

## A QUADRATIC INTEGRAL EQUATION IN THE SPACE OF FUNCTIONS WITH TEMPERED MODULI OF CONTINUITY<sup>†</sup>

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**ABSTRACT.** In this paper, we investigate existence of solutions to a class of quadratic integral equation of Fredholm type in the space of functions with tempered moduli of continuity. Two numerical examples are given to illustrate our results.

AMS Mathematics Subject Classification : 26A33, 26A51, 26D15.

*Key words and phrases* : Quadratic integral equation, Tempered moduli of continuity, Schauder fixed point theorem.

### 1. Introduction

Fractional integral and differential equations play increasingly important roles in the modeling of real world problems. Some problems in physics, mechanics and other fields can be described with the help of all kinds of fractional differential and integral equations. For more recent development on Riemann-Liouville, Caputo and Hadamard fractional calculus, the reader can refer to the monographs [1, 2, 3, 4, 5, 6].

Quadratic integral equations arise naturally in applications of real world problems. For example, problems in the theory of radiative transfer in the theory of neutron transport and in the kinetic theory of gases lead to the quadratic equation [7, 8, 9, 10]. There are many interesting existence results for all kinds of quadratic integral equations, one can refer to [11, 12, 13, 14, 15, 16, 17]. Our group extend to study the existence, local attractivity and stability of solutions

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Received July 25, 2014. Revised November 2, 2014. Accepted November 4, 2014.  
\*Corresponding author. <sup>†</sup> The first and second authors acknowledge the support by the National Natural Science Foundation of China (11201091), Outstanding Scientific and Technological Innovation Talent Award of Education Department of Guizhou Province and Doctor Project of Guizhou Normal College (13BS010). The third author acknowledges the National Natural Science Foundation of Hunan Province under Grant 13JJ3120.

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to fractional version Urysohn type quadratic integral equations [18] and Erdélyi-Kober type quadratic integral equations [19] and Hadamard types quadratic integral equations [20] in the space of continuous functions.

Very recently, Banaś and Nalepa [21] study the space of real functions defined on a bounded metric space and having growths tempered by a modulus of continuity and derive the existence theorem for some quadratic integral equations of Fredholm type in the space of functions satisfying the Hölder condition. Further, Caballero et al. [22] study the solvability of a quadratic integral equation of Fredholm type in Hölder spaces.

The aim of the paper is to investigate the existence of solutions of the following integral equation of Fredholm type

$$x(t) = f(t, x(t)) + x(t) \int_a^b k(t, \tau)x(\tau)d\tau, \quad t \in [a, b], \quad (1)$$

in  $C_{\omega, g}[a, b]$  (see Section 2), where the functions  $f$  and  $k$  will be defined in the later.

By using a sufficient condition for the relative compactness in the space of functions with tempered moduli of continuity (see Theorem 2.5) and the classical Schauder fixed point theorem, we derive new existence result (see Theorem 3.5). Finally, two numerical examples are given to illustrate our results.

## 2. Preliminaries

**Definition 2.1** (see Section 2 [21]). A function  $\omega : \mathbb{R}_+ \rightarrow \mathbb{R}_+$  is said to be a modulus of continuity if  $\omega(0) = 0$ ,  $\omega(\epsilon) > 0$  for  $\epsilon > 0$ , and  $\omega$  is nondecreasing on  $\mathbb{R}$ .

Let  $C[a, b]$  be the space of continuous functions on  $[a, b]$  equipped with  $\|x\|_\infty = \sup\{|x(t)| : t \in [a, b]\}$  for  $x \in C[a, b]$ . We denote  $C_{\omega, g}[a, b]$  be the set of all real functions defined on  $[a, b]$  such that their growths are tempered by the modulus of continuity  $\omega$  with respect to a function  $g$ . That is, there exists a constant  $H_x^{\omega, g} > 0$  such that

$$|x(t) - x(s)| \leq H_x^{\omega, g} \omega(g(t) - g(s)) \quad (2)$$

for all  $t, s \in [a, b]$  where  $g : [a, b] \rightarrow \mathbb{R}$  is a monotonic function.

Without loss of generality, we suppose that the above  $g$  be a increasing function and  $g(t) - g(s) \geq 0$  for  $t \geq s$  in the this paper. Obviously,  $C_{\omega, g}[a, b]$  is a linear subspace of  $C[a, b]$ .

For  $x \in C_{\omega, g}[a, b]$ , we denote  $H_x^{\omega, g}$  be the least possible constant for which inequality (2) is satisfied. More precisely, we set

$$H_x^{\omega, g} = \sup \left\{ \frac{|x(t) - x(s)|}{\omega(g(t) - g(s))} : t, s \in [a, b], t > s \right\}.$$

Next, the space  $C_{\omega, g}[a, b]$  can be equipped with the norm

$$\|x\|_{\omega, g} = |x(a)| + \sup \left\{ \frac{|x(t) - x(s)|}{\omega(g(t) - g(s))} : t, s \in [a, b], t > s \right\},$$

for  $x \in C_{\omega,g}[a, b]$ . Then  $(C_{\omega,g}[a, b], \|\cdot\|_{\omega,g})$  is a Banach space.

