

**SENSITIVITY ANALYSIS FOR A SYSTEM OF
GENERALIZED NONLINEAR MIXED QUASI-VARIATIONAL
INCLUSIONS WITH (A, η) -ACCRETIVE MAPPINGS
IN BANACH SPACES**

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ABSTRACT. In this paper, we study the behavior and sensitivity analysis of the solution set for a new system of parametric generalized nonlinear mixed quasi-variational inclusions with (A, η) -accretive mappings in q -uniformly smooth Banach spaces. The present results improve and extend many known results in the literature.

1. Introduction

Sensitivity analysis of solutions of variational inequalities with single-valued mappings has been studied by many authors via quite different techniques.

By using the projection method, Dafermos [2], Yen [9], Mukherjee and Verma [6], Noor [7], and Pan [8] studied the sensitivity analysis of solutions of some variational inequalities with single-valued mappings in finite-dimensional spaces or Hilbert spaces.

In 2004, using the concept and technique of resolvent operators, Agawal et. al [1] introduced and studied the behavior and sensitivity analysis of the solution set for a system of parametric variational inclusions in a Hilbert space H , which is called the system of parametric generalized nonlinear mixed quasi-variational inclusion problem:

For a given two nonempty open subsets Ω and Λ of H in which the parameters ω and λ take values, two maximal monotone mappings $M : H \times \Omega \rightarrow 2^H$ and $N : H \times \Lambda \rightarrow 2^H$, nonlinear single-valued mappings $A, S : H \times \Omega \rightarrow H$ and $B, T : H \times \Lambda \rightarrow H$, find $(x, y) \in H \times H$ such that

$$\begin{aligned} 0 &\in x - y + \rho(A(y, \omega) + S(y, \omega)) + \rho M(x, \omega), \\ 0 &\in y - x + \gamma(B(x, \lambda) + T(x, \lambda)) + \gamma N(y, \lambda), \end{aligned}$$

where $\rho, \lambda > 0$ are two constants.

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In this paper, we study the behavior and sensitivity analysis of the solution set for a system of parametric generalized nonlinear mixed quasi-variational inclusions with (A, η) -accretive mappings in q -uniformly smooth Banach spaces. The present results improve and extend many known results in the literature.

2. Preliminaries

Let E be a real Banach space with dual space E^* , $\langle \cdot, \cdot \rangle$ be the dual pair between E and E^* and 2^E denote the family of all the nonempty subsets of E . The generalized duality mapping $J_q : E \rightarrow 2^{E^*}$ is defined by

$$J_q(x) = \{f \in E^* | \langle x, f^* \rangle = \|x\|^q \text{ and } \|f^*\| = \|x\|^{q-1}\}, \forall x \in E,$$

where $q > 1$ is a constant. In particular, J_2 is the usual normalized duality mapping. It is known that, in general, $J_q(x) = \|x\|^{q-2} J_2(x)$ for all $x \neq 0$ and J_q is single-valued if E^* is strictly convex. If $E = H$ is a Hilbert space, then J_2 becomes the identity mapping of H .

The modulus of smoothness of E is the function $\rho_E : [0, \infty) \rightarrow [0, \infty)$ defined by

$$\rho_E(t) = \sup \left\{ \frac{1}{2} (\|x + y\| + \|x - y\|) - 1 : \|x\| \leq 1, \|y\| \leq t \right\}.$$

A Banach space E is called uniformly smooth if $\lim_{t \rightarrow 0} \frac{\rho_E(t)}{t} = 0$. E is called q -uniformly smooth if there exists a constant $c > 0$ such that $\rho_E(t) \leq ct^q$, $q > 1$. Note that J_q is single-valued if E is uniformly smooth.

We consider now a system of parametric generalized nonlinear mixed quasi-variational inclusions with (A, η) -accretive mappings in q -uniformly smooth Banach spaces. To this end, let Ω and Λ be two nonempty open subsets of E in which the parameters ω and λ take values, $S, T : E \times \Omega \rightarrow E$ and $U, V : E \times \Lambda \rightarrow E$ be nonlinear single-valued mappings. Let $M : E \times \Omega \rightarrow 2^E$ and $N : E \times \Lambda \rightarrow 2^E$ be set-valued mappings such that for each given $(\omega, \lambda) \in \Omega \times \Lambda$, $M(\cdot, \omega)$ and $N(\cdot, \lambda) : E \rightarrow 2^E$ are (A, η) -accretive mappings. For each fixed $(\omega, \lambda) \in \Omega \times \Lambda$, the system of parametric generalized nonlinear mixed quasi-variational inclusions with (A, η) -accretive mappings in q -uniformly smooth Banach spaces consist of finding $(x, y) \in E \times E$ such that

$$(2.1) \quad \begin{aligned} 0 &\in A(x) - y + \rho(S(y, \omega) + T(y, \omega)) + \rho M(x, \omega), \\ 0 &\in A(y) - x + \gamma(U(x, \lambda) + V(x, \lambda)) + \gamma N(y, \lambda), \end{aligned}$$

where $\rho > 0$ and $\gamma > 0$ are two constants.

We now discuss some special cases.

Case I. Let $E = H$ be a Hilbert space, $A = I$, the identity mappings, Ω and Λ be two nonempty open subsets of H in which the parameters ω and λ takes values. Let $\phi_1 : H \times \Omega \rightarrow R \cup \{+\infty\}$ and $\phi_2 : H \times \Lambda \rightarrow R \cup \{+\infty\}$ be functionals such that for $(x, \omega) \in H \times \Omega$ and $(y, \lambda) \in H \times \Lambda$, $\partial\phi_1(\cdot, \omega)$ and $\partial\phi_2(\cdot, \lambda)$ denote the subdifferential of proper convex lower semicontinuous functions ϕ_1 and ϕ_2 , respectively. Let $M(\cdot, \omega) = \partial\phi_1(\cdot, \omega)$ and $N(\cdot, \lambda) = \partial\phi_2(\cdot, \lambda)$ for all

$(\omega, \lambda) \in \Omega \times \Lambda$. Then problem (2.1) is equivalent to finding $(x^*, y^*) \in H \times H$ such that

$$(2.2) \quad \begin{aligned} \langle \rho(S(y^*, \omega) + T(y^*, \omega)) + x^* - y^*, x - x^* \rangle &\geq \rho\phi_1(x^*, \omega) - \rho\phi_1(x, \omega), \\ \langle \gamma(U(x^*, \lambda) + V(x^*, \lambda)) + y^* - x^*, x - y^* \rangle &\geq \gamma\phi_2(y^*, \lambda) - \gamma\phi_2(x, \lambda) \end{aligned}$$

for all $x \in H$, which is called the system of parametric generalized nonlinear mixed variational inequalities in Hilbert spaces [1].

