

CALCULATION OF SOME TOPOLOGICAL INDICES OF SPLICES AND LINKS OF GRAPHS[†]

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ABSTRACT. Explicit formulas are given for the first and second Zagreb index, degree-distance and Wiener-type invariants of splice and link of graphs. As a consequence, the first and second Zagreb coindex of these classes of composite graphs are also computed.

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1. Introduction

Throughout this paper graph means simple connected graphs. The distance $d_G(u, v)$ between the vertices u and v of a graph G is defined as the length of a shortest path connecting u and v . Let $d(G, k)$ be the number of pairs of vertices of G that are at distance k , λ a real number, and $W_\lambda(G) = \sum_{k \geq 1} d(G, k)k^\lambda$. $W_\lambda(G)$ is called the Wiener-type invariant of G associated to real number λ , see [7, 11] for details. Note that $d(G, 0)$ and $d(G, 1)$ represent the number of vertices and edges, respectively. The case of $\lambda = 1$ is called the classical Wiener index [25]. The quantities $WW = \frac{1}{2}[W_1 + W_2]$ and $TSZ = \frac{1}{6}W_3 + \frac{1}{2}W_2 + \frac{1}{3}W_1$ are the so-called hyper-Wiener index and Tratch–Stankevich–Zefirov index [7].

Suppose G and H are graphs with disjoint vertex sets. Following Došlić [5], for given vertices $y \in V(G)$ and $z \in V(H)$ a splice of G and H by vertices y and z , $(G \cdot H)(y, z)$, is defined by identifying the vertices y and z in the union of G and H . Similarly, a link of G and H by vertices y and z is defined as the graph $(G \sim H)(y, z)$ obtained by joining y and z by an edge in the union of these graphs.

The Zagreb indices have been introduced more than thirty years ago by Gutman and Trinajstić, [8]. They are defined as $M_1(G) = \sum_{u \in V(G)} \deg_G(u)^2$

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and $M_2(G) = \sum_{uv \in E(G)} \deg_G(u)\deg_G(v)$. As the sums involved run over the edges of the complement of G , such quantities were called Zagreb coindices. More formally, the first Zagreb coindex of a graph G is defined as $\bar{M}_1(G) = \sum_{uv \notin E(G)} [\deg_G(u) + \deg_G(v)]$, and the second Zagreb coindex of a graph G is given by $\bar{M}_2(G) = \sum_{uv \notin E(G)} \deg_G(u)\deg_G(v)$. The reader should note that Zagreb coindices of G are not Zagreb indices of \bar{G} ; the defining sums run over $E(\bar{G})$, but the degrees are with respect to G . We encourage the reader to consult papers [6, 9, 14, 22, 27] and references therein for more information on Zagreb indices of graphs.

In some recent papers Dobrynin and Kochetova [4] and Gutman [10] introduced a new graph invariant defined as follows: the degree-distance of a vertex x , denoted by $D'(x)$, is defined as $D'(x) = D(x)\deg_G(x)$, where $\deg_G(x)$ is the degree of x , $D(x) = \sum_{y \in V(G)} d_G(x, y)$ and the degree-distance of G , denoted by $D'(G)$, is

$$\begin{aligned} D'(G) &= \sum_{x \in V(G)} D'(x) = \sum_{x \in V(G)} D(x)\deg_G(x) \\ &= \frac{1}{2} \sum_{x, y \in V(G)} d(x, y)[\deg_G(x) + \deg_G(y)]. \end{aligned}$$

Throughout this paper our other notations are standard and taken mainly from [3, 24].

