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WEAK SOLUTIONS OF GRADIENT FLOW OF LANDAU-DE GENNES ENERGY

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ABSTRACT. Taking into account the flexoelectric effects, we consider a gradient flow of Landau-de Gennes energy which generalizes the Oseen-Frank energy. In this article, we discuss existence of weak solutions of the gradient flow in an appropriate function space.

1. Introduction

Molecules in Nematic Liquid Crystals are described by a traceless symmetric second order tensor

(1.1)
$$\mathbf{Q} = \int_{\mathbb{S}^2} \ell \otimes \ell f(\ell) \, d\ell - \frac{1}{3} I,$$

where f is a probability distribution function satisfying $f(\ell) = f(-\ell)$ for all $\ell \in \mathbb{S}^2$. Shapes of molecules are characterized by three eigenvalues of \mathbf{Q} and the direction of a molecule is defined by the unit eigenvector whose corresponding eigenvalue has the largest magnitude. The order tensor \mathbf{Q} is a measure of the local degree of orientational order in liquid crystals. The liquid crystal is said to be uniaxial if two eigenvalues of \mathbf{Q} are equal, and it is biaxial when \mathbf{Q} has three distinct eigenvalues. The tensor \mathbf{Q} is zero in the isotropic phase. Since \mathbf{Q} is a symmetric matrix, all eigenvalues of \mathbf{Q} are real and expressed in term of \mathbf{Q} as [4]

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$$\begin{cases} \lambda_1 = \frac{2\sqrt{\operatorname{tr} \mathbf{Q}^2}}{\sqrt{6}} \cos \alpha, \\ \lambda_2 = \frac{2\sqrt{\operatorname{tr} \mathbf{Q}^2}}{\sqrt{6}} \left(-\frac{1}{2} \cos \alpha - \frac{\sqrt{3}}{2} \sin \alpha \right), \\ \lambda_3 = \frac{2\sqrt{\operatorname{tr} \mathbf{Q}^2}}{\sqrt{6}} \left(-\frac{1}{2} \cos \alpha + \frac{\sqrt{3}}{2} \sin \alpha \right), \end{cases}$$

where

$$\cos(3\alpha) = -\frac{\sqrt{6}\mathrm{tr}\,\mathbf{Q}^3}{\mathrm{tr}\,\mathbf{Q}^2\sqrt{\mathrm{tr}\mathbf{Q}^2}}, \quad \sin(3\alpha) = \sqrt{1 - \frac{6(\mathrm{tr}\,\mathbf{Q}^3)^2}{(\mathrm{tr}\,\mathbf{Q}^2)^3}}, \quad \alpha \in \left[0, \frac{\pi}{3}\right].$$

It follows from $\operatorname{tr} \mathbf{Q} = 0$ and $\mathbf{Q} = \mathbf{Q}^T$ that $6(\operatorname{tr} \mathbf{Q}^3)^2 \leq (\operatorname{tr} \mathbf{Q}^2)^3$. Moreover, \mathbf{Q} has two distinct eigenvalues if and only if $6(\operatorname{tr} \mathbf{Q}^3)^2 = (\operatorname{tr} \mathbf{Q}^2)^3$. From (1.1), it can be easily seen that $-\frac{1}{3} \leq \lambda_i \leq \frac{2}{3}$ for i = 1, 2, 3. It then follows that $\operatorname{tr} \mathbf{Q}^2 \leq \frac{1}{6}$.

If \mathbf{Q} is expressed by

$$\mathbf{Q} = S_1\left(\mathbf{m}\otimes\mathbf{m} - \frac{1}{3}\mathbf{I}\right) + S_2\left(\mathbf{n}\otimes\mathbf{n} - \frac{1}{3}\mathbf{I}\right),$$

where $\{\mathbf{m}, \mathbf{n}, \mathbf{m} \times \mathbf{n}\}$ is an orthonormal basis for \mathbf{R}^3 consisting of unit eigenvectors of \mathbf{Q} , then the eigenvalues are

$$\frac{1}{3}(2S_1 - S_2), -\frac{1}{3}(S_1 + S_2), \frac{1}{3}(2S_2 - S_1).$$

In the Landau-de Gennes theory, neglecting the higher derivatives and powers of \mathbf{Q} the free energy density \mathcal{F} for nematic liquid crystals is given by

$$\mathcal{F}(\mathbf{Q}, \nabla \mathbf{Q}) = \frac{1}{2} \left(L_1 Q_{\alpha\beta,\gamma} Q_{\alpha\beta,\gamma} + L_2 Q_{\alpha\beta,\beta} Q_{\alpha\gamma,\gamma} + L_3 Q_{\alpha\beta,\gamma} Q_{\alpha\gamma,\beta} \right) + f_{bulk}(\mathbf{Q}),$$

where

$$f_{bulk}(\mathbf{Q}) = \frac{A}{2} \operatorname{tr} \mathbf{Q}^2 - \frac{B}{3} \operatorname{tr} \mathbf{Q}^3 + \frac{C}{4} \left(\operatorname{tr} \mathbf{Q}^2 \right)^2.$$

