

GENERALIZED RELAXED PROXIMAL POINT ALGORITHMS INVOLVING RELATIVE MAXIMAL ACCRETIVE MODELS WITH APPLICATIONS IN BANACH SPACES

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ABSTRACT. General models for the relaxed proximal point algorithm using the notion of relative maximal accretiveness (RMA) are developed, and then the convergence analysis for these models in the context of solving a general class of nonlinear inclusion problems differs significantly than that of Rockafellar (1976), where the local Lipschitz continuity at zero is adopted instead. Moreover, our approach not only generalizes convergence results to real Banach space settings, but also provides a suitable alternative to other problems arising from other related fields.

1. Introduction

Let X be a real Banach space with X^* , the dual space of X . Let $\|\cdot\|$ denote the norm on X and X^* , and let $\langle \cdot, \cdot \rangle$ denote the duality pairing between X and X^* . We consider the inclusion problem: find a solution to

$$(1) \quad 0 \in M(g(x)),$$

where $M : X \rightarrow 2^X$ is a set-valued mapping on X , and $g : X \rightarrow X$ is a single-valued mapping on X such that $\text{range}(g) \cap \text{dom}(M) \neq \emptyset$.

Just recently, the author [15] based on the work of Eckstein and Bertsekas [2] generalized the relaxed version of the proximal point algorithm and has shown that the sequence converges linearly to a solution of (1). On applying a local Lipschitz condition on the mapping M^{-1} and with a more strengthened error tolerance, a convergence rate was obtained for the ordinary proximal point algorithm by Rockafellar [10], while Eckstein and Bertsekas [2] introduced a more relaxed version of the proximal point algorithm and applied the obtained results to the Douglas-Rachford splitting method for finding the zero of the sum of two monotone operators. Motivated by these algorithmic developments, we

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generalize the relaxed proximal point algorithm based on the notion of relative maximal accretiveness [1] for solving general inclusion problems in Banach space settings. This notion generalizes the general theory of maximal accretive set-valued mappings in a Banach space setting. In order to achieve local convergence, our approach differs significantly than that of Rockafellar [10], where the local Lipschitz type condition on the mapping M^{-1} is imposed to derive the convergence rate estimate.

In this communication, our aim is to introduce relative maximal accretiveness (RMA) models and then apply them to approximation solvability of variational inclusion problems of the form (1) in a real Banach space setting. Unlike other existing notions, RMA models are applicable to other problems arising from several other fields, such as equilibria problems in economics, applied optimization and control theory, operations research, mathematical finance, management and decision sciences, and mathematical programming. For more details on the resolvent operator technique and its applications, and further developments, we refer the reader [1-38].

2. Relative maximal accretiveness (RMA)

In this section we discuss some results based on the basic properties and auxiliary results on relative maximal accretiveness. Let X be a real Banach space and X^* be the dual space of X . Let $\|\cdot\|$ denote the norm on X and X^* , and let $\langle \cdot, \cdot \rangle$ denote the duality pairing between X and X^* . Let $M : X \rightarrow 2^X$ be a multivalued mapping on X . We shall denote both the map M and its graph by M , that is, the set $\{(x, y) : y \in M(x)\}$. This is equivalent to stating that a mapping is any subset M of $X \times X$, and $M(x) = \{y : (x, y) \in M\}$. If M is single-valued, we shall still use $M(x)$ to represent the unique y such that $(x, y) \in M$ rather than the singleton set $\{y\}$. This interpretation shall much depend on the context. The domain of a map M is defined (as its projection onto the first argument) by

$$D(M) = \{x \in X : \exists y \in X : (x, y) \in M\} = \{x \in X : M(x) \neq \emptyset\}.$$

