

Center of Gravity and a Characterization of Parabolas

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ABSTRACT. Archimedes determined the center of gravity of a parabolic section as follows. For a parabolic section between a parabola and any chord AB on the parabola, let us denote by P the point on the parabola where the tangent is parallel to AB and by V the point where the line through P parallel to the axis of the parabola meets the chord AB . Then the center G of gravity of the section lies on PV called the axis of the parabolic section with $PG = \frac{3}{5}PV$. In this paper, we study strictly locally convex plane curves satisfying the above center of gravity properties. As a result, we prove that among strictly locally convex plane curves, those properties characterize parabolas.

1. Introduction

Archimedes found some interesting area properties of parabolas. Consider the region bounded by a parabola and a chord AB . Let P be the point on the parabola where the tangent is parallel to the chord AB . The parallel line through P to the axis of the parabola meets the chord AB at a point V . Then, he proved that the

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area of the parabolic region is $4/3$ times the area of triangle $\triangle ABP$ whose base is the chord and the third vertex is P .

Furthermore, he showed that the center G of gravity of the parabolic section lies on the segment PV called the axis of the parabolic section with $PG = \frac{3}{5}PV$. For the proofs of Archimedes, see Chapter 7 of [25].

Recently, two of the present authors showed that among strictly convex plane curves, the above area properties of parabolic sections characterize parabolas. More precisely, they proved as follows ([18]).

Proposition 1. *Let X be a strictly convex curve in the plane \mathbb{R}^2 . Then X is a parabola if and only if it satisfies*

(C) : *For a point P on X and a chord AB of X parallel to the tangent of X at P , the area of the region bounded by the curve and AB is $4/3$ times the area of triangle $\triangle ABP$.*

Actually, in [18], they established five characterizations of parabolas, which are the converses of well-known properties of parabolas originally due to Archimedes ([25]). In [21], they gave some characterizations of parabolas using area of triangles associated with a plane curve, which are generalizations of some results in [23]. See also [10, 11, 12] for some generalizations of results in [21].

In [16] and [17], two of the present authors proved the higher dimensional analogues of some results in [18]. Some characteristic properties of hyperspheres, ellipsoids, elliptic hyperboloids, hypercylinders and W -curves in the $(n+1)$ -dimensional Euclidean space \mathbb{E}^{n+1} were given in [1, 4, 6, 7, 13, 15, 22]. In [19], some characteristics for hyperbolic spaces embedded in the Minkowski space were established.

For some characterizations of parabolas or conic sections by properties of tangent lines, see [8] and [20]. In [14], using curvature function κ and support function h of a plane curve, the first and second authors of the present paper gave a characterization of ellipses and hyperbolas centered at the origin.

Among the graphs of functions, Á. Bényi et al. proved some characterizations of parabolas ([2, 3]). B. Richmond and T. Richmond established a dozen characterizations of parabolas using elementary techniques ([24]). In their paper, parabola means the graph of a quadratic polynomial in one variable.

In this paper, we study strictly locally convex plane curves satisfying the above mentioned properties on the center of gravity. Recall that a regular plane curve $X : I \rightarrow \mathbb{R}^2$ in the plane \mathbb{R}^2 , where I is an open interval, is called *convex* if, for all $s \in I$ the trace $X(I)$ of X lies entirely on one side of the closed half-plane determined by the tangent line at s ([5]). A regular plane curve $X : I \rightarrow \mathbb{R}^2$ is called *locally convex* if, for each $s \in I$ there exists an open subinterval $J \subset I$ containing s such that the curve $X|_J$ restricted to J is a convex curve.

Hereafter, we will say that a locally convex curve X in the plane \mathbb{R}^2 is *strictly locally convex* if the curve is smooth (that is, of class $C^{(3)}$) and is of positive curvature κ with respect to the unit normal N pointing to the convex side. Hence,

in this case we have $\kappa(s) = \langle X''(s), N(X(s)) \rangle > 0$, where $X(s)$ is an arc-length parametrization of X .