The bulk energy f_{bulk} is a potential function for uniaxial nematic liquid crystals, meaning that f_{bulk} favors molecules to be uniaxial. In order to study biaxial liquid crystals, we need to add higher powers of \mathbf{Q} to f_{bulk} . In liquid crystals, there exists a polarization induced by a splay and bending distortion [2, 1]. Such a polarization is called flexoelectric polarization which is analogous to piezoelectric polarization in solids. The flexoelectric polarization can be written in terms of \mathbf{Q} as

$$\mathbf{P}^{f} = (P_1, P_2, P_3),$$

$$P_i = \epsilon_3 Q_{ij,j} + \epsilon_4 Q_{jk} Q_{ij,k} + \epsilon_5 Q_{ij} Q_{jk,k} + \text{ higher order.}$$

Due to the appearance of the flexoelectric polarization, the following electrostatic equations (Maxwell's equations) will be taken into account in the system

(1.2)
$$\nabla \cdot (\boldsymbol{\epsilon}(\mathbf{Q})\mathbf{E}) = -\nabla \cdot \mathbf{P}^f, \quad \nabla \times \mathbf{E} = 0,$$

where $\epsilon(\mathbf{Q})$ is the dielectric permittivity tensor given by

$$\epsilon(\mathbf{Q}) = \epsilon_0 \mathbf{I} + \epsilon_1 \mathbf{Q} + \epsilon_2 \mathbf{Q}^2.$$

Hence the electrostatic energy is

$$f_{elec} = -\frac{1}{2} (\epsilon(\mathbf{Q}) \mathbf{E}) \cdot \mathbf{E} - \mathbf{P}^f \cdot \mathbf{E}.$$

If we let

$$\mathbf{Q} = \frac{3}{2}S(\mathbf{n} \otimes \mathbf{n} - \frac{1}{3}\mathbf{I}),$$

then

$$\epsilon(\mathbf{Q})\mathbf{E} \cdot \mathbf{E} = \left(\epsilon_0 - \frac{\epsilon_1}{2}S + \frac{\epsilon_2}{4}S^2\right) |\mathbf{E}|^2 + \frac{3}{2}S\left(\epsilon_1 + \frac{\epsilon_2}{2}S\right) (\mathbf{n} \cdot \mathbf{E})^2,$$

$$\mathbf{P}^f = e_{11}(\nabla \cdot \mathbf{n})\mathbf{n} + e_{33}\mathbf{n} \times \nabla \times \mathbf{n},$$

$$e_{11} = \frac{3}{2}\epsilon_3S + \frac{3}{4}(2\epsilon_5 - \epsilon_4)S^2, \quad e_{33} = \frac{3}{2}\epsilon_3S + \frac{3}{4}(2\epsilon_4 - \epsilon_5)S^2.$$

Then the permittivity ϵ_{\perp} and dielectric anisotropic constant ϵ_a are defined by

$$\epsilon_{\perp} = \epsilon_0 - \frac{\epsilon_1}{2}S + \frac{\epsilon_2}{4}S^2, \ \epsilon_a = \frac{3}{2}S\left(\epsilon_1 + \frac{\epsilon_2}{2}S\right).$$

Now, since eigenvalues of \mathbf{Q} are in between $-\frac{1}{3}$ and $\frac{2}{3}$, we impose the following condition for strong ellipticity of (1.2)

 $3\epsilon_0 > \epsilon_1$ if $\epsilon_1 > 0$, and $3\epsilon_0 > -2\epsilon_1$ if $\epsilon_1 \le 0$.

Since some material can have $\epsilon_1 > 0$ and S > 0, we have to include ϵ_2 -term in order to satisfy solvability condition $\epsilon_{\perp} > |\epsilon_a|$. For a sake of simplicity, we take $\epsilon_4 = \epsilon_5 = 0$ so that equations (1.2) become

(1.3)
$$\nabla \cdot \left[\left(\epsilon_0 \mathbf{I} + \epsilon_1 \mathbf{Q} + \epsilon_2 \mathbf{Q}^2 \right) \nabla \varphi \right] = -\epsilon_3 \nabla \cdot (\nabla \cdot \mathbf{Q}),$$

where $\nabla \cdot \mathbf{Q} = Q_{1j,j}\mathbf{e}_x + Q_{2j,j}\mathbf{e}_y + Q_{3j,j}\mathbf{e}_z$, $\{\mathbf{e}_x, \mathbf{e}_y, \mathbf{e}_z\}$ is a set of unit vectors in x, y, z axes respectively, and φ is an electric potential function, i.e. $\mathbf{E} = \nabla \varphi$.