$D(M) = X$, shall denote the full domain of M , and the range of M is defined by

$$R(M) = \{y \in X : \exists x \in X : (x, y) \in M\}.$$

The inverse M^{-1} of M is $\{(y, x) : (x, y) \in M\}$. For a real number ρ and a mapping M , let $\rho M = \{x, \rho y) : (x, y) \in M\}$. If L and M are any mappings, we define

$$L + M = \{(x, y + z) : (x, y) \in L, (x, z) \in M\}.$$

As we prepare for basic notions, we start with the generalized duality mapping $J_q : X \rightarrow 2^{X^*}$

$$J_q(x) = \{f^* \in X^* : \langle x, f^* \rangle = \|x\|^q, \|f^*\| = \|x\|^{q-1}\} \quad \forall x \in X,$$

where $q > 1$. As a special case, J_2 is the normalized duality mapping, and $J_q(x) = \|x\|^{q-2}J_2(x)$ for $x \neq 0$. Next, as we head to uniformly smooth Banach spaces, we define the modulus of smoothness $\rho_X : [0, \infty) \rightarrow [0, \infty)$ by

$$\rho_X(t) = \sup \left\{ \frac{1}{2}(\|x+y\| + \|x-y\|) - 1 : \|x\| \leq 1, \|y\| \leq t \right\}.$$

A Banach space X is uniformly smooth if

$$\lim_{t \rightarrow 0} \frac{\rho_X(t)}{t} = 0,$$

and X is q -uniformly smooth if there is a positive constant c such that

$$\rho_X(t) \leq ct^q, \quad q > 1.$$

Note that J_q is single-valued if X is uniformly smooth. In this context, we state the following lemma from Xu [34].

Lemma 2.1 ([34]). *Let X be a uniformly smooth Banach space. Then X is q -uniformly smooth if there exists a positive constant c_q such that*

$$\|x+y\|^q \leq \|x\|^q + q\langle y, J_q(x) \rangle + c_q\|y\|^q,$$

where $q > 1$.

Lemma 2.2. *For any two nonnegative real numbers a and b , we have*

$$(a+b)^q \leq 2^q(a^q + b^q) \quad \text{for } q > 1.$$

Definition 2.1. Let $M : X \rightarrow 2^X$ be a multivalued mapping on X and $q > 1$. The map M is said to be:

(i) accretive if

$$\langle u^* - v^*, J_q(u - v) \rangle \geq 0 \quad \forall (u, u^*), (v, v^*) \in M.$$

(ii) (r)-strongly accretive if there exists a positive constant r such that

$$\langle u^* - v^*, J_q(u - v) \rangle \geq r\|u - v\|^q \quad \forall (u, u^*), (v, v^*) \in M.$$

(iii) (m)-relaxed accretive if there exists a positive constant m such that

$$\langle u^* - v^*, J_q(u - v) \rangle \geq (-m)\|u - v\|^q \quad \forall (u, u^*), (v, v^*) \in M.$$

(iv) (c)-cocoercively accretive if there exists a positive constant c such that

$$\langle u^* - v^*, J_q(u - v) \rangle \geq c\|u^* - v^*\|^q \quad \forall (u, u^*), (v, v^*) \in M.$$

Definition 2.2. Let $A, B : X \rightarrow X$ be single-valued mappings on X and $q > 1$. The map A is said to be:

(i) (γ)-cocoercively accretive with respect to B if there exists a positive constant γ such that

$$\langle B(u) - B(v), J_q(A(u) - A(v)) \rangle \geq \gamma\|A(u) - A(v)\|^q \quad \forall u, v \in X.$$

(ii) cocoercively accretive with respect to B if

$$\langle B(u) - B(v), J_q(A(u) - A(v)) \rangle \geq \|A(u) - A(v)\|^q \quad \forall u, v \in X.$$

(iii) (γ) -cocoercively accretive if

$$\langle u - v, J_q(A(u) - A(v)) \rangle \geq \gamma \|A(u) - A(v)\|^q \quad \forall u, v \in X.$$

(iv) cocoercively accretive if

$$\langle u - v, J_q(A(u) - A(v)) \rangle \geq \|A(u) - A(v)\|^q \quad \forall u, v \in X.$$

Definition 2.3. Let $A : X \rightarrow X$ be a single-valued mapping. The map $M : X \rightarrow 2^X$ is said to be relative maximal accretive if

(i) M is relative accretive (with respect to A), that is,

$$\langle u^* - v^*, J_q(A(u) - A(v)) \rangle \geq 0 \quad \forall (u, u^*), (v, v^*) \in M.$$

(ii) $R(I + \rho M) = X$ for $\rho > 0$.