Inspired by the properties of the space of Hölder functions in [21, see (41), (45)], we give the following sharp results.

**Lemma 2.2.** *For any  $x \in C_{\omega,g}[a, b]$ , the following inequality is satisfied*

$$\|x\|_{\infty} \leq \max\{1, \omega(g(b) - g(a))\} \|x\|_{\omega,g}.$$

*Proof.* For any  $x \in C_{\omega,g}[a, b]$  and  $t \in [a, b]$  we obtain

$$\begin{aligned} & |x(t)| \\ & \leq |x(t) - x(a)| + |x(a)| \\ & \leq \sup\{|x(t) - x(s)| : t, s \in [a, b]\} + |x(a)| \\ & = |x(a)| + \sup\left\{\frac{|x(t) - x(s)|}{\omega(g(t) - g(s))} \cdot \omega(g(t) - g(s)) : t, s \in [a, b], t > s\right\} \\ & \leq |x(a)| + \omega(g(b) - g(a)) \sup\left\{\frac{|x(t) - x(s)|}{\omega(g(t) - g(s))} : t, s \in [a, b], t > s\right\} \\ & \leq \max\{1, \omega(g(b) - g(a))\} \\ & \quad \times \left\{|x(a)| + \sup\left\{\frac{|x(t) - x(s)|}{\omega(g(t) - g(s))} : t, s \in [a, b], t > s\right\}\right\} \\ & \leq \max\{1, \omega(g(b) - g(a))\} \|x\|_{\omega,g}. \end{aligned}$$

□

**Lemma 2.3.** *Suppose that  $\omega_2(g(t) - g(s)) \leq G\omega_1(g(t) - g(s))$  for  $t, s \in [a, b]$  where  $G > 0$ . Then we have*

$$C_{\omega_2,g}[a, b] \subset C_{\omega_1,g}[a, b] \subset C[a, b].$$

Moreover, for any  $x \in C_{\omega_2,g}[a, b]$  the following inequality holds

$$\|x\|_{\omega_1,g} \leq \max\{1, G\} \|x\|_{\omega_2,g}.$$

*Proof.* For any  $x \in C_{\omega_2,g}[a, b]$ , we obtain

$$|x(t) - x(s)| \leq H_x^{\omega_2,g} \omega_2(g(t) - g(s)) \leq GH_x^{\omega_2,g} \omega_1(g(t) - g(s)).$$

This shows that  $x \in C_{\omega_1,g}[a, b]$  and hence we infer that inclusions hold. Further,

$$\begin{aligned} \|x\|_{\omega_1,g} &= |x(a)| + \sup\left\{\frac{|x(t) - x(s)|}{\omega_1(g(t) - g(s))} : t, s \in [a, b], t > s\right\} \\ &\leq |x(a)| + G \sup\left\{\frac{|x(t) - x(s)|}{\omega_2(g(t) - g(s))} : t, s \in [a, b], t > s\right\} \\ &\leq \max\{1, G\} \|x\|_{\omega_2,g}. \end{aligned}$$

□

**Remark 2.1.** In particular, if  $\lim_{\epsilon \rightarrow 0} \frac{\omega_2(\epsilon)}{\omega_1(\epsilon)} = 0$  then the above imbedding relations also hold and for any  $x \in C_{\omega_2,g}[a, b]$ , we have  $\|x\|_{\omega_1,g} \leq \max\{1, M\} \|x\|_{\omega_2,g} = \|x\|_{\omega_2,g}$ , where  $M$  is an arbitrarily small positive number.

**Theorem 2.4** (see Theorem 5 [21]). *Assume that  $\omega_1, \omega_2$  are moduli of continuity being continuous at zero and such that  $\lim_{\epsilon \rightarrow 0} \frac{\omega_2(\epsilon)}{\omega_1(\epsilon)} = 0$ . Further, assume that  $(X, d)$  is a compact metric space. Then, if  $A$  is a bounded subset of the space  $C_{\omega_2, g}(X)$  then  $A$  is relatively compact in the space  $C_{\omega_1, g}(X)$ .*

**Theorem 2.5.** *Suppose that  $\lim_{\epsilon \rightarrow 0} \frac{\omega_2(\epsilon)}{\omega_1(\epsilon)} = 0$ . Denote  $B_r^{\omega_2, g} = \{x \in C_{\omega_2, g}[a, b] : \|x\|_{\omega_2, g} \leq r\}$ . Then  $B_r^{\omega_2, g}$  is compact in the space  $C_{\omega_1, g}[a, b]$ .*

*Proof.* By Theorem 2.4, since  $B_r^{\omega_2, g}$  is a bounded subset in  $C_{\omega_2, g}[a, b]$ , it is a relatively compact subset of  $C_{\omega_1, g}[a, b]$ . Suppose that  $(x_n) \subset B_r^{\omega_2, g}$  and

$$x_n \rightarrow x \text{ (according to } \|\cdot\|_{\omega_1, g}\text{)}$$

with  $x \in C_{\omega_1, g}[a, b]$ . This means that for  $\varepsilon > 0$  we can find  $n_0 \in \mathbb{N}$  such that

$$\|x_n - x\|_{\omega_1, g} \leq \varepsilon,$$

for any  $n \geq n_0$ , or, equivalently

$$\begin{aligned} & |x_n(a) - x(a)| \\ & + \sup \left\{ \frac{|x_n(t) - x(t) - (x_n(s) - x(s))|}{\omega_1(g(t) - g(s))} : t, s \in [a, b], t > s \right\} \leq \varepsilon, \end{aligned} \quad (3)$$

for any  $n \geq n_0$ .

