

## GLOBAL GRADIENT ESTIMATES FOR NONLINEAR ELLIPTIC EQUATIONS

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ABSTRACT. We prove global gradient estimates in weighted Orlicz spaces for weak solutions of nonlinear elliptic equations in divergence form over a bounded non-smooth domain as a generalization of Calderón-Zygmund theory. For each point and each small scale, the main assumptions are that nonlinearity is assumed to have a uniformly small mean oscillation and that the boundary of the domain is sufficiently flat.

### 1. Introduction

Let  $\Omega$  be a bounded domain in  $\mathbb{R}^n$ ,  $n \geq 2$ , with its non-smooth boundary  $\partial\Omega$  and let  $F = F(x) : \Omega \rightarrow \mathbb{R}^n$  be a given vector-valued function at least in  $L^2(\Omega, \mathbb{R}^n)$ . With these notations, consider the following nonlinear elliptic equation in divergence form:

$$(1.1) \quad \begin{cases} \operatorname{div} \mathbf{a}(Du, x) = \operatorname{div} F & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega, \end{cases}$$

where the nonlinearity  $\mathbf{a} = \mathbf{a}(\xi, x) : \mathbb{R}^n \times \mathbb{R}^n \rightarrow \mathbb{R}^n$  is measurable in  $x$  for all  $\xi \in \mathbb{R}^n$  and continuous in  $\xi$  for almost all  $x \in \mathbb{R}^n$ . Here assume standard monotonicity and growth conditions on  $\mathbf{a}$  as follows: For some positive constants  $c_0$  and  $c_1$ ,

$$(1.2) \quad \begin{cases} c_0|\xi - \eta|^2 \leq [\mathbf{a}(\xi, x) - \mathbf{a}(\eta, x)] \cdot (\xi - \eta) \\ |\mathbf{a}(\xi, x)| + |\xi| |D_\xi \mathbf{a}(\xi, x)| \leq c_1 |\xi| \end{cases}$$

for all  $\xi, \eta \in \mathbb{R}^n$  and for almost every  $x \in \mathbb{R}^n$ .

As usual, we consider a weak solution  $u \in H_0^1(\Omega)$ , which means that the following integral formula holds:

$$\int_{\Omega} \mathbf{a}(Du, x) \cdot D\varphi \, dx = \int_{\Omega} F \cdot D\varphi \, dx, \quad \forall \varphi \in H_0^1(\Omega).$$

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Received February 14, 2014.

2010 *Mathematics Subject Classification.* 35J60, 46E30.

*Key words and phrases.* nonlinear elliptic equation, global gradient estimate, Calderón-Zygmund theory, BMO space, Reifenberg flat domain.

This work was supported by the 2013 Research Fund of the University of Seoul.

The existence and uniqueness of a weak solution to problem (1.1) can be obtained by the Minty-Browder method for monotone operators, see [9, 20], under the assumption  $F \in L^2(\Omega, \mathbb{R}^n)$ , with the estimate

$$\| |Du|^2 \|_{L^1(\Omega, \mathbb{R}^n)} \leq c \| |F|^2 \|_{L^1(\Omega, \mathbb{R}^n)},$$

the constant  $c$  is independent of  $u$  and  $F$ .

In this paper

$$B_\rho(y) = \{x \in \mathbb{R}^n : |x - y| < \rho\}$$

denotes the open ball on  $\mathbb{R}^n$  centered  $y \in \mathbb{R}^n$  and radius  $\rho > 0$  and  $|E|$  denotes the  $n$ -dimensional Lebesgue measure of a set  $E \subset \mathbb{R}^n$ . With the notation, the regularity assumption on the nonlinearity  $\mathbf{a} = \mathbf{a}(\xi, x)$  and a finer geometric assumption on the domain  $\Omega$  are introduced. First set

$$\theta(\mathbf{a}; B_\rho(y))(x) = \sup_{\xi \in \mathbb{R}^n \setminus \{0\}} \frac{|\mathbf{a}(\xi, x) - \bar{\mathbf{a}}_{B_\rho(y)}(\xi)|}{|\xi|},$$

where

$$\bar{\mathbf{a}}_{B_\rho(y)}(\xi) = \int_{B_\rho(y)} \mathbf{a}(\xi, x) dx = \frac{1}{|B_\rho(y)|} \int_{B_\rho(y)} \mathbf{a}(\xi, x) dx$$

is the integral average of  $\mathbf{a}(\xi, x)$  in the variable  $x$  over  $B_\rho(y)$  for fixed  $\xi \in \mathbb{R}^n$ . The function  $\theta(\mathbf{a}; B_\rho(y))$  provides the measurement of the oscillation of  $\frac{\mathbf{a}(\xi, x)}{|\xi|}$  in the variable  $x$  over  $B_\rho(y)$ , uniformly in  $\xi$ .

