

SURFACES WITH POINTWISE 1-TYPE GAUSS MAP

DONG-SOO KIM

ABSTRACT. In this article, we study generalized slant cylindrical surfaces (GSCS's) with pointwise 1-type Gauss map of the first and second kinds. Our main results state that GSCS's with pointwise 1-type Gauss map of the first kind coincide with surfaces of revolution with constant mean curvature; and the right cones are the only polynomial kind GSCS's with pointwise 1-type Gauss map of the second kind.

1. INTRODUCTION AND PRELIMINARIES

The notion of finite type submanifolds in Euclidean or pseudo-Euclidean space, introduced by B.-Y. Chen during the late 1970's, has become a useful tool for investigating and characterizing many important submanifolds (cf. [3, 4]). In [1, 2, 6] the notion of finite type was extended to differential maps, in particular, to Gauss map of submanifolds.

If a submanifold M of Euclidean or pseudo-Euclidean space has 1-type Gauss map G , then G satisfies $\Delta G = \lambda(G + C)$ for some $\lambda \in \mathbb{R}$ and some constant vector C , where Δ is the Laplace operator corresponding to the induced metric on M (cf [1, 2, 9]). However, the Laplacian of the Gauss map of several important surfaces such as helicoids, catenoids and right cones take a somewhat different form; namely,

$$(1.1) \quad \Delta G = f(G + C)$$

for some non-constant function f and some constant vector C . For this reason, a submanifold is said to have *pointwise 1-type Gauss map* if its Gauss map satisfies (1.1) for some smooth function f on M and vector C . A submanifold with pointwise 1-type Gauss map is said to be *of the first kind* if the vector C in (1.1) is the zero

Received by the editors September 26, 2011. Revised Oct. 19, 2011. Accepted Oct. 20, 2011.

2000 *Mathematics Subject Classification.* 53B25, 53C40.

Key words and phrases. cylindrical surfaces, slant cylindrical surfaces, generalized slant cylindrical surfaces, pointwise 1-type Gauss map.

This study was financially supported by Chonnam National University, 2010.

vector. Otherwise, the pointwise 1-type Gauss map is said to be *of the second kind* ([5]).

Let M be a surface of Euclidean 3-space \mathbb{E}^3 . The map $G : M \rightarrow S^2 \subset \mathbb{E}^3$ which sends each point of M to the unit normal vector to M at the point is called the *Gauss map* of the surface M , where S^2 is the unit sphere in \mathbb{E}^3 centered at the origin.

For the matrix $g = (g_{ij})$ consisting of the components of the metric on M , we denote by $g^{-1} = (g^{ij})$ (resp. \mathcal{G}) the inverse matrix (resp. the determinant) of the matrix (g_{ij}) . The Laplacian Δ on M is, in turn, given by

$$(1.2) \quad \Delta = -\frac{1}{\sqrt{\mathcal{G}}} \sum_{i,j} \frac{\partial}{\partial x^i} \left(\sqrt{\mathcal{G}} g^{ij} \frac{\partial}{\partial x^j} \right).$$

Here, we give an example of surfaces of revolution with pointwise 1-type Gauss map of the second kind.

Example 1.1. Consider the right cone C_a which is parameterized by

$$x(u, v) = (v \cos u, v \sin u, av), \quad a \geq 0.$$

Then the Gauss map G and its Laplacian ΔG are respectively given by

$$G = \frac{1}{\sqrt{1+a^2}} (a \cos u, a \sin u, -1)$$

and

$$\Delta G = \frac{1}{v^2} \left(G + \left(0, 0, \frac{1}{\sqrt{1+a^2}} \right) \right).$$

It implies that the right cone has pointwise 1-type Gauss map of the second kind.

In [5], B.-Y. Chen, M. Choi and Y.H. Kim studied surfaces of revolution with pointwise 1-type Gauss map. In [7], U. Dursun studied flat surfaces in Euclidean 3-space with pointwise 1-type Gauss map.

The author and Y.H. Kim introduced the class of generalized slant cylindrical surfaces (GSCS's) in [8]. This class includes surfaces of revolution and cylindrical surfaces as special cases. Thus, we need to consider the GSCS's in \mathbb{E}^3 with pointwise 1-type Gauss map.

In this paper, we study the GSCS's with pointwise 1-type Gauss map. In particular, we prove that GSCS's with pointwise 1-type Gauss map of the first kind coincide with surfaces of revolution with constant mean curvature; and the right cones are the only polynomial kind GSCS's with pointwise 1-type Gauss map of the second kind.

