

ZWEIER I-CONVERGENT DOUBLE SEQUENCE SPACES DEFINED BY ORLICZ FUNCTION[†]

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ABSTRACT. In this article we introduce the zweier double sequence spaces ${}_2\mathcal{Z}^I(M)$, ${}_2\mathcal{Z}_0^I(M)$ and ${}_2\mathcal{Z}_\infty^I(M)$ using the Orlicz function M . We study the algebraic properties and inclusion relations on these spaces.

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1. Introduction

Let \mathbb{N} , \mathbb{R} and \mathbb{C} be the sets of all natural, real and complex numbers respectively. We write

$$\omega = \{x = (x_{ij}) : x_{ij} \in \mathbb{R} \times \mathbb{R} \text{ or } \mathbb{C} \times \mathbb{C}\},$$

the space of all double sequences real or complex.

Let ℓ_∞ , c and c_0 denote the Banach spaces of bounded, convergent and null sequences respectively normed by

$$\|x\|_\infty = \sup_k |x_k|.$$

At the initial stage the notion of I-convergence was introduced by Kostyrko, Šalát and Wilczyński [1]. Later on it was studied by Šalát, Tripathy and Ziman[2], Demirci [3] and many others. I-convergence is a generalization of Statistical Convergence.

Now we have a list of some basic definitions used in the paper .

Definition 1.1 ([4,5]). Let X be a non empty set. Then a family of sets $I \subseteq 2^X$ (2^X denoting the power set of X) is said to be an ideal in X if

- (i) $\emptyset \in I$
- (ii) I is additive i.e $A, B \in I \Rightarrow A \cup B \in I$.
- (iii) I is hereditary i.e $A \in I, B \subseteq A \Rightarrow B \in I$.

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For more details see [6,7,8,9,10]. An Ideal $I \subseteq 2^X$ is called non-trivial if $I \neq 2^X$. A non-trivial ideal $I \subseteq 2^X$ is called admissible if $\{\{x\} : x \in X\} \subseteq I$.

A non-trivial ideal I is maximal if there cannot exist any non-trivial ideal $J \neq I$ containing I as a subset.

For each ideal I , there is a filter $\mathcal{L}(I)$ corresponding to I . i.e

$$\mathcal{L}(I) = \{K \subseteq N : K^c \in I\}, \text{ where } K^c = N - K.$$

Definition 1.2. A double sequence of complex numbers is defined as a function $x : \mathbb{N} \times \mathbb{N} \rightarrow \mathbb{C}$. We denote a double sequence as (x_{ij}) , where the two subscripts run through the sequence of natural numbers independent of each other. A number $a \in \mathbb{C}$ is called a double limit of a double sequence (x_{ij}) if for every $\epsilon > 0$ there exists some $N = N(\epsilon) \in \mathbb{N}$ such that

$$|x_{ij} - a| < \epsilon, \forall i, j \geq N \text{ (see [11, 12, 13])}$$

Definition 1.3 ([12]). A double sequence $(x_{ij}) \in \omega$ is said to be I-convergent to a number L if for every $\epsilon > 0$,

$$\{i, j \in \mathbb{N} : |x_{ij} - L| \geq \epsilon\} \in I.$$

In this case we write $I - \lim x_{ij} = L$.

Definition 1.4 ([12]). A double sequence $(x_{ij}) \in \omega$ is said to be I-null if $L = 0$. In this case we write

$$I - \lim x_{ij} = 0.$$

Definition 1.5 ([12]). A double sequence $(x_{ij}) \in \omega$ is said to be I-Cauchy if for every $\epsilon > 0$ there exist numbers $m = m(\epsilon)$, $n = n(\epsilon)$ such that

$$\{i, j \in \mathbb{N} : |x_{ij} - x_{mn}| \geq \epsilon\} \in I.$$

Definition 1.6 ([12]). A double sequence $(x_{ij}) \in \omega$ is said to be I-bounded if there exists $M > 0$ such that

$$\{i, j \in \mathbb{N} : |x_{ij}| > M\}.$$

Definition 1.7 ([12]). A double sequence space E is said to be solid or normal if $(x_{ij}) \in E$ implies $(\alpha_{ij}x_{ij}) \in E$ for all sequence of scalars (α_{ij}) with $|\alpha_{ij}| < 1$ for all $i, j \in \mathbb{N}$.

