Bull. Korean Math. Soc. ${\bf 51}$ (2014), No. 2, pp. 479–499 http://dx.doi.org/10.4134/BKMS.2014.51.2.479

FIXED POINT SOLUTION METHODS FOR SOLVING EQUILIBRIUM PROBLEMS

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ABSTRACT. In this paper, we propose new iteration methods for finding a common point of the solution set of a pseudomonotone equilibrium problem and the solution set of a monotone equilibrium problem. The methods are based on both the extragradient-type method and the viscosity approximation method. We obtain weak convergence theorems for the sequences generated by these methods in a real Hilbert space.

1. Introduction

Let \mathcal{H} be a real Hilbert space with inner product $\langle \cdot, \cdot \rangle$ and norm $\|\cdot\|$. Let C be a nonempty closed convex subset of a real Hilbert space \mathcal{H} . Let $F : C \times C \to \mathcal{R}$ and $f : C \times C \to \mathcal{R}$ be two bifunctions such that F(x, x) = 0 and f(x, x) = 0for all $x \in C$. We consider the equilibrium problems in the sense of Blum and Oettli (see [9]) which are presented as follows:

Find
$$x^* \in C$$
 such that $F(x^*, y) \ge 0$ for all $y \in C$, $EP(F, C)$

and

Find
$$\bar{x} \in C$$
 such that $f(\bar{x}, y) \ge 0$ for all $y \in C$. $EP(f, C)$

The set of solutions of the problem EP(F, C) is denoted by Sol(F, C) and the problem EP(f, C) is denoted by Sol(f, C). Our aim in this paper is to address to the problem of finding a common solution of two equilibrium problems EP(F, C) and EP(f, C). Typically, this problem is stated as follows:

(1.1) Find
$$x^* \in Sol(F, C) \cap Sol(f, C)$$

An important example of the problem (1.1) is a multiobjective optimization problem which is formulated as the following:

(1.2)
$$\min\{g(x): x \in C\},\$$

O2014Korean Mathematical Society

Received November 16, 2012; Revised May 2, 2013.

²⁰¹⁰ Mathematics Subject Classification. 65Kxx, 90Cxx.

Key words and phrases. equilibrium problems, monotone, pseudomonotone, Lipschitz-type continuous, fixed point.

This work is supported by National Foundation for Science and Technology Development of Vietnam (NAFOSTED).

where $g_i : C \to \mathcal{R}(i = 1, 2)$ and $g(x) = (g_1(x), g_2(x))$ for all $x \in C$. Suppose that there is a vector $\bar{y} = (\bar{y}_1, \bar{y}_2)^T \in \mathcal{R}^2$ with the property that $\bar{y}_i < g_i(x)$ for all $x \in C$ and i = 1, 2. Then, it is well-known to see that a vector $\bar{x} \in C$ is a minimal solution of the problem (1.2) if and only if there are positive real numbers a_1 and a_2 such that

$$\max\{\frac{g_i(\bar{x}) - \bar{y}_i}{a_i} : i = 1, 2\} < \max\{\frac{g_i(x) - \bar{y}_i}{a_i} : i = 1, 2\} \quad \forall x \in C, g(x) \neq g(\bar{x}).$$

In fact, it is not easy to define the constants a_1 and a_2 . Now, for each $(x, y) \in C \times C$ we set $F(x, y) = g_1(y) - g_1(x)$ and $f(x, y) = g_2(y) - g_2(x)$. Then, we can see that the multiobjective optimization problem (1.2) is equivalent to the problem (1.1). Moreover, the problem (1.1) covers many other important problems in optimization as well as in nonlinear analysis such as variational inequalities, the nonlinear complementary problem, the nonlinear optimization problem, just to name a few (see [1, 6, 15, 17]). On the other hand, it is rather convenient for reformulating many practical problems in economic, transportation and engineering (see [14, 16]).

We recall that the bifunction f is called *monotone* on C, if

$$f(x,y) + f(y,x) \le 0 \quad \forall x, y \in C;$$

pseudomonotone on C, if

$$f(x,y) \ge 0$$
 implies $f(y,x) \le 0 \quad \forall x,y \in C;$

Lipschitz-type continuous on C with constants $c_1 > 0$ and $c_2 > 0$ (see [16]), if

$$f(x,y) + f(y,z) \ge f(x,z) - c_1 ||x - y||^2 - c_2 ||y - z||^2 \quad \forall x, y, z \in C.$$

In recent years, the problem to solve equilibrium problems becomes an attractive field for many researchers. Methods for solving the problems have studied extensively in many different ways. The proximal point method was first extended by Moudafi in [17] to equilibrium problems with monotone bifunctions. In [15], Konnov used the proximal point method for solving the equilibrium problems with weakly monotone bifunctions in a real Hilbert space. Also in the framework of proximal point methods, Nguyen et al. in [18] developed a bundle algorithm for solving the equilibrium problems where the bifunctions satisfy a certain cocoercivity condition. Extended to the methods of Fukushima in [13] for variational inequalities, Mastroeni in [16] proposed the gap function method for equilibrium problems where the gap function is introduced to convert an equilibrium problem into an optimization problem. Then, the convergence is established under continuously differentiable and strongly monotone assumptions of the bifunction. Recently, Anh et al. in [5] introduced an Armijo-type method for pseudomonotone equilibrium problems and fixed point problems. The method is based on the auxiliary problem principle and the Armijo-type linesearch techniques. Then, convergent properties of the method are established, among them the global convergence is proved under pseudomonotone assumptions of the bifunction and without Lipschitz-type

continuous conditions. This technique also has extensively developed by many authors for solving equilibrium problems and others (see [2, 5, 7, 11, 19, 20]).

Motivated by fixed point techniques of Takahashi and Takahashi in [21] and an improvement set of extragradient-type iteration methods in [5], we introduce new iteration algorithms for finding a common of the solution set of an equilibrium problem with a monotone bifunction and the solution set of a pseudomonotone equilibrium problem. In the first one, the second equilibrium problem is not required to satisfy any monotonicity property, but it must satisfy a certain Lipschitz-type continuous condition. To avoid this requirement, we propose linesearch procedures commonly used in variational inequalities to obtain projection-type algorithms for solving the problem (1.1). We show that all of the iterative sequences generated by this algorithm weakly converge to the common element in a real Hilbert space.

2. Preliminaries

Let C be a nonempty closed convex subset of a real Hilbert space \mathcal{H} . We write $x^n \to x$ to indicate that the sequence $\{x^n\}$ weakly converges to x as $n \to \infty, x^n \to x$ implies that $\{x^n\}$ strongly converges to x. For any $x \in \mathcal{H}$, there exists a nearest point in C, denoted by $Pr_C(x)$, such that

$$||x - Pr_C(x)|| \le ||x - y|| \quad \forall y \in C.$$

 Pr_C is called the metric projection of \mathcal{H} to C. It is well known that Pr_C satisfies the following properties:

(2.1) $\langle x - y, Pr_C(x) - Pr_C(y) \rangle \ge \|Pr_C(x) - Pr_C(y)\|^2 \quad \forall x, y \in \mathcal{H},$

(2.2)
$$\langle x - Pr_C(x), Pr_C(x) - y \rangle \ge 0 \quad \forall x \in \mathcal{H}, y \in C,$$

(2.3)
$$\|x - y\|^2 \ge \|x - Pr_C(x)\|^2 + \|y - Pr_C(x)\|^2 \quad \forall x \in \mathcal{H}, y \in C.$$

For solving the problem (1.1) with two bifunctions F and f, let us assume that F and f satisfy the following conditions:

- (A_1) F is monotone on C;
- (A_2) for each $x \in C$, $F(x, \cdot)$ is lower semicontinuous and convex on C;
- (A_3) for each $x, y, z \in C$,

$$\lim_{\lambda \to 0^+} F(\lambda z + (1 - \lambda)x, y) \le F(x, y);$$

- (A_4) f is pseudomonotone on C;
- (A_5) for each $x \in C$, $f(x, \cdot)$ is convex on C and f is weak continuous on C: (A_6) $Sol(F,C) \cap Sol(f,C) \neq \emptyset$.

