# MERIDIAN SURFACES IN $\mathbb{E}^{4}$ WITH POINTWISE 1-TYPE GAUSS MAP 

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#### Abstract

In the present article we study a special class of surfaces in the four-dimensional Euclidean space, which are one-parameter systems of meridians of the standard rotational hypersurface. They are called meridian surfaces. We show that a meridian surface has a harmonic Gauss map if and only if it is part of a plane. Further, we give necessary and sufficient conditions for a meridian surface to have pointwise 1-type Gauss map and find all meridian surfaces with pointwise 1-type Gauss map.


## 1. Introduction

The study of submanifolds of Euclidean space or pseudo-Euclidean space via the notion of finite type immersions began in the late 1970's with the papers $[6,7]$ of B.-Y. Chen and has been extensively carried out since then. An isometric immersion $x: M \rightarrow \mathbb{E}^{m}$ of a submanifold $M$ in Euclidean $m$-space $\mathbb{E}^{m}$ is said to be of finite type [6] if $x$ identified with the position vector field of $M$ in $\mathbb{E}^{m}$ can be expressed as a finite sum of eigenvectors of the Laplacian $\Delta$ of $M$, i.e.,

$$
x=x_{0}+\sum_{i=1}^{k} x_{i}
$$

where $x_{0}$ is a constant map, $x_{1}, x_{2}, \ldots, x_{k}$ are non-constant maps such that $\Delta x_{i}=\lambda_{i} x_{i}, \lambda_{i} \in \mathbb{R}, 1 \leq i \leq k$. If $\lambda_{1}, \lambda_{2}, \ldots, \lambda_{k}$ are different, then $M$ is said to be of $k$-type. Many results on finite type immersions have been collected in the survey paper [8]. Similarly, a smooth map $\phi$ of an $n$-dimensional Riemannian manifold $M$ of $\mathbb{E}^{m}$ is said to be of finite type if $\phi$ is a finite sum of $\mathbb{E}^{m}$-valued eigenfunctions of $\Delta$. The notion of finite type immersion is naturally extended to the Gauss map $G$ on $M$ in Euclidean space [10]. Thus, a submanifold $M$ of Euclidean space has 1-type Gauss map $G$, if $G$ satisfies $\Delta G=\mu(G+C)$ for some $\mu \in \mathbb{R}$ and some constant vector $C$ (of [2], [3], [4], [13]). However, the Laplacian

Received June 10, 2013.
2010 Mathematics Subject Classification. 53A07, 53C40, 53C42.
Key words and phrases. Meridian surfaces, Gauss map, finite type immersions, pointwise 1-type Gauss map.
of the Gauss map of some typical well-known surfaces such as the helicoid, the catenoid and the right cone in the Euclidean 3 -space $\mathbb{E}^{3}$ takes a somewhat different form, namely, $\Delta G=\lambda(G+C)$ for some non-constant function $\lambda$ and some constant vector $C$. Therefore, it is worth studying the class of surfaces satisfying such an equation. A submanifold $M$ of the Euclidean space $\mathbb{E}^{m}$ is said to have pointwise 1-type Gauss map if its Gauss map $G$ satisfies

$$
\begin{equation*}
\Delta G=\lambda(G+C) \tag{1}
\end{equation*}
$$

for some non-zero smooth function $\lambda$ on $M$ and some constant vector $C$ [11]. A pointwise 1-type Gauss map is called proper if the function $\lambda$ defined by (1) is non-constant. A submanifold with pointwise 1-type Gauss map is said to be of the first kind if the vector $C$ in (1) is zero. Otherwise, the pointwise 1-type Gauss map is said to be of the second kind ([9], [11], [14], [15]). In [11] M. Choi and Y. Kim characterized the minimal helicoid in terms of pointwise 1-type Gauss map of the first kind. Also, together with B. Y. Chen, they proved that surfaces of revolution with pointwise 1-type Gauss map of the first kind coincide with surfaces of revolution with constant mean curvature [9]. Moreover, they characterized the rational surfaces of revolution with pointwise 1-type Gauss map. In [17] D. Yoon studied Vranceanu rotation surfaces in Euclidean 4-space $\mathbb{E}^{4}$. He obtained classification theorems for the flat Vranceanu rotation surfaces with 1-type Gauss map and an equation in terms of the mean curvature vector [16]. For the general case see [1].

The study of meridian surfaces in the Euclidean 4 -space $\mathbb{E}^{4}$ was first introduced by G. Ganchev and the third author in [12]. The meridian surfaces are one-parameter systems of meridians of the standard rotational hypersurface in $\mathbb{E}^{4}$. In this paper we investigate the meridian surfaces with pointwise 1-type Gauss map. We give necessary and sufficient conditions for a meridian surface to have pointwise 1-type Gauss map and find all meridian surfaces with pointwise 1 -type Gauss map of first and second kind.

