)y(D(z)D(x) + D(x)D(z))\} + t^{2}I_{1}(x,y) + t^{3}I_{2}(x,y) + t^{4}I_{3}(x,y)$$

$$(2.58) + t^{5}g(z)yD(z)^{2} = 0, \ x, y, z \in \mathbb{R}, t \in S_{4}$$

where $I_i, 1 \leq i \leq 3$, denotes the term satisfying the identity (2.58). From (2.46) and (2.58), we obtain

(2.59)
$$t\{([B(x,z),x] + [f(x),z])yD(x)^2 + g(x)y(D(z)D(x) + D(x)D(z))\} + t^2I_1(x,y) + t^3I_2(x,y) + t^4I_3(x,y) = 0, x, y, z \in \mathbb{R}, t \in S_3.$$

Since R is 3!-torsion free by assumption, by Lemma 2.1 the relation (2.59) yields

$$([B(x,z),x] + [f(x),z])yD(x)^2 + g(x)y(D(z)D(x) + D(x)D(z))$$

 $(2.60) = 0, x, y, z \in R.$

Writing ug(x)y for y in (2.60), we get

$$([B(x,z),x] + [f(x),z])ug(x)yD(x)^2$$

(2.61)
$$+g(x)ug(x)y(D(z)D(x) + D(x)D(z)) = 0, u, x, y, z \in R.$$

Combining (2.46) with (2.61),

(2.62)
$$g(x)ug(x)y(D(z)D(x) + D(x)D(z)) = 0, u, x, y, z \in R.$$

Replacing y(D(z)D(x) + D(x)D(z))u for u in (2.62), we get

$$g(x)y(D(z)D(x)+D(x)D(z))ug(x)y(D(z)D(x)+D(x)D(z))\\$$

$$(2.63) = 0, u, x, y, z \in R$$

And so, by semiprimeness of R, it follows that

(2.64)
$$g(x)y(D(z)D(x) + D(x)D(z)) = 0, x, y, z \in R.$$

Replacing x + tw for x in (2.64), we have

$$g(x + tw)y(D(z)D(x + tw) + D(x + tw)D(z) \equiv g(x)y(D(z)D(x) + D(x)D(z)) + t\{([B(x,w),x] + [f(x),w])y(D(z)D(x) + D(x)D(z)) + g(x)y(D(z)D(w) + D(w)D(z))\} + t^2J_1(x,y) + t^3J_2(x,y) + t^4g(w)y(D(z)D(w) + D(w)D(z)) = 0, w, x, y, z \in \mathbb{R}, t \in S_4$$

$$(2.65)$$

where J_1 and J_2 denote the term satisfying the identity (2.65). From (2.64) and (2.65), we obtain

$$t\{([B(x,w),x] + [f(x),w])y(D(z)D(x) + D(x)D(z)) + g(x)y(D(z)D(w) + D(w)D(z))\} + t^2J_1(x,y) + t^3J_2(x,y) = 0, w, x, y, z \in \mathbb{R}, t \in S_3.$$

Since R is 3!-torsion free by assumption, by Lemma 2.1 the relation (2.66) yields

$$([B(x,w),x] + [f(x),w])y(D(z)D(x) + D(x)D(z)) + g(x)y(D(z)D(w))$$

 $(2.67) + D(w)D(z)) = 0, w, x, y, z \in R.$

Replacing ug(x)y for y in (2.67), we get

$$([B(x,w),x] + [f(x),w])yg(x)ug(x)y(D(z)D(x) + D(x)D(z)) +g(x)ug(x)y(D(z)D(w) + D(w)D(z)) = 0, w, x, y, z \in R.$$

Combining (2.64) with (2.68),

(2.69)
$$g(x)ug(x)y(D(z)D(w) + D(w)D(z)) = 0, w, x, y, z \in R.$$

Replacing y(D(z)D(w) + D(w)D(z))u for u in (2.69), we obtain

$$g(x)y(D(z)D(w) + D(w)D(z))ug(x)y(D(z)D(x) + D(x)D(z))$$

 $(2.70) = 0, u, w, x, y, z \in R.$

And so, by semiprimeness of R, it follows from (2.70) that

(2.71)
$$g(x)y(D(z)D(w) + D(w)D(z)) = 0, x, y, z \in R.$$

Let w = z in (2.71). Then we get

(2.72)
$$g(x)yD(z)^2 = 0, x, y, z \in R$$

Replacing x + tw for x in (2.72), we have

$$g(x+tw)yD(z)^{2} \equiv g(x)yD(z)^{2} + t\{([B(x,w),x] + [f(x),w])yD(z)^{2}\}$$

(2.73)
$$+t^{2}K(x,y) + t^{3}g(w)yD(z)^{2} = 0, \ w,x,y,z \in R, t \in S_{3}$$

where K denotes the term satisfying the identity (2.73). From (2.72) and (2.73), we obtain

$$t\{([B(x,w),x] + [f(x),w])yD(z)^2\} + t^2K(x,y)$$

$$(2.74) = 0, w, x, y, z \in R, t \in S_3.$$

Since R is 2!-torsion free by assumption, by Lemma 2.1 the relation (2.74) yields

(2.75)
$$([B(x,w),x] + [f(x),w])yD(z)^2 = 0, w, x, y, z \in R.$$

Replacing wx for w in (2.75), we get

$$([B(x,w),x]x + 3[w,x]f(x) + 3wg(x) + [[w,x],x]D(x) + [f(x),w]x)yD(x)^{2}$$

(2.76) = 0, w, x, y, z \in R.