This implies that  $x_n(a) \rightarrow x(a)$ .

Moreover, if in (3) we put  $s = a$ , then we get

$$\sup \left\{ \frac{|x_n(t) - x(t) - (x_n(a) - x(a))|}{\omega_1(g(t) - g(s))} : t, s \in [a, b], t > s \right\} < \varepsilon,$$

for any  $n \geq n_0$ .

The last inequality implies that

$$|x_n(t) - x(t) - (x_n(a) - x(a))| < \varepsilon \omega_1(g(t) - g(s)) \leq \varepsilon \omega_1(g(b) - g(a)), \quad (4)$$

for any  $n \geq n_0$  and for any  $t \in [a, b]$ .

Therefore, for any  $n \geq n_0$  and any  $t \in [a, b]$  and taking into account (3) and (4), we have

$$\begin{aligned} |x_n(t) - x(t)| & \leq |(x_n(t) - x(t)) - (x_n(a) - x(a))| + |x_n(a) - x(a)| \\ & < \varepsilon \omega_1(g(b) - g(a)) + \varepsilon. \end{aligned}$$

Consequently,

$$\|x_n - x\|_{\infty} \rightarrow 0. \quad (5)$$

Next, we will prove that  $x \in B_r^{\omega_2, g}$ .

In fact, since  $(x_n) \subset B_r^{\omega_2, g} \subset C_{\omega_2, g}[a, b]$ , we have that

$$\frac{|x_n(t) - x_n(s)|}{\omega_2(g(t) - g(s))} \leq r,$$

for any  $t, s \in [a, b]$  with  $t > s$ , and, accordingly,

$$|x_n(t) - x_n(s)| \leq r \omega_2(g(t) - g(s)),$$

for any  $t, s \in [a, b]$ .

Letting in the above inequality with  $n \rightarrow \infty$  and taking into account (5), we deduce that

$$|x(t) - x(s)| \leq r\omega_2(g(t) - g(s)),$$

for any  $t, s \in [a, b]$ .

Hence we get

$$\frac{|x(t) - x(s)|}{\omega_2(g(t) - g(s))} \leq r,$$

for any  $t, s \in [a, b]$ , and this means that  $x \in B_r^{\omega_2, g}$ . This proves that  $B_r^{\omega_2, g}$  is a closed subset of  $C_{\omega_1, g}[a, b]$ . Thus,  $x \in B_r^{\omega_2, g}$  is a compact subset of  $C_{\omega_1, g}[a, b]$ . This finishes the proof.  $\square$

### 3. Main results

In this section, we will study the solvability of the equation (1) in  $C_{\omega, g}[a, b]$ . We will use the following assumptions:

(H<sub>1</sub>)  $f : [a, b] \times \mathbb{R} \rightarrow \mathbb{R}$  is a continuous function and there exists a positive number  $k_1$  such that

$$|f(t, x) - f(t, y)| \leq k_1|x - y|,$$

and set  $k = |f(a, a)|$ . Meanwhile, for any  $t, s \in [a, b]$  and  $t > s$ , there exists a positive constant  $k_2$  such that the inequality

$$\frac{|f(t, x(s)) - f(s, x(s))|}{\omega_2(g(t) - g(s))} \leq k_2|x(s)|.$$

(H<sub>2</sub>)  $k : [a, b] \times [a, b] \rightarrow \mathbb{R}$  is a continuous function satisfies the tempered by the modulus of continuity with respect to the first variable, that is, there exists a constant  $K_{\omega_2}$  such that

$$|k(t, \tau) - k(s, \tau)| \leq K_{\omega_2}\omega_2(g(t) - g(s)),$$

for any  $t, s, \tau \in [a, b]$ .

(H<sub>3</sub>) The following inequality is satisfied

$$(2K + K_{\omega_2}(b - a))\max^2\{1, \omega_2(g(b) - g(a))\}r^2 + \left[ k_1 + (k_1 + k_2) \max\{1, \omega_2(g(b) - g(a))\} - 1 \right] r + k + |a|k_1 < 0, \quad (6)$$

where  $K = \sup \left\{ \int_a^b |k(t, \tau)| d\tau : t \in [a, b] \right\}$ .