2. Main Results

In this section, formulas for the Zagreb index, Zagreb coindex, degree-distance and Wiener-type invariants of the splices and links of graphs are presented. The interested readers for more information on topological indices of graph operations can be referred to the papers [1, 2, 12 – 21, 23, 26] and their references. The following simple lemma is crucial in this paper:

Lemma 2.1. Suppose G_1 and G_2 are connected graphs. Then the following are hold:

- $|E((G_1 \cdot G_2)(y, z))| = |E(G_1)| + |E(G_2)|$,
- $|V((G_1 \cdot G_2)(y, z))| = |V(G_1)| + |V(G_2)| - 1$,
- $|E((G_1 \sim G_2)(y, z))| = |E(G_1)| + |E(G_2)| + 1$,
- $|V((G_1 \sim G_2)(y, z))| = |V(G_1)| + |V(G_2)|$,

e) If $u, y \in V(G_1)$ and $u \neq y$ then $\deg_{(G_1 \cdot G_2)(y, z)}(u) = \deg_{G_1}(u)$. If $u, z \in V(G_2)$ and $u \neq z$ then $\deg_{(G_1 \cdot G_2)(y, z)}(u) = \deg_{G_2}(u)$. Moreover, $\deg_{(G_1 \cdot G_2)(y, z)}(y) = \deg_{G_1}(y) + \deg_{G_2}(z)$ and $\deg_{(G_1 \cdot G_2)(y, z)}(z) = \deg_{G_1}(y) + \deg_{G_2}(z)$.

f) If $u, y \in V(G_1)$ and $u \neq y$ then $deg_{(G_1 \sim G_2)(y,z)}(u) = deg_{G_1}(u)$ and if $u, z \in V(G_2)$ and $u \neq z$ then $deg_{(G_1 \sim G_2)(y,z)}(u) = deg_{G_2}(u)$.
 Moreover, $deg_{(G_1 \sim G_2)(y,z)}(y) = deg_{G_1}(y)+1$ and $deg_{(G_1 \sim G_2)(y,z)}(z) = 1+deg_{G_2}(z)$.

g) If $V(G_1) = \{u_1, \dots, u_n\}$ and $V(G_2) = \{v_1, \dots, v_m\}$ then

$$\begin{aligned} d_{(G_1 \cdot G_2)(y,z)}(u_i, u_j) &= d_{G_1}(u_i, u_j), \\ d_{(G_1 \cdot G_2)(y,z)}(u_i, v_j) &= d_{G_1}(u_i, y) + d_{G_2}(v_j, z), \\ d_{(G_1 \cdot G_2)(y,z)}(v_i, v_j) &= d_{G_2}(v_i, v_j). \end{aligned}$$

and

$$\begin{aligned} d_{(G_1 \sim G_2)(y,z)}(u_i, u_j) &= d_{G_1}(u_i, u_j), \\ d_{(G_1 \sim G_2)(y,z)}(u_i, v_j) &= d_{G_1}(u_i, y) + d_{G_2}(v_j, z) + 1, \\ d_{(G_1 \sim G_2)(y,z)}(v_i, v_j) &= d_{G_2}(v_i, v_j). \end{aligned}$$

Proof. The proof is trivial and so omitted. □

In the following lemma, the set of all neighbors of z in G is denoted by $N_1(z)$.

Lemma 2.2. If G_1 and G_2 are connected graphs then $M_1((G_1 \cdot G_2)(y, z)) = M_1(G_1) + M_1(G_2) + 2deg_{G_1}(y)deg_{G_2}(z)$ and $M_2((G_1 \cdot G_2)(y, z)) = M_2(G_1) + M_2(G_2) + deg_{G_2}(z)(\sum_{u \in N_1(y)} deg_{G_1}(u)) + deg_{G_1}(y)(\sum_{v \in N_1(z)} deg_{G_2}(v))$.

Proof. By definition of the first Zagreb index, one can prove the first part of the lemma. To prove the second part, we can see that:

$$\begin{aligned} M_2((G_1 \cdot G_2)(y, z)) &= \sum_{uv \in E(G_1); u, v \neq y} deg_{G_1}(u)deg_{G_1}(v) \\ &+ \sum_{uv \in E(G_2); u, v \neq z} deg_{G_2}(u)deg_{G_2}(v) \\ &+ \sum_{\substack{uv \in E(G_1) \\ u=y \\ v \in V(G_1)}} (deg_{G_1}(y) + deg_{G_2}(z))deg_{G_1}(v) \\ &+ \sum_{\substack{uv \in E(G_2) \\ u=z \\ v \in V(G_2)}} (deg_{G_1}(y) + deg_{G_2}(z))deg_{G_2}(v) \\ &= M_2(G_1) + M_2(G_2) + deg_{G_2}(z)(\sum_{u \in N_1(y)} deg_{G_1}(u)) \\ &+ deg_{G_1}(y)(\sum_{v \in N_1(z)} deg_{G_2}(v)), \end{aligned}$$