By Maxwell's equation, the electrostatic energy functional can be written as

$$\int_{\Omega} f_{elec} \, dx = -\frac{1}{2} \int_{\Omega} (\nabla \cdot \mathbf{Q}) \cdot \nabla \varphi \, dx$$

The total energy functional \mathcal{E} is

$$\mathcal{E}(\mathbf{Q},\varphi) = \int_{\Omega} \left\{ \frac{1}{2}L |\nabla \mathbf{Q}|^2 + \frac{A}{2} \operatorname{tr} \mathbf{Q}^2 - \frac{B}{3} \operatorname{tr} \mathbf{Q}^3 + \frac{C}{4} \left(\operatorname{tr} \mathbf{Q}^2 \right)^2 - \frac{1}{2} \epsilon_3 (\nabla \cdot \mathbf{Q}) \cdot \nabla \varphi \right\} dx.$$

In the absence of a flow, equations for dynamic problems are

(1.4)
$$\frac{\partial \mathbf{Q}}{\partial t} = L\Delta \mathbf{Q} - A\mathbf{Q} + B\left(\mathbf{Q}^2 - \frac{\operatorname{tr} \mathbf{Q}^2}{3}\mathbf{I}\right) - C(\operatorname{tr} \mathbf{Q}^2)\mathbf{Q}$$
$$-\frac{1}{2}\epsilon_3\left(\nabla^2\varphi - \frac{1}{3}\Delta\varphi\mathbf{I}\right) \text{ in }\Omega.$$

subject to

(1.5)
$$\nabla \cdot (\epsilon(\mathbf{Q})\nabla\varphi) = -\epsilon_3 \nabla \cdot (\nabla \cdot \mathbf{Q}) \quad \text{in } \Omega,$$

and boundary conditions

(1.6)
$$\begin{cases} \frac{\partial \mathbf{Q}(x,t)}{\partial \nu} = \mathbf{0} & \text{on } \Gamma, \quad \mathbf{Q}(x,t) = \mathbf{Q}_1(x) & \text{on } \partial\Omega \setminus \Gamma, \\ \varphi(x,t) = \varphi_0(x) & \text{on } \Gamma, \quad \frac{\partial \varphi(x,t)}{\partial \nu} = 0 & \text{on } \partial\Omega \setminus \Gamma, \end{cases}$$

where \mathbf{Q}_1 is fixed.

From now on, we study existence of weak solutions of the system (1.4)-(1.5) with the boundary conditions (1.6).

2. A priori estimates

In this section, we study a priori estimates for solutions which will be used in the next section. Let us introduce

$$\begin{split} W^{1,2}(\Omega;\mathcal{S}_0) &= \left\{ \mathbf{Q} : ||\mathbf{Q}||_{L^2(\Omega)} + ||\nabla \mathbf{Q}||_{L^2(\Omega)} < \infty, \mathbf{Q} : \Omega \to \mathcal{S}_0 \right\}, \\ H^1_{\Gamma}(\Omega) &= \left\{ \psi \in H^1(\Omega) : \psi = 0 \text{ on } \Gamma, \ \frac{\partial \psi}{\partial \nu} = 0 \text{ on } \partial \Omega \setminus \Gamma \right\}. \end{split}$$

For any p > 0, and t > 0, we denote by $L^p(0,t;\mathcal{V})$ the space of all functions $\mathbf{Q}: (0,t) \to \mathcal{V}$ such that

$$\int_0^t ||\mathbf{Q}||_{\mathcal{V}} \, dt < \infty,$$

where \mathcal{V} is a function space equipped with its norm $|| \cdot ||_{\mathcal{V}}$. We look for a weak solution of the system (1.4),(1.5), and (1.6). In other words, the problem is to find $\mathbf{Q} \in L^2(0,T; W^{1,2}(\Omega; \mathcal{S}_0))$ and $\varphi \in L^2(0,T; H^1(\Omega))$ satisfying

