

Isoparametric Curve of Quadratic F-Bézier Curve

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Abstract

In this thesis, we consider isoparametric curves of quadratic F-Bézier curves. F-Bézier curves unify C-Bézier curves whose basis is $\{\sin t, \cos t, t, 1\}$ and H-Bézier curves whose basis is $\{\sinh t, \cosh t, t, 1\}$. Thus F-Bézier curves are more useful in Geometric Modeling or CAGD(Computer Aided Geometric Design). We derive the relation between the quadratic F-Bézier curves and the quadratic rational Bézier curves. We also obtain the geometric properties of isoparametric curve of the quadratic F-Bézier curves at both end points and prove the continuity of the isoparametric curve.

Key words : F-Bézier Curve, Quadratic Rational Bézier Curve, Isoparametric Curve, Q-Bézier Curve, H-Bézier Curve

1. Introduction

C-Bézier curve^[1,2] is an extension of Beizer curve using $\cos(t)$ and $\sin(t)$, which is used to express circular arc, ellipse, cycloid and helix. Zhang developed the C-B-spline from the C-Bézier curves^[3] and C-Bézier curves and surfaces^[4]. It is more advantage of F-Bézier curve than rational Bézier curve to able to express helix or cycloid^[5]. Chen and Wang^[6] presented C-Bézier curves of higher degree.

H-Bézier curve^[7] is the curve combined by Bézier curve and hyperbolic functions $\cosh(t)$, $\sinh(t)$. Zhang and Krause^[8] unified these curves into F-Bézier curve. Zhang et al.^[9] also unified the coefficient of F-Bézier curves using complex number.

Every quadratic F-Bézier curve has the same graph of a quadratic rational Bézier curve, and vice versa. Any isoparametric curve of quadratic Bézier curves is a straight line, but that of F-Bézier curves is not. So we study the isoparametric curve of quadratic F-Bézier curves in this paper. We show that the isoparametric curve is tangent to the polygon at the end point of the curve, or a straight line. We also prove that the iso-

parametric curves are C^1 continuous but not twice differentiable.

This paper is constructed as follows. In Section 2, the well-known facts about the quadratic rational Bézier curves and the quadratic F-Bézier curves are given. In Section 3, we present some geometric properties of F-Bézier curves, and we summary them in Section 4.

2. Prior Works

In this section we remind the definition and properties of quadratic rational Bézier curve and quadratic F-Bezier curve.

The quadratic rational Bézier curve is well introduced by Farin^[10].

Definition 2.1 Quadratic rational Bézier curve is

$$r(t) = \frac{\sum_{i=0}^2 w_i B_i^2(t) \mathbf{b}_i}{\sum_{i=0}^2 w_i B_i^2(t)}$$

where $\mathbf{b}_i, i = 0, 1, 2$, is control point, $w_i > 0$ is weight, and $B_i^2(t) = \binom{2}{i} t^i (1-t)^{2-i}$ is the quadratic Bernstein polynomial. If $w_0 = w_2 = 1$, the quadratic Bézier curve is called by standard form.

Any quadratic rational Bézier curve $r(t)$ with control points \mathbf{b}_i and weights $w_i (i = 0, 1, 2)$ can be reparametrized

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by standard form with new weights $1, \frac{w_1}{\sqrt{w_0 w_2}}, 1$ without change of graph^[6]. Actually, using the reparametrization

$$t(s) = \frac{s}{\rho(1-s) + s}, \rho = \sqrt{\frac{w_2}{w_0}}$$

new reparametrized quadratic Bézier curve is obtained by

$$\begin{aligned} \hat{r}(s) &= r(t(s)) \\ &= \frac{\rho^2 w_0 B_0^2(s) \mathbf{b}_0 + \rho w_1 B_1^2(s) \mathbf{b}_1 + w_2 B_2^2(s) \mathbf{b}_2}{\rho^2 w_0 B_0^2(s) + \rho w_1 B_1^2(s) + w_2 B_2^2(s)} \end{aligned}$$

which is a standard quadratic rational Bézier curve. $r(t(s))$ and $\hat{r}(s)$ have the same graph. Thus any quadratic rational Bézier curve can be rewritten by the standard form

$$r(t) = \frac{B_0^2(t) \mathbf{b}_0 + w B_1^2(t) \mathbf{b}_1 + B_2^2(t) \mathbf{b}_2}{B_0^2(t) + w B_1^2(t) + B_2^2(t)}$$

where $w = \frac{w_1}{\sqrt{w_0 w_2}}$. It is well known that $w < 1$ iff r is ellipse, $w = 1$ iff r is parabola, and $w > 1$ iff r is hyperbola, as shown in Fig. 1^[10].

