

Parametric Study of Offshore Pipeline Wall Thickness by DNV-OS-F101, 2010

Han-Suk Choi*, Su-Young Yu*, Dae-Hoon Kang** and Hyo-Dong Kang**

*Graduate School of Engineering Mastership, Postech, Pohang, Korea

**Daewoo Shipbuilding & Marine Engineering Co., Seoul, Korea

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ABSTRACT: DNV-OS-F101 includes the concept development, design, construction, operation, and abandonment of offshore pipeline systems. The main objective of this offshore standard (OS) is to ensure that pipeline systems are safe during the installation and operational period. The pipeline design philosophy also includes public safety and environmental protection. The mechanical wall thickness design of a pipeline shall follow the design objectives and safety philosophy. This new design code includes a very sophisticated design procedure to ensure a safe pipeline, public safety, and environmental protection. This paper presents the results of a parametric study for the wall thickness design of offshore pipelines. A design matrix was developed to cover the many design factors of pipeline integrity, public safety, and environmental protection. Sensitivity analyses of the various parameters were carried out to identify the impacts on offshore pipeline design.

1. 서 론

Det Norske Veritas (DNV) published the offshore pipeline design rules (DNV, 1976; DNV, 1981). These design rules were based on the working stress design and have been used over two decades. In the year 2000, DNV published first offshore standard (OS) DNV-OS-F101 for the design of the offshore pipeline systems with limit states or load and resistance factor design (LRFD). This offshore standard has been continuously updated based on various joint industry projects and many offshore installations (DNV, 2000, 2005, 2007, 2010). This new design code covers the all aspects of offshore pipeline system including concept development, design, construction, operation and abandonment at the end of production life. The main objective of this offshore standard is to ensure that pipeline systems are safe during the design life. Pipeline design philosophy also includes the public safety and environmental protection. Mechanical wall thickness design of a pipeline shall be followed by the design objectives and safety philosophy. This new design code includes a very sophisticated design procedure to ensure pipeline safety, public safety and environmental protection. Design and application to real projects were conducted by recent studies (Brown et al., 2004; Choi, 2006; Choi and Do, 2006; Choi et al., 2008; Choi et al., 2010).

This paper is presented to summarize the recent design code and to establish a wall thickness design matrix. The main objective of this paper is to assess a parametric study of

the offshore pipeline design. A design matrix was developed to include many design factors of pipeline integrity, public safety, and environmental protection with a consistent design methodology. Parametric sensitivity analyses were carried out to identify the impacts on the offshore pipeline wall thickness design. Various results of the parametric study are presented.

2. Safety, Concept Development and Design Premise

An overall safety philosophy is applied in the concept development, design, construction, operation and abandonment of pipelines. DNV-OS-F101 defines two integrity stages: establishment of integrity in the concept development, design and construction phases; and maintaining integrity in the operating phases. The integrity of the offshore pipeline system is ensured through safety philosophy integrating with each of the different parts such as safety objective, systematic review, safety class methodology and quality assurance.

An overall safety objective shall be established, planned and implemented, covering all phases from a conceptual development to abandonment. Systematic review of risks shall be carried out at all phases to identify and evaluate threats, consequences of a single failure and series of failures in the pipeline system. A methodology for a systematic review is quantitative risk analysis (QRA). There are two

Corresponding author Han-Suk Choi: 77 Cheongam-Ro, Nam-Gu, Pohang, Korea, +82-54-279-0134, hchoi@postech.ac.kr

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parts of safety philosophy such as safety class methodology and quality assurance. Structural safety of the pipeline system is ensured by use of a safety class methodology based on failure consequences and a set of partial safety factors. Quality objectives are established by the operator of pipeline system and a quality assurance is controlled during all relevant phases.

Generally, pipeline system design is conducted in compliance with national legislation and company policy with respect to health, safety and environmental aspects as well as designated design codes such as DNV-OS-F101.

The objective of concept development and design premise provide a basis for the definition of relevant offshore field development characteristics. When selecting a pipeline system concept in a stage of development, all aspects related to design, construction, operation and abandonment shall be considered. Data and description of a field development and general arrangements of the pipeline systems are established.