## 2. Preliminaries

In the present section we recall definitions and results of [5]. Let $x: M \rightarrow$ $\mathbb{E}^{m}$ be an immersion from an $n$-dimensional connected Riemannian manifold $M$ into an $m$-dimensional Euclidean space $\mathbb{E}^{m}$. We denote by $\langle$,$\rangle the metric$ tensor of $\mathbb{E}^{m}$ as well as the induced metric on M . Let $\nabla^{\prime}$ be the Levi-Civita connection of $\mathbb{E}^{m}$ and $\nabla$ the induced connection on $M$. Then the Gauss and Weingarten formulas are given, respectively, by

$$
\begin{aligned}
\nabla_{X}^{\prime} Y & =\nabla_{X} Y+h(X, Y) \\
\nabla_{X}^{\prime} \xi & =-A_{\xi} X+D_{X} \xi
\end{aligned}
$$

where $X, Y$ are vector fields tangent to $M$ and $\xi$ is a vector field normal to $M$. Moreover, $h$ is the second fundamental form, $D$ is the linear connection induced in the normal bundle $T^{\perp} M$, called normal connection, and $A_{\xi}$ is the
shape operator in the direction of $\xi$ that is related with $h$ by

$$
\langle h(X, Y), \xi\rangle=\left\langle A_{\xi} X, Y\right\rangle
$$

The covariant differentiation $\bar{\nabla} h$ of the second fundamental form $h$ on the direct sum of the tangent bundle and the normal bundle $T M \oplus T^{\perp} M$ of $M$ is defined by

$$
\left(\bar{\nabla}_{X} h\right)(Y, Z)=D_{X} h(Y, Z)-h\left(\nabla_{X} Y, Z\right)-h\left(Y, \nabla_{X} Z\right)
$$

for any vector fields $X, Y$ and $Z$ tangent to $M$. The Codazzi equation is given by

$$
\left(\bar{\nabla}_{X} h\right)(Y, Z)=\left(\bar{\nabla}_{Y} h\right)(X, Z)
$$

We denote by $R$ the curvature tensor associated with $\nabla$, i.e.,

$$
R(X, Y) Z=\nabla_{X} \nabla_{Y} Z-\nabla_{Y} \nabla_{X} Z-\nabla_{[X, Y]} Z
$$

The equations of Gauss and Ricci are given, respectively, by

$$
\begin{aligned}
& \langle R(X, Y) Z, W\rangle=\langle h(X, W), h(Y, Z)\rangle-\langle h(X, Z), h(Y, W)\rangle \\
& \left\langle R^{\perp}(X, Y) \xi, \eta\right\rangle=\left\langle\left[A_{\xi}, A \eta\right] X, Y\right\rangle
\end{aligned}
$$

for vector fields $X, Y, Z, W$ tangent to $M$ and $\xi, \eta$ normal to $M$.
The mean curvature vector field $H$ of an $n$-dimensional submanifold $M$ in $\mathbb{E}^{m}$ is given by

$$
H=\frac{1}{n} \text { trace } h
$$

A submanifold $M$ is said to be minimal (respectively, totally geodesic) if $H \equiv 0$ (respectively, $h \equiv 0$ ).

We shall recall the definition of Gauss map $G$ of a submanifold $M$. Let $G(n, m)$ denotes the Grassmannian manifold consisting of all oriented $n$-planes through the origin of $\mathbb{E}^{m}$ and $\wedge^{n} \mathbb{E}^{m}$ be the vector space obtained by the exterior product of $n$ vectors in $\mathbb{E}^{m}$. In a natural way, we can identify $\wedge^{n} \mathbb{E}^{m}$ with some Euclidean space $\mathbb{E}^{N}$ where $N=\binom{m}{n}$. Let $\left\{e_{1}, \ldots, e_{n}, e_{n+1}, \ldots, e_{m}\right\}$ be an adapted local orthonormal frame field in $\mathbb{E}^{m}$ such that $e_{1}, e_{2}, \ldots, e_{n}$, are tangent to $M$ and $e_{n+1}, e_{n+2}, \ldots, e_{m}$ are normal to $M$. The map $G: M \rightarrow$ $G(n, m)$ defined by $G(p)=\left(e_{1} \wedge e_{2} \wedge \cdots \wedge e_{n}\right)(p)$ is called the Gauss map of $M$. It is a smooth map which carries a point $p$ in $M$ into the oriented $n$-plane in $\mathbb{E}^{m}$ obtained by the parallel translation of the tangent space of $M$ at $p$ in $\mathbb{E}^{m}$.