For a smooth function $f : I \rightarrow \mathbb{R}$ defined on an open interval, we will also say that f is *strictly convex* if the graph of f has positive curvature κ with respect to the upward unit normal N . This condition is equivalent to the positivity of $f''(x)$ on I .

First of all, in Section 2 we prove the following:

Theorem 2. *Let X be a strictly locally convex plane curve in the plane \mathbb{R}^2 . For a fixed point P on X and a sufficiently small $h > 0$, we denote by l the parallel line through $P + hN(P)$ to the tangent t of the curve X at P . If we let $d_P(h)$ the distance from the center G of gravity of the section of X cut off by l to the tangent t of the curve X at P , then we have*

$$(1.1) \quad \lim_{h \rightarrow 0} \frac{d_P(h)}{h} = \frac{3}{5}.$$

Without the help of Proposition 1, in Section 3 we prove the following characterization theorem for parabolas with axis parallel to the y -axis, that is, the graph of a quadratic function.

Theorem 3. *Let X be the graph of a strictly convex function $g : I \rightarrow \mathbb{R}$ in the uv -plane \mathbb{R}^2 with the upward unit normal N . For a fixed point $P = (u, g(u))$ on X and a sufficiently small $h > 0$, we denote by l (resp., V) the parallel line through $P + hN(P)$ to the tangent t of the curve X at P (resp., the point where the parallel line through P to the v -axis meets l). Then X is an open arc of a parabola with axis parallel to the v -axis if and only if it satisfies*

(D) : *For a fixed point P on X and a sufficiently small $h > 0$, the center G of gravity of the section of X cut off by l lies on the segment PV with*

$$(1.2) \quad PG = \frac{3}{5}PV,$$

where we denote by PV both of the segment and its length.

Note that if X is an open arc of a parabola with axis which is not parallel to the v -axis (for example, the graph of g given in (3.23) with $\alpha \neq 0$), then it does not satisfy Condition (D).

Finally using Proposition 1, in Section 4 we prove the following characterization theorem for parabolas.

Theorem 4. *Let X be a strictly locally convex plane curve in the plane \mathbb{R}^2 . For a fixed point P on X and a sufficiently small $h > 0$, we denote by l the parallel line through $P + hN(P)$ to the tangent t of the curve X at P . We let $d_P(h)$ the distance from the center G of gravity of the section of X cut off by l to the tangent t of the curve X at P . Then X is an open arc of a parabola if and only if it satisfies*

(E) : For a fixed point P on X and a sufficiently small $h > 0$, we have

$$(1.3) \quad d_P(h) = \frac{3}{5}h.$$

In [9], using the results in this paper and the centroids of triangles associated with a strictly convex curve, some characterizations of parabolas were established.

Throughout this article, all curves are of class $C^{(3)}$ and connected, unless otherwise mentioned.

2. Preliminaries and Theorem 2

Suppose that X is a strictly locally convex curve in the plane \mathbb{R}^2 with the unit normal N pointing to the convex side. For a fixed point $P \in X$, and for a sufficiently small $h > 0$, consider the parallel line l through $P + hN(P)$ to the tangent t of X at P . Let's denote by A and B the points where the line l intersects the curve X .

We denote by $S_P(h)$ (respectively, $R_P(h)$) the area of the region bounded by the curve X and chord AB (respectively, of the rectangle with a side AB and another one on the tangent t of X at P with height $h > 0$). We also denote by $L_P(h)$ the length of the chord AB . Then we have $R_P(h) = hL_P(h)$.

We may adopt a coordinate system (x, y) of \mathbb{R}^2 in such a way that P is taken to be the origin $(0, 0)$ and the x -axis is the tangent line of X at P . Furthermore, we may assume that X is locally the graph of a non-negative strictly convex function $f : \mathbb{R} \rightarrow \mathbb{R}$.

