

ON THE RECURSIVE SEQUENCE $x_{n+1} = \frac{a+bx_{n-1}}{A+Bx_n^k}$

A. M. AHMED*, H. M. EL-OWAIDY, ALAA E. HAMZA AND A. M. YOUSSEF

ABSTRACT. In this paper, we investigate the global behavior of the difference equation

$$x_{n+1} = \frac{a + bx_{n-1}}{A + Bx_n^k}, \quad n = 0, 1, \dots,$$

where $a, b, B \in [0, \infty)$ and $A, k \in (0, \infty)$ with non-negative initial conditions.

AMS Mathematics Subject Classification : 39A10;39A11.

Key words and phrases : Difference equations; recursive sequences; global asymptotic stability; oscillation; period two solutions; semicycles.

1. Introduction and preliminaries

Recently there has been a great interest in studying the behavior of rational and non-rational nonlinear difference equations. A. M. Amleh et al [1] studied the dynamics of

$$x_{n+1} = \frac{a + bx_{n-1}}{A + Bx_{n-2}}, \quad n = 0, 1, \dots,$$

Gibbons et al [9] investigated the global behavior of the recursive sequence

$$y_{n+1} = \frac{\alpha + \beta y_{n-1}}{\gamma + y_n}, \quad n = 0, 1, \dots,$$

where α, β , and γ are nonnegative real numbers. El-Owaidy et al [7] studied the dynamics of

$$x_{n+1} = \frac{bx_{n-1}}{A + Bx_{n-2}^p}, \quad n = 0, 1, \dots,$$

where b, A, B and p are nonnegative real parameters. For related results see ([2]-[5],[10]-[20]). Some of these results can be applied to biological and population

Received August 31, 2006. Revised October 18, 2008. Accepted October 25, 2008.

*Corresponding author.

© 2009 Korean SIGCAM and KSCAM .

models. In this paper we generalize the results obtained in [9] to the second-order rational difference equation

$$x_{n+1} = \frac{a + bx_{n-1}}{A + Bx_n^k}, \quad n = 0, 1, \dots, \quad (1)$$

where $a, b, B \in [0, \infty)$ and $A, k \in (0, \infty)$ with non-negative initial conditions such that $A + Bx_n^k > 0 \quad \forall n \geq 0$. The change of variables of Eq.(1) by $x_n = \sqrt[k]{\frac{b}{B}}y_n$, yields

$$y_{n+1} = \frac{s + y_{n-1}}{r + y_n^k}, \quad n = 0, 1, \dots, \quad (2)$$

where $s = \frac{a}{b} \sqrt[k]{\frac{B}{b}}$ and $r = \frac{A}{b}$. For definitions and notations, we refer the reader to ([6],[11],[12] and[13]).

Let I be an interval of real numbers and let

$$f : I \times I \rightarrow I$$

be a continuously differentiable function.

For every set of initial conditions $\{x_0, x_{-1}\} \subset I$, the difference equation

$$x_{n+1} = f(x_n, x_{n-1}), \quad n = 0, 1, \dots, \quad (3)$$

has a unique solution $\{x_n\}_{n=-1}^{\infty}$. We denote by

$$p = \frac{\partial f}{\partial u}(\bar{x}, \bar{x}) \quad \text{and} \quad q = \frac{\partial f}{\partial v}(\bar{x}, \bar{x})$$

the partial derivatives of $f(u, v)$ evaluated at the equilibrium \bar{x} of Eq.(3). The equation

$$y_{n+1} = py_n + qy_{n-1}, \quad n = 0, 1, \dots, \quad (4)$$

is called the linearized equation associated with Eq.(3) about the equilibrium point \bar{x} . Then its characteristic equation is

$$\lambda^2 - p\lambda - q = 0. \quad (5)$$

2. The recursive sequence $y_{n+1} = y_{n-1}/(r + y_n^k)$

In this section we study the global behavior of Eq.(2), when $s = 0$, that is Eq.(2) yields

$$y_{n+1} = \frac{y_{n-1}}{r + y_n^k}, \quad n = 0, 1, \dots, \quad (6)$$

where y_{-1} and y_0 are non-negative real numbers, k and r are positive real numbers.

Theorem 1. *The following statements are true*

(1) *If $r > 1$, then Eq.(6) has a unique equilibrium point $\bar{y}_1 = 0$ which is locally asymptotically stable.*

(2) *If $r < 1$, then Eq.(6) has two equilibrium points $\bar{y}_2 = 0$ which is a repeller and $\bar{y}_3 = \sqrt[k]{1-r}$ which is unstable, in fact saddle.*

(3) *If $r = 1$, then Eq.(6) has a unique equilibrium point $\bar{y}_4 = 0$ which is non-hyperbolic point.*

Proof. The characteristic equation of the associated linearized equation about \bar{y}_i , $i = 1, 2, 4$ is $\lambda^2 - \frac{1}{r} = 0$, and about \bar{y}_3 is $\lambda^2 + k(1-r)\lambda - 1 = 0$, then the results follow directly by applying the Linearized stability Theorem [13]. \square

In the following Theorem we prove the global asymptotic stability of the zero equilibrium point $\bar{y} = 0$ when $r > 1$.

Theorem 2. *Assume that $r > 1$. The equilibrium point $\bar{y} = 0$ is globally asymptotically stable.*

Proof. Let $r > 1$, by Theorem (1), $\bar{y} = 0$ is locally asymptotically stable. Now we show that $\bar{y} = 0$ is a global attractor. We have

$$y_{n+1} = \frac{y_{n-1}}{r + y_n^k} < \frac{1}{r} y_{n-1}, \quad n = 0, 1, 2, \dots,$$

then by induction, we get

$$y_{2n} < \left(\frac{1}{r}\right)^n y_0 \quad \text{and} \quad y_{2n-1} < \left(\frac{1}{r}\right)^n y_{-1}, \quad n = 1, 2, \dots$$

Therefore $\lim_{n \rightarrow \infty} y_n = 0$. \square

Theorem 3. *A necessary and sufficient condition for Eq.(6) to have a prime period two solution is $r = 1$. In this case the prime period two solution is of the form*

$$\dots, \phi, 0, \phi, 0, \dots$$

Furthermore; if $r = 1$, then every solution of Eq.(6) converges to a period (not necessary prime) two solution

$$\dots, \phi, 0, \phi, 0, \dots$$

with $\phi \geq 0$.