For any real function $\phi$ on $M$ the Laplacian of $\phi$ is defined by

$$
\begin{equation*}
\Delta \phi=-\sum_{i}\left(\nabla_{e_{i}}^{\prime} \nabla_{e_{i}}^{\prime} \phi-\nabla_{\nabla_{e_{i}} e_{i}}^{\prime} \phi\right) \tag{2}
\end{equation*}
$$

## 3. Classification of meridian surfaces with pointwise 1-type Gauss map

Let $\left\{e_{1}, e_{2}, e_{3}, e_{4}\right\}$ be the standard orthonormal frame in $\mathbb{E}^{4}$, and $S^{2}(1)$ be the 2-dimensional sphere in $\mathbb{E}^{3}=\operatorname{span}\left\{e_{1}, e_{2}, e_{3}\right\}$, centered at the origin $O$. We consider a smooth curve $c: r=r(v), v \in J, J \subset \mathbb{R}$ on $S^{2}(1)$, parameterized by the arc-length $\left(r^{\prime 2}(v)=1\right)$. Let $t(v)=r^{\prime}(v)$ be the tangent vector field of $c$. We consider the moving frame field $\{t(v), n(v), r(v)\}$ of the curve $c$ on $S^{2}(1)$. With respect to this orthonormal frame field the following Frenet formulas hold:

$$
\begin{align*}
r^{\prime} & =t ; \\
t^{\prime} & =\kappa n-r ;  \tag{3}\\
n^{\prime} & =-\kappa t,
\end{align*}
$$

where $\kappa(v)=\left\langle t^{\prime}(v), n(v)\right\rangle$ is the spherical curvature of $c$.
Let $f=f(u), g=g(u)$ be non-zero smooth functions, defined in an interval $I \subset \mathbb{R}$, such that $\left(f^{\prime}(u)\right)^{2}+\left(g^{\prime}(u)\right)^{2}=1, u \in I$. We consider the surface $M^{2}$ in $\mathbb{E}^{4}$ constructed in the following way:

$$
\begin{equation*}
M^{2}: z(u, v)=f(u) r(v)+g(u) e_{4}, \quad u \in I, v \in J \tag{4}
\end{equation*}
$$

(see [12]).
The surface $M^{2}$ lies on the rotational hypersurface $M^{3}$ in $\mathbb{E}^{4}$ obtained by the rotation of the meridian curve $\alpha: u \rightarrow(f(u), g(u))$ about the $O e_{4}$-axis in $\mathbb{E}^{4} . M^{2}$ is called a meridian surface on $M^{3}$ since it is a one-parameter system of meridians of $M^{3}$.

The tangent space of $M^{2}$ is spanned by the vector fields:

$$
\begin{align*}
& z_{u}=f^{\prime} r+g^{\prime} e_{4} ;  \tag{5}\\
& z_{v}=f t,
\end{align*}
$$

and hence, the coefficients of the first fundamental form of $M^{2}$ are $E=1 ; F=$ $0 ; G=f^{2}(u)$. Taking into account (3) and (5), we calculate the second partial derivatives of $z(u, v)$ :

$$
\begin{aligned}
& z_{u u}=f^{\prime \prime} r+g^{\prime \prime} e_{4} ; \\
& z_{u v}=f^{\prime} t ; \\
& z_{v v}=f \kappa n-f r .
\end{aligned}
$$

Let us denote $x=z_{u}, y=\frac{z_{v}}{f}=t$ and consider the following orthonormal normal frame field of $M^{2}$ :

$$
n_{1}=n(v) ; \quad n_{2}=-g^{\prime}(u) r(v)+f^{\prime}(u) e_{4} .
$$

Thus we obtain a positive orthonormal frame field $\left\{x, y, n_{1}, n_{2}\right\}$ of $M^{2}$. We denote by $\kappa_{\alpha}$ the curvature of the meridian curve $\alpha$, i.e.,

$$
\kappa_{\alpha}(u)=f^{\prime}(u) g^{\prime \prime}(u)-g^{\prime}(u) f^{\prime \prime}(u) .
$$

By covariant differentiation with respect to $x$ and $y$, and a straightforward calculation we obtain

$$
\begin{align*}
\nabla_{x}^{\prime} x & =\kappa_{\alpha} n_{2} \\
\nabla_{x}^{\prime} y & =0 \\
\nabla_{y}^{\prime} x & =\frac{f^{\prime}}{f} y  \tag{6}\\
\nabla_{y}^{\prime} y & =-\frac{f^{\prime}}{f} x+\frac{\kappa}{f} n_{1}+\frac{g^{\prime}}{f} n_{2} ;
\end{align*}
$$

and

$$
\begin{align*}
\nabla_{x}^{\prime} n_{1} & =0 ; \\
\nabla_{y}^{\prime} n_{1} & =-\frac{\kappa}{f} y ; \\
\nabla_{x}^{\prime} n_{2} & =-\kappa_{\alpha} x ;  \tag{7}\\
\nabla_{y}^{\prime} n_{2} & =-\frac{g^{\prime}}{f} y,
\end{align*}
$$

where $\kappa(v)$ and $\kappa_{\alpha}(u)$ are the curvatures of the spherical $c$ and the meridian curve $\alpha$, respectively (see [12]).