For a sufficiently small $h > 0$, we have

$$(2.1) \quad \begin{aligned} S_P(h) &= \int_{f(x) < h} \{h - f(x)\} dx, \\ R_P(h) &= hL_P(h) = h \int_{f(x) < h} 1 dx. \end{aligned}$$

The integration is taken on the interval $I_P(h) = \{x \in \mathbb{R} | f(x) < h\}$.

On the other hand, we also have

$$S_P(h) = \int_{y=0}^h L_P(y) dy,$$

which shows that

$$(2.2) \quad S'_P(h) = L_P(h).$$

First of all, we need the following lemma ([18]), which is useful in this article.

Lemma 5. *Suppose that X is a strictly locally convex curve in the plane \mathbb{R}^2 with the unit normal N pointing to the convex side. Then we have*

$$(2.3) \quad \lim_{h \rightarrow 0} \frac{1}{\sqrt{h}} L_P(h) = \frac{2\sqrt{2}}{\sqrt{\kappa(P)}},$$

where $\kappa(P)$ is the curvature of X at P with respect to the unit normal N .

From Lemma 5, we get a geometric meaning of curvature $\kappa(P)$ of a locally strictly convex plane curve X at a point $P \in M$. That is, we obtain

$$(2.4) \quad \kappa(P) = \lim_{h \rightarrow 0} \frac{8h}{L_P(h)^2}.$$

Now, we give a proof of Theorem 2.

Let us denote by $d_P(h)$ the distance from the center G of gravity of the section of X cut off by l to the tangent t of the curve X at P . Note that the curve X is of class $C^{(3)}$. If we adopt a coordinate system (x, y) of \mathbb{R}^2 as in the beginning of this section, then the curve X is locally the graph of a non-negative strictly convex $C^{(3)}$ function $f : \mathbb{R} \rightarrow \mathbb{R}$. Hence, the Taylor's formula of $f(x)$ is given by

$$(2.5) \quad f(x) = ax^2 + f_3(x),$$

where $a = f''(0)/2$, and $f_3(x)$ is an $O(|x|^3)$ function. Since $\kappa(P) = 2a > 0$, we see that a is positive.

From the definition of $d_P(h)$, we have

$$(2.6) \quad S_P(h)d_P(h) = \phi(h),$$

where we put

$$(2.7) \quad \phi(h) = \frac{1}{2} \int_{f(x) < h} \{h^2 - f(x)^2\} dx.$$

We decompose $\phi(h) = \phi_1(h) - \phi_2(h)$ as follows:

$$(2.8) \quad \phi_1(h) = \frac{1}{2} \int_{f(x) < h} h^2 dx, \quad \phi_2(h) = \frac{1}{2} \int_{f(x) < h} f(x)^2 dx.$$

It follows from the definition of $L_P(h)$ that

$$(2.9) \quad \phi_1(h) = \frac{1}{2} h^2 L_P(h).$$

Hence, Lemma 5 shows that

$$(2.10) \quad \lim_{h \rightarrow 0} \frac{\phi_1(h)}{h^2 \sqrt{h}} = \frac{\sqrt{2}}{\sqrt{\kappa(P)}}.$$

Lemma 6. *For the limit of $\phi_2(h)/(h^2\sqrt{h})$ as h tends to 0, we get*

$$(2.11) \quad \lim_{h \rightarrow 0} \frac{\phi_2(h)}{h^2\sqrt{h}} = \frac{\sqrt{2}}{5\sqrt{\kappa(P)}}.$$

Proof. If we put $g(x) = f(x)^2$, then we have from (2.5)

$$(2.12) \quad g(x) = a^2x^4 + f_5(x),$$

where $f_5(x)$ is an $O(|x|^5)$ function. We let $x = \sqrt{h}\xi$. Then, together with (2.5), (2.8) gives

$$(2.13) \quad \begin{aligned} \frac{\phi_2(h)}{h^2\sqrt{h}} &= \frac{1}{2h^2\sqrt{h}} \int_{f(x) < h} g(x) dx \\ &= \frac{1}{2h^2} \int_{a\xi^2 + g_3(\sqrt{h}\xi) < 1} g(\sqrt{h}\xi) d\xi, \end{aligned}$$

where we denote $g_3(\sqrt{h}\xi) = \frac{f_3(\sqrt{h}\xi)}{h}$.

