

ON SOME CLASSES OF GENERALIZED QUASI-EINSTEIN MANIFOLDS

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ABSTRACT. The object of the present paper is to study the generalized quasi-Einstein manifolds satisfying some conditions. Finally the existence of such manifolds is ensured by several interesting examples.

1. Introduction

The notion of quasi-Einstein manifolds was introduced by M. C. Chaki and R. K. Maity [1]. A Riemannian manifold (M^n, g) ($n > 2$) is said to be quasi-Einstein manifold if its Ricci tensor S of type $(0, 2)$ is not identically zero and satisfies the following:

$$(1.1) \quad S(X, Y) = \alpha g(X, Y) + \beta A(X)A(Y),$$

where α, β are scalars of which $\beta \neq 0$ and A is a nowhere vanishing 1-form defined by $g(X, \rho) = A(X)$ for all vector fields X ; ρ being a unit vector field, called the generator of the manifold. An n -dimensional manifold of this kind is denoted by $(QE)_n$. The scalars α, β are known as the associated scalars.

As a generalization of quasi-Einstein manifold, in [2], U. C. De and G. C. Ghosh introduced the notion of generalized quasi-Einstein manifold. A Riemannian manifold (M^n, g) ($n \geq 3$) is said to be generalized quasi-Einstein manifold if its Ricci tensor S of type $(0, 2)$ is not identically zero and satisfies the following:

$$(1.2) \quad S(X, Y) = \alpha g(X, Y) + \beta A(X)A(Y) + \gamma B(X)B(Y),$$

where α, β, γ are scalars of which $\beta \neq 0, \gamma \neq 0$ and A, B are nowhere vanishing 1-forms such that $g(X, \rho) = A(X), g(X, \mu) = B(X)$ for all vector fields X . The unit vectors ρ and μ corresponding to the 1-forms A and B are orthogonal to each other. Also ρ and μ are known as the generators of the manifold. Such an n -dimensional manifold is denoted by $G(QE)_n$.

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The present paper deals with $G(QE)_n$ satisfying some conditions. The paper is organized as follows. Section 2 is concerned with the preliminaries. Section 3 is devoted to the study of Ricci-pseudosymmetric $G(QE)_n$. In Sections 4–7, we investigate the $G(QE)_n$ ($n > 3$) satisfying the conditions $C \cdot S = 0$, $\tilde{C} \cdot S = 0$, $W \cdot S = 0$ and $P \cdot S = 0$, where C , \tilde{C} , W and P respectively denote the conformal curvature tensor, concircular curvature tensor, quasi-conformal curvature tensor and projective curvature tensor. Then it is proved that in each of the case, either the associated scalars β and γ are equal or the curvature tensor R satisfies a definite condition.

In Section 8, we study conformally flat Ricci-semisymmetric $G(QE)_n$ ($n > 3$) and it is shown that if in a conformally flat Ricci-semisymmetric $G(QE)_n$ ($n > 3$), $\frac{r}{n-1}$ is not an eigenvalue of the Ricci-operator, then either the associated scalars β and γ are equal or the vector fields ρ and μ corresponding to the 1-forms A and B are co-directional. The last section provides the existence of proper $G(QE)_n$.

2. Preliminaries

In this section we will obtain some formulas of $G(QE)_n$, which will be required in the sequel. Let $\{e_i : i = 1, 2, \dots, n\}$ be an orthonormal frame field at any point of $G(QE)_n$. Then setting $X = Y = e_i$ in (1.2) and taking summation over i , $1 \leq i \leq n$, we obtain

$$(2.1) \quad r = n\alpha + \beta + \gamma,$$

where r is the scalar curvature of the manifold.

Also, from (1.2), we have

$$(2.2) \quad S(\rho, \rho) = \alpha + \beta,$$

$$(2.3) \quad S(\mu, \mu) = \alpha + \gamma,$$

and

$$(2.4) \quad S(\rho, \mu) = 0.$$

Let Q be the Ricci-operator, i.e., $g(QX, Y) = S(X, Y)$ for all X, Y .

