# DIRECTIONAL ASSOCIATED CURVES OF A NULL CURVE IN MINKOWSKI 3-SPACE

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ABSTRACT. In this paper, we define the directional associated curve and the self-associated curve of a null curve in Minkowski 3-space. We study the properties and relations between the null curve, its directional associated curve and its self-associated curve. At the same time, by solving certain differential equations, we get the explicit representations of some null curves.

#### 1. Introduction

In the history of differential geometry, the theory of the associated curve of a given curve has been one of interesting topics. Many geometers have investigated this problem from various viewpoints: For instance, in Euclidean 3-space, the Bertrand partner and the Mannheim partner curves are two important kinds of associated curves. They are characterized by the curvature and the torsion, namely, a Bertrand curve satisfies  $\lambda \kappa + \mu \tau = 1$  and a Mannheim curve has  $\kappa = \lambda(\kappa^2 + \tau^2)$ , where  $\kappa$  is the curvature and  $\tau$  the torsion.

In Minkowski 3-space, there are three kinds of typical curves, that is, space-like, time-like and null (light-like) curves. Among them, a null curve is quite different from other types of curves. Motivated by the idea about partner curves, we naturally consider the associated curves of a null curve in Minkowski 3-space.

In [4], the authors defined the W-direction curve  $\tilde{r}$  of a null curve r in such a way that the tangent vector field of  $\tilde{r}$  is W, where W is a vector field along the given null curve. In this case, the curve r is called the W-direction donor curve of  $\tilde{r}$ .

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In this paper, we define the directional associated curves of a null curve, and introduce the notion of the self-associated curve of a null curve. Using the representation formulas of cone curves introduced in [8], we study the properties of a null curve and its directional associated curves in Minkowski 3-space.

In Section 2, we will review some basic facts for null curves and non-null curves in Minkowski 3-space (see [1]-[8]). In Sections 3-5, we discuss some specific directional associated curve of a null curve. In Section 6, we study the relations between the null curve and its self-associated curve.

All geometric objects under consideration are smooth and curves are regular unless otherwise stated.

#### 2. Preliminaries

In this section, we review some basic facts for null curves and non-null curves in Minkowski 3-space.

### 2.1. Vector product in Minkowski 3-space

Let  $E_1^3$  be a Minkowski 3-space with natural Lorentzian metric

$$\langle \cdot, \cdot \rangle = dx_1^2 + dx_2^2 - dx_3^2$$

in terms of the natural coordinate system  $(x_1, x_2, x_3)$ .

Let  $a = (a_1, a_2, a_3)$ ,  $b = (b_1, b_2, b_3)$  and  $c = (c_1, c_2, c_3)$  be vectors in  $E_1^3$ . Then their scalar product is given by

$$\langle a, b \rangle = a_1 b_1 + a_2 b_2 - a_3 b_3,$$

and the exterior product by

$$a \times b = \begin{vmatrix} e_1 & e_2 & e_3 \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{vmatrix} = \left( \begin{vmatrix} a_2 & a_3 \\ b_2 & b_3 \end{vmatrix}, \begin{vmatrix} a_3 & a_1 \\ b_3 & b_1 \end{vmatrix}, - \begin{vmatrix} a_1 & a_2 \\ b_1 & b_2 \end{vmatrix} \right),$$

where  $\{e_1, e_2, e_3\}$  is an orthonormal basis in  $E_1^3$ . One can have

$$e_1 \times e_2 = -e_3$$
,  $e_2 \times e_3 = e_1$ ,  $e_3 \times e_1 = e_2$ .

On the other hand, the mixed product is given by

$$\langle a \times b, c \rangle = \begin{vmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix}$$

and the double exterior product is then obtained as

$$(2.1) (a \times b) \times c = \langle b, c \rangle a - \langle a, c \rangle b.$$

A vector  $v \in E_1^3$  is said to be space-like if  $\langle v, v \rangle > 0$  or v = 0; time-like if  $\langle v, v \rangle < 0$ ; null (light-like) if  $\langle v, v \rangle = 0$ , respectively.

Remark 2.1. Hereafter, we assume that a null geodesic in  $E_1^3$  is not regarded as a null curve.

## 2.2. Frenet formulas of null curves in $E_1^3$

Let r(s) be a null curve with parameter s in  $E_1^3$ . If  $\langle r''(s), r''(s) \rangle \neq 0$ , we can take  $\tilde{s}$  appropriately in such a way that  $\langle r''(\tilde{s}), r''(\tilde{s}) \rangle = 1$ . In this case, the parameter  $\tilde{s}$  is called the null arc length parameter. For a null curve r = r(s) with null arc length parameter s, there exists a unique frame field  $\{x, \alpha, y\}$  such that

(2.2) 
$$\begin{cases} r'(s) = x(s), \\ x'(s) = \alpha(s), \\ \alpha'(s) = \kappa(s)x(s) - y(s), \\ y'(s) = -\kappa(s)\alpha(s), \end{cases}$$

where

$$\langle x, x \rangle = \langle y, y \rangle = \langle x, \alpha \rangle = \langle y, \alpha \rangle = 0, \quad \langle x, y \rangle = \langle \alpha, \alpha \rangle = 1,$$
  
$$\alpha = x \times y, \quad \alpha \times x = x, \quad \alpha \times y = -y.$$

Here in the sequel,  $x, \alpha, y$  are also called the tangent, principal normal and binormal vector field of r(s), respectively and the function  $\kappa(s)$  is called the null curvature function of r(s).

