

ON GENERALIZED JORDAN LEFT DERIVATIONS IN RINGS

MOHAMMAD ASHRAF AND SHAKIR ALI

ABSTRACT. In this paper, we introduce the notion of generalized left derivation on a ring R and prove that every generalized Jordan left derivation on a 2-torsion free prime ring is a generalized left derivation on R . Some related results are also obtained.

1. Introduction

Throughout the present paper R will denote an associative ring with centre $Z(R)$. Recall that R is prime if $aRb = \{0\}$ implies that $a = 0$ or $b = 0$. As usual $[x, y]$ will denote the commutator $xy - yx$. An additive mapping $d : R \rightarrow R$ is called a derivation (resp. Jordan derivation) if $d(xy) = d(x)y + xd(y)$ (resp. $d(x^2) = d(x)x + xd(x)$) holds for all $x, y \in R$. An additive mapping $\delta : R \rightarrow R$ is said to be a left derivation (resp. Jordan left derivation) if $\delta(xy) = x\delta(y) + y\delta(x)$ (resp. $\delta(x^2) = 2x\delta(x)$) holds for all $x, y \in R$. Clearly, every left derivation on a ring R is a Jordan left derivation but the converse need not be true in general; (see for example [18, Example 1.1]). First author together with Rehman [4] proved that a Jordan left derivation on a 2-torsion free prime ring is a left derivation. Further in [5], authors together with Rehman proved that if R is a 2-torsion free prime ring and $\delta : R \rightarrow R$ is an additive mapping such that $\delta(u^2) = 2u\delta(u)$ for all u in a square closed Lie ideal U of R , then either $U \subseteq Z(R)$ or $\delta(U) = \{0\}$. During the last two decades, there has been ongoing interest concerning the relationship between the left derivation and Jordan left derivation on a prime ring (cf. [1, 4, 5, 7, 9, 14, 17, 18] and reference therein).

Following [12], an additive mapping $F : R \rightarrow R$ is called a generalized derivation (resp. generalized Jordan derivation) if there exists a derivation $d : R \rightarrow R$ such that $F(xy) = F(x)y + xd(y)$ (resp. $F(x^2) = F(x)x + xd(x)$) holds for all $x, y \in R$. Clearly, every generalized derivation on a ring is a

Received January 3, 2007.

2000 *Mathematics Subject Classification.* 16W25, 16N60, 16U80.

Key words and phrases. prime rings, generalized left derivation, generalized Jordan left derivation.

generalized Jordan derivation. But the converse statement does not hold in general (see e.g., [6]). It is shown in [3] that if R is a ring with a commutator which is not a divisor of zero, then every generalized Jordan derivation on R is a generalized derivation. It should be mentioned that the result in [3] concerning generalized Jordan derivation has been improved in [2] and [6] by authors together with Rehman. More related results have also been obtained in [8], [13], and [15], where further references can be found.

Inspired by the definition of generalized derivation, we introduce the notion of generalized left derivation as follows: an additive mapping $G : R \rightarrow R$ is called a *generalized left derivation* (resp. *generalized Jordan left derivation*) if there exists a Jordan left derivation $\delta : R \rightarrow R$ such that $G(xy) = xG(y) + y\delta(x)$ (resp. $G(x^2) = xG(x) + x\delta(x)$) holds for all $x, y \in R$. It is obvious to see that every generalized left derivation on a ring R is a generalized Jordan left derivation. But the converse need not be true in general. The following example justifies this fact:

Example 1.1. Let S be a ring such that the square of each element in S is zero, but the product of some nonzero elements in S is nonzero. Next, let

$$R = \left\{ \begin{pmatrix} 0 & a & b \\ 0 & 0 & a \\ 0 & 0 & 0 \end{pmatrix} \mid a, b \in S \right\}.$$

Define a map $G : R \rightarrow R$ such that

$$G \begin{pmatrix} 0 & a & b \\ 0 & 0 & a \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 0 & b \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}.$$

Then, we can find an associated Jordan left derivation $\delta : R \rightarrow R$ such that

$$\delta \begin{pmatrix} 0 & a & b \\ 0 & 0 & a \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 0 & a & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}.$$

It is straightforward to check that G is a generalized Jordan left derivation but not a generalized left derivation.

In the present paper, our aim is to establish set of conditions under which every generalized Jordan left derivation on a ring is a generalized left derivation. This lead to the discovery of some new results which can be regarded as a contribution to the theory of Jordan derivations in rings.