From (2.72) and (2.76), we have

$$\{[B(x,w),x]x + 3[w,x]f(x) + [[w,x],x]D(x) + [f(x),w]x\}yD(x)^2$$

 $(2.77) = 0, w, x, y, z \in R.$

Substituting xy for y in (2.75), we get

(2.78)
$$([B(x,w),x]x + [f(x),w]x)yD(z)^2 = 0, w, x, y, z \in R.$$

Combining (2.77) with (2.78),

(2.79)
$$(3[w,x]f(x) + [[w,x],x]D(x))yD(z)^2 = 0, w, x, y, z \in R.$$

Replacing D(x)w for w in (2.79), we obtain

$$\{3f(x)wf(x) + 3D(x)[w, x]f(x) + g(x)wD(x) + 2f(x)[w, x]D(x) + D(x)[[w, x], x]D(x)\}yD(z)^2 = 0, w, x, y, z \in \mathbb{R}.$$

Substituting D(x)y for y in (2.80), we have

$$\{3f(x)wf(x)D(x) + 3D(x)[w,x]f(x)D(x) + g(x)wD(x)^{2} + 2f(x)[w,x]D(x)^{2} + 2f(x)[w,x]D(x)^$$

Combining (2.16), (2.66) with (2.81),

(2.82)
$$(2f(x)[w,x]D(x)^{2} + D(x)[[w,x],x]D(x)^{2})yD(z)^{2}$$
$$= 0, w, x, y, z \in R.$$

Left multiplication of (2.82) by D(x) leads to

(2.83)
$$(2D(x)f(x)[w,x]D(x)^2 + D(x)^2[[w,x],x]D(x)^2)yD(z)^2$$
$$= 0, w, x, y, z \in R.$$

Substituting $yD(x)^2w$ for y in (2.50), we get

$$(2.84) 2D(x)f(x)yD(x)^{2}wD(x)f(x) + D(x)^{2}[y,x]D(x)^{2}wD(x)f(x) + D(x)^{2}yD(x)f(x)wD(x)f(x) + D(x)^{2}yf(x)D(x)wD(x)f(x) + D(x)^{2}yD(x)^{2}[w,x]D(x)f(x) = 0, w, x, y, z \in R.$$

Combining (2.16) with (2.84), we obtain

$$2D(x)f(x)yD(x)^{2}wD(x)f(x) + D(x)^{2}[y,x]D(x)^{2}wD(x)f(x) +D(x)^{2}yD(x)f(x)wD(x)f(x) + D(x)^{2}yD(x)^{2}[w,x]D(x)f(x)$$

 $(2.85) = 0, w, x, y, z \in R.$

From (2.49) and (2.85), we have

(2.86)
$$(2D(x)f(x)yD(x)^2 + D(x)^2[y,x]D(x)^2 - D(x)^2yD(x)f(x)) \times wD(x)f(x) = 0, w, x, y, z \in R.$$

Replacing [y, x] for y in (2.86), we get

$$(2D(x)f(x)[y,x]D(x)^{2} + D(x)^{2}[[y,x],x]D(x)^{2} - D(x)^{2}yD(x)f(x))$$

(2.87) $wD(x)f(x) = 0, w, x, y, z \in R.$

Combining (2.49), (2.57) with (2.87),

$$(4D(x)f(x)yD(x)f(x) + D(x)^{2}[[y,x],x]D(x)^{2})wD(x)f(x)$$

 $(2.88) = 0, w, x, y, z \in R.$

From (2.16) and (2.83), we arrive at

$$(2D(x)f(x)[y,x]D(x)^{2} + D(x)^{2}[[y,x],x]D(x)^{2})w[D(z)^{2},z]$$

= $(2D(x)f(x)[y,x]D(x)^{2} + D(x)^{2}[[y,x],x]D(x)^{2})wD(z)f(z)$

(2.89) $= 0, w, x, y, z \in R.$

Let z = x in (2.89). Then

$$(2D(x)f(x)[y,x]D(x)^{2} + D(x)^{2}[[y,x],x]D(x)^{2})wD(x)f(x)$$

 $(2.90) = 0, w, x, y, z \in R.$

Combining (2.88) with (2.90),

$$2(2D(x)f(x)yD(x)f(x) - D(x)f(x)[y,x]D(x)^{2})wD(x)f(x)$$

$$(2.91) = 0, w, x, y, z \in R.$$

Since R is 2!-torsion free by assumption, the relation (2.90) yields

$$(2D(x)f(x)yD(x)f(x) - D(x)f(x)[y,x]D(x)^2)wD(x)f(x) = 0, w, x, y, z \in R.$$

From (2.92), we have

(2.92)

$$(2D(x)f(x)yD(x)f(x) - D(x)f(x)[y,x]D(x)^{2})w(2D(x)f(x)yD(x)f(x))$$

$$(2.93) \quad -D(x)f(x)[y,x]D(x)^{2}) = 0, w, x, y, z \in R.$$

And so, by semiprimeness of R, we get from (2.93)

(2.94)
$$2D(x)f(x)yD(x)f(x) - D(x)f(x)[y,x]D(x)^2 = 0, x, y, z \in R.$$

Combining (2.57) with (2.94),

(2.95)
$$D(x)f(x)yD(x)f(x) = 0, x, y \in R.$$

And so, by semiprimeness of R, it follows from (2.95) that

$$D(x)f(x) = 0, x \in R.$$

(ii) (\Leftarrow): Suppose that

$$(2.96) D(x)f(x) = 0, x, y, z \in R.$$

Replacing x + ty for x in (2.96), we have

$$D(x+ty)[D(x+ty), x+ty] \equiv +t\{D(y)f(x) + D(x)B(x,y)\}$$

(2.97) $+t^2 P(x,y) + t^3 D(y)f(y) = 0, \ x, y \in \mathbb{R}, t \in S_3$

where P denotes the term satisfying the identity (2.97). From (2.96) and (2.97), we obtain

(2.98)
$$t\{D(y)f(x) + D(x)B(x,y)\} + t^2P(x,y) = 0, x, y \in \mathbb{R}, t \in S_3.$$

Since R is 2!-torsion free by assumption, by Lemma 2.1 the relation (2.98) yields