Equalities (7) imply the following result.
Lemma 3.1. Let $M^{2}$ be a meridian surface given with the surface patch (4). Then

$$
A_{n_{1}}=\left[\begin{array}{cc}
0 & 0 \\
0 & \frac{\kappa}{f}
\end{array}\right], \quad A_{n_{2}}=\left[\begin{array}{ll}
\kappa_{\alpha} & 0 \\
0 & \frac{g^{\prime}}{f}
\end{array}\right] .
$$

So, the Gauss curvature is given by

$$
K=\frac{\kappa_{\alpha} g^{\prime}}{f}
$$

and the mean curvature vector field $H$ of $M^{2}$ is

$$
H=\frac{\kappa}{2 f} n_{1}+\frac{\kappa_{\alpha} f+g^{\prime}}{2 f} n_{2}
$$

The Gauss map $G$ of $M^{2}$ is defined by $G=x \wedge y$. Using (2), (6), and (7) we calculate that the Laplacian of the Gauss map is expressed as

$$
\begin{align*}
\Delta G= & \frac{\left(f \kappa_{\alpha}\right)^{2}+\kappa^{2}+g^{\prime 2}}{f^{2}} x \wedge y-\frac{\kappa^{\prime}}{f^{2}} x \wedge n_{1}  \tag{8}\\
& -\frac{\kappa f^{\prime}}{f^{2}} y \wedge n_{1}-\frac{f^{\prime} g^{\prime}-f\left(f \kappa_{\alpha}\right)^{\prime}}{f^{2}} y \wedge n_{2}
\end{align*}
$$

where $\kappa^{\prime}=\frac{d}{d v}(\kappa)$.

First, we suppose that the Gauss map of $M^{2}$ is harmonic, i.e., $\Delta G=0$. Then from (8) we get

$$
\begin{align*}
\kappa_{\alpha} & =0 \\
\kappa & =0  \tag{9}\\
g^{\prime} & =0
\end{align*}
$$

So, (6) and (9) imply that $M^{2}$ is a totally geodesic surface in $\mathbb{E}^{4}$. Conversely, if $M^{2}$ is totally geodesic, then $\Delta G=0$.

Thus we obtain the following result.
Theorem 3.2. Let $M^{2}$ be a meridian surfaces in the Euclidean space $\mathbb{E}^{4}$. The Gauss map of $M^{2}$ is harmonic if and only if $M^{2}$ is part of a plane.

Now, we suppose that the meridian surface $M^{2}$ is of pointwise 1-type Gauss map, i.e., $G$ satisfies (1), where $\lambda \neq 0$. Then, from equalities (1) and (8) we get

$$
\begin{align*}
\lambda+\lambda\langle C, x \wedge y\rangle & =\frac{\left(f \kappa_{\alpha}\right)^{2}+\kappa^{2}+g^{\prime 2}}{f^{2}} \\
\lambda\left\langle C, x \wedge n_{1}\right\rangle & =-\frac{\kappa^{\prime}}{f^{2}}  \tag{10}\\
\lambda\left\langle C, y \wedge n_{1}\right\rangle & =-\frac{\kappa f^{\prime}}{f^{2}} \\
\lambda\left\langle C, y \wedge n_{2}\right\rangle & =-\frac{f^{\prime} g^{\prime}-f\left(f \kappa_{\alpha}\right)^{\prime}}{f^{2}}
\end{align*}
$$

Using (8) we obtain

$$
\begin{align*}
\lambda\left\langle C, x \wedge n_{2}\right\rangle & =0 \\
\lambda\left\langle C, n_{1} \wedge n_{2}\right\rangle & =0 \tag{11}
\end{align*}
$$

Differentiating (11) with respect to $u$ and $v$ we get

$$
\begin{align*}
\kappa_{\alpha}\left\langle C, x \wedge n_{1}\right\rangle & =0 \\
\frac{f^{\prime}}{f}\left\langle C, y \wedge n_{2}\right\rangle-\frac{g^{\prime}}{f}\langle C, x \wedge y\rangle & =0  \tag{12}\\
-\frac{\kappa}{f}\left\langle C, y \wedge n_{2}\right\rangle+\frac{g^{\prime}}{f}\left\langle C, y \wedge n_{1}\right\rangle & =0 .
\end{align*}
$$

Since $\lambda \neq 0$ equalities (10) and (12) imply

$$
\begin{align*}
\kappa_{\alpha} \kappa^{\prime} & =0 ; \\
\kappa\left(f \kappa_{\alpha}\right)^{\prime} & =0 ;  \tag{13}\\
\lambda f^{2} g^{\prime} & =g^{\prime}\left(1+\left(f \kappa_{\alpha}\right)^{2}+\kappa^{2}\right)-f f^{\prime}\left(f \kappa_{\alpha}\right)^{\prime} .
\end{align*}
$$

We distinguish the following cases.

Case I: $g^{\prime}=0$. In such case $\kappa_{\alpha}=0$. Then equality (8) implies that

$$
\begin{equation*}
\Delta G=\frac{\kappa^{2}}{f^{2}} x \wedge y-\frac{\kappa^{\prime}}{f^{2}} x \wedge n_{1}-\frac{\kappa f^{\prime}}{f^{2}} y \wedge n_{1} \tag{14}
\end{equation*}
$$

If we assume that $M^{2}$ has pointwise 1-type Gauss map of the first kind, i.e., $C=0$, then from (14) we get $\kappa^{\prime}=0$ and $\kappa f^{\prime}=0$, which imply $\kappa=0$ since $f^{\prime} \neq 0$. Hence $\Delta G=0$, which contradicts the assumption that $\lambda \neq 0$. Consequently, in the case $g^{\prime}=0$ there are no meridian surfaces of pointwise 1-type Gauss map of the first kind.