Definition 1.8 ([12]). A double sequence space E is said to be monotone if it contains the canonical preimages of its stepsaces.

Definition 1.9 ([12]). A double sequence space E is said to be convergence free if $(y_{ij}) \in E$ whenever $(x_{ij}) \in E$ and $x_{ij} = 0$ implies $y_{ij} = 0$.

Definition 1.10 ([12]). A double sequence space E is said to be a sequence algebra if $(x_{ij} \cdot y_{ij}) \in E$ whenever $(x_{ij}), (y_{ij}) \in E$.

Definition 1.11 ([12]). A double sequence space E is said to be symmetric if $(x_{ij}) \in E$ implies $(x_{\pi(ij)}) \in E$, where π is a permutation on \mathbb{N} .

Any linear subspace of ω , is called a sequence space.

A sequence space λ with linear topology is called a K-space provided each of maps $p_i \rightarrow \mathbb{C}$ defined by $p_i(x) = x_i$ is continuous for all $i \in \mathbb{N}$.

A K-space λ is called an FK-space provided λ is a complete linear metric space.

An FK-space whose topology is normable is called a BK-space.

Let λ and μ be two sequence spaces and $A = (a_{nk})$ be an infinite matrix of real or complex numbers a_{nk} , where $n, k \in \mathbb{N}$. Then we say that A defines a matrix mapping from λ to μ , and we denote it by writing $A : \lambda \rightarrow \mu$.

If for every sequence $x = (x_k) \in \lambda$ the sequence $Ax = \{(Ax)_n\}$, the A transform of x is in μ , where

$$(Ax)_n = \sum_k a_{nk}x_k, \quad (n \in \mathbb{N}). \quad (1)$$

By $(\lambda : \mu)$, we denote the class of matrices A such that $A : \lambda \rightarrow \mu$.

Thus, $A \in (\lambda : \mu)$ if and only if the series on the right side of (1) converges for each $n \in \mathbb{N}$ and every $x \in \lambda$. (see[14]).

The approach of constructing the new sequence spaces by means of the matrix domain of a particular limitation method have been recently studied by Başar and Altay[15], Malkowsky[16], Ng and Lee[17] and Wang[18], Başar, Altay and Mursaleen[19].

Şengönül[20] defined the sequence $y = (y_i)$ which is frequently used as the Z^p transform of the sequence $x = (x_i)$ i.e.,

$$y_i = px_i + (1 - p)x_{i-1}$$

where $x_{-1} = 0, p \neq 1, 1 < p < \infty$ and Z^p denotes the matrix $Z^p = (z_{ik})$ defined by

$$z_{ik} = \begin{cases} p, & (i = k), \\ 1 - p, & (i - 1 = k); (i, k \in \mathbb{N}), \\ 0, & \text{otherwise.} \end{cases}$$

Following Basar and Altay [15], Şengönül[20] introduced the Zweier sequence spaces \mathcal{Z} and \mathcal{Z}_0 as follows

$$\mathcal{Z} = \{x = (x_k) \in \omega : Z^p x \in \omega\}$$

$$\mathcal{Z}_0 = \{x = (x_k) \in \omega : Z^p x \in c_0\}.$$

An Orlicz function is a function $M : [0, \infty) \rightarrow [0, \infty)$, which is continuous, non-decreasing and convex with $M(0) = 0, M(x) > 0$ for $x > 0$ and $M(x) \rightarrow \infty$ as $x \rightarrow \infty$.(see[21,22]).

Lindenstrauss and Tzafriri[22] used the idea of Orlicz functions to construct the sequence space

$$\ell_M = \{x \in \ell^0 : \sum_{k=1}^{\infty} M\left(\frac{|x_k|}{\rho}\right) < \infty, \text{ for some } \rho > 0\}$$

The space ℓ_M is a Banach space with the norm

$$\|x\| = \inf\{\rho > 0 : \sum_{k=1}^{\infty} M\left(\frac{|x_k|}{\rho}\right) \leq 1\}$$

The space ℓ_M is closely related to the space ℓ_p which is an Orlicz sequence space with $M(x) = x^p$ for $1 \leq p < \infty$ (c.f [23],[24],[25]).