(2.99)
$$D(y)f(x) + D(x)B(x,y) = 0, x, y \in R.$$

Let $y = x^2$ in (2.213). Then using (2.96), we obtain from (2.99)

$$(D(x)x + xD(x))f(x) + 2D(x)(f(x)x + xf(x))$$

(2.100)
$$= 3D(x)xf(x) + xD(x)f(x) + 2D(x)f(x)x = 0, x \in \mathbb{R}.$$

From (2.96) and (2.100), we get

(2.101)
$$3D(x)xf(x) = 3f(x)^2 = -3D(x)g(x) = 0, x \in R.$$

Since R is 3!-torsion free, it follows from (2.101) that

(2.102)
$$f(x)^2 = 0, x \in R,$$

and

(2.103)
$$D(x)g(x) = 0, x \in R.$$

Writing xy for y in (2.99),

$$(xD(y)f(x) + D(x)yf(x) + D(x)(xB(x,y) + 2f(x)y + D(x)[y,x])) = 0$$

$$(2.104) = 0, x, y \in R.$$

Left multiplication of (2.104) by D(x) leads to

(2.105)
$$xD(y)f(x) + xD(x)B(x,y) = 0, x \in R$$

Combining (2.218) with (2.105),

$$(2.106) \quad D(x)yf(x) + f(x)B(x,y) + 2D(x)f(x)y + D(x)^{2}[y,x] = 0, x, y \in R.$$

From (2.96) and (2.106), we have

(2.107)
$$D(x)yf(x) + f(x)B(x,y) + D(x)^{2}[y,x] = 0, x, y \in \mathbb{R}$$

Left multiplication of (2.107) by D(x) yields

(2.108)
$$D(x)^2 y f(x) + D(x) f(x) B(x, y) + D(x)^3 [y, x] = 0, x, y \in \mathbb{R}.$$

Comparing (2.96) and (2.108), we obtain

(2.109)
$$D(x)^2 y f(x) + D(x)^3 [y, x] = 0, x, y \in R$$

Putting yx instead of y in (2.99), we get

$$(D(y)x + yD(x))f(x) + D(x)(B(x,y)x + 2yf(x) + [y,x]D(x))$$

$$(2.110) = 0, x, y \in R.$$

Right multiplication of (2.110) by x leads to

(2.111)
$$D(y)f(x)x + D(x)B(x,y)x = 0, x \in R$$

Combining (2.110) with (2.111),

$$(2.112) - D(y)g(x) + yD(x)f(x) + 2D(x)yf(x) + D(x)[y,x]D(x) = 0, x, y \in \mathbb{R}.$$

From (2.96) and (2.112), we have

$$(2.113) -D(y)g(x) + 2D(x)yf(x) + D(x)[y,x]D(x) = 0, x, y \in R.$$

Writing xy for y in (2.113), we get

$$-xD(y)g(x) - D(x)yg(x) + 2D(x)xyf(x) + D(x)x[y,x]D(x)$$

 $(2.114) = 0, x, y \in R.$

Left multiplication of (2.113) by x leads to

$$(2.115) -xD(y)g(x) + 2xD(x)yf(x) + xD(x)[y,x]D(x) = 0, x, y \in R.$$

Combining (2.114) with (2.115),

(2.116)
$$-D(x)yg(x) + 2f(x)yf(x) + f(x)[y,x]D(x) = 0, x, y \in R.$$

Left multiplication of (2.116) by D(x) gives

$$(2.117) \quad -D(x)^2 yg(x) + 2D(x)f(x)yf(x) + D(x)f(x)[y,x]D(x) = 0, x, y \in \mathbb{R}.$$

Comparing (2.96) and (2.117), we obtain

(2.118)
$$D(x)^2 yg(x) = 0, x, y \in R.$$

Let y = D(x) in (2.113). Then we get

$$(2.119) -D^2(x)g(x) + 2D(x)^2f(x) + D(x)f(x)D(x) = 0, x, y \in R.$$

Combining (2.96) with (2.119),

(2.120)
$$D^2(x)g(x) = 0, x \in R.$$

Writing yD(x) for y in (2.113), we have

$$-D(y)D(x)g(x) - yD^{2}(x)g(x) + 2D(x)yD(x)f(x) + D(x)[y,x]D(x)^{2}$$

$$(2.121) +D(x)yf(x)D(x) = 0, x, y \in R.$$

Combining (2.96), (2.103), (2.120) with (2.121), we arrive at

(2.122)
$$D(x)[y,x]D(x)^2 + D(x)yf(x)D(x) = 0, x, y \in R.$$

Left multiplication of (2.122) by f(x) leads to

(2.123)
$$f(x)D(x)[y,x]D(x)^2 + f(x)D(x)yf(x)D(x) = 0, x, y \in \mathbb{R}.$$

Writing yD(x) for y in (2.116), we get

$$-D(x)yD(x)g(x) + 2f(x)yD(x)f(x) + f(x)[y,x]D(x)^{2} + f(x)yf(x)D(x)$$

(2.124) = 0, x, y \in R.

Comparing (2.96) and (2.103), we obtain from (2.124)

(2.125)
$$f(x)[y,x]D(x)^2 + f(x)yf(x)D(x) = 0, x, y \in R.$$

Substituting D(x)y for y in (2.116),

$$-D(x)^{2}yg(x) + 2f(x)D(x)yf(x) + f(x)D(x)[y,x]D(x) + f(x)^{2}yD(x)$$

$$(2.126) = 0, x, y \in R.$$

Comparing (2.102) and (2.118) and (2.126), we obtain

(2.127)
$$2f(x)D(x)yf(x) + f(x)D(x)[y,x]D(x) = 0, x, y \in R.$$

Right multiplication of (2.127) by D(x) leads to

(2.128)
$$2f(x)D(x)yf(x)D(x) + f(x)D(x)[y,x]D(x)^2 = 0, x, y \in R.$$

From (2.237) and (2.128), we have

$$f(x)D(x) = 0, x \in R.$$

Corollary 2.3. Let R be a 3!-torsion free noncommutative semiprime ring and $D: R \longrightarrow R$ a Jordan derivation. Then

$$[D(x), x]D(x) = 0 \iff D(x)[D(x), x] = 0$$

for all $x \in R$.