**Definition 1.1.** A vector field  $\mathbf{a}$  is said to be  $(\delta, R)$ -vanishing if

$$\sup_{0 < \rho \leq R} \sup_{y \in \mathbb{R}^n} \int_{B_\rho(y)} \theta(\mathbf{a}; B_\rho(y))(x) dx \leq \delta.$$

To measure the deviation of  $\partial\Omega$  from being an  $(n - 1)$ -dimensional affine space at each scale  $\rho > 0$ , use the following so-called ‘‘Reifenberg flatness’’.

**Definition 1.2.** A bounded domain  $\Omega$  is said to be  $(\delta, R)$ -Reifenberg flat if for every  $x \in \partial\Omega$  and every  $\rho \in (0, R]$ , there exists a coordinate system  $\{y_1, \dots, y_n\}$ , which can depend on  $\rho$  and  $x$  such that  $x = 0$  in this coordinate system and that

$$(1.3) \quad B_\rho(0) \cap \{y_n > \delta\rho\} \subset B_\rho(0) \cap \Omega \subset B_\rho(0) \cap \{y_n > -\delta\rho\}.$$

*Remark 1.3.* The above definition warrants a few comments. Because the main problem (1.1) has a scaling invariance property, the constant  $R$  can be taken as 1 or any other constant greater than 1. However, the constant  $\delta$  is a small positive constant still invariant under such scaling (see Lemma 2.1). In fact, the Reifenberg flatness (1.3) is meaningful when  $0 < \delta < \frac{1}{8}$ , see [25], and with such small  $\delta$ , these flatness conditions mean that the deviation of  $\partial\Omega$  from being an  $(n - 1)$ -dimensional affine space is small enough at each scale  $\rho > 0$ . In addition, by (1.3), the following measure density condition is obtained:

$$|\Omega \cap B_\rho(y)| \geq \left(\frac{1 - \delta}{2}\right)^n |B_\rho(y)| \geq \left(\frac{7}{16}\right)^n |B_\rho(y)|$$

for all  $y \in \Omega$  and  $\rho \in (0, R)$ .

Here the purpose is to generalize Calderón-Zygmund-type estimates of the gradient of a weak solution of (1.1) in weighted Orlicz spaces. Because these Calderón-Zygmund-type estimates play an important role in regularity theory with Hölder estimates, studies have examined for classical  $L^p$  estimates or their generalizations (e.g., [8, 11, 13, 21, 26]).

From a technical point of view, this paper appropriately applies the approach introduced in [10] and later developed in [3, 6, 7]. Although the main tools are the Hardy-Littlewood maximal function and the Calderón-Zygmund-Krylov-Safonov-type decomposition, the general theory of singular integrals employed in [15, 22, 24] is not used. Note that this approach is useful even when considering global estimates with non-smooth boundaries. It should be pointed out that one may obtain the same results based on the so-called “Harmonic-analysis-free” technique in [1]. This approach is quite effective for  $L^p$  regularity estimates for nonlinear parabolic problems with no invariance property under normalization, see [2, 4, 14]. In addition, note that the so-called “sharp maximal function method”, first introduced in [18] and later modified in [11, 12, 19], is useful when differential operators related to problems are bounded and linear.

The Muchenhaupt weight is now introduced. A positive and locally integrable function  $w$  on  $\mathbb{R}^n$  is said to be of class  $A_p$ ,  $1 < p < \infty$ , if

$$(1.4) \quad \sup \left( \frac{1}{|B|} \int_B w(x) dx \right) \left( \frac{1}{|B|} \int_B w(x)^{\frac{-1}{p-1}} dx \right)^{p-1} \leq A < \infty,$$

where the supremum runs over all balls  $B$  formed by  $B = B_\rho(y)$ . Note that the smallest constant  $A$  for which (1.4) holds is denoted by  $[w]_p$ . Given  $w \in A_p$  and a measurable set  $E \subset \mathbb{R}^n$ , we use the notation

$$w(E) = \int_E w(x) dx$$

to denote the  $w$ -measure of the set  $E$ . On the other hand, there is another way to define the  $A_p$  class: That is, the weight  $w$  belongs to  $A_p$  if and only if

$$(1.5) \quad \left( \frac{1}{|B|} \int_B f(x) dx \right)^p \leq \frac{c}{w(B)} \int_B (f(x))^p w(x) dx$$

holds for all positive functions  $f$  and all balls  $B$ . The smallest constant  $c$  for which (1.5) is valid equals  $[w]_p$ . As a direct consequence of (1.5), the  $A_p$  weight has a doubling property (see the first inequality (\*) of (1.6)). First, a remarkable feature of  $A_p$  weights is that they have the reverse Hölder property. That is, for  $w \in A_p$  ( $1 < p < \infty$ ), there exists a small positive constant  $\epsilon_0$  depending only on  $n, p$  and  $[w]_p$  such that  $w \in A_{p-\epsilon_0}$  with the estimate  $[w]_{p-\epsilon_0} < c[w]_p$  for some  $c = c(n, p, [w]_p) > 0$ . The unification of the doubling and reverse Hölder properties produces the following comparability between