From (2.2) we have

$$\kappa(s) = -\frac{1}{2} \langle r^{\prime\prime\prime}(s), r^{\prime\prime\prime}(s) \rangle$$

and

(2.3) 
$$r^{(4)}(s) - 2\kappa(s)r''(s) - \kappa'(s)r'(s) = 0.$$

### 2.3. Representation formulas of null curves in $E_1^3$

In [8], the authors defined the structure function f of a cone curve in  $Q^2 \subset E_1^3$  and described it with f, where  $Q^2 = \{(x_1, x_2, x_3) \in E_1^3 : x_1^2 + x_2^2 - x_3^2 = 0\}$ . It is well-known that the integral curve of a cone curve in  $Q^2$  is a null curve in  $E_1^3$ , so we can easily get the representation formulas of null curves in the sense of [8].

**Proposition 2.2** ([8]). Let  $r(s): I \to E_1^3$  be a null curve parameterized by null arc length parameter s. Then r(s) can be written as

$$r(s) = \int \frac{f}{2f_s} (f - f^{-1}, 2, f + f^{-1}) ds,$$

where f(s) is called the structure function of r(s). The structure function f(s) and the null curvature function  $\kappa(s)$  satisfy

$$\kappa(s) = \frac{1}{2} [(\log f_s)_s]^2 - [(\log f_s)_s]_s$$

with  $f_s = \frac{df(s)}{ds}$ .

## 2.4. Frenet formulas of space-like and time-like curves in $E_1^3$

Let  $r = r(s) : I \to E_1^3$  be a space-like curve parameterized by arc length s with the Frenet frame  $\{T, N, B\}$ .

Case 1: If  $\langle r''(s), r''(s) \rangle \neq 0$ , the following Frenet equations are satisfied

$$\begin{cases} r'(s) = T(s), \\ T'(s) = \kappa(s)N(s), \\ N'(s) = -\varepsilon\kappa(s)T(s) + \tau(s)B(s), \\ B'(s) = \tau(s)N(s), \end{cases}$$

where  $\langle T, T \rangle = 1$ ,  $\langle N, N \rangle = \varepsilon = \pm 1$ ,  $\langle B, B \rangle = -\varepsilon$ ,  $\langle T, N \rangle = \langle T, B \rangle = \langle B, N \rangle = 0$  for some functions  $\kappa$  and  $\tau$  which are called the curvature and the torsion of r, respectively.

Case 2: If  $\langle r''(s), r''(s) \rangle = 0$ , the Frenet equations are given by

$$\begin{cases} r'(s) = T(s), \\ T'(s) = N(s), \\ N'(s) = \kappa(s)N(s), \\ B'(s) = -T(s) - \kappa(s)B(s), \end{cases}$$

where  $\langle T, T \rangle = \langle N, B \rangle = 1$ ,  $\langle N, N \rangle = \langle B, B \rangle = \langle T, N \rangle = \langle T, B \rangle = 0$ . The function  $\kappa(s)$  is also called the curvature function of r.

Remark 2.3. Let r be a space-like curve in Minkowski 3-space with arc length parameter s. In particular, the space-like curve r is said to be null type space-like if  $\langle r''(s), r''(s) \rangle = 0$ .

If  $r = r(s) : I \to E_1^3$  is a time-like curve parameterized by arc length and framed by the Frenet frame  $\{T, N, B\}$ , then the following Frenet equations are satisfied

$$\left\{ \begin{array}{l} r'(s) = T(s), \\ T'(s) = \kappa(s)N(s), \\ N'(s) = \kappa(s)T(s) + \tau(s)B(s), \\ B'(s) = -\tau(s)N(s), \end{array} \right.$$

where  $\langle T, T \rangle = -1$ ,  $\langle N, N \rangle = \langle B, B \rangle = 1$ ,  $\langle T, N \rangle = \langle T, B \rangle = \langle B, N \rangle = 0$ . Similarly to those of the space-like curve, the functions  $\kappa(s)$  and  $\tau(s)$  are called the curvature and the torsion of r(s), respectively.

# 2.5. Directional associated curves and self-associated curve of a null curve in $E_1^3$

In this section, the definition of the directional associated curves of a null curve is given. Also, the self-associated curve of a null curve is defined in  $E_1^3$ .

**Definition.** Let  $r(s): I \to E_1^3$  be a null curve parametrized by null arc length parameter s with the Frenet frame  $\{x, \alpha, y\}$  and W a vector field along r(s). A curve  $\tilde{r}(\tilde{s}): I \to E_1^3$  is called the W-directional associated curve of r(s) if  $\tilde{r}(\tilde{s})$  is in the direction of W which is in the Frenet frame of  $\tilde{r}(\tilde{s})$  at each r(s).

Remark 2.4. From now on we assume that  $\tilde{s}$  is the null arc length parameter if  $\tilde{r}$  is a null curve and the arc length parameter if  $\tilde{r}$  is a non-null curve.

Remark 2.5. If the vector filed W is parallel to x (respectively, y or  $\alpha$ ) the directional associated curve of r(s) is called the x-directional (respectively, y-directional or  $\alpha$ -directional) associated curve and it can be expressed by, respectively,

$$\tilde{r}(\tilde{s}(s)) = r(s) + \lambda(s)x(s),$$
  
 $\tilde{r}(\tilde{s}(s)) = r(s) + \lambda(s)y(s)$ 

or

$$\tilde{r}(\tilde{s}(s)) = r(s) + \lambda(s)\alpha(s)$$

for some function  $\lambda$ , which is called the distance function between r(s) and  $\tilde{r}(\tilde{s})$ . The distance function  $\lambda$  is assumed to be non-zero.