The following Lemmas will be used for establishing some results of this article.

Lemma 1.12 ([24]). *A sequence space E is solid implies that E is monotone.*

Lemma 1.13 ([26,27,28]). *Let $K \in \mathcal{L}(I)$ and $M \subseteq N$. If $M \notin I$, then $M \cap K \notin I$.*

Lemma 1.14 ([26,27,28]). *If $I \subset 2^N$ and $M \subseteq N$. If $M \notin I$, then $M \cap K \notin I$.*

Recently Vakeel.A.Khan et. al.[29] introduced and studied the following classes of sequence spaces.

$$\begin{aligned} \mathcal{Z}^I &= \{k \in \mathbb{N} : \{x = (x_k) \in \omega : I - \lim Z^p x = L \text{ for some } L\} \in I\} \\ \mathcal{Z}_0^I &= \{k \in \mathbb{N} : \{x = (x_k) \in \omega : I - \lim Z^p x = 0\} \in I\} \\ \mathcal{Z}_\infty^I &= \{k \in \mathbb{N} : \{x = (x_k) \in \omega : \sup_k |Z^p x| < \infty\} \in I\} \end{aligned}$$

We also denote by

$$m_{\mathcal{Z}}^I = \mathcal{Z}_\infty^I \cap \mathcal{Z}^I$$

and

$$m_{\mathcal{Z}_0}^I = \mathcal{Z}_\infty^I \cap \mathcal{Z}_0^I.$$

2. Main results

In this article we introduce the following classes of zweier I-Convergent double sequence spaces defined by the Orlicz function.

$$\begin{aligned} {}_2\mathcal{Z}^I(M) &= \{x = (x_{ij}) \in \omega : I - \lim M\left(\frac{|x'_{ij} - L|}{\rho}\right) = 0 \text{ for some } L \text{ and } \rho > 0\}, \\ {}_2\mathcal{Z}_0^I(M) &= \{x = (x_{ij}) \in \omega : I - \lim M\left(\frac{|x'_{ij}|}{\rho}\right) = 0 \text{ for some } \rho > 0\}, \\ {}_2\mathcal{Z}_\infty^I(M) &= \{x = (x_{ij}) \in \omega : \sup_{i,j} M\left(\frac{|x'_{ij}|}{\rho}\right) < \infty \text{ for some } \rho > 0\}. \end{aligned}$$

Also we denote by

$${}_2m_{\mathcal{Z}}^I(M) = {}_2\mathcal{Z}_\infty^I(M) \cap {}_2\mathcal{Z}^I(M)$$

and

$${}_2m_{\mathcal{Z}_0}^I(M) = {}_2\mathcal{Z}_\infty^I(M) \cap {}_2\mathcal{Z}_0^I(M).$$

Throughout the article, for the sake of convenience, we will denote by $Z^p(x_k) = x'_k$, $Z^p(y_k) = y'_k$, $Z^p(z_k) = z'_k$ for $x, y, z \in \omega$.

Theorem 2.1. For any Orlicz function M , the classes of sequences ${}_2\mathcal{Z}^I(M)$, ${}_2\mathcal{Z}_0^I(M)$, ${}_2m_{\mathcal{Z}}^I(M)$ and ${}_2m_{\mathcal{Z}_0}^I(M)$ are linear spaces.