3. Ricci-pseudosymmetric $G(QE)_n$

An n -dimensional Riemannian manifold (M^n, g) is called Ricci-pseudosymmetric [4] if the tensors $R \cdot S$ and $Q(g, S)$ are linearly dependent, where

$$(3.1) \quad (R(X, Y) \cdot S)(Z, U) = -S(R(X, Y)Z, U) - S(Z, R(X, Y)U),$$

$$(3.2) \quad Q(g, S)(Z, U; X, Y) = -S((X \wedge_g Y)Z, U) - S(Z, (X \wedge_g Y)U),$$

and

$$(3.3) \quad (X \wedge_g Y)Z = g(Y, Z)X - g(X, Z)Y$$

for all vector fields X, Y, Z, U of M , R denotes the curvature tensor of M .

Then (M^n, g) is Ricci-pseudosymmetric if and only if

$$(3.4) \quad (R(X, Y) \cdot S)(Z, U) = L_S Q(g, S)(Z, U; X, Y)$$

holds on $U_s = \{x \in M : S \neq \frac{r}{n}g \text{ at } x\}$, where L_S is some function on U_s . If $R \cdot S = 0$, then M^n is called Ricci-semisymmetric. Every Ricci-semisymmetric manifold is Ricci-pseudosymmetric but the converse is not true [4].

In [2] De and Ghosh studied a Ricci-semisymmetric $G(QE)_n$. We now consider a Ricci-pseudosymmetric $G(QE)_n$. Then, from (3.1)–(3.4), we can write

$$(3.5) \quad \begin{aligned} & S(R(X, Y)Z, U) + S(Z, R(X, Y)U) \\ &= L_S [g(Y, Z)S(X, U) - g(X, Z)S(Y, U) \\ & \quad + g(Y, U)S(X, Z) - g(X, U)S(Y, Z)]. \end{aligned}$$

Using (1.2) in (3.5), we get

$$(3.6) \quad \begin{aligned} & \beta[A(R(X, Y)Z)A(U) + A(Z)A(R(X, Y)U)] \\ & \quad + \gamma[B(R(X, Y)Z)B(U) + B(Z)B(R(X, Y)U)] \\ &= L_S [\beta\{g(Y, Z)A(X)A(U) - g(X, Z)A(Y)A(U) + g(Y, U)A(X)A(Z) \\ & \quad - g(X, U)A(Y)A(Z)\} + \gamma\{g(Y, Z)B(X)B(U) \\ & \quad - g(X, Z)B(Y)B(U) + g(Y, U)B(X)B(Z) - g(X, U)B(Y)B(Z)\}]. \end{aligned}$$

Setting $Z = \rho$ and $U = \mu$ in (3.6), we get

$$(3.7) \quad (\gamma - \beta)[R(X, Y, \rho, \mu) - L_S\{A(Y)B(X) - A(X)B(Y)\}] = 0,$$

which yields either $\beta = \gamma$ or

$$(3.8) \quad R(X, Y, \rho, \mu) = L_S\{A(Y)B(X) - A(X)B(Y)\}.$$

Hence we can state the following:

Theorem 3.1. *In a Ricci-pseudosymmetric $G(QE)_n (n > 3)$, either the associated scalars β and γ are equal or the curvature tensor R of the manifold satisfies the relation (3.8).*

Corollary 3.1. *In a Ricci-semisymmetric $G(QE)_n (n > 3)$, the associated scalars β and γ are equal [2].*

4. $G(QE)_n (n > 3)$ satisfying the condition $C \cdot S = 0$

The Weyl conformal curvature tensor C of type (1,3) of an n -dimensional Riemannian manifold $(M^n, g) (n > 3)$ is defined by [3]

$$(4.1) \quad \begin{aligned} C(X, Y)Z &= R(X, Y)Z - \frac{1}{n-2}[S(Y, Z)X - S(X, Z)Y \\ & \quad + g(Y, Z)QX - g(X, Z)QY] \\ & \quad + \frac{r}{(n-1)(n-2)}\{g(Y, Z)X - g(X, Z)Y\}. \end{aligned}$$

We now consider a $G(QE)_n (n > 3)$ satisfying the condition $C \cdot S = 0$. Then we have

$$(4.2) \quad S(C(X, Y)Z, U) + S(Z, C(X, Y)U) = 0.$$

Using (1.2) in (4.2), we obtain

$$(4.3) \quad \beta[A(C(X, Y)Z)A(U) + A(Z)A(C(X, Y)U)] \\ + \gamma[B(C(X, Y)Z)B(U) + B(Z)B(C(X, Y)U)] = 0.$$