**Example.** Let r(s) be a null curve of null curvature  $-\frac{1}{2}$  and parametrized by null arc length given by

$$r(s) = (\cos s, \sin s, s).$$

Then, the Frenet frame is given by

$$x(s) = (-\sin s, \cos s, 1), \ \alpha(s) = (-\cos s, -\sin s, 0), \ y(s) = \frac{1}{2}(-\sin s, \cos s, -1).$$

Define  $\tilde{r}$  by  $\tilde{r}(s) = r(s) + 2\alpha(s)$ . Then

$$\tilde{r}(s) = (-\cos s, -\sin s, s).$$

Obviously,  $\tilde{r}(s)$  is also a null curve parametrized by null arc length and its Frenet frame  $\{\tilde{x}, \tilde{\alpha}, \tilde{y}\}$  is

$$\tilde{x}(s) = (\sin s, -\cos s, 1), \ \tilde{\alpha}(s) = (\cos s, \sin s, 0), \ \tilde{y}(s) = \frac{1}{2}(\sin s, -\cos s, -1).$$

In this example,  $\tilde{\alpha} = -\alpha$ , so  $\tilde{r}(s)$  is an  $\alpha$ -directional associated curve of r(s).

**Definition.** Let  $r(s): I \to E_1^3$  be a null curve parametrized by the null arc length parameter s with the Frenet frame  $\{x,\alpha,y\}$ . The integral curve  $\tilde{r}(\tilde{s}) = \int y(\tilde{s}) d\tilde{s}$  is called the self-associated curve of r(s).

### 3. x-directional associated curves of a null curve in $E_1^3$

**Theorem 3.1.** Let  $r = r(s) : I \to E_1^3$  be a null curve parametrized by null arc length parameter s and  $\tilde{r}(\tilde{s})$  its x-directional associated curve. Then, we get

- (1)  $\tilde{r}(\tilde{s})$  must be a null type space-like curve;
- (2) the curvature function of  $\tilde{r}(\tilde{s})$  satisfies

$$\tilde{\kappa} = \pm \frac{1}{\lambda^2};$$

(3) the null curvature function of r(s) can be expressed by

$$\kappa = \frac{1 + 4\lambda' + 3\lambda'^2 - 2\lambda\lambda''}{2\lambda^2},$$

where  $\lambda(s)$  is the distance function.

*Proof.* The x-directional associated curve  $\tilde{r}$  of r is given by

$$\tilde{r}(\tilde{s}) = r(s) + \lambda(s)x(s),$$

which implies

(3.1) 
$$\dot{\tilde{r}}(\tilde{s})\frac{d\tilde{s}}{ds} = (1 + \lambda')x + \lambda\alpha,$$

where  $\dot{\tilde{r}}(\tilde{s}) = \frac{d\tilde{r}}{d\tilde{s}}$ . Then, (3.1) yields

(3.2) 
$$\langle \dot{\tilde{r}}, \dot{\tilde{r}} \rangle (\frac{d\tilde{s}}{ds})^2 = \lambda^2.$$

Since the distance function  $\lambda(s) \neq 0$  and  $\tilde{r}$  is regular,  $\tilde{r}(\tilde{s})$  must be a space-like curve, i.e.,  $\langle \dot{\tilde{r}}, \dot{\tilde{r}} \rangle > 0$ . By definition of the *x*-directional associated curve, we know  $\tilde{r}(\tilde{s})$  must be a null type space-like curve, i.e.,  $\langle \ddot{\tilde{r}}, \ddot{\tilde{r}} \rangle = 0$ .

Let  $\{\tilde{T}, \tilde{N}, \tilde{B}\}$  be the Frenet frame of  $\tilde{r}$ . Then  $\dot{\tilde{r}}(\tilde{s}) = \tilde{T}(\tilde{s})$ . So, equation (3.1) can be written as

(3.3) 
$$\tilde{T}\frac{d\tilde{s}}{ds} = (1 + \lambda')x + \lambda\alpha.$$

Based on the definition of the x-directional associated curve and the Frenet frame of the null type space-like curve, we consider the following cases.

Case 1:  $\tilde{N}(\tilde{s}(s)) \wedge x(s) = 0$  along r. In this case, we get

(3.4) 
$$\tilde{N}(\tilde{s}(s)) = a(s)x(s)$$

for some function  $a(s) \neq 0$ .

Differentiating (3.4) gives

(3.5) 
$$\tilde{\kappa}\tilde{N}\frac{d\tilde{s}}{ds} = a'x + a\alpha,$$

from which,

$$a(s) = 0$$
,

a contradiction.

Case 2:  $\tilde{B}(\tilde{s}(s)) \wedge x(s) = 0$  along r.

We may suppose

(3.6) 
$$\tilde{B}(\tilde{s}(s)) = a(s)x(s)$$

for some function  $a(s) \neq 0$ .