Proof. We shall prove the result for the space ${}_2\mathcal{Z}^I(M)$. The proof for the other spaces will follow similarly. Let $(x_{ij}), (y_{ij}) \in {}_2\mathcal{Z}^I(M)$ and let α, β be scalars. Then there exists positive numbers ρ_1 and ρ_2 such that

$$I - \lim M\left(\frac{|x'_{ij} - L_1|}{\rho_1}\right) = 0, \text{ for some } L_1 \in \mathbb{C};$$

$$I - \lim M\left(\frac{|y'_{ij} - L_2|}{\rho_2}\right) = 0, \text{ for some } L_2 \in \mathbb{C}.$$

That is for a given $\epsilon > 0$, we have

$$A_1 = \{(i, j) \in \mathbb{N} \times \mathbb{N} : M\left(\frac{|x'_{ij} - L_1|}{\rho_1}\right) > \frac{\epsilon}{2}\} \in I, \tag{1}$$

$$A_2 = \{(i, j) \in \mathbb{N} \times \mathbb{N} : M\left(\frac{|y'_{ij} - L_2|}{\rho_2}\right) > \frac{\epsilon}{2}\} \in I. \tag{2}$$

Let $\rho_3 = \max\{2|\alpha|\rho_1, 2|\beta|\rho_2\}$. Since M is non-decreasing and convex function, we have

$$\begin{aligned} M\left(\frac{|(\alpha x'_{ij} + \beta y'_{ij}) - (\alpha L_1 + \beta L_2)|}{\rho_3}\right) &\leq M\left(\frac{|\alpha||x'_{ij} - L_1|}{\rho_3}\right) + M\left(\frac{|\beta||y'_{ij} - L_2|}{\rho_3}\right). \\ &\leq M\left(\frac{|x'_{ij} - L_1|}{\rho_1}\right) + M\left(\frac{|y'_{ij} - L_2|}{\rho_2}\right) \end{aligned}$$

Now, by (1) and (2),

$$\{(i, j) \in \mathbb{N} \times \mathbb{N} : M\left(\frac{|(\alpha x'_{ij} + \beta y'_{ij}) - (\alpha L_1 + \beta L_2)|}{\rho_3}\right) > \epsilon\} \subset A_1 \cup A_2.$$

Therefore $(\alpha x_{ij} + \beta y_{ij}) \in {}_2\mathcal{Z}^I(M)$. Hence ${}_2\mathcal{Z}^I(M)$ is a linear space. □

Theorem 2.2. The spaces ${}_2m_{\mathcal{Z}}^I(M)$ and ${}_2m_{\mathcal{Z}_0}^I(M)$ are Banach spaces normed by

$$\|x_{ij}\| = \inf\{\rho > 0 : \{i, j \in \mathbb{N}\} | \sup M\left(\frac{|x_{ij}|}{\rho}\right) \leq 1\}.$$

Proof. Proof of this result is easy in view of the existing techniques and therefore is omitted. □

Theorem 2.3. Let M_1 and M_2 be Orlicz functions that satisfy the Δ_2 -condition. Then

- (a) $X(M_2) \subseteq X(M_1.M_2)$;
- (b) $X(M_1) \cap X(M_2) \subseteq X(M_1 + M_2)$ For $X = {}_2\mathcal{Z}^I, {}_2\mathcal{Z}_0^I, {}_2m_{\mathcal{Z}}^I$ and ${}_2m_{\mathcal{Z}_0}^I$.

Proof. (a) Let $(x_{ij}) \in {}_2\mathcal{Z}_0^I(M_2)$. Then there exists $\rho > 0$ such that

$$I - \lim_{i,j} M_2\left(\frac{|x'_{ij}|}{\rho}\right) = 0 \tag{3}$$

Let $\epsilon > 0$ and choose δ with $0 < \delta < 1$ such that $M_1(t) < \epsilon$ for $0 \leq t \leq \delta$.

Write $y_{ij} = M_2\left(\frac{|x'_{ij}|}{\rho}\right)$ and consider for all $(i, j) \in \mathbb{N} \times \mathbb{N}$ we have

$$\lim_{0 \leq y_{ij} \leq \delta} M_1(y_{ij}) = \lim_{y_{ij} \leq \delta} M_1(y_{ij}) + \lim_{y_{ij} > \delta} M_1(y_{ij}).$$

We have

$$\lim_{y_{ij} \leq \delta} M_1(y_{ij}) \leq M_1(2) \lim_{y_{ij} \leq \delta} (y_{ij}). \tag{4}$$

For $(y_{ij}) > \delta$, we have

$$(y_{ij}) < \left(\frac{y_{ij}}{\delta}\right) < 1 + \left(\frac{y_{ij}}{\delta}\right).$$