the  $w$ -measure and the Lebesgue measure:

$$(1.6) \quad \frac{1}{[w]_p} \left( \frac{|E|}{|B|} \right)^p \stackrel{(*)}{\leq} \frac{w(E)}{w(B)} \leq c_2 \left( \frac{|E|}{|B|} \right)^{\tau_1}, \quad E \subset B,$$

for some constants  $c_2 > 1$  and  $\tau_1 \in (0, 1)$ . We remark that these  $c_2$  and  $\tau_1$  depend only on  $n, p$ , and  $[w]_p$  and thus not on  $E$  and  $B$ .

We now turn to Orlicz spaces. The function  $\Phi : [0, \infty) \rightarrow [0, \infty)$  is said to be a *Young function* if  $\Phi$  is increasing, convex, and satisfies

$$\Phi(0) = 0, \quad \Phi(\infty) = \lim_{\rho \rightarrow +\infty} \Phi(\rho) = +\infty, \quad \lim_{\rho \rightarrow 0+} \frac{\Phi(\rho)}{\rho} = 0, \quad \lim_{\rho \rightarrow +\infty} \frac{\Phi(\rho)}{\rho} = +\infty.$$

Throughout the paper, the Young function  $\Phi$  is assumed to satisfy  $\Delta_2$  and  $\nabla_2$  conditions, denoted by  $\Phi \in \Delta_2 \cap \nabla_2$ ,

- ( $\Delta_2$ -condition) there exists  $\mu > 1$  such that  $\Phi(2\rho) \leq \mu\Phi(\rho)$  for all  $\rho > 0$ ;
- ( $\nabla_2$ -condition) there exists  $\nu > 1$  such that  $2\nu\Phi(\rho) \leq \Phi(\nu\rho)$  for all  $\rho > 0$ .

We next define the lower index of  $\Phi$ , denoted by  $i(\Phi)$ , by

$$i(\Phi) = \lim_{\lambda \rightarrow 0+} \frac{\log(h_\Phi(\lambda))}{\log \lambda} = \sup_{0 < \lambda < 1} \frac{\log(h_\Phi(\lambda))}{\log \lambda},$$

where

$$h_\Phi(\lambda) = \sup_{\rho > 0} \frac{\Phi(\lambda\rho)}{\Phi(\rho)} \quad (\lambda > 0).$$

For example,  $i(\Phi) = q$  if  $\Phi(\rho) = \rho^q$  with  $q > 1$ . In addition, this  $\Delta_2 \cap \nabla_2$ -condition ensures that the Young function increases moderately. That is, there are two constants  $q_0$  and  $q_1$  with  $1 < q_0 \leq q_1 < \infty$  such that

$$(1.7) \quad \frac{1}{c_3} \min\{\lambda^{q_0}, \lambda^{q_1}\} \Phi(\rho) \leq \Phi(\lambda\rho) \leq c_3 \max\{\lambda^{q_0}, \lambda^{q_1}\} \Phi(\rho), \quad \lambda, \rho \geq 0,$$

where the constant  $c_3$  is independent of  $\lambda$  and  $\rho$ . In fact, the index number  $i(\Phi)$  is equal to the supremum of  $q_0$  satisfying (1.7). Finally, we would like to mention that the  $\Delta_2 \cap \nabla_2$ -condition is unavoidable for the type of regularity considered here, see [27].

The condition  $w \in A_{i(\Phi)}$  is the main assumption on the Muckenhoupt weight  $w(x)$ . Because  $\Phi \in \Delta_2 \cap \nabla_2$ ,  $1 < i(\Phi) < \infty$ . It is worth summarizing an important property of the  $A_{i(\Phi)}$  weight  $w$  considered here. There exists a small positive constant  $\epsilon_0$  depending the index  $i(\Phi)$  and the dimension such that  $w \in A_{i(\Phi)-\epsilon_0}$  with the estimate  $[w]_{i(\Phi)-\epsilon_0} \leq c_{n, i(\Phi)} [w]_{i(\Phi)}$ . Consequently,

$$[w]_{i(\Phi)} \leq [w]_{i(\Phi)-\epsilon_0} \leq c [w]_{i(\Phi)}$$

and therefore assume that

$$(1.8) \quad \lambda^{i(\Phi)-\epsilon_0} \Phi(t) \leq c \Phi(\lambda t), \quad \lambda \geq 1, \quad t \geq 0.$$

We refer to [16, 17] for a more in-depth discussion on the condition  $w \in A_{i(\Phi)}$ .