Example 2.1. Let $X = (-\infty, +\infty)$, $M(x) = -x$ and $A(x) = -\frac{1}{2}x$. Then M is relative monotone (with respect to A) but not monotone.

Example 2.2. Let X be a real Hilbert space, and let $M : X \rightarrow 2^X$ be a maximal monotone mapping on X . Let $M_\rho = \rho^{-1}(I - R_\rho^M)$ denote the Yosida approximation of M , and $R_\rho^M = (I + \rho M)^{-1}$ denote the corresponding resolvent of M . Then for all $u, v \in X$,

$$M_\rho(u) \in M(R_\rho^M(u)) \quad \text{and} \quad M_\rho(v) \in M(R_\rho^M(v)).$$

Since M is maximal monotone, we have

$$\langle M_\rho(u) - M_\rho(v), R_\rho^M(u) - R_\rho^M(v) \rangle \geq 0 \quad \text{for } \rho > 0.$$

Thus, M_ρ is relative monotone (with respect to R_ρ^M).

Definition 2.4. Let $A : X \rightarrow X$ be an (r) -strongly accretive mapping and let $M : X \rightarrow 2^X$ be a relative maximal accretive mapping. Then the relative resolvent operator $J_{\rho,A}^M : X \rightarrow X$ is defined by

$$J_{\rho,A}^M(u) = (I + \rho M)^{-1}(u) \quad \text{for } \rho > 0.$$

Proposition 2.1. Let $A : X \rightarrow X$ be an (r) -strongly monotone mapping and let $M : X \rightarrow 2^X$ be a relative maximal monotone mapping. Then the operator $(I + \rho M)^{-1}$ is single-valued.

3. Generalized relaxed proximal point algorithm

This section deals with an introduction of a generalized version of the relaxed proximal point algorithm and its applications to approximation solvability of the inclusion problem (1) based on the relative maximal accretiveness.

Lemma 3.1. Let X be a real Banach space, let $A : X \rightarrow X$ be (r) -strongly accretive, and let $M : X \rightarrow 2^X$ be relative maximal accretive. In addition, if we suppose that

$$\langle J_{\rho,A}^M(u) - J_{\rho,A}^M(v), J_q(A(J_{\rho,A}^M(u)) - A(J_{\rho,A}^M(v))) \rangle \geq \|A(J_{\rho,A}^M(u)) - A(J_{\rho,A}^M(v))\|^q,$$

then the corresponding resolvent operator associated with M and defined by

$$J_{\rho,A}^M(u) = (I + \rho M)^{-1}(u) \quad \forall u \in X,$$

is $(\frac{1}{r})$ -Lipschitz continuous, where $q > 1$.

Proof. The proof follows from the definition of the resolvent operator

$$J_{\rho,A}^M(u) = (I + \rho M)^{-1}.$$

For any elements $u, v \in X$, we have

$$\rho^{-1}[u - J_{\rho,A}^M(u)] \in M(J_{\rho,A}^M(u))$$

and

$$\rho^{-1}[v - J_{\rho,A}^M(v)] \in M(J_{\rho,A}^M(v)).$$

Since M is relative maximal accretive (with respect to A), we have

$$\langle u - v - (J_{\rho,A}^M(u) - J_{\rho,A}^M(v)), J_q(A(J_{\rho,A}^M(u)) - A(J_{\rho,A}^M(v))) \rangle \geq 0.$$

It follows that

$$\begin{aligned} & \langle u - v, J_q(A(J_{\rho,A}^M(u)) - A(J_{\rho,A}^M(v))) \rangle \\ & \geq \langle J_{\rho,A}^M(u) - J_{\rho,A}^M(v), J_q(A(J_{\rho,A}^M(u)) - A(J_{\rho,A}^M(v))) \rangle \\ & \geq \|A(J_{\rho,A}^M(u)) - A(J_{\rho,A}^M(v))\|^q. \end{aligned} \quad \square$$