2. Preliminary results

To facilitate our discussion, we define a mapping $H : R^2 \rightarrow R$ such that $H(x, y) = G(xy) - xG(y) - y\delta(x)$. Since G and δ both are additive, we have for any $x, y, z \in R$;

$$H(x, y + z) = H(x, y) + H(x, z) \text{ and } H(x + y, z) = H(x, z) + H(y, z).$$

Moreover, if H is zero then G is a generalized left derivation on R . We shall make use of commutator identities; $[x, yz] = [x, y]z + y[x, z]$ and $[xy, z] = [x, z]y + x[y, z]$.

We begin with the following lemmas which are essential for developing the proof of our results.

Lemma 2.1 ([14, Proposition 2.2]). *Let R be a ring and X be a 2-torsion free left R -module. If $\delta : R \rightarrow X$ is an additive mapping satisfying $\delta(x^2) = 2x\delta(x)$ for all $x \in R$, then*

- (i) $\delta(x^2y) = x^2\delta(y) + (xy + yx)\delta(x) + x\delta(xy - yx)$ for all $x, y \in R$,
- (ii) $\delta(yx^2) = x^2\delta(y) + (3yx - xy)\delta(x) - x\delta(xy - yx)$ for all $x, y \in R$,
- (iii) $[x, y]\delta([x, y]) = 0$ for all $x, y \in R$,
- (iv) $(x^2y - 2xyx + yx^2)\delta(y) = 0$ for all $x, y \in R$.

Lemma 2.2. *Let R be a 2-torsion free ring and $G : R \rightarrow R$ be a generalized Jordan left derivation with associated Jordan left derivation $\delta : R \rightarrow R$. Then*

- (i) $G(xy + yx) = xG(y) + yG(x) + x\delta(y) + y\delta(x)$ for all $x, y \in R$,
- (ii) $G(xyx) = xyG(x) + 2xy\delta(x) + x^2\delta(y) - yx\delta(x)$ for all $x, y \in R$,
- (iii) $G(xyz + zyx) = xyG(z) + zyG(x) + 2xy\delta(z) + 2zy\delta(x) + xz\delta(y) + zx\delta(y) - yx\delta(z) - yz\delta(x)$ for all $x, y, z \in R$.

Proof. (i) We are given that G is a generalized Jordan left derivation of R such that

$$(2.1) \quad G(x^2) = xG(x) + x\delta(x) \quad \text{for all } x \in R.$$

Linearizing (2.1), we get

$$(2.2) \quad \begin{aligned} G((x + y)^2) &= (x + y)G(x + y) + (x + y)\delta(x + y) \\ &= xG(x) + xG(y) + yG(x) + yG(y) + x\delta(x) \\ &\quad + x\delta(y) + y\delta(x) + y\delta(y) \text{ for all } x, y \in R. \end{aligned}$$

On the other hand, we have

$$(2.3) \quad \begin{aligned} &G((x + y)^2) \\ &= G(x^2 + xy + yx + y^2) \\ &= xG(x) + x\delta(x) + G(xy + yx) + yG(y) + y\delta(y) \text{ for all } x, y \in R. \end{aligned}$$

Combining (2.2) and (2.3), we get the required result.

(ii) Replacing y by $xy + yx$ in (i), we get

$$\begin{aligned} &G(x(xy + yx) + (xy + yx)x) \\ &= xG(xy + yx) + (xy + yx)G(x) + x\delta(xy + yx) \\ &\quad + (xy + yx)\delta(x) \text{ for all } x, y \in R. \end{aligned}$$

Since, $\delta : R \rightarrow R$ is a Jordan left derivation, linearizing $\delta(x^2) = 2x\delta(x)$, we find that

$$\delta(xy + yx) = 2x\delta(y) + 2y\delta(x) \quad \text{for all } x, y \in R,$$

and hence

$$(2.4) \quad \begin{aligned} & G(xy + yx) + (xy + yx)x \\ &= x^2G(y) + 2xyG(x) + 4xy\delta(x) + 3x^2\delta(y) \\ & \quad + yx\delta(x) + yxG(x) \text{ for all } x, y \in R. \end{aligned}$$

Also,

$$(2.5) \quad \begin{aligned} & G(xy + yx) + (xy + yx)x \\ &= G(x^2y) + 2G(xy x) + G(yx^2) \\ &= x^2G(y) + yxG(x) + yx\delta(x) + x^2\delta(y) \\ & \quad + 2yx\delta(x) + 2G(xy x) \text{ for all } x, y \in R. \end{aligned}$$

Comparing (2.4), (2.5) and using the fact that $\text{char}R \neq 2$, we obtain

$$(2.6) \quad G(xy x) = xyG(x) + 2xy\delta(x) + x^2