Similarly as was given in Case 1, by differentiating (3.6), we have

(3.7) 
$$(-\tilde{T} - \tilde{\kappa}\tilde{B})\frac{d\tilde{s}}{ds} = a'x + a\alpha.$$

Taking the scalar product on both sides of (3.7), we obtain

$$(3.8) \qquad \qquad (\frac{d\tilde{s}}{ds})^2 = a^2.$$

By taking the scalar product with (3.7) with  $\tilde{T}$  and using (3.3), we get

$$(3.9) -(\frac{d\tilde{s}}{ds})^2 = a\lambda.$$

Thus, (3.8) and (3.9) give

$$a = -\lambda$$
.

Therefore, we get  $\frac{d\tilde{s}}{ds} = \pm \lambda$ . Without loss of generality, we may assume

$$\frac{d\tilde{s}}{ds} = \lambda.$$

Differentiating (3.3) with (3.10), we get

(3.11) 
$$\lambda' \tilde{T} + \lambda^2 \tilde{N} = (\lambda'' + \lambda \kappa) x + (1 + 2\lambda') \alpha - \lambda y,$$

from which,

$$\lambda'^2 = (1 + 2\lambda')^2 - 2\lambda(\lambda'' + \lambda\kappa).$$

Thus, the null curvature function  $\kappa$  can be expressed by

(3.12) 
$$\kappa = \frac{1 + 4\lambda' + 3\lambda'^2 - 2\lambda\lambda''}{2\lambda^2}.$$

Taking the scalar product with (3.7) and (3.11), we obtain

$$\tilde{\kappa} = \frac{1}{\lambda^2}.$$

If 
$$\frac{d\tilde{s}}{ds} = -\lambda$$
, equation (3.12) still holds with  $\tilde{\kappa} = -\frac{1}{\lambda^2}$ .

**Corollary 3.2.** Let  $r(s): I \to E_1^3$  be a null curve with null arc length parameter s and  $\tilde{r}(\tilde{s})$  the x-directional associated curve. If the distance function  $\lambda(s)$  is a nonzero constant, then we have

- (1) the null curvature function of r(s) is a positive constant and the curvature function of  $\tilde{r}(\tilde{s})$  is a nonzero constant;
- (2) r(s) can be expressed as

$$r(s) = C_1 \sinh(\sqrt{2\kappa})s + C_2 \cosh(\sqrt{2\kappa})s + C_3 s,$$

where  $C_1, C_2, C_3 \in E_1^3$ ;

(3) the x-directional associated curve  $\tilde{r}(\tilde{s})$  is

$$\tilde{r}(s) = C_4 \sinh(\sqrt{2\kappa})s + C_5 \cosh(\sqrt{2\kappa})s + C_6 s$$

where  $C_4, C_5, C_6 \in E_1^3$ .

*Proof.* By Theorem 3.1, if the distance function is a nonzero constant, the null curvature function  $\kappa$  is a positive constant and the curvature function  $\tilde{\kappa}$  is a nonzero constant.

From (2.3), we have

(3.13) 
$$r^{(4)} = 2\kappa r''.$$

Solving the equation (3.13), we get up to translation in  $E_1^3$ 

$$r(s) = C_1 \sinh(\sqrt{2\kappa})s + C_2 \cosh(\sqrt{2\kappa})s + C_3 s.$$

Therefore, the x-directional associated curve is given as

$$\tilde{r}(s) = C_4 \sinh(\sqrt{2\kappa})s + C_5 \cosh(\sqrt{2\kappa})s + C_6 s,$$

where 
$$C_1, C_2, C_3, C_4, C_5, C_6 \in E_1^3$$
.

Corollary 3.3. Let  $r(s): I \to E_1^3$  be a null curve parametrized by null arc length parameter s and  $\tilde{r}(\tilde{s})$  its x-directional associated curve. If the distance function  $\lambda(s)$  is a linear function of s, then we obtain

(1) the null curvature function of r(s) is

$$\kappa(s) = a(s+b)^{-2},$$

where  $a \neq 0, b$  are constants;

- (2) r(s) can be expressed by one of the following forms:
  - (a)  $r(s) = C_1 s^2 + C_2 s^{(2+\sqrt{1+2a})} + C_3 s^{(2-\sqrt{1+2a})}$  for 2a > -1,
  - (b)  $r(s) = C_1 s^2 + C_2 s^2 \log s + C_3 s^2 \log^2 s$  for 2a = -1,
  - (c)  $r(s) = C_1 s^2 + C_2 s^2 \sin[(\sqrt{-1-2a})\log s] + C_3 s^2 \cos[(\sqrt{-1-2a})\log s]$ for 2a < -1,

where  $C_1, C_2, C_3 \in E_1^3$ ;

(3) the curvature function of  $\tilde{r}(\tilde{s})$  is given by

$$\tilde{\kappa}(s) = \pm (cs + d)^{-2},$$

where  $c \neq 0, d$  are constants.

*Proof.* By Theorem 3.1, if the distance function is a linear function of s, the null curvature function can be written as

$$\kappa(s) = a(s+b)^{-2},$$

where  $a \neq 0$ , b are constants. By a parameter transformation, we can put b = 0. From (2.3), we have

$$(3.14) s^3 r^{(4)} - 2asr'' + 2ar' = 0.$$

Solving the differential equation (3.14), we get

- (1)  $r(s) = C_1 s^2 + C_2 s^{(2+\sqrt{1+2a})} + C_3 s^{(2-\sqrt{1+2a})}$  if 2a > -1,
- (2)  $r(s) = C_1 s^2 + C_2 s^2 \log s + C_3 s^2 \log^2 s$  if 2a = -1, (3)  $r(s) = C_1 s^2 + C_2 s^2 \sin[(\sqrt{-1} 2a) \log s] + C_3 s^2 \cos[(\sqrt{-1} 2a) \log s]$ if 2a < -1,

where  $C_1, C_2, C_3 \in E_1^3$ .