Proof. (Sufficiency): Let $r = 1$, for every $\phi > 0$, we have

$$\dots, \phi, 0, \phi, 0, \dots$$

is a prime period two solution for Eq.(6).

(Necessity): Assume that Eq.(6) has a prime period two solution

$$\dots, \phi, \psi, \phi, \psi, \dots$$

Then $\phi = \frac{\phi}{r+\psi^k}$ and $\psi = \frac{\psi}{r+\phi^k}$. Hence,

$$\phi [(r-1) + \psi^k] = 0, \quad (7)$$

and

$$\psi [(r-1) + \phi^k] = 0. \quad (8)$$

Assume for the sake of contradiction that $r \neq 1$. From (7), we have either $\phi = 0$ or $\psi = \sqrt[k]{1-r}$.

(1) If $\phi = 0$, by (8), we get $\psi = \phi = 0$, which is a contradiction.

(2) If $\psi = \sqrt[k]{1-r}$, by (8), we get $\phi = \sqrt[k]{1-r}$, which is a contradiction. Therefore $r = 1$. Now assume that $r = 1$ and $\{y_n\}_{n=-1}^{\infty}$ is a solution of Eq.(6). Then

$$y_{n+1} - y_{n-1} = \frac{-y_n y_{n-1}^k}{1 + y_n^k} \leq 0,$$

hence $\{y_{2n}\}$ and $\{y_{2n-1}\}$ are monotonically decreasing to two limits say ϕ , and ψ . So, we obtain the equations

$$\phi = \frac{\phi}{1 + \psi^k} \quad \text{and} \quad \psi = \frac{\psi}{1 + \phi^k},$$

which imply that $\phi\psi = 0$. □

Theorem 4. *Let \bar{y} be an equilibrium point of Eq.(6). Then except possibly for the first semicycle, every solution of Eq.(6) has semicycles of length one.*

Proof. Let $\{y_n\}_{n=-1}^{\infty}$ be a solution of Eq.(6) with at least two semicycles, then there exists $N \geq 0$ such that either

$$y_{N-1} < \bar{y} \leq y_N \quad \text{or} \quad y_{N-1} \geq \bar{y} > y_N.$$

We assume the first case (the second case is similar and will be omitted). So we get

$$y_{N+1} = \frac{y_{N-1}}{r + y_N^k} < \frac{\bar{y}}{r + \bar{y}^k} = \bar{y} \quad \text{and} \quad y_{N+2} = \frac{y_N}{r + y_{N+1}^k} > \frac{\bar{y}}{r + \bar{y}^k} = \bar{y}.$$

Thus $y_{N+1} < \bar{y} < y_{N+2}$, and the result follows by induction. □

Theorem 5. *Assume that $r < 1$, and $\bar{y} = \sqrt[k]{1-r}$. The following statements are true:*

(1) *If $y_0 < \bar{y}$, and $y_{-1} > \bar{y}$, then $\{y_{2n-1}\}$ is monotonically increasing to ∞ , and $\{y_{2n}\}$ is monotonically decreasing to zero.*

(2) *If $y_0 > \bar{y}$, and $y_{-1} < \bar{y}$, then $\{y_{2n}\}$ is monotonically increasing to ∞ , and $\{y_{2n+1}\}$ is monotonically decreasing to zero.*

Proof. Let $r < 1$. (1) Assume that $y_0 < \bar{y} = \sqrt[k]{1-r}$, and $y_{-1} > \bar{y} = \sqrt[k]{1-r}$. Then we have

$$y_1 = \frac{y_{-1}}{r+y_0^k} > \frac{y_{-1}}{r+1-r} = y_{-1} > \bar{y},$$

$$y_2 = \frac{y_0}{r+y_1^k} < \frac{y_0}{r+1-r} = y_0 < \bar{y}.$$

By induction, the odd sequence monotonically increases to a limit (say) $L > 0$, while the even sequence monotonically decreases to a limit (say) $M < \infty$. Hence,

$$M = \frac{M}{r+L^k} \quad \text{and} \quad L = \frac{L}{r+M^k},$$

which implies that $M = 0$, and $L = \infty$.

(2) is similar to (1), and will be omitted. □

3. The recursive sequence $y_{n+1} = (s + y_{n-1}) / (r + y_n^k)$

In this section we investigate the global behavior of

$$y_{n+1} = \frac{s + y_{n-1}}{r + y_n^k}, \quad n = 0, 1, \dots, \tag{9}$$

where s, r , and k are positive real numbers.

Lemma 1. *The following statements are true:*

- (1) Assume that $r > 1$. Then Eq.(9) has a unique equilibrium point in $(0, \frac{s}{r-1})$.
- (2) Assume that $r < 1$.
 - (a) If $r \geq s$, then Eq.(9) has a unique equilibrium point in $(s, 1]$.
 - (b) If $r < s$, then Eq.(9) has a unique equilibrium point in $(1, \frac{s}{r})$.
- (3) If $r = 1$, then Eq.(9) has a unique equilibrium point $\bar{y} = \sqrt[k+1]{s}$.

Proof. Clearly, \bar{y} is an equilibrium point of Eq.(9) if and only if \bar{y} is a root of the function

$$f(x) = x^{k+1} + (r-1)x - s, \tag{10}$$

(1) Let $r > 1$, since $f(0) = -s < 0$, $f(\frac{s}{r-1}) = (\frac{s}{r-1})^{k+1} > 0$, and $f(x)$ is increasing, then $f(x)$ has a unique root $\bar{y} \in (0, \frac{s}{r-1})$. Equivalently Eq.(9) has a unique equilibrium point $\bar{y} \in (0, \frac{s}{r-1})$.