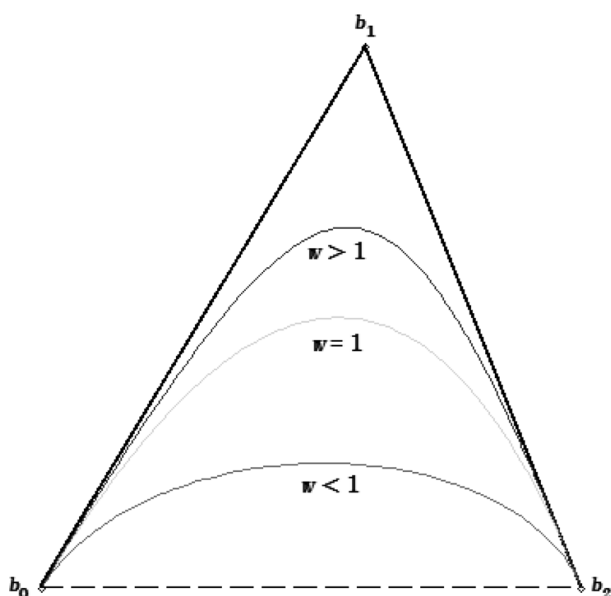


Fig. 1. Quadratic rational Bézier curves with weight $w < 1$ (ellipse), $w = 1$ (parabola), or $w > 1$ (hyperbola). $[\mathbf{b}_0, \mathbf{b}_1, \mathbf{b}_2]$ is control polygon (black).

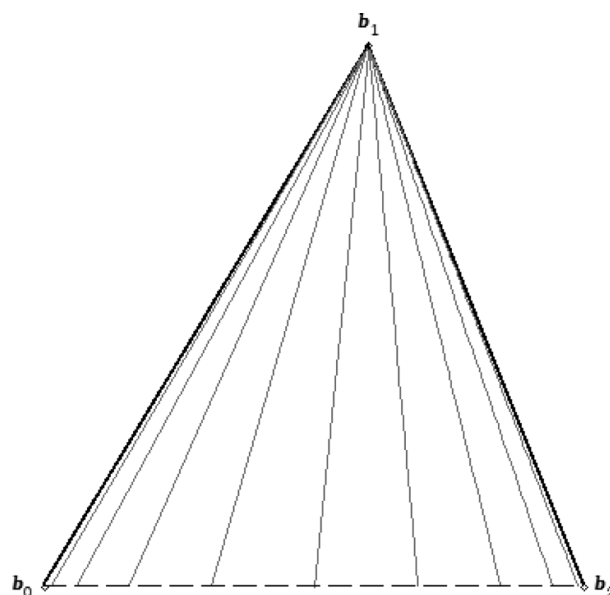


Fig. 2. isoparametric curves of quadratic rational Bézier curves: $r^*(w, t_0)$ for $t_0 = \frac{i}{10}, (i = 1, 2, \dots, 9)$.

It is well known that the function $r^*: (0, 1) \times (0, \infty) \rightarrow \Delta_{\mathbf{p}_0 \mathbf{p}_1 \mathbf{p}_2}$ defined by $r^*(w, t) = r(t)$ is homeomorphic on $(0, 1) \times (0, \infty)$. For each $t_0 \in (0, 1)$, the isoparametric curve is

$$r^*(w, t_0) = \mathbf{b}_1 + \frac{B_0^2(t_0)(\mathbf{b}_0 - \mathbf{b}_1) + B_2^2(t_0)(\mathbf{b}_2 - \mathbf{b}_1)}{B_0^2(t_0) + w B_1^2(t_0) + B_2^2(t_0)}$$

Hence $r^*(w, t_0)$ is a straight line between the two points $\frac{B_0^2(t_0) \mathbf{b}_0 + B_2^2(t_0) \mathbf{b}_2}{B_0^2(t_0) + B_2^2(t_0)}$ and \mathbf{b}_1 as shown in Fig. 2.