Since M_1 is non-decreasing and convex, it follows that

$$M_1(y_{ij}) < M_1\left(1 + \left(\frac{y_{ij}}{\delta}\right)\right) < \frac{1}{2}M_1(2) + \frac{1}{2}M_1\left(\frac{2y_{ij}}{\delta}\right)$$

Since M_1 satisfies the Δ_2 -condition, we have

$$M_1(y_{ij}) < \frac{1}{2}K\left(\frac{y_{ij}}{\delta}\right)M_1(2) + \frac{1}{2}K\left(\frac{y_{ij}}{\delta}\right)M_1(2) = K\left(\frac{y_{ij}}{\delta}\right)M_1(2).$$

Hence

$$\lim_{y_{ij} > \delta} M_1(y_{ij}) \leq \max(1, K\delta^{-1}M_1(2)) \lim_{y_{ij} > \delta} (y_{ij}). \tag{5}$$

From (3), (4) and (5), we have $(x_{ij}) \in \mathcal{Z}_0^I(M_1.M_2)$. Thus

$$\mathcal{Z}_0^I(M_2) \subseteq \mathcal{Z}_0^I(M_1.M_2).$$

The other cases can be proved similarly.

(b) Let $(x_k) \in \mathcal{Z}_0^I(M_1) \cap \mathcal{Z}_0^I(M_2)$. Then there exists $\rho > 0$ such that

$$I - \lim_k M_1\left(\frac{|x'_k|}{\rho}\right) = 0 \text{ and } I - \lim_k M_2\left(\frac{|x'_k|}{\rho}\right) = 0$$

The rest of the proof follows from the following equality

$$\lim_{k \in \mathbb{N}} (M_1 + M_2)\left(\frac{|x'_k|}{\rho}\right) = \lim_{k \in \mathbb{N}} M_1\left(\frac{|x'_k|}{\rho}\right) + \lim_{k \in \mathbb{N}} M_2\left(\frac{|x'_k|}{\rho}\right)$$

□

Theorem 2.4. *The spaces ${}_2\mathcal{Z}_0^I(M)$ and ${}_2m_{\mathcal{Z}_0}^I(M)$ are solid and monotone.*

Proof. We shall prove the result for ${}_2\mathcal{Z}_0^I(M)$. For $m_{\mathcal{Z}_0}^I(M)$ the result can be proved similarly. Let $(x_{ij}) \in {}_2\mathcal{Z}_0^I(M)$. Then there exists $\rho > 0$ such that

$$I - \lim_{i,j} M\left(\frac{|x'_{ij}|}{\rho}\right) = 0 \tag{6}$$

Let (α_{ij}) be a sequence of scalars with $|\alpha_{ij}| \leq 1$ for all $(i, j) \in \mathbb{N} \times \mathbb{N}$. Then the result follows from (6) and the following inequality for all

$$M\left(\frac{|\alpha_{ij}x'_{ij}|}{\rho}\right) \leq |\alpha_{ij}|M\left(\frac{|x'_{ij}|}{\rho}\right) \leq M\left(\frac{|x'_{ij}|}{\rho}\right).$$

By Lemma 1.12, a sequence space E is solid implies that E is monotone. We have the space ${}_2\mathcal{Z}_0^I(M)$ is monotone. □

Theorem 2.5. *The spaces ${}_2\mathcal{Z}^I(M)$ and ${}_2m_{\mathcal{Z}}^I(M)$ are neither solid nor monotone in general.*

Proof. Here we give a counter example. Let $I = I_\delta$ and $M(x) = x^2$ for all $x \in [0, \infty)$. Consider the K-step space $X_K(M)$ of $X(M)$ defined as follows, let $(x_{ij}) \in X(M)$ and let $(y_{ij}) \in X_K(M)$ be such that

$$y_{ij} = \begin{cases} x_{ij}, & \text{if } (i+j) \text{ is even,} \\ 0, & \text{otherwise.} \end{cases}$$

