

ON NULL CUT POINTS IN TWO-DIMENSIONAL SPACETIMES

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ABSTRACT. It is shown that any two-dimensional globally hyperbolic spacetime with noncompact Cauchy surfaces has no null cut points.

1. Introduction

Conjugate point and cut point, defined in terms of Jacobi field along a geodesic and Riemannian distance, play important roles in global analysis of Riemannian manifold. Likewise, in Lorentzian geometry, they play essential roles in singularity theory of spacetimes. In connection with singularity theory, causality theory developed by Penrose [6], is an essential tool for global analysis of spacetimes. Lorentzian cut point, defined in terms of Lorentzian distance function, has a close relation to conjugate points and it is well-known that there is no null conjugate points in two-dimensional spacetimes ([1], [4], [5], [6]).

In contrast to this, there exists a two-dimensional spacetime in which every null geodesic has cut points which can be easily seen in two-dimensional Einstein static universe. In two-dimensional Einstein static universe, we can see that the spacetime has compact Cauchy surfaces.

In this paper, we show that if a two-dimensional Lorentzian manifold has noncompact Cauchy surfaces, then there exist no cut points along null geodesics by use of topological property of its Cauchy surface.

2. Preliminaries

In this section, we assume that M is an arbitrary dimensional globally hyperbolic Lorentzian manifold with a noncompact Cauchy surface Σ . By the work of Bernal and Sánchez ([2] and [3]), we can assume that Σ is a smooth, spacelike hypersurface. If there exists a future-directed timelike curve from x to y , then we write $x \ll y$ and we say that y lies in the chronological future

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of x or x lies in the chronological past of y . We define a subset $S \subset M$ to be achronal if no two points in S are chronologically related. If there exists a future-directed causal curve from x to y , then we write $x \leq y$ and we say that y lies in the causal future of x or x lies in the causal past of y . We define $I^+(x)$ ($I^-(x)$, respectively) to be the set of all chronological future (past, respectively) of x and $J^+(x)$ ($J^-(x)$, respectively) to be the set of all causal future (past, respectively) of x .

The relation “ $x \leq y$ but not $x \ll y$ ” is written $x \rightarrow y$ and is termed horismos. It is known that if $x \rightarrow y$, then any causal curve from x to y is a null geodesic without conjugate points except at most its endpoints (See Proposition 46 and Theorem 51 of Chapter 10 in [5]) and this is the main property which we use in this paper.

Definition. Let S be an achronal subset of M . The edge of S is the set of points x such that for every neighborhood U of x , there are two points y and z in U and two timelike curves in U from y to z , just one of which meets S .

If Σ is a non-compact Cauchy surface, then $S_p = J^-(p) \cap \Sigma$ is compact for each $p \in J^+(\Sigma)$ and, by the definition of edge points, it is easy to see that $\text{edge}S$ is precisely the set of boundary points of S_p in Σ . Furthermore, since Σ is noncompact and S_p is compact, the boundary of S_p in Σ is non-empty and thus $\text{edge}S_p$ is non-empty for any $p \in J^+(\Sigma)$.

Proposition 2.1. *If $x \in \text{edge}S_p$, then we have $x \rightarrow p$ and thus there exists a future-directed null geodesic from x to p without conjugate points except at most its endpoints.*

Proof. Since S_p is compact, it is closed and thus it contains its boundary points in Σ , which is precisely $\text{edge}S_p$. Therefore $x \in S_p$ and we have $x \leq p$. If $x \ll p$, then there exists a neighborhood U of x such that $y \ll p$ for all $y \in U$ since the relation \ll is open. This contradicts to the fact that $x \in \text{edge}S_p$, which is the boundary of S_p in Σ . Thus, we have $x \leq p$ but not $x \ll p$. \square

Proposition 2.2. *S_p is connected.*

Proof. Let X be a non-vanishing past-directed timelike vector field on M and Φ be its flow. If we let x and y be arbitrary points in S_p , then we have two causal curves γ_1 from x to p and γ_2 from y to p . By projecting $\gamma_1 \cup -\gamma_2$ into Σ through Φ , we get a curve from x to y in S_p . \square

We can define null cut points in terms of Lorentzian distance function d which is defined as, for $p \leq q$, $d(p, q) = \sup\{L(\gamma) \mid \gamma \text{ is a causal curve from } p \text{ to } q\}$ and $d(p, q) = 0$ if $p \not\leq q$.