Theorem 2.4. Let R be a 3!-torsion free noncommutative semiprime ring, U a Lie ideal of R, and let $D : R \longrightarrow R$ be a Jordan derivation on R. And suppose that [D(x), x]D(x) = 0 for all $x \in U$. Then $[D(x), x]^2 = 0$ for all $x \in U$.

Proof. By Theorem 2.2, we can see that D is a derivation on R. By assumption,

$$(2.129) [D(x), x]D(x) = 0, x \in U$$

Replacing x + ty for x in (2.129), we have

(2.130)
$$[D(x+ty), x+ty]D(x+ty) \equiv +t\{B(x,y)D(x)+f(x)D(y)\}$$
$$+t^{2}H(x,y)+t^{3}[D(y),y]D(y) = 0, \ x,y \in U, t \in S_{3}$$

where H denotes the term satisfying the identity (2.130). From (2.129) and (2.130), we obtain

(2.131)
$$t\{B(x,y)D(x) + f(x)D(y)\} + t^2H(x,y) = 0, x, y \in U, t \in S_3.$$

Since R is 2!-torsion free by assumption, by Lemma 2.1 the relation (2.131) yields

(2.132)
$$B(x,y)D(x) + f(x)D(y) = 0, x, y \in U.$$

Let $y = x^2$ in (2.132). Then using (2.129), we get

(2.133)
$$2(f(x)x + xf(x))D(x) + f(x)(D(x)x + xD(x)) = 0, x \in U.$$

From (2.129) and (2.133), we arrive at

(2.134)
$$3f(x)xD(x) + 2xf(x)D(x) + f(x)D(x)x = 3f(x)^2 = 0, x \in U.$$

Since R is 3!-torsion free, it follows from (2.134) that

(2.135)
$$f(x)^2 = 0, x \in U$$

From (2.129), we obtain

(2.136)
$$0 = [f(x)D(x), x] = g(x)D(x) + f(x)^2, x \in U.$$

From (2.135) and (2.136), we have

(2.137)
$$g(x)D(x) = 0, x \in R.$$

Writing yx for y in (2.132), we get

$$(B(x,y)x + 2yf(x) + [y,x]D(x))D(x) + f(x)(D(y)x + yD(x))$$

 $(2.138) = 0, x, y \in U.$

Right multiplication of (2.132) by x leads to

(2.139)
$$B(x,y)D(x)x + f(x)D(y)x = 0, x, y \in U.$$

Combining (2.138) with (2.139),

$$(2.140) \quad -B(x,y)f(x) + 2yf(x)D(x) + [y,x]D(x)^2 + f(x)yD(x) = 0, x, y \in R.$$

From (2.129) and (2.140), we have

(2.141)
$$-B(x,y)f(x) + [y,x]D(x)^2 + f(x)yD(x) = 0, x, y \in U.$$

Substituting x^2 for y in (2.141), we get

(2.142)
$$-2(f(x)x + xf(x))f(x) + f(x)x^2D(x) = 0, x \in R.$$

Comparing (2.135) and (2.137), we obtain

(2.143)
$$\begin{aligned} -2f(x)xf(x) - xf(x)^2 - f(x)(f(x)x + xf(x)) \\ &= -3f(x)xf(x) = -3g(x)f(x) = 3f(x)g(x) = 0, x \in \mathbb{R}. \end{aligned}$$

Since R is 3!-torsion free by assumption, the relation (2.143) yields

(2.144)
$$g(x)f(x) = f(x)g(x) = 0, x \in U.$$

Right multiplication of (2.141) by D(x) leads to

(2.145)
$$-B(x,y)f(x)^{2} + [y,x]D(x)^{2}f(x) + f(x)yD(x)f(x) = 0, x, y \in U.$$

From (2.135) and (2.145), we have

(2.146)
$$[y,x]D(x)^2f(x) + f(x)yD(x)f(x) = 0, x, y \in U.$$

Substituting xy for y in (2.146), we get

(2.147)
$$x[y,x]D(x)^2f(x) + f(x)xyD(x)f(x) = 0, x, y \in U.$$

Left multiplication of (2.147) by D(x) gives

(2.148)
$$-x[y,x]D(x)^{2}f(x) + xf(x)yD(x)f(x) = 0, x, y \in U.$$

From (2.147) and (2.148), we have

(2.149)
$$g(x)yD(x)f(x) = 0, x, y \in U.$$

Replacing yx for y in (2.149), we get

$$(2.150) g(x)yxD(x)f(x) = 0, x, y \in U.$$

Right multiplication of (2.149) by x yields

(2.151)
$$g(x)yD(x)f(x)x = 0, x, y \in U.$$

From (2.135), (2.150) and (2.151), we have

(2.152)
$$g(x)yD(x)g(x) = 0, x, y \in U.$$

Left multiplication of (2.152) by D(x) leads to

(2.153)
$$D(x)g(x)yD(x)g(x) = 0, x, y \in U.$$

Thus by semiprimeness of R, it is clear that

(2.154)
$$D(x)g(x) = 0, x \in U.$$

Putting xy instead of y in (2.141), we get

$$-(xB(x,y) + 2f(x)y + D(x)[y,x])f(x) + x[y,x]D(x)^{2} + f(x)xyD(x)$$

$$(2.155) = 0, x, y \in U.$$

Left multiplication of (2.141) by x yields

(2.156)
$$-xB(x,y)f(x) + x[y,x]D(x)^2 + xf(x)yD(x) = 0, x, y \in U.$$

Combining (2.155) with (2.156),

(2.157)
$$-2f(x)yf(x) - D(x)[y,x]f(x) + g(x)yD(x) = 0, x, y \in U.$$

Right multiplication of (2.157) by D(x) leads to

$$(2.158) \quad -2f(x)yf(x)D(x) - D(x)[y,x]f(x)D(x) + g(x)yD(x)^2 = 0, x \in U.$$

Combining (2.129) with (2.158),

(2.159)
$$g(x)yD(x)^2 = 0, x, y \in U$$

Replacing yD(x) for y in (2.158), we get

$$-2f(x)yD(x)f(x) - D(x)[y,x]D(x)f(x) - D(x)yf(x)^{2} + g(x)yD(x)^{2}$$

(2.160) = 0, x \in U.