Hereafter, all objects are assumed to be connected and smooth unless mentioned otherwise.

2. GENERALIZED SLANT CYLINDRICAL SURFACES

For a fixed unit speed plane curve $X(s) = (x(s), y(s), 0)$, let $T(s) = X'(s)$ and $N(s) = (-y'(s), x'(s), 0)$ denote the unit tangent and principal normal vector, respectively. The curvature $\kappa(s)$ of $X(s)$ is defined by $T'(s) = \kappa(s)N(s)$ and we have $T(s) \times N(s) = V$, where V denotes the unit vector $(0, 0, 1)$. For a constant θ , we let $Y_\theta(s) = \cos \theta N(s) + \sin \theta V$. Then the ruled surface M defined by

$$(2.1) \quad F(s, t) = X(s) + tY_\theta(s)$$

is regular at (s, t) where $1 - \cos \theta \kappa(s)t$ does not vanish. This ruled surface M is called a *slant cylindrical surface (SCS)* over $X(s)$. For the unit normal vector $G = -\sin \theta N(s) + \cos \theta V$, M satisfies

$$\langle F_s, F_t \rangle = 0, \langle F_{st}, G \rangle = 0.$$

This shows that the coordinate lines of F are lines of curvature of M with corresponding principal curvatures

$$(2.2) \quad k_1(s, t) = \frac{-\kappa(s) \sin \theta}{1 - \kappa(s)t \cos \theta}, k_2(s, t) = 0,$$

respectively. The SCS with $\sin \theta = 0$ or $\cos \theta = 0$ is nothing but a parametrization of either a plane or a cylindrical surface.

In general, we consider another unit speed plane curve $W(t) = (z(t), w(t))$. If we let $Y_s(t) = z(t)N(s) + w(t)V$, then the parametrized surface defined by

$$(2.3) \quad H(s, t) = X(s) + Y_s(t)$$

is regular at (s, t) where $1 - \kappa(s)z(t)$ does not vanish. This parametrized surface M is called a *generalized slant cylindrical surface (GSCS)* over $X(s)$. For the unit normal vector $G(s, t) = -w'(t)N(s) + z'(t)V$, M satisfies

$$\langle H_s, H_t \rangle = 0, \langle H_{st}, G \rangle = 0.$$

This shows that $H(s, t)$ is a principal curvature coordinate system of M with corresponding principal curvatures

$$(2.4) \quad k_1(s, t) = \frac{-\kappa(s)w'(t)}{1 - \kappa(s)z(t)}, k_2(s, t) = \kappa(t),$$

respectively, where $\kappa(t) = z'(t)w''(t) - z''(t)w'(t)$ denotes the curvature of $W(t)$.

If $W(t)$ is a straight line, then the GSCS $H(s, t)$ is nothing but a SCS. If $X(s)$ is a straight line, then the GSCS $H(s, t)$ is nothing but a cylindrical surface. Furthermore, we have the following ([8]).

Proposition 2.1. *If $X(s)$ is a circle, then GSCS M over $X(s)$ is a surface of revolution.*

Therefore cylindrical surfaces and surfaces of revolution are special cases of GSCS's.

Now we give the following:

Proposition 2.2. *Let M denote a GSCS given by (2.3). Then we have the following.*

- (1) *If the mean curvature H is constant, then M is a surface of revolution.*
- (2) *If the Gaussian curvature K is constant, then M is either a surface of revolution or an SCS.*

Proof. It follows from (2.4) that

$$(2.5) \quad 2H = \kappa(t) + \frac{-\kappa(s)w'(t)}{1 - \kappa(s)z(t)}, \quad K = \frac{-\kappa(s)\kappa(t)w'(t)}{1 - \kappa(s)z(t)}.$$

Hence we have

$$(2.6) \quad \kappa(t) - 2H = \kappa(s)\{\kappa(t)z(t) - 2Hz(t) + w'(t)\},$$

and

$$(2.7) \quad K = \kappa(s)\{Kz(t) - \kappa(t)w'(t)\}.$$

Suppose that H is constant. If $\kappa(t) - 2H \neq 0$, then (2.6) shows that $\kappa(s)$ is a nonzero constant, and hence M is a surface of revolution. If $\kappa(t) - 2H = 0$, then (2.5) implies $\kappa(s)w'(t) = 0$. In case $\kappa(s_0) \neq 0$ for some s_0 , $w'(t)$ vanishes identically, and hence M is a part of a plane. Otherwise, $\kappa(s)$ vanishes identically. Hence $X(s)$ is a straight line. Thus M is a part of a plane ($H = 0$) or a circular cylinder ($H \neq 0$).