Case II. Let K be a nonempty closed convex subset of H and $\phi_i = I_K$ ($i = 1, 2$) are the indicator functions of K . Then problem (2.2) reduces to the problem of finding $(x^*, y^*) \in K \times K$ such that

$$\begin{aligned} \langle \rho(S(y^*, \omega) + T(y^*, \omega)) + x^* - y^*, x - x^* \rangle &\geq 0, \\ \langle \gamma(U(x^*, \lambda) + V(x^*, \lambda)) + y^* - x^*, x - y^* \rangle &\geq 0 \end{aligned}$$

for all $x \in K$, which is called the system of parametric generalized nonlinear quasi-variational inequalities in Hilbert spaces [1].

Definition 2.1. Let $A : E \rightarrow E, \eta : E \times E \rightarrow E$ be two single-valued mappings. Then a multivalued mapping $M : E \rightarrow 2^E$ is said to be

(i) accretive if

$$\langle u - v, J_q(x - y) \rangle \geq 0, \quad \forall x, y \in E, u \in M(x), v \in M(y);$$

(ii) m -relaxed η -accretive if there exists a constant $m > 0$ such that

$$\langle u - v, J_q(\eta(x, y)) \rangle \geq -m\|x - y\|^q, \quad \forall x, y \in E, u \in M(x), v \in M(y);$$

(iii) (A, η) -accretive if M is m -relaxed η -accretive and $(A + \rho M)(E) = E$ for every $\rho > 0$.

Definition 2.2. A mapping $S : E \times \Omega \rightarrow E$ is said to be

(i) δ -strongly accretive with respect to the first argument, $\delta \in (0, 1)$, if

$$\langle S(x, \omega) - S(y, \omega), J_q(x - y) \rangle \geq \delta\|x - y\|^q, \quad \forall x, y \in E;$$

(ii) λ_S -Lipschitz continuous with respect to the first argument if there exists a constant $\lambda_S > 0$ such that

$$\|S(x, \omega) - S(y, \omega)\| \leq \lambda_S\|x - y\|, \quad \forall (x, y, \omega) \in E \times E \times \Omega.$$

Definition 2.3. A single-valued mapping $A : E \rightarrow E$ is said to be

(i) η -accretive if

$$\langle A(x) - A(y), J_q(\eta(x, y)) \rangle \geq 0, \quad \forall x, y \in E;$$

(ii) strictly η -accretive if A is η -accretive and equality holds if and only if $x = y$.

(iii) γ -strongly η -accretive if there exists a constant $\gamma > 0$ such that

$$\langle A(x) - A(y), J_q(\eta(x, y)) \rangle \geq \gamma\|x - y\|^q, \quad \forall x, y \in E.$$

If $A : E \rightarrow E$ is a strictly η -accretive mapping and $M : E \rightarrow 2^E$ is an (A, η) -accretive mapping, then for a constant $\rho > 0$, the resolvent operator associated with A and M is defined by

$$R_{M,\rho}^{A,\eta}(u) = (A + \rho M)^{-1}(u), \quad \forall u \in E.$$

It is well known that $R_{M,\rho}^{A,\eta}$ is a single-valued mapping [5].

Remark 2.1. Since M is an (A, η) -accretive mapping with respect to the first argument, for any fixed $\omega \in \Omega$, we define

$$R_{M(\cdot,\omega),\rho}^{A,\eta}(u) = (A + \rho M(\cdot, \omega))^{-1}(u), \quad \forall u \in D(M),$$

which is called the parametric resolvent operator associated with A and $M(\cdot, \omega)$.

Remark 2.2. Resolvent operators associated with (A, η) -accretive mappings include as special cases the corresponding resolvent operators associated with (H, η) -accretive operators [8], (H, η) -monotone operators [10], H -accretive operators [4], H -monotone operators [3], A -monotone operators [11], the classical m -accretive and maximal monotone operators [14].

Now we need some lemmas which will be used in the proofs for the main results in the next section.

Lemma 2.1 ([12]). *Let E be a real uniformly smooth Banach space. Then E is q -uniformly smooth if and only if there exists a constant $c_q > 0$ such that for all $x, y \in E$*

$$\|x + y\|^q \leq \|x\|^q + q\langle y, J_q(x) \rangle + c_q \|y\|^q.$$

Lemma 2.2 ([5]). *Let E be a q -uniformly smooth Banach space, $\eta : E \times E \rightarrow E$ be τ -Lipschitz continuous, $A : E \rightarrow E$ be r -strongly η -accretive mapping and $M : E \rightarrow 2^E$ be an (A, η) -accretive mapping. Then the resolvent operator $R_{M(\cdot,\omega),\rho}^{A,\eta} : E \rightarrow E$ is $\frac{\tau^{q-1}}{r-\rho m}$ -Lipschitz continuous, i.e.,*

$$\|R_{M(\cdot,\omega),\rho}^{A,\eta}(u) - R_{M(\cdot,\omega),\rho}^{A,\eta}(v)\| \leq \frac{\tau^{q-1}}{r-\rho m} \|u - v\|, \quad \forall u, v \in E,$$

where $\rho \in (0, \frac{r}{m})$ is a constant.

3. Sensitivity analysis of solution set

Throughout the rest of this paper, we always assume that E is a real q -uniformly smooth Banach space. First of all, we prove the following lemma.

Lemma 3.1. *For all fixed $(\omega, \lambda) \in \Omega \times \Lambda$, $(\bar{x}(\omega, \lambda), \bar{y}(\omega, \lambda))$ is a solution of the system of parametric generalized nonlinear quasi-variational inclusions with (A, η) -accretive mapping in q -uniformly smooth Banach space (2.1) if and only if for some given $\rho, \gamma > 0$, the mapping $F : E \times \Omega \times \Lambda \rightarrow E$ defined by*

$$\begin{aligned}
 F(x, \omega, y) &= R_{M(\cdot, \omega), \rho}^{A, \eta} [R_{N(\cdot, \lambda), \gamma}^{A, \eta} (x - \gamma(U + V)(x, \lambda)) \\
 (3.1) \quad &\quad - \rho(S + T)(R_{N(\cdot, \lambda), \gamma}^{A, \eta} (x - \gamma(U + V)(x, \lambda)), \omega)]
 \end{aligned}$$

has a fixed point \bar{x} .