Definition. Let $\gamma : [0, a) \rightarrow M$ be a future-directed null geodesic from $p = \gamma(0)$. If we let $t_0 = \sup\{t \in [0, a) \mid d(p, \gamma(t)) = 0\}$ and if $0 < t_0 < a$, then we say $\gamma(t_0)$ is the future null cut point of p along γ . Past null cut points are defined dually.

By the above definition, null cut points are characterized by the property that if $\gamma(a)$ is a cut point of $\gamma(0)$ along a future-directed null geodesic, then we have $\gamma(0) \ll \gamma(t)$ for each $t > a$. Also, we can see that if $x \rightarrow y$, then any causal curve from x to y is a null geodesic without cut points except at most its endpoints.

3. Main result

In this section, let M be a two-dimensional spacetime with a noncompact Cauchy surface Σ . Since the only noncompact one-dimensional manifold is the set of real numbers, \mathbb{R} , we have $\Sigma = \mathbb{R}$ and by the famous result of Bernal and Sánchez [2], we can assume that M is diffeomorphic to $\mathbb{R} \times \mathbb{R}$. So we can use a natural coordinate system of M as $\mathbb{R} \times \mathbb{R}$ and it naturally induces a coordinate system on Σ as \mathbb{R} .

Lemma 3.1. *For a two-dimensional spacetime M with a noncompact Cauchy surface Σ , if $S_p = J^-(p) \cap \Sigma$ for $p \in I^+(\Sigma)$, then $\text{edge}S_p$ is non-empty and has exactly two points.*

Proof. Since M is two-dimensional, and Σ is noncompact, we have that Σ is diffeomorphic to \mathbb{R} . Since S_p is a connected and compact subset of $\Sigma = \mathbb{R}$, S_p must be of the form $[\alpha, \beta]$, the closed and bounded interval in \mathbb{R} . Therefore $\text{edge}S_p = \{\alpha, \beta\}$ since $\text{edge}S_p$ is precisely the set of boundary points of S_p in $\Sigma = \mathbb{R}$. \square

For our main purpose, by symmetry, we only need to show that for any $p \in M$ and any past-directed null geodesic η from p , p has no null cut points along η .

Theorem 3.1. *Let M be a two-dimensional spacetime with noncompact Cauchy surfaces and let η be a past-directed null geodesic from $p \in M$. Then p has no null cut points along η .*

Proof. Bernal and Sánchez ([2], [3]) have shown that a globally hyperbolic spacetime M has a smooth function $f : M \rightarrow \mathbb{R}$ such that f increases along any future-directed causal curves and its level set $f^{-1}(a)$ forms a smooth, spacelike Cauchy surface Σ_a for each $a \in \mathbb{R}$. For our purpose, if we let $t = -f$, then t increases along any past-directed causal curves and we can parameterize η by t .

Let $t(p) = 0$ and assume that $p = \eta(0)$ has a cut point at $\eta(t_0)$ along η . If Σ_{t_0} is a Cauchy surface through $\eta(t_0)$, choose another Cauchy surface Σ_{t_1} in $I^-(\Sigma_{t_0})$. Then, by the previous lemma, $S_p(t_1) = J^-(p) \cap \Sigma(t_1)$ has two edge points, say, (t_1, α) and (t_1, β) . By Proposition 2.1, we have two null geodesics η_1 from p to (t_1, α) and η_2 from p to (t_1, β) . Since (t_1, α) and (t_1, β) are edge points, η_1 and η_2 have no null cut points. Since M is two-dimensional, the only past-directed null directions are either $\eta'_1(0)$ or $\eta'_2(0)$. Therefore, without loss of generality, we can assume that the direction of $\eta'(0)$ is the same with that of

$\eta'_1(0)$. However, by the uniqueness of geodesic, this implies that $\eta = \eta_1$, which is a contradiction since η has a cut point and η_1 does not. \square

If a globally hyperbolic spacetime has a future-directed null geodesic η such that $\eta(a)$ is a cut point of $\eta(0)$ along η , then there is a future-directed timelike geodesic γ from $\eta(0)$ to $\eta(a+\epsilon)$. By considering the fact that timelike geodesic is a freely falling observer, the existence of null cut point implies that there exists a freely falling observer with non-zero rest mass, who emits a light signal and he gets the emitted light signal after a finite time interval. The main theorem of this paper states that if a two-dimensional spacetime has a noncompact Cauchy surface, then no observer can catch up with light.

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