$$\begin{cases} (2.1) \\ \begin{cases} \int_{\Omega} \left\{ \left(\frac{\partial \mathbf{Q}}{\partial t} + L \nabla \mathbf{Q} + A \mathbf{Q} - B \mathbf{Q}^{2} + C(\operatorname{tr} \mathbf{Q}^{2}) \mathbf{Q} \right) \cdot \mathbf{T} \right\} dx \\ &= \frac{1}{2} \epsilon_{3} \int_{\Omega} \nabla \varphi \cdot (\nabla \cdot \mathbf{T}) dx, \\ \int_{\Omega} \left(\epsilon(\mathbf{Q}) \nabla \varphi \right) \cdot \nabla \psi \, dx = \int_{\Gamma} \left(\epsilon(\mathbf{Q}_{1}) \nabla \varphi_{0} \cdot \boldsymbol{\nu} \right) \psi \, dA - \int_{\Omega} (\nabla \cdot \mathbf{Q}) \cdot \nabla \psi \, dx, \\ &\frac{\partial \mathbf{Q}(x,t)}{\partial \nu} = \mathbf{0} \quad \text{on } \Gamma, \quad \mathbf{Q}(x,t) = \mathbf{Q}_{1}(x) \quad \text{on } \partial\Omega \setminus \Gamma, \\ &\varphi(x,t) = \varphi_{0}(x) \quad \text{on } \Gamma, \quad \frac{\partial \varphi(x,t)}{\partial \nu} = \mathbf{0} \quad \text{on } \partial\Omega \setminus \Gamma, \end{cases}$$

for all $\mathbf{T} \in W^{1,2}(\Omega; \mathcal{S}_0)$ and $\psi \in H^1_{\Gamma}(\Omega)$.

LEMMA 2.1. Let (\mathbf{Q}, φ) be a solution pair of functions to (1.4), (1.5), and (1.6). Then

$$\mathbf{Q} \in L^2(0,T; W^{1,2}(\Omega; \mathcal{S}_0)) \cap L^4(0,T; L^4(\Omega; \mathcal{S}_0)), \quad \varphi \in L^2(0,T; H^1(\Omega)).$$

Proof. Let (\mathbf{Q}, φ) be a solution pair of functions to (1.4), (1.5), and (1.6). Multiplying each equation in (1.4) by Q_{ij} and integrating by parts followed by summing up, we obtain

$$\frac{d}{dt} \int_{\Omega} |\mathbf{Q}|^2 dx + \int_{\Omega} \left(L |\nabla \mathbf{Q}|^2 + A \operatorname{tr} \mathbf{Q}^2 - B \operatorname{tr} \mathbf{Q}^3 + C(\operatorname{tr} \mathbf{Q}^2)^2 \right) dx$$

$$(2.2) \qquad \qquad = \frac{1}{2} \epsilon_1 \int_{\Omega} \nabla \varphi \cdot (\nabla \cdot \mathbf{Q}) dx.$$

Similarly, multiplying (1.5) by φ and integrating by parts yield

(2.3)
$$\int_{\Omega} (\epsilon(\mathbf{Q})\nabla\varphi) \cdot \nabla\varphi \, dx = -\epsilon_3 \int_{\Omega} (\nabla \cdot \mathbf{Q}) \cdot \nabla\varphi \, dx.$$

Combining (2.2) with (2.3) we obtain

$$\frac{d}{dt} \int_{\Omega} |\mathbf{Q}|^2 \, dx + \int_{\Omega} \left(L |\nabla \mathbf{Q}|^2 + C(\operatorname{tr} \mathbf{Q}^2)^2 + \frac{1}{2} \left(\epsilon(\mathbf{Q}) \nabla \varphi \right) \cdot \nabla \varphi \right) \, dx$$

$$(2.4) \qquad \qquad = \int_{\Omega} \left(-A \operatorname{tr} \mathbf{Q}^2 + B \operatorname{tr} \mathbf{Q}^3 \right) \, dx.$$

By Hölder inequality, choose $\eta > 0$ such that $C - B\eta^2 > 0$ and

(2.5)
$$\int_{\Omega} \operatorname{tr} \mathbf{Q}^3 \, dx \leq \int_{\Omega} \left\{ \frac{1}{\eta^2} \operatorname{tr} \mathbf{Q}^2 + \eta^2 (\operatorname{tr} \mathbf{Q}^2)^2 \right\} \, dx.$$

It follows from (2.4) and (2.5) that

$$\frac{d}{dt} \int_{\Omega} |\mathbf{Q}|^2 dx + \int_{\Omega} \left(L |\nabla \mathbf{Q}|^2 + \tilde{C} (\operatorname{tr} \mathbf{Q}^2)^2 + \frac{1}{2} (\epsilon(\mathbf{Q}) \nabla \varphi) \cdot \nabla \varphi \right) dx$$
(2.6) $\leq \mathcal{M} ||\mathbf{Q}||_{L^2} + \mathcal{D},$

where $\tilde{C} = C - \frac{1}{\eta^2}$, and $\mathcal{M} = -A + \frac{B}{\eta^2}$. Hence we get

$$\frac{d}{dt} ||\mathbf{Q}||_{L^2}^2 \le \mathcal{M} ||\mathbf{Q}||_{L^2}^2 + \mathcal{D},$$

and Grownwall's inequality leads us to have

(2.7)
$$||\mathbf{Q}(t)||_{L^2}^2 \le ||\mathbf{Q}(0)||_{L^2}^2 e^{\mathcal{M}t} + \frac{\mathcal{D}}{\mathcal{M}} \left(e^{\mathcal{M}t} - 1\right)$$