Proof. For each fixed $(\omega, \lambda) \in \Omega \times \Lambda$, let $(\bar{x}(\omega, \lambda), \bar{y}(\omega, \lambda))$ be a solution of problem (2.1). Then for given $\rho, \gamma > 0$,

$$\begin{aligned}
 0 &\in A(\bar{x}) - \bar{y} + \rho(S(\bar{y}, \omega) + T(\bar{y}, \omega)) + \rho M(\bar{x}, \omega), \\
 0 &\in A(\bar{y}) - \bar{x} + \gamma(U(\bar{x}, \lambda) + V(\bar{x}, \lambda)) + \gamma N(\bar{y}, \lambda),
 \end{aligned}$$

which implies that

$$\begin{aligned}
 \bar{y} - \rho(S + T)(\bar{y}, \omega) &\in [A + \rho M(\cdot, \omega)](\bar{x}), \\
 \bar{x} - \gamma(U + V)(\bar{x}, \lambda) &\in [A + \gamma N(\cdot, \lambda)](\bar{y}).
 \end{aligned}$$

Thus, we obtain

$$\begin{aligned}
 (A + \rho M(\cdot, \omega))^{-1}[\bar{y} - \rho(S + T)(\bar{y}, \omega)] &= \bar{x}, \\
 (A + \gamma N(\cdot, \lambda))^{-1}[\bar{x} - \gamma(U + V)(\bar{x}, \lambda)] &= \bar{y},
 \end{aligned}$$

i.e.,

$$\begin{aligned}
 R_{M(\cdot, \omega), \rho}^{A, \eta}[\bar{y} - \rho(S + T)(\bar{y}, \omega)] &= \bar{x}, \\
 R_{N(\cdot, \lambda), \gamma}^{A, \eta}[\bar{x} - \gamma(U + V)(\bar{x}, \lambda)] &= \bar{y}.
 \end{aligned}$$

Hence, we have

$$\begin{aligned}
 \bar{x} &= R_{M(\cdot, \omega), \rho}^{A, \eta} [R_{N(\cdot, \lambda), \gamma}^{A, \eta} (\bar{x} - \gamma(U + V)(\bar{x}, \lambda)) \\
 &\quad - \rho(S + T)(R_{N(\cdot, \lambda), \gamma}^{A, \eta} (\bar{x} - \gamma(U + V)(\bar{x}, \lambda)), \omega)] \\
 &= F(\bar{x}, \omega, \lambda).
 \end{aligned}$$

This means that \bar{x} is a fixed point of $F(x, \omega, \lambda)$.

Now, for any fixed point $(\omega, \lambda) \in (\Omega \times \Lambda)$, let \bar{x} be a fixed point of $F(x, \omega, \lambda)$. By the definition of F ,

$$\begin{aligned}
 \bar{x} &= F(\bar{x}, \omega, \lambda) \\
 &= R_{M(\cdot, \omega), \rho}^{A, \eta} [R_{N(\cdot, \lambda), \gamma}^{A, \eta} (\bar{x} - \gamma(U + V)(\bar{x}, \lambda)) \\
 &\quad - \rho(S + T)(R_{N(\cdot, \lambda), \gamma}^{A, \eta} (\bar{x} - \gamma(U + V)(\bar{x}, \lambda)), \omega)].
 \end{aligned}$$

Let

$$\bar{y} = R_{N(\cdot, \lambda), \gamma}^{A, \eta} (\bar{x} - \gamma(U + V)(\bar{x}, \lambda)).$$

Then we have

$$\bar{x} = R_{M(\cdot, \omega), \rho}^{A, \eta} [\bar{y} - \rho(S + T)(\bar{y}, \omega)].$$

By the definitions of $R_{M(\cdot, \omega), \rho}^{A, \eta}$ and $R_{N(\cdot, \lambda), \gamma}^{A, \eta}$, we get

$$\bar{x} = (A + \rho M(\cdot, \omega))^{-1}[\bar{y} - \rho(S + T)(\bar{y}, \omega)],$$

$$\bar{y} = (A + \gamma N(\cdot, \lambda))^{-1}[\bar{x} - \gamma(U + T)(\bar{x}, \lambda)],$$

which implies that

$$\begin{aligned}\bar{y} - \rho(S + T)(\bar{y}, \omega) &\in [A + \rho M(\cdot, \omega)](\bar{x}), \\ \bar{x} - \gamma(U + V)(\bar{x}, \lambda) &\in [A + \gamma N(\cdot, \lambda)](\bar{y}).\end{aligned}$$

Hence

$$\begin{aligned}0 &\in A(\bar{x}) - \bar{y} + \rho(S(\bar{y}, \omega) + T(\bar{y}, \omega)) + \rho M(\bar{x}, \omega), \\ 0 &\in A(\bar{y}) - \bar{x} + \gamma(U(\bar{x}, \lambda) + V(\bar{x}, \lambda)) + \gamma N(\bar{y}, \lambda).\end{aligned}$$

This completes the proof. \square

Theorem 3.1. *Let $A : E \rightarrow E$, $S, T : E \times \Omega \rightarrow E$, $U, V : E \times \Lambda \rightarrow E$ be five mappings and $M : E \times \Omega \rightarrow 2^E$, $N : E \times \Lambda \rightarrow 2^E$ be two set-valued mappings satisfying the following conditions:*

- (i) A is r -strongly η -accretive mapping,
- (ii) S is λ_S -Lipschitz continuous with respect to the first argument,
- (iii) T is δ -strongly accretive and λ_T -Lipschitz continuous with respect to the first argument,
- (iv) U is λ_U -Lipschitz continuous with respect to the first argument,
- (v) V is α -strongly accretive and λ_V -Lipschitz continuous with respect to the first argument,
- (vi) M and N are (A, η) -accretive with respect to the first argument.