A mapping $S: C \to C$ is called *nonexpansive*, if $||S(x) - S(y)|| \le ||x - y||$ for all $x, y \in C$. For finding a common point of the set of fixed points of S and the solution set of the equilibrium problem EP(f, C), Takahashi and Takahashi in [21] first introduced an iterative scheme by the viscosity approximation method.

The iterative sequence $\{x^k\}$ is defined by:

$$\begin{cases} x^{0} \in \mathcal{H}, \\ \text{Find } u^{k} \in C \text{ such that } f(u^{k}, y) + \frac{1}{r_{k}} \langle y - u^{k}, u^{k} - x^{k} \rangle \geq 0 \quad \forall y \in C, \\ x^{k+1} = \alpha_{k} g(x^{k}) + (1 - \alpha_{k}) S(u^{k}) \quad \forall k \geq 0, \end{cases}$$

where g is a contractive mapping of \mathcal{H} into itself. The authors showed that under certain conditions over $\{\alpha_k\}$ and $\{r_k\}$, sequences $\{x^k\}$ and $\{u^k\}$ strongly converge to $z = Pr_{Sol(f,C)\cap Fix(S)}(g(z))$. Recently, iterative methods for finding a common element of the set of solutions of equilibrium problems and the set of fixed points of a nonexpansive mapping have further developed by many authors (see [3, 8, 10, 22, 21] and the references quoted therein).

A self-mapping $S:C\to C$ is called a $strict\ pseudocontraction,$ if there exists a constant $0\leq L<1$ such that

$$||S(x) - S(y)||^{2} \le ||x - y||^{2} + L||(I - S)(x) - (I - S)(y)||^{2} \quad \forall x, y \in C,$$

where I is the identity mapping on C. In [5], Anh and Hien introduced an Armijo-type iteration method for finding a common element of the set of fixed points of strict pseudocontractions $S_i(i = 1, 2, ..., p)$ and the set of solutions of the problem EP(f, C) for the pseudomonotone bifunction f without Lipschitz-type continuous conditions. The iterative process is based on the extragradient method and Armijo-type linesearch techniques as the following:

Step 0. Choose $x^0 \in C$.

Step 1. Solve the strongly convex problem

$$y^{k} = \operatorname{argmin}\{f(x^{k}, y) + \frac{\beta}{2}||y - x^{k}||^{2}: y \in C\}$$

and set $r(x^{k}) = x^{k} - y^{k}$.

If $||r(x^k)|| \neq 0$ then go to Step 1.

Otherwise, set $w^k = x^k$ and go to Step 2.

Step 2. Find the smallest positive integer number m_k such that

 $f(x^k - \gamma^{m_k} r(x^k), y^k) \le -\sigma ||r(x^k)||^2.$

Step 3. Compute $w^k = Pr_{C \cap H_k}(x^k)$,

where $z^k = x^k - \gamma^{m_k} r(x^k), v^k \in \partial_2 f(z^k, z^k)$

and $H_k = \{x \in \mathcal{H} : \langle v^k, x - z^k \rangle \leq 0\}$, and go to Step 3.

Step 4. Compute $x^{k+1} = \alpha_k w^k + (1 - \alpha_k) \sum_{i=1}^p \lambda_{k,i} S_i(w^k), k := k + 1,$ go back to Step 1.

Under appropriate assumptions on the parameters, the authors showed that the sequences $\{x^k\}, \{y^k\}$ and $\{w^k\}$ weakly converge to the point x^* , where

$$x^* = \lim_{k \to \infty} Pr_{\bigcap_{i=1}^p \operatorname{Fix}(S_i, C) \cap \operatorname{Sol}(f, C)}(x^k).$$

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In this paper, we propose new iteration methods for finding a common point of the set $Sol(F, C) \cap Sol(f, C)$. These methods can be considered as an improvement of the viscosity approximation method in [21] and Armijo-type linesearch techniques in [5]. Then, the algorithms are modified by projecting on a suitable convex set to obtain a new variant which possesses a better convergence property. The first algorithm is now described as follows.

Algorithm 2.1. Step 0. Choose $x^0 \in C, k := 0$, positive sequences $\{\lambda_k\}, \{\beta_k\}$ and $\{\alpha_k\}$ such that $\alpha_k \in [0, 1]$ for all $k \ge 0$.

Step 1. Solve the auxiliary equilibrium problems and

the strongly convex programs:

(2.4) Finding
$$y^k \in C$$
 such that $F(y^k, y) + \frac{1}{\beta_k} \langle y - y^k, y^k - x^k \rangle \ge 0 \ \forall y \in C$,

(2.5)
$$z^k = \operatorname{argmin}\{\lambda_k f(y^k, z) + \frac{1}{2} ||z - y^k||^2 : y \in C\}$$

(2.6)
$$t^{k} = \operatorname{argmin}\{\lambda_{k}f(z^{k},t) + \frac{1}{2}\|t - y^{k}\|^{2}: y \in C\},\ x^{k+1} := \alpha_{k}g(x^{k}) + (1 - \alpha_{k})t^{k}.$$

If $y^k = x^k$ and $z^k = y^k$ then STOP. Otherwise, go to Step 2.

Step 2. Set k := k + 1, and return to Step 1.

The main task of Algorithm 2.1 is to solve the auxiliary equilibrium problem (2.4) and two strongly convex programming problems (2.5)-(2.6) at Step 1. Note that problems (2.5) and (2.6) are strongly convex and C is nonempty, they are uniquely solvable.

For each $\beta > 0$, Combettes and Hirstoaga in [12] defined the solution mapping

(2.7)
$$T_{\beta}(x) := \{ \bar{x} \in C : F(\bar{x}, y) + \frac{1}{\beta} \langle y - \bar{x}, \bar{x} - x \rangle \ge 0 \quad \forall y \in C \},$$

and the authors showed that \bar{x} is a solution to the problem EP(F, C) is and only if its a fixed point of the mapping T_{β} . With assumption (A_1) and for each $x \in C$, the mapping $F_x(t, y) := F(t, y) + \frac{1}{\beta} \langle y - t, t - x \rangle$ is strongly monotone on C, then the mapping T_{β} is single-valued. Otherwise, since x^* is a solution to the problem EP(f, C) if and only if its a fixed point of the solution mapping S, where S is defined by

$$S(x) := \operatorname{argmin}\{\lambda f(x,t) + \frac{1}{2} \| t - x \|^2 : \ y \in C\}$$

for each $x \in C$ and $\lambda > 0$. So that if $y^k = x^k$ and $z^k = y^k$, then x^k is the common solution of two sets Sol(F, C) and Sol(f, C). We can talk that x^k is an ϵ -solution to the problem (1.1) with the tolerance $\epsilon > 0$, if $||x^k - y^k|| \leq \epsilon$ and $||y^k - t^k|| \leq \epsilon$. In the next algorithm, we extended the algorithms in [21] and [5] for finding a common solution of the set $Sol(F, C) \cap Sol(f, C)$ to obtain

a weakly convergence algorithm. This algorithm is similar to Algorithm 2.1, where an augmented step will be added to Algorithm 2.1 and obtain a new variant of the iterative algorithm in [4]. The algorithm is described as follows.

Algorithm 2.2. Step 0. Choose $x^0 \in C, k := 0, \gamma \in (0, 1)$, positive sequences $\{\lambda_k\}, \{\beta_k\}$ and $\{\alpha_k\}$ such that $\alpha_k \in [0, 1]$ for all $k \ge 0$. Take $\sigma \in (0, \frac{\beta}{2})$.

Step 1. Solve the auxiliary equilibrium problem:

(2.8) Finding
$$y^k \in C$$
 such that $F(y^k, y) + \frac{1}{\beta_k} \langle y - y^k, y^k - x^k \rangle \ge 0 \ \forall y \in C.$

Step 2. Solve the strongly convex program:

(2.9) $z^k = \operatorname{argmin}\{\lambda_k f(y^k, z) + \frac{1}{2} ||z - y^k||^2 : y \in C\}.$ If $y^k = x^k$ and $z^k = y^k$ then STOP. If $y^k \neq x^k$ and $z^k = y^k$ then set $w^k = y^k$ and go to Step 4. Otherwise, go to Step 3.