Setting $Z = \rho$ and $U = \mu$ in (4.3), we get

$$(4.4) \quad (\gamma - \beta)C(X, Y, \rho, \mu) = 0.$$

From (4.4), it follows that either $\beta = \gamma$ or

$$C(X, Y, \rho, \mu) = 0,$$

which further yields

$$(4.5) \quad R(X, Y, \rho, \mu) = \frac{1}{n-2}[A(QY)B(X) - A(X)B(QY) \\ + A(Y)B(QX) - A(QX)B(Y)] \\ - \frac{r}{(n-1)(n-2)}\{A(Y)B(X) - A(X)B(Y)\}.$$

Hence we can state the following:

Theorem 4.1. *If a $G(QE)_n (n > 3)$ satisfies the condition $C \cdot S = 0$, then either the associated scalars β and γ are equal or the curvature tensor R of the manifold satisfies the property (4.5).*

5. $G(QE)_n (n > 3)$ satisfying the condition $\tilde{C} \cdot S = 0$

The concircular curvature tensor \tilde{C} of type (1,3) of an n -dimensional Riemannian manifold $(M^n, g) (n > 3)$ is defined by [3]

$$(5.1) \quad \tilde{C}(X, Y)Z = R(X, Y)Z - \frac{r}{n(n-1)}[g(Y, Z)X - g(X, Z)Y]$$

for any vector fields $X, Y, Z \in \chi(M)$. Let us consider a $G(QE)_n (n > 3)$ satisfying the condition $\tilde{C} \cdot S = 0$. Then we have

$$(5.2) \quad S(\tilde{C}(X, Y)Z, U) + S(Z, \tilde{C}(X, Y)U) = 0.$$

By virtue of (1.2), it follows from (5.2) that

$$(5.3) \quad \beta[A(\tilde{C}(X, Y)Z)A(U) + A(Z)A(\tilde{C}(X, Y)U)] \\ + \gamma[B(\tilde{C}(X, Y)Z)B(U) + B(Z)B(\tilde{C}(X, Y)U)] = 0.$$

Putting $Z = \rho$ and $U = \mu$ in (5.3), we get

$$(5.4) \quad (\gamma - \beta)[R(X, Y, \rho, \mu) - \frac{r}{n(n-1)}\{A(Y)B(X) - A(X)B(Y)\}] = 0.$$

This leads to the following:

Theorem 5.1. *In a $G(QE)_n(n > 3)$ with $\tilde{C} \cdot S = 0$, either the associated scalars β and γ are equal or the curvature tensor R of the manifold satisfies the following property*

$$(5.5) \quad R(X, Y, \rho, \mu) = \frac{r}{n(n-1)}\{A(Y)B(X) - A(X)B(Y)\}.$$

6. $G(QE)_n(n > 3)$ satisfying the condition $W \cdot S = 0$

In 1968, Yano and Sawaki [5] defined and studied a curvature tensor W of type (1,3) which includes both the conformal curvature tensor C and the concircular curvature tensor \tilde{C} as special cases and is called quasi-conformal curvature tensor. The quasi-conformal curvature tensor W of type (1, 3) of a manifold $(M^n, g)(n > 3)$ is defined by

$$(6.1) \quad W(X, Y)Z = -(n-2)bC(X, Y)Z + [a + (n-2)b]\tilde{C}(X, Y)Z,$$

where a and b are arbitrary constants not simultaneously zero. In particular, if $a = 1, b = 0$, then W reduces to the concircular curvature tensor and if $a = 1$ and $b = -\frac{1}{(n-2)}$, then W reduces to the conformal curvature tensor. Using the expression of the conformal and the concircular curvature tensor in (6.1), the quasi-conformal curvature tensor W of type (1, 3) can be written as

$$(6.2) \quad \begin{aligned} W(X, Y)Z &= aR(X, Y)Z + b[S(Y, Z)X - S(X, Z)Y \\ &\quad + g(Y, Z)QX - g(X, Z)QY] \\ &\quad - \frac{r}{n} \left(\frac{a}{n-1} + 2b \right) \{g(Y, Z)X - g(X, Z)Y\}. \end{aligned}$$