Suppose that there exist $\rho > 0$ and $\gamma > 0$ such that

$$\begin{aligned}(3.2) \quad &1 - \alpha q \gamma + c_q \gamma^q \lambda_V^q < \left(\frac{\gamma - \rho m}{\tau^{q-1}} - \gamma \lambda_U \right)^q, \\ &1 - q \rho \delta + c_q \rho^q \lambda_T^q < \left(\frac{\gamma - \lambda m}{\tau^{q-1}} - \rho \lambda_S \right)^q.\end{aligned}$$

Then

(1) the mapping $F : E \times \Omega \times \Lambda \rightarrow E$ defined by (3.1) is a uniform θ -contractive mapping with respect to $(\omega, \lambda) \in \Omega \times \Lambda$.

(2) for each $(\omega, \lambda) \in \Omega \times \Lambda$, the system of parametric generalized non-linear mixed quasi-variational inclusions with (A, η) -accretive mappings in q -uniformly smooth Banach spaces (2.1) has a nonempty solution set $S(\omega, \lambda)$ and $S(\omega, \lambda)$ is a closed subset of E .

Proof. (1) By the definition of F , for any $x, y \in E$, we have

$$\begin{aligned}(3.3) \quad &\|F(x, \omega, \lambda) - F(y, \omega, \lambda)\| \\ &= \|R_{M(\cdot, \omega), \rho}^{A, \eta} [R_{N(\cdot, \lambda), \gamma}^{A, \eta} (x - \gamma(U + V)(x, \lambda)) \\ &\quad - \rho(S + T)(R_{N(\cdot, \lambda), \gamma}^{A, \eta} (x - \gamma(U + V)(x, \lambda)), \omega)] \\ &\quad - R_{M(\cdot, \omega), \rho}^{A, \eta} [R_{N(\cdot, \lambda), \gamma}^{A, \eta} (y - \gamma(U + V)(y, \lambda))]\end{aligned}$$

$$\begin{aligned}
 & - \rho(S + T)(R_{N(\cdot, \lambda), \gamma}^{A, \eta}(y - \gamma(U + V)(y, \lambda)), \omega) \| \\
 \leq & \frac{\tau^{q-1}}{r - \rho m} \|R_{N(\cdot, \lambda), \gamma}^{A, \eta}(x - \gamma(U + V)(x, \lambda)) \\
 & - \rho(S + T)(R_{N(\cdot, \lambda), \gamma}^{A, \eta}(x - \gamma(U + V)(x, \lambda)), \omega) \\
 & - (R_{N(\cdot, \lambda), \gamma}^{A, \eta}(y - \gamma(U + V)(y, \lambda)) \\
 & - \rho(S + T)(R_{N(\cdot, \lambda), \gamma}^{A, \eta}(y - \gamma(U + V)(y, \lambda)), \omega) \| \\
 \leq & \frac{\tau^{q-1}}{r - \rho m} \|R_{N(\cdot, \lambda), \gamma}^{A, \eta}(x - \gamma(U + V)(x, \lambda)) - R_{N(\cdot, \lambda), \gamma}^{A, \eta}(y - \gamma(U + V)(y, \lambda)) \\
 & - \rho[T(R_{N(\cdot, \lambda), \gamma}^{A, \eta}(x - \gamma(U + V)(x, \lambda)), \omega) \\
 & - T(R_{N(\cdot, \lambda), \gamma}^{A, \eta}(y - \gamma(U + V)(y, \lambda)), \omega)] \| \\
 & + \frac{\tau^{q-1}}{r - \rho m} \rho \|S(R_{N(\cdot, \lambda), \gamma}^{A, \eta}(x - \gamma(U + V)(x, \lambda)), \omega) \\
 & - S(R_{N(\cdot, \lambda), \gamma}^{A, \eta}(y - \gamma(U + V)(y, \lambda)), \omega) \|.
 \end{aligned}$$

From Lemma 2.1, the δ -strong accretivity and λ_T -Lipschitz continuity of T it follows that

(3.4)

$$\begin{aligned}
 & \|R_{N(\cdot, \lambda), \gamma}^{A, \eta}(x - \gamma(U + V)(x, \lambda)) - R_{N(\cdot, \lambda), \gamma}^{A, \eta}(y - \gamma(U + V)(y, \lambda)) \\
 & - \rho\{T(R_{N(\cdot, \lambda), \gamma}^{A, \eta}(x - \gamma(U + V)(x, \lambda)), \omega) \\
 & - T(R_{N(\cdot, \lambda), \gamma}^{A, \eta}(y - \gamma(U + V)(y, \lambda)), \omega)\} \|^q \\
 \leq & \|R_{N(\cdot, \lambda), \gamma}^{A, \eta}(x - \gamma(U + V)(x, \lambda)) - R_{N(\cdot, \lambda), \gamma}^{A, \eta}(y - \gamma(U + V)(y, \lambda))\|^q \\
 & - q\rho\langle T(R_{N(\cdot, \lambda), \gamma}^{A, \eta}(x - \gamma(U + V)(x, \lambda)), \omega) \\
 & - T(R_{N(\cdot, \lambda), \gamma}^{A, \eta}(y - \gamma(U + V)(y, \lambda)), \omega), J_q(R_{N(\cdot, \lambda), \gamma}^{A, \eta}(x - \gamma(U + V)(x, \lambda)) \\
 & - R_{N(\cdot, \lambda), \gamma}^{A, \eta}(y - \gamma(U + V)(y, \lambda))) \rangle \\
 & + c_q \rho^q \|T(R_{N(\cdot, \lambda), \gamma}^{A, \eta}(x - \gamma(U + V)(x, \lambda)), \omega) \\
 & - T(R_{N(\cdot, \lambda), \gamma}^{A, \eta}(y - \gamma(U + V)(y, \lambda)), \omega)\|^q \\
 \leq & (1 - q\rho\delta + c_q \rho^q \lambda_T^q) \|R_{N(\cdot, \lambda), \gamma}^{A, \eta}(x - \gamma(U + V)(x, \lambda)) \\
 & - R_{N(\cdot, \lambda), \gamma}^{A, \eta}(y - \gamma(U + V)(y, \lambda))\|^q \\
 \leq & (1 - q\rho\delta + c_q \rho^q \lambda_T^q) \left(\frac{\tau^{q-1}}{r - \lambda m}\right)^q (\|x - y - \gamma(V(x, \lambda) - V(y, \lambda))\| \\
 & + \gamma\|U(x, \lambda) - U(y, \lambda)\|)^q.
 \end{aligned}$$