Lemma 3.2. Let X be a real Banach space, let $A : X \rightarrow X$ be (r) -strongly accretive, and let $M : X \rightarrow 2^X$ be relative maximal accretive. In addition, suppose that

$$\begin{aligned} & \langle J_{\rho,A}^M(u) - J_{\rho,A}^M(v), J_q(A(J_{\rho,A}^M(u)) - A(J_{\rho,A}^M(v))) \rangle \\ & \geq \gamma \|A(J_{\rho,A}^M(u)) - A(J_{\rho,A}^M(v))\|^q \text{ for } \gamma > 0, \end{aligned}$$

where $q > 1$. Then the generalized resolvent operator associated with M and defined by

$$J_{\rho,A}^M(u) = (I + \rho M)^{-1}(u) \quad \forall u \in X,$$

satisfies

$$\|J_{\rho,A}^M(u) - J_{\rho,A}^M(v)\| \leq \frac{1}{\gamma r} \|u - v\|,$$

where $\gamma > 0$.

Proof. The proofs is quite similar to that of Lemma 3.1. Since A is (r) -strongly accretive (and hence $\|A(u) - A(v)\| \geq r\|u - v\|$), we have

$$\|u - v\| \geq \gamma \|A(J_{\rho,A}^M(u)) - A(J_{\rho,A}^M(v))\|,$$

or

$$\|u - v\| \geq \gamma r \|J_{\rho,A}^M(u) - J_{\rho,A}^M(v)\|. \quad \square$$

Remark 3.1. Note that this is a new class of mappings that satisfies

$$\begin{aligned} & \langle J_{\rho,A}^M(u) - J_{\rho,A}^M(v), J_q(A(J_{\rho,A}^M(u)) - A(J_{\rho,A}^M(v))) \rangle \\ & \geq \gamma \|A(J_{\rho,A}^M(u)) - A(J_{\rho,A}^M(v))\|^q \text{ for } \gamma > 0, \end{aligned}$$

in a Banach space setting, but it coincides with the notions of the relative cocoercivity or just cocoercivity in a Hilbert space setting, for example, in following Lemmas 3.3 and 3.4.

Lemma 3.3. *Let X be a real Hilbert space, let $A : X \rightarrow X$ be (r) -strongly monotone and (γ) -cocoercive, that is,*

$$\langle A(u) - A(v), u - v \rangle \geq \gamma \|A(u) - A(v)\|^2 \text{ for } u, v \in X,$$

and let $M : X \rightarrow 2^X$ be relative maximal monotone. Then the generalized resolvent operator associated with M and defined by

$$J_{\rho,A}^M(u) = (I + \rho M)^{-1}(u) \quad \forall u \in X,$$

satisfies

$$\|J_{\rho,A}^M(u) - J_{\rho,A}^M(v)\| \leq \frac{1}{\gamma r} \|u - v\|,$$

where $\gamma > 0$.

Proof. The proof follows from the definition of the resolvent operator

$$J_{\rho,A}^M(u) = (I + \rho M)^{-1}.$$

For any elements $u, v \in X$, we have

$$\rho^{-1}[u - J_{\rho,A}^M(u)] \in M(J_{\rho,A}^M(u))$$

and

$$\rho^{-1}[v - J_{\rho,A}^M(v)] \in M(J_{\rho,A}^M(v)).$$

Since M is relative maximal monotone (with respect to A), we have

$$\langle u - v - (J_{\rho,A}^M(u) - J_{\rho,A}^M(v)), A(J_{\rho,A}^M(u)) - A(J_{\rho,A}^M(v)) \rangle \geq 0.$$

It follows that

$$\begin{aligned} & \langle u - v, A(J_{\rho,A}^M(u)) - A(J_{\rho,A}^M(v)) \rangle \\ & \geq \langle J_{\rho,A}^M(u) - J_{\rho,A}^M(v), A(J_{\rho,A}^M(u)) - A(J_{\rho,A}^M(v)) \rangle \\ & \geq \gamma \|A(J_{\rho,A}^M(u)) - A(J_{\rho,A}^M(v))\|^2. \end{aligned} \quad \square$$

Lemma 3.4. *Let X be a real Hilbert space, and let $M : X \rightarrow 2^X$ be maximal monotone. Then the resolvent operator associated with M and defined by*

$$R_{\rho}^M(u) = (I + \rho M)^{-1}(u) \quad \forall u \in X,$$

satisfies

$$\|R_{\rho}^M(u) - R_{\rho}^M(v)\| \leq \|u - v\|,$$

where $\rho > 0$.