We now consider a $G(QE)_n(n > 3)$ satisfying the condition $W \cdot S = 0$. Then we have

$$(6.3) \quad S(W(X, Y)Z, U) + S(Z, W(X, Y)U) = 0.$$

In view of (1.2), (6.3) yields

$$(6.4) \quad \begin{aligned} &\beta[A(W(X, Y)Z)A(U) + A(Z)A(W(X, Y)U)] \\ &+ \gamma[B(W(X, Y)Z)B(U) + B(Z)B(W(X, Y)U)] = 0. \end{aligned}$$

Substituting $Z = \rho$ and $U = \mu$ in (6.4), we obtain

$$(6.5) \quad (\gamma - \beta)W(X, Y, \rho, \mu) = 0.$$

From (6.5), it follows that either $\beta = \gamma$ or

$$W(X, Y, \rho, \mu) = 0,$$

which implies that

$$(6.6) \quad \begin{aligned} aR(X, Y, \rho, \mu) &= -b[A(QY)B(X) - A(QX)B(Y) \\ &\quad + A(Y)B(QX) - A(X)B(QY)] \\ &\quad + \frac{r}{n} \left(\frac{a}{n-1} + 2b \right) \{A(Y)B(X) - A(X)B(Y)\}. \end{aligned}$$

Thus we can state the following:

Theorem 6.1. *If a $G(QE)_n$ ($n > 3$) satisfies the condition $W \cdot S = 0$, then either the associated scalars β and γ are equal or the curvature tensor R of the manifold satisfies the property (6.6).*

7. $G(QE)_n$ ($n > 3$) satisfying the condition $P \cdot S = 0$

The Weyl projective curvature tensor P of type (1,3) of an n -dimensional Riemannian manifold (M^n, g) ($n > 3$) is defined by [3]

$$(7.1) \quad P(X, Y)Z = R(X, Y)Z - \frac{1}{n-1}[S(Y, Z)X - S(X, Z)Y]$$

for any vector fields $X, Y, Z \in \chi(M)$. Let us take a $G(QE)_n$ ($n > 3$) with $P \cdot S = 0$. Then we get

$$(7.2) \quad S(P(X, Y)Z, U) + S(Z, P(X, Y)U) = 0.$$

Using (1.2) in (7.2), we get

$$(7.3) \quad \alpha[\tilde{P}(X, Y, Z, U) + \tilde{P}(X, Y, U, Z)] + \beta[A(P(X, Y)Z)A(U) \\ + A(Z)A(P(X, Y)U)] + \gamma[B(P(X, Y)Z)B(U) \\ + B(Z)B(P(X, Y)U)] = 0,$$

where $\tilde{P}(X, Y, Z, U) = g(P(X, Y)Z, U)$. Setting $Z = \rho$ and $U = \mu$ in (7.3), we get

$$(7.4) \quad (\alpha + \gamma)\tilde{P}(X, Y, \rho, \mu) + (\alpha + \beta)\tilde{P}(X, Y, \mu, \rho) = 0.$$

In view of (7.1), we have from (7.4) that

$$(7.5) \quad (n-1)(\gamma - \beta)R(X, Y, \rho, \mu) \\ = (\alpha + \gamma)\{A(QY)B(X) - A(QX)B(Y)\} \\ + (\alpha + \beta)\{A(X)B(QY) - A(Y)B(QX)\},$$

provided $\gamma - \beta \neq 0$. This leads to the following:

Theorem 7.1. *If a $G(QE)_n$ ($n > 3$) satisfies the condition $P \cdot S = 0$, then the curvature tensor R of the manifold satisfies the property (7.5), provided $\beta \neq \gamma$.*

8. Conformally flat $G(QE)_n$ ($n > 3$) with $R(X, Y) \cdot S = 0$

Let us consider a conformally flat $G(QE)_n$ ($n > 3$). Then, from (4.1), we get

$$(8.1) \quad R(X, Y)Z = \frac{1}{n-2}[S(Y, Z)X - S(X, Z)Y \\ + g(Y, Z)QX - g(X, Z)QY] \\ - \frac{r}{(n-1)(n-2)}\{g(Y, Z)X - g(X, Z)Y\}.$$

Since the manifold satisfies $R(X, Y) \cdot S = 0$, we get

$$(8.2) \quad S(R(X, Y)Z, U) + S(Z, R(X, Y)U) = 0.$$

Using (8.1) in (8.2), we get

$$\begin{aligned}
 (8.3) \quad & g(Y, Z)S(QX, U) - g(X, Z)S(QY, U) \\
 & + g(Y, U)S(QX, Z) - g(X, U)S(QY, Z) \\
 = & \frac{r}{n-1} [g(Y, Z)S(X, U) - g(X, Z)S(Y, U) \\
 & + g(Y, U)S(X, Z) - g(X, U)S(Y, Z)].
 \end{aligned}$$

