

ON THE SYMMETRY OF ANNULAR BRYANT SURFACE WITH CONSTANT CONTACT ANGLE

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ABSTRACT. We show that a compact immersed annular Bryant surface in \mathbb{H}^3 meeting two parallel horospheres in constant contact angles is rotational.

1. introduction

Catenoid is the only nonplanar minimal surface of rotation in \mathbb{R}^3 . Therefore a catenoid meets each plane perpendicular to the axis of rotation in constant contact angle. Conversely, if a compact embedded minimal or constant mean curvature (cmc) surface in \mathbb{R}^3 meets two parallel planes in constant contact angles, then the surface is part of a catenoid or part of a cmc surface of rotation, i.e., a Delaunay surface. This can be proved by using the Alexandrov's moving plane argument [4], [11] to planes perpendicular to the parallel planes. Recently, Pyo showed that a compact immersed minimal annulus meeting two parallel planes in constant contact angles is also part of a catenoid [9]. In the case of cmc surfaces, the result fails to hold: Wente constructed examples of immersed constant mean curvature annuli in a slab or in a ball meeting the boundary planes or the boundary sphere perpendicularly [12].

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The hyperbolic gauss map of a Bryant surface in \mathbb{H}^3 is meromorphic as the gauss map of a minimal surface in \mathbb{R}^3 is meromorphic [2]. Moreover, the cousin correspondence [5] shows a close relation between minimal surfaces in \mathbb{R}^3 and Bryant surfaces in \mathbb{H}^3 : for each simply connected minimal surface in \mathbb{R}^3 , there exists a differentiable, 2π -periodic family of Bryant surfaces in \mathbb{H}^3 . The cousin of a plane in \mathbb{R}^3 is the associate surfaces of a horosphere in \mathbb{H}^3 . The cousin of the catenoid is called the catenoid cousin. In this paper, we generalize Pyo's result to Bryant surfaces in \mathbb{H}^3 .

THEOREM 1. *Let Σ be a compact immersed annular Bryant surface in \mathbb{H}^3 meeting two parallel horospheres in constant contact angles. Let f be the hyperbolic gauss map of Σ . If f' does not attain 0 and ∞ , then Σ is rotational.*

Two horospheres in \mathbb{H}^3 are said to be *parallel* if they have the same ideal boundary point. We note that the gauss map of a minimal surface in a slab in \mathbb{R}^3 cannot attain 0 or ∞ [3]. But the hyperbolic gauss map of a catenoid cousin meeting two parallel horospheres can attain 0 or ∞ [10]. In the embedded surface case, one can use the Alexandrov reflection argument to prove that a compact embedded Bryant surface in \mathbb{H}^3 meeting two parallel horospheres in constant contact angles is rotational.

We use the Bianchi-Calò method which represents a Bryant surface very simply which is homeomorphic to a region in \mathbb{C} [6].

2. Bianchi-Calò method

We use the upper half space model (\mathbb{R}_+^3, ds_h^2) for \mathbb{H}^3 : $\mathbb{R}_+^3 = \{(x_1, x_2, x_3) \in \mathbb{R}^3 : x_3 \leq 0\}$ and $ds_h^2 = (dx_1^2 + dx_2^2 + dx_3^2)/x_3^2$. In this model, horosphere is either a (euclidean) sphere tangent to the $\{x_3 = 0\}$ -plane or a horizontal plane $\{x_3 = \text{constant}\}$.

Let $\psi : \Sigma \rightarrow \mathbb{H}^3$ be an immersed oriented surface. Let ν be the unit normal vector field on Σ . The hyperbolic gauss map $f : \Sigma \rightarrow \partial_\infty \mathbb{H}^3$ relates to $p \in \Sigma$ the end point on the ideal boundary $\partial_\infty \mathbb{H}^3$ of the oriented normal geodesic starting from p in the direction of ν .

REMARK 1. Geometrically, the hyperbolic gauss map f can be interpreted in two ways as follows (the geodesic half sphere and horosphere are assumed to be located in the direction of ν . cf. Figure 1.):

(a) $f(p)$ is the euclidean center on $\partial_\infty \mathbb{H}^3 = \mathbb{C}^2 \cup \{\infty\}$ of the geodesic plane tangent to M at p .

(b) $f(p)$ is the point on $\partial_\infty \mathbb{H}^3$ of the horosphere tangent to M at p .