Step 3. Find the smallest nonnegative integer m_k such that (2.10)

$$f(y^{k} - \gamma^{m_{k}} r(y^{k}), z^{k}) \leq -\sigma \|r(y^{k})\|^{2}, \text{ where } r(y^{k}) := y^{k} - z^{k}.$$

Set $\bar{z}^{k} = y^{k} - \gamma^{m_{k}} r(y^{k}).$
Compute $w^{k} := Pr_{C \cap H_{k}}(x^{k}),$
where $v^{k} \in \partial f(\bar{z}^{k}, \cdot)(\bar{z}^{k})$ and $H_{k} := \{x \in \mathcal{H} : \langle v^{k}, x - \bar{z}^{k} \rangle \leq 0\}.$
Step 4. Compute $x^{k+1} = \alpha_{k} x^{k} + (1 - \alpha_{k}) w^{k}.$

Set k := k + 1, and return to Step 1.

To investigate the convergence of this scheme, we recall the following technical lemmas which will be used in the sequel.

Lemma 2.3 (see [4], Lemma 3.1). Let C be a nonempty closed convex subset of a real Hilbert space \mathcal{H} . Let $f: C \times C \to \mathcal{R}$ be a pseudomonotone, Lipschitztype continuous bifunction with constants $c_1 > 0$ and $c_2 > 0$. For each $x \in C$, let $f(x, \cdot)$ be convex and subdifferentiable on C. Suppose that the sequences $\{y^k\}, \{z^k\}, \{t^k\}$ generated by Schemes (2.5) and (2.6). For each $x^* \in Sol(f, C)$, we have

$$||t^{k} - x^{*}||^{2} \le ||y^{k} - x^{*}||^{2} - (1 - 2\lambda_{k}c_{1})||y^{k} - z^{k}||^{2} - (1 - 2\lambda_{k}c_{2})||z^{k} - t^{k}||^{2} \quad \forall k \ge 0.$$

Lemma 2.4 (see [10], Lemma 2.1). Let $\{a_k\}, \{b_k\}$ and $\{c_k\}$ be three sequences of nonnegative real numbers satisfying the inequality

$$a_{k+1} \le (1+b_k)a_k + c_k,$$

for some integer $k \geq 1$, where $\sum_{k=1}^{\infty} b_k < \infty$ and $\sum_{k=1}^{\infty} c_k < \infty$. Then, $\lim_{k\to\infty} a_k$ exists.

Lemma 2.5 (see [12]). Let $F : C \times C \to \mathcal{R}$ satisfy the assumptions A_1 - A_4 , $\beta > 0$ and the mapping T_β is defined by (2.7). Then, the following hold:

- (i) T_{β} is single-valued;
- (ii) T_{β} is firmly nonexpansive, i.e.,

$$||T_{\beta}(x) - T_{\beta}(y)||^{2} \le \langle T_{\beta}(x) - T_{\beta}(y), x - y \rangle \quad \forall x, y \in C;$$

- (iii) the fixed point set of T_{β} is equivalent to Sol(F, C);
- (iv) the solution set Sol(F, C) is closed and convex.

Lemma 2.6 (see [22], Lemma 3.2). Let \mathcal{H} be a real Hilbert space and let C be a nonempty, closed and convex subset of \mathcal{H} . Let the sequence $\{x^k\} \subset \mathcal{H}$ be Fejer-monotone with respect to C, i.e., for every $u \in D$,

$$\|x^{k+1} - u\| \le \|x^k - u\| \quad \forall k \ge 0.$$

Then, $\{Pr_C(x^k)\}$ strongly converges to some $z \in C$.

3. Convergent theorems

Now, we prove the main convergence theorems.

Theorem 3.1. Suppose that Assumptions $A_1 - A_6$ are satisfied, f is Lipschitztype continuous on C with constants $c_1 > 0, c_2 > 0, x^0 \in C, \lambda$ and two sequences $\{\lambda_k\}, \{\alpha_k\}$ satisfy the following restrictions:

(3.1)
$$\begin{cases} 0 < \delta < \frac{1}{\sqrt{2}}, \\ \alpha_k \in (0,1), \sum_{k=0}^{\infty} \alpha_k < \infty, \\ \{\lambda_k\} \subset [a,b] \text{ for some } a, b \in (0,\frac{1}{L}), \text{ where } L = \max\{2c_1, 2c_2\}. \end{cases}$$

Then, the sequences $\{x^k\}$, $\{y^k\}$, $\{z^k\}$ and $\{t^k\}$ generated by Algorithm 2.1 weakly converge to the same point $x^* \in Sol(F, C) \cap Sol(f, C)$.

The proof of this theorem is divided into several steps. **Step 1.** Claim that

$$\lim_{k \to \infty} \|y^k - t^k\| = \lim_{k \to \infty} \|y^k - z^k\| = \lim_{k \to \infty} \|y^k - x^k\| = 0.$$

Proof of Step 1. Let $x^* \in Sol(F,C) \cap Sol(f,C)$, and $\{T_{\beta_k}\}$ be a sequence of the mappings defined as in Lemma 2.5 and y^k defined by (2.4). Then, x^* is the unique solution to the strongly monotone equilibrium problem:

$$F(x^*, y) + \frac{1}{\beta_k} \langle y - x^*, x^* - x^k \rangle \ge 0 \quad \forall y \in C.$$

This means that $x^* = T_{\beta_k}(x^*)$. For any $k \ge 0$, we get

(3.2)
$$||y^k - x^*|| = ||T_{\beta_k}(x^k) - T_{\beta_k}(x^*)|| \le ||x^k - x^*||.$$

For each $x^* \in Sol(F, C) \cap Sol(f, C)$, it follows from $x^{k+1} = \alpha_k g(x^k) + (1-\alpha_k)t^k$, (3.2), Lemma 2.3 and $\delta \in (0, \frac{1}{2})$ that

$$(3.3) ||x^{k+1} - x^*||^2 = ||\alpha_k(g(x^k) - x^*) + (1 - \alpha_k)(t^k - x^*)||^2 \le \alpha_k ||g(x^k) - x^*||^2 + (1 - \alpha_k)||t^k - x^*||^2 = \alpha_k ||(g(x^k) - g(x^*)) + (g(x^*) - x^*)||^2 + (1 - \alpha_k)||t^k - x^*||^2 \le 2\alpha_k ||g(x^k) - g(x^*)||^2 + 2\alpha_k ||g(x^*) - x^*||^2 + (1 - \alpha_k)||t^k - x^*||^2 \le 2\delta^2 \alpha_k ||x^k - x^*||^2 + 2\alpha_k ||g(x^*) - x^*||^2 + (1 - \alpha_k)||t^k - x^*||^2 \le 2\delta^2 \alpha_k ||x^k - x^*||^2 + 2\alpha_k ||g(x^*) - x^*||^2 + (1 - \alpha_k)||t^k - x^*||^2 - (1 - \alpha_k)(1 - 2\lambda_k c_1)||y^k - z^k||^2 - (1 - \alpha_k)(1 - 2\lambda_k c_2)||z^k - t^k||^2 \le [1 - \alpha_k(1 - 2\delta^2)]||x^k - x^*||^2 + 2\alpha_k ||g(x^*) - x^*||^2 - (1 - \alpha_k)(1 - 2\lambda_k c_1)||y^k - z^k||^2 - (1 - \alpha_k)(1 - 2\lambda_k c_2)||z^k - t^k||^2.$$

Then, using Lemma 2.4 and $\sum_{k=1}^{\infty} \alpha_k < \infty$, we have the existence of $c := \lim_{k \to \infty} \|x^k - x^*\|^2$ and