Since $f_3(x)$ is an $O(|x|^3)$ function, we have for some constant C_1

$$(2.14) \quad |g_3(\sqrt{h}\xi)| \leq C_1\sqrt{h}|\xi|^3.$$

We also obtain from (2.12) that

$$(2.15) \quad \frac{|g(\sqrt{h}\xi) - a^2h^2\xi^4|}{h^2} \leq C_2\sqrt{h}|\xi|^5$$

where C_2 is a constant.

If we let $h \rightarrow 0$, it follows from (2.13)-(2.15) that

$$(2.16) \quad \begin{aligned} \lim_{h \rightarrow 0} \frac{\phi_2(h)}{h^2\sqrt{h}} &= \frac{1}{2} \int_{a\xi^2 < 1} a^2\xi^4 d\xi \\ &= \frac{1}{5\sqrt{a}}. \end{aligned}$$

This completes the proof of Lemma 6. □

Together with (2.10), Lemma 6 shows that

$$(2.17) \quad \lim_{h \rightarrow 0} \frac{\phi(h)}{h^2\sqrt{h}} = \frac{4\sqrt{2}}{5\sqrt{\kappa(P)}}.$$

Since $S'_P(h) = L_P(h)$, it follows from Lemma 5 that

$$(2.18) \quad \lim_{h \rightarrow 0} \frac{1}{h\sqrt{h}} S_P(h) = \frac{4\sqrt{2}}{3\sqrt{\kappa(P)}}.$$

Thus, together with (2.17) and (2.18), (2.6) completes the proof of Theorem 2.

3. Proof of Theorem 3

In this section, we give a proof of Theorem 3.

Let X be the graph of a strictly convex function $g : I \rightarrow \mathbb{R}$ in the uv -plane \mathbb{R}^2 with the upward unit normal N .

For a fixed point $P = (b, c) \in X$ with $c = g(b)$, we denote by θ the angle between the normal $N(P)$ and the positive v -axis. Then we have $g'(b) = \tan \theta$ and $V = (b, c + wh)$ for sufficiently small $h > 0$, where $w = \sqrt{1 + g'(b)^2} = \sec \theta$.

By a change of coordinates in the plane \mathbb{R}^2 given by

$$(3.1) \quad \begin{aligned} u &= x \cos \theta - y \sin \theta + b, \\ v &= x \sin \theta + y \cos \theta + c, \end{aligned}$$

the graph $X : v = g(u), u \in I$ is represented by $X : y = f(x), x \in J$, P by the origin and V by the point $(\alpha h, h)$, where $\alpha = \tan \theta$.

Since $f(0) = f'(0) = 0$, the Taylor's formula of $f(x)$ is given by

$$(3.2) \quad f(x) = ax^2 + f_3(x),$$

where $a = f''(0)/2$, and $f_3(x)$ is an $O(|x|^3)$ function. Since $\kappa(P) = 2a > 0$, we see that a is positive.