Now we consider meridian surfaces of pointwise 1-type Gauss map of the second kind, i.e., $C \neq 0$. So we suppose that $\kappa \neq 0$. From equalities (1) and (14) we obtain

$$
\begin{equation*}
C=\left(\frac{\kappa^{2}}{\lambda f^{2}}-1\right) x \wedge y-\frac{\kappa^{\prime}}{\lambda f^{2}} x \wedge n_{1}-\frac{\kappa f^{\prime}}{\lambda f^{2}} y \wedge n_{1} \tag{15}
\end{equation*}
$$

Using (6), (7) and (15) we obtain

$$
\begin{aligned}
\nabla_{x}^{\prime} C= & \kappa^{2}\left(\frac{1}{\lambda f^{2}}\right)_{u}^{\prime} x \wedge y-\kappa^{\prime}\left(\frac{1}{\lambda f^{2}}\right)_{u}^{\prime} x \wedge n_{1}-\kappa f^{\prime}\left(\frac{1}{\lambda f^{2}}\right)_{u}^{\prime} y \wedge n_{1} \\
\nabla_{y}^{\prime} C= & \frac{\kappa}{\lambda^{2} f^{3}}\left(3 \kappa^{\prime} \lambda-\kappa \lambda_{v}^{\prime}\right) x \wedge y \\
& +\frac{1}{\lambda^{2} f^{3}}\left(-\kappa^{\prime \prime} \lambda+k^{\prime} \lambda_{v}^{\prime}+\kappa^{3} \lambda+\kappa \lambda-\kappa \lambda^{2} f^{2}\right) x \wedge n_{1} \\
& +\frac{f^{\prime}}{\lambda^{2} f^{3}}\left(-2 \kappa^{\prime} \lambda+\kappa \lambda_{v}^{\prime}\right) y \wedge n_{1}
\end{aligned}
$$

The last formulas imply that $C=$ const if and only if $\kappa=$ const and $\lambda=$ $\frac{\kappa^{2}+1}{f^{2}}$.

The condition $\kappa=$ const $\neq 0$ implies that the curve $c$ on $S^{2}(1)$ is a circle with non-zero constant spherical curvature. Since $g^{\prime}=0$ and $\left(f^{\prime 2}+g^{\prime 2}\right)=1$ we get $f(u)= \pm u+a, g(u)=b$, where $a=$ const, $b=$ const. In this case $M^{2}$ is a developable ruled surface. Moreover, from (7) it follows that $\nabla_{x}^{\prime} n_{2}=$ $0 ; \nabla_{y}^{\prime} n_{2}=0$, which implies that $M^{2}$ lies in the 3 -dimensional space spanned by $\left\{x, y, n_{1}\right\}$.

Conversely, if $g^{\prime}=0$ and $\kappa=$ const, by direct computation we get

$$
\Delta G=\frac{\kappa^{2}+1}{f^{2}}(G+C)
$$

where $C=-\frac{1}{\kappa^{2}+1} x \wedge y-\frac{\kappa f^{\prime}}{\kappa^{2}+1} y \wedge n_{1}$. Hence, $M^{2}$ is a surface with pointwise 1-type Gauss map of the second kind.

Summing up we obtain the following result.
Theorem 3.3. Let $M^{2}$ be a meridian surface given with parametrization (4) and $g^{\prime}=0$. Then $M^{2}$ has pointwise 1-type Gauss map of the second kind if and only if the curve $c$ is a circle with non-zero constant spherical curvature
and the meridian curve $\alpha$ is determined by $f(u)= \pm u+a ; g(u)=b$, where $a=$ const, $b=$ const. In this case $M^{2}$ is a developable ruled surface lying in 3-dimensional space.

Case II: $g^{\prime} \neq 0$. In such case from the third equality of (13) we obtain

$$
\begin{equation*}
\lambda=\frac{g^{\prime}\left(1+\left(f \kappa_{\alpha}\right)^{2}+\kappa^{2}\right)-f f^{\prime}\left(f \kappa_{\alpha}\right)^{\prime}}{f^{2} g^{\prime}} \tag{16}
\end{equation*}
$$

First we shall consider the case of pointwise 1-type Gauss map surfaces of the first kind. From (8) it follows that $M^{2}$ is of the first kind $(C=0)$ if and only if

$$
\begin{align*}
& \kappa^{\prime}=0 \\
& \kappa f^{\prime}=0  \tag{17}\\
& f^{\prime} g^{\prime}-f\left(f \kappa_{\alpha}\right)^{\prime}=0
\end{align*}
$$

The first equality of (17) implies that $\kappa=$ const. There are two subcases:

1. $\kappa=0$. Then the meridian curve $\alpha$ is determined by the equation

$$
\begin{equation*}
f^{\prime} g^{\prime}-f\left(f \kappa_{\alpha}\right)^{\prime}=0 \tag{18}
\end{equation*}
$$

The equalities $\kappa_{\alpha}=f^{\prime} g^{\prime \prime}-g^{\prime} f^{\prime \prime}$ and $f^{\prime 2}+g^{\prime 2}=1$ imply that $\kappa_{\alpha}=-\frac{f^{\prime \prime}}{g^{\prime}}$. Hence equation (18) can be rewritten in the form

$$
\begin{equation*}
f^{\prime} \sqrt{1-f^{\prime 2}}+f\left(\frac{f f^{\prime \prime}}{\sqrt{1-f^{\prime 2}}}\right)^{\prime}=0 \tag{19}
\end{equation*}
$$

Since $\kappa=0, M^{2}$ lies in the 3 -dimensional space spanned by $\left\{x, y, n_{2}\right\}$.
Conversely, if $\kappa=0$ and the meridian curve $\alpha$ is determined by a solution $f(u)$ of differential equation (19), the function $g(u)$ is defined by $g^{\prime}=\sqrt{1-f^{\prime 2}}$, then the surface $M^{2}$, parameterized by (4), is a surface of pointwise 1-type Gauss map of the first kind.
2. $\kappa \neq 0$. Then the second equality of (17) implies that $f^{\prime}=0$. In this case $f(u)=a ; g(u)= \pm u+b$, where $a=$ const, $b=$ const. By a result of [12], $M^{2}$ is a developable ruled surface in a 3 -dimensional space, since $\kappa_{\alpha}=0$ and $\kappa=$ const. It follows from (16) that $\lambda=\frac{1+\kappa^{2}}{a^{2}}=$ const, which implies that $M^{2}$ has 1-type Gauss map, i.e., $M^{2}$ is non-proper. The converse is also true.

Thus we obtain the following result.
Theorem 3.4. Let $M^{2}$ be a meridian surface given with parametrization (4) and $g^{\prime} \neq 0$. Then $M^{2}$ has pointwise 1-type Gauss map of the first kind if and only if one of the following holds:
(i) the curve $c$ is a great circle on $S^{2}(1)$ and the meridian curve $\alpha$ is determined by the solutions of the following differential equation

$$
f^{\prime} \sqrt{1-f^{\prime 2}}+f\left(\frac{f f^{\prime \prime}}{\sqrt{1-f^{\prime 2}}}\right)^{\prime}=0
$$

(ii) the curve c is a circle on $S^{2}(1)$ with non-zero constant spherical curvature and the meridian curve $\alpha$ is determined by $f(u)=a ; g(u)= \pm u+b$, where $a=$ const, $b=$ const. In this case $M^{2}$ is a developable ruled surface in a 3 -dimensional space. Moreover, $M^{2}$ is non-proper.

Now we shall consider the case of pointwise 1-type Gauss map surfaces of the second kind. It follows from equalities (13) that there are three subcases.

1. $\kappa_{\alpha}=0$. In this subcase

$$
\begin{equation*}
\Delta G=\frac{\kappa^{2}+g^{\prime 2}}{f^{2}} x \wedge y-\frac{\kappa^{\prime}}{f^{2}} x \wedge n_{1}-\frac{\kappa f^{\prime}}{f^{2}} y \wedge n_{1}-\frac{f^{\prime} g^{\prime}}{f^{2}} y \wedge n_{2} \tag{20}
\end{equation*}
$$

From equalities (1) and (20) we obtain

$$
C=\left(\frac{\kappa^{2}+g^{\prime 2}}{\lambda f^{2}}-1\right) x \wedge y-\frac{\kappa^{\prime}}{\lambda f^{2}} x \wedge n_{1}-\frac{\kappa f^{\prime}}{\lambda f^{2}} y \wedge n_{1}-\frac{f^{\prime} g^{\prime}}{\lambda f^{2}} y \wedge n_{2}
$$

The third equality in (13) implies that in this case $\lambda=\frac{1+\kappa^{2}}{f^{2}}$ and hence, $C$ is expressed as follows:

$$
\begin{equation*}
C=-\frac{1}{1+\kappa^{2}}\left(f^{\prime 2} x \wedge y+\kappa^{\prime} x \wedge n_{1}+\kappa f^{\prime} y \wedge n_{1}+f^{\prime} g^{\prime} y \wedge n_{2}\right) \tag{21}
\end{equation*}
$$