From (2.135) and (2.160), we have

(2.161)
$$-2f(x)yD(x)f(x) - D(x)[y,x]D(x)f(x) + g(x)yD(x)^2 = 0, x, y \in U.$$

Comparing (2.159) and (2.161),

(2.162)
$$2f(x)yD(x)f(x) + D(x)[y,x]D(x)f(x) = 0, x, y \in U.$$

Left multiplication of (2.162) by D(x) gives

(2.163)
$$2D(x)f(x)yD(x)f(x) + D(x)^{2}[y,x]D(x)f(x) = 0, x, y \in U.$$

Substituting f(x)y for y in (2.162), we get

$$2f(x)^2 y D(x) f(x) + D(x) f(x) [y, x] D(x) f(x) + D(x) g(x) y D(x) f(x)$$

$$(2.164) = 0, x, y \in U.$$

Combining (2.135), (2.154) with (2.164), we obtain

(2.165)
$$D(x)f(x)[y,x]D(x)f(x) = 0, x, y \in U.$$

Substituting $yD(x)^2z$ for y in (2.165),

$$D(x)f(x)[y,x]D(x)^{2}zD(x)f(x) + D(x)f(x)y[D(x)^{2},x]zD(x)f(x) + D(x)f(x)yD(x)^{2}[z,x]D(x)f(x) = 0, x, y \in U.$$
(2.166)

From (2.129) and (2.166), we have

$$D(x)f(x)[y,x]D(x)^{2}zD(x)f(x) + D(x)f(x)yD(x)f(x)zD(x)f(x) + D(x)f(x)yD(x)^{2}[z,x]D(x)f(x) = 0, x, y \in U.$$

Comparing (2.163) and (2.167),

$$D(x)f(x)[y,x]D(x)^{2}zD(x)f(x) + D(x)f(x)yD(x)f(x)zD(x)f(x) -2D(x)f(x)yD(x)f(x)zD(x)f(x) = D(x)f(x)[y,x]D(x)^{2}zD(x)f(x) - D(x)f(x)yD(x)f(x)zD(x)f(x) (2.168) = {D(x)f(x)[y,x]D(x)^{2} - D(x)f(x)yD(x)f(x)}zD(x)f(x) = 0, x, y \in U$$

From (2.168), we obtain

$$\{D(x)f(x)[y,x]D(x)^{2} - D(x)f(x)yD(x)f(x)\}z(D(x)f(x)[y,x]D(x)^{2} - D(x)f(x)yD(x)f(x)) = 0, x, y \in U.$$
(2.169) $-D(x)f(x)yD(x)f(x) = 0, x, y \in U.$

Thus by semiprimeness of R, it is obvious that

(2.170)
$$D(x)f(x)[y,x]D(x)^2 - D(x)f(x)yD(x)f(x) = 0, x, y \in U.$$

Replacing x + tz for x in (2.159), we have

$$g(x+tz)yD(x+tz)^{2} \equiv g(x)yD(x)^{2} + t\{([B(x,z),x] + [f(x),z])yD(x)^{2} + g(x)y(D(z)D(x) + D(x)D(z))\} + t^{2}L_{1}(x,y) + t^{3}L_{2}(x,y) + t^{4}L_{3}(x,y)$$

$$(2.171) + t^{5}g(z)yD(z)^{2} = 0, \ x, y, z \in U, t \in S_{4}$$

where $L_i, 1 \le i \le 3$, denotes the term satisfying the identity (2.171). From (2.159) and (2.171), we obtain

(2.172)
$$t\{([B(x,z),x] + [f(x),z])yD(x)^2 + g(x)y(D(z)D(x) + D(x)D(z))\} + t^2L_1(x,y) + t^3L_2(x,y) + t^4L_3(x,y) = 0, x, y, z \in U, t \in S_3.$$

Since R is 3!-torsion free by assumption, by Lemma 2.1 the relation (2.172) yields

$$([B(x,z),x] + [f(x),z])yD(x)^2 + g(x)y(D(z)D(x) + D(x)D(z))$$

$$(2.173) = 0, x, y, z \in U.$$

Writing ug(x)y for y in (2.173), we get

$$([B(x,z),x] + [f(x),z])ug(x)yD(x)^2 + g(x)ug(x)y(D(z)D(x) + D(x)D(z))$$

(2.174) = 0, u, x, y, z \in U.

Combining (2.159) with (2.174),

(2.175)
$$g(x)ug(x)y(D(z)D(x) + D(x)D(z)) = 0, u, x, y, z \in U.$$

Replacing y(D(z)D(x) + D(x)D(z))u for u in (2.175), we obtain

$$g(x)y(D(z)D(x) + D(x)D(z))ug(x)y(D(z)D(x) + D(x)D(z))$$

 $(2.176) = 0, u, x, y, z \in U.$

And so, by semiprimeness of R, it follows that

(2.177)
$$g(x)y(D(z)D(x) + D(x)D(z)) = 0, x, y, z \in U.$$

Replacing x + tw for x in (2.177), we have

$$g(x + tw)y(D(z)D(x + tw) + D(x + tw)D(z)$$

$$\equiv g(x)y(D(z)D(x) + D(x)D(z)) + t\{([B(x,w), x] + [f(x), w])y(D(z)D(x) + D(x)D(z)) + g(x)y(D(z)D(w) + D(w)D(z))\} + t^2M_1(x, y) + t^3M_2(x, y)$$

$$(2.178) + t^4g(w)y(D(z)D(w) + D(w)D(z)) = 0, \ w, x, y, z \in U, t \in S_4$$

where M_1 and M_2 denote the term satisfying the identity (2.178). From (2.177) and (2.178), we arrive at