(3.4)
$$[1 - \alpha_k (1 - 2\delta^2)](1 - 2bc_1) \|y^k - z^k\|^2$$

$$\leq (1 - \alpha_k)(1 - 2\lambda_k c_1) \|y^k - z^k\|^2$$

$$\leq \|x^k - x^*\|^2 - \|x^{k+1} - x^*\|^2 + 2\alpha_k \|g(x^*) - x^*\|^2$$

$$\rightarrow 0 \text{ as } k \rightarrow \infty,$$

and

(3.5)
$$\lim_{k \to \infty} \|z^k - y^k\| = 0.$$

By the similar way, also

$$\lim_{k \to \infty} \|z^k - t^k\| = 0.$$

 $\lim_{k\to\infty} \|z^k - t^k\| = 0.$ Combining this, (3.5) and the inequality $\|y^k - t^k\| \le \|y^k - z^k\| + \|z^k - t^k\|$, we have

$$\lim_{k \to \infty} \|y^k - t^k\| = 0.$$

By Lemma 2.5, we have

$$\begin{split} \|y^{k} - x^{*}\|^{2} &= \|T_{\beta_{k}}(x^{k}) - T_{\beta_{k}}(x^{*})\|^{2} \\ &\leq \langle T_{\beta_{k}}(x^{k}) - T_{\beta_{k}}(x^{*}), x^{k} - x^{*} \rangle \\ &= \langle y^{k} - x^{*}, x^{k} - x^{*} \rangle \\ &= \frac{1}{2} \left(\|y^{k} - x^{*}\|^{2} + \|x^{k} - x^{*}\|^{2} - \|y^{k} - x^{k}\|^{2} \right), \end{split}$$

and hence

(3.6)
$$\|y^k - x^*\|^2 \le \|x^k - x^*\|^2 - \|y^k - x^k\|^2.$$

Then, from $x^{k+1} = \alpha_k g(x^k) + (1 - \alpha_k) t^k$ and Lemma 2.3, it follows that

$$\begin{aligned} \|x^{k+1} - x^*\|^2 &= \|\alpha_k g(x^k) + (1 - \alpha_k) t^k - x^*\|^2 \\ &\leq \alpha_k \|g(x^k) - x^*\|^2 + (1 - \alpha_k) \|t^k - x^*\|^2 \\ &\leq \alpha_k \|g(x^k) - x^*\|^2 + (1 - \alpha_k) \|y^k - x^*\|^2 \\ &\leq \alpha_k \|g(x^k) - x^*\|^2 + (1 - \alpha_k) (\|x^k - x^*\|^2 - \|y^k - x^k\|^2). \end{aligned}$$

Then

 $(1 - \alpha_k) \|y^k - x^k\|^2 \le \alpha_k \|g(x^k) - x^*\|^2 + (1 - \alpha_k) \|x^k - x^*\|^2 - \|x^{k+1} - x^*\|^2.$ Combining this, $\{\alpha_k\} \subset (0, 1), \sum_{k \to \infty}^{\infty} \alpha_k < \infty$ and $\lim_{k \to \infty} \|x^k - x^*\|^2 = c$, we get

$$\lim_{k \to \infty} \|x^k - y^k\| = 0.$$

By Step 1, we have $c = \lim_{k\to\infty} ||x^k - x^*||^2$ and hence the sequence $\{x^k\}$ is bounded. So, there exists a subsequence $\{x^{k_j}\}$ such that the subsequence weakly converges to \bar{t} .

Step 2. Claim that the sequences $\{x^k\}, \{y^k\}$ and $\{t^k\}$ weakly converge to the same point $\overline{t} \in Sol(F, C) \cap Sol(f, C)$.

Proof of Step 2. By Step 1, we also have $h_{1} = -h_{2}$

 $y^{k_i} \rightharpoonup \bar{t}, \ z^{k_i} \rightharpoonup \bar{t}, \ t^{k_i} \rightharpoonup \bar{t}.$

Since z^k is the unique solution of the strongly convex problem

$$\min\{\frac{1}{2}\|y-y^k\|^2 + f(y^k,y): y \in C\},\$$

we have

$$\in \partial (\lambda_k f(y^k, y) + \frac{1}{2} ||y - y^k||^2) (y^k) + N_C(z^k).$$

This follows that

$$0 = \lambda_k w + z^k - y^k + w^k,$$

where $w \in \partial f(y^k, \cdot)(z^k)$ and $w^k \in N_C(z^k)$. By the definition of the normal cone N_C , we have

(3.7)
$$\langle z^k - y^k, y - z^k \rangle \ge \lambda_k \langle w, z^k - y \rangle \quad \forall y \in C.$$

On the other hand, since $f(y^k, \cdot)$ is subdifferentiable on C, by the well-known Moreau-Rockafellar theorem, there exists $w \in \partial f(y^k, \cdot)(z^k)$ such that

$$f(y^k, y) - f(y^k, z^k) \ge \langle w, y - z^k \rangle \quad \forall y \in C.$$

Combining this with (3.7), we have

0

$$\lambda_k \left(f(y^k, y) - f(y^k, z^k) \right) \ge \langle z^k - y^k, z^k - y \rangle \quad \forall y \in C.$$

Hence

$$\lambda_{k_i} \left(f(y^{k_i}, y) - f(y^{k_i}, z^{k_i}) \right) \ge \langle z^{k_i} - y^{k_i}, z^{k_i} - y \rangle \quad \forall y \in C.$$

Then, using $\{\lambda_k\} \subset [a, b] \subset (0, \frac{1}{L})$ and the weak continuity of f, we have

$$f(\bar{t}, y) \ge 0 \quad \forall y \in C.$$

Thus, \bar{t} is belong to the solution set of EP(f, C). Let us show $\bar{t} \in Sol(F, C)$. By $y^k = T_{\beta_k}(x^k)$, we have

$$F(y^k, y) + \frac{1}{\beta_k} \langle y - y^k, y^k - x^k \rangle \ge 0 \quad \forall y \in C.$$

Since F is monotone on C, we also have

$$\frac{1}{\beta_k} \langle y - y^k, y^k - x^k \rangle \ge F(y, y^k) \quad \forall y \in C,$$

and hence

$$\frac{1}{\beta_{k_i}} \langle y - y^{k_i}, y^{k_i} - x^{k_i} \rangle \ge F(y, y^{k_i}).$$

Since $||y^{k_i} - x^{k_i}|| \to 0, y^{k_i} \rightharpoonup \overline{t}$, the lower semicontinuity and convexity of $F(y, \cdot)$ for all $y \in C$, we have $F(y, \overline{t}) \leq 0$. So, from the convexity of $F(y, \cdot)$, for all $\lambda \in (0, 1]$, we have

$$0 = F(\lambda y + (1 - \lambda)\bar{t}, \lambda y + (1 - \lambda)\bar{t})$$

$$\leq \lambda F(\lambda y + (1 - \lambda)\bar{t}, y) + (1 - \lambda)F(\lambda y + (1 - \lambda)\bar{t}, \bar{t})$$

$$\leq \lambda F(\lambda y + (1 - \lambda)\bar{t}, y)$$

and hence $F(\lambda y + (1-\lambda)\bar{t}, y) \ge 0 \quad \forall y \ge 0$. Let $\lambda \to 0$ and using the assumption (A_3) , we have $F(\bar{t}, y) \ge 0 \quad \forall y \ge 0$ and hence \bar{t} is also belong to the solution set Sol(F, C). Thus, the subsequences $\{x^{k_i}\}, \{y^{k_i}\}$ and $\{z^{k_i}\}$ weakly converge to the same point $\bar{t} \in Sol(F, C) \cap Sol(f, C)$.

In order to show that the entire sequence $\{x^k\}$ weakly converges to \bar{t} , assume that there is another subsequence $\{\bar{x}^{k_i}\}$ of the sequence $\{x^k\}$ that weakly converges to some $\hat{t} \in Sol(F, C) \cap Sol(f, C)$ and $\hat{t} \neq \bar{t}$. Note that from Step 1 it follows that there exists $\lim_{k\to\infty} \|x^k - \hat{t}\|$ and $\lim_{k\to\infty} \|x^k - \bar{t}\|$. By the Opial condition, we have

$$\lim_{k \to \infty} \|x^k - \bar{t}\| = \liminf_{i \to \infty} \|x^{k_i} - \bar{t}\|$$

$$< \liminf_{i \to \infty} \|x^{k_i} - \hat{t}\|$$

$$= \lim_{k \to \infty} \|x^k - \hat{t}\|$$

$$= \lim_{i \to \infty} \|\bar{x}^{k_i} - \hat{t}\|$$

$$< \lim_{i \to \infty} \|\bar{x}^{k_i} - \bar{t}\|$$

$$= \lim_{k \to \infty} \|x^k - \bar{t}\|.$$

This is a contraction and thus $\bar{t} = \hat{t}$. So, the sequence $\{x^k\}$ weakly converges to \bar{t} and hence the sequences $\{y^k\}, \{z^k\}$ and $\{t^k\}$ also weakly converges to the same point $\bar{t} \in Sol(F, C) \cap Sol(f, C)$.