The following Lemma shows the special feature of the Bryant surfaces in \mathbb{H}^3 [2].

LEMMA 1. A surface $\psi : \Sigma \rightarrow \mathbb{H}^3$ has mean curvature one if and only if the hyperbolic gauss map $h : \Sigma \rightarrow \mathbb{C} \cup \{\infty\}$ is meromorphic.

Instead of the usual Bryant representation formula, we use the Bianchi-Calò method to represent a Bryant surface which is homeomorphic to a region in \mathbb{C} [6]. Let $f = f(z)$ be a holomorphic map defined in a region $\Omega \subset \mathbb{C}$, and let

$$(1) \quad R_{f(z)} = \frac{1 + |z|^2}{2} |f'(z)|.$$

Let $S_{f(z)} \subset \mathbb{R}_+^3$ be the sphere which is tangent to $\partial_\infty \mathbb{H}^3$ at $f(z)$ and has euclidean radius $R_{f(z)}$. Note that $S_{f(z)}$ is a two-parameter family of spheres. Clearly, $\partial_\infty \mathbb{H}^3$ is one of the two envelopes of $S_{f(z)}$. The second envelope gives a Bryant surface whose gauss map is f [6].

Bianchi-Calò method: In the above situation, the parametrization

$$(2) \quad x_1 = \operatorname{Re}(f) - \frac{|f'|^2 \operatorname{Re}(f'z) + \frac{1+|z|^2}{2} \operatorname{Re}((f')^2 \bar{f}'')}{|f'|^2 + \operatorname{Re}(f' \bar{f}'' \bar{z}) + \frac{|f''|^2(1+|z|^2)}{4}}$$

$$(3) \quad x_2 = \operatorname{Im}(f) - \frac{|f'|^2 \operatorname{Im}(f'z) + \frac{1+|z|^2}{2} \operatorname{Im}((f')^2 \bar{f}'')}{|f'|^2 + \operatorname{Re}(f' \bar{f}'' \bar{z}) + \frac{|f''|^2(1+|z|^2)}{4}}$$

$$(4) \quad x_3 = \frac{|f'|^3}{|f'|^2 + \operatorname{Re}(f' \bar{f}'' \bar{z}) + \frac{|f''|^2(1+|z|^2)}{4}}$$

in terms of f gives a Bryant surface Σ_f in \mathbb{H}^3 . (Here, we use $'$ to denote d/dz .) Moreover, f is the hyperbolic gauss map of Σ_f in terms of the local complex parameter $z = x + iy$ on Ω .

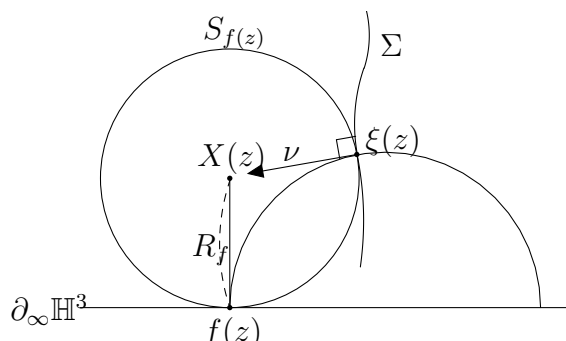


FIGURE 1. Bianchi-Calò method

REMARK 2. For a given Bryant surface Σ homeomorphic to a region in \mathbb{C} with hyperbolic gauss map f , the radius R_f of (1) is just the euclidean radius of the horosphere tangent to $\partial_\infty \mathbb{H}^3$ and Σ . Therefore Σ_f derived from f by the Bianchi-Calò method coincides with Σ .

We briefly explain Σ_f . Details can be found in [6]. Let $f = f_1 + if_2$, and let

$$X(z) = (f_1(z), f_2(z), R_{f(z)})$$

be the surface of centers of $S_{f(z)}$. Since Σ_f is an envelope of $S_{f(z)}$, we have $T_p \Sigma_f = T_p S_{f(z)}$ at each $p \in \Sigma_f$ and for suitable z . Therefore Σ_f is given by

$$(5) \quad \xi(z) = X(z) - R_{f(z)} \nu,$$

where ν is the euclidean unit normal of Σ_f in the direction of $X - \xi$ (cf. Figure 2). Here we have (for simplicity, we let $R = R_f$) [6]

$$\nu = \frac{1}{|\nabla R|^2 + |f'|^2} \left(2\alpha_1, 2\alpha_2, |\nabla R|^2 - |f'|^2 \right),$$

where

$$\alpha_1 = R_y f_{2,x} - R_x f_{2,y}, \quad \alpha_2 = R_x f_{1,y} - R_y f_{2,x}$$

and

$$(6) \quad |\nabla R|^2 + |f'|^2 = (|z|^2 + 1) \left(|f'|^2 + \operatorname{Re}(f' \bar{f}'' \bar{z}) + \frac{|f''|^2 (1 + |z|^2)}{4} \right).$$