We now ready to introduce the weighted Orlicz space considered here. For a Young function  $\Phi \in \Delta \cap \nabla_2$  and a positive and locally integrable function  $w = w(x) \in A_{i(\Phi)}$ , the weighted Orlicz space  $L_w^\Phi(\Omega)$  is the class of all measurable functions  $g : \Omega \rightarrow \mathbb{R}$  satisfying

$$\int_{\Omega} \Phi(|g(x)|)w(x)dx < +\infty.$$

Indeed, the weighted Luxemburg norm,

$$\|g\|_{L_w^\Phi(\Omega)} = \inf \left\{ \kappa > 0 : \int_{\Omega} \Phi \left( \frac{|g(x)|}{\kappa} \right) w(x) dx \leq 1 \right\},$$

is well-defined as a norm, up to equal almost everywhere, on  $L_w^\Phi(\Omega)$ , see [17].

By the convexity of  $\Phi$  and the estimate (1.7), the following is obtained:

$$(1.9) \quad \begin{aligned} & \frac{1}{c_3} \min\{\|g\|_{L_w^{\Phi_0}(\Omega)}^{q_0}, \|g\|_{L_w^{\Phi_1}(\Omega)}^{q_1}\} \\ & \leq \int_{\Omega} \Phi(|g(x)|)w(x)dx \leq c_3 \max\{\|g\|_{L_w^{\Phi_0}(\Omega)}^{q_0}, \|g\|_{L_w^{\Phi_1}(\Omega)}^{q_1}\}. \end{aligned}$$

If  $\|g\|_{L_w^\Phi(\Omega)} \leq 1$ , then it follows from (1.7) that

$$\frac{1}{c_3} \left( \frac{1}{\|g\|_{L_w^\Phi(\Omega)} + \epsilon} \right)^{q_0} \int_{\Omega} \Phi(|g(x)|)w(x)dx \leq \int_{\Omega} \Phi \left( \frac{|g(x)|}{\|g\|_{L_w^\Phi(\Omega)} + \epsilon} \right) w(x)dx \leq 1$$

and that

$$1 < \int_{\Omega} \Phi \left( \frac{|g(x)|}{\|g\|_{L_w^\Phi(\Omega)} - \epsilon} \right) w(x)dx \leq c_3 \left( \frac{1}{\|g\|_{L_w^\Phi(\Omega)} - \epsilon} \right)^{q_1} \int_{\Omega} \Phi(|g(x)|)w(x)dx$$

for all sufficiently small  $\epsilon > 0$ . Therefore,

$$\frac{1}{c_3} \|g\|_{L_w^{\Phi_1}(\Omega)}^{q_1} \leq \int_{\Omega} \Phi(|g(x)|)w(x)dx \leq c_3 \|g\|_{L_w^{\Phi_0}(\Omega)}^{q_0}$$

provided that  $\|g\|_{L_w^\Phi(\Omega)} \leq 1$ . Similarly, we have

$$\frac{1}{c_3} \|g\|_{L_w^{\Phi_0}(\Omega)}^{q_0} \leq \int_{\Omega} \Phi(|g(x)|)w(x)dx \leq c_3 \|g\|_{L_w^{\Phi_1}(\Omega)}^{q_1}$$

in the case  $\|g\|_{L_w^\Phi(\Omega)} > 1$ . This finishes the proof for (1.9).

We are now ready to state the main result.

**Theorem 1.4.** *Given a Young function  $\Phi \in \Delta_2 \cap \nabla_2$ , let  $w \in A_{i(\Phi)}$ . Suppose that  $|F|^2 \in L_w^\Phi(\Omega)$  and  $u \in H_0^1(\Omega)$  is a weak solution of (1.1). Then there exists a small positive constant  $\delta = \delta(c_0, c_1, n, \Phi, w)$  such that if  $\mathbf{a}$  is  $(\delta, R)$ -vanishing and  $\Omega$  is  $(\delta, R)$ -Reifenberg flat, then  $|Du|^2 \in L_w^\Phi(\Omega)$  with the estimate*

$$(1.10) \quad \||Du|^2\|_{L_w^\Phi(\Omega)} \leq c \| |F|^2 \|_{L_w^\Phi(\Omega)},$$

the constant  $c$  depending on  $c_0, c_1, n, R, \Phi, w$ , and  $\Omega$ .

We remark that the present result is a natural extension of previous research [9, 20]. In fact, the problem (1.1) under the same conditions is considered in unweighted [9] and weighted [20] Lebesgue spaces.

Before ending this section, we check the existence and uniqueness of a weak solution. The following lemma ensures that for each  $F(x)$  with  $|F|^2 \in L_w^\Phi(\Omega)$ , the problem (1.1) has a unique weak solution.