(2.179)
$$t\{([B(x,w),x] + [f(x),w])y(D(z)D(x) + D(x)D(z)) + g(x)y(D(z)D(w) + D(w)D(z))\} + t^2M_1(x,y) + t^3M_2(x,y) = 0, w, x, y, z \in U, t \in S_3.$$

Since R is 3!-torsion free by assumption, by Lemma 2.1 the relation (2.179) yields

([
$$B(x, w), x$$
] + [$f(x), w$]) $y(D(z)D(x) + D(x)D(z)$)
+ $g(x)y(D(z)D(w) + D(w)D(z)) = 0, w, x, y, z \in U.$

Replacing ug(x)y for y in (2.180), we get

$$([B(x,w),x] + [f(x),w])yg(x)ug(x)y(D(z)D(x) + D(x)D(z)) +g(x)ug(x)y(D(z)D(w) + D(w)D(z)) = 0, w, x, y, z \in U.$$

Combining (2.177) with (2.181),

(2.182)
$$g(x)ug(x)y(D(z)D(w) + D(w)D(z)) = 0, w, x, y, z \in U.$$

Replacing y(D(z)D(w) + D(w)D(z))u for u in (2.182), we obtain

$$g(x)y(D(z)D(w) + D(w)D(z))ug(x)y(D(z)D(x) + D(x)D(z))$$

 $(2.183) = 0, u, w, x, y, z \in U.$

And so, by semiprimeness of R, it follows from (2.183) that

(2.184)
$$g(x)y(D(z)D(w) + D(w)D(z)) = 0, x, y, z \in U.$$

Let w = z in (2.184). Then we get

(2.185)
$$g(x)yD(z)^2 = 0, x, y, z \in U$$

Replacing x + tw for x in (2.185), we have

$$g(x+tw)yD(z)^{2} \equiv g(x)yD(z)^{2} + t\{([B(x,w),x] + [f(x),w])yD(z)^{2}\}$$

(2.186) $+t^{2}P(x,y) + t^{3}g(w)yD(z)^{2} = 0, w, x, y, z \in U, t \in S_{3}$

where P denotes the term satisfying the identity (2.186). From (2.185) and (2.186), we obtain

(2.187)
$$t\{([B(x,w),x] + [f(x),w])yD(z)^2\} + t^2P(x,y) = 0, w, x, y, z \in U, t \in S_3.$$

Since R is 2!-torsion free by assumption, by Lemma 2.1 the relation (2.187) yields

(2.188)
$$([B(x,w),x] + [f(x),w])yD(z)^2 = 0, w, x, y, z \in U.$$

Replacing wx for w in (2.188), we get

 $([B(x,w),x]x + 3[w,x]f(x) + 3wg(x) + [[w,x],x]D(x) + [f(x),w]x)yD(x)^2$ $(2.189) = 0, w, x, y, z \in U.$

From (2.185) and (2.189), we have

$$([B(x,w),x]x + 3[w,x]f(x) + [[w,x],x]D(x) + [f(x),w]x)yD(x)^{2}$$

 $(2.190) = 0, w, x, y, z \in U.$

Substituting xy for y in (2.188),

(2.191)
$$([B(x,w),x]x + [f(x),w]x)yD(z)^2 = 0, w, x, y, z \in U.$$

Combining (2.190) with (2.191),

(2.192)
$$(3[w,x]f(x) + [[w,x],x]D(x))yD(z)^2 = 0, w, x, y, z \in U.$$

Replacing D(x)w for w in (2.192), we obtain

$$(3f(x)wf(x) + 3D(x)[w, x]f(x) + g(x)wD(x) + 2f(x)[w, x]D(x)$$

(2.193)
$$+D(x)[[w,x],x]D(x))yD(z)^2 = 0, w, x, y, z \in U.$$

Substituting D(x)y for y in (2.193), we have

$$(3f(x)wf(x)D(x) + 3D(x)[w, x]f(x)D(x) + g(x)wD(x)^{2})$$

(2.194) $+2f(x)[w,x]D(x)^2 + D(x)[[w,x],x]D(x)^2)yD(z)^2 = 0, w, x, y, z \in U.$ Combining (2.129), (2.179) with (2.194),

$$(2.195) (2f(x)[w,x]D(x)^2 + D(x)[[w,x],x]D(x)^2)yD(z)^2 = 0, w, x, y, z \in U.$$
 Left multiplication of (2.195) by $D(x)$ leads to

$$(2D(x)f(x)[w,x]D(x)^{2} + D(x)^{2}[[w,x],x]D(x)^{2})yD(z)^{2}$$

= 0, w, x, y, z \in U.

Left multiplication of (2.162) by D(x) yields

(2.197)
$$2D(x)f(x)yD(x)f(x) + D(x)^{2}[y,x]D(x)f(x) = 0, x, y \in U.$$

Substituting $yD(x)^2w$ for y in (2.197), we get

$$\begin{split} & 2D(x)f(x)yD(x)^2wD(x)f(x) + D(x)^2[y,x]D(x)^2wD(x)f(x) \\ & + D(x)^2y[D(x)^2,x]wD(x)f(x) + D(x)^2yD(x)^2[w,x]D(x)f(x) \end{split}$$

 $(2.198) = 0, w, x, y, z \in U.$

(2.196)

Combining (2.129) with (2.198), we obtain

$$2D(x)f(x)yD(x)^{2}wD(x)f(x) + D(x)^{2}[y,x]D(x)^{2}wD(x)f(x) +D(x)^{2}yD(x)f(x)wD(x)f(x) + D(x)^{2}yD(x)^{2}[w,x]D(x)f(x)$$

$$(2.199) = 0, w, x, y, z \in U.$$

From (2.162) and (2.199),

(2.200)
$$(2D(x)f(x)yD(x)^2 + D(x)^2[y,x]D(x)^2 - D(x)^2yD(x)f(x))$$
$$wD(x)f(x) = 0, w, x, y, z \in U.$$