Since V is α -strongly accretive and λ_V -Lipschitz continuous with respect to the first argument,

$$\begin{aligned}
 (3.5) \quad & \|x - y - \gamma(V(x, \lambda) - V(y, \lambda))\|^q \\
 & \leq \|x - y\|^q - q\gamma \langle V(x, \lambda) - V(y, \lambda), J_q(x - y) \rangle \\
 & \quad + c_q \gamma^q \|V(x, \lambda) - V(y, \lambda)\|^q \\
 & \leq (1 - \alpha q \gamma + c_q \gamma^q \lambda_V^q) \|x - y\|^q.
 \end{aligned}$$

By the λ_U -Lipschitz continuity of U , we have

$$(3.6) \quad \|U(x, \lambda) - U(y, \lambda)\| \leq \lambda_U \|x - y\|.$$

By the λ_S -Lipschitz continuity of S , (3.5) and (3.6), we obtain

$$\begin{aligned}
 (3.7) \quad & \|S(R_{N(\cdot, \lambda), \gamma}^{A, \eta}(x - \gamma(U + V)(x, \lambda)), \omega) - S(R_{N(\cdot, \lambda), \gamma}^{A, \eta}(y - \gamma(U + V)(y, \lambda)), \omega)\| \\
 & \leq \lambda_S \|R_{N(\cdot, \lambda), \gamma}^{A, \eta}(x - \gamma(U + V)(x, \lambda)), \omega) - R_{N(\cdot, \lambda), \gamma}^{A, \eta}(y - \gamma(U + V)(y, \lambda)), \omega)\| \\
 & \leq \lambda_S \frac{\tau^{q-1}}{r - \lambda m} (\|x - y - \gamma(V(x, \lambda) - V(y, \lambda))\| + \gamma \|U(x, \lambda) - U(y, \lambda)\|) \\
 & \leq \frac{\lambda_S \tau^{q-1}}{r - \lambda m} [(1 - \alpha q \gamma + c_q \gamma^q \lambda_V^q)^{\frac{1}{q}} + \gamma \lambda_U] \|x - y\|.
 \end{aligned}$$

By (3.3)-(3.7), we have

$$\begin{aligned}
 & \|F(x, \omega, \lambda) - F(y, \omega, \lambda)\| \\
 & \leq \left(\frac{\tau^{q-1}}{r - \rho m}\right) \left(\frac{\tau^{q-1}}{r - \lambda m}\right) [(1 - \alpha q \gamma + c_q \gamma^q \lambda_V^q)^{\frac{1}{q}} + \gamma \lambda_U] \\
 & \quad [(1 - q \rho \delta + c_q \rho^q \lambda_T^q)^{\frac{1}{q}} + \rho \lambda_S] \|x - y\| \\
 & = \left(\frac{\tau^{q-1}}{r - \rho m}\right) \left(\frac{\tau^{q-1}}{r - \lambda m}\right) \theta_1 \theta_2 \|x - y\| \\
 (3.8) \quad & = \theta \|x - y\|,
 \end{aligned}$$

where $\theta_1 = (1 - \alpha q \gamma + c_q \gamma^q \lambda_V^q)^{\frac{1}{q}} + \gamma \lambda_U$, $\theta_2 = (1 - q \rho \delta + c_q \rho^q \lambda_T^q)^{\frac{1}{q}} + \rho \lambda_S$ and $\theta = \left(\frac{\tau^{q-1}}{r - \rho m}\right) \left(\frac{\tau^{q-1}}{r - \lambda m}\right) \theta_1 \theta_2$. It follows from condition (3.2) that $\theta < 1$. Thus, (3.8) implies that F is a contractive mapping which is uniform with respect to $(\omega, \lambda) \in \Omega \times \Lambda$.

(2) Since $F(x, \omega, \lambda)$ is a uniform θ -contractive mapping with respect to $(\omega, \lambda) \in \Omega \times \Lambda$, by the Banach fixed point theorem, $F(x, \omega, \lambda)$ has a fixed point $\bar{x}(\omega, \lambda)$ for each $(\omega, \lambda) \in \Omega \times \Lambda$. By Lemma 3.1, $S(\omega, \lambda) \neq \phi$. For each $(\omega, \lambda) \in \Omega \times \Lambda$, let $(x_n, y_n) \in S(\omega, \lambda)$ and $x_n \rightarrow x_0$, $y_n \rightarrow y_0$ as $n \rightarrow \infty$. Then we have

$$x_n \in F(x_n, \omega, \lambda), \quad n = 1, 2, \dots$$

By (1), we have

$$\|F(x_n, \omega, \lambda) - F(x, \omega, \lambda)\| \leq \theta \|x_n - x\|.$$

It follows that

$$\begin{aligned} \|x_0 - F(x_0, \omega, \lambda)\| &\leq \|x_0 - x_n\| + \|x_n - F(x_n, \omega, \lambda)\| \\ &\quad + \|F(x_n, \omega, \lambda) - F(x_0, \omega, \lambda)\| \\ &\leq (1 + \theta) \|x_n - x_0\| \\ &\rightarrow 0 \quad \text{as } n \rightarrow \infty. \end{aligned}$$

Hence we have $x_0 \in F(x_0, \omega, \lambda)$. From Lemma 3.1 we have $(x_0, y_0) \in S(\omega, \lambda)$. Therefore $S(\omega, \lambda)$ is a nonempty closed subset of E . \square

Theorem 3.2. *Under the hypotheses of Theorem 3.1, further assume that for any $x, y \in E$, the mappings $\omega \mapsto S(x, \omega)$, $\omega \mapsto T(x, \omega)$, $\lambda \mapsto U(y, \lambda)$ and $\lambda \mapsto V(y, \lambda)$ are Lipschitz continuous with constants l_S, l_T, l_U, l_V , respectively. Suppose that for any $(t, \omega, \bar{\omega}) \in E \times \Omega \times \Omega$ and $(z, \lambda, \bar{\lambda}) \in E \times \Lambda \times \Lambda$,*

$$\begin{aligned} &\|R_{M(\cdot, \omega), \rho}^{A, \eta}(t) - R_{M(\cdot, \bar{\omega}), \rho}^{A, \eta}(t)\| \leq \mu \|\omega - \bar{\omega}\|, \\ (3.9) \quad &\|R_{N(\cdot, \lambda), \gamma}^{A, \eta}(z) - R_{N(\cdot, \bar{\lambda}), \gamma}^{A, \eta}(z)\| \leq \tau \|\lambda - \bar{\lambda}\|, \end{aligned}$$

where $\mu > 0$ and $\tau > 0$ are two constants.