Using (6), (7) and (21) we obtain

$$
\begin{aligned}
\nabla_{x}^{\prime} C= & -\frac{1}{1+\kappa^{2}}\left(2 f^{\prime} f^{\prime \prime} x \wedge y+\kappa f^{\prime \prime} y \wedge n_{1}+\left(f^{\prime} g^{\prime \prime}+f^{\prime \prime} g^{\prime}\right) y \wedge n_{2}\right) \\
\nabla_{y}^{\prime} C= & \frac{1}{f\left(1+\kappa^{2}\right)^{2}}\left(\left(2 \kappa \kappa^{\prime} f^{\prime 2}+\kappa \kappa^{\prime}\left(1+\kappa^{2}\right)\right) x \wedge y\right. \\
& \left.+\left(2 \kappa \kappa^{\prime 2}-\left(1+\kappa^{2}\right) \kappa^{\prime \prime}\right) x \wedge n_{1}\right) \\
& +\frac{1}{f\left(1+\kappa^{2}\right)^{2}}\left(-2 \kappa^{\prime} f^{\prime} y \wedge n_{1}+2 \kappa \kappa^{\prime} f^{\prime} g^{\prime} y \wedge n_{2}\right)
\end{aligned}
$$

The last formulas imply that $C=$ const if and only if $\kappa=$ const, $f^{\prime}=a=$ const, $g^{\prime}=b=$ const, $a^{2}+b^{2}=1$.

The condition $\kappa=$ const implies that the curve $c$ is a circle on $S^{2}(1)$. The meridian curve $\alpha$ is given by $f(u)=a u+a_{1} ; g(u)=b u+b_{1}$, where $a_{1}=$ const, $b_{1}=$ const. In this case $M^{2}$ is a developable ruled surface lying in a 3 -dimensional space.

Conversely, if $f(u)=a u+a_{1} ; g(u)=b u+b_{1}$ and $\kappa=$ const, then

$$
\Delta G=\frac{\kappa^{2}+b^{2}}{f^{2}} x \wedge y-\frac{\kappa a}{f^{2}} y \wedge n_{1}-\frac{a b}{f^{2}} y \wedge n_{2}
$$

Hence, by direct computation we get

$$
\Delta G=\frac{1+\kappa^{2}}{f^{2}}(G+C)
$$

where $C=-\frac{a}{1+\kappa^{2}}\left(a x \wedge y+\kappa y \wedge n_{1}+b y \wedge n_{2}\right)$. Consequently, $M^{2}$ is a surface of pointwise 1-type Gauss map of the second kind.
2. $\kappa=0$. In this subcase

$$
\begin{equation*}
\Delta G=\frac{\left(f \kappa_{\alpha}\right)^{2}+g^{\prime 2}}{f^{2}} x \wedge y-\frac{f^{\prime} g^{\prime}-f\left(f \kappa_{\alpha}\right)^{\prime}}{f^{2}} y \wedge n_{2} \tag{22}
\end{equation*}
$$

From equalities (1) and (22) we obtain

$$
C=\left(\frac{\left(f \kappa_{\alpha}\right)^{2}+g^{\prime 2}}{\lambda f^{2}}-1\right) x \wedge y-\frac{f^{\prime} g^{\prime}-f\left(f \kappa_{\alpha}\right)^{\prime}}{\lambda f^{2}} y \wedge n_{2}
$$

Using the third equality of (13) we obtain that $C$ is expressed as follows:

$$
\begin{equation*}
C=-\frac{f^{\prime} g^{\prime}-f\left(f \kappa_{\alpha}\right)^{\prime}}{\lambda f^{2}}\left(\frac{f^{\prime}}{g^{\prime}} x \wedge y+y \wedge n_{2}\right) \tag{23}
\end{equation*}
$$

where $\lambda=\frac{1}{f^{2}}\left(1+\left(f \kappa_{\alpha}\right)^{2}-\frac{f f^{\prime}}{g^{\prime}}\left(f \kappa_{\alpha}\right)^{\prime}\right)$. We denote

$$
\begin{equation*}
\varphi=-\frac{f^{\prime} g^{\prime}-f\left(f \kappa_{\alpha}\right)^{\prime}}{\lambda f^{2}} \tag{24}
\end{equation*}
$$

Then equalities (6), (7) and (23) imply

$$
\begin{align*}
& \nabla_{x}^{\prime} C=\left(\left(\varphi \frac{f^{\prime}}{g^{\prime}}\right)^{\prime}+\varphi \kappa_{\alpha}\right) x \wedge y+\left(\varphi^{\prime}-\varphi \frac{f^{\prime}}{g^{\prime}} \kappa_{\alpha}\right) y \wedge n_{2}  \tag{25}\\
& \nabla_{y}^{\prime} C=0
\end{align*}
$$

It follows from (25) that $C=$ const if and only if $\varphi^{\prime}=\varphi \frac{f^{\prime}}{g^{\prime}} \kappa_{\alpha}$, or equivalently

$$
\begin{equation*}
(\ln \varphi)^{\prime}=\frac{f^{\prime}}{g^{\prime}} \kappa_{\alpha} . \tag{26}
\end{equation*}
$$

Using that $f \kappa_{\alpha}=-\frac{f f^{\prime \prime}}{\sqrt{1-f^{\prime 2}}}$, from (24) we get

$$
\begin{equation*}
\varphi=\frac{-\sqrt{1-f^{\prime 2}}\left(f\left(1-f^{\prime 2}\right)\left(f f^{\prime \prime}\right)^{\prime 2} f^{\prime} f^{\prime \prime 2}+f^{\prime}\left(1-f^{\prime 2}\right)^{2}\right)}{f f^{\prime}\left(f f^{\prime \prime}\right)^{\prime}\left(1-f^{\prime 2}\right)+f^{2} f^{\prime \prime 2}+\left(1-f^{\prime 2}\right)^{2}} \tag{27}
\end{equation*}
$$