In what follows, we will need to consider the implicit form of a conic section. Any point $(x, y) \in \mathbb{R}^2$ can be written uniquely in terms of barycentric coordinates (τ_0, τ_1, τ_2) , where $\tau_0 + \tau_1 + \tau_2 = 1$, with respect to the triangle $\Delta_{\mathbf{p}_0 \mathbf{p}_1 \mathbf{p}_2} : (x, y) = \tau_0 \mathbf{p}_0 + \tau_1 \mathbf{p}_1 + \tau_2 \mathbf{p}_2$. Consequently any function $f : \Delta_{\mathbf{b}_0 \mathbf{b}_1 \mathbf{b}_2} \rightarrow \mathbb{R}$ can be expressed as a function of τ_0, τ_1, τ_2 . The following lemma is well known^[10,11].

Lemma 2.2 Let r be a quadratic rational Bézier curve with control points $\mathbf{b}_0, \mathbf{b}_1, \mathbf{b}_2$ and weight w and let f be defined as

$$f(x, y) = \tau_1^2 - 4w^2 \tau_0 \tau_2.$$

Then r satisfies the equation $f(r(t)) = 0$ for all $t \in [0, 1]$.

Zhang and Krause^[9] unified the C-Bézier curve and H-Bézier curve, which is called F-Bézier curve.

Definition 2.3 The F-Bézier curve of degree n with a parameter $\alpha \in (-\pi, \infty)$ is

$$q(t) = \sum_{i=0}^n Z_i^n(t) q_i$$

where $q_i, i = 0, 1, \dots, n$, is control point, and Z_i^n is the F-basis functions defined by

$$Z_1^1(t) = \begin{cases} \frac{\sin(\alpha t)}{\sin(\alpha)} & (-\pi < \alpha < 0) \\ t & (\alpha = 0) \\ \frac{\sinh(\alpha t)}{\sinh(\alpha)} & (\alpha > 0) \end{cases}$$

$$Z_0^1(t) = Z_1^1(1-t)$$

and recursively

$$W_i^n(t) = \alpha \int_0^t Z_i^n(t) dt$$

$$(0 \leq i \leq n, n \geq 1)$$

$$Z_n^n(t) = \frac{W_{n-1}^{n-1}(t)}{W_{n-1}^{n-1}(1)}$$

$$Z_0^n(t) = 1 - \frac{W_0^{n-1}(t)}{W_0^{n-1}(1)}$$

$$Z_i^n(t) = \frac{W_{i-1}^{n-1}(t)}{W_{i-1}^{n-1}(1)} - \frac{W_i^{n-1}(t)}{W_i^{n-1}(1)}$$

$$(1 \leq i \leq n-1, n \geq 2).$$

In this paper we concentrate the quadratic F-Bézier curve, which can be rewritten as follows.

Definition 2.4 The quadratic F-Bézier curve is

$$q(t) = \sum_{i=0}^2 Z_i^2(t) q_i$$

where $q_i, i = 0, 1, 2$, is control point, and Z_i^2 is quadratic F-basis functions defined by