Now suppose that K is constant. If $K \neq 0$, it follows from (2.7) that $\kappa(s)$ is a nonzero constant, and hence M is a surface of revolution. In case $K = 0$ and $\kappa(s_0) \neq 0$, (2.7) shows that $\kappa(t)$ vanishes identically, and hence M is an SCS. In case $K = 0$ and $\kappa(s)$ vanish identically, then M is a cylindrical surface. \square

3. GSCS'S WITH POINTWISE 1-TYPE GAUSS MAP OF THE FIRST KIND

Let $X(s) = (x(s), y(s), 0)$ be a unit speed plane curve with the Frenet frame $\{T(s), N(s)\}$. We consider GSCS's parametrized by

$$(3.1) \quad H(s, t) = X(s) + Y_s(t),$$

where $W(t) = (z(t), w(t))$ is a unit speed plane curve, $Y_s(t) = z(t)N(s) + w(t)V$, and $V = (0, 0, 1)$. Then $H(s, t)$ is regular at (s, t) where $Q(s, t) = 1 - \kappa(s)z(t)$ does not vanish and we get

$$(3.2) \quad \begin{aligned} H_s &= Q(s, t)T(s), & H_t &= z'(t)N(s) + w'(t)V, \\ G(s, t) &= -w'(t)N(s) + z'(t)V. \end{aligned}$$

The Laplacian Δ on M is given by

$$(3.3) \quad \Delta f = -Q^{-3}\{\kappa'(s)z(t)f_s + Qf_{ss} - Q^2\kappa(s)z'(t)f_t + Q^3f_{tt}\}.$$

Hence it follows from (3.2) and (3.3) that

$$(3.4) \quad \begin{aligned} -Q^3\Delta G &= \kappa'(s)w'(t)T(s) + Q\{\kappa(s)^2w'(t) + Q\kappa(s)z'(t)w''(t) \\ &\quad - Q^2w'''(t)\}N(s) + Q^2\{-\kappa(s)z'(t)z''(t) + Qz'''(t)\}V. \end{aligned}$$

Now suppose that M has the pointwise 1-type Gauss map G which satisfies (1.1). Then, letting $C = C_1(s)T(s) + C_2(s)N(s) + C_3V$, we have the following.

$$(3.5) \quad \kappa'(s)w'(t) = -Q^3C_1(s)f(s, t),$$

$$(3.6) \quad \kappa(s)^2w'(t) + Q\kappa(s)z'(t)w''(t) - Q^2w'''(t) = Q^2f(s, t)\{w'(t) - C_2(s)\},$$

and

$$(3.7) \quad \kappa(s)z'(t)z''(t) - Qz'''(t) = Qf(s, t)\{z'(t) + C_3\}.$$

Using above, we get the following:

Theorem 3.1. *Let M be a GSCS given by (3.1). Suppose that M has pointwise 1-type Gauss map G of the first kind. Then M is a surface of revolution.*

Proof. Since $C = C_1(s)T(s) + C_2(s)N(s) + C_3V = 0$, it follows from (3.5) that $\kappa'(s)w'(t) = 0$. In case $\kappa'(s_0) \neq 0$ for some s_0 , $w(t)$ is constant, and hence M is a part of a plane. Otherwise, κ is constant. If κ is nonzero, then M is a surface of revolution. If $\kappa = 0$, then it follows from (3.6) and (3.7) that

$$(3.8) \quad z'''(t) + f(s, t)z'(t) = 0, \quad w'''(t) + f(s, t)w'(t) = 0.$$

This shows that $\kappa'(t) = 0$. Thus M is a plane or a circular cylinder. □

Combining Theorem 3.1 in [5] and Proposition 2.2, Theorem 3.1 shows directly the following.

Corollary 3.2. *Let M be a GSCS given by (3.1). Then the following are equivalent.*

- (1) M has pointwise 1-type Gauss map G of the first kind.
- (2) M has constant mean curvature.
- (3) M is a surface of revolution with constant mean curvature.

Remark 3.3. Surfaces of revolution with constant mean curvature are also known as *surfaces of Delaunay* (cf. [10, p.115]).