which completes our argument. □

Corollary 2.3. With notation of Lemma 2.2, $\bar{M}_1((G_1 \cdot G_2)(y, z)) = \bar{M}_1(G_1) + \bar{M}_1(G_2) + 2(|V(G_2)||E(G_1)| + |E(G_2)||V(G_1)| - |E(G_1)| - deg_{G_1}(y)deg_{G_2}(z))$

$$- |E(G_2)|) \text{ and } \bar{M}_2((G_1 \cdot G_2)(y, z)) = \bar{M}_2(G_1) + \bar{M}_2(G_2) + 4|E(G_1)||E(G_2)| - \deg_{G_2}(z) \sum_{u \in N_1(y)} \deg_{G_1}(u) - \deg_{G_1}(y) \sum_{v \in N_1(z)} \deg_{G_2}(v) - \deg_{G_1}(y) \deg_{G_2}(z).$$

Proof. The proof is straightforward and follows from $\bar{M}_1(G) = 2|E(G)|(|V(G)| - 1) - M_1(G)$ and $\bar{M}_2(G) = 2|E(G)|^2 - M_2(G) - \frac{1}{2}M_1(G)$. \square

Lemma 2.4. If G_1 and G_2 are connected graphs then $M_1((G_1 \sim G_2)(y, z)) = M_1(G_1) + M_1(G_2) + 2(\deg_{G_1}(y) + \deg_{G_2}(z) + 1)$ and $M_2((G_1 \sim G_2)(y, z)) = \sum_{u \in N_1(y)} \deg_{G_1}(u) + \sum_{v \in N_1(z)} \deg_{G_2}(v) + (\deg_{G_1}(y) + 1)(1 + \deg_{G_2}(z)) + M_2(G_1) + M_2(G_2)$.

Proof. The first part is an easy consequence of definition and for the second part, we have:

$$\begin{aligned} M_2((G_1 \sim G_2)(y, z)) &= \sum_{uv \in E(G_1); u, v \neq y} \deg_{G_1}(u) \deg_{G_1}(v) \\ &+ \sum_{uv \in E(G_2); u, v \neq z} \deg_{G_2}(u) \deg_{G_2}(v) \\ &+ \sum_{\substack{uv \in E(G_1) \\ u=y \\ v \in V(G_1)}} (\deg_{G_1}(y) + 1) \deg_{G_1}(v) \\ &+ \sum_{\substack{uv \in E(G_2) \\ u=z \\ v \in V(G_2)}} (1 + \deg_{G_2}(z)) \deg_{G_2}(v) \\ &+ (\deg_{G_1}(y) + 1)(1 + \deg_{G_2}(z)) \\ &= M_2(G_1) + M_2(G_2) + \sum_{u \in N_1(y)} \deg_{G_1}(u) \\ &+ \sum_{v \in N_1(z)} \deg_{G_2}(v) + (\deg_{G_1}(y) + 1)(1 + \deg_{G_2}(z)), \end{aligned}$$

proving the lemma. \square

Corollary 2.5. By the notation of Lemma 2.4, $\bar{M}_1((G_1 \sim G_2)(y, z)) = \bar{M}_1(G_1) + \bar{M}_1(G_2) + 2|V(G_2)||E(G_1)| + 2|E(G_2)||V(G_1)| + 2|V(G_1)| + 2|V(G_2)| - 2(\deg_{G_1}(y) + \deg_{G_2}(z) + 1)$ and $\bar{M}_2((G_1 \sim G_2)(y, z)) = \bar{M}_2(G_1) + \bar{M}_2(G_2) + 4|E(G_2)| + 4|E(G_1)||E(G_2)| + 1 - \sum_{u \in N_1(y)} \deg_{G_1}(u) - \sum_{v \in N_1(z)} \deg_{G_2}(v) - \deg_{G_1}(y) \deg_{G_2}(z) - 2\deg_{G_1}(y) - 2\deg_{G_2}(z)$. \square

In what follows, the degree distance of splices and links of graphs are computed.