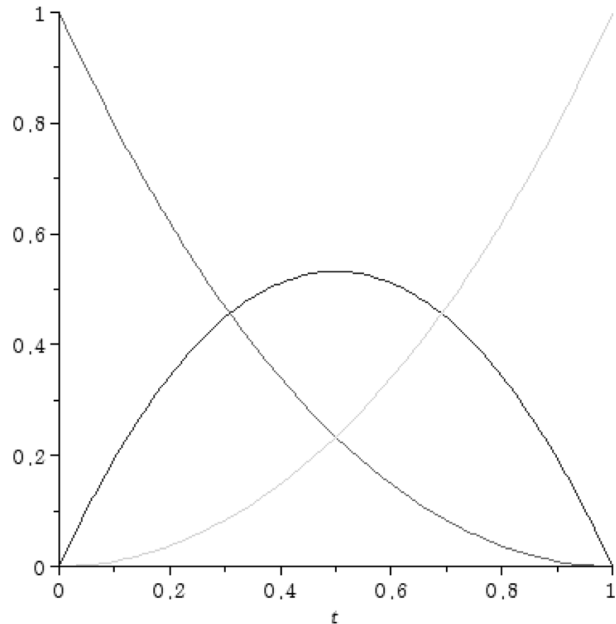


Fig. 3. Basis functions of quadratic F-Bézier curve for $\alpha = \pi/3$: $Z_0^2(t)$ (red), $Z_1^2(t)$ (blue), $Z_2^2(t)$ (green).

$$Z_2^2(t) = \begin{cases} \frac{1 - \cos(\alpha t)}{1 - \cos\alpha} & (-\pi < \alpha < 0) \\ t^2 & (\alpha = 0) \\ \frac{1 - \cosh(\alpha t)}{1 - \cosh\alpha} & (\alpha > 0) \end{cases}$$

and

$$Z_0^2(t) = Z_2^2(1-t)$$

$$Z_1^2(t) = 1 - Z_0^2(t) - Z_2^2(t).$$

As shown in Fig. 3, the basis functions $Z_i^2(t), i = 0, 1, 2$ satisfy the partition of unity, so the quadratic F-Bézier curves satisfy convex-hull property.

3. Relation between F-Bézier Curve and Quadratic Rational Bézier Curve

In this section we present some geometric properties of the isoparametric curves of the quadratic F-Bézier curves. The results in this section is an improvement of the results in the thesis^[12] of the first author in this paper. We consider the nonlinear control polygons of F-Bézier curve and quadratic rational Bézier curves

$$q_0, q_1, q_2 \text{ and } b_0, b_1, b_2.$$

Proposition 3.1 F-Bézier curve has the same graph of quadratic rational Bézier curve if and only if $q_i = b_i$ ($i = 0, 1, 2$), and

$$w = \begin{cases} \cos(\alpha/2) & (-\pi < \alpha \leq 0) \\ \cosh(\alpha/2) & (\alpha > 0). \end{cases}$$

proof. By Definition 2.4, $q(t)$ has the barycentric coordinates $(Z_0^2(t), Z_1^2(t), Z_2^2(t))$, and by Lemma 2.2, $q(t)$ is a conic section iff $Z_1^2(t)/2\sqrt{Z_0^2(t)Z_2^2(t)}$ is a constant which is equal to the weight of the conic.

For $-\pi < \alpha < 0$,

$$\begin{aligned} & \frac{Z_1^2(t)}{2\sqrt{Z_0^2(t)Z_2^2(t)}} \\ &= \frac{1 - \frac{1 - \cos(\alpha t)}{1 - \cos\alpha} - \frac{1 - \cos(\alpha(1-t))}{1 - \cos\alpha}}{2\sqrt{\frac{1 - \cos(\alpha t)}{1 - \cos\alpha} \cdot \frac{1 - \cos(\alpha(1-t))}{1 - \cos\alpha}}} \\ &= \frac{\cos(\alpha t) - \cos\alpha + \cos(\alpha(1-t)) - 1}{2\sqrt{(1 - \cos(\alpha t)) \cdot (1 - \cos(\alpha(1-t)))}} \\ &= -\frac{1}{2} \frac{\sin\left(\frac{\alpha t + \alpha}{2}\right) \sin\left(\frac{\alpha t - \alpha}{2}\right) + \sin^2\left(\frac{\alpha(1-t)}{2}\right)}{\sin\frac{\alpha t}{2} \cdot \sin\frac{\alpha(1-t)}{2}} \\ &= \frac{1}{2} \frac{\sin\left(\frac{\alpha t + \alpha}{2}\right) - \sin\left(\frac{\alpha(1-t)}{2}\right)}{\sin\left(\frac{\alpha t}{2}\right)} \\ &= \frac{1}{2} \frac{2\cos\left(\frac{\alpha}{2}\right) \sin\left(\frac{\alpha t}{2}\right)}{\sin\left(\frac{\alpha t}{2}\right)} = \cos\left(\frac{\alpha}{2}\right). \end{aligned}$$

For $\alpha = 0$, trivially $Z_1^2(t)/2\sqrt{Z_0^2(t)Z_2^2(t)} = 1$.