(2) Let $r < 1$. The function $f(x)$ is decreasing on $[s, \sqrt[k]{\frac{1-r}{k+1}}]$ and increasing on $[\sqrt[k]{\frac{1-r}{k+1}}, \infty)$.

(a) Assume that $r \geq s$, then $f(1) = r - s \geq 0$. In view of $f(s) = s^{k+1} + rs - 2s < 0$, since $s \leq r < 1$, Eq.(9) has a unique equilibrium point $\bar{y} \in (s, 1]$.

(b) Assume that $r < s$. Then $f(1) = r - s < 0$ and $f(\frac{s}{r}) > 0$, consequently Eq.(9) has a unique equilibrium point $\bar{y} \in (1, \frac{s}{r})$.

(3) By (10), $\bar{y} = \sqrt[k+1]{s}$. □

We apply the linearized stability Theorem to get a sufficient condition for the equilibrium point \bar{y} to be locally asymptotically stable.

Theorem 6. Assume $r > 0$, and \bar{y} is the equilibrium point of Eq.(9). The following statements are true:

- (1) If $\bar{y}^{k+1} < \frac{s}{k}$, then \bar{y} is locally asymptotically stable.
- (2) If $\bar{y}^{k+1} > \frac{s}{k}$, then \bar{y} is unstable, in fact saddle.
- (3) If $\bar{y}^{k+1} = \frac{s}{k}$, then \bar{y} is non-hyperbolic point.

Proof. The characteristic equation of the associated linearized equation to Eq.(9) is $\lambda^2 = p\lambda + q$, where

$$p = \frac{-k\bar{y}^k}{r + \bar{y}^k}, \text{ and } q = \frac{1}{r + \bar{y}^k}.$$

By the linearized stability Theorem [13], we have:

- (1) If $\bar{y}^{k+1} < \frac{s}{k}$, then $|p| < 1 - q < 2$, consequently \bar{y} is locally asymptotically stable.
- (2) If $\bar{y}^{k+1} > \frac{s}{k}$, then $p^2 + 4q > 0$ and $|p| > 1 - q$, consequently \bar{y} is unstable, in fact saddle.
- (3) If $\bar{y}^{k+1} = \frac{s}{k}$, then $|p| = |1 - q|$, consequently \bar{y} is non-hyperbolic point. \square

Definition ([6]). An Interval I of real numbers is said to be invariant under a real function $G(x, y)$ if $G(x, y) \in I \quad \forall x, y \in I$.

We need the following Lemmas to prove the main result of this section.

Theorem 7. Assume that $G(x, y)$ is a continuous function which is non - decreasing (non-increasing) in x for each y and non-increasing (non-decreasing) in y for each x . Assume that every solution of the equation

$$y_{n+1} = G(y_n, y_{n-k}), \quad n = 0, 1, \dots \quad (11)$$

has an inferior limit λ and superior limit Λ such that λ and Λ belong to an invariant interval $I = [a, b]$ under G . Let \bar{y} be a unique equilibrium point in I . If the system

$$x = G(x, y) \quad \text{and} \quad y = G(y, x) \quad (12)$$

$$(x = G(y, x) \quad \text{and} \quad y = G(x, y)) \quad (13)$$

has exactly one solution in I^2 , then \bar{y} is a global attractor .

Proof. Let $\{y_n\}_{n=-1}^{\infty}$ be a solution of (11), $\lambda = \lim_{n \rightarrow \infty} \inf y_n$ and $\Lambda = \lim_{n \rightarrow \infty} \sup y_n$. Assume that $G(x, y)$ is non-decreasing (non-increasing) in x for each y and non-increasing (non-decreasing) in y for each x . Take $U_1 = G(\Lambda, \lambda)$ ($U_1 = G(\lambda, \Lambda)$) and $L_1 = G(\lambda, \Lambda)$ ($L_1 = G(\Lambda, \lambda)$). For every $\epsilon \in (0, \lambda - a)$ $\exists n_0 \in \mathbb{N}$ such that

$$\lambda - \epsilon < y_n < \Lambda + \epsilon \quad \forall n \geq n_0.$$

Then $L_1 \leq \lambda \leq \Lambda \leq U_1$. Set $U_{n+1} = G(U_n, L_n)$ ($U_{n+1} = G(L_n, U_n$) and $L_{n+1} = G(L_n, U_n)$ ($L_{n+1} = G(U_n, L_n$)), $n = 1, 2, \dots$. One can see that

$$a \leq \dots \leq L_2 \leq L_1 \leq \lambda \leq \Lambda \leq U_1 \leq U_2 \leq \dots \leq b.$$

Hence $\{U_n\}$ is monotonically increasing to a number say $U \in I$ and $\{L_n\}$ is monotonically decreasing to a number say $L \in I$. This implies that $(U, L) \in I^2$ is a solution of system (12) ((13)). Therefore, $U = L = \bar{y} = \lambda = \Lambda$. \square

Corollary 1. Assume that $G(x, y)$ is a continuous function which is non-decreasing (non-increasing) in x for each y and non-increasing (non-decreasing) in y for each x . Let $I = [a, b]$ be an invariant interval under $G(x, y)$. Assume that $\bar{y} \in I$ is a unique equilibrium point of Eq.(11). Assume that J is a closed interval such that $G(x, y) \in I \forall x, y \in J$. If the system

$$x = G(x, y) \quad \text{and} \quad y = G(y, x) \quad (x = G(y, x) \quad \text{and} \quad y = G(x, y))$$

has exactly one solution in I^2 , then \bar{y} is a global attractor with basin I^{k+1} .

Theorem 8. Assume that $r > 0$. Then Eq.(9) has a period (not necessary prime) two solution $\{y_n\}_{n=-1}^\infty$ if and only if (y_{-1}, y_0) is a solution of the system

$$x = \frac{s+x}{r+y^k} \quad \text{and} \quad y = \frac{s+y}{r+x^k}. \tag{14}$$

Furthermore, $y_{-1} \neq y_0$ if and only if $\{y_n\}_{n=-1}^\infty$ is a prime period two solution of Eq.(9).