**Lemma 1.5.** *Let  $\Phi \in \Delta_2 \cap \nabla_2$  and  $w \in A_{i(\Phi)}$ . If  $|F|^2 \in L_w^\Phi(\Omega)$ , then  $|F|^2 \in L^1(\Omega)$ , and*

$$(1.11) \quad \int_{\Omega} |F(x)|^2 dx \leq c \left[ \left( \int_{\Omega} \Phi(|F|^2)w(x)dx \right)^{\frac{1}{q_0}} + \left( \int_{\Omega} \Phi(|F|^2)w(x)dx \right)^{\frac{1}{q_1}} \right],$$

where  $q_0$  and  $q_1$  are defined in (1.7).

*Proof.* We first recall the self-improving property of  $A_{i(\Phi)}$ -weight, that is,  $w \in A_{i(\Phi)-\epsilon_0}$  with (1.8). Set  $f(x) = |F(x)|^2$ . With a direct calculation,

$$\begin{aligned} \int_{\{\Omega:|f|\geq 1\}} |f(x)| dx &= \int_{\{\Omega:|f|\geq 1\}} |f(x)|w(x)^{\frac{1}{i(\Phi)-\epsilon_0}} w(x)^{-\frac{1}{i(\Phi)-\epsilon_0}} dx \\ &\leq \left( \int_{\{\Omega:|f|\geq 1\}} |f(x)|^{i(\Phi)-\epsilon_0} w(x) dx \right)^{\frac{1}{i(\Phi)-\epsilon_0}} \\ &\quad \times \left( \int_{\Omega} w(x)^{\frac{-1}{i(\Phi)-\epsilon_0-1}} dx \right)^{\frac{i(\Phi)-\epsilon_0-1}{i(\Phi)-\epsilon_0}} \\ &\leq \frac{|\Omega|[w]_{i(\Phi)-\epsilon_0}}{w(\Omega)^{\frac{1}{i(\Phi)-\epsilon_0}}} \left( \int_{\{\Omega:|f|\geq 1\}} |f(x)|^{i(\Phi)-\epsilon_0} w(x) dx \right)^{\frac{1}{i(\Phi)-\epsilon_0}}. \end{aligned}$$

It follows from (1.8) that

$$|f(x)|^{i(\Phi)-\epsilon_0} \leq \frac{c}{\Phi(1)} \Phi(|f(x)|) \quad \text{if } |f(x)| \geq 1,$$

and so

$$\int_{\{\Omega:|f|\geq 1\}} |f(x)| dx \leq c \left( \int_{\Omega} \Phi(|f(x)|)w(x)dx \right)^{\frac{1}{i(\Phi)-\epsilon_0}}.$$

On the other hand, it follows from  $i(\Phi) \leq q_1$  that  $w \in A_{q_1}$  with  $[w]_{q_1} \leq [w]_{i(\Phi)}$ . Because, by (1.7),

$$|f(x)|^{q_1} \leq \frac{c}{\Phi(1)} \Phi(|f(x)|) \quad \text{if } |f(x)| \leq 1,$$

$$\int_{\{\Omega:|f|\leq 1\}} |f(x)| dx \leq c \left( \int_{\Omega} \Phi(|f(x)|)w(x)dx \right)^{\frac{1}{q_1}}.$$

Since  $\epsilon_0$  is small enough, we get

$$\int_{\Omega} |f(x)| dx \leq c \left[ \left( \int_{\Omega} \Phi(|f(x)|)w(x)dx \right)^{\frac{1}{q_0}} + \left( \int_{\Omega} \Phi(|f(x)|)w(x)dx \right)^{\frac{1}{q_1}} \right]. \quad \square$$

### 2. Preliminary tools

We begin this section with the following invariance property under normalization and scaling. The proof follows by direct computations (for further details, see [9]).

**Lemma 2.1.** *Let  $u$  be a weak solution to the problem (1.1). Assume that the nonlinearity  $\mathbf{a}(\xi, x)$  satisfies (1.2) and is  $(\delta, R)$ -vanishing. For each  $\lambda > 1$  and  $0 < r < 1$ , define the rescaled maps*

$$\tilde{\mathbf{a}}(\xi, x) = \frac{\mathbf{a}(\lambda\xi, rx)}{\lambda}, \quad \tilde{\Omega} = \left\{ \frac{1}{r}x : x \in \Omega \right\}, \quad \tilde{u}(x) = \frac{u(rx)}{\lambda r}, \quad \tilde{F}(x) = \frac{F(rx)}{\lambda}.$$

Then

- (1)  $\tilde{u} \in H_0^1(\tilde{\Omega})$  is the weak solution of
 
$$\operatorname{div} \tilde{\mathbf{a}}(D\tilde{u}, x) = \operatorname{div} \tilde{F} \quad \text{in } \tilde{\Omega},$$
- (2)  $\tilde{\mathbf{a}}(\xi, x)$  satisfies the structural assumption (1.2) with the same constants  $c_0$  and  $c_1$ ,
- (3)  $\tilde{\mathbf{a}}$  is  $(\delta, \frac{R}{r})$ -vanishing and  $\tilde{\Omega}$  is  $(\delta, \frac{R}{r})$ -Reifenberg flat.