For a sufficiently small $h > 0$, it follows from the definition of the center $G = (\bar{x}_P(h), \bar{y}_P(h))$ of gravity of the section of X cut off by the parallel line l through $P + hN(P)$ to the tangent t of X at P that

$$(3.3) \quad \begin{aligned} \bar{y}_P(h)S_P(h) &= \phi(h), \\ \bar{x}_P(h)S_P(h) &= \psi(h), \end{aligned}$$

where we put

$$(3.4) \quad \phi(h) = \frac{1}{2} \int_{f(x) < h} \{h^2 - f(x)^2\} dx$$

and

$$(3.5) \quad \psi(h) = \int_{f(x) < h} \{x(h - f(x))\} dx.$$

First of all, we get

Lemma 7. *If we let $I_P(h) = \{x | f(x) < h\} = (x_1(h), x_2(h))$, then we have*

$$(3.6) \quad \phi'(h) = h\{x_2(h) - x_1(h)\} = hL_P(h)$$

and

$$(3.7) \quad \psi'(h) = \frac{1}{2}\{x_2(h)^2 - x_1(h)^2\}.$$

Proof. If we put $\bar{f}(x) = f(x)^2$ and $k = h^2$, then we have

$$(3.8) \quad \begin{aligned} 2\phi(h) &= \int_{f(x)^2 < h^2} \{h^2 - f(x)^2\} dx \\ &= \int_{\bar{f}(x) < k} \{k - \bar{f}(x)\} dx. \end{aligned}$$

We denote by $\bar{S}_P(k)$ the area of the region bounded by the graph of $y = \bar{f}(x)$ and the line $y = k$. Then (3.8) shows that

$$(3.9) \quad 2\phi(h) = \bar{S}_P(k).$$

It follows from (2.2) that

$$(3.10) \quad \frac{d}{dk} \bar{S}_P(k) = \bar{L}_P(k),$$

where $\bar{L}_P(k)$ denotes the length of the interval $\bar{I}_P(k) = \{x \in \mathbb{R} | \bar{f}(x) < k\}$.

Since $k = h^2$, $\bar{I}_P(k)$ coincides with the interval $I_P(h) = \{x \in \mathbb{R} | f(x) < h\}$. Hence we get $\bar{L}_P(k) = L_P(h)$. This, together with (3.9) and (3.10) shows that

$$(3.11) \quad \phi'(h) = hL_P(h),$$

which completes the proof of (3.6).

Finally, note that $\psi(h)$ is also given by

$$(3.12) \quad \psi(h) = \frac{1}{2} \int_{y=0}^h \{x_2(y)^2 - x_1(y)^2\} dy,$$

which shows that (3.7) holds.

This completes the proof of Lemma 7. \square

We, now, suppose that X satisfies Condition (D). Then for each sufficiently small $h > 0$, $V = (\alpha h, h)$. Hence, we obtain $G = \frac{3}{5}(\alpha h, h)$. Therefore we get from (3.3) that

$$(3.13) \quad \frac{3}{5}hS_P(h) = \phi(h)$$

and

$$(3.14) \quad \frac{3}{5}\alpha hS_P(h) = \psi(h).$$

It also follows from (3.13) and (3.14) that

$$(3.15) \quad \psi(h) = \alpha\phi(h).$$

By differentiating (3.13) with respect to h , (3.6) shows that

$$(3.16) \quad S_P(h) = \frac{2}{3}hL_P(h).$$

Differentiating (3.16) with respect to h yields

$$(3.17) \quad 2hL'_P(h) = L_P(h).$$

Integrating (3.17) shows that

$$(3.18) \quad L_P(h) = C(P)\sqrt{h},$$

where $C(P)$ is a constant. Hence, it follows from Lemma 5 that

$$(3.19) \quad L_P(h) = \frac{2}{\sqrt{a}}\sqrt{h},$$

from which we get

$$(3.20) \quad x_2(h) - x_1(h) = \frac{2}{\sqrt{a}}\sqrt{h}.$$

Now, differentiating (3.15) and applying Lemma 7 show that

$$(3.21) \quad x_2(h) + x_1(h) = 2\alpha h.$$

Hence, we get from (3.20) and (3.21) that

$$(3.22) \quad x_1(h) = \alpha h - \frac{1}{\sqrt{a}}\sqrt{h}, \quad x_2(h) = \alpha h + \frac{1}{\sqrt{a}}\sqrt{h}.$$