For $\alpha > 0$, by the identity $\cosh(x) = \cos(ix)$,

$$\begin{aligned} & \frac{Z_{1,2}^2(t)}{2\sqrt{Z_{0,2}^2(t)Z_{2,2}^2(t)}} \\ &= \frac{\cosh(\alpha t) - \cosh\alpha + \cosh(\alpha(1-t)) - 1}{2\sqrt{(1 - \cosh(\alpha t)) \cdot (1 - \cosh(\alpha(1-t)))}} \\ &= \cosh\left(\frac{\alpha}{2}\right). \end{aligned}$$

Corollary 3.2 If $q_i = b_i$ ($i = 0, 1, 2$), and

$$w = \begin{cases} \cos(\alpha/2) & (-\pi < \alpha \leq 0) \\ \cosh(\alpha/2) & (\alpha > 0), \end{cases}$$

then for all $t \in [0, 1]$

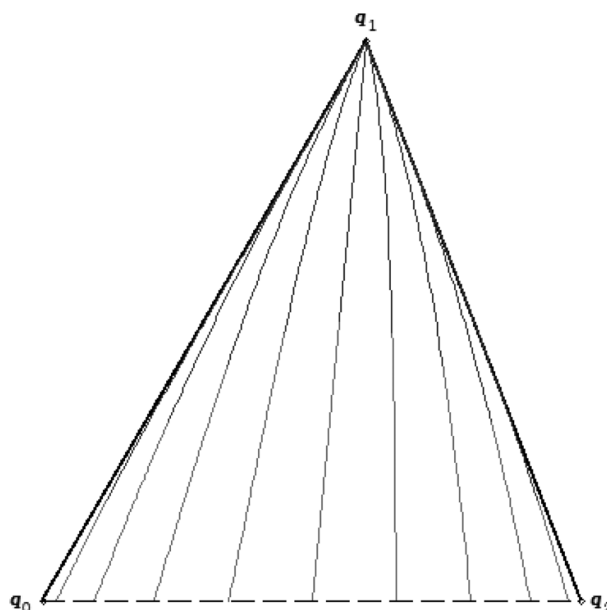


Fig. 4. Isoparametric curves of quadratic F-Bézier curves: $q^*(\alpha, t_0)$ for $t_0 = \frac{i}{10}$, ($i = 1, 2, \dots, 9$), for $-\pi < \alpha < 0$ (red) and $0 < \alpha < \infty$ (blue).

$$r(t) = \begin{cases} q(\arccos(1 - \mu_2(t)(1 - \cos\alpha))/\alpha) \\ q(\operatorname{arccosh}(1 - \mu_2(t)(1 - \cosh\alpha))/\alpha), \end{cases}$$

respectively, where

$$\mu_2(t) = \frac{B_2^2(t)}{B_0^2(t) + wB_1^2(t) + B_2^2(t)}.$$

Actually there are two parameters $\alpha \in (-\pi, \infty)$ and $t \in [0, 1]$ in the F-Bézier curve $q(t)$. Let the isoparametric curve $q(t_0)$ with $\alpha \in (-\pi, \infty)$ denoted by $q^*(\alpha, t_0)$, as shown Fig. 4. If $t_0 = 0$ or 1, the the isoparametric curve $q^*(\alpha, t_0)$ is a one point q_0 or q_2 .