The pipeline system shall be designed, constructed and operated in such a manner that the specified transport capacity is fulfilled and the flow assured. Resistance against loads and the safety margin against accidental loads or unplanned operational conditions shall be fulfilled. A design matrix was established to satisfy the concept development and design premise. Parameters which could affect on the integrity of a pipeline system were evaluated in this study.

3. Design - Limit State Criteria

All relevant limit states shall be considered in a design for all relevant phases and conditions. As a minimum requirement of an ultimate limit state, the offshore pipeline system shall be designed against bursting, ovalization/ratcheting, local buckling, global buckling, fatigue, unstable fracture and plastic collapse. The design matrix is based upon several limit states and partial safety factors, is also called as a load and resistance factor design.

The design load should be checked by the limit state design criteria. These criteria include load scenarios to be considered, categorization of loads such as functional, environmental and accidental loads. All loads and forced displacements which influence the pipeline integrity were considered in this study.

3.1 Pressure containment (bursting)

A bursting of pipeline due to the fluid pressure containment shall be satisfied the following criteria. The criteria are valid if the pipe mill pressure test has been satisfied. If not, a corresponding decreased utilization factor shall be applied. Reduction in pressure containment resistance due to true

compressive forces (load controlled) shall be also considered.

$$P_{lx} - P_e \leq \frac{P_b(t_1)}{\gamma_m \cdot \gamma_{SC}} \quad (1)$$

where

$P_{lx} = P_{li}$, local incidental pressure during operation

$P_{lx} = P_{lt}$, local system test pressure during system test

P_e = external pressure

γ_m = material resistance factor

γ_{SC} = safety class resistance factor

t_1 = characteristic wall thickness

$P_b(t) = 2 \cdot \frac{t}{(D-t)} \cdot f_{cb} \cdot \frac{2}{\sqrt{3}}$, pressure containment resistance

where

t = pipeline wall thickness

D = nominal outside diameter

$f_{cb} = \text{Min}[f_y; \frac{f_u}{1.15}]$

where

f_y = yield stress

f_u = tensile stress

3.2 Local buckling - external over-pressure only (system collapse)

The characteristic resistance for external pressure is calculated as:

$$(P_c(t) - P_{el}(t)) \cdot (P_c(t)^2 - P_p(t)^2) = P_c(t) \cdot P_{el}(t) \cdot P_p(t) \cdot f_o \cdot \frac{D}{t} \quad (2)$$

where

$P_c(t)$ = characteristic resistance for external pressure (collapse)

$P_{el}(t) = \frac{2 \cdot E \cdot (\frac{t}{D})^3}{1 - \nu^2}$, elastic collapse pressure

$P_p(t) = f_y \cdot \alpha_{fab} \cdot \frac{2 \cdot t}{D}$, plastic collapse pressure

$f_o = \frac{D_{max} - D_{min}}{D}$, ovality

where

α_{fab} = fabrication factor

D_{max} = greatest measured inside or outside diameter

D_{min} = smallest measured inside or outside diameter

3.3 Propagation buckling

Propagation buckling cannot be initiated unless a local buckling has occurred. Propagation buckling results in very thick pipes. Propagation buckling is an option for the wall thickness design. If the external pressure exceeds the propa-

gation criteria, buckle arrestors should be installed. A buckle arrestor capacity depends on propagating buckle resistance of adjacent pipes and size of the buckle arrestor (Torseletti et al, 2003). The propagating buckle criterion is as below:

$$P_e < \frac{P_{pr}}{\gamma_m \cdot \gamma_{SC}} \quad (3)$$

where

$$P_{pr} = 35 \cdot f_y \cdot \alpha_{fab} \cdot \left(\frac{t_2}{D}\right)^{2.5} \quad \text{for } D/t_2 < 45, \quad \text{propagating}$$

pressure

where

t_2 = characteristic wall thickness

3.4 Local buckling - combined loading criteria

3.4.1 Load controlled condition (LCC)

Load controlled condition is that the structural response is primarily governed by the imposed load. This design criterion can always be applied in place of a displacement controlled condition (DCC) (DNV, 2010).