Since $I_P(h) = (x_1(h), x_2(h))$, we obtain from (3.22) that the graph $X : y = f(x)$ is given by

$$(3.23) \quad f(x) = \begin{cases} \frac{1}{2a\alpha^2}\{2a\alpha x + 1 - \sqrt{4a\alpha x + 1}\}, & \text{if } \alpha \neq 0, \\ ax^2, & \text{if } \alpha = 0. \end{cases}$$

It follows from (3.23) that X is an open arc of the parabola defined by

$$(3.24) \quad ax^2 - 2a\alpha xy + a\alpha^2 y^2 - y = 0.$$

Note that if $\alpha \neq 0$, the function $f(x)$ in (3.23) is defined on an interval J such that $J \subset (-\infty, -1/(4a\alpha))$ or $J \subset (-1/(4a\alpha), \infty)$ according to the sign of α .

Finally, we use the following coordinate change from (3.1):

$$(3.25) \quad \begin{aligned} x &= u \cos \theta + v \sin \theta - b \cos \theta - c \sin \theta, \\ y &= -u \sin \theta + v \cos \theta + b \sin \theta - c \cos \theta. \end{aligned}$$

Then, after a long calculation we see that the curve $X : v = g(u)$ is an open arc of the parabola determined by the following quadratic polynomial

$$(3.26) \quad g(u) = \begin{cases} aw^3(u-b)^2 + \alpha(u-b) + c, & \text{if } \alpha \neq 0, \\ a(u-b)^2 + c, & \text{if } \alpha = 0. \end{cases}$$

Note that $g(b) = c$, $g'(b) = \alpha$ and $\kappa(P) = 2a$. This completes the proof of the if part of Theorem 3.

It is elementary to show the only if part of Theorem 3, or see Chapter 7 of [25], which is originally due to Archimedes. This completes the proof of Theorem 3.

4. Proof of Theorem 4

In this section, using Proposition 1, we give the proof of Theorem 4.

Let X be a strictly locally convex plane curve in the plane \mathbb{R}^2 with the unit normal N pointing to the convex side. For a fixed point P on X and a sufficiently small $h > 0$, we denote by l the parallel line through $P + hN(P)$ to the tangent t of the curve X at P . We let $d_P(h)$ the distance from the center G of gravity of the section of X cut off by l to the tangent t of the curve X at P .

First, suppose that X satisfies Condition (E).

For a fixed point $P \in X$, we adopt a coordinate system (x, y) of \mathbb{R}^2 as in the beginning of Section 2. Then the curve X is locally the graph of a non-negative strictly convex $C^{(3)}$ function $f : \mathbb{R} \rightarrow \mathbb{R}$. Hence, the Taylor's formula of $f(x)$ is given by

$$(4.1) \quad f(x) = ax^2 + f_3(x),$$

where $a = f''(0)/2$, and $f_3(x)$ is an $O(|x|^3)$ function. Since $\kappa(P) = 2a > 0$, we see that a is positive.

It follows from (E) and the definition of $d_P(h)$ that

$$(4.2) \quad \frac{3}{5}hS_P(h) = \phi(h),$$

where we put

$$(4.3) \quad \phi(h) = \frac{1}{2} \int_{f(x) < h} \{h^2 - f(x)^2\} dx.$$

If we differentiate $\phi(h)$ with respect to h , then Lemma 7 shows that

$$(4.4) \quad \phi'(h) = hL_P(h).$$

By differentiating both sides of (4.2) with respect to h , we get from (4.4) and (2.2) that

$$(4.5) \quad S_P(h) = \frac{2}{3}hL_P(h),$$

which shows that the curve X satisfies Condition (C) in Proposition 1. Note that the argument in the proof of Proposition 1 given by [18] can be applied even if the curve X is a strictly locally convex plane curve. This completes the proof of the if part of Theorem 4.

For a proof of the only if part of Theorem 4, see Chapter 7 of [25], which is originally due to Archimedes. This completes the proof of Theorem 4.

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