Proposition 3.3 For each $t_0 \in (0, 1)$, the isoparametric curve $q^*(\alpha, t_0)$ starts at $q^*(-\pi, t_0) = \frac{1}{2}((1 + \cos(\pi t_0))q_0 + (1 - \cos(\pi t_0))q_2)$ and ends at q_1 .

proof. By Definition 2.4,

$$\begin{aligned} \lim_{\alpha \rightarrow -\pi} Z_2^2(t) &= \frac{1 - \cos(\pi t)}{2} \\ \lim_{\alpha \rightarrow -\pi} Z_0^2(t) &= \frac{1 + \cos(\pi t)}{2} \\ \lim_{\alpha \rightarrow -\pi} Z_1^2(t) &= 0 \end{aligned}$$

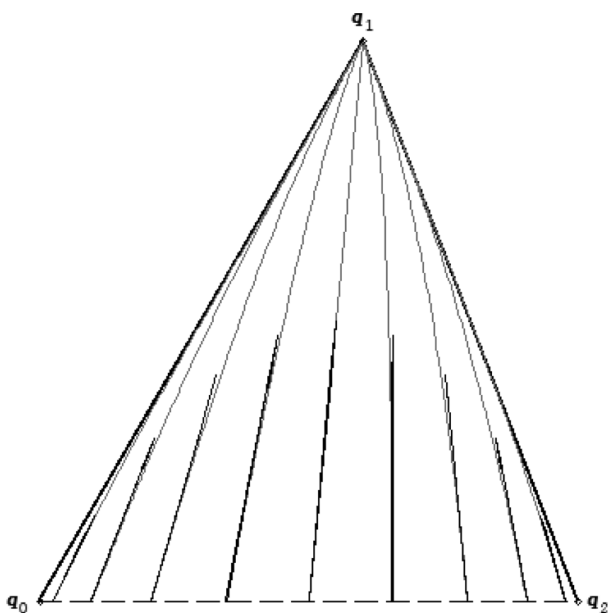


Fig.5. Tangent vectors(blue) of isoparametric curves(red) of F-Bézier curves $\mathbf{q}^*(\alpha, t_0)$ at $\alpha = -\pi$.

so the start point is

$$\mathbf{q}^*(-\pi, t_0) = \frac{(1 + \cos(\pi t_0)) \mathbf{q}_0 + (1 - \cos(\pi t_0)) \mathbf{q}_2}{2}$$

and by

$$\begin{aligned} \lim_{\alpha \rightarrow \infty} Z_2^2(t) &= \lim_{\alpha \rightarrow \infty} \frac{1 - \cosh(\alpha t)}{1 - \cosh \alpha} = 0 \\ \lim_{\alpha \rightarrow -\pi} Z_0^2(t) &= \lim_{\alpha \rightarrow \infty} \frac{1 - \cosh(\alpha(1-t))}{1 - \cosh \alpha} = 0 \\ \lim_{\alpha \rightarrow -\pi} Z_1^2(t) &= 1, \end{aligned}$$

the end point is $\lim_{\alpha \rightarrow \infty} \mathbf{q}^*(\alpha, t_0) = \mathbf{q}_1$.

Let D_α be the partial derivative with respect to α , and let $Z_i^*(\alpha, t) = Z_i^2(t)$ for $i = 0, 1, 2$.

Proposition 3.4 For each $t_0 \in (0, 1)$, the isoparametric curve $\mathbf{q}^*(\alpha, t_0)$ is of tangent direction $\frac{1}{2} \sin(\pi t_0) (\mathbf{q}_1 - (1 - t_0)\mathbf{q}_0 - t_0\mathbf{q}_2)$ at the start point $\mathbf{q}^*(-\pi, t_0)$.

proof. Since for $\alpha \in (-\pi, 0)$

$$D_\alpha Z_2^*(\alpha, t) = \frac{\sin(\alpha t) t}{1 - \cos \alpha} - \frac{(1 - \cos(\alpha t)) \sin \alpha}{(1 - \cos \alpha)^2}$$

we have

$$\lim_{\alpha \rightarrow -\pi} D_\alpha Z_2^*(\alpha, t) = -\frac{\sin(\pi t) t}{2}$$

and so

$$\lim_{\alpha \rightarrow -\pi} D_\alpha Z_0^*(\alpha, t) = -\frac{\sin(\pi t) (1-t)}{2}$$

$$\lim_{\alpha \rightarrow -\pi} D_\alpha Z_1^*(\alpha, t) = \frac{\sin(\pi t)}{2}.$$

By Definition 2.4,

$$D_\alpha \mathbf{q}^*(-\pi, t_0) = \frac{\sin(\pi t_0)}{2} (\mathbf{q}_1 - (1 - t_0)\mathbf{q}_0 - t_0\mathbf{q}_2).$$