Also by Theorem 3.1, the curvature function of  $\tilde{r}(\tilde{s})$  is given by

$$\tilde{\kappa}(s) = \pm (cs + d)^{-2},$$

where  $c \neq 0, d$  are constants.

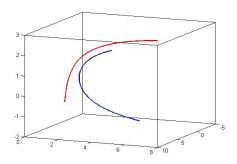


FIGURE 1. The blue curve is a given null curve and the red one is its x-directional associated curve when  $\lambda=1,\,\kappa=1/2.$ 

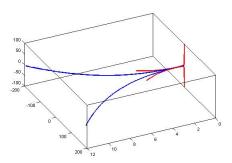


FIGURE 2. The red curve is a given null curve and the blue one is its x-directional associated curve when  $\lambda = s$ ,  $\kappa = 4/s^2$ .

# 4. y-directional associated curves of a null curve in $E_1^3$

**Theorem 4.1.** Let  $r = r(s): I \to E_1^3$  be a null curve parametrized by null arc length and  $\tilde{r}(\tilde{s})$  its y-directional associated curve. Then we have

- (1) the y-directional associated curve must be a null curve;
- (2) the null curvature functions  $\kappa$  and  $\tilde{\kappa}$  satisfy

$$\tilde{\kappa} = \kappa, \quad \kappa^2 = 2(\frac{1}{\lambda})',$$

where  $\lambda(s)$  is the distance function.

*Proof.* The definition of the y-directional associated curve of a null curve yields

(4.1) 
$$\tilde{r}(\tilde{s}) = r(s) + \lambda(s)y(s),$$

from which, we get

$$\dot{\tilde{r}}(\tilde{s})\frac{d\tilde{s}}{ds} = x + \lambda' y - \lambda \kappa \alpha$$

and

$$\langle \dot{\tilde{r}}, \dot{\tilde{r}} \rangle (\frac{d\tilde{s}}{ds})^2 = \lambda^2 \kappa^2 + 2\lambda'.$$

It is not difficult to find that a null curve and a null type space-like curve in  $E_1^3$  can be the y-directional associated curve of a null curve by the definition.

Case 1: If  $\tilde{r}(\tilde{s})$  is a null curve with null arc length parameter  $\tilde{s}$  and the Frenet frame  $\{\tilde{x}, \tilde{\alpha}, \tilde{y}\}$ , then we get  $\dot{\tilde{r}}(\tilde{s}) = \tilde{x}(\tilde{s})$  and

(4.2) 
$$\tilde{x}(\tilde{s})\frac{d\tilde{s}}{ds} = x + \lambda' y - \lambda \kappa \alpha.$$

It implies

$$\lambda^2 \kappa^2 + 2\lambda' = 0,$$

or, equivalently,

$$\kappa^2 = 2(\frac{1}{\lambda})'.$$

Case 1.1:  $\tilde{x}(\tilde{s}) \wedge y(s) = 0$ .

Then, we get

(4.4) 
$$\tilde{x}(\tilde{s}) = a(s)y(s)$$

for some function  $a(s) \neq 0$ . Taking the scalar product with (4.2) and (4.4) implies a(s) = 0, a contradiction.

Case 1.2:  $\tilde{y}(\tilde{s}) \wedge y(s) = 0$ .

Similarly, we may put

$$\tilde{y}(\tilde{s}) = a(s)y(s)$$

for some function  $a(s) \neq 0$  and some parametrization  $\tilde{s} = \tilde{s}(s)$ .

Taking the scalar product with (4.2) and (4.5), we get

$$\frac{d\tilde{s}}{ds} = a(s).$$

Thus, (4.2) implies

$$\tilde{x}a = x + \lambda' y - \lambda \kappa \alpha.$$

Differentiating (4.6) yields

(4.7) 
$$a^{2}\tilde{\alpha} + \tilde{x}a' = -\lambda\kappa^{2}x + (\lambda'' + \lambda\kappa)y + (1 - 2\lambda'\kappa - \lambda\kappa')\alpha.$$

Making use of (4.5) and (4.7), we get

$$(4.8) a' = -a\lambda \kappa^2.$$

Together with (4.3) and (4.8), we obtain

$$\frac{a'}{a} = \frac{2\lambda'}{\lambda}.$$

Thus, we have

$$a = c\lambda^2$$

for some positive constant c.

On the other hand, differentiating (4.5), we obtain

$$(4.9) -\tilde{\kappa}\tilde{\alpha}a = a'y - a\kappa\alpha.$$

Using (4.9) and (4.6), we get

$$(4.10) -a^2 \tilde{\kappa} \tilde{x} = -a' \alpha - a \kappa x + (a \kappa \lambda' - \lambda \kappa a') y.$$

Taking account of (4.5) and (4.10), we have

$$\tilde{\kappa} = \kappa$$
.

Case 2: In case that  $\tilde{r}(\tilde{s})$  is a null type space-like curve parametrized by arc length with the Frenet frame  $\{\tilde{T}, \tilde{N}, \tilde{B}\}$ , a contradiction is derived no matter the direction of  $\tilde{N}$  or  $\tilde{B}$  coincides with that of y.