(1) Internal over-pressure

Pipe members subjected to bending moment, effective axial force and internal over-pressure are designed to satisfy the following condition:

$$\left[\gamma_m \cdot \gamma_{SC} \cdot \frac{|M_{Sd}|}{\alpha_c \cdot M_p(t_2)} + \left[\frac{\gamma_m \cdot \gamma_{SC} \cdot S_{Sd}(P_i)}{\alpha_c \cdot S_p(t_2)} \right]^2 \right]^2 + \left(\alpha_p + \frac{P_i - P_e}{\alpha_c \cdot P_b(t_2)} \right)^2 \leq 1$$

$$D/t_2 \leq 45, \quad P_i > P_e \quad (4)$$

where

M_{Sd} = design moment

S_{Sd} = design effective axial force

P_i = internal pressure

$S_p(t) = f_y \cdot \pi \cdot (D-t)^3 \cdot t$, plastic capacity of effective axial force

$M_p(t) = f_y \cdot (D-t)^3 \cdot t$, plastic capacity of design moment

$\alpha_c = (1-\beta) + \beta \cdot \frac{f_u}{f_y}$, flow stress parameter

$$\alpha_p = \begin{cases} 1-\beta & \frac{P_i - P_e}{P_b} < \frac{2}{3} \\ 1-3\beta\left(1-\frac{P_i - P_e}{P_b}\right) & \frac{P_i - P_e}{P_b} \geq \frac{2}{3} \end{cases}, \quad \text{effect of } D/t_2 \text{ ratio}$$

$$\beta = \begin{cases} 0.5 & \text{for } D/t_2 < 15 \\ (60 - D/t_2)/90 & \text{for } 15 \leq D/t_2 \leq 60 \\ 0 & \text{for } D/t_2 > 60 \end{cases}, \quad \text{factor used in}$$

combined loading criteria

(2) External over-pressure

Pipe members subjected to bending moment, effective axial

force and external over-pressure are designed to satisfy the following condition:

$$\left[\gamma_m \cdot \gamma_{SC} \cdot \frac{|M_{Sd}|}{\alpha_c \cdot M_p(t_2)} + \left[\frac{\gamma_m \cdot \gamma_{SC} \cdot S_{Sd}}{\alpha_c \cdot S_p(t_2)} \right]^2 \right]^2 + (\gamma_m \cdot \gamma_{SC} \cdot \frac{P_e - P_{min}}{P_c(t_2)})^2 \leq 1$$

$$D/t_2 \leq 45, \quad P_i < P_e \quad (5)$$

where

P_{min} = minimum internal pressure

3.4.2 Displacement controlled condition

Displacement controlled condition is that the structural response is primarily governed by imposed geometric displacements.

(1) Internal over-pressure

Pipe members subjected to longitudinal compressive strain (bending moment and axial force) and internal over-pressure are designed to satisfy the following condition:

$$\epsilon_{Sd} \leq \epsilon_{Rd} = \frac{\epsilon_c(t_2, P_{min} - P_e)}{\gamma_\epsilon} \quad D/t_2 \leq 45, \quad P_i \geq P_e \quad (6)$$

where

ϵ_{Sd} = design compressive strain

$$\epsilon_c(t_2, P_{min} - P_e) = 0.78 \cdot \left(\frac{t}{D} - 0.01\right) \cdot \left(1 + 5.75 \cdot \frac{P_{min} - P_e}{P_b(t)}\right) \cdot (\alpha_h)^{-1.5} \cdot \alpha_{gw}$$

γ_ϵ = strain resistance factor

α_{gw} = girth weld factor

$\alpha_h = \left(\frac{R_{t0.5}}{R_m}\right)_{max}$, minimum strain hardening

where

$R_{t0.5}$ = strength equivalent to a total elongation of 0.5 % (actual stress)