Lemma 2.6. If G_1 and G_2 are connected graphs then the degree-distance of splices and links are computed as follows:

$$\begin{aligned}
 D'((G_1 \cdot G_2)(y, z)) &= (|V(G_2)| - 1) \sum_{y \neq u \in V(G_1)} \text{deg}_{G_1}(u) d_{G_1}(u, y) \\
 &+ (|V(G_1)| - 1) \sum_{z \neq v \in V(G_2)} \text{deg}_{G_2}(v) d_{G_2}(v, z) \\
 &+ 2|E(G_1)|D(z) + D'(G_1) + D'(G_2) \\
 &+ 2|E(G_2)|D(y),
 \end{aligned}$$

$$\begin{aligned}
 D'((G_1 \sim G_2)(y, z)) &= |V(G_2)| \sum_{y \neq u \in V(G_1)} \text{deg}_{G_1}(u) d_{G_1}(u, y) \\
 &+ |V(G_1)| \sum_{z \neq v \in V(G_2)} \text{deg}_{G_2}(v) d_{G_2}(v, z) \\
 &+ (2|E(G_1)| + 2)D(z) + D'(G_1) \\
 &+ (2|E(G_2)| + 2)D(y) + D'(G_2) \\
 &+ (|V(G_2)| - 1)(2|E(G_1)| + 1) + 2|E(G_1)| \\
 &+ (|V(G_1)| - 1)(2|E(G_2)| + 1) + 2|E(G_2)| + 2.
 \end{aligned}$$

Proof. By Lemma 2.1 and definition, we have:

$$\begin{aligned}
 D'((G_1 \cdot G_2)(y, z)) &= \frac{1}{2} \sum_{u, v} (\text{deg}_{(G_1 \cdot G_2)(y, z)}(u) + \text{deg}_{(G_1 \cdot G_2)(y, z)}(v)) d_{(G_1 \cdot G_2)(y, z)}(u, v) \\
 &= \frac{1}{2} \sum_{\substack{u, v \neq y \\ u, v \in V(G_1)}} (\text{deg}_{G_1}(u) + \text{deg}_{G_1}(v)) d_{G_1}(u, v) \\
 &+ \frac{1}{2} \sum_{\substack{u=y \\ v \in V(G_1)}} (\text{deg}_{G_1}(y) + \text{deg}_{G_2}(z) + \text{deg}_{G_1}(v)) d_{G_1}(v, y) \\
 &+ \frac{1}{2} \sum_{\substack{u, v \neq z \\ u, v \in V(G_2)}} (\text{deg}_{G_2}(u) + \text{deg}_{G_2}(v)) d_{G_2}(u, v) \\
 &+ \frac{1}{2} \sum_{\substack{u=z \\ v \in V(G_2)}} (\text{deg}_{G_1}(y) + \text{deg}_{G_2}(z) + \text{deg}_{G_2}(v)) d_{G_2}(v, z) \\
 &+ \frac{1}{2} \sum_{\substack{y \neq u \in V(G_1) \\ z \neq v \in V(G_2)}} (\text{deg}_{G_1}(u) + \text{deg}_{G_2}(v)) (d_{G_1}(u, y) + d_{G_2}(v, z)) \\
 &= D'(G_1) + D'(G_2) + (|V(G_2)| - 1) \sum_{y \neq u \in V(G_1)} \text{deg}_{G_1}(u) d_{G_1}(u, y) \\
 &+ (|V(G_1)| - 1) \sum_{z \neq v \in V(G_2)} \text{deg}_{G_2}(v) d_{G_2}(v, z) + 2|E(G_1)|D(z) \\
 &+ 2|E(G_2)|D(y),
 \end{aligned}$$