This implies that

$$\sup_{0 \le t \le T} ||\mathbf{Q}(t)||_{L^2}^2 \le ||\mathbf{Q}(0)||_{L^2}^2 e^{\mathcal{M}T} + \frac{\mathcal{D}}{\mathcal{M}} \left(e^{\mathcal{M}T} - 1 \right),$$

and integrating (2.6) with respect to t yields

$$\int_0^T \int_\Omega \left(L |\nabla \mathbf{Q}|^2 + \tilde{C} (\operatorname{tr} \mathbf{Q}^2)^2 + \frac{1}{2} \left(\epsilon(\mathbf{Q}) \nabla \varphi \right) \cdot \nabla \varphi \right) \, dx \, dt < \infty.$$

Since $(\epsilon(\mathbf{Q})\nabla\varphi)\cdot\nabla\varphi \geq \lambda||\nabla\varphi||^2$ for some $\lambda > 0$, by Poincare inequality we have

$$\mathbf{Q} \in L^{2}(0,T; W^{1,2}(\Omega; \mathcal{S}_{0})) \cap L^{4}(0,T; L^{4}(\Omega; \mathcal{S}_{0})), \varphi \in L^{2}(0,T; H^{1}(\Omega)).$$

3. Existence of weak solution

THEOREM 3.1. For any given T > 0, $\mathbf{Q}_0 \in L^2(\Omega; \mathcal{S}_0)$, there exists a solution pair (\mathbf{Q}, φ) to (2.1) such that $\mathbf{Q} \in L^{(0)}(0, T; W^{1,2}(\Omega; \mathcal{S}_0))$ and $\varphi \in L^2(0, T; H^1(\Omega))$. Moreover, if $\mathbf{Q}_0 \in W^{1,2}(\Omega; \mathcal{S}_0)$, then

$$\mathbf{Q} \in \mathcal{C}(0,T; W^{1,2}(\Omega; \mathcal{S}_0)) \cap L^4(0,T; L^4(\Omega; \mathcal{S}_0)), \frac{\partial \mathbf{Q}}{\partial t} \in L^2(0,T; L^2(\Omega; \mathcal{S}_0)).$$

Proof. We use the Galerkin Method [6] to obtain a weak solution (\mathbf{Q}, φ) to (2.1). We first approximate $W^{1,2}(\Omega, \mathcal{S}_0)$ and $H^1(\Omega)$ by increasing sequences of finite dimensional subspaces $\mathcal{X}^m \subset W^{1,2}(\Omega, \mathcal{S}_0)$, and $\mathcal{Y}^m \subset H^1(\Omega)$ such that

$$\cup_{m=1}^{\infty} \mathcal{X}^m = W^{1,2}(\Omega, \mathcal{S}_0), \quad \cup_{m=1}^{\infty} \mathcal{Y}^m = H^1(\Omega).$$

For each $m \in \mathbb{N}$, let $\{\mathbf{x}_i\}_{i=1}^m$ and $\{y_i\}_{i=1}^m$ be orthonormal bases for \mathcal{X}^m and \mathcal{Y}^m , respectively. We first seek a solution pair $(\mathbf{Q}^m, \varphi^m)$ in $\mathcal{X}^m \times \mathcal{Y}^m$ in the form

$$\mathbf{Q}^m(x,t) = \sum_{i=1}^m p_i(t)\mathbf{x}_i(x), \quad \varphi^m(x,t) = \sum_{i=1}^m q_i(t)y_i(x).$$

Substituting $(\mathbf{Q}^m, \varphi^m)$ for (\mathbf{Q}, φ) in (2.1), and taking $\mathbf{T} = \mathbf{x}_j, \psi = y_k$, we obtain a system of nonlinear ordinary differential equations for $\{p_i(t), q_i(t)\}_{i=1}^m$. It follows from the standard theory of ODEs that the new system has a unique solution on some interval $[0, t_m] \subset [0, T]$. By lemma 2.1, we know that

$$\sup_{0 \le t \le T} \{ ||\mathbf{Q}^m(t)||_{L^2}, ||\varphi^m(t)||_{L^2} \} < \infty.$$