Remark 3.2. In the special cases $\alpha_k = 0$ for all $k \ge 0$ or g is the identity mapping, it follows from (3.3) that $||x^{k+1} - \bar{x}|| \le ||x^k - \bar{x}||$ for all $\bar{x} \in Sol(F, C) \cap Sol(f, C)$. By Lemma 2.6, the sequence $\{Pr_{Sol(F,C)\cap Sol(f,C)}(x^k)\}$ strongly converges to some $x^* \in Sol(F, C) \cap Sol(f, C)$. Set $u^k = Pr_{Sol(F,C)\cap Sol(f,C)}(x^k)$. Combining

$$\langle \bar{t} - u^k, u^k - x^k \rangle \le 0 \quad \forall k \ge 0,$$

and

$$x^k \rightharpoonup \bar{t}, y^k \rightharpoonup \bar{t}, z^k \rightharpoonup \bar{t} \in Sol(F, C) \cap Sol(f, C),$$

we get

$$\langle \bar{t} - x^*, x^* - \bar{t} \rangle \le 0,$$

and hence $\bar{t} = x^*$. Thus, the sequences $\{x^k\}, \{y^k\}, \{z^k\}$ and $\{t^k\}$ generated by Algorithm 2.1 weakly converge to the same point $x^* \in Sol(F, C) \cap Sol(f, C)$, where

$$x^* = \lim_{k \to \infty} Pr_{Sol(F,C) \cap Sol(f,C)}(x^k).$$

Let the sequence $\{x^k\}$ be defined by Algorithm 2.2. Suppose that there does not exist a natural number k_0 such that $r(x^k) = 0$ for all $k \ge k_0$. We take a subsequence $\{x^{k_j}\}$ of the sequence $\{x^k\}$ such that

$$\|r(y^{k_j-1})\| \neq 0 \quad \forall j \ge 0$$

By a same way as the proof of Theorem 3.2 in [5], we also get the following lemma.

Lemma 3.3. The following statements hold.

(a) There exists the smallest nonnegative integer m_{k_j-1} such that

$$f(y^{k_j-1} - \gamma^{m_{k_j-1}} r(y^{k_j-1}), y^{k_j-1}) \leq -\sigma \|r(y^{k_j-1})\|^2.$$
(b) $y^{k_j-1} \notin H_{k_j-1}$ for all $j \geq 0$.
(c) $w^{k_j-1} = Pr_{C \cap H_{k_j-1}}(\bar{y}^{k_j-1}),$ where $\bar{y}^{k_j-1} = Pr_{H_{k_j-1}}(y^{k_j-1}).$
(d) If $\|r(y^k)\| > 0$, then
(e) $\|w^k - \bar{w}^*\|^2 \leq \|w^k - \bar{w}^*\|^2$

(3.8)
$$\|w^k - x^*\|^2 \le \|y^k - x^*\|^2 - \|w^k - \bar{y}^k\|^2 - \left(\frac{\gamma^{m_k}\sigma}{\|v^k\|(1 - \gamma^{m_k})}\right) \|r(y^k)\|^4$$

for all $x^* \in Sol(f, C)$.
(e) If $\|r(y^k)\| > 0$, then $Sol(f, C) \subseteq C \cap H_k$.

Lemma 3.4. Claim that the sequence $\{||x^k - x^*||\}$ is nonincreasing and hence convergent. Moreover, if $||r(y^k)|| > 0$ for all $k \ge 0$, then we have

$$\|x^{k+1} - x^*\|^2 \le \|x^k - x^*\|^2 - (1 - \alpha_k) \|w^k - \bar{y}^k\|^2 - (1 - \alpha_k) \left(\frac{\gamma^{m_k}\sigma}{\|v^k\|(1 - \gamma^{m_k})}\right)^2 \|r(y^k)\|^4,$$

where $\bar{y}^k = Pr_{H_k}(y^k)$ and $x^* \in Sol(F, C) \cap Sol(f, C)$.

Proof. Using (3.8) and $x^{k+1} = \alpha_n x^k + (1 - \alpha_k) w^k$, for each $x^* \in Sol(f, C)$ we have

$$(3.9) ||x^{k+1} - x^*||^2 = ||\alpha_k x^k + (1 - \alpha_k)w^k - x^*||^2
\leq \alpha_k ||x^k - x^*||^2 + (1 - \alpha_k)||w^k - x^*||^2
\leq \alpha_n ||x^k - x^*||^2 + (1 - \alpha_k)[||y^k - x^*||^2 - ||w^k - \bar{y}^k||^2
- \left(\frac{\gamma^{m_k}\sigma}{||v^k||(1 - \gamma^{m_k})}\right)^2 ||r(y^k)||^4]
\leq ||x^k - x^*||^2 - (1 - \alpha_k)||w^k - \bar{y}^k||^2
- (1 - \alpha_k) \left(\frac{\gamma^{m_k}\sigma}{||v^k||(1 - \gamma^{m_k})}\right)^2 ||r(y^k)||^4.$$

In the case $||r(y^k)|| = 0$, by Step 2 of Algorithm 2.2, we have $w^k = y^k$ and

$$||x^{k+1} - x^*|| = ||\alpha_k x^k + (1 - \alpha_k)y^k - x^*||$$

$$\leq \alpha_k ||x^k - x^*|| + (1 - \alpha_k)||y^k - x^*||$$

$$\leq \alpha_k ||x^k - x^*|| + (1 - \alpha_k)||x^k - x^*||$$

$$= ||x^k - x^*||.$$

Using this and (3.9), we have

$$||x^{k+1} - x^*|| \le ||x^k - x^*|| \quad \forall k \ge 0.$$

So the sequence $\{\|x^k - x^*\|\}$ is nonincreasing and hence convergent.

Lemma 3.5. Claim that there exists $c = \lim_{k\to\infty} ||x^k - x^*|| = \lim_{k\to\infty} ||w^k - x^*||$, where $x^* \in Sol(F, C) \cap Sol(f, C)$. Consequently, the sequences $\{x^k\}, \{y^k\}, \{z^k\}, \{v^k\}$ and $\{w^k\}$ are bounded.

Proof. By Lemma 3.4, there exists

(3.10)
$$c = \lim_{k \to \infty} \|x^k - x^*\|.$$

Since Lemma 3.3(e), and the fact that $w^k = y^k$ if $||r(y^k)|| = 0$ and $w^k = Pr_{C \cap H_k}(y^k)$ if $||r(y^k)|| \neq 0$, we have

$$||w^k - x^*|| \le ||y^k - x^*|| \le ||x^k - x^*|| \quad \forall k \ge 0.$$

Hence

(3.11)
$$\lim_{k \to \infty} \|w^k - x^*\| \le \lim_{k \to \infty} \|x^k - x^*\| = c.$$

Using $x^{k+1} = \alpha_k x^k + (1 - \alpha_k) w^k$, we have

$$||x^{k+1} - x^*|| = ||\alpha_k x^k + (1 - \alpha_k)w^k - x^*||$$

$$\leq \alpha_k ||x^k - x^*|| + (1 - \alpha_k)||w^k - x^*||.$$

Hence

(3.12)
$$c \le \lim_{k \to \infty} \|w^k - x^*\|.$$

From (3.12) and (3.11), it follows that

$$c = \lim_{k \to \infty} \|w^k - x^*\|$$

Since z^k is the unique solution to

$$\min\{f(y^k, y) + \frac{\beta}{2} ||y - y^k|^2 : y \in C\},\$$

we have

$$f(y^{k}, y) + \frac{\beta}{2} \|y - y^{k}\|^{2} \ge f(y^{k}, z^{k}) + \frac{\beta}{2} \|z^{k} - y^{k}\|^{2} \quad \forall y \in C.$$

Therefore, with $y = y^k \in C$, it holds:

(3.13)
$$0 \ge f(y^k, z^k) + \frac{\beta}{2} \|z^k - y^k\|^2.$$

Since $f(y^k, \cdot)$ is convex and subdifferentiable on C, i.e.,

$$f(y^k, z^k) - f(y^k, y^k) \ge \langle s^n, z^k - y^k \rangle \quad \forall s^k \in \partial f(y^k, \cdot)(y^k),$$

we have $f(y^k, z^k) \ge \langle s^k, z^k - y^k \rangle$. Then, using (3.13) we obtain

$$\langle s^k, z^k - y^k \rangle + \frac{\beta}{2} \|y^k - z^k\|^2 \le 0.$$

This implies that

$$\frac{1}{\beta^2} \|s^k\|^2 + \frac{2}{\beta} \langle s^k, z^k - y^k \rangle + \|y^k - z^k\|^2 \le \frac{1}{\beta^2} \|s^k\|^2.$$

Hence

(3.14)
$$\|y^k - z^k + \frac{1}{\beta}s^k\| \le \frac{1}{\beta}\|s^k\|.$$

From the assumption (iv) and (3.10), it implies that the sequence $\{s^k\}$ is bounded. Then, it follows from (3.14) that $\{y^k\}$ is bounded and hence $\bar{z}^k = y^k - \gamma^{m_k}(y^k - z^k)$ is also bounded. Also the sequences $\{v^k\}$ and $\{w^k\}$ are bounded. \Box

Lemma 3.6. Let $x^* \in Sol(F, C) \cap Sol(f, C)$. Assume that if the sequence $\{s^k\}$ is bounded then $\{v^k\}$ is also bounded, where $v^k \in \partial f(s^k, \cdot)(s^k)$. Then, we have

(3.15)
$$\begin{aligned} \|x^{k_{j+1}} - x^*\|^2 &\leq \|x^{k_j} - x^*\|^2 - (1-b)\|w^{k_j+p_j} - \bar{y}^{k_j+p_j}\|^2 \\ &- (1-b)\left(\frac{\gamma^{m_{k_j+p_j}}\sigma}{M(1-\gamma^{m_{k_j+p_j}})}\right)^2 \|r(y^{k_j+p_j})\|^4, \end{aligned}$$

where $0 < a \le \alpha_n \le b < 1, p_j = k_{j+1} - k_j - 1, r(y^{k_j+i}) = 0 \ \forall i = 0, 1, \dots, p_j - 1, r(y^{k_j+p_j}) \ne 0, \ \bar{y}^{k_j+p_k} = Pr_{H_{k_j+p_j}}(y^{k_j+p_j}), \ and \ the \ sequence \ \{v^k\} \ is \ uniformly bounded \ by \ M > 0.$

Proof. Using the assumption and Lemma 3.5, there exists M > 0 such that $||v^n|| \leq M$ for all $n \geq 0$. Then, if $k_{j+1} = k_j + 1$, then the inequality (3.15) is clear from Lemma 3.4. Otherwise, we suppose that there exists a positive integer p_j such that $k_j + p_j + 1 = n_{j+1}$ and $||r(x^{k_j+i})|| = 0$ for all $i = 0, 1, \ldots, p_j - 1$. By the assumptions $0 < a \leq \alpha_k \leq b < 1$, $||r(y^{k_j+p_j})|| > 0$ and Lemma 3.4, we have

$$\begin{split} \|x^{k_{j+1}} - x^*\|^2 &= \|x^{k_j + p_j + 1} - x^*\|^2 \\ &\leq \|x^{k_j + p_j} - x^*\|^2 - (1 - \alpha_{k_j + p_j}) \|w^{k_j + p_j} - \bar{y}^{k_j + p_j}\|^2 \\ &- (1 - \alpha_{k_j + p_j}) \left(\frac{\gamma^{m_{k_j + p_j}} \sigma}{M(1 - \gamma^{m_{k_j + p_j}})}\right)^2 \|r(y^{k_j + p_j})\|^4 \\ &\leq \|\alpha_{k_j + p_j - 1} x^{k_j + p_j - 1} + (1 - \alpha_{k_j + p_j - 1}) w^{k_j + p_j - 1} - x^*\|^2 \\ &- (1 - b) \|w^{k_j + p_j} - \bar{y}^{k_j + p_j}\right)^2 \|r(x^{k_j + p_j})\|^4 \\ &\leq \alpha_{k_j + p_j - 1} \|x^{k_j + p_j - 1} - x^*\|^2 + (1 - \alpha_{k_j + p_j - 1})\|w^{k_j + p_j - 1} - x^*\|^2 \\ &- (1 - b) \left(\frac{\gamma^{m_{k_j + p_j}} \sigma}{M(1 - \gamma^{m_{k_j + p_j}})}\right)^2 \|r(y^{k_j + p_j})\|^4 \\ &\leq \alpha_{k_j + p_j - 1} \|x^{k_j + p_j - 1} - x^*\|^2 + (1 - \alpha_{k_j + p_j - 1})\|y^{k_j + p_j - 1} - x^*\|^2 \\ &- (1 - b) \left(\frac{\gamma^{m_{k_j + p_j}} \sigma}{M(1 - \gamma^{m_{k_j + p_j}})}\right)^2 \|r(y^{k_j + p_j})\|^4 \\ &\leq \|x^{k_j + p_j - 1} - x^*\|^2 - (1 - b)\|w^{k_j + p_j - 1} - \bar{y}^{k_j + p_j}\|^2 \\ &- (1 - b) \left(\frac{\gamma^{m_{k_j + p_j}} \sigma}{M(1 - \gamma^{m_{k_j + p_j}})}\right)^2 \|r(y^{k_j + p_j})\|^4 \\ &\leq \dots \\ &\leq \|x^{k_j - x^*}\|^2 - (1 - b)\|w^{k_j + p_j} - \bar{y}^{k_j + p_j}\|^2 \\ &- (1 - b) \left(\frac{\gamma^{m_{k_j + p_j}} \sigma}{M(1 - \gamma^{m_{k_j + p_j}})}\right)^2 \|r(y^{k_j + p_j})\|^4. \end{aligned}$$

This implies (3.15).

Now, we turn to the main convergence result of Algorithm 2.2.

Theorem 3.7. Suppose that the bifunction f satisfy the conditions $A_1 - A_6$, if the sequence $\{s^k\}$ is bounded then $\{v^k\}$ is also bounded, where $v^k \in$

 $\partial f(s^k, \cdot)(s^k)$, and the parameters satisfy the following conditions:

$$(3.16) \qquad \begin{cases} 0 < a \le \alpha_k \le b < 1 \quad \forall k \ge 0, \\ \beta = \liminf_{k \to \infty} \lambda_k > 0, \\ 0 < \sigma < \frac{\beta}{2}, \\ 0 < \gamma < 1, \\ \liminf_{k \to \infty} \beta_k > 0, 0 < \beta_k \quad \forall k \ge 0. \end{cases}$$

Then, the sequences $\{x^k\}, \{y^k\}$ and $\{w^k\}$ generated by Algorithm 2.2 weakly converge to the same point $x^* \in Sol(F, C) \cap Sol(f, C)$, where

$$x^* = \lim_{k \to \infty} Pr_{Sol(F,C) \cap Sol(f,C)}(x^k).$$

Proof. We consider two cases:

Case a) There is no natural number k_0 such that $r(y^k) = 0$ for all $k \ge k_0$. Using Lemma 3.6 and Lemma 3.5, we obtain that the sequence $\{v^k\}$ is bounded by M > 0 and

$$\|x^{k_{j+1}} - x^*\|^2 \le \|x^{k_j} - x^*\|^2 - (1-b) \left(\frac{\gamma^{m_{k_j+p_j}}\sigma}{M(1-\gamma^{m_{k_j+p_j}})}\right)^2 \|r(y^{k_j+p_j})\|^4,$$

with $p_j = k_{j+1} - k_j - 1$. Since $\{||x^k - x^*||\}$ is convergent, it is easy to see that

$$\lim_{j \to \infty} \gamma^{m_{k_j + p_j}} \| r(y^{k_j + p_j}) \| = 0.$$

 $Case \ a_1) \limsup_{j \to \infty} \gamma^{m_{k_j + p_j}} > 0.$

In this case it follows that $\liminf_{k\to\infty} ||r(y^{k_j+p_j})|| = 0$. Since $\{x^{k_j+p_j}\}$ is bounded, there exists an accumulation point \bar{x} of $\{x^{k_j+p_j}\}$. In other words, a subsequence $\{x^{k_{j_i}+p_{j_i}}\}$ weakly converges to some \bar{x} , as $i \to \infty$ such that $r(\bar{x}) = 0.$ It means that $\bar{x} \in Sol(f, C)$. $Case \ a_2) \lim_{j \to \infty} \gamma^{m_{k_j+p_j}} = 0.$