and,

$$\begin{aligned}
D'((G_1 \sim G_2)(y, z)) &= \frac{1}{2} \sum_{u, v} (deg_{(G_1 \sim G_2)(y, z)}(u)) d_{(G_1 \sim G_2)(y, z)}(u, v) \\
&+ \frac{1}{2} \sum_{u, v} (deg_{(G_1 \sim G_2)(y, z)}(v)) d_{(G_1 \sim G_2)(y, z)}(u, v) \\
&= \frac{1}{2} \sum_{\substack{u, v \neq y \\ u, v \in V(G_1)}} (deg_{G_1}(u) + deg_{G_1}(v)) d_{G_1}(u, v) \\
&+ \frac{1}{2} \sum_{\substack{u=y \\ v \in V(G_1)}} (deg_{G_1}(y) + 1 + deg_{G_1}(v)) d_{G_1}(v, y) \\
&+ \frac{1}{2} \sum_{\substack{u, v \neq z \\ u, v \in V(G_2)}} (deg_{G_2}(u) + deg_{G_2}(v)) d_{G_2}(u, v) \\
&+ \frac{1}{2} \sum_{\substack{u=z \\ v \in V(G_2)}} (1 + deg_{G_2}(z) + deg_{G_2}(v)) d_{G_2}(v, z) \\
&+ \sum_{\substack{v=z \\ u \neq y \in V(G_1)}} (1 + deg_{G_2}(z) + deg_{G_1}(u)) (1 + d_{G_1}(u, y)) \\
&+ \frac{1}{2} \sum_{\substack{y \neq u \in V(G_1) \\ z \neq v \in V(G_2)}} (deg_{G_1}(u) + deg_{G_2}(v)) (d_{G_1}(u, y) + d_{G_2}(v, z) + 1) \\
&+ deg_{G_1}(y) + deg_{G_2}(z) + 2 \\
&= |V(G_2)| \sum_{y \neq u \in V(G_1)} deg_{G_1}(u) d_{G_1}(u, y) \\
&+ |V(G_1)| \sum_{z \neq v \in V(G_2)} deg_{G_2}(v) d_{G_2}(v, z) \\
&+ (2|E(G_1)| + 2)D(z) + D'(G_1) \\
&+ (2|E(G_2)| + 2)D(y) + D'(G_2) \\
&+ (|V(G_2)| - 1)(2|E(G_1)| + 1) + 2|E(G_1)| \\
&+ (|V(G_1)| - 1)(2|E(G_2)| + 1) + 2|E(G_2)| + 2.
\end{aligned}$$

This completes our proof. \square

Lemma 2.7. Suppose G_1 and G_2 are connected graphs and λ, j are positive integers. Define $D^j(z, G) = \sum_{v \in V(G)} d_G^j(v, z)$. Then

$$\begin{aligned}
W_\lambda((G_1 \cdot G_2)(y, z)) &= W_\lambda(G_1) + W_\lambda(G_2) + [(|V(G_1)| - 1)D^\lambda(z, G_2) \\
&+ \binom{\lambda}{1} D(y, G_1) D^{\lambda-1}(z, G_2) + \dots \\
&+ \binom{\lambda}{\lambda-1} D^{\lambda-1}(y, G_1) D(z, G_2) \\
&+ (|V(G_2)| - 1)D^\lambda(y, G_1)].
\end{aligned}$$