Now we focus our attention to establish the main results on the relative maximal accretivity (RMA) relating to the approximation solvability of (1).

Theorem 3.1. *Let X be a real Banach space, let $A : X \rightarrow X$ be (r) -strongly accretive, and let $M : X \rightarrow 2^X$ be relative maximal accretive. Let $g : X \rightarrow X$ be a map on X . Then the following statements are equivalent:*

- (i) *An element $u \in X$ is a solution to (1).*
- (ii) *For an $u \in X$, we have*

$$g(u) = J_{\rho,A}^M(g(u)),$$

where

$$J_{\rho,A}^M(u) = (I + \rho M)^{-1}(u) \text{ for } \rho > 0.$$

In the following theorem, we apply the generalized relaxed proximal point algorithm to approximate the solution of (1), and as a result, we achieve linear convergence.

Theorem 3.2. *Let X be a real q -uniformly smooth Banach space, let $A : X \rightarrow X$ be (r) -strongly accretive, let $g : X \rightarrow X$ be (c) -strongly accretive, and let $M : X \rightarrow 2^X$ be relative maximal accretive (RMA). Furthermore, suppose that*

$$\begin{aligned} & \langle J_{\rho,A}^M(g(u)) - J_{\rho,A}^M(g(v)), J_q(A(J_{\rho,A}^M(g(u))) - A(J_{\rho,A}^M(g(v)))) \rangle \\ & \geq \gamma \|A(J_{\rho,A}^M(g(u))) - A(J_{\rho,A}^M(g(v)))\|^q \text{ for } \gamma > 0, \end{aligned}$$

where $q > 1$.

For an arbitrarily chosen initial point x^0 , suppose that the sequence $\{g(x^k)\}$ is generated by the generalized proximal point algorithm

$$(2) \quad g(x^{k+1}) = (1 - \alpha_k)g(x^k) + \alpha_k y^k \quad \forall k \geq 0,$$

and y^k satisfies

$$\|y^k - J_{\rho,A}^M(g(x^k))\| \leq \delta_k \|y^k - g(x^k)\|,$$

where

$$J_{\rho,A}^M = (I + \rho M)^{-1}$$

and

$$\{\delta_k\}, \{\alpha_k\} \subseteq [0, \infty)$$

are scalar sequences. Then the sequence $\{x^k\}$ converges linearly to a solution of (1) with the convergence rate

$$\limsup \frac{\theta_k + \delta_k}{1 - \delta_k} = \limsup \theta_k = [1 - \Delta(1 - \frac{1}{\gamma r})] < 1,$$

where $\gamma r > 1$, $\sum_{k=0}^{\infty} \delta_k < \infty$, $\delta_k \rightarrow 0$, $\alpha_k \leq 1$, $\Delta = \inf \alpha_k > 0$, and $\alpha = \limsup_{k \rightarrow \infty} \alpha_k$.

Proof. Suppose that x^* is a zero of M . From Theorem 3.1, it follows that any solution to (1) is a fixed point of $J_{\rho,A}^M$. Since A is (r) -strongly accretive (and hence $\|A(u) - A(v)\| \geq r\|u - v\|$) and using Lemma 3.2, we have a crucial inequality

$$(3) \quad \|J_{\rho,A}^M(g(x^k)) - J_{\rho,A}^M(g(x^*))\| \leq \frac{1}{\gamma r} \|g(x^k) - g(x^*)\|.$$