Consider the operator  $F$  defined on  $C_{\omega_2, g}[a, b]$  by

$$(Fx)(t) = f(t, x(t)) + x(t) \int_a^b k(t, \tau)x(\tau)d\tau, \quad t \in [a, b].$$

**Lemma 3.1.** *The operator  $F$  maps  $C_{\omega_2, g}[a, b]$  into itself.*

*Proof.* In fact, we take  $x \in C_{\omega_2, g}[a, b]$  and  $t, s \in [a, b]$  with  $t > s$ . Then, by assumptions  $(H_1)$ - $(H_3)$ , we obtain

$$\begin{aligned}
& \frac{|(Fx)(t) - (Fx)(s)|}{\omega_2(g(t) - g(s))} \\
\leq & \frac{|f(t, x(t)) - f(s, x(s))|}{\omega_2(g(t) - g(s))} + \frac{|x(t) \int_a^b k(t, \tau)x(\tau)d\tau - x(s) \int_a^b k(t, \tau)x(\tau)d\tau|}{\omega_2(g(t) - g(s))} \\
& + \frac{|x(s) \int_a^b k(t, \tau)x(\tau)d\tau - x(s) \int_a^b k(s, \tau)x(\tau)d\tau|}{\omega_2(g(t) - g(s))} \\
\leq & \frac{|f(t, x(t)) - f(t, x(s))| + |f(t, x(s)) - f(s, x(s))|}{\omega_2(g(t) - g(s))} \\
& + \frac{|x(t) - x(s)|}{\omega_2(g(t) - g(s))} \int_a^b |k(t, \tau)||x(\tau)|d\tau + \frac{|x(s)| \int_a^b |k(t, \tau) - k(s, \tau)||x(\tau)|d\tau}{\omega_2(g(t) - g(s))} \\
\leq & \frac{k_1|x(t) - x(s)|}{\omega_2(g(t) - g(s))} + \frac{|f(t, x(s)) - f(s, x(s))|}{\omega_2(g(t) - g(s))} \\
& + \frac{|x(t) - x(s)|}{\omega_2(g(t) - g(s))} \|x\|_\infty \int_a^b |k(t, \tau)|d\tau + \frac{\|x\|_\infty \|x\|_\infty \int_a^b |k(t, \tau) - k(s, \tau)|d\tau}{\omega_2(g(t) - g(s))} \\
\leq & k_1 H_x^{\omega_2, g} + k_2|x(s)| + K\|x\|_\infty \frac{|x(t) - x(s)|}{\omega_2(g(t) - g(s))} \\
& + \frac{\|x\|_\infty^2 \int_a^b K_{\omega_2} \omega_2(g(t) - g(s))d\tau}{\omega_2(g(t) - g(s))} \\
\leq & k_1 H_x^{\omega_2, g} + k_2 \|x\|_\infty + K\|x\|_\infty H_x^{\omega_2, g} + K_{\omega_2}(b-a)\|x\|_\infty^2.
\end{aligned}$$

By Lemma 2.2, since  $\|x\|_\infty \leq \max\{1, \omega_2(g(b) - g(a))\} \|x\|_{\omega_2, g}$  and, as  $H_x^{\omega_2, g} \leq \|x\|_{\omega_2, g}$ , we infer that

$$\begin{aligned}
& \frac{|(Fx)(t) - (Fx)(s)|}{\omega_2(g(t) - g(s))} \\
\leq & (k_1 + k_2 \max\{1, \omega_2(g(b) - g(a))\}) \|x\|_{\omega_2, g} \\
& + (K + K_{\omega_2}(b-a)) \max^2\{1, \omega_2(g(b) - g(a))\} \|x\|_{\omega_2, g}^2.
\end{aligned}$$

This proves that the operator  $F$  maps  $C_{\omega_2, g}[a, b]$  into itself.  $\square$

**Lemma 3.2.** Let  $B_{r_0}^{\omega_2, g} = \{x \in C_{\omega_2, g}[a, b] : \|x\|_{\omega_2, g} \leq r_0\}$  where  $r_0 > 0$  satisfying the inequality (6). Then  $F : B_{r_0}^{\omega_2, g} \rightarrow B_{r_0}^{\omega_2, g}$ .

*Proof.* For any  $x \in B_{r_0}^{\omega_2, g}$ , one has

$$\begin{aligned}
\|Fx\|_{\omega_2, g} & \leq |f(a, x(a))| + |x(a)| \int_a^b |k(a, \tau)||x(\tau)|d\tau \\
& + (k_1 + k_2 \max\{1, \omega_2(g(b) - g(a))\}) \|x\|_{\omega_2, g} \\
& + (K + K_{\omega_2}(b-a)) \max^2\{1, \omega_2(g(b) - g(a))\} \|x\|_{\omega_2, g}^2,
\end{aligned}$$