Proof. By Lemma 2.1,

$$\begin{aligned}
 W_\lambda((G_1 \cdot G_2)(y, z)) &= \frac{1}{2} \sum_{u,v} d_{G_1 \cdot G_2}^\lambda(u, v) \\
 &= \frac{1}{2} \sum_{u,v \in V(G_1)} d_{G_1}^\lambda(u, v) + \frac{1}{2} \sum_{u,v \in V(G_2)} d_{G_2}^\lambda(u, v) \\
 &+ \sum_{\substack{y \neq u \in V(G_1) \\ z \neq v \in V(G_2)}} d_{G_1 \cdot G_2}^\lambda(u, v) \\
 &= W_\lambda(G_1) + W_\lambda(G_2) + \sum_{\substack{y \neq u \in V(G_1) \\ z \neq v \in V(G_2)}} (d_{G_1}(u, y) + d_{G_2}(v, z))^\lambda \\
 &= W_\lambda(G_1) + W_\lambda(G_2) + \sum_{\substack{y \neq u \in V(G_1) \\ z \neq v \in V(G_2)}} \left(\sum_{i=0}^{\lambda} \binom{\lambda}{i} d_{G_1}^i(u, y) d_{G_2}^{\lambda-i}(v, z) \right) \\
 &= W_\lambda(G_1) + W_\lambda(G_2) + [(|V(G_1)| - 1)D^\lambda(z, G_2) \\
 &+ \binom{\lambda}{1}D(y, G_1)D^{\lambda-1}(z, G_2) + \dots + \binom{\lambda}{\lambda-1}D^{\lambda-1}(y, G_1)D(z, G_2) \\
 &+ (|V(G_2)| - 1)D^\lambda(y, G_1)],
 \end{aligned}$$

proving the lemma. □

Corollary 2.8. The Wiener, hyper-Wiener and TSZ indices of the splices of graphs are computed as follows:

$$\begin{aligned}
 W((G_1 \cdot G_2)(y, z)) &= W(G_1) + W(G_2) + (|V(G_1)| - 1)D(z, G_2) \\
 &+ (|V(G_2)| - 1)D(y, G_1),
 \end{aligned}$$

$$\begin{aligned}
 WW((G_1 \cdot G_2)(y, z)) &= WW(G_1) + WW(G_2) + \frac{1}{2}(|V(G_1)| - 1)D(z, G_2) \\
 &+ \frac{1}{2}(|V(G_2)| - 1)D(y, G_1) + 2D(y, G_1)D(z, G_2) \\
 &+ \frac{1}{2}(|V(G_2)| - 1)D^2(y, G_1) + \frac{1}{2}(|V(G_1)| - 1)D^2(z, G_2),
 \end{aligned}$$

$$\begin{aligned}
 TSZ((G_1 \cdot G_2)(y, z)) &= TSZ(G_1) + TSZ(G_2) + \frac{1}{3}(|V(G_1)| - 1)D(z, G_2) \\
 &+ D(y, G_1)D^2(z, G_2) + D^2(y, G_1)D(z, G_2) \\
 &+ \frac{1}{6}(|V(G_1)| - 1)D^3(z, G_2) + 2D(y, G_1)D(z, G_2) \\
 &+ \frac{1}{2}(|V(G_2)| - 1)D^2(y, G_1) + \frac{1}{2}(|V(G_1)| - 1)D^2(z, G_2) \\
 &+ \frac{1}{3}(|V(G_2)| - 1)D(y, G_1) + \frac{1}{6}(|V(G_2)| - 1)D^3(y, G_1).
 \end{aligned}$$

□

Lemma 2.9. Suppose G_1 and G_2 are connected graphs. The Wiener and hyper-Wiener indices of the links of graphs G_1 and G_2 are computed as follows:

$$\begin{aligned} W((G_1 \sim G_2)(y, z)) &= W(G_1) + W(G_2) + |V(G_1)|D(z, G_2) \\ &\quad + |V(G_2)|D(y, G_1) + |V(G_1)||V(G_2)|, \\ \\ WW((G_1 \sim G_2)(y, z)) &= WW(G_1) + WW(G_2) + \frac{3}{2}|V(G_1)|D(z, G_2) \\ &\quad + \frac{3}{2}|V(G_2)|D(y, G_1) + D(y, G_1)D(z, G_2) \\ &\quad + \frac{1}{2}|V(G_2)|D^2(y, G_1) + \frac{1}{2}|V(G_1)|D^2(z, G_2) \\ &\quad + |V(G_1)||V(G_2)|. \end{aligned}$$

□

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