Since $\{\|x^{k_j+p_j}-x^*\|\}$ is convergent and Lemma 3.5, there are subsequences $\{x^{k_{j_i}+p_{j_i}}\}$ of $\{x^{k_j+p_j}\}$ and $\{y^{k_{j_i}+p_{j_i}}\}$ of $\{y^{k_j+p_j}\}$ such that $\{x^{k_{j_i}+p_{j_i}}\}$ weakly converges to \bar{x} and $\{y^{k_{j_i}+p_{j_i}}\}$ weakly converges to \bar{y} as $i \to \infty$. Since $m_{k_j+p_j}$ is the smallest nonnegative integer, $m_{k_j+p_j} - 1$ does not satisfy (2.10). Hence, we have

$$f(x^{k_{j_i}+p_{j_i}}-\gamma^{m_{k_{j_i}+p_{j_i}}-1}r(y^{k_{j_i}+p_{j_i}}), z^{k_{j_i}+p_{j_i}}) > -\sigma||r(y^{k_{j_i}+p_{j_i}})||^2$$

Passing onto the limit, as $i \to \infty$ and using the continuity of f, we have

(3.17)
$$f(\bar{x}, \bar{y}) \ge -\sigma ||r(\bar{x})||^2$$

where $r(\bar{x}) = \bar{x} - \bar{y}$. It follows from (2.10) that

$$f(x^{k_{j_i}+p_{j_i}}-\gamma^{m_{k_{j_i}+p_{j_i}}}r(y^{k_{j_i}+p_{j_i}}), y^{k_{j_i}+p_{j_i}}) + \frac{\beta}{2}||r(y^{k_{j_i}+p_{j_i}})||^2 \le 0.$$

Passing onto the limit, as $i \to \infty$ (f is continuous), we obtain

$$f(\bar{x}, \bar{y}) + \frac{\beta}{2} ||r(\bar{x})||^2 \le 0.$$

Combining this with (3.17), we have

$$\sigma \|r(\bar{x})\|^2 \ge -f(\bar{x},\bar{y}) \ge \frac{\beta}{2} \|r(\bar{x})\|^2,$$

which implies that $r(\bar{x}) = 0$, and hence $\bar{x} = \bar{y} \in Sol(f, C)$. Thus, every weak cluster point of the sequence $\{x^{k_j+p_j}\}$ is a solution of the problem EP(f, C).

Now we show that every weak cluster point of $\{x^{k_j+p_j}\}$ is long to the set Sol(F, C). Suppose that the subsequences $\{x^{k_{j_i}+p_{j_i}}\}$ of $\{x^{k_j+p_j}\}$ and $\{y^{k_{j_i}+p_{j_i}}\}$ of $\{y^{k_j+p_j}\}$ such that $\{x^{k_{j_i}+p_{j_i}}\}$ weakly converges to \bar{x} and $\{y^{k_{j_i}+p_{j_i}}\}$ weakly converges to \bar{y} as $i \to \infty$. By $y^k = T_{\beta_k}(x^k)$, we have

$$F(y^k, y) + \frac{1}{\beta_k} \langle y - y^k, y^k - x^k \rangle \ge 0 \quad \forall y \in C.$$

Since F is monotone on C, we get

$$\frac{1}{\beta_k} \langle y - y^k, y^k - x^k \rangle \ge F(y, y^k) \quad \forall y \in C,$$

and hence

$$\frac{1}{\beta_{k_{j_i}}} \langle y - y^{k_{j_i}}, y^{k_{j_i}} - x^{k_{j_i}} \rangle \ge F(y, y^{k_{j_i}}) \quad \forall y \in C.$$

Since $||y^{k_{j_i}} - x^{k_{j_i}}|| \to 0$ as $i \to \infty$, the lower semicontinuity and the convexity of $F(y, \cdot)$ for all $y \in C$, we have $F(y, \bar{x}) \leq 0$. So, for all $\lambda \in (0, 1]$ we have

$$0 = F(\lambda y + (1 - \lambda)\bar{x}, \lambda y + (1 - \lambda)\bar{x})$$

$$\leq \lambda F(\lambda y + (1 - \lambda)\bar{x}, y) + (1 - \lambda)F(\lambda y + (1 - \lambda)\bar{x}, \bar{x})$$

$$\leq \lambda F(\lambda y + (1 - \lambda)\bar{x}, y),$$

and hence $F(\lambda y + (1 - \lambda)\bar{x}, y) \ge 0$ for all $y \in C$. Let $\lambda \to 0$, we get $F(\bar{x}, y) \ge 0$ for all $y \in C$ and so $\bar{x} \in Sol(F, C)$. Thus, every weak cluster point of the sequence $\{x^{k_j+p_j}\}$ is belong to the set Sol(F, C).

In order to show that the entire sequence $\{x^k\}$ weakly converges to \bar{x} . Assume that there is another subsequence $\{\bar{x}^{k_i}\}$ which weakly converges to some $\hat{x} \in Sol(F,C) \cap Sol(f,C)$ and $\bar{x} \neq \hat{x}$. By the Opial condition and Lemma 3.5, we have

$$\lim_{k \to \infty} \|x^k - \bar{x}\| = \liminf_{i \to \infty} \|x^{k_{j_i}} - \bar{x}\|$$
$$< \liminf_{i \to \infty} \|x^{k_{j_i}} - \hat{x}\|$$
$$= \lim_{k \to \infty} \|x^k - \hat{x}\|$$
$$= \lim_{i \to \infty} \|\bar{x}^{k_i} - \hat{x}\|$$
$$< \lim_{i \to \infty} \|\bar{x}^{k_i} - \bar{x}\|$$

$$= \lim_{k \to \infty} \|x^k - \bar{x}\|.$$

This is a contraction and thus $\bar{x} = \hat{x}$. So the subsequence $\{x^k\}$ weakly converges to $\bar{x} \in Sol(F, C) \cap Sol(f, C)$. Then, the sequences $\{y^k\}, \{z^k\}$ and $\{w^k\}$ also weakly converge to the same point $\bar{x} \in Sol(F, C) \cap Sol(f, C)$.

Now we will prove that the sequences $\{x^k\}, \{y^k\}$ and $\{w^k\}$ weakly converge to \bar{x} , where

$$\bar{x} = \lim_{k \to \infty} \Pr_{Sol(F,C) \cap Sol(f,C)}(x^k)$$

Indeed, we suppose that $t^k := Pr_{Sol(F,C)\cap Sol(f,C)}(x^k)$ and $x^k \rightharpoonup \bar{x}$. By the definition of $Pr_C(\cdot)$, we have

(3.18)
$$\langle t^k - x^k, t^k - x \rangle \le 0 \quad \forall x \in Sol(F, C) \cap Sol(f, C).$$

It follows from Lemma 3.4 that

$$|x^{k+1} - x^*|| \le ||x^k - x^*|| \quad \forall x^* \in Sol(F, C) \cap Sol(f, C).$$

Then, by Lemma 2.6, we have

(3.19)
$$t^k = Pr_{Sol(F,C)\cap Sol(f,C)}(x^k) \to \hat{x} \in Sol(F,C) \cap Sol(f,C) \text{ as } k \to \infty.$$

Passing to the limit in (3.18) and combining this with (3.19), we have

$$\langle \hat{x} - \bar{x}, \hat{x} - x \rangle \le 0 \quad \forall x \in Sol(F, C) \cap Sol(f, C).$$

This means that $\bar{x} = \hat{x}$ and $\bar{x} = \lim_{k \to \infty} Pr_{Sol(F,C) \cap Sol(f,C)}(x^k)$. Thus, both sequences $\{y^k\}$ and $\{w^k\}$ weakly converge to \bar{x} , where

$$\bar{x} = \lim_{k \to \infty} \Pr_{Sol(F,C) \cap Sol(f,C)}(x^k).$$

Case b) There exists k_0 such that $r(y^k) = 0$ for all $k \ge k_0$. Thus $x^k \in Sol(f, C)$ for all $k \ge k_0$ and Algorithm 2.2 becomes the viscosity approximation algorithm proposed by Takahashi and Takahashi in [21]. Then, the iteration sequences $\{x^k\}$ and $\{y^k\}$ strongly converge to the common solution point $x^* \in Sol(F, C) \cap Sol(f, C)$, where

$$x^* = \lim_{k \to \infty} Pr_{Sol(F,C) \cap Sol(f,C)}(x^k).$$

The proof is completed.