R_m = tensile strength

(2) External over-pressure

Pipe members subjected to longitudinal compressive strain and external over-pressure are designed to satisfy the following condition:

$$\left(\frac{\epsilon_{Sd}}{\epsilon(t_2, D)/\gamma_\epsilon}\right)^{0.8} + \frac{P_e - P_{min}}{P_c(t_2)/(\gamma_m \cdot \gamma_{SC})} \leq 1 \quad D/t_2 \leq 45, \quad P_{min} < P_e \quad (7)$$

4. Design Matrix

4.1 Input parameters

Input parameters used in a benchmark case are shown in Table 1. These data were taken from the Sakhalin 1, Chayvo-

Table 1 Input parameters for wall thickness calculation (Benchmark case)

Input	Value
Outside diameter	914.4 mm
Corrosion allowance	3 mm
Water depth	21.8 m
Burial depth	2.35 m
Design pressure	9.763 MPa
Operating temperature	68°C
Effective axial force	222.4 kN
Moment	1897 kN · m
Strain	0.002
Specified minimum yield stress	415 MPa
Specified minimum tensile stress	520 MPa
Elastic modulus	207 GPa
Poisson ratio	0.3

Orlan pipeline project (Technip, 2005).

4.2 Design matrix

A design matrix was developed to include the design factors of pipeline integrity, public safety, and environmental protection in DNV-OS-F101. This design matrix was deve-

loped under a consistent design methodology and philosophy for wall thickness design. Then, this design matrix was used for a benchmark case and a parametric study. The design matrix for the benchmark case of wall thickness is internal over-pressure problem as shown in Table 2. The benchmark case shows the negligible results for external over-pressure cases. External over-pressure and other parametric studies are presented in the following section.

5. Parametric Sensitivity Analyses

Parameters and the varied values used in sensitivity analyses are indicated in Table 3. After numerous calculations, appropriate ranges of variables were determined to identify their sensitivities.

Fig. 1 shows a parametric analysis of water depths for internal over-pressure cases. Propagation buckling is the most sensitive to the water depth. Displacement controlled combined load cases are also sensitive to water depth due to minimum internal pressure that can be continuously sustained with the associated strain. However, load controlled combined conditions indicate tendency of decrement of wall thickness due to maximum internal pressure. Water depth increments have also negative effects for pressure containment cases.

Table 2 Design matrix for wall thickness calculations (Benchmark case)

Case	Description	System condition	Wall thickness (mm)	Code section
Pressure containment (bursting)	Operation	Low	16.5	D200
	Operation	Medium	17.6	
	Operation	High	19.8	
	System test	Low	14.5	
Local buckling - External over-pressure (system collapse)	Installation & operation	High	13.6	D400
Propagation buckling	Installation & operation	High	19.4	D500
Local buckling - Combined loading criteria (load controlled condition)	Internal over-pressure (System check)	High	14.3	D605
	External over-pressure (System check)		1.2	
	Internal over-pressure (Local check)	High	13.1	D607
	External over-pressure (Local check)		1.1	
Local buckling - Combined loading criteria (displacement controlled condition)	Internal over-pressure (System check)	High	19.8	D608
	External over-pressure (System check)		20.8	
	Internal over-pressure (Local check)	High	18.9	D609
	External over-pressure (Local check)		20.1	

Table 3 Parameters for sensitivity analyses

Parameters	Values
Water depth (Internal over-pressure)	0 ~ 950 m
Water depth (External over-pressure)	100 ~ 1,000 m
Burial depth	0 ~ 5 m
Axial force	- 5,000 ~ 5,000 kN
Moment	- 5,000 ~ 5,000 N · m
Strain	0 ~ 0.01
Temperature	50 ~ 200 °C

sensitive to the wall thickness design. Both of the combined load cases are also sensitive to wall thickness. Results of pressure containment does not appear in this figure due to external over-pressure cases.

Fig. 3 illustrates a parametric analysis of pipeline burial depths. The results of parametric study are separated into two groups. Upper group including pressure containment in operation, propagation buckling and displacement controlled condition is more sensitive than lower group. Most of the results show mild rates of increments with respect to pipeline burial depths.

Fig. 4 shows a parametric analysis of effective axial forces. Effective axial forces have influence only on load controlled combined conditions. Wall Thickness is very sensitive to axial force increment. Increments of wall thicknesses by compressive and tensile force are symmetric.