**Corollary 4.2.** Let  $r = r(s) : I \to E_1^3$  be a null curve parametrized by null arc length s and  $\tilde{r}(\tilde{s})$  the y-directional associated curve. If the distance function  $\lambda(s)$  is a nonzero constant, then we have

- (1) r(s) and  $\tilde{r}(\tilde{s})$  are all null cubics;
- (2) r(s) can be expressed as

$$r(s) = C_1 s^3 + C_2 s^2 + C_3 s,$$

where  $C_i \in E_1^3$  (i = 1, 2, 3).

*Proof.* In Theorem 4.1, if the distance function is a nonzero constant, both of the null curvatures  $\kappa$  and  $\tilde{\kappa}$  are equal to zero. Thus, they are null cubics.

From (2.3), we have

$$(4.11) r^{(4)} = 0.$$

Therefore, up to translation, we get

$$(4.12) r(s) = C_1 s^3 + C_2 s^2 + C_3 s,$$

where 
$$C_1, C_2, C_3 \in E_1^3$$
. (For the null cubics, see [6].)

**Corollary 4.3.** Let  $r(s): I \to E_1^3$  be a null curve with null arc length parameter s and  $\tilde{r}(\tilde{s})$  the y-directional associated curve. When the distance function  $\lambda(s)$  is a linear function of s, we have

(1) the null curvature function is given by

$$\tilde{\kappa} = \kappa = a(s+b)^{-1},$$

where  $a \neq 0, b$  are constants.

(2) r(s) can be expressed by

$$r(s) = C_1 \int u^2(s)ds + C_2 \int u(s)v(s)ds + C_3 \int v^2(s)ds,$$

where  $C_1, C_2, C_3 \in E_1^3$ .

*Proof.* In Theorem 4.1, if the distance function is a linear function of s, the null curvature functions are easily obtained as

$$\tilde{\kappa} = \kappa = a(s+b)^{-1},$$

where  $a \neq 0$ , b are constants.

From (2.3), when  $\kappa(s) = \frac{a}{s}$  (by a parameter transformation we can put b=0), the curve r(s) satisfies

$$(4.13) s^2 r^{(4)} - 2asr'' + ar' = 0.$$

Solving the equation (4.13), we get

$$r(s) = C_1 \int u^2(s)ds + C_2 \int u(s)v(s)ds + C_3 \int v^2(s)ds$$

for some functions u and v given by

$$\begin{cases} u(s) = \sqrt{s} J_1(\sqrt{-2a} s^{\frac{1}{2}}), \\ v(s) = \sqrt{s} Y_1(\sqrt{-2a} s^{\frac{1}{2}}) & \text{if } a < 0 \end{cases}$$

and

$$\begin{cases} u(s) = \operatorname{Re}(\sqrt{s}Z_1(i\sqrt{2a}s^{\frac{1}{2}})), \\ v(s) = \operatorname{Im}(\sqrt{s}Z_1(i\sqrt{2a}s^{\frac{1}{2}})) & \text{if} \quad a > 0, \end{cases}$$

where  $C_1, C_2, C_3 \in E_1^3$ ,  $Z_v(s)$  is the cylinder function,  $J_v(s)$  is the Bessel function of the first kind and  $Y_v(s)$  is the Bessel function of the second kind (see [9]).

## 5. $\alpha$ -directional associated curves of a null curve in $E_1^3$

**Theorem 5.1.** Let  $r: I \to E_1^3$  be a null curve parametrized by null arc length parameter s and  $\tilde{r}(\tilde{s})$  its  $\alpha$ -directional associated curve. When the direction of the principal normal vector field of  $\tilde{r}(\tilde{s})$  coincides with that of  $\alpha$ , we have

1.  $\tilde{r}(\tilde{s})$  is a null curve written as

$$\tilde{r}(s) = \lambda \int y(s)ds,$$

that is, r(s) is the binormal donor curve of  $\tilde{r}(\tilde{s})$ , where  $\lambda$  is a nonzero constant. In this case, the null curvature function  $\kappa$  of r(s) is a nonzero constant and r(s) can be expressed by one of following forms:

(1) 
$$r(s) = C_1 \sinh(\sqrt{2\kappa})s + C_2 \cosh(\sqrt{2\kappa})s + C_3 s \text{ for } \kappa > 0,$$

(2) 
$$r(s) = C_1 \sin(\sqrt{-2\kappa})s + C_2 \cos(\sqrt{-2\kappa})s + C_3 s \text{ for } \kappa < 0,$$

where  $C_1, C_2, C_3 \in E_1^3$ .

2.  $\tilde{r}(\tilde{s})$  is a curve on a de Sitter 3-space or hyperbolic 3-space written as

$$\tilde{r}(s) = r(s) + C\alpha(s)$$

for some nonzero constant C. In this case, the null curvature function  $\kappa$  of r(s) is a constant and r(s) is given by

- (1)  $r(s) = C_1 s^3 + C_2 s^2 + C_3 s$  for  $\kappa = 0$ ;
- (2)  $r(s) = C_1 \sinh(\sqrt{2\kappa})s + C_2 \cosh(\sqrt{2\kappa})s + C_3 s \text{ for } \kappa > 0;$ (3)  $r(s) = C_1 \sin(\sqrt{-2\kappa})s + C_2 \cos(\sqrt{-2\kappa})s + C_3 s \text{ for } \kappa < 0,$

where  $C_1, C_2, C_3 \in E_1^3$ .