Then the solution $(x(\omega, \lambda), y(\omega, \lambda))$ for the system of parametric generalized nonlinear mixed quasi-variational inclusions with (A, η) -accretive mappings in q -uniformly smooth Banach spaces (2.1) is Lipschitz continuous.

Proof. For each $(\omega, \lambda), (\bar{\omega}, \bar{\lambda}) \in \Omega \times \Lambda$, by Theorem 3.1, $S(\omega, \lambda)$ and $S(\bar{\omega}, \bar{\lambda})$ are both nonempty closed subsets. Also, $F(x, \omega, \lambda)$ and $F(x, \bar{\omega}, \bar{\lambda})$ are contractive mappings with same constant $\theta \in (0, 1)$ and have fixed points $x(\omega, \lambda)$ and $x(\bar{\omega}, \bar{\lambda})$, respectively. For any fixed $(\omega, \lambda), (\bar{\omega}, \bar{\lambda}) \in \Omega \times \Lambda$, we have

$$\begin{aligned} &\|x(\omega, \lambda) - x(\bar{\omega}, \bar{\lambda})\| \\ &= \|F(x(\omega, \lambda), \omega, \lambda) - F(x(\bar{\omega}, \bar{\lambda}), \bar{\omega}, \bar{\lambda})\| \\ &\leq \|F(x(\omega, \lambda), \omega, \lambda) - F(x(\bar{\omega}, \bar{\lambda}), \omega, \lambda)\| \\ &\quad + \|F(x(\bar{\omega}, \bar{\lambda}), \omega, \lambda) - F(x(\bar{\omega}, \bar{\lambda}), \bar{\omega}, \bar{\lambda})\| \\ &\leq \theta \|x(\omega, \lambda) - x(\bar{\omega}, \bar{\lambda})\| + \|F(x(\bar{\omega}, \bar{\lambda}), \omega, \lambda) - F(x(\bar{\omega}, \bar{\lambda}), \bar{\omega}, \bar{\lambda})\|, \end{aligned}$$

which implies that

$$(3.10) \quad \|x(\omega, \lambda) - x(\bar{\omega}, \bar{\lambda})\| \leq \frac{1}{1 - \theta} \|F(x(\bar{\omega}, \bar{\lambda}), \omega, \lambda) - F(x(\bar{\omega}, \bar{\lambda}), \bar{\omega}, \bar{\lambda})\|.$$

By condition (3.9), we have

$$\begin{aligned} (3.11) \quad &\|F(x(\bar{\omega}, \bar{\lambda}), \omega, \lambda) - F(x(\bar{\omega}, \bar{\lambda}), \bar{\omega}, \bar{\lambda})\| \\ &\leq \|R_{M(\cdot, \omega), \rho}^{A, \eta}[R_{N(\cdot, \lambda), \gamma}^{A, \eta}(x(\bar{\omega}, \bar{\lambda}) - \gamma(U + V)(x(\bar{\omega}, \bar{\lambda}), \lambda))\| \end{aligned}$$

$$\begin{aligned}
 & - S(R_{N(\cdot, \bar{\lambda}), \gamma}^{A, \eta}(x(\bar{\omega}, \bar{\lambda}) - \gamma(U + V)(x(\bar{\omega}, \bar{\lambda}), \bar{\lambda})), \bar{\omega}) \| \\
 & + \mu \|\omega - \bar{\omega}\|.
 \end{aligned}$$

The δ -strongly accretivity of T and the Lipschitz continuity of T , U and V imply

$$\begin{aligned}
 (3.12) \quad & \|R_{N(\cdot, \lambda), \gamma}^{A, \eta}(x(\bar{\omega}, \bar{\lambda}) - \gamma(U + V)(x(\bar{\omega}, \bar{\lambda}), \lambda)) \\
 & - R_{N(\cdot, \lambda), \gamma}^{A, \eta}(x(\bar{\omega}, \bar{\lambda}) - \gamma(U + V)(x(\bar{\omega}, \bar{\lambda}), \bar{\lambda})) \\
 & - \rho \{T(R_{N(\cdot, \lambda), \gamma}^{A, \eta}(x(\bar{\omega}, \bar{\lambda}) - \gamma(U + V)(x(\bar{\omega}, \bar{\lambda}), \lambda)), \omega) \\
 & - T(R_{N(\cdot, \lambda), \gamma}^{A, \eta}(x(\bar{\omega}, \bar{\lambda}) - \gamma(U + V)(x(\bar{\omega}, \bar{\lambda}), \bar{\lambda})), \omega)\} \|^q \\
 \leq & \|R_{N(\cdot, \lambda), \gamma}^{A, \eta}(x(\bar{\omega}, \bar{\lambda}) - \gamma(U + V)(x(\bar{\omega}, \bar{\lambda}), \lambda)) \\
 & - R_{N(\cdot, \lambda), \gamma}^{A, \eta}(x(\bar{\omega}, \bar{\lambda}) - \gamma(U + V)(x(\bar{\omega}, \bar{\lambda}), \bar{\lambda}))\|^q \\
 & - q\rho \langle T(R_{N(\cdot, \lambda), \gamma}^{A, \eta}(x(\bar{\omega}, \bar{\lambda}) - \gamma(U + V)(x(\bar{\omega}, \bar{\lambda}), \lambda)), \omega) \\
 & - T(R_{N(\cdot, \lambda), \gamma}^{A, \eta}(x(\bar{\omega}, \bar{\lambda}) - \gamma(U + V)(x(\bar{\omega}, \bar{\lambda}), \bar{\lambda})), \omega), \\
 & J_q(R_{N(\cdot, \lambda), \gamma}^{A, \eta}(x(\bar{\omega}, \bar{\lambda}) - \gamma(U + V)(x(\bar{\omega}, \bar{\lambda}), \lambda)) \\
 & - R_{N(\cdot, \lambda), \gamma}^{A, \eta}(x(\bar{\omega}, \bar{\lambda}) - \gamma(U + V)(x(\bar{\omega}, \bar{\lambda}), \bar{\lambda}))) \rangle \\
 & + c_q \rho^q \|T(R_{N(\cdot, \lambda), \gamma}^{A, \eta}(x(\bar{\omega}, \bar{\lambda}) - \gamma(C + D)(x(\bar{\omega}, \bar{\lambda}), \lambda)), \omega) \\
 & - T(R_{N(\cdot, \lambda), \gamma}^{A, \eta}(x(\bar{\omega}, \bar{\lambda}) - \gamma(C + D)(x(\bar{\omega}, \bar{\lambda}), \bar{\lambda})), \omega)\|^q \\
 \leq & (1 - q\rho\delta + c_q \rho^q \lambda_T^q) \|R_{N(\cdot, \lambda), \gamma}^{A, \eta}(x(\bar{\omega}, \bar{\lambda}) - \gamma(U + V)(x(\bar{\omega}, \bar{\lambda}), \lambda)) \\
 & - R_{N(\cdot, \lambda), \gamma}^{A, \eta}(x(\bar{\omega}, \bar{\lambda}) - \gamma(U + V)(x(\bar{\omega}, \bar{\lambda}), \bar{\lambda}))\|^q \\
 \leq & (1 - q\rho\delta + c_q \rho^q \lambda_T^q) \frac{\tau^{q(q-1)} \gamma^q}{(r - \lambda m)^q} (\|U(x(\bar{\omega}, \bar{\lambda}), \lambda) - U(x(\bar{\omega}, \bar{\lambda}), \bar{\lambda})\| \\
 & + \|V(x(\bar{\omega}, \bar{\lambda}), \lambda) - V(x(\bar{\omega}, \bar{\lambda}), \bar{\lambda})\|)^q \\
 \leq & (1 - q\rho\delta + c_q \rho^q \lambda_T^q) \frac{\tau^{q(q-1)} \gamma^q}{(r - \lambda m)^q} (l_U + l_V)^q \|\lambda - \bar{\lambda}\|^q.
 \end{aligned}$$