$$\begin{aligned}
 &\leq |f(a, x(a)) - f(a, a)| + |f(a, a)| + K\|x\|_\infty^2 \\
 &\quad + (k_1 + k_2 \max\{1, \omega_2(g(b) - g(a))\}) \|x\|_{\omega_2, g} \\
 &\quad + (K + K_{\omega_2}(b - a)) \max^2\{1, \omega_2(g(b) - g(a))\} \|x\|_{\omega_2, g}^2 \\
 &\leq k_1|x(a) - a| + k + (k_1 + k_2 \max\{1, \omega_2(g(b) - g(a))\}) \|x\|_{\omega_2, g} \\
 &\quad + (2K + K_{\omega_2}(b - a)) \max^2\{1, \omega_2(g(b) - g(a))\} \|x\|_{\omega_2, g}^2 \\
 &\leq |a|k_1 + k_1\|x\|_\infty + k + (k_1 + k_2 \max\{1, \omega_2(g(b) - g(a))\}) \|x\|_{\omega_2, g} \\
 &\quad + (2K + K_{\omega_2}(b - a)) \max^2\{1, \omega_2(g(b) - g(a))\} \|x\|_{\omega_2, g}^2 \\
 &= k + |a|k_1 + \left[ k_1 + (k_1 + k_2) \max\{1, \omega_2(g(b) - g(a))\} \right] \|x\|_{\omega_2, g} \\
 &\quad + (2K + K_{\omega_2}(b - a)) \max^2\{1, \omega_2(g(b) - g(a))\} \|x\|_{\omega_2, g}^2.
 \end{aligned}$$

Consequently, from above it follows that  $F$  transforms the ball  $B_{r_0}^{\omega_2, g} = \{x \in C_{\omega_2, g}[a, b] : \|x\|_{\omega_2, g} \leq r_0\}$  into itself, for any  $r_0 \in [r_1, r_2]$ ; i.e.,  $F : B_{r_0}^{\omega_2, g} \rightarrow B_{r_0}^{\omega_2, g}$ , where  $r_1 \leq r_0 \leq r_2$ .  $\square$

**Lemma 3.3.**  $B_{r_0}^{\omega_2, g}$  is a compact subset in  $C_{\omega_1, g}[a, b]$ .

*Proof.* According to Theorem 2.5, we can know  $B_{r_0}^{\omega_2, g}$  is a compact subset in  $C_{\omega_1, g}[a, b]$ .  $\square$

**Lemma 3.4.** The operator  $F$  is continuous on  $B_{r_0}^{\omega_2, g}$ , where we consider the norm  $\|\cdot\|_{\omega_1, g}$  in  $B_{r_0}^{\omega_2, g}$ .

*Proof.* To do this, we fix  $x \in B_{r_0}^{\omega_2, g}$  and  $\varepsilon > 0$ . Suppose that  $y \in B_{r_0}^{\omega_2, g}$  and  $\|x - y\|_{\omega_1, g} \leq \delta$ , where  $\delta$  is a positive number such that  $\delta < \frac{\varepsilon}{2\rho}$  where  $\rho = \max\{\rho_1, \rho_2\}$ ,  $\rho_1, \rho_2$  is defined below. Then, for any  $t, s \in [a, b]$  with  $t > s$ , we have

$$\begin{aligned}
 &\frac{|[(Fx)(t) - (Fy)(t)] - [(Fx)(s) - (Fy)(s)]|}{\omega_1(g(t) - g(s))} \\
 &\leq \frac{\left| k_1|x(t) - y(t)| - k_1|x(s) - y(s)| \right|}{\omega_1(g(t) - g(s))} \\
 &\quad + \left| \frac{[x(t) \int_a^b k(t, \tau)x(\tau)d\tau - y(t) \int_a^b k(t, \tau)x(\tau)d\tau]}{\omega_1(g(t) - g(s))} \right. \\
 &\quad + \frac{[y(t) \int_a^b k(t, \tau)x(\tau)d\tau - y(t) \int_a^b k(t, \tau)y(\tau)d\tau]}{\omega_1(g(t) - g(s))} \\
 &\quad - \frac{[x(s) \int_a^b k(s, \tau)x(\tau)d\tau - y(s) \int_a^b k(s, \tau)x(\tau)d\tau]}{\omega_1(g(t) - g(s))} \\
 &\quad \left. - \frac{[y(s) \int_a^b k(s, \tau)x(\tau)d\tau - y(s) \int_a^b k(s, \tau)y(\tau)d\tau]}{\omega_1(g(t) - g(s))} \right|
 \end{aligned}$$