3. When  $\tilde{r}(\tilde{s})$  is not a null curve or a curve on a de Sitter 3-space or hyperbolic 3-space, it is given by

$$\tilde{r}(s) = r(s) - \frac{2}{\kappa + C}\alpha(s).$$

In this case, the null curvature function  $\kappa(s)$  of r(s) is given by the differential equation

$$2\kappa'' - 3\kappa^2 - 2\kappa C + C^2 = 0.$$

where C is a constant.

*Proof.* In the proof, we use the same parameter s for the null curve r and the associated curve  $\tilde{r}$ . Then, we have

$$\tilde{r}(s) = r(s) + \lambda(s)\alpha(s),$$

from which,

(5.1) 
$$\tilde{r}'(s) = (1 + \lambda \kappa)x + \lambda'\alpha - \lambda y,$$
$$\tilde{r}''(s) = (2\lambda'\kappa + \lambda\kappa')x + (1 + 2\lambda\kappa + \lambda'')\alpha - 2\lambda'y.$$

It implies

(5.2) 
$$\langle \tilde{r}', \tilde{r}' \rangle = \lambda'^2 - 2\lambda - 2\lambda^2 \kappa.$$

From (2.1) and (5.1), we have

$$(5.3) \quad (\tilde{r}' \times \tilde{r}'') \times \tilde{r}' = (\lambda' \lambda'' - \lambda' - 2\lambda \lambda' \kappa - \lambda^2 \kappa') \tilde{r}' - (\lambda'^2 - 2\lambda - 2\lambda^2 \kappa) \tilde{r}''.$$

When the direction of the principal normal vector field of  $\tilde{r}(\tilde{s})$  coincides with that of  $\alpha$ , from (5.3), we have

$$\begin{cases} 2\lambda'(\lambda'^2 - 2\lambda - 2\lambda^2\kappa) = \lambda(\lambda'\lambda'' - \lambda' - 2\lambda\lambda'\kappa - \lambda^2\kappa'), \\ (\lambda'^2 - 2\lambda - 2\lambda^2\kappa)(2\lambda'\kappa + \lambda\kappa') = (1 + \lambda\kappa)(\lambda'\lambda'' - \lambda' - 2\lambda\lambda'\kappa - \lambda^2\kappa'). \end{cases}$$

We put

$$A=\lambda'^2-2\lambda-2\lambda^2\kappa,\quad B=\frac{1}{2}A'=\lambda'\lambda''-\lambda'-2\lambda\lambda'\kappa-\lambda^2\kappa'.$$

Case 1:  $A \equiv 0$ .

Since  $\lambda \neq 0$ , B = 0. From (5.2),  $\tilde{r}(s)$  is a null curve. From the Frenent frame (2.2),  $\tilde{r}(s)$  can be written as

(5.5) 
$$\tilde{r}(s) = c \int y(s) ds,$$

where c is a nonzero constant.

Thus, from (5.5) and (5.1),  $\lambda$  and  $\kappa$  are non-zero constants. Then r(s) can be written as

- (1)  $r(s) = C_1 \sinh(\sqrt{2\kappa})s + C_2 \cosh(\sqrt{2\kappa})s + C_3 s$  for  $\kappa > 0$ ;
- (2)  $r(s) = C_1 \sin(\sqrt{-2\kappa})s + C_2 \cos(\sqrt{-2\kappa})s + C_3 s$  for  $\kappa < 0$ ,

where  $C_1, C_2, C_3 \in E_1^3$ .

Case 2:  $A \neq 0, B = 0$ .

From (5.4),  $\lambda$  is a nonzero constant and  $\kappa' = 0$ . Therefore, r(s) is given as follow:

- (1)  $r(s) = C_1 s^3 + C_2 s^2 + C_3 s$  for  $\kappa = 0$ ;
- (2)  $r(s) = C_1 \sinh(\sqrt{2\kappa})s + C_2 \cosh(\sqrt{2\kappa})s + C_3 s$  for  $\kappa > 0$ ;
- (3)  $r(s) = C_1 \sin(\sqrt{-2\kappa})s + C_2 \cos(\sqrt{-2\kappa})s + C_3 s$  for  $\kappa < 0$ ,

where  $C_1, C_2, C_3 \in E_1^3$ .

Its  $\alpha$ -directional associated curve is expressed as

$$\tilde{r}(s) = r(s) + \lambda \alpha(s),$$

where  $\lambda$  is a nonzero constant. Apparently,  $\tilde{r}(s)$  is a curve on a de Sitter 3-space or a hyperbolic 3-space.

Case 3:  $A \neq 0, B \neq 0$ .

From (5.4), we have

$$\frac{2\lambda'A}{A(2\lambda'\kappa + \lambda\kappa')} = \frac{\lambda B}{(1 + \lambda\kappa)B},$$

i.e.,

$$(5.6) 2\lambda' = \lambda^2 \kappa'.$$

Solving the differential equation (5.6), we have

$$\lambda = \frac{-2}{\kappa + C},$$

where C is a constant of integration.