Let λ be the eigenvalue of the endomorphism Q corresponding to an eigenvector X . Then $QX = \lambda X$, i.e., $S(X, U) = \lambda g(X, U)$ and hence

$$(8.4) \quad S(QX, U) = \lambda S(X, U).$$

By virtue of (8.4), it follows from (8.3) that

$$\begin{aligned}
 & \left(\lambda - \frac{r}{n-1} \right) [g(Y, Z)S(X, U) - g(X, Z)S(Y, U) \\
 & + g(Y, U)S(X, Z) - g(X, U)S(Y, Z)] = 0,
 \end{aligned}$$

which yields

$$(8.5) \quad g(Y, Z)S(X, U) - g(X, Z)S(Y, U) + g(Y, U)S(X, Z) - g(X, U)S(Y, Z) = 0,$$

provided $\lambda \neq \frac{r}{n-1}$. Again using (1.2) in (8.5), we get

$$\begin{aligned}
 (8.6) \quad & \beta [g(Y, Z)A(X)A(U) - g(X, Z)A(Y)A(U) + g(Y, U)A(X)A(Z) \\
 & - g(X, U)A(Y)A(Z)] + \gamma [g(Y, Z)B(X)B(U) - g(X, Z)B(Y)B(U) \\
 & + g(Y, U)B(X)B(Z) - g(X, U)B(Y)B(Z)] = 0, \quad \text{provided } \lambda \neq \frac{r}{n-1}.
 \end{aligned}$$

Setting $Z = \rho$ and $U = \mu$, we get

$$(8.7) \quad (\beta - \gamma) \{A(X)B(Y) - A(Y)B(X)\} = 0.$$

From (8.7), we get either $\beta = \gamma$ or

$$A(X)B(Y) = A(Y)B(X),$$

that is, the vector fields ρ and μ are co-directional. Thus we can state the following:

Theorem 8.1. *If, in a conformally flat Ricci-semisymmetric $G(QE)_n (n > 3)$, $\frac{r}{n-1}$ is not an eigenvalue of the Ricci-operator Q , then either the associated scalars β and γ of the manifold are equal or the vector fields ρ and μ corresponding to the 1-forms A and B respectively are co-directional.*

9. Some Examples of $G(QE)_n$

This section deals with several non-trivial examples of $G(QE)_n$.

Example 9.1. We define a Riemannian metric g on \mathbb{R}^4 by the formula

$$(9.1) \quad ds^2 = g_{ij} dx^i dx^j = (1 + 2p)[(dx^1)^2 + (dx^2)^2 + (dx^3)^2 + (dx^4)^2], \quad (i, j = 1, 2, 3, 4),$$

where $p = \frac{e^{x^1}}{k^2}$ and k is a non-zero constant. Then the only non-vanishing components of the Christoffel symbols, the curvature tensor, the Ricci tensor and scalar curvature are given by

$$\begin{aligned}\Gamma_{22}^1 &= -\frac{p}{(1+2p)} = \Gamma_{33}^1 = \Gamma_{44}^1 = -\Gamma_{11}^1 = -\Gamma_{12}^2 = -\Gamma_{13}^3 = -\Gamma_{14}^4, \\ R_{1221} &= R_{1331} = R_{1441} = \frac{p}{(1+2p)}, S_{11} = \frac{3p}{(1+2p)^2}, \\ S_{22} &= S_{33} = S_{44} = \frac{p}{(1+2p)^2}, r = \frac{6p}{(1+2p)^3} \neq 0\end{aligned}$$

and the components which can be obtained from these by the symmetry properties.