We now recall the Hardy-Littlewood maximal function and its basic properties. Let  $g$  be a locally integrable function on  $\mathbb{R}^n$ . Then the Hardy-Littlewood maximal function is given by

$$(\mathcal{M}g)(x) = \sup_{\rho>0} \int_{B_{\rho}(x)} |g(y)| dy = \sup_{\rho>0} \frac{1}{|B_{\rho}(x)|} \int_{B_{\rho}(x)} |g(y)| dy.$$

If  $g$  is defined only on a bounded subset of  $\mathbb{R}^n$ , then we define as

$$\mathcal{M}g = \mathcal{M}\bar{g},$$

where  $\bar{g}$  is the zero extension of  $g$  in  $\mathbb{R}^n$ . This maximal function holds the so-called *weak (1, 1) inequality*. More specifically, there exists a positive constant  $c = c(n)$  such that

$$(2.1) \quad |\{x \in \mathbb{R}^n : (\mathcal{M}g)(x) > \lambda\}| \leq \frac{c}{\lambda} \int_{\mathbb{R}^n} |g(x)| dx$$

for any  $\lambda > 0$ . As the well-known Muchenhaupt characterization of the  $A_p$ -weight, the Hardy-Littlewood maximal operator is bounded from weighted Lebesgue space  $L_w^p(\mathbb{R}^n)$  to itself and the  $A_{i(\Phi)}$ -weight can be classified as follows: Given a Young function  $\Phi \in \Delta_2 \cap \nabla_2$ , the weight  $w$  belongs to the  $A_{i(\Phi)}$  class if and only if there exists  $c = c(n, \Phi, w)$  such that

$$(2.2) \quad \int_{\mathbb{R}^n} \Phi(\mathcal{M}g(x))w(x)dx \leq c \int_{\mathbb{R}^n} \Phi(|g(x)|)w(x) dx$$

for all  $g \in L_w^\Phi(\mathbb{R}^n)$  with compact support in  $\mathbb{R}^n$ . We refer to [16, 17] and the references given therein.

The following measure theory in the weighted Orlicz space is needed:

**Lemma 2.2.** *Given a Young function  $\Phi \in \Delta_2 \cap \nabla_2$ , let  $w \in A_{i(\Phi)}$ . Assume that  $g$  is a nonnegative and measurable function defined on a bounded domain  $\Omega$  in  $\mathbb{R}^n$ . Let  $\theta > 0$  and  $\lambda > 1$  be constants. Then*

$$g \in L_w^\Phi(\Omega) \iff S = \sum_{k \geq 1} \Phi(\lambda^k) w(\{x \in \Omega : g(x) > \theta \lambda^k\}) < \infty$$

and

$$(2.3) \quad \frac{1}{c} S \leq \int_\Omega \Phi(g(x)) w(x) dx \leq c(w(\Omega) + S),$$

the positive constant  $c$  depending only on  $\theta, \lambda, \Phi$ , and  $w$ .

The following version of the Calderon-Zygmund-Krylov-Safonov-type covering lemma is used to prove the main theorem. The following lemma can be found in [5, Lemma 5.4] or [23, Lemma 3.4] with slight modifications.

**Lemma 2.3.** *Given a Young function  $\Phi \in \Delta_2 \cap \nabla_2$ , let  $w \in A_{i(\Phi)}$ . Let  $\Omega$  be a bounded  $(\delta, 1)$ -Reifenberg flat domain for some small  $\delta > 0$  and let  $C$  and  $D$  be measurable sets with  $C \subset D \subset \Omega$ . Suppose that there exists small  $\epsilon > 0$  such that*

- (1) for any  $y \in \Omega$ ,  $w(C \cap B_1(y)) < \epsilon w(B_1(y))$ ,
- (2) for each  $y \in \Omega$  and  $r \in (0, 1)$ ,

$$\text{if } w(C \cap B_r(y)) \geq \epsilon w(B_r(y)), \text{ then } B_r(y) \cap \Omega \subset D.$$

Then

$$w(C) \leq c_4 \epsilon w(D),$$

the constant  $c_4$  depending only on  $n, \Phi, w$ , and the constant  $\frac{1}{1-\delta}$ .

### 3. Global $W^{1,p}$ estimates

In this section, we will complete the proof of Theorem 1.4. The following lemma is based on the same method as in the proof in [20, Theorem 4.10].