$$\begin{aligned}
&= k_1 \frac{\left| |x(t) - y(t)| - |x(s) - y(s)| \right|}{\omega_1(g(t) - g(s))} \\
&\quad + \frac{1}{\omega_1(g(t) - g(s))} \left| (x(t) - y(t)) \int_a^b k(t, \tau) x(\tau) d\tau \right. \\
&\quad \left. + y(t) \int_a^b k(t, \tau) (x(\tau) - y(\tau)) d\tau \right. \\
&\quad \left. - (x(s) - y(s)) \int_a^b k(s, \tau) x(\tau) d\tau - y(s) \int_a^b k(s, \tau) (x(\tau) - y(\tau)) d\tau \right| \\
&\leq k_1 \|x - y\|_{\omega_1, g} + \frac{|(x(t) - y(t)) - (x(s) - y(s))|}{\omega_1(g(t) - g(s))} \|x\|_\infty \int_a^b |k(t, \tau)| d\tau \\
&\quad + [|(x(s) - y(s)) - (x(a) - y(a))| + |(x(a) - y(a))|] \|x\|_\infty \\
&\quad \times \int_a^b \frac{|k(t, \tau) - k(s, \tau)|}{\omega_1(g(t) - g(s))} d\tau \\
&\quad + \frac{\left| y(t) \int_a^b k(t, \tau) (x(\tau) - y(\tau)) d\tau - y(s) \int_a^b k(t, \tau) (x(\tau) - y(\tau)) d\tau \right|}{\omega_1(g(t) - g(s))} \\
&\quad + \frac{\left| y(s) \int_a^b k(t, \tau) (x(\tau) - y(\tau)) d\tau - y(s) \int_a^b k(s, \tau) (x(\tau) - y(\tau)) d\tau \right|}{\omega_1(g(t) - g(s))} \\
&\leq k_1 \|x - y\|_{\omega_1, g} + K \|x - y\|_{\omega_1, g} \|x\|_\infty \\
&\quad + \sup \left\{ |(x(t) - y(t)) - (x(s) - y(s))| \right\} \|x\|_\infty \int_a^b \frac{K_{\omega_2} \omega_2(g(t) - g(s))}{\omega_1(f(t) - f(s))} d\tau \\
&\quad + |(x(a) - y(a))| \|x\|_\infty \int_a^b \frac{K_{\omega_2} \omega_2(g(t) - g(s))}{\omega_1(g(t) - g(s))} d\tau \\
&\quad + \frac{|y(t) - y(s)|}{\omega_1(g(t) - g(s))} \int_a^b |k(t, \tau)| |x(\tau) - y(\tau)| d\tau \\
&\quad + |y(s)| \int_a^b \frac{|k(t, \tau) - k(s, \tau)|}{\omega_1(g(t) - g(s))} |x(\tau) - y(\tau)| d\tau \\
&\leq k_1 \|x - y\|_{\omega_1, g} + K \|x - y\|_{\omega_1, g} \|x\|_\infty \\
&\quad + M(b - a) \|x\|_\infty K_{\omega_2} \sup \left\{ \frac{|(x(t) - y(t)) - (x(s) - y(s))|}{\omega_1(g(t) - g(s))} \omega_1(g(t) - g(s)) \right\} \\
&\quad + M(b - a) K_{\omega_2} \|x\|_\infty |(x(a) - y(a))| + KH_y^{\omega_1, g} \|x - y\|_\infty \\
&\quad + \|y\|_\infty \|x - y\|_\infty \int_a^b \frac{K_{\omega_2} \omega_2(g(t) - g(s))}{\omega_1(g(t) - g(s))} d\tau \\
&\leq k_1 \|x - y\|_{\omega_1, g} + K \|x - y\|_{\omega_1, g} \|x\|_\infty \\
&\quad + M(b - a) \|x\|_\infty K_{\omega_2} \omega_1(g(b) - g(a)) \|x - y\|_{\omega_1, g}
\end{aligned}$$



$$\begin{aligned}
 & +M(b-a)K_{\omega_2}\|x\|_{\infty}\|x-y\|_{\infty} + K\|y\|_{\omega_1,g}\|x-y\|_{\infty} \\
 & +M(b-a)K_{\omega_2}\|y\|_{\infty}\|x-y\|_{\infty} \\
 \leq & k_1\|x-y\|_{\omega_1,g} + K\max\{1,\omega_2(g(b)-g(a))\}\|x-y\|_{\omega_1,g}\|x\|_{\omega_2,g} \\
 & +M(b-a)K_{\omega_2}\omega_1(g(b)-g(a))\max\{1,\omega_2(g(b)-g(a))\}\|x-y\|_{\omega_1,g}\|x\|_{\omega_2,g} \\
 & +M(b-a)K_{\omega_2}\max\{1,\omega_2(g(b)-g(a))\} \\
 & \times \max\{1,\omega_1(g(b)-g(a))\}\|x-y\|_{\omega_1,g}\|x\|_{\omega_2,g} \\
 & +K\max\{1,\omega_1(g(b)-g(a))\}\|x-y\|_{\omega_1,g}\|y\|_{\omega_1,g} \\
 & +M(b-a)K_{\omega_2}\max\{1,\omega_2(g(b)-g(a))\} \\
 & \times \max\{1,\omega_1(g(b)-g(a))\}\|x-y\|_{\omega_1,g}\|y\|_{\omega_2,g}.
 \end{aligned}$$

Define

$$\begin{aligned}
 \rho_1 = & k_1 + K\max\{1,\omega_2(g(b)-g(a))\}r_0 \\
 & +M(b-a)K_{\omega_2}\omega_1(g(b)-g(a))\max\{1,\omega_2(g(b)-g(a))\}r_0 \\
 & +2M(b-a)K_{\omega_2}\max\{1,\omega_2(g(b)-g(a))\}\max\{1,\omega_1(g(b)-g(a))\}r_0 \\
 & +K\max\{1,\omega_1(g(b)-g(a))\}r_0.
 \end{aligned}$$

Since  $\|y\|_{\omega_1,g} \leq \|y\|_{\omega_2,g}$  (see Remark 2.1) and  $x, y \in B_{r_0}^{\omega_2,g}$ , from the above inequality we infer that

$$\frac{|[(Fx)(t) - (Fy)(t)] - [(Fx)(s) - (Fy)(s)]|}{\omega_1(g(t) - g(s))} \leq \rho_1\delta < \frac{\varepsilon}{2}. \tag{7}$$