Next, for all $k \geq 0$, we express

$$g(x^{k+1}) = (1 - \alpha_k)g(x^k) + \alpha_k J_{\rho,A}^M(g(x^k)).$$

Then we find the estimate using (3) that

$$\begin{aligned} \|g(x^{k+1}) - g(x^*)\| &= \|(1 - \alpha_k)g(x^k) + \alpha_k J_{\rho,A}^M(g(x^k)) - g(x^*)\| \\ &= \|(1 - \alpha_k)(g(x^k) - g(x^*)) + \alpha_k(J_{\rho,A}^M(g(x^k)) - J_{\rho,A}^M(g(x^*)))\| \\ &\leq (1 - \alpha_k)\|g(x^k) - g(x^*)\| + \alpha_k\|J_{\rho,A}^M(g(x^k)) - J_{\rho,A}^M(g(x^*))\| \\ &\leq [(1 - \alpha_k) + \frac{\alpha_k}{\gamma r}]\|g(x^k) - g(x^*)\| \\ &= [1 - \alpha_k(1 - \frac{1}{\gamma r})]\|g(x^k) - g(x^*)\| \\ &\leq [1 - \Delta(1 - \frac{1}{\gamma r})]\|g(x^k) - g(x^*)\| \\ &= \theta_k\|g(x^k) - g(x^*)\|, \end{aligned}$$

where $\theta_k = [1 - \Delta(1 - \frac{1}{\gamma r})]$ and $\gamma r > 1$. Thus, we have

$$(4) \quad \|g(x^{k+1}) - g(x^*)\| \leq \theta_k\|g(x^k) - g(x^*)\|.$$

Since $g(x^{k+1}) = (1 - \alpha_k)g(x^k) + \alpha_k y^k$, we have

$$g(x^{k+1}) - g(x^k) = \alpha_k(y^k - g(x^k)).$$

On the other hand, we have

$$\begin{aligned} &\|g(x^{k+1}) - g(x^k)\| \\ &= \|(1 - \alpha_k)g(x^k) + \alpha_k y^k - [(1 - \alpha_k)g(x^k) + \alpha_k J_{\rho,A}^M(g(x^k))]\| \\ &= \|\alpha_k(y^k - J_{\rho,A}^M(g(x^k)))\| \\ &\leq \alpha_k \delta_k \|y^k - g(x^k)\|. \end{aligned}$$

Finally, we estimate using the above arguments that

$$\begin{aligned} &\|g(x^{k+1}) - g(x^*)\| \\ &\leq \|g(x^{k+1}) - g(x^*)\| + \|g(x^{k+1}) - g(x^k)\| \\ &\leq \|g(x^{k+1}) - g(x^*)\| + \alpha_k \delta_k \|y^k - g(x^k)\| \\ &\leq \|g(x^{k+1}) - g(x^*)\| + \delta_k \|g(x^{k+1}) - g(x^k)\| \\ (5) \quad &\leq \|g(x^{k+1}) - g(x^*)\| + \delta_k \|g(x^{k+1}) - g(x^*)\| + \delta_k \|g(x^k) - g(x^*)\|. \end{aligned}$$

Thus, we conclude that

$$\begin{aligned}
 & (1 - \delta_k) \|g(x^{k+1}) - g(x^*)\| \\
 & \leq \|g(z^{k+1}) - g(x^*)\| + \delta_k \|g(x^k) - g(x^*)\| \\
 & \leq \theta_k \|g(x^k) - g(x^*)\| + \delta_k \|g(x^k) - g(x^*)\| \\
 (6) \quad & = (\theta_k + \delta_k) \|g(x^k) - g(x^*)\|,
 \end{aligned}$$

so we have

$$(7) \quad \|g(x^{k+1}) - g(x^*)\| \leq \frac{\theta_k + \delta_k}{1 - \delta_k} \|g(x^k) - g(x^*)\|.$$

Hence, $\{g(x^k)\}$ converges to $g(x^*)$.