Replacing [y, x] for y in (2.200), we have

$$(2D(x)f(x)[y,x]D(x)^{2} + D(x)^{2}[[y,x],x]D(x)^{2} - D(x)^{2}yD(x)f(x))$$

$$(2.201) \qquad wD(x)f(x) = 0, w, x, y, z \in U.$$

Combining (2.162), (2.170) with (2.201),

$$(4D(x)f(x)yD(x)f(x) + D(x)^{2}[[y,x],x]D(x)^{2})wD(x)f(x)$$

 $(2.202) = 0, w, x, y, z \in U.$

From (2.129) and (2.196),

$$(2D(x)f(x)[y,x]D(x)^{2} + D(x)^{2}[[y,x],x]D(x)^{2}w[D(z)^{2},z]$$

= $(2D(x)f(x)[y,x]D(x)^{2} + D(x)^{2}[[y,x],x]D(x)^{2}wD(z)f(z)$

 $(2.203) = 0, w, x, y, z \in U.$

Let z = x in (2.203). Then

(2.204)
$$(2D(x)f(x)[y,x]D(x)^2 + D(x)^2[[y,x],x]D(x)^2wD(x)f(x) = 0, w, x, y, z \in U.$$

Combining (2.203) with (2.204),

$$2(2D(x)f(x)yD(x)f(x) - D(x)f(x)[y,x]D(x)^2wD(x)f(x)$$

 $(2.205) = 0, w, x, y, z \in U.$

Since R is 2!-torsion free by assumption, the relation (2.204) yields

$$(2D(x)f(x)yD(x)f(x) - D(x)f(x)[y,x]D(x)^2wD(x)f(x)$$

 $(2.206) = 0, w, x, y, z \in U.$

From (2.206), we have

$$(2D(x)f(x)yD(x)f(x) - D(x)f(x)[y,x]D(x)^2)w(2D(x)f(x)yD(x)f(x))$$

(2.207) $-D(x)f(x)[y,x]D(x)^2) = 0, w, x, y, z \in U.$

And so, by semiprimeness of R, it follows from (2.207) that

(2.208)
$$2D(x)f(x)yD(x)f(x) - D(x)f(x)[y,x]D(x)^2 = 0, x, y, z \in U.$$

Combining (2.170) with (2.208),

(2.209)
$$D(x)f(x)yD(x)f(x) = 0, x, y \in U.$$

And so, by semiprimeness of R, obtain from (2.209)

$$D(x)f(x) = 0, x \in U.$$

 (\Leftarrow) : Suppose that

$$(2.210) D(x)f(x) = 0, x \in R$$

Replacing x + ty for x in (2.210), we have

(2.211)
$$D(x+ty)[D(x+ty), x+ty] \equiv +t\{D(y)f(x) + D(x)B(x,y)\} +t^2Q(x,y) + t^3D(y)f(y) = 0, x, y \in R, t \in S_3$$

where Q denotes the term satisfying the identity (2.211). From (2.210) and (2.211), we get

(2.212)
$$t\{D(y)f(x) + D(x)B(x,y)\} + t^2Q(x,y) = 0, \ x, y \in \mathbb{R}, t \in S_3.$$

Since R is 2!-torsion free by assumption, by Lemma 2.1 the relation (2.212) yields

(2.213)
$$D(y)f(x) + D(x)B(x,y) = 0, x, y \in R.$$

Let $y = x^2$ in (2.213). Then using (2.210), we obtain from (2.213)

(2.214)
$$(D(x)x + xD(x))f(x) + 2D(x)(f(x)x + xf(x)) = 3D(x)xf(x) + xD(x)f(x) + 2D(x)f(x)x = 0, x \in R.$$

From (2.210) and (2.214), we get

(2.215)
$$3D(x)xf(x) = 3f(x)^2 = -3D(x)g(x) = 0, x \in R.$$

Since R is 3!-torsion free, it follows from (2.215) that

(2.216)
$$f(x)^2 = 0, x \in R,$$

and

(2.217)
$$D(x)g(x) = 0, x \in R.$$

Writing xy for y in (2.213), we obtain

$$(xD(y)f(x) + D(x)yf(x) + D(x)(xB(x,y) + 2f(x)y + D(x)[y,x])$$

$$(2.218) = 0, x, y \in R.$$

Left multiplication of (2.218) by D(x) leads to

(2.219)
$$xD(y)f(x) + xD(x)B(x,y) = 0, x \in \mathbb{R}.$$

Combining (2.218) with (2.219),

$$(2.220) \quad D(x)yf(x) + f(x)B(x,y) + 2D(x)f(x)y + D(x)^{2}[y,x] = 0, x, y \in \mathbb{R}.$$

From (2.210) and (2.220), we have

(2.221)
$$D(x)yf(x) + f(x)B(x,y) + D(x)^{2}[y,x] = 0, x, y \in R.$$

Left multiplication of (2.221) by D(x) yields

(2.222)
$$D(x)^2 y f(x) + D(x) f(x) B(x, y) + D(x)^3 [y, x] = 0, x, y \in \mathbb{R}.$$

Comparing (2.210) and (2.222),

(2.223)
$$D(x)^2 y f(x) + D(x)^3 [y, x] = 0, x, y \in \mathbb{R}.$$

Putting yx instead of y in (2.213), we get

$$(D(y)x + yD(x))f(x) + D(x)(B(x,y)x + 2yf(x) + [y,x]D(x))$$

 $(2.224) = 0, x, y \in R.$

Right multiplication of (2.224) by x gives

(2.225)
$$D(y)f(x)x + D(x)B(x,y)x = 0, x \in R.$$

Combining (2.224) with (2.225),

$$(2.226) \quad -D(y)g(x) + yD(x)f(x) + 2D(x)yf(x) + D(x)[y,x]D(x) = 0, x, y \in \mathbb{R}.$$