Consider the sequence (x_{ij}) defined by $x_{ij} = 1$ for all $(i, j) \in \mathbb{N} \times \mathbb{N}$. Then $(x_{ij}) \in {}_2\mathcal{Z}^I(M)$ but its K-stepspace preimage does not belong to ${}_2\mathcal{Z}^I(M)$. Thus ${}_2\mathcal{Z}^I(M)$ is not monotone. Hence ${}_2\mathcal{Z}^I(M)$ is not solid. □

Theorem 2.6. *The spaces ${}_2\mathcal{Z}_0^I(M)$ and ${}_2\mathcal{Z}^I(M)$ are not convergence free in general.*

Proof. Here we give a counter example. Let $I = I_f$ and $M(x) = x^3$ for all $x \in [0, \infty)$. Consider the sequence (x_{ij}) and (y_{ij}) defined by

$$x_{ij} = \frac{1}{i+j} \quad \text{and} \quad y_{ij} = i+j$$

Then $(x_{ij}) \in {}_2\mathcal{Z}^I(M)$ and ${}_2\mathcal{Z}_0^I(M)$, but $(y_{ij}) \notin {}_2\mathcal{Z}^I(M)$ and ${}_2\mathcal{Z}_0^I(M)$. Hence the spaces ${}_2\mathcal{Z}^I(M)$ and ${}_2\mathcal{Z}_0^I(M)$ are not convergence free. □

Theorem 2.7. *The spaces ${}_2\mathcal{Z}_0^I(M)$ and ${}_2\mathcal{Z}^I(M)$ are sequence algebras.*

Proof. We prove that ${}_2\mathcal{Z}_0^I(M)$ is a sequence algebra. For the space ${}_2\mathcal{Z}^I(M)$, the result can be proved similarly. Let $(x_{ij}), (y_{ij}) \in {}_2\mathcal{Z}_0^I(M)$. Then

$$I - \lim_{i,j} M\left(\frac{|x'_{ij}|}{\rho_1}\right) = 0 \quad \text{and} \quad I - \lim_{i,j} M\left(\frac{|y'_{ij}|}{\rho_2}\right) = 0$$

Let $\rho = \rho_1 \cdot \rho_2 > 0$. Then we can show that

$$I - \lim_{i,j} M\left(\frac{|(x'_{ij} \cdot y'_{ij})|}{\rho}\right) = 0.$$

Thus $(x_{ij} \cdot y_{ij}) \in {}_2\mathcal{Z}_0^I(M)$. Hence ${}_2\mathcal{Z}_0^I(M)$ is a sequence algebra. \square

Theorem 2.8. *If I is not maximal and $I \neq I_f$, then the spaces ${}_2\mathcal{Z}^I(M)$ and ${}_2\mathcal{Z}_0^I(M)$ are not symmetric.*

Proof. Let $A \in I$ be infinite and $M(x) = x$ for all $x = (x_{ij})$. If

$$x_{ij} = \begin{cases} 1, & \text{for } i, j \in A, \\ 0, & \text{otherwise.} \end{cases}$$

Then $(x_{ij}) \in {}_2\mathcal{Z}_0^I(M) \subset {}_2\mathcal{Z}^I(M)$, by lemma 1.14. Let $K \subset \mathbb{N}$ be such that $K \notin I$ and $\mathbb{N} - K \notin I$. Let $\phi : K \rightarrow A$ and $\psi : \mathbb{N} - K \rightarrow \mathbb{N} - A$ be bijections, then the map $\pi : \mathbb{N} \rightarrow \mathbb{N}$ defined by

$$\pi(k) = \begin{cases} \phi(k), & \text{for } k \in K, \\ \psi(k), & \text{otherwise,} \end{cases} \quad \text{and } \pi_k = \begin{cases} \phi_k, & \text{for } k \in K, \\ \psi_k, & \text{for } k \in \mathbb{N} - K. \end{cases}$$

is a permutation on \mathbb{N} , but $(x_{\pi(i)\pi(j)}) \notin {}_2\mathcal{Z}^I(M)$ and $(x_{\pi(i)\pi(j)}) \notin {}_2\mathcal{Z}_0^I(M)$. Hence ${}_2\mathcal{Z}_0^I(M)$ and ${}_2\mathcal{Z}^I(M)$ are not symmetric. \square

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