We extend \mathbf{Q}^m, φ^m to the interval [0, T] by the standard continuation method [3, 6]. Apply Lemma 2.1 again to show that $\{\mathbf{Q}^m\}_{m\in\mathbb{N}}$ is bounded in $L^2(0, T; W^{1,2}(\Omega; \mathcal{S}_0)) \cap L^4(0, T; L^4(\Omega; \mathcal{S}_0))$, and $\{\varphi^m\}_{m\in\mathbb{N}}$ is bounded in $L^2(0, T; H^1(\Omega))$. Note that $\{(\operatorname{tr}(\mathbf{Q}^m)^2)\mathbf{Q}^m\}_{m\in\mathbb{N}}$ is bounded in $L^{\frac{4}{3}}((0, T) \times \Omega))$.

We can extract a subsequence (not relabeled) $\{(\mathbf{Q}^m,\varphi^m)\}_{m\in\mathbb{N}}$ such that

(3.1)
$$\begin{cases} \mathbf{Q}^m \to \bar{\mathbf{Q}} \text{ weakly in } L^2(0,T; W^{1,2}(\Omega; \mathcal{S}_0)), \\ \mathbf{Q}^m \to \bar{\mathbf{Q}} \text{ weakly in } L^4(0,T; L^4(\Omega; \mathcal{S}_0)), \\ (\operatorname{tr}(\mathbf{Q}^m)^2) \mathbf{Q}^m \to \mathbf{P} \text{ weakly in } L^{\frac{4}{3}}((0,T) \times \Omega)), \\ \varphi^m \to \bar{\varphi} \text{ weakly in } L^2(0,T; H^1(\Omega)). \end{cases}$$

Using the Sobolev imbedding $W^{1,2} \subset L^4[5]$, we obtain imbeddings

$$L^{4}(0,T;W^{1,2}(\Omega;\mathcal{S}_{0})) \hookrightarrow L^{4}((0,T) \times \Omega;\mathcal{S}_{0}),$$
$$L^{\frac{4}{3}}((0,T) \times \Omega;\mathcal{S}_{0}) \hookrightarrow L^{\frac{4}{3}}(0,T;[W^{1,2}(\Omega;\mathcal{S}_{0})]').$$

It follows that $\left\{\frac{\partial \mathbf{Q}^m}{\partial t}\right\}_{m\in\mathbb{N}}$ is bounded in $L^{\frac{4}{3}}(0,T; \left[W^{1,2}(\Omega;\mathcal{S}_0)\right]')$. Since $\{\mathbf{Q}^m\}_{m\in\mathbb{N}}$ is bounded in $L^2(0,T;W^{1,2}(\Omega;\mathcal{S}_0))$, Aubin's compactness shows that

$$\mathbf{Q}^m \to \bar{\mathbf{Q}}$$
 strongly in $L^2(0,T; L^2(\Omega; \mathcal{S}_0))$.

This concludes that $(\operatorname{tr} \bar{\mathbf{Q}}^2)\bar{\mathbf{Q}} = \mathbf{P}$, and therefore $(\bar{\mathbf{Q}}, \bar{\varphi})$ is a weak solution pair.

COROLLARY 1. There exists a weak solution pair (\mathbf{Q}, φ) which belongs to $L^2(0, \infty; W^{1,2}(\Omega; \mathcal{S}_0) \times L^2(0, \infty; H^1(\Omega))$ to (1.4),(1.5), and (1.6).

Proof. As in the proof of lemma 2.1, multiplying (1.4), (1.5) by **Q** and φ followed by integration by parts we obtain (3.2)

$$\int_{\Omega} \left(L |\nabla \mathbf{Q}|^2 + A \operatorname{tr} \mathbf{Q}^2 - B \operatorname{tr} \mathbf{Q}^3 + C (\operatorname{tr} \mathbf{Q}^2)^2 + \frac{1}{2} \left(\epsilon(\mathbf{Q}) \nabla \varphi \right) \cdot \nabla \varphi \right) dx$$
$$+ \frac{d}{dt} \int_{\Omega} |\mathbf{Q}|^2 dx = 0$$

Since C > 0, there exists \mathcal{D} such that $A \operatorname{tr} \mathbf{Q}^2 - B \operatorname{tr} \mathbf{Q}^3 + C(\operatorname{tr} \mathbf{Q}^2)^2 \geq -\mathcal{D}$. It follows from (3.2) and the Poincare inequality that

$$\frac{d}{dt} \int_{\Omega} |\mathbf{Q}|^2 \, dx + \mathcal{M} \int_{\Omega} |\mathbf{Q}|^2 \, dx \le \mathcal{D}|\Omega|,$$

where $\mathcal{M} = \frac{L}{\mathcal{K}} > 0$ with the Poincare constant \mathcal{K} . By Grownwall's inequality we have

$$||\mathbf{Q}(t)||_{L^2} \le ||\mathbf{Q}(0)||_{L^2} e^{-\mathcal{M}t} + \frac{\mathcal{D}|\Omega|}{\mathcal{M}} \left(1 - e^{-\mathcal{M}t}\right).$$

Therefore $\sup_{0 \le t < \infty} ||\mathbf{Q}(t)||_{L^2} \le \frac{\mathcal{D}|\Omega|}{\mathcal{M}}$ and the proof is complete. \Box

Next, we prove that such a weak solution is unique and it converges to an equilibrium solution of the energy functional \mathcal{E} .