Therefore \mathbb{R}^4 is a Riemannian manifold (M^4, g) of non-vanishing scalar curvature. We shall now show that M^4 is a $G(QE)_4$, i.e., it satisfies (1.2). Let us now consider the associated scalars as follows:

$$(9.2) \quad \alpha = \frac{p}{(1+2p)^3}, \quad \beta = 3p, \quad \gamma = -\frac{1}{(1+2p)^2}.$$

In terms of local coordinate system, let us consider the 1-forms A and B as follows:

$$(9.3) \quad \begin{aligned}A_i(x) &= \begin{cases} \frac{1}{1+2p} & \text{for } i = 1, \\ 0 & \text{otherwise,} \end{cases} \\ B_i(x) &= \begin{cases} \sqrt{p} & \text{for } i = 1, \\ 0 & \text{otherwise.} \end{cases}\end{aligned}$$

In terms of local coordinate system, the defining condition (1.2) of a $G(QE)_n$ can be written as

$$(9.4) \quad S_{ij} = \alpha g_{ij} + \beta A_i A_j + \gamma B_i B_j, \quad i, j = 1, 2, 3, 4.$$

By virtue of (9.2) and (9.3), it can be easily shown that (9.4) holds for $i, j = 1, 2, 3, 4$. Therefore (M^4, g) is a $G(QE)_4$, which is not quasi-Einstein. Hence we can state the following:

Theorem 9.1. *Let (M^4, g) be a Riemannian manifold endowed with the metric given in (9.1). Then (M^4, g) is a $G(QE)_4$ with non-vanishing scalar curvature which is not quasi-Einstein.*

Example 9.2. We define a Riemannian metric g on \mathbb{R}^4 by the formula

$$(9.5) \quad ds^2 = e^{2x^1} (dx^1)^2 + \sin^2 x^1 [(dx^2)^2 + (dx^3)^2 + (dx^4)^2],$$

where $0 < x^1 < \frac{\pi}{2}$ but $x^1 \neq \frac{\pi}{4}$. Then the only non-vanishing components of the Christoffel symbols, the curvature tensor, the Ricci tensor and scalar curvature

are

$$\begin{aligned} \Gamma_{11}^1 &= 1, \Gamma_{12}^2 = \Gamma_{13}^3 = \Gamma_{14}^4 = \cot x^1, \\ \Gamma_{22}^1 &= -\frac{\sin 2x^1}{2e^{2x^1}} = \Gamma_{33}^1 = \Gamma_{44}^1, \\ R_{1221} &= -\sin^2 x^1(1 + \cot x^1) = R_{1331} = R_{1441}, \\ R_{2332} &= \frac{\sin^2 x^1 \cos^2 x^1}{e^{2x^1}} = R_{2442} = R_{3443}, \\ S_{22} &= \frac{2 \cos^2 x^1 - \sin^2 x^1(1 + \cot x^1)}{e^{2x^1}} = S_{33} = S_{44}, \\ S_{11} &= -3(1 + \cot x^1), r = \frac{6(\cot^2 x^1 - \cot x^1 - 1)}{e^{2x^1}} \neq 0, \end{aligned}$$

provided $(\cot^2 x^1 - \cot x^1 - 1) \neq 0$ and the components which can be obtained from these by the symmetry properties. Therefore \mathbb{R}^4 with the considered metric is a Riemannian manifold (M^4, g) of non-vanishing scalar curvature. We shall now show that this M^4 is a $G(QE)_4$, i.e., it satisfies (1.2). Let us now consider the associated scalars as follows:

$$(9.6) \quad \alpha = \frac{2 \cot^2 x^1 - \cot x^1 - 1}{e^{2x^1}}, \beta = -(1 + \cot x^1), \gamma = -2 \cot x^1.$$

In terms of local coordinate system, let us consider the 1-forms A and B as follows:

$$(9.7) \quad \begin{aligned} A_i(x) &= \begin{cases} \sqrt{2} & \text{for } i = 1, \\ 0 & \text{otherwise,} \end{cases} \\ B_i(x) &= \begin{cases} \sqrt{\cot x^1} & \text{for } i = 1, \\ 0 & \text{otherwise.} \end{cases} \end{aligned}$$

In terms of local coordinate system, the defining condition (1.2) of a $G(QE)_n$ can be written as (9.4). By virtue of (9.6) and (9.7), it can be easily shown that (9.4) holds for $i, j = 1, 2, 3, 4$. Therefore (M^4, g) is a $G(QE)_4$, which is not quasi-Einstein. Hence we can state the following:

Theorem 9.2. *Let (M^4, g) be a Riemannian manifold endowed with the metric given in (9.5). Then (M^4, g) is a $G(QE)_4$ with non-vanishing scalar curvature which is not quasi-Einstein.*

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