Proof. Assume that (y_{-1}, y_0) is a solution of system (14). Then

$$y_1 = \frac{s+y_{-1}}{r+y_0^k} = y_{-1} \quad \text{and} \quad y_2 = \frac{s+y_0}{r+y_1^k} = \frac{s+y_0}{r+y_{-1}^k} = y_0.$$

By induction $y_{n+2} = y_n, n \geq -1$. For the other direction let $\{y_n\}_{n=-1}^\infty$ be a period two solution. Then

$$y_1 = \frac{s+y_{-1}}{r+y_0^k} = y_{-1} \quad \text{and} \quad y_2 = \frac{s+y_0}{r+y_1^k} = \frac{s+y_0}{r+y_{-1}^k} = y_0.$$

Clearly, $y_{-1} \neq y_0$ if and only if $\{y_n\}_{n=-1}^\infty$ is a prime period two solution. \square

Theorem 9. Let \bar{y} be the positive equilibrium point of Eq.(9). Then except possibly for the first semicycle, every solution of Eq.(9) has semicycles of length one.

Proof. Let $y_{n-1} < \bar{y} \leq y_n$ or $y_{n-1} \geq \bar{y} > y_n$. Consider $y_{n-1} < \bar{y} \leq y_n$ (the other case is similar and will be omitted), then we get

$$y_{n+1} = \frac{s+y_{n-1}}{r+y_n^k} < \frac{s+\bar{y}}{r+\bar{y}^k} = \bar{y} \quad \text{and} \quad y_{n+2} = \frac{s+y_n}{r+y_{n+1}^k} > \frac{s+\bar{y}}{r+\bar{y}^k} = \bar{y}.$$

By induction we get the result. \square

In the following Theorem we determine more precisely necessary conditions (on parameters) for \bar{y} to be locally asymptotically stable and for \bar{y} to be unstable.

Theorem 10. *Assume that $r > 1$, and \bar{y} is the equilibrium point of Eq.(9). The following statements are true*

- (1) *If $k \leq 1$, then \bar{y} is locally asymptotically stable.*
- (2) *Assume that $k > 1$. We have:*
 - (i) *If $s < k \left(\frac{r-1}{k-1}\right)^{\frac{k+1}{k}}$, then \bar{y} is locally asymptotically stable.*
 - (ii) *If $s > k \left(\frac{r-1}{k-1}\right)^{\frac{k+1}{k}}$, then \bar{y} is unstable, in fact saddle.*
 - (iii) *If $s = k \left(\frac{r-1}{k-1}\right)^{\frac{k+1}{k}}$, then \bar{y} is non-hyperbolic.*

Proof. It is easy to show that

$$\begin{aligned} \bar{y}^{k+1} < \frac{s}{k} &\iff \bar{y} > \frac{s(k-1)}{k(r-1)}, \\ \bar{y}^{k+1} > \frac{s}{k} &\iff \bar{y} < \frac{s(k-1)}{k(r-1)}, \quad \bar{y}^{k+1} = \frac{s}{k} \iff \bar{y} = \frac{s(k-1)}{k(r-1)}. \end{aligned}$$

(1) Let $k \leq 1$, then $\bar{y} > \frac{s(k-1)}{k(r-1)}$, whence $\bar{y}^{k+1} < \frac{s}{k}$. Hence, \bar{y} is locally asymptotically stable by Theorem (6).

(2) Let $k > 1$, We have

$$f\left(\frac{s(k-1)}{k(r-1)}\right) = \frac{s}{k} \left[\left(\frac{s}{k}\right)^k \left(\frac{k-1}{r-1}\right)^{k+1} - 1 \right]$$

where $f(x)$ is defined in (10).

(i) Assume that $s < k \left(\frac{r-1}{k-1}\right)^{\frac{k+1}{k}}$, then $f\left(\frac{s(k-1)}{k(r-1)}\right) < 0$. Hence $\bar{y} > \frac{s(k-1)}{k(r-1)}$ and $\bar{y}^{k+1} < \frac{s}{k}$. Therefore \bar{y} is locally asymptotically stable.

(ii) Assume that $s > k \left(\frac{r-1}{k-1}\right)^{\frac{k+1}{k}}$, then $f\left(\frac{s(k-1)}{k(r-1)}\right) > 0$. Hence $\bar{y} < \frac{s(k-1)}{k(r-1)}$ and $\bar{y}^{k+1} > \frac{s}{k}$. Therefore \bar{y} is unstable (saddle).

(iii) Assume that $s = k \left(\frac{r-1}{k-1}\right)^{\frac{k+1}{k}}$, then $f\left(\frac{s(k-1)}{k(r-1)}\right) = 0$. Then $\bar{y} = \frac{s(k-1)}{k(r-1)}$ and $\bar{y}^{k+1} = \frac{s}{k}$. Therefore \bar{y} is non-hyperbolic. \square

Lemma 2. *If $\{y_n\}_{n=-1}^{\infty}$ is a solution of Eq.(9), then*

$$\frac{\alpha}{1 + \beta \left[\frac{\alpha(1-\beta^n)}{1-\beta} + y_{-1}\beta^n \right]^k} \leq y_{2n} \leq \frac{\alpha(1-\beta^n)}{1-\beta} + y_0\beta^n, \quad n \geq 1 \quad (15)$$

and

$$\frac{\alpha}{1 + \beta \left[\frac{\alpha(1-\beta^n)}{1-\beta} + y_0\beta^n \right]^k} \leq y_{2n-1} \leq \frac{\alpha(1-\beta^n)}{1-\beta} + y_{-1}\beta^n, \quad n \geq 1 \quad (16)$$

where $\alpha = s/r$ and $\beta = 1/r$.