Substituting (5.7) into (5.4) yields

$$(5.8) 2\kappa'' - 3\kappa^2 - 2\kappa C + C^2 = 0.$$

Solving (5.8) (by a parameter transformation), we have the solution in parametric forms:

$$\begin{cases} s = \pm \frac{1}{\sqrt{|2C|}} \int (C_1 + \eta^3 \pm \eta^2)^{\frac{-1}{2}} d\eta + C_2, \\ \kappa = \pm 2C\eta - C, \end{cases}$$

or

$$\begin{cases} s = \pm \frac{1}{\sqrt{|2C|}} \int (C_1 - \eta^3 \pm \eta^2)^{\frac{-1}{2}} d\eta + C_2, \\ \kappa = \pm 2C\eta - C, \end{cases}$$

where  $C, C_1, C_2$  are constants (see [9]).

In this case, its  $\alpha$ -directional associated curve can be written as

$$\tilde{r}(s) = r(s) - \frac{2}{\kappa + C}\alpha(s),$$

where C is a constant and  $\alpha(s) = r''(s)$ .

**Theorem 5.2.** Let  $r: I \to E_1^3$  be a null curve parametrized by null arc length parameter s and  $\tilde{r}(\tilde{s})$  the  $\alpha$ -directional associated curve. When the direction of the binormal vector field of  $\tilde{r}(\tilde{s})$  coincides with that of  $\alpha$ , we have

1.  $\tilde{r}(\tilde{s})$  is a curve on a de Sitter 3-space or hyperbolic 3-space written as

$$\tilde{r}(s) = r(s) + C\alpha(s)$$

for some non-zero constant C. In this case, the null curvature function of r(s) is a non-zero constant and r(s) is given by

- (1)  $r(s) = C_1 \sinh(\sqrt{2\kappa})s + C_2 \cosh(\sqrt{2\kappa})s + C_3 s \text{ for } \kappa > 0;$
- (2)  $r(s) = C_1 \sin(\sqrt{-2\kappa})s + C_2 \cos(\sqrt{-2\kappa})s + C_3 s \text{ for } \kappa < 0,$

where  $C_1, C_2, C_3 \in E_1^3$ .

2. When  $\tilde{r}(\tilde{s})$  is not a curve on a de Sitter 3-space or hyperbolic 3-space, it is given by

$$\tilde{r}(s) = r(s) - \frac{2}{\kappa + C}\alpha(s).$$

In this case, the null curvature function  $\kappa(s)$  of r(s) is given by the differential equation

$$2\kappa'' - 3\kappa^2 - 2\kappa C + C^2 = 0,$$

where C is a constant.

Remark 5.3. For a null curve r with the  $\alpha$ -directional associated curve  $\tilde{r}$ , if the binormal vector field of  $\tilde{r}$  is parallel to  $\alpha$  or the principal normal vector field of  $\tilde{r}$  is parallel to  $\alpha$ , we have similar results.

# 6. Self-associated curve of a null curve in $E_1^3$

**Theorem 6.1.** Let r(s) be a null curve in Minkowski 3-space  $E_1^3$  with null arc length parameter s and  $\tilde{r}(\tilde{s})$  its self-associated null curve. Then the followings are equivalent:

- (1) The null curvature functions  $\kappa$  and  $\tilde{\kappa}$  satisfy  $\tilde{\kappa} = \frac{1}{\kappa}$ .
- (2) The self-associated curve of  $\tilde{r}(\tilde{s})$  is r(s).
- (3) r(s) is the binormal donor curve of  $\tilde{r}(\tilde{s})$ .

*Proof.* Define  $\tilde{r}(\tilde{s}) = \int y(\tilde{s})d\tilde{s}$ , where  $\tilde{s}$  denotes the null arc length parameter of  $\tilde{r}$ . Let  $\{\tilde{x}, \tilde{\alpha}, \tilde{y}\}$  be the Frenet frame of  $\tilde{r}$ .

From  $\tilde{r}(\tilde{s}) = \int y(\tilde{s})d\tilde{s}$ , we have

(6.1) 
$$\tilde{x}(\tilde{s}) = y(\tilde{s}).$$

Differentiating (6.1) with respect to  $\tilde{s}$ , we have

$$\tilde{\alpha} = -\kappa \alpha \frac{ds}{d\tilde{s}}.$$

It gives

$$(\frac{d\tilde{s}}{ds})^2 = \kappa^2.$$

For convenience, we put

$$\frac{d\tilde{s}}{ds} = -\kappa.$$

Then, we get

(6.2) 
$$\tilde{\alpha} = \alpha.$$

Differentiating (6.2), we have

$$\tilde{\kappa}\tilde{x} - \tilde{y} = (\kappa x - y)\frac{ds}{d\tilde{s}},$$

in other words,

$$\tilde{\kappa}\tilde{x} - \tilde{y} = -x + \frac{y}{\kappa}.$$

It implies

$$\tilde{\kappa} = \frac{1}{\kappa}.$$

Therefore, we get

$$\tilde{y}(\tilde{s}) = x(s),$$

from which,

$$\int \tilde{y}(\tilde{s})ds = \int x(s)ds = r(s).$$

This completes the proof.

Finally, we give a simple example to show the null curve and its self-associated curve. Let  $r(s)=(\cos s,\sin s,s)$  with null curvature  $\kappa=-1/2$  and parametrized by null arc length.

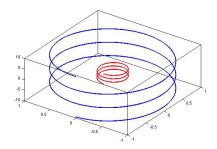


FIGURE 3. The blue curve is a null curve and the red one is its self-associated curve.

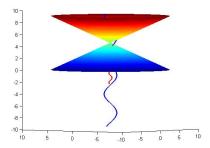


FIGURE 4. A null curve and its self-associated null curve on light-like cone.

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