By condition (3.9), we have

$$\begin{aligned}
 (3.13) \quad & \|R_{N(\cdot, \lambda), \gamma}^{A, \eta}(x(\bar{\omega}, \bar{\lambda}) - \gamma(U + V)(x(\bar{\omega}, \bar{\lambda}), \bar{\lambda})) \\
 & - R_{N(\cdot, \bar{\lambda}), \gamma}^{A, \eta}(x(\bar{\omega}, \bar{\lambda}) - \gamma(U + V)(x(\bar{\omega}, \bar{\lambda}), \bar{\lambda}))\| \\
 & \leq \tau \|\lambda - \bar{\lambda}\|.
 \end{aligned}$$

By the l_T -Lipschitz continuity of T , we have

$$\begin{aligned}
 (3.14) \quad & \|T(R_{N(\cdot, \lambda), \gamma}^{A, \eta}(x(\bar{\omega}, \bar{\lambda}) - \gamma(U + V)(x(\bar{\omega}, \bar{\lambda}), \bar{\lambda})), \omega) \\
 & - T(R_{N(\cdot, \lambda), \gamma}^{A, \eta}(x(\bar{\omega}, \bar{\lambda}) - \gamma(U + V)(x(\bar{\omega}, \bar{\lambda}), \bar{\lambda})), \bar{\omega})\|
 \end{aligned}$$

$$\leq l_T \|\omega - \bar{\omega}\|.$$

By using same argument, we can prove

$$(3.15) \quad \begin{aligned} & \|T(R_{N(\cdot, \lambda), \gamma}^{A, \eta}(x(\bar{\omega}, \bar{\lambda}) - \gamma(U + V)(x(\bar{\omega}, \bar{\lambda}), \bar{\lambda})), \bar{\omega}) \\ & \quad - T(R_{N(\cdot, \bar{\lambda}), \gamma}^{A, \eta}(x(\bar{\omega}, \bar{\lambda}) - \gamma(U + V)(x(\bar{\omega}, \bar{\lambda}), \bar{\lambda})), \bar{\omega})\| \\ & \leq \lambda_T \tau \|\lambda - \bar{\lambda}\|, \end{aligned}$$

$$(3.16) \quad \begin{aligned} & \|S(R_{N(\cdot, \lambda), \gamma}^{A, \eta}(x(\bar{\omega}, \bar{\lambda}) - \gamma(U + V)(x(\bar{\omega}, \bar{\lambda}), \lambda)), \omega) \\ & \quad - S(R_{N(\cdot, \lambda), \gamma}^{A, \eta}(x(\bar{\omega}, \bar{\lambda}) - \gamma(U + V)(x(\bar{\omega}, \bar{\lambda}), \bar{\lambda})), \bar{\omega})\| \\ & \leq \|S(R_{N(\cdot, \lambda), \gamma}^{A, \eta}(x(\bar{\omega}, \bar{\lambda}) - \gamma(U + V)(x(\bar{\omega}, \bar{\lambda}), \lambda)), \omega) \\ & \quad - S(R_{N(\cdot, \lambda), \gamma}^{A, \eta}(x(\bar{\omega}, \bar{\lambda}) - \gamma(U + V)(x(\bar{\omega}, \bar{\lambda}), \lambda)), \bar{\omega})\| \\ & \quad + \|S(R_{N(\cdot, \lambda), \gamma}^{A, \eta}(x(\bar{\omega}, \bar{\lambda}) - \gamma(U + V)(x(\bar{\omega}, \bar{\lambda}), \lambda)), \bar{\omega}) \\ & \quad - S(R_{N(\cdot, \lambda), \gamma}^{A, \eta}(x(\bar{\omega}, \bar{\lambda}) - \gamma(U + V)(x(\bar{\omega}, \bar{\lambda}), \bar{\lambda})), \bar{\omega})\| \\ & \leq l_S \|\omega - \bar{\omega}\| + \frac{\lambda_S \tau^{q-1} \gamma}{r - \lambda m} [\|U(x(\bar{\omega}, \bar{\lambda}), \lambda) - U(x(\bar{\omega}, \bar{\lambda}), \bar{\lambda})\| \\ & \quad + \|V(x(\bar{\omega}, \bar{\lambda}), \lambda) - V(x(\bar{\omega}, \bar{\lambda}), \bar{\lambda})\|] \\ & \leq l_S \|\omega - \bar{\omega}\| + \frac{\lambda_S \tau^{q-1} \gamma}{r - \lambda m} (l_U + l_V) \|\lambda - \bar{\lambda}\|, \end{aligned}$$

$$(3.17) \quad \begin{aligned} & \|S(R_{N(\cdot, \lambda), \gamma}^{A, \eta}(x(\bar{\omega}, \bar{\lambda}) - \gamma(U + V)(x(\bar{\omega}, \bar{\lambda}), \bar{\lambda})), \bar{\omega}) \\ & \quad - S(R_{N(\cdot, \bar{\lambda}), \gamma}^{A, \eta}(x(\bar{\omega}, \bar{\lambda}) - \gamma(U + V)(x(\bar{\omega}, \bar{\lambda}), \bar{\lambda})), \bar{\omega})\| \\ & \leq \lambda_S \tau \|\lambda - \bar{\lambda}\|. \end{aligned}$$