Then it is easy to see that

$$(7) \quad x_3 = \xi_3 = R - R \nu_3 = \frac{2R|f'|^2}{|\nabla R|^2 + |f'|^2}.$$

3. Proof of the Main result

In the following, the two parallel horospheres under consideration are assumed to be two horizontal planes Π_1 and Π_2 in \mathbb{R}_+^3 . Let Σ be a compact immersed annular Bryant surface meeting Π_1 and Π_2 in constant contact angles. Let $\xi : A \rightarrow \mathbb{H}^3$ be the immersion of Σ , where $A = \{(x, y) \in \mathbb{R}^2 : R_1 \leq r = \sqrt{x^2 + y^2} \leq R_2\}$ is an annulus. Let $f : A \rightarrow \partial_\infty \mathbb{H}^3 = \mathbb{C}^2 \cup \{\infty\}$ be the hyperbolic gauss map of Σ . Hereafter we identify the Bryant surface Σ_f derived from f with Σ . Since the hyperbolic gauss map f is assumed to be bounded, f is holomorphic on A . Now we prove Theorem 1.

Proof of Theorem 1. The constant contact angle condition implies that the third component $\nu_3 = (|\nabla R|^2 - |f'|^2)/(|\nabla R|^2 + |f'|^2)$ of ν is constant on each component of ∂A . Therefore $|f'|^2/|\nabla R|^2$ is constant on each component of ∂A .

Since $\partial \Sigma_f$ lies on horizontal planes, $x_3 = 2R|f'|^2/(|\nabla R|^2 + |f'|^2)$ is also constant on each component of ∂A . From the constancy of $|f'|^2/|\nabla R|^2$ on ∂A , it follows that $2R = 2|f'|^2/(1 + |z|^2)$ is constant on each component of ∂A . Since ∂A consists of two concentric circles centered at the origin, $|f'|$ is also constant on each component of ∂A . Since $|f'|$ is assumed not to attain 0 and ∞ , $\log |f'|$ is a bounded harmonic function on A . Since $|f'|$ is constant on each component of ∂A , we have $\log |f'| = a \log |z| + b$ for some real constants a and b . Hence we have $f'(z) = e^b z^a = Bz^a$. Since f is a single-valued holomorphic function on A , we have $f'(z) = Bz^n$ for some integer n .

From (4), we see that

$$\begin{aligned} x_3 &= \frac{|Bz^n|^3}{|Bz^n|^2 + B^2 \operatorname{Re}(z^n \cdot n \cdot \bar{z}^{n-1} \cdot \bar{z}) + \frac{|nBz^{n-1}|^2(1+|z|^2)}{4}} \\ &= \frac{|B||z|^{n+2}}{(n+1)|z|^2 + \frac{n^2}{4}(1+|z|^2)} \end{aligned}$$

Hence x_3 is constant on each circle $C_r = \{z : |z| = r\}$, for $R_1 \leq r \leq R_2$. It follows that the x_3 -level curves of Σ_f are images of C_r .

From (1), it follows that R is also constant on each circle $C_r = \{z : |z| = r\}$. We may assume that $f(z) = \frac{B}{n+1}z^{n+1}$. Hence the image of C_r under f is a circle on $\partial_\infty \mathbb{H}^3$. Since Σ_f is one of the envelopes of $S_{f(z)}$,

we conclude that $\xi(C_r)$ is a circle on a horizontal plane. It is clear that $\xi(C_r)$ are coaxial. Hence Σ_f is rotational. \square

Finally, we raise the following question.

Let Σ be a compact immersed annular Bryant surface in \mathbb{H}^3 meeting two parallel horospheres in constant contact angles. Is Σ rotational, even if the derivative of the hyperbolic gauss map attain 0 or ∞ ?

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