From (2.210) and (2.226), we have

$$(2.227) -D(y)g(x) + 2D(x)yf(x) + D(x)[y,x]D(x) = 0, x, y \in R.$$

Writing xy for y in (2.227), we get

$$-xD(y)g(x) - D(x)yg(x) + 2D(x)xyf(x) + D(x)x[y,x]D(x)$$

$$(2.228) = 0, x, y \in R.$$

Left multiplication of (2.227) by x leads to

(2.229)
$$-xD(y)g(x) + 2xD(x)yf(x) + xD(x)[y,x]D(x) = 0, x, y \in R.$$

Combining (2.228) with (2.229),

$$(2.230) -D(x)yg(x) + 2f(x)yf(x) + f(x)[y,x]D(x) = 0, x, y \in R.$$

Left multiplication of (2.230) by D(x) yields

 $(2.231) \quad -D(x)^2 yg(x) + 2D(x)f(x)yf(x) + D(x)f(x)[y,x]D(x) = 0, x, y \in R.$

Comparing (2.210) and (2.231), we obtain

(2.232)
$$D(x)^2 yg(x) = 0, x, y \in R.$$

Let y = D(x) in (2.227). Then we get

(2.233)
$$-D^{2}(x)g(x) + 2D(x)^{2}f(x) + D(x)f(x)D(x) = 0, x, y \in \mathbb{R}.$$

Combining (2.210) with (2.233),

(2.234)
$$D^2(x)g(x) = 0, x \in R$$

Writing yD(x) for y in (2.227), we have

$$-D(y)D(x)g(x) - yD^{2}(x)g(x) + 2D(x)yD(x)f(x) + D(x)[y,x]D(x)^{2}$$

$$(2.235) +D(x)yf(x)D(x) = 0, x, y \in R.$$

Combining (2.210), (2.217), (2.234) with (2.235),

(2.236)
$$D(x)[y,x]D(x)^2 + D(x)yf(x)D(x) = 0, x, y \in R.$$

Left multiplication of (2.236) by f(x) leads to

(2.237)
$$f(x)D(x)[y,x]D(x)^2 + f(x)D(x)yf(x)D(x) = 0, x, y \in R.$$

Writing yD(x) for y in (2.230), we get

$$-D(x)yD(x)g(x) + 2f(x)yD(x)f(x) + f(x)[y,x]D(x)^{2} + f(x)yf(x)D(x)$$

(2.238) = 0, x, y \in R.

Comparing (2.210) and (2.217), we obtain from (2.238)

(2.239)
$$f(x)[y,x]D(x)^2 + f(x)yf(x)D(x) = 0, x, y \in R.$$

Substituting D(x)y for y in (2.230), we have

$$-D(x)^2 yg(x) + 2f(x)D(x)yf(x) + f(x)D(x)[y,x]D(x) + f(x)^2 yD(x)$$
(2.240) = 0, x, y \in R.

From
$$(2.216)$$
, (2.232) and (2.240) , we obtain

(2.241)
$$2f(x)D(x)yf(x) + f(x)D(x)[y,x]D(x) = 0, x, y \in R.$$

Right multiplication of (2.241) by D(x) leads to

$$(2.242) 2f(x)D(x)yf(x)D(x) + f(x)D(x)[y,x]D(x)^2 = 0, x, y \in \mathbb{R}$$

From (2.237) and (2.242),

$$f(x)D(x) = 0, x \in R.$$

Theorem 2.5. Let A be a noncommutative Banach algebra. Suppose there exists a continuous linear Jordan derivation $D: A \longrightarrow A$. Then we have

 $[D(x), x]D(x) \in rad(A) \iff D(x)[D(x), x] \in rad(A)$

for all $x \in A$.

Proof. By the result of B.E. Johnson and A.M. Sinclair^[5] any linear derivation on a semisimple Banach algebra is continuous. Sinclair [12] proved that every continuous linear Jordan derivation on a Banach algebra leaves the primitive ideals of Ainvariant. Hence for any primitive ideal $P \subseteq A$ one can introduce a linear Jordan derivation $D_P: A/P \longrightarrow A/P$, where A/P is a prime and factor Banach algebra, by $D_P(\hat{x}) = D(x) + P$, $\hat{x} = x + P$. Then D is a derivation on A/P. By the assumption that $D(x)^2 f(x) \in \operatorname{rad}(A), x \in A$, we obtain $(D_P(\hat{x}))^2 [D_P(\hat{x}), \hat{x}] = 0, \hat{x} \in A/P$, since all the assumptions of Theorem 2.4 are fulfilled. And since the prime and factor algebra A/P is noncommutative, from Theorem 2.4 we have $[D_P(\hat{x}), \hat{x}]^7 = 0, \ \hat{x} \in A/P$. And for each P, by the elementary properties of the spectral radius r_P in a Banach algebra A/P, it follows that $r_P([D_P(\hat{x}), \hat{x}])^7 = r_P([D_P(\hat{x}), \hat{x}]^7) = 0$ for all $\hat{x} \in A/P$. Hence we obtain $r_P([D_P(\hat{x}), \hat{x}]) = 0$ for all $\hat{x} \in A/P$. Thus $[D_P(\hat{x}), \hat{x}] \in Q(A/P)$ for all $\hat{x} \in A/P$. On the one hand, since D is continuous, we see that D_P is also continuous. Thus by Theorem 2.3, we obtain $D_P(A/P) \subseteq \operatorname{rad}(A/P)$. But since A/P is semisimple, $D_P(A/P) = \{0\}$ for all primitive ideals of A. Hence we see that $D(A) \subseteq P$ for all primitive ideals of A. And so, $D(A) \subseteq \operatorname{rad}(A)$. On the other hand, In case A/P is a commutative Banach algebra, one can conclude that $D_P = 0$ as well, since A/P is semisimple and since we know that there are no nonzero linear derivations on a commutative semisimple Banach algebra. In other words, $D(x) \in P$ for all primitive ideals of A and all $x \in A$. i.e. we get $D(A) \subseteq \operatorname{rad}(A)$. Therefore in any case we have $D(A) \subseteq \operatorname{rad}(A)$.

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