Finally, since g is (c) -strongly accretive (and hence, $\|g(x) - g(y)\| \geq c\|x - y\|$), we conclude that the sequence $\{x^k\}$ converges to x^* . \square

For $\gamma=1$ in Theorem 3.2, we have:

Theorem 3.3. *Let X be a real q -uniformly smooth Banach space, let $A : X \rightarrow X$ be (r) -strongly accretive, and let $M : X \rightarrow 2^X$ be RMA. Furthermore, suppose*

$$\begin{aligned}
 & \langle J_{\rho,A}^M(u) - J_{\rho,A}^M(v), J_q(A(J_{\rho,A}^M(u)) - A(J_{\rho,A}^M(v))) \rangle \\
 & \geq \|A(J_{\rho,A}^M(u)) - A(J_{\rho,A}^M(v))\|^q \text{ for } \gamma > 0,
 \end{aligned}$$

where $q > 1$.

For an arbitrarily chosen initial point x^0 , suppose that the sequence $\{x^k\}$ is generated by the generalized proximal point algorithm

$$(8) \quad g(x^{k+1}) = (1 - \alpha_k)g(x^k) + \alpha_k y^k \quad \forall k \geq 0,$$

and y^k satisfies

$$\|y^k - J_{\rho,A}^M(g(x^k))\| \leq \delta_k \|y^k - g(x^k)\|,$$

where

$$J_{\rho_k}^M = (I + \rho M)^{-1}$$

and

$$\{\delta_k\}, \{\alpha_k\} \subseteq [0, \infty)$$

are scalar sequences. Then the sequence $\{x^k\}$ converges linearly to a solution of (1) with the convergence rate

$$\theta_k = [1 - \Delta(1 - \frac{1}{r})] < 1,$$

where $r > 1$, $\sum_{k=0}^{\infty} \delta_k < \infty$, $\delta_k \rightarrow 0$, $\Delta = \inf \alpha_k > 0$, and $\alpha = \limsup_{k \rightarrow \infty} \alpha_k$.

When $g = I$, Theorem 3.2 reduces to the approximation solvability of the inclusion problem: determine a solution to

$$(9) \quad 0 \in M(x).$$

Theorem 3.4. *Let X be a real q -uniformly smooth Banach space, let $A : X \rightarrow X$ be (r) -strongly accretive, and let $M : X \rightarrow 2^X$ be relative maximal accretive (RMA). Furthermore, suppose that*

$$\begin{aligned} & \langle J_{\rho,A}^M(u) - J_{\rho,A}^M(v), J_q(A(J_{\rho,A}^M(u)) - A(J_{\rho,A}^M(v))) \rangle \\ & \geq \gamma \|A(J_{\rho,A}^M(u)) - A(J_{\rho,A}^M(v))\|^q \text{ for } \gamma > 0, \end{aligned}$$

where $q > 1$.

For an arbitrarily chosen initial point x^0 , suppose that the sequence $\{x^k\}$ is generated by the generalized proximal point algorithm

$$(10) \quad x^{k+1} = (1 - \alpha_k)x^k + \alpha_k y^k \quad \forall k \geq 0,$$

and y^k satisfies

$$\|y^k - J_{\rho,A}^M(x^k)\| \leq \delta_k \|y^k - x^k\|,$$

where

$$J_{\rho,A}^M = (I + \rho M)^{-1}$$

and

$$\{\delta_k\}, \{\alpha_k\} \subseteq [0, \infty)$$

are scalar sequences. Then the sequence $\{x^k\}$ converges linearly to a solution of (9) with the convergence rate

$$\theta_k = [1 - \Delta(1 - \frac{1}{\gamma r})] < 1,$$

where $\gamma r > 1$, $\sum_{k=0}^{\infty} \delta_k < \infty$, $\delta_k \rightarrow 0$, $\alpha_k \leq 1$, $\Delta = \inf \alpha_k > 0$, and $\alpha = \limsup_{k \rightarrow \infty} \alpha_k$.