Now, formulas (26) and (27) imply that $C=$ const if and only if the function $f(u)$ is a solution of the following differential equation
(28) $\left(\ln \frac{-\sqrt{1-f^{\prime 2}}\left(f\left(1-f^{\prime 2}\right)\left(f f^{\prime \prime}\right)^{\prime 2} f^{\prime} f^{\prime \prime 2}+f^{\prime}\left(1-f^{\prime 2}\right)^{2}\right)}{f f^{\prime}\left(f f^{\prime \prime}\right)^{\prime}\left(1-f^{\prime 2}\right)+f^{2} f^{\prime \prime 2}+\left(1-f^{\prime 2}\right)^{2}}\right)^{\prime}=-\frac{f^{\prime} f^{\prime \prime}}{1-f^{\prime 2}}$.

Conversely, if $\kappa=0$ and the meridian curve $\alpha$ is determined by a solution $f(u)$ of differential equation (28), $g(u)$ is defined by $g^{\prime}=\sqrt{1-f^{\prime 2}}$, then the surface $M^{2}$, parameterized by (4), is a surface of pointwise 1-type Gauss map of the second kind.
3. $\kappa=$ const $\neq 0$ and $f \kappa_{\alpha}=a=$ const, $a \neq 0$. In this subcase

$$
\begin{equation*}
\Delta G=\frac{a^{2}+\kappa^{2}+g^{\prime 2}}{f^{2}} x \wedge y-\frac{\kappa f^{\prime}}{f^{2}} y \wedge n_{1}-\frac{f^{\prime} g^{\prime}}{f^{2}} y \wedge n_{2} \tag{29}
\end{equation*}
$$

From equalities (1), (16) and (29) we obtain

$$
\begin{equation*}
C=-\frac{1}{1+a^{2}+\kappa^{2}}\left(f^{\prime 2} x \wedge y+\kappa f^{\prime} y \wedge n_{1}+f^{\prime} g^{\prime} y \wedge n_{2}\right) \tag{30}
\end{equation*}
$$

Then equalities (6), (7) and (30) imply

$$
\begin{align*}
& \nabla_{x}^{\prime} C=-\frac{1}{1+a^{2}+\kappa^{2}}\left(f^{\prime} f^{\prime \prime} x \wedge y+\kappa f^{\prime \prime} y \wedge n_{1}+g^{\prime} f^{\prime \prime} y \wedge n_{2}\right)  \tag{31}\\
& \nabla_{y}^{\prime} C=0
\end{align*}
$$

Formulas (31) imply that $C=$ const if and only if $f^{\prime \prime}=0$. But, if $f^{\prime \prime}=0$, then $\kappa_{\alpha}=0$, which contradicts the assumption that $f \kappa_{\alpha} \neq 0$.

Consequently, if $\kappa=$ const $\neq 0$ and $f \kappa_{\alpha}=a=$ const, $a \neq 0$, then there are no meridian surfaces of pointwise 1-type Gauss map of the second kind.

Summing up we obtain the following result.
Theorem 3.5. Let $M^{2}$ be a meridian surface given with parametrization (4) and $g^{\prime} \neq 0$. Then $M^{2}$ has pointwise 1-type Gauss map of the second kind if and only if one of the following holds:
(i) the curve $c$ is a circle on $S^{2}(1)$ and the meridian curve $\alpha$ is determined by $f(u)=a u+a_{1} ; g(u)=b u+b_{1}$, where $a, a_{1}, b, b_{1}$ are constants. In this case $M^{2}$ is a developable ruled surface lying in a 3-dimensional space;
(ii) the curve $c$ is a great circle on $S^{2}(1)$ and the meridian curve $\alpha$ is determined by the solutions of the following differential equation

$$
\left(\ln \frac{-\sqrt{1-f^{\prime 2}}\left(f\left(1-f^{\prime 2}\right)\left(f f^{\prime \prime}\right)^{\prime 2} f^{\prime} f^{\prime \prime 2}+f^{\prime}\left(1-f^{\prime 2}\right)^{2}\right)}{f f^{\prime}\left(f f^{\prime \prime}\right)^{\prime}\left(1-f^{\prime 2}\right)+f^{2} f^{\prime \prime 2}+\left(1-f^{\prime 2}\right)^{2}}\right)^{\prime}=-\frac{f^{\prime} f^{\prime \prime}}{1-f^{\prime 2}}
$$

Theorem 3.3, Theorem 3.4, and Theorem 3.5 describe all meridian surfaces with pointwise 1-type Gauss map.

Acknowledgements. This paper is prepared during the third named author's visit to the Uludağ University, Bursa, Turkey in January 2011.

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