It follows from (3.10)-(3.17) that

$$\begin{aligned} & \|x(\omega, \lambda) - x(\bar{\omega}, \bar{\lambda})\| \\ & \leq \frac{1}{1 - \theta} \left[\frac{\tau^{q-1}}{r - \rho m} \left\{ (1 - q\rho\delta + c_q \rho^q \lambda_T^q)^{\frac{1}{q}} \frac{\tau^{q-1} \gamma}{r - \rho m} (l_U + l_V) \|\lambda - \bar{\lambda}\| \right. \right. \\ & \quad + \tau \|\lambda - \bar{\lambda}\| + \rho l_T \|\omega - \bar{\omega}\| + \rho \lambda_T \tau \|\lambda - \bar{\lambda}\| + \rho l_S \|\omega - \bar{\omega}\| \\ & \quad \left. \left. + \rho \lambda_S \frac{\tau^{q-1} \gamma}{r - \lambda m} (l_U + l_V) \|\lambda - \bar{\lambda}\| + \rho \lambda_S \tau \|\lambda - \bar{\lambda}\| \right\} + \mu \|\omega - \bar{\omega}\| \right] \\ & = \frac{1}{1 - \theta} \left[\frac{\tau^{q-1} \rho}{r - \rho m} (l_S + l_T) + \mu \right] \|\omega - \bar{\omega}\| \\ & \quad + \left(\frac{1}{1 - \theta} \right) \left(\frac{\tau^{q-1}}{r - \rho m} \right) \left[\frac{\tau^{q-1}}{r - \rho m} (1 - q\rho\delta + c_q \rho^q \lambda_T^q)^{\frac{1}{q}} \gamma (l_U + l_V) \right. \\ & \quad \left. + \tau + \rho \lambda_T \tau + \frac{\tau^{q-1}}{r - \lambda m} \rho \lambda_S \gamma (l_U + l_V) + \rho \lambda_S \tau \right] \|\lambda - \bar{\lambda}\|, \end{aligned}$$

where θ is the constant of (3.8). This proves that $x(\omega, \lambda)$ is Lipschitz continuous in $(\omega, \lambda) \in \Omega \times \Lambda$.

On the other hand,

$$y(\omega, \lambda) = R_{N(\cdot, \lambda), \gamma}^{A, \eta}(x(\omega, \lambda) - \gamma(U + V)(x(\omega, \lambda), \lambda)),$$

$$y(\bar{\omega}, \bar{\lambda}) = R_{N(\cdot, \bar{\lambda}), \gamma}^{A, \eta}(x(\bar{\omega}, \bar{\lambda}) - \gamma(U + V)(x(\bar{\omega}, \bar{\lambda}), \bar{\lambda})).$$

Hence, we have

$$\begin{aligned} & \|y(\omega, \lambda) - y(\bar{\omega}, \bar{\lambda})\| \\ & \leq \|R_{N(\cdot, \lambda), \gamma}^{A, \eta}(x(\omega, \lambda) - \gamma(U + V)(x(\omega, \lambda), \lambda)) \\ & \quad - R_{N(\cdot, \lambda), \gamma}^{A, \eta}(x(\bar{\omega}, \bar{\lambda}) - \gamma(U + V)(x(\bar{\omega}, \bar{\lambda}), \bar{\lambda}))\| \\ & \quad + \|R_{N(\cdot, \lambda), \gamma}^{A, \eta}(x(\bar{\omega}, \bar{\lambda}) - \gamma(U + V)(x(\bar{\omega}, \bar{\lambda}), \bar{\lambda})) \\ & \quad - R_{N(\cdot, \bar{\lambda}), \gamma}^{A, \eta}(x(\bar{\omega}, \bar{\lambda}) - \gamma(U + V)(x(\bar{\omega}, \bar{\lambda}), \bar{\lambda}))\| \\ & \leq \frac{\tau^{q-1}}{r - \lambda m} [\|x(\omega, \lambda) - x(\bar{\omega}, \bar{\lambda}) - \gamma(V(x(\omega, \lambda), \lambda) - V(x(\bar{\omega}, \bar{\lambda}), \lambda))\| \\ & \quad + \gamma\|V(x(\bar{\omega}, \bar{\lambda}), \lambda) - V(x(\bar{\omega}, \bar{\lambda}), \bar{\lambda})\| + \gamma\|U(x(\omega, \lambda), \lambda) - U(x(\bar{\omega}, \bar{\lambda}), \lambda)\| \\ & \quad + \gamma\|U(x(\bar{\omega}, \bar{\lambda}), \lambda) - U(x(\bar{\omega}, \bar{\lambda}), \bar{\lambda})\|] + \tau\|\lambda - \bar{\lambda}\| \\ & \leq \frac{\tau^{q-1}}{r - \lambda m} [(1 - \alpha q \gamma + c_q \gamma^q \lambda_V^q)^{\frac{1}{q}} \|x(\omega, \lambda) - x(\bar{\omega}, \bar{\lambda})\| + \gamma l_V \|\lambda - \bar{\lambda}\| \\ & \quad + \gamma \lambda_U \|x(\omega, \lambda) - x(\bar{\omega}, \bar{\lambda})\| + \gamma l_U \|\lambda - \bar{\lambda}\|] + \tau \|\lambda - \bar{\lambda}\| \\ & = \frac{\tau^{q-1}}{r - \lambda m} [(1 - \alpha q \gamma + c_q \gamma^q \lambda_V^q)^{\frac{1}{q}} + \gamma \lambda_U] \|x(\omega, \lambda) - x(\bar{\omega}, \bar{\lambda})\| \\ & \quad + [\frac{\tau^{q-1}}{r - \lambda m} \gamma (l_U + l_V) + \tau] \|\lambda - \bar{\lambda}\|. \end{aligned}$$

It follows from the Lipschitz continuity of $x(\omega, \lambda)$ that $y(\omega, \lambda)$ is Lipschitz continuous. This completes the proof of Theorem 3.2. \square

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