Proof. Suppose that x^* is a zero of M . From Theorem 3.1, it follows that any solution to (9) is a fixed point of $J_{\rho,A}^M$. Since A is (r) -strongly accretive (and hence $\|A(u) - A(v)\| \geq r\|u - v\|$) and using Lemma 3.2, we have the inequality

$$(11) \quad \|J_{\rho,A}^M(x^k) - J_{\rho,A}^M(x^*)\| \leq \frac{1}{\gamma r} \|x^k - x^*\|.$$

Next, for all $k \geq 0$, we express

$$z^{k+1} = (1 - \alpha_k)x^k + \alpha_k J_{\rho,A}^M(x^k).$$

Then we find the estimate using (11) that

$$\begin{aligned} \|z^{k+1} - x^*\| &= \|(1 - \alpha_k)x^k + \alpha_k J_{\rho,A}^M(x^k) - x^*\| \\ &= \|(1 - \alpha_k)(x^k - x^*) + \alpha_k(J_{\rho,A}^M(x^k) - J_{\rho,A}^M(x^*))\| \\ &\leq (1 - \alpha_k)\|x^k - x^*\| + \alpha_k\|J_{\rho,A}^M(x^k) - J_{\rho,A}^M(x^*)\| \\ &\leq [(1 - \alpha_k) + \frac{\alpha_k}{\gamma r}]\|x^k - x^*\| \\ &= [1 - \alpha_k(1 - \frac{1}{\gamma r})]\|x^k - x^*\| \end{aligned}$$

$$\begin{aligned}
&\leq [1 - \triangle(1 - \frac{1}{\gamma r})] \|x^k - x^*\| \\
&= \theta_k \|x^k - x^*\|,
\end{aligned}$$

where $\theta_k = [1 - \triangle(1 - \frac{1}{\gamma r})]$ and $\gamma r > 1$. Thus, we have

$$(12) \quad \|z^{k+1} - x^*\| \leq \theta_k \|x^k - x^*\|.$$

Since $x^{k+1} = (1 - \alpha_k)x^k + \alpha_k y^k$, we have $x^{k+1} - x^k = \alpha_k(y^k - x^k)$.

On the other hand, we have

$$\begin{aligned}
&\|x^{k+1} - z^{k+1}\| \\
&= \|(1 - \alpha_k)x^k + \alpha_k y^k - [(1 - \alpha_k)x^k + \alpha_k J_{\rho, A}^M(x^k)]\| \\
&= \|\alpha_k(y^k - J_{\rho, A}^M(x^k))\| \\
&\leq \alpha_k \delta_k \|y^k - x^k\|.
\end{aligned}$$

It follows that

$$\begin{aligned}
&\|x^{k+1} - x^*\| \\
&\leq \|z^{k+1} - x^*\| + \|x^{k+1} - z^{k+1}\| \\
&\leq \|z^{k+1} - x^*\| + \alpha_k \delta_k \|y^k - x^k\| \\
&\leq \|z^{k+1} - x^*\| + \delta_k \|x^{k+1} - x^k\| \\
(13) \quad &\leq \|z^{k+1} - x^*\| + \delta_k \|x^{k+1} - x^*\| + \delta_k \|x^k - x^*\|.
\end{aligned}$$

Thus, we conclude that

$$\begin{aligned}
&(1 - \delta_k) \|x^{k+1} - x^*\| \\
&\leq \|z^{k+1} - x^*\| + \delta_k \|x^k - x^*\| \\
&\leq \theta_k \|x^k - x^*\| + \delta_k \|x^k - x^*\| \\
(14) \quad &= (\theta_k + \delta_k) \|x^k - x^*\|,
\end{aligned}$$

so we have

$$(15) \quad \|x^{k+1} - x^*\| \leq \frac{\theta_k + \delta_k}{1 - \delta_k} \|x^k - x^*\|.$$

Hence, $\{x^k\}$ converges to x^* . \square

4. An application

Let X be a real Banach space and let $f : X \rightarrow R$ be a locally Lipschitz functional on X . We consider the inclusion problem: determine a solution to

$$(16) \quad 0 \in \partial f(x),$$

where $\partial f : X \rightarrow 2^X$ is a set-valued mapping on X . Then it turns out that $I + \partial f$ is relative accretive if $A : X \rightarrow X$ is (r) -strongly accretive, and $\partial f : X \rightarrow 2^X$ is relative accretive. This is equivalent to stating that ∂f is relative maximal accretive. Now all the conditions for Theorem 3.2 are satisfied, and one can apply Theorem 3.2 to the solvability of (16).

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