Proof. We have $\frac{s}{r+y_n^k} \leq y_{n+1} \leq \frac{s}{r} + \frac{y_{n-1}}{r}$. Hence

$$\frac{\alpha}{1 + \beta y_n^k} \leq y_{n+1} \leq \alpha + \beta y_{n-1}, \quad n \geq 0. \tag{17}$$

Inequalities (15) and (16) are obtained by (17), using induction on n . □

Corollary 2. Assume that $r > 1$. Let $\{y_n\}_{n=-1}^\infty$ be a solution of Eq.(9) and $\Lambda = \lim_{n \rightarrow \infty} \sup y_n$ and $\lambda = \lim_{n \rightarrow \infty} \inf y_n$, then Λ and λ satisfy the two inequalities,

$$\frac{s}{r + (\frac{s}{r-1})^k} \leq \lambda \leq \Lambda \leq \frac{s}{r-1}, \tag{18}$$

and

$$\frac{s + \lambda}{r + \Lambda^k} \leq \lambda \leq \Lambda \leq \frac{s + \Lambda}{r + \lambda^k}, \tag{19}$$

Proof. Inequality (18) is a direct consequence of (15), and (16). For every $\epsilon \in (0, \lambda) \exists n_0 \in \mathbb{N}$ such that $\lambda - \epsilon \leq y_n \leq \Lambda + \epsilon \forall n \geq n_0$. Then

$$\frac{s + \lambda - \epsilon}{r + (\Lambda + \epsilon)^k} \leq y_n \leq \frac{s + \Lambda + \epsilon}{r + (\lambda - \epsilon)^k} \quad \forall n \geq n_0 + 1.$$

Therefore, $\frac{s+\lambda}{r+\Lambda^k} \leq \lambda \leq \Lambda \leq \frac{s+\Lambda}{r+\lambda^k}$. □

In the following we denote by $I_0 = \left[0, \frac{s}{r-1}\right]$.

Lemma 3. Assume that $r > 1$. The interval I_0 is invariant under the function

$$G(x, y) = \frac{s + x}{r + y^k}. \tag{20}$$

Proof. Let $x, y \in I_0$. Then

$$0 < \frac{s}{r + \left(\frac{s}{r-1}\right)^k} < G(x, y) < \frac{s + x}{r} < \frac{s}{r-1}$$

□

Theorem 11. Assume that $r > 1$. If the system

$$y = \frac{s + y}{r + x^k} \quad \text{and} \quad x = \frac{s + x}{r + y^k}, \tag{21}$$

has exactly one solution in I_0^2 , then the equilibrium point \bar{y} is a global attractor.

Proof. Let $\{y_n\}_{n=-1}^\infty$ be a solution of Eq.(9), $\lambda = \lim_{n \rightarrow \infty} \inf y_n$ and $\Lambda = \lim_{n \rightarrow \infty} \sup y_n$. By corollary (2), $\lambda, \Lambda \in I_0$, which is invariant under $G(x, y)$ (defined in (20)). By Theorem (7), \bar{y} is a global attractor. □

Theorem 12. If $r \geq 1 + (ks^k)^{\frac{1}{k+1}}$, then system (21) has exactly one solution in I_0^2 .

Proof. Assume that (x, y) is a solution of system (21) in I_0^2 . Then we have

$$r + x^k = \frac{s}{y} + 1 \quad \text{and} \quad r + y^k = \frac{s}{x} + 1.$$

Hence, $x^k - y^k = \frac{s}{y} - \frac{s}{x} = \frac{s(x-y)}{xy}$. Assume towards a contradiction that $x \neq y$ say $(y < x)$. Hence

$$\frac{x^k - y^k}{x - y} = \frac{s}{xy}.$$

By the Mean Value Theorem, there exists $c \in (y, x)$ such that $\frac{s}{xy} = kc^{k-1}$. When $k \geq 1$, we have $\frac{s}{xy} < kx^{k-1}$ which implies that $r - 1 < k\left(\frac{s}{r-1}\right)^k$, which is a contradiction. When $k < 1$, we have $\frac{s}{xy} < ky^{k-1}$ which implies that $r - 1 < k\left(\frac{s}{r-1}\right)^k$, which is a contradiction. Then system (21) has exactly one solution $(x, y) = (\bar{y}, \bar{y})$. □

In the following Theorem we establish a sufficient condition for the global asymptotic stability of Eq.(9).

Theorem 13. *If $r \geq 1 + (ks^k)^{\frac{1}{k+1}}$, then the equilibrium point \bar{y} of Eq.(9) is globally asymptotically stable.*

Proof. In the case where $k \leq 1$, \bar{y} is locally asymptotically stable by Theorem (10), and in the case where $k > 1$, the condition $r \geq 1 + (ks^k)^{\frac{1}{k+1}}$ implies that $\left(\frac{k-1}{r-1}\right)^{k+1} < \left(\frac{k}{s}\right)^k$, whence $s < k\left(\frac{r-1}{k-1}\right)^{\frac{k+1}{k}}$ which implies that \bar{y} is locally asymptotically stable. By combining Theorems (11) and (12), we see that \bar{y} is globally asymptotically. □

In the following, we show that the equilibrium point \bar{y} of the equation

$$y_{n+1} = \frac{s + y_{n-1}}{r + y_n^k}, \quad n = 0, 1, \dots, \tag{22}$$

where $r < 1$, is a global attractor with some basin that depends on the coefficients. Let \bar{y} be the equilibrium point of Eq.(22). We can see that

$$\begin{aligned} \bar{y}^{k+1} < \frac{s}{k} & \text{ if and only if } \bar{y} < \frac{s(1-k)}{k(1-r)}, \\ \bar{y}^{k+1} > \frac{s}{k} & \text{ if and only if } \bar{y} > \frac{s(1-k)}{k(1-r)}, \\ \bar{y}^{k+1} = \frac{s}{k} & \text{ if and only if } \bar{y} = \frac{s(1-k)}{k(1-r)}. \end{aligned}$$

In the following Theorem a sufficient condition for \bar{y} to be locally asymptotically stable will be given.

Theorem 14. Assume that $r < 1$. The following statements are true

- (1) If $k \geq 1$, then \bar{y} is unstable.
- (2) Assume that $k < 1$. We have:
 - (i) If $s > k \left(\frac{1-r}{1-k}\right)^{\frac{k+1}{k}}$, then \bar{y} is locally asymptotically stable.
 - (ii) If $s < k \left(\frac{1-r}{1-k}\right)^{\frac{k+1}{k}}$, then \bar{y} is unstable, in fact saddle.
 - (iii) If $s = k \left(\frac{1-r}{1-k}\right)^{\frac{k+1}{k}}$, then \bar{y} is non-hyperbolic.