**Lemma 3.1.** *Let  $u \in H_0^1(\Omega)$  be the weak solution of (1.1). Then there exists a constant  $N = N(c_0, c_1, n) > 1$  such that for each  $0 < \epsilon < 1$  fixed, one can select small  $\delta = \delta(\epsilon, c_0, c_1, n, \Phi, w) \in (0, \frac{1}{8})$  such that if  $\mathbf{a}$  is  $(\delta, 1)$ -vanishing,  $\Omega$  is  $(\delta, 1)$ -Reifenberg flat, and if for  $0 < r < 1$  and  $y \in \Omega$ ,  $B_r(y)$  satisfies*

$$w(\{x \in \Omega : \mathcal{M}(|Du|^2) > N^2\} \cap B_r(y)) \geq \epsilon w(B_r(y)),$$

then we have

$$B_r(y) \cap \Omega \subset \{x \in \Omega : \mathcal{M}(|Du|^2) > 1\} \cup \{x \in \Omega : \mathcal{M}(|F|^2) > \delta^2\}.$$



We remark that there are similar technical lemmas in the unweighted case for higher order linear problems, see [7, 11, 13].

From now on, for simplicity and clearance the symbol  $c$  denotes a constant that can be explicitly calculated in terms of known quantities. This constant may vary in different occurrences.

Now, we are ready to prove the main theorem.

*Proof of Theorem 1.4.* Thanks to Lemma 2.1, it suffices to prove that

$$(3.1) \quad \| |Du|^2 \|_{L^{\Phi}_w(\Omega)} \leq c, \quad \text{under the assumption} \quad \| |F|^2 \|_{L^{\Phi}_w(\Omega)} \leq \delta^2.$$

In fact, taking

$$u_1 = \frac{\delta u}{\sqrt{\| |F|^2 \|_{L^{\Phi}_w(\Omega)} + \sigma}} \quad \text{and} \quad F_1 = \frac{\delta F}{\sqrt{\| |F|^2 \|_{L^{\Phi}_w(\Omega)} + \sigma}}$$

in place of  $u$  and  $F$ , respectively, in the problem (1.1), it follows from (1.11) and (1.9) that

$$(3.2) \quad \| |F_1|^2 \|_{L^{\Phi}_w(\Omega)} \leq \delta^2 \quad \text{and} \quad \int_{\Omega} |F_1(x)|^2 dx \leq c\delta^{2\tau_2},$$

where  $\tau_2 = \frac{q_0}{q_1}$ . Therefore if (3.1) is obtained with  $Du_1$  instead of  $Du$ , then the proof is completed after letting  $\sigma \rightarrow 0$ . However, in view of (1.9) and (2.2),

$$\| |Du|^2 \|_{L^{\Phi}_w(\Omega)}^{\alpha} \leq c \int_{\Omega} \Phi(|Du|^2) w(x) dx \leq c \int_{\Omega} \Phi(\mathcal{M}(|Du|^2)) w(x) dx$$

for some  $\alpha > 0$ . Consequently, it suffices to show that, by Lemma 2.2,

$$S = \sum_{k \geq 1} \Phi(N^{2k}) w(\{x \in \Omega : \mathcal{M}(|Du|^2) > N^{2k}\}) < \infty.$$

We now turn to derive the power decay estimates of the weighted measure of the upper-level set  $\{x \in \Omega : \mathcal{M}(|Du|^2) > N^{2k}\}$  for  $k = 1, 2, 3, \dots$ . To apply Lemma 2.3, first fix  $\epsilon$  and take  $\delta$  and  $N$  as given in Lemma 3.1. Then define the sets

$$\begin{cases} C = \{x \in \Omega : \mathcal{M}(|Du|^2) > N^2\}, \\ D = \{x \in \Omega : \mathcal{M}(|Du|^2) > 1\} \cup \{x \in \Omega : \mathcal{M}(|F|^2) > \delta^2\}. \end{cases}$$

Next check its hypotheses. Clearly,  $C \subset D \subset \Omega$ , and for each  $y \in \Omega$ ,

$$\begin{aligned} \frac{w(C \cap B_1(y))}{w(B_1(y))} &\stackrel{(1.6)}{\leq} c_2 \left( \frac{|C \cap B_1(y)|}{|B_1(y)|} \right)^{\tau_1} \leq c|C|^{\tau_1} \\ &\stackrel{(2.1)}{\leq} c \left( \int_{\Omega} |Du|^2 dx \right)^{\tau_1} \leq c \left( \int_{\Omega} |F|^2 dx \right)^{\tau_1} \stackrel{(3.2)}{\leq} c\delta^{2\tau_1\tau_2} < \epsilon \end{aligned}$$

for  $\delta$  small enough. Because the second condition of Lemma 2.3 is already checked in Lemma 3.1,

$$(3.3) \quad \begin{aligned} & w\left(\{x \in \Omega : \mathcal{M}(|Du|^2) > N^{2k}\}\right) \\ & \leq c_4 \epsilon w\left(\{x \in \Omega : \mathcal{M}(|Du|^2) > 1\}\right) \\ & \quad + c_4 \epsilon w\left(\{x \in \Omega : \mathcal{M}(|F|^2) > \delta^2 N^{2(k-i)}\}\right). \end{aligned}$$