Theorem 3.5 For each $t_0 \in (0, 1)$, the isoparametric curve $\mathbf{q}^*(\alpha, t_0)$ is tangent to $\overline{\mathbf{q}_0\mathbf{q}_1}$, $\overline{\mathbf{m}\mathbf{q}_1}$, or $\overline{\mathbf{q}_2\mathbf{q}_1}$ at \mathbf{q}_1 iff $0 < t_0 < 1/2$, $t_0 = 1/2$ or $1/2 < t_0 < 1$, respectively, where $\mathbf{m} = (\mathbf{q}_0 + \mathbf{q}_2)/2$. Moreover, $\mathbf{q}^*(\alpha, 1/2)$, $\alpha \in [-\pi, \infty)$ is a line segment $\overline{\mathbf{m}\mathbf{q}_1}$.

proof. For $\alpha > 0$, from Definition 2.4,

$$D_\alpha Z_2^*(\alpha, t) = -\frac{\sinh(\alpha t) t}{1 - \cosh \alpha} + \frac{(1 - \cosh(\alpha t)) \sinh \alpha}{(1 - \cosh \alpha)^2}$$

and so

$$\begin{aligned} D_\alpha Z_0^*(\alpha, t) &= -\frac{\sinh(\alpha(1-t)) (1-t)}{1 - \cosh \alpha} \\ &\quad + \frac{(1 - \cosh(\alpha(1-t))) \sinh \alpha}{(1 - \cosh \alpha)^2} \end{aligned}$$

$$D_\alpha Z_1^*(\alpha, t) = -D_\alpha Z_0^*(\alpha, t) - D_\alpha Z_2^*(\alpha, t).$$

Thus $\lim_{\alpha \rightarrow \infty} \frac{D_\alpha Z_0^*(\alpha, t)}{D_\alpha Z_2^*(\alpha, t)} = \infty, 1,$ or 0 iff $t < \frac{1}{2}$,

$t_0 = \frac{1}{2}$, or $t > \frac{1}{2}$, respectively. If $0 < t_0 < \frac{1}{2}$,

then

$$\lim_{t \rightarrow \infty} \frac{D_\alpha Z_1^*(\alpha, t)}{D_\alpha Z_0^*(\alpha, t)} = -1,$$

so that

$$\begin{aligned} \lim_{t \rightarrow \infty} \frac{D_\alpha \mathbf{q}^*(\alpha, t)}{D_\alpha Z_0^*(\alpha, t)} &= \lim_{t \rightarrow \infty} \frac{D_\alpha Z_0^*(\alpha, t)\mathbf{q}_0 + D_\alpha Z_1^*(\alpha, t)\mathbf{q}_1 + D_\alpha Z_2^*(\alpha, t)\mathbf{q}_2}{D_\alpha Z_0^*(\alpha, t)} \\ &= \mathbf{q}_0 - \mathbf{q}_1. \end{aligned}$$

If $1/2 < t_0 < 1$, then

$$\lim_{t \rightarrow \infty} \frac{D_\alpha Z_1^*(\alpha, t)}{D_\alpha Z_2^*(\alpha, t)} = -1,$$

so that

$$\lim_{t \rightarrow \infty} \frac{D_\alpha \mathbf{q}^*(\alpha, t)}{D_\alpha Z_2^*(\alpha, t)} = \mathbf{q}_2 - \mathbf{q}_1.$$

If $t_0 = 1/2$, then $Z_0^*(\alpha, 1/2) = Z_2^*(\alpha, 1/2)$ and $\mathbf{q}^*(\alpha, 1/2) = 2Z_0^*(\alpha, 1/2)\mathbf{m} + (1 - 2Z_0^*(\alpha, 1/2))\mathbf{q}_1$.

Since $Z_0^*(\alpha, 1/2) \in (0, 1/2]$ for $\alpha \in [-\pi, \infty)$, the isoparametric curve $\mathbf{q}^*(\alpha, 1/2)$ is a line segment $\overline{\mathbf{m}\mathbf{q}_1}$.