THEOREM 3.2. If $\epsilon_1 = \epsilon_2 = 0$ in (1.5), then there exists a unique weak solution to (1.4),(1.5), and (1.6).

Proof. Let $(\mathbf{Q}_1, \varphi_1)$ and $(\mathbf{Q}_2, \varphi_2)$ be two weak solutions. Then

$$\begin{split} \frac{1}{2} \frac{d}{dt} \int_{\Omega} |\mathbf{Q}|^2 \, dx + \int_{\Omega} \left[L |\nabla \mathbf{Q}|^2 + \left(f'_{bulk}(\mathbf{Q}_1) - f'_{bulk}(\mathbf{Q}_2) \right) \cdot \mathbf{Q} \right] \\ &= \frac{1}{2} \epsilon_3 \int_{\Omega} \nabla \varphi \cdot (\nabla \cdot \mathbf{Q}) \, dx, \\ \int_{\Omega} \left(\epsilon_0 \nabla \varphi \right) \cdot \nabla \varphi \, dx = -\epsilon_3 \int_{\Omega} (\nabla \cdot \mathbf{Q}) \cdot \nabla \varphi \, dx, \end{split}$$

where $\mathbf{Q} = \mathbf{Q}_1 - \mathbf{Q}_2$, $\varphi = \varphi_1 - \varphi_2$. Plugging the second equation into the first one, we get

$$\frac{1}{2}\frac{d}{dt}\int_{\Omega} |\mathbf{Q}|^2 dx + \int_{\Omega} \left(L|\nabla \mathbf{Q}|^2 + \frac{1}{2}\epsilon_0|\nabla \varphi|^2\right) dx$$
$$= \int_{\Omega} \left[\left(f'_{bulk}(\mathbf{Q}_1) - f'_{bulk}(\mathbf{Q}_2)\right) \cdot \mathbf{Q} \right] dx$$
$$\leq M \int_{\Omega} |\mathbf{Q}|^2 dx \text{ for some } M > 0.$$

Hence $||\mathbf{Q}||_{L^2} \le ||Q(0)||_{L^2} e^t = 0$ so that $\mathbf{Q}_1 = \mathbf{Q}_2$ and $\varphi_1 = \varphi_2$.

THEOREM 3.3. If $\mathbf{Q}_0 \in W^{1,2}(\Omega, \mathcal{S}_0)$, then there is a subsequence of solutions to (1.4) which converges to a solution of the steady state problem as $t \to \infty$.

Proof. Multiplying individual equation by $\frac{\partial Q_{ij}}{\partial t}$ and integrating by parts followed by summing up, we obtain

$$\int_{\Omega} |\mathbf{Q}_t|^2 = -\frac{d}{dt} \int_{\Omega} \left[\frac{L}{2} |\nabla \mathbf{Q}|^2 + A \operatorname{tr} \mathbf{Q}^2 - B \operatorname{tr} \mathbf{Q}^3 + C \left(\operatorname{tr} \mathbf{Q}^2 \right)^2 \right] dx$$
$$+ \epsilon_3 \int_{\Omega} \nabla \cdot \mathbf{Q}_t \cdot \nabla \varphi \, dx - \frac{d}{dt} \int_{\Omega} |\nabla \varphi|^2 \, dx$$
$$= \epsilon_3 \int_{\Omega} \nabla \cdot \mathbf{Q}_t \cdot \nabla \varphi \, dx.$$