On the other hand, the main problem (1.1) has the invariance property from normalization (see Lemma 2.1) and therefore the same result (3.3) may be obtained for  $(\frac{u}{N}, \frac{F}{N})$ ,  $(\frac{u}{N^2}, \frac{F}{N^2})$ ,  $(\frac{u}{N^3}, \frac{F}{N^3})$ ,  $\dots$ , inductively. From this iteration argument (for further details see, [20, Corollary 4.11]), the following power decay estimates are obtained:

$$(3.4) \quad \begin{aligned} & w\left(\{x \in \Omega : \mathcal{M}(|Du|^2) > N^{2k}\}\right) \\ & \leq \epsilon_1^k w\left(\{x \in \Omega : \mathcal{M}(|Du|^2) > 1\}\right) \\ & \quad + \sum_{i=1}^k \epsilon_1^i w\left(\{x \in \Omega : \mathcal{M}(|F|^2) > \delta^2 N^{2(k-i)}\}\right) \end{aligned}$$

for  $k = 1, 2, \dots$ , where  $\epsilon_1 = c_4 \epsilon$ . Then a direct computation yields

$$\begin{aligned} S &= \sum_{k \geq 1} \Phi(N^{2k}) w\left(\{x \in \Omega : \mathcal{M}(|Du|^2) > N^{2k}\}\right) \\ &\leq \sum_{k \geq 1} \Phi(N^{2k}) \epsilon_1^k w\left(\{x \in \Omega : \mathcal{M}(|Du|^2) > 1\}\right) \\ &\quad + \sum_{k \geq 1} \Phi(N^{2k}) \sum_{i=1}^k \epsilon_1^i w\left(\{x \in \Omega : \mathcal{M}(|F|^2) > \delta^2 N^{2(k-i)}\}\right) \\ &=: S_1 + S_2. \end{aligned}$$

Recall the following property of  $\Phi \in \Delta_2$ : There exists a constant  $\mu_1$ , depending only on  $\Phi$  and  $N$  such that  $\Phi(N^2) \leq \mu_1 \Phi(1)$ , and therefore

$$\Phi(N^{2k}) \leq \mu_1^k \Phi(1), \quad k = 1, 2, 3, \dots$$

$S_1$  is estimated as follows:

$$S_1 \leq \sum_{k \geq 1} \left( \Phi(1) \mu_1^k \epsilon_1^k w(\Omega) \right) \leq c \sum_{k \geq 1} (\mu_1 \epsilon_1)^k.$$

On the other hand,

$$\begin{aligned} S_2 &= \sum_{k \geq 1} \Phi(N^{2(k-i)} N^{2i}) \sum_{i=1}^k \epsilon_1^i w\left(\{x \in \Omega : \mathcal{M}(|F|^2) > \delta^2 N^{2(k-i)}\}\right) \\ &\leq \sum_{i \geq 1} \sum_{k \geq i} \Phi(N^{2(k-i)}) \mu_1^i \epsilon_1^i w\left(\{x \in \Omega : \mathcal{M}(|F|^2) > \delta^2 N^{2(k-i)}\}\right) \end{aligned}$$

$$\begin{aligned}
 &\leq c \sum_{i \geq 1} (\mu_1 \epsilon_1)^i \sum_{k \geq i} \Phi(N^{2(k-i)}) w \left( \left\{ x \in \Omega : \mathcal{M}(|F|^2) > \delta^2 N^{2(k-i)} \right\} \right) \\
 &\leq c \sum_{i \geq 1} (\mu_1 \epsilon_1)^i \sum_{j \geq 0} \Phi(N^{2j}) w \left( \left\{ x \in \Omega : \mathcal{M} \left( \left| \frac{F}{\delta} \right|^2 \right) > N^{2j} \right\} \right) \\
 &\stackrel{(2.3)}{\leq} c \sum_{i \geq 1} (\mu_1 \epsilon_1)^i \int_{\Omega} \Phi \left( \mathcal{M} \left( \left| \frac{F}{\delta} \right|^2 \right) \right) w(x) dx \\
 &\stackrel{(2.2), (1.9)}{\leq} c \sum_{i \geq 1} (\mu_1 \epsilon_1)^i \left\| \left| \frac{F}{\delta^2} \right|^2 \right\|_{L_w^\Phi(\Omega)}^{q_0} \stackrel{(3.1)}{\leq} c \sum_{i \geq 1} (\mu_1 \epsilon_1)^i .
 \end{aligned}$$

Therefore,

$$S \leq c \sum_{k \geq 1} (\mu_1 \epsilon_1)^k$$

where  $\epsilon_1 = c_4 \epsilon$ , as in Lemma 2.3.

First take sufficiently small  $\epsilon > 0$  to get

$$\mu_1 \epsilon_1 < 1.$$

Then one can select correspondingly small  $\delta = \delta(c_0, c_1, n, \Phi, w) > 0$  from Lemma 3.1. This completes the proof.  $\square$

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