On the other hand,

$$\begin{aligned}
 & |(Fx)(a) - (Fy)(a)| \\
 \leq & |f(a, x(a)) - f(a, y(a))| + \left| x(a) \int_a^b k(a, \tau)x(\tau)d\tau - x(a) \int_a^b k(a, \tau)y(\tau)d\tau \right| \\
 & + \left| x(a) \int_a^b k(a, \tau)y(\tau)d\tau - y(a) \int_a^b k(a, \tau)y(\tau)d\tau \right| \\
 \leq & k_1|x(a) - y(a)| + \left| x(a) \int_a^b k(a, \tau)(x(\tau) - y(\tau))d\tau \right| \\
 & + \left| (x(a) - y(a)) \int_a^b k(a, \tau)y(\tau)d\tau \right| \\
 \leq & k_1\|x-y\|_{\infty} + K\|x\|_{\infty}\|x-y\|_{\infty} + K\|y\|_{\infty}\|x-y\|_{\infty} \\
 \leq & k_1\max\{1,\omega_1(g(b)-g(a))\}\|x-y\|_{\omega_1,g} \\
 & +K\max\{1,\omega_2(g(b)-g(a))\}\max\{1,\omega_1(g(b)-g(a))\}\|x\|_{\omega_2,g}\|x-y\|_{\omega_1,g} \\
 & +K\max\{1,\omega_2(g(b)-g(a))\}\max\{1,\omega_1(g(b)-g(a))\}\|y\|_{\omega_2,g}\|x-y\|_{\omega_1,g} \\
 \leq & \rho_2\delta,
 \end{aligned}$$

where

$$\rho_2 = k_1\max\{1,\omega_1(g(b)-g(a))\}$$

$$+2K \max\{1, \omega_2(g(b) - g(a))\} \max\{1, \omega_1(g(b) - g(a))\} r_0.$$

which yields that

$$|(Fx)(a) - (Fy)(a)| \leq \rho_2 \delta < \frac{\varepsilon}{2}. \tag{8}$$

By (7) and (8), we have

$$\begin{aligned} & \|Fx - Fy\|_{\omega_1, g} \\ = & |(Fx)(a) - (Fy)(a)| \\ & + \sup \left\{ \frac{|[(Fx)(t) - (Fy)(t)] - [(Fx)(s) - (Fy)(s)]|}{\omega_1(g(t) - g(s))} : t, s \in [a, b], t > s \right\} \\ < & \frac{\varepsilon}{2} + \frac{\varepsilon}{2} = \varepsilon. \end{aligned}$$

This proves the operator  $F$  is continuous at the point  $x \in B_{r_0}^{\omega_2, g}$  for the norm  $\|\cdot\|_{\omega_1, g}$ .  $\square$

**Theorem 3.5.** *Under assumptions  $(H_1)$ - $(H_3)$ , the equation (1) has at least one solution in the space  $C_{\omega_1, g}[a, b]$ .*

*Proof.* According to Lemma 3.1, Lemma 3.2, Lemma 3.3 and Lemma 3.4, the operator  $F$  is continuous at the point  $x \in B_{r_0}^{\omega_2, g}$  for the norm  $\|\cdot\|_{\omega_1, g}$ . Since  $B_{r_0}^{\omega_2, g}$  is compact in  $C_{\omega_2, g}[a, b]$ , applying the classical Schauder fixed point theorem we obtain the desired result.  $\square$

### 4. Examples

Now we make two examples illustrating the main results in the above section.

**Example 4.1.** Let us consider the quadratic integral equation

$$x(t) = \frac{1}{100} \sqrt{\ln t} \arctan x(t) + x(t) \int_1^e \sqrt{\ln t + \ln \tau} \frac{x(\tau)}{\tau} d\tau, \quad t \in [1, e]. \tag{9}$$

Set  $f(t, x(t)) = \frac{1}{100} \sqrt{\ln t} \arctan x(t)$  and  $k(t, \tau) = \frac{\sqrt{\ln t + \ln \tau}}{\tau}$  for  $t, \tau \in [1, e]$ . It is easy to see that

$$|k(t, \tau) - k(s, \tau)| \leq |\ln t - \ln s|^{\frac{1}{2}},$$

which implies  $K_{\omega_2} = 1$  and

$$g(t) = \ln t, \quad \omega_2(g(t) - g(s)) = |\ln t - \ln s|^{\frac{1}{2}}, \quad \omega_2(g(e) - g(1)) = 1.$$

So we can choose

$$\omega_1(g(t) - g(s)) = |\ln t - \ln s|^\alpha, \quad 0 < \alpha < \frac{1}{2}.$$

Moreover,  $K = \sup\{\int_1^e |\frac{\sqrt{\ln t + \ln \tau}}{\tau}| d\tau : t \in [1, e]\} = \frac{2}{3}(2\sqrt{2} - 1)$ .