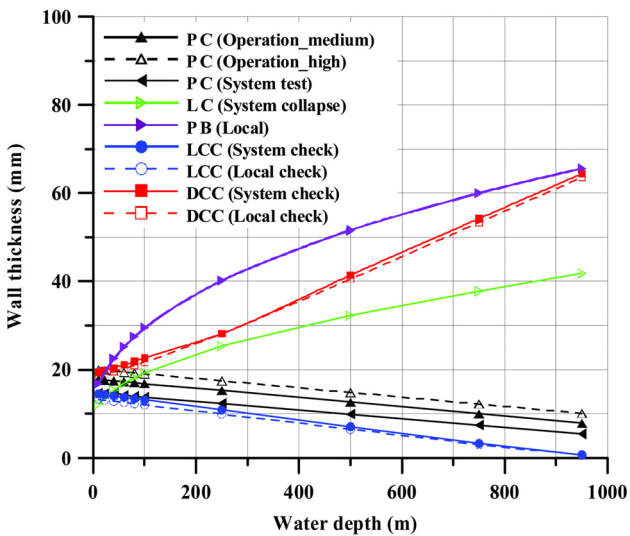


Fig. 1 Wall thickness results of water depths for internal over-pressure cases ($P_i = 9763$ kPa)

Fig. 2 indicates a parametric analysis of water depths for external over-pressure cases. Propagation buckling is the most

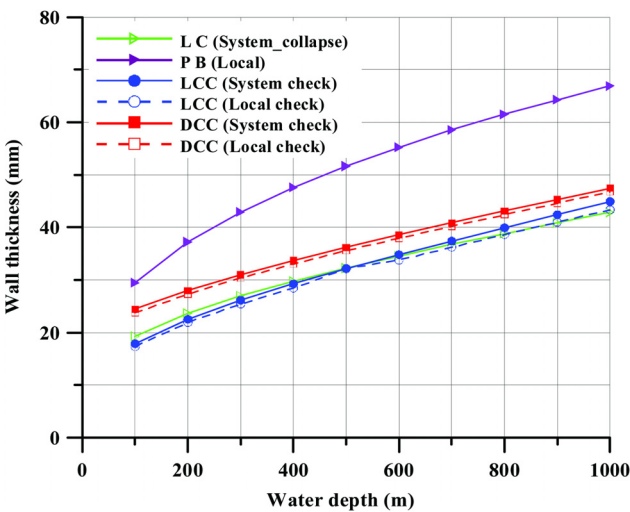


Fig. 2 Wall thickness results of water depths for external over-pressure cases ($P_i = 976$ kPa)