Thus the isoparametric curve $\mathbf{q}^*(\alpha, t_0)$ is tangent to $\overline{\mathbf{q}_0\mathbf{q}_1}$, $\overline{\mathbf{m}\mathbf{q}_1}$, or $\overline{\mathbf{q}_1\mathbf{q}_2}$ at \mathbf{q}_1 iff $0 < t_0 < 1/2$, $t_0 = 1/2$ or $1/2 < t_0 < 1$, respectively.

Proposition 3.6 For each $t_0 \in (0, 1)$, the isoparametric curve $\mathbf{q}^*(\alpha, t_0)$, $\alpha \in (-\pi, \infty)$ is a C^1 continuous curve.

proof. It is sufficient to show that $\mathbf{q}^*(\alpha, t_0)$ is continuous and differentiable at $\alpha = 0$. By the series expansion

$$\frac{1 - \cos(\alpha t)}{1 - \cos\alpha} = \frac{\frac{t^2}{2!}\alpha^2 - \frac{t^4}{4!}\alpha^4 + \dots}{\frac{\alpha^2}{2!} - \frac{\alpha^4}{4!} + \dots} = \frac{t^2 - \frac{2t^4}{4!}\alpha^2 + \dots}{1 - \frac{2\alpha^2}{4!} + \dots}$$

$$= t^2 + \frac{t^2(1-t^2)}{12}\alpha^2 + O(\alpha^4)$$

$$\frac{1 - \cosh(\alpha t)}{1 - \cosh\alpha} = t^2 - \frac{t^2(1-t^2)}{12}\alpha^2 + O(\alpha^4)$$

we have

$$Z_2^*(\alpha, t) = \begin{cases} t^2 + \frac{t^2(1-t^2)}{12}\alpha^2 + \dots & (-\pi < \alpha < 0) \\ t^2 & (\alpha = 0) \\ t^2 - \frac{t^2(1-t^2)}{12}\alpha^2 + \dots & (\alpha > 0). \end{cases}$$

Thus $Z_2^*(\alpha, t)$ is continuous and differentiable at $\alpha = 0$. Since $D_\alpha Z_2^*(0, t) = \lim_{\alpha \rightarrow 0} \frac{Z_2^*(\alpha, t)}{\alpha} = 0$, $Z_2^*(\alpha, t_0)$, $\alpha \in (-\pi, \infty)$ is C^1 continuous, and so are $Z_1^*(\alpha, t)$ and $Z_0^*(\alpha, t)$ by Definition 2.4. Hence $\mathbf{q}^*(\alpha, t_0)$, $\alpha \in (-\pi, \infty)$ is C^1 continuous.

Proposition 3.7 For each $t_0 \in (0, 1)$, the isoparametric curve $\mathbf{q}^*(\alpha, t_0)$, $\alpha \in (-\pi, \infty)$ is not twice differentiable.

proof. Since

$$\lim_{\alpha \rightarrow 0^+} \frac{D_\alpha Z_2^*(\alpha, t) - D_\alpha Z_2^*(0, t)}{\alpha} = -\frac{t^2(1-t^2)}{6}$$

$$\lim_{\alpha \rightarrow 0^-} \frac{D_\alpha Z_2^*(\alpha, t) - D_\alpha Z_2^*(0, t)}{\alpha} = \frac{t^2(1-t^2)}{6},$$

the second derivative of $Z_2^*(\alpha, t)$ with respect to α does not exist. Thus the isoparametric curve $\mathbf{q}^*(\alpha, t_0)$, $\alpha \in (-\pi, \infty)$ is not twice differentiable.

Remark. Even if the isoparametric curve $\mathbf{q}^*(\alpha, 1/2)$ is a straight line segment $\overline{\mathbf{m}\mathbf{q}_1}$, it is not twice differentiable.

4. Conclusion

In this paper, we found some geometric properties of the isoparametric curve of quadratic F-Bézier curves. We showed that the isoparametric curve is tangent to the control polygon at the end point of the curve, or a straight line, and proved that the isoparametric curves are C^1 continuous but not twice differentiable.

In future works, we have plans to find the necessary and sufficient condition for the cubic F-Bézier curve to be a conic section, and to obtain some geometric properties of the isoparametric curve of cubic F-Bézier curves.

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