On the other hand,

$$|f(t, x(t)) - f(t, y(t))| = \frac{1}{100} \sqrt{\ln t} |\arctan x(t) - \arctan y(t)| \leq \frac{1}{100} |x(t) - y(t)|,$$

so we can get  $k_1 = \frac{1}{100}, k = |f(1, 1)| = 0$  and

$$\frac{|\frac{1}{100}\sqrt{\ln t} \arctan x(s) - \frac{1}{100}\sqrt{\ln s} \arctan x(s)|}{|\ln t - \ln s|^{\frac{1}{2}}} \leq \frac{1}{100} |\arctan x(s)| \leq \frac{1}{100} |x(s)|,$$

so  $k_2 = \frac{1}{100}$ .

In what follows, the condition  $(H_3)$  reduce to the inequality

$$\left(\frac{8\sqrt{2}-7}{3} + e\right)r^2 - \frac{97}{100}r + \frac{1}{100} < 0.$$

Obviously, there exist a positive number satisfying these conditions. For example, one can choose  $r = 0.1$ .

Finally, applying Theorem 3.5, we conclude that the quadratic integral equation has at least one solution in the space  $C_{|\cdot|^\alpha, \ln} [1, e]$  and displayed in Fig.1.

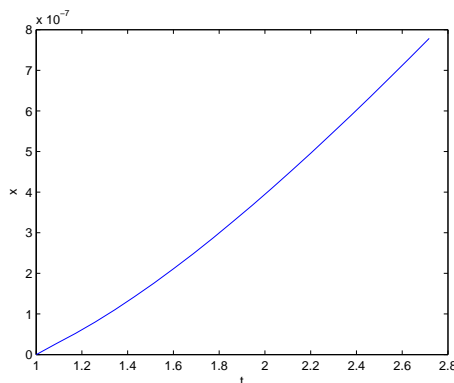


Fig.1 The solution of the equation (9).

**Example 4.2.** Consider another quadratic integral equation

$$x(t) = \frac{1}{10} \sqrt[5]{t+1} \sin x(t) + x(t) \int_0^1 \sqrt[5]{3t^2 + \tau} x(\tau) d\tau, \quad t \in [0, 1]. \quad (10)$$

Set  $f(t, x(t)) = \frac{1}{10} \sqrt[5]{t+1} \sin x(t)$  and  $k(t, \tau) = \sqrt[5]{3t^2 + \tau}, t \in [0, 1]$ . Obviously,

$$|k(t, \tau) - k(s, \tau)| \leq |3t^2 - 3s^2|^{\frac{1}{5}} \leq \sqrt[5]{6}|t - s|^{\frac{1}{5}},$$

which gives  $K_{\omega_2} = \sqrt[5]{6}, g(t) = t, \omega_2(g(t) - g(s)) = |t - s|^{\frac{1}{5}}, \omega_2(g(1) - g(0)) = 1$ . Then we choose

$$\omega_1(g(t) - g(s)) = |t - s|^\alpha, \quad 0 < \alpha < \frac{1}{5}.$$

Moreover,  $K = \sup\{\int_0^1 \sqrt[5]{3t^2 + \tau} d\tau : t \in [0, 1]\} = \sup\{\frac{5}{6}(3t^2 + \tau)^{\frac{6}{5}}|_0^1 : t \in [0, 1]\} = \frac{5}{6}(4\sqrt[5]{4} - 3\sqrt[5]{3})$ .

On the other hand,

$$|f(t, x(t)) - f(t, y(t))| = \frac{1}{10} \sqrt[5]{t+1} |\sin x(t) - \sin y(t)| \leq \frac{\sqrt[5]{2}}{10} |x(t) - y(t)|,$$

we can get  $k_1 = \frac{\sqrt[5]{2}}{10}$ ,  $k = |f(0, 0)| = 0$  and

$$\frac{|\frac{1}{10} \sqrt[5]{t+1} \sin x(s) - \frac{1}{10} \sqrt[5]{s+1} \sin x(s)|}{|t-s|^{\frac{1}{5}}} \leq \frac{1}{10} |\sin x(s)| \leq \frac{1}{10} |x(s)|,$$

so derive  $k_2 = \frac{1}{10}$ .

In what follows, the condition  $(H_3)$  reduce to the inequality

$$(200\sqrt[5]{4} - 150\sqrt[5]{3} + 30\sqrt[5]{6})r^2 + (6\sqrt[5]{2} - 27)r < 0.$$

The condition reduce to  $r < 0.1676$ . Obviously, there exist a positive number satisfying these conditions. For example, one can choose  $r = 0.16$ .

Finally, applying Theorem 3.5, we conclude that the quadratic integral equation has at least one solution in the space  $C_{|\cdot|^\alpha, \cdot}[0, 1]$  and displayed in Fig.2.

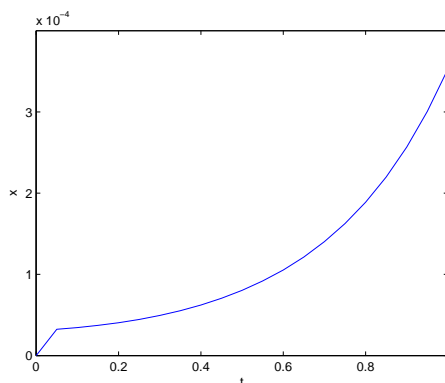


Fig.2 The solution of the equation (10).

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