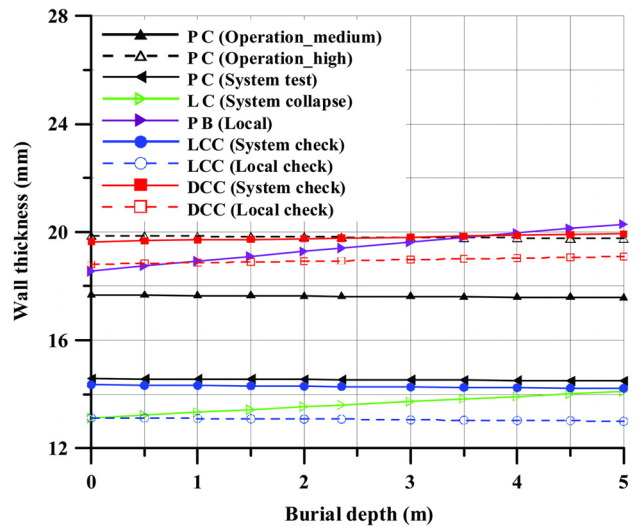


Fig. 3 Wall thickness results of burial depths

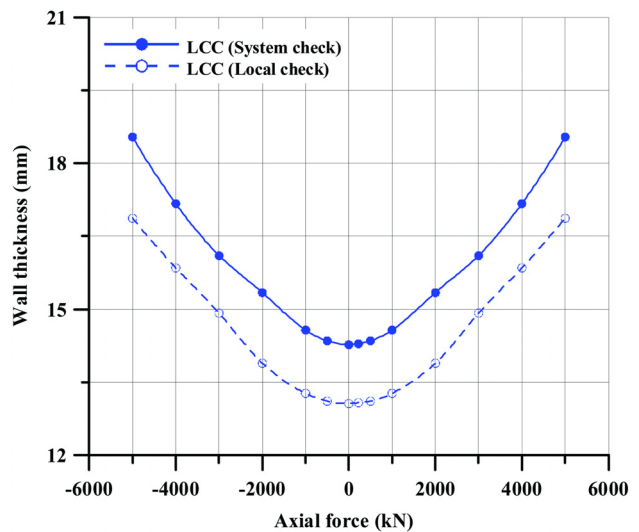


Fig. 4 Wall thickness results of effective axial forces

Fig. 5 illustrates a parametric analysis of moments on pipeline systems. Moment has a significant influence only on load controlled combined conditions for wall thickness design. There are little differences in wall thicknesses between system check cases and local check cases due to the load control condition by external moments.

Fig. 6 shows a parametric analysis of strains due to pipeline installation. System check cases in displacement controlled condition are more sensitive than load controlled condition. As strains are increased, the wall thickness in system check case is increased linearly within allowable strain limits.

Fig. 7 shows a parametric analysis of operational temperatures. Pressure containment in the high safety case and operation case are the most sensitive to the operational temperatures. Displacement controlled condition and propagation buck