Then

$$\int_{\Omega} |\mathbf{Q}_t|^2$$

= $-\frac{d}{dt} \int_{\Omega} \left[\frac{L}{2} |\nabla \mathbf{Q}|^2 + A \operatorname{tr} \mathbf{Q}^2 - B \operatorname{tr} \mathbf{Q}^3 + C \left(\operatorname{tr} \mathbf{Q}^2 \right)^2 + |\nabla \varphi|^2 \right] dx$

and

$$\begin{split} &\int_{0}^{T} \int_{\Omega} |\mathbf{Q}_{t}|^{2} \, dx \, dt \\ &= -\int_{\Omega} \left[\frac{L}{2} |\nabla \mathbf{Q}|^{2} + A \mathrm{tr} \, \mathbf{Q}^{2} - B \, \mathrm{tr} \, \mathbf{Q}^{3} + C \left(\mathrm{tr} \, \mathbf{Q}^{2} \right)^{2} + |\nabla \varphi|^{2} \right]_{t=T} \, dx \\ &+ \int_{\Omega} \left[\frac{L}{2} |\nabla \mathbf{Q}|^{2} + A \mathrm{tr} \, \mathbf{Q}^{2} - B \, \mathrm{tr} \, \mathbf{Q}^{3} + C \left(\mathrm{tr} \, \mathbf{Q}^{2} \right)^{2} + |\nabla \varphi|^{2} \right]_{t=0} \, dx \\ &\leq \int_{\Omega} \left[\frac{L}{2} |\nabla \mathbf{Q}|^{2} + A \mathrm{tr} \, \mathbf{Q}^{2} - B \, \mathrm{tr} \, \mathbf{Q}^{3} + C \left(\mathrm{tr} \, \mathbf{Q}^{2} \right)^{2} + |\nabla \varphi|^{2} \right]_{t=0} \, dx \\ &+ M |\Omega|, \end{split}$$

where M is the minimum value of $A \operatorname{tr} \mathbf{Q}^2 - B \operatorname{tr} \mathbf{Q}^3 + C (\operatorname{tr} \mathbf{Q}^2)^2$. Hence we obtain $\mathbf{Q}_t \in L^2(0, \infty; L^2(\Omega; \mathcal{S}_0))$. This shows that

$$\int_{\Omega} |\mathbf{Q}_t(x,t_i)|^2 \, dx \to 0 \text{ as } i \to \infty,$$

for almost all sequence $\{t_i\}_{i\in\mathbb{N}}$ satisfying $t_i \to \infty$ as $i \to \infty$. Furthermore, we also get

$$(\nabla \mathbf{Q}, \nabla \varphi) \in L^{\infty}(0, \infty; L^2(\Omega; \mathcal{S}_0)) \times L^{\infty}(0, \infty; L^2(\Omega)).$$

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By Poincare inequality, we have

 $(\mathbf{Q}, \varphi) \in L^{\infty}(0, \infty; W^{1,2}(\Omega; \mathcal{S}_0)) \times L^{\infty}(0, \infty; W^{1,2}(\Omega))$

and there is a sequence $\{t_i\}_{i\in\mathbb{N}}$ with $t_i \to \infty$ as $i \to \infty$ such that

$$(\mathbf{Q}(x,t_i),\varphi(x,t_i)) \rightarrow (\mathbf{Q},\bar{\varphi})$$
 weakly in $W^{1,2}$ as $t_i \rightarrow \infty$.

Since (\mathbf{Q}, φ) is a weak solution pair,

$$\begin{cases} \left\langle \frac{\partial \mathbf{Q}}{\partial t}, \tilde{\mathbf{Q}} \right\rangle + \left\langle L \nabla \mathbf{Q} + A \mathbf{Q} - B \operatorname{tr} \mathbf{Q}^2 + C(\operatorname{tr} \mathbf{Q}^2) \mathbf{Q}, \nabla \tilde{\mathbf{Q}} \right\rangle \\ + \epsilon \left\langle \nabla \varphi, \nabla \cdot \tilde{\mathbf{Q}} \right\rangle = 0, \\ \int_{\Omega} \left(\nabla \varphi \cdot \nabla \psi + \nabla \cdot \mathbf{Q} \cdot \nabla \psi \right) \, dx = 0, \end{cases}$$

for all $\tilde{\mathbf{Q}} \in W^{1,2}(\Omega, \mathcal{S}_0), \psi \in W^{1,2}(\Omega)$. Passing to the limit as $t_i \to \infty$, we obtain

$$\begin{cases} \int_{\Omega} \left(L\nabla \bar{\mathbf{Q}} + A\bar{\mathbf{Q}} - B\mathrm{tr}\,\bar{\mathbf{Q}}^2 + C(\mathrm{tr}\,\bar{\mathbf{Q}}^2)\bar{\mathbf{Q}} \right) \cdot \nabla \tilde{\mathbf{Q}} \\ +\epsilon \int_{\Omega} \nabla \bar{\varphi} \cdot (\nabla \cdot \tilde{\mathbf{Q}})\,dx = 0, \\ \int_{\Omega} \left(\nabla \bar{\varphi} \cdot \nabla \psi + \nabla \cdot \bar{\mathbf{Q}} \cdot \nabla \psi \right)\,dx = 0. \end{cases}$$

This completes the proof.

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