Proof. (1) Clearly, if $k \geq 1$, then $\bar{y} > \frac{s(1-k)}{k(1-r)}$, whence, $\bar{y}^{k+1} > \frac{s}{k}$. Hence by Theorem (6), \bar{y} is unstable.

(2) Assume that $k < 1$. Consider the function $f(x) = x^{k+1} + (r-1)x - s$. We have

$$f\left(\frac{s(1-k)}{k(1-r)}\right) = \frac{s}{k} \left[\left(\frac{s}{k}\right)^k \left(\frac{1-k}{1-r}\right)^{k+1} - 1 \right].$$

(i) Assume that $s > k \left(\frac{1-r}{1-k}\right)^{\frac{k+1}{k}}$, then $f\left(\frac{s(1-k)}{k(1-r)}\right) > 0$. Hence $\bar{y} < \frac{s(1-k)}{k(1-r)}$ and $\bar{y}^{k+1} < \frac{s}{k}$. Hence \bar{y} is locally asymptotically stable.

(ii) Assume that $s < k \left(\frac{1-r}{1-k}\right)^{\frac{k+1}{k}}$, then $f\left(\frac{s(1-k)}{k(1-r)}\right) < 0$. Hence $\bar{y} > \frac{s(1-k)}{k(1-r)}$ and $\bar{y}^{k+1} > \frac{s}{k}$. Therefore \bar{y} is unstable (saddle).

(iii) Assume that $s = k \left(\frac{1-r}{1-k}\right)^{\frac{k+1}{k}}$, then $f\left(\frac{s(1-k)}{k(1-r)}\right) = 0$. Then $\bar{y} = \frac{s(1-k)}{k(1-r)}$ and $\bar{y}^{k+1} = \frac{s}{k}$. Therefore \bar{y} is non-hyperbolic. □

In the following we denote by $G(x, y) = \frac{s+x}{r+y^k}$.

Lemma 4. Assume that $r < 1$ and $k < 1$.

- (1) If $r \geq \frac{k-1}{k}$, then $I = [1, \frac{s}{r}]$ is invariant under G and I contains \bar{y} .
- (2) If $r \geq 1 + s - s^k$, then $I = [s, 1]$ is invariant under G and I contains \bar{y} .

Proof. (1) The condition $r \geq \frac{k-1}{k}$ implies that $s > 1$. Hence by Lemma (1), $\bar{y} \in (1, \frac{s}{r})$. Let $x, y \in [1, \frac{s}{r}]$, then we have

$$1 = \frac{s+1}{1 + \left(\frac{s}{r}\right)^k} \leq G(x, y) = \frac{s+x}{r+y^k} \leq \frac{s+\frac{s}{r}}{r+1} \leq \frac{s}{r}.$$

(2) The condition $r \geq 1 + s - s^k$, implies that $s < 1$. Also we can see that $s \leq r$. Hence by Lemma (1) $\bar{y} \in [s, 1]$. Let $x, y \in [s, 1]$, then we have

$$s = \frac{s+s}{1+1} \leq G(x, y) = \frac{s+x}{r+y^k} \leq \frac{s+1}{r+s^k} \leq 1.$$

□

Theorem 15. Assume that $r < 1$, $k < 1$.

(i) If $r < s < (\frac{1}{k}r^{k+1})^{\frac{1}{k}}$, then system (21) has exactly one solution $(x, y) \in [1, \frac{s}{r}]^2$.

(ii) If $k < s \leq r$, then system (21) has exactly one solution $(x, y) \in [s, 1]^2$.

Proof. Assume that $(x, y) \in I^2$ is a solution of system (21), and $y < x$, where $I = [1, \frac{s}{r}]$ in statement (i) and $I = [s, 1]$ in statement (ii). Then as before

$$\frac{x^k - y^k}{x - y} = \frac{s}{xy}.$$

There exists $c \in (y, x)$ such that $\frac{s}{xy} = kc^{k-1} \leq ky^{k-1}$. Hence $ky^k \geq \frac{s}{x}$.

(i) Since $r < s$, then $[1, \frac{s}{r}]$ contains \bar{y} . Since $1 \leq x, y \leq \frac{s}{r}$, then $k(\frac{s}{r})^k \geq ky^k \geq \frac{s}{x} \geq \frac{rs}{s} = r$, whence $s^k \geq \frac{r^{k+1}}{k}$, which is a contradiction. Therefore, $x = y = \bar{y}$.

(ii) Since $s \leq r < 1$, then $[s, 1]$ contains \bar{y} . Since $s \leq x, y \leq 1$, then $k \geq ky^k \geq \frac{s}{x} \geq s$, which is a contradiction. Therefore, $x = y = \bar{y}$. \square

Theorem 16. Assume that $r < 1$ and $k < 1$.

(i) If $r^{\frac{k}{k-1}} < s < (\frac{1}{k}r^{k+1})^{\frac{1}{k}}$, then \bar{y} is a global attractor with basin $[1, \frac{s}{r}]^2$.

(ii) If $r \geq 1 + s - s^k$ and $k < s$, then \bar{y} is a global attractor with basin $[s, 1]^2$.

Proof. (i) By Lemma (4) the interval $[1, \frac{s}{r}]$ is invariant under G and contains \bar{y} . The condition $r^{\frac{k}{k-1}} < s < (\frac{1}{k}r^{k+1})^{\frac{1}{k}}$ implies that system (21) has a unique solution in $[1, \frac{s}{r}]^2$. By Corollary (1) \bar{y} is a global attractor with basin $[1, \frac{s}{r}]^2$.

(ii) By the same argument of (i) we can prove (ii). \square

Theorem 17. Assume that $r < 1$, $k < 1$.

(i) If $r^{\frac{k}{k-1}} < s < (\frac{1}{k}r^{k+1})^{\frac{1}{k}}$, then \bar{y} is globally asymptotically stable with basin $[1, \frac{s}{r}]^2$.