4. Applications to variational inequalities

Let C is a nonempty, convex and subset of \mathcal{H} , G and H be functions from C into \mathcal{H} , $\varphi : C \to \mathcal{R}$ and $\phi : C \to \mathcal{R}$ be proper, continuous and convex functions. We consider the generalized variational inequalities formulated as follows

 $VI(G,C) \text{ Find } x^* \in C \text{ such that } \langle G(x^*), x - x^* \rangle + \varphi(x) - \varphi(x^*) \geq 0 \ \, \forall x \in C, \text{ and }$

VI(H,C) Find $\bar{x} \in C$ such that $\langle H(\bar{x}), x - \bar{x} \rangle + \phi(x) - \phi(\bar{x}) \ge 0 \quad \forall x \in C.$

We consider the problem which is to a common point of the solution set of the problem VI(G, C) (shortly SVI(G, C)) and the solution set of the problem VI(H, C) (shortly SVI(H, C)). It details that

(4.1) Find
$$x^* \in SVI(G,C) \cap SVI(H,C)$$
.

Let $F: C \times C \to \mathcal{R}$ be defined by $F(x, y) := \langle G(x), y - x \rangle + \varphi(y) - \varphi(x)$, and $f: C \times C \to \mathcal{R}$ such that $f(x, y) := \langle H(x), y - x \rangle + \phi(y) - \phi(x)$. Then, the problem (4.1) can be written in the form of the problem (1.1).

Let $G: C \to \mathcal{H}$. The mapping G is called

(i) monotone on C if

$$\langle G(x) - G(y), x - y \rangle \ge 0 \quad \forall x, y \in C;$$

(ii) pseudomonotone on C if

$$\langle G(y), x - y \rangle \ge 0$$
 implies $\langle G(x), x - y \rangle \ge 0 \quad \forall x, y \in C;$

(iii) Lipschitz continuous on C with constant L > 0 if

 $||G(x) - G(y)|| \le L||x - y|| \quad \forall x, y \in C.$

It is easy to see that G is pseudomonotone (*L*-Lipschitz continuous) on C if and only if F is pseudomonotone (corresponding: Lipschitz-type continuous with constants $c_1 = c_2 = \frac{L}{2}$) on C. Then, Algorithm 2.1 applied to solve the problem (4.1) can be described as follows:

Algorithm 4.1. Step 0. Choose $x^0 \in C, k := 0$, positive sequences $\{\lambda_k\}, \{\beta_k\}$ and $\{\alpha_k\}$ such that $\alpha_k \in [0, 1]$ for all $k \ge 0$.

Step 1. Solve the auxiliary variational inequalities and the strongly convex programs:

$$\begin{split} \langle G(y^k), y - y^k \rangle + \varphi(y) - \varphi(y^k) + \frac{1}{\beta_k} \langle y - y^k, y^k - x^k \rangle &\geq 0 \quad \forall y \in C, \\ z^k = \operatorname{argmin}\{\lambda_k \langle H(y^k), y - y^k \rangle + \lambda_k \phi(y) + \frac{1}{2} \|z - y^k\|^2 : \ y \in C\}, \\ t^k = \operatorname{argmin}\{\lambda_k \langle H(z^k), y - y^k \rangle + \lambda_k \phi(y) + \frac{1}{2} \|t - y^k\|^2 : \ y \in C\}, \\ x^{k+1} &:= \alpha_k g(x^k) + (1 - \alpha_k) t^k. \end{split}$$

If
$$y^k = x^k$$
 and $z^k = y^k$ then STOP. Otherwise, go to Step 2.

Step 2. Set k := k + 1, and return to Step 1.

Similar to Theorems 3.1, the convergence of Algorithm 4.1 is presented as the following:

Theorem 4.2. Let $G : C \to \mathcal{H}$ be monotone and lower semicontinuous, $H: C \to \mathcal{H}$ be pseudomonotone and Lipschitz continuous with constant L > 0, two convex functions $\varphi, \phi : C \to \mathcal{R}$, and $SVI(G, C) \cap SVI(H, C) \neq \emptyset$. Under certain conditions (3.1) with $c_1 = c_2 = \frac{L}{2}$, the sequences $\{x^k\}, \{y^k\}, \{z^k\}$ and $\{t^k\}$ generated by Algorithm 4.1 weakly converge to the same point $x^* \in SVI(G,C) \cap SVI(H,C)$. In the special case $\alpha_k = 0$ for all $k \geq 0$ or g is the identity mapping, the sequences weakly converge to the same point $x^* \in Sol(F,C) \cap Sol(f,C)$, where

$$x^* = \lim_{k \to \infty} Pr_{SVI(G,C) \cap SVI(H,C)}(x^k)$$

By applying Algorithm 2.2 for the problem (4.1), we have the following.

Algorithm 4.3. Step 0. Choose $x^0 \in C, k := 0, \gamma \in (0, 1)$, positive sequences $\{\lambda_k\}, \{\beta_k\}$ and $\{\alpha_k\}$ such that $\alpha_k \in [0, 1]$ for all $k \ge 0$. Take $\sigma \in (0, \frac{\beta}{2})$.

Step 1. Solve the auxiliary variational inequalities

$$\langle G(y^k), y - y^k \rangle + \varphi(y) - \varphi(y^k) + \frac{1}{\beta_k} \langle y - y^k, y^k - x^k \rangle \ge 0 \quad \forall y \in C,$$

Step 2. Solve the strongly convex program:

$$z^{k} = \operatorname{argmin}\{\lambda_{k}\langle H(y^{k}), y - y^{k}\rangle + \lambda_{k}\phi(y) + \frac{1}{2}||z - y^{k}||^{2}: y \in C\},\$$

If $y^{k} = x^{k}$ and $z^{k} = y^{k}$ then STOP.
If $y^{k} \neq x^{k}$ and $z^{k} = y^{k}$ then set $w^{k} = y^{k}$

and go to Step 4. Otherwise, go to Step 3.

Step 3. Find the smallest nonnegative integer m_k such that

$$\begin{aligned} (1-\gamma^{m_k})\langle H(\bar{z}^k), r(y^k)\rangle + \phi(\bar{z}^k) - \phi(z^k) &\geq \sigma \|r(y^k)\|^2, \\ \text{where } r(y^k) &:= y^k - z^k. \\ \text{Set } \bar{z}^k &= y^k - \gamma^{m_k} r(y^k). \text{ Compute } w^k &:= Pr_{C \cap H_k}(x^k), \\ H_k &:= \{x \in \mathcal{H} : \ \langle H(\bar{z}^k), x - \bar{z}^k \rangle \leq 0\}. \end{aligned}$$

Step 4. Compute $x^{k+1} = \alpha_k x^k + (1-\alpha_k) w^k. \end{aligned}$

Set k := k + 1, and return to Step 1.

As in Theorem 3.7, we give the convergent results of Algorithm 4.3 as the following.

Theorem 4.4. Let $G : C \to \mathcal{H}$ be monotone and lower semicontinuous, $H : C \to \mathcal{H}$ be pseudomonotone and lower semicontinuous, two convex functions $\varphi, \phi : C \to \mathcal{R}$, and $SVI(G, C) \cap SVI(H, C) \neq \emptyset$. Under certain conditions (3.16), the sequences $\{x^k\}, \{y^k\}$ and $\{w^k\}$ generated by Algorithm 4.3 weakly converge to the same point $x^* \in SVI(G, C) \cap SVI(H, C)$, where

$$x^* = \lim_{k \to \infty} Pr_{SVI(G,C) \cap SVI(H,C)}(x^k).$$

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