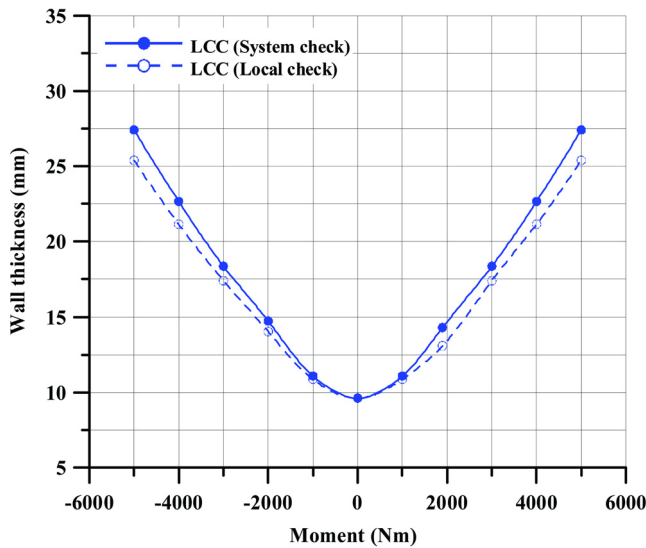


Fig. 5 Wall thickness results of external moments

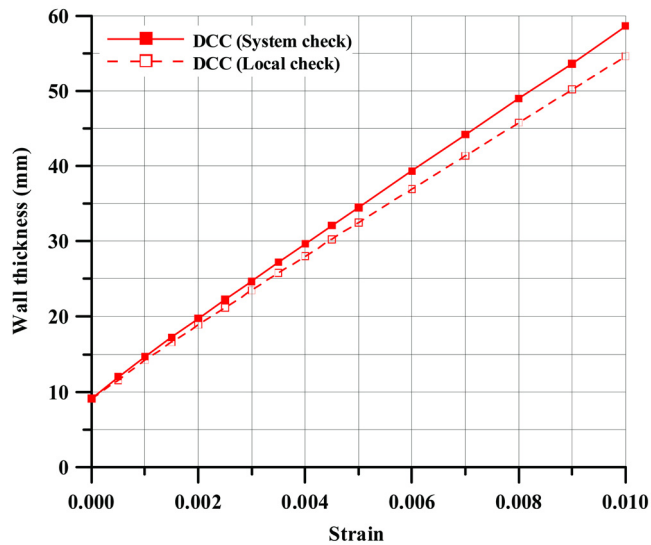


Fig. 6 Wall thickness results of pipeline strains

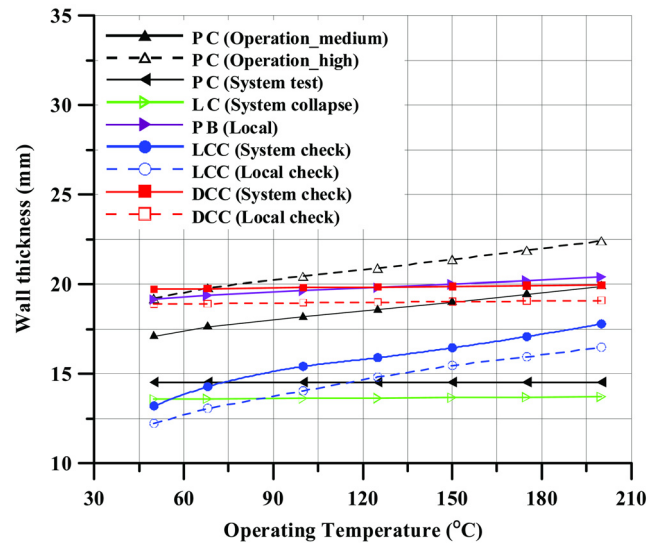


Fig. 7 Wall thickness results of operating temperatures

ling cases are also sensitive to the operational temperatures. But load controlled condition cases show mild increments of wall thicknesses.

Fig. 8 shows a summary of the parametric sensitivity analyses. Vertical axis indicates the ratios of wall thicknesses between the benchmark case and sensitivity analyses. Horizontal axis indicates the ratios of the parameters between the benchmark case and sensitivity analyses. Load controlled cases due to external moments and installation strains are most sensitive to wall thickness design. Water depth is also sensitive to wall thickness, but less sensitive than combined load cases. Remaining parameters such as burial depth, axial force, and operating temperature have little influences for wall thickness design. These tendency is similar to the results of Vitali et al (1999).

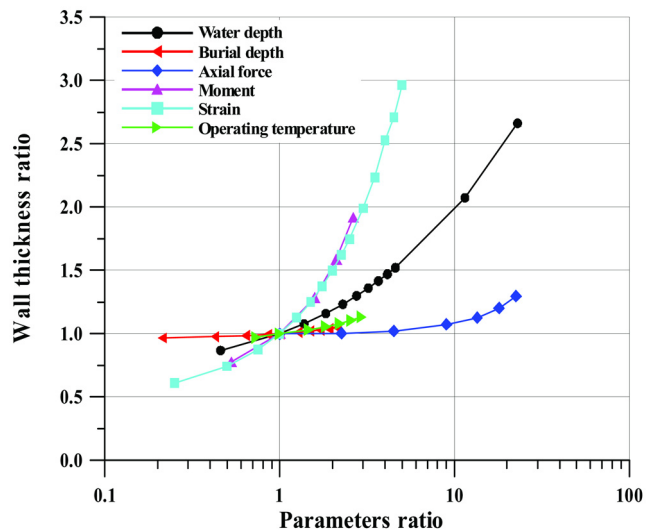


Fig. 8 A summary of the parametric sensitivity analyses

6. Concluding Remarks

Following concluding remarks were obtained from the parametric sensitivity study.

(1) A design matrix was developed in accordance with DNV-OS-F101, 2010. Then the design matrix was used for a real project benchmarking and parametric sensitivity analyses.

(2) In case of water depth variations, propagation buckling is the most sensitive to the wall thickness design.

(3) Results of pipeline burial depth variation are separated into two groups. The group including pressure containment in operation, propagation buckling and displacement controlled condition is sensitive to wall thickness design.

(4) Effective axial forces and moments have influenced only load controlled conditions. The results of system check cases are higher than those of local check cases.

(5) System check cases in displacement controlled conditions are more sensitive than those of load controlled conditions.

(6) Results of operational temperature variation show that pressure containment, displacement controlled condition and propagation buckling cases are sensitive to the wall thickness design.

(7) External moments and installation strains are the most sensitive to wall thickness design. Water depth is an important variable to design wall thickness, but less sensitive than the combined load cases.

후 기

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