4. GSCS'S WITH POINTWISE 1-TYPE GAUSS MAP OF THE SECOND KIND

Consider a GSCS M parametrized by (3.1). If M is not cylindrical, then $W(t)$ can be parametrized by $W(t) = (t, g(t))$ for some function $g = g(t)$. Hence M is given by

$$(4.1) \quad H(s, t) = X(s) + tN(s) + g(t)V.$$

If $g(t)$ is a polynomial in t , Then M is said to be of polynomial kind ([5]). $H(s, t)$ is regular at (s, t) where $Q(s, t) = 1 - t\kappa(s) \neq 0$ and we get

$$(4.2) \quad \begin{aligned} H_s &= Q(s, t)T(s), H_t = N(s) + g'(t)V, \\ G(s, t) &= \frac{1}{P(t)}\{-g'(t)N(s) + V\}, P(t) = \sqrt{1 + g'(t)^2}. \end{aligned}$$

The Laplacian Δ on M is given by

$$(4.3) \quad \begin{aligned} \Delta f &= -P^{-4}Q^{-3}\{\kappa'(s)tP^4f_s + P^4Qf_{ss} \\ &\quad - (P^2Q^2\kappa(s) + Q^3g'g'')f_t + P^2Q^3f_{tt}\}. \end{aligned}$$

Hence it follows from (4.2) and (4.3) that

$$(4.4) \quad \begin{aligned} \Delta G &= -\kappa'(s)g'P^{-1}Q^{-3}T(s) \\ &\quad - P^{-7}Q^{-2}\{\kappa(s)^2g'P^6 + \kappa(s)g''P^2Q \\ &\quad + g'(g'')^2Q^2 - g'''P^2Q^2 + 3g'(g'')^2Q^2\}N(s) \\ &\quad - P^{-7}Q^{-1}\{3(g')^2(g'')^2 - (g'')^2 - g'g''' - (g')^3g'''\}Q + \kappa(s)g'g''P^2\}V. \end{aligned}$$

Suppose that the Gauss map G satisfies (1.1) with nonzero constant vector C . Then, letting $C = C_1(s)T(s) + C_2(s)N(s) + C_3V$, we have the following.

$$(4.5) \quad PQ^3C_1(s)f(s, t) + \kappa'(s)g'(t) = 0,$$

$$(4.6) \quad \begin{aligned} &P^6Q^2f(s,t)\{-g'(t) + PC_2(s)\} + \kappa(s)^2g'P^6 \\ &+ \kappa(s)g''P^2Q + g'(g'')^2Q^2 - g'''P^2Q^2 + 3g'(g'')^2Q^2 = 0, \end{aligned}$$

and

$$(4.7) \quad \begin{aligned} &P^6Qf(s,t)\{1 + C_3P\} + \{3(g')^2(g'')^2 \\ &- (g'')^2 - g'g''' - (g')^3g'''\}Q + \kappa(s)g'g''P^2 = 0. \end{aligned}$$

It follows from (4.5) and (4.7) that

$$(4.8) \quad \begin{aligned} &C_3\kappa'(s)g'P^6 + \kappa'(s)g'P^5 \\ &= C_1(s)Q^3\{3(g')^2(g'')^2 - (g')^3g'''\} + C_1(s)\kappa(s)g'g''P^2Q^2 \\ &- C_1(s)Q^3\{(g'')^2 + g'g'''\} \end{aligned}$$

Suppose that M is a GSCS of polynomial kind, that is, $g(t)$ is a polynomial in t . Denote by $\text{deg}g(t)$ the degree of $g(t)$.

If $\text{deg}g(t) = n \geq 2$, then P^2 is a polynomial of degree $2n - 2$. By comparing the degree of both sides of (4.8), we see that $C_3\kappa'(s) = 0$, and hence we get

$$(4.9) \quad \begin{aligned} \kappa'(s)g'P^5 &= C_1(s)Q^3\{3(g')^2(g'')^2 - (g')^3g'''\} + C_1(s)\kappa(s)g'g''P^2Q^2 \\ &- C_1(s)Q^3\{(g'')^2 + g'g'''\}. \end{aligned}$$

By comparing the degree of both sides of (4.9), we see that $\kappa'(s) = 0$. Thus, if $\kappa \neq 0$, M is a surface of revolution. If $\kappa = 0$, then T, N are constant vectors and M is a cylindrical surface over a plane curve $W(t)$. Since $Q = 1$, we have from (4.4)

$$(4.10) \quad \begin{aligned} \Delta G &= -P^{-7}\{g'(g'')^2 - g'''P^2 + 3g'(g'')^2\}N \\ &- P^{-7}\{3(g')^2(g'')^2 - (g'')^2 - g'g''' - (g')^3g'''\}V. \end{aligned}$$