(ii) If $r \geq 1 + s - s^k$ and $k < s$, then \bar{y} is globally asymptotically stable with basin $[s, 1]^2$.

Proof. (i) Since $r < 1$ and $k < 1$, then $r < r^{\frac{k}{k-1}} < s$. The condition $r^{\frac{k}{k-1}} < s < (\frac{1}{k}r^{k+1})^{\frac{1}{k}}$ implies that $k < r^{\frac{1}{1-k}} < r$. Hence, $k < r < r^{\frac{k}{k-1}} < s$. Therefore, $\frac{s}{k} > 1 > (\frac{1-r}{1-k})^{\frac{k+1}{k}}$, hence $s > k(\frac{1-r}{1-k})^{\frac{k+1}{k}}$. In view of Theorem (14), \bar{y} is locally asymptotically stable and by Theorem (16), \bar{y} is globally asymptotically stable with basin $[1, \frac{s}{r}]^2$.

(ii) Since, $r \geq 1 + s - s^k$, then $s < 1$. The condition $s - s^k + 1 \leq r < 1$ implies that $s < 1$, which in turn that $s \leq s - s^k + 1$. Hence $k < s \leq r$. Therefore $\frac{s}{k} > 1 > (\frac{1-r}{1-k})^{\frac{k+1}{k}}$. By Theorem (14), \bar{y} is locally asymptotically stable. Again, by Theorem (16), whence \bar{y} is globally asymptotically stable with basin $[s, 1]^2$. \square

Now, we give examples in which conditions of Theorem (17) hold.

Example 1. Consider the recursive sequence

$$x_{n+1} = \frac{s + x_{n-1}}{0.3 + x_n^{0.1}}, \quad n = 0, 1, \dots$$

It is easy to show that for every $s \in (1.15, 17714.7)$, \bar{y} is globally asymptotically stable with basin $[1, \frac{s}{0.3}]$.

The following Theorem shows that outside the basins indicated in the above Theorem, we can establish unbounded solutions for Eq.(22).

Theorem 18. Assume that $r < 1$, $y_{-1}^k < (1 - r)$, $y_0^k > 1 - r + \frac{s}{\sqrt[k]{1-r}}$. Then

$$\lim_{n \rightarrow \infty} y_{2n} = \infty \quad \text{and} \quad \lim_{n \rightarrow \infty} y_{2n-1} = 0.$$

Proof. By induction on n , we can see that $y_{2n-1} < \sqrt[k]{1-r}$, and $y_{2n} > ns + y_0$. Hence $\lim_{n \rightarrow \infty} y_{2n} = \infty$, and consequently, $\lim_{n \rightarrow \infty} y_{2n-1} = 0$. \square

Now, we study the global behavior of Eq.(9) when $r = 1$, that is Eq.(9) yields

$$y_{n+1} = \frac{s + y_{n-1}}{1 + y_n^k}, \quad n = 0, 1, \dots \tag{23}$$

In the sequel we assume that $s \neq 0$, otherwise see section (2).

Lemma 5. (a) Assume that $k < 1$. Then the unique equilibrium point $\bar{y} = \sqrt[k+1]{s}$ of Eq.(23) is locally asymptotically stable.

(b) Assume that $k > 1$. Then the unique equilibrium point $\bar{y} = \sqrt[k+1]{s}$ of Eq.(23) is unstable. In fact, saddle.

Proof. It is clear that Eq.(23) always has a unique equilibrium point $\bar{y} = \sqrt[k+1]{s}$. We can show that

$$p = \frac{-k\bar{y}^k}{1 + \bar{y}^k} \quad \text{and} \quad q = \frac{1}{1 + \bar{y}^k}.$$

(a) Let $k < 1$, whence, the condition $|p| < 1 - q \iff (k - 1)\bar{y}^k < 0$, and $1 - q < 2 \iff 0 < 2 + \bar{y}^k$ is always true. Therefore, the equilibrium point $\bar{y} = \sqrt[k+1]{s}$ is locally asymptotically stable.

(b) Let $k > 1$, whence, the condition $|p| > |1 - q| \iff (k - 1)\bar{y}^k > 0$, and $p^2 + 4q > 0$ is always true. Therefore, the equilibrium point $\bar{y} = \sqrt[k+1]{s}$ is unstable. In fact, saddle. \square

In the sequel we denote \bar{y} the unique equilibrium point of Eq.(23).

Theorem 19. The system

$$x = \frac{s + x}{1 + y^k} \quad \text{and} \quad y = \frac{s + y}{1 + x^k} \tag{24}$$

has exactly one solution (\bar{y}, \bar{y}) .

Proof. Assume on the contrary that the system (24) has a solution (x, y) such that $x \neq y$, then we get $xy(y^{k-1} - x^{k-1}) = 0$, since, $x \neq y$. Hence $xy = 0$ so either $x = 0$ or $y = 0$ both of them imply that $s = 0$, which is a contradiction. Therefore the system has exactly one solution (\bar{y}, \bar{y}) . \square

N.B: Clearly, system (25) has exactly one solution if and only if Eq.(23) has no prime period two solutions. Consider, the function $G(x, y) = \frac{s+y}{1+x^k}$.

Theorem 20. Assume that $k < 1$.

(a) If $s \leq 1$, then $[s, 1]$ is invariant under $G(x, y)$ and $\bar{y} \in [s, 1]$.

(b) If $s > 1$, then $[1, s]$ is invariant under $G(x, y)$ and $\bar{y} \in [1, s]$.

Proof. (a) Let $s \leq 1$ and $k < 1$, we have

$$s = \frac{s+s}{1+1} \leq G(x, y) = \frac{s+y}{1+x^k} \leq \frac{s+1}{1+s^k} \leq 1$$

Therefore, $[s, 1]$ is invariant under G . One can see that $\bar{y} \in [s, 1]$.

(b) Let $s > 1$ and $k < 1$, we have

$$1 \leq \frac{s+1}{1+s^k} \leq \frac{s+y}{1+x^k} = G(x, y) \leq \frac{s+s}{1+1} = s$$

Therefore, $[1, s]$ is invariant under G . One can see that $\bar{y} \in [1, s]$. This completes the proof. \square

We combine Corollary (1), Lemma (5), Theorems (19) and (20), to obtain the following results.

Theorem 21. Assume that $k < 1$. Then the equilibrium point $\bar{y} = \sqrt[k+1]{s}$ of Eq.(23) is globally asymptotically stable with basin $[s, 1]^2$ when $s \leq 1$ and with basin $[1, s]^2$ when $s > 1$.

REFERENCES

1. A. M. Amleh, G. Ladas, and V. Krik ; *On the Dynamics of $x_{n+1} = (a + bx_{n-1})/(A + Bx_{n-2})$* , Math. Sci. Res. Hot-Line 5(2001)1-15 .
2. L. Berg, *On the Asymptotic of nonlinear Difference Equations*. Z. Anal. Anwendungen 21, No., 4,1061-1074(2002).
3. E. Chatterjee, E. A. Grove, Y. Kostrov and G. Ladas, *On the Trichotomy Character of $x_{n+1} = \frac{\alpha + \gamma x_{n-1}}{A + Bx_n + x_{n-2}}$* , Journal of Difference Equations and Applications 9(2003),1113-1128.
4. K. C. Cunningham, M. R. S. Kulenvić, G. Ladas and S. V. Valicenti, *On the Recursive sequence $x_{n+1} = (\alpha + \alpha x_n)/(Bx_n + Cx_{n-1})$* , Nonlinear Anal. TMA 47(2001),4603-4614.
5. R. Devault, W. Kosmala, G. Ladas and S. W. Schultz, *Global Behavior of $y_{n+1} = \frac{p + y_{n-k}}{qy_n + y_{n-k}}$* , Nonlinear Anal. 47(2001),4743-4751.
6. S. Elaydi, *An Introduction to Difference Equations*, 2nd ed., Springer-Verlag, New York, 1999.
7. H. M. El-Owaidy, A. M. Ahmed, and A. M. Youssef ; *On the Dynamics of the Recursive Sequence $x_{n+1} = (\alpha x_{n-1})/(\beta + \gamma x_{n-2}^p)$* , Appl. Math. Lett. 18(9)(2005)1013-1018.

8. H. M. El-Owaidy, A. M. Youssef, and A. M. Ahmed ; *On the Dynamics of $x_{n+1} = (bx_{n-1}^2)(A + Bx_{n-2})^{-1}$* , Rostock, Math. Kolloq. 59,11-18(2005).
9. C. Gibbons, M. Kulenović, and G. Ladas ; *On the Recursive Sequence $y_{n+1} = (\alpha + \beta y_{n-1})/(\gamma + y_n)$* , Math. Sci. Res. Hot-Line 4(2)(2000)1-11.
10. Mona T. Aboutaleb, M. A. El-Sayed, and Alaa E. Hamza, *Stability of the Recursive Sequence $x_{n+1} = \frac{\alpha - \beta x_n}{\gamma + x_{n-1}}$* , Journal of Mathematical Analysis and Applications 261(2001),126-133.
11. W. G. Kelly and A. C. Peterson, *Difference Equations*, Academic Press, New York, 1991.
12. V. L. Kocic and G. Ladas ; *Global Behavior of Nonlinear Difference Equations of Higher Order with applications*. Kluwer Academic publisher, Dordrecht, 1993
13. M. R. S. Kulenović, G. Ladas ; *Dynamics of Second Order Rational Difference Equations*. CHAPMAN&HALL/CRC (2002).
14. S. Stević, *A generalization of the Copson's theorem concerning sequences which satisfy a linear inequality*, Indian J. Math. 43 (3) (2001), 277-282.
15. S. Stević, *On the recursive sequence $x_{n+1} = g(x_n, x_{n-1})/(A + x_n)$* , Appl. Math. Lett. 15 (2002), 305-308.
16. S. Stević, *On the recursive sequence $x_{n+1} = x_{n-1}/g(x_n)$* , Taiwanese J. Math. 6 (3) (2002), 405-414.
17. S. Stević, *On the recursive sequence $x_{n+1} = \frac{\alpha + \beta x_{n-1}}{1 + g(x_n)}$* , Indian J. Pure Appl. Math. 33 (12) (2002), 1767-1774.
18. S. Stević, *Asymptotic behavior of a nonlinear difference equation*, Indian J. Pure Appl. Math. 34 (12) (2003), 1681-1689.
19. Z. Zhang, B. Ping and W. Dong, *Oscillatory of Unstable Type Second-Order neutral Difference Equations*, J. App. Math. & Computing, 9 (1)(2002), 87-100.
20. Z. Zhou, J. Yu and G. Lie *Oscillations for Even-Order Neutral Difference Equations*, J. App. Math. & Computing, 7(3)(2000), 601-610.

H.M.El-Owaidy received his B.Sc.Engin.,B.Sc. Mathematics ,Ph.D at Hungarian Academy of Sc.Budapest Hungary under the direction of Prof.Farkas Miklos .Since 1973 has been at Al-Azhar University ,Cairo.He obtained the rank professor in 1983 .His research interests in difference equations and bio-mathematics.

Mathematics Department, Faculty of Science, Al-Azhar University , Nasr City (11884), Cairo, Egypt.

A.M.Ahmed obtained his B. Sc.(1997),M. Sc.(2000) and Ph.D. (2004)from Al-Azhar University. Now he is doing research in difference equations and its applications.

Mathematics Department, Faculty of Science, Al-Azhar University , Nasr City(11884), Cairo, Egypt.

E-mail: ahmedelkb@yahoo.com.

Alaa E.Hamza: Assistant professor of Mathematics.

Mathematics Department, Faculty of Science, Cairo University, Cairo, Egypt.

A. M. Youssef: Assistant lecturer of Mathematics.

Department of Basic Science, Faculty of Engineering, Misr University for Science and Technology, 6 October city, Giza, Egypt.

E-mail: amr.youssef@hotmail.com (El-negawy).