Using (1.1), we get $C_1 = 0, C'_2 = C'_3 = 0$, and

$$(4.11) \quad \{1 + (g')^2\}\{C_2A - C_2B - C_3D\}^2 = \{g'A - g'B + D\}^2,$$

where

$$(4.12) \quad \begin{aligned} A &= 3(g')^2(g'')^2 - (g')^3g''', \quad B = (g'')^2 + g'g''', \\ D &= 4g'(g'')^2 - g''' - (g')^2g'''. \end{aligned}$$

By comparing the coefficient of highest degree of both sides of (4.11), we get $C_2^2 = 1$, and hence again we get $C_3 = 0$. This shows that the coefficient of highest degree of $g'AD$ becomes zero, which is a contradiction.

If $\text{deg}g(t) = 1$, then M is a slant cylindrical (non-cylindrical) surface. Note that $P = \sqrt{1 + a^2}$, where $g'(t) = a \neq 0$. By applying (4.5) and (4.6), we get

$$(4.13) \quad PQ^3C_1(s)f(s,t) + a\kappa'(s) = 0,$$

and

$$(4.14) \quad Q^2 f(s, t) \{PC_2(s) - a\} + a\kappa(s)^2 = 0.$$

Suppose that $\kappa'(s_0) \neq 0$ for some s_0 . Then on an interval I , we have $\kappa'(s) \neq 0$. On I , $f(s, t)$ is given by

$$(4.15) \quad f(s, t) = \frac{-a\kappa'(s)}{PQ^3C_1(s)}.$$

Hence, by applying $Q = 1 - \kappa(s)t$, it follows from (4.13) and (4.14) that

$$(4.16) \quad aP\kappa(s)^2C_1(s) - aP\kappa'(s)C_2(s) + a^2\kappa'(s) - aP\kappa(s)^3C_1(s)t = 0.$$

The coefficient of t in (4.16) must vanish, and hence $C_1(s) = 0$ on I , which contradicts to (4.13). This contradiction shows that $\kappa(s)$ is a constant. Therefore M is a plane or a right circular cone.

Summarizing above, we obtain

Theorem 4.1. *Suppose that a GSCS M of polynomial kind has pointwise 1-type Gauss map G of the second kind. Then M is a surface of revolution.*

Hence, combining Theorem 4.1 in [5], we get

Corollary 4.2. *A GSCS M of polynomial kind has the pointwise 1-type Gauss map G of the second kind if and only if it is a plane or a right circular cone.*

REFERENCES

1. C. Baikoussis & D. E. Blair: On the Gauss map of ruled surfaces. *Glasgow Math. J.* **34** (1992), 355-359.
2. C. Baikoussis, B.-Y. Chen & L. Verstraelen: Ruled surfaces and tubes with finite type Gauss map. *Tokyo J. Math.* **16** (1993), 341-348.
3. B.-Y. Chen: *Total mean curvature and submanifolds of finite type*. World Scientific Publ., New Jersey (1984).
4. ———: *Finite type submanifolds and generalizations*. University of Rome (1985).
5. B.-Y. Chen, M. Choi & Y.H. Kim: Surfaces of revolution with pointwise 1-type Gauss map. *J. Korean Math. Soc.* **42** (2005), 447-455.
6. B.-Y. Chen & P. Piccinni: Submanifolds with finite type Gauss map. *Bull. Austral. Math. Soc.* **35** (1987), 161-186.
7. U. Dursun: Flat surfaces in the Euclidean space E^3 with pointwise 1-type Gauss map. *Bull. Malays. Math. Sci. Soc.(2)* **33** (2010), no. 3, 469-478.
8. D.-S. Kim & Y.H. Kim: Surfaces with planar lines of curvature. *Honam Math. J.* **32** (2010), 777-790.

9. Y.H. Kim & D.W. Yoon: Ruled surfaces with finite type Gauss map in Minkowski spaces. *Soochow J. Math.* **26** (2000), 85-96.
10. J. Oprea: *Differential geometry and its applications*. Prentice Hall, New Jersey, 1997.

DEPARTMENT OF MATHEMATICS, CHONNAM NATIONAL UNIVERSITY, KWANGJU 500-757, KOREA
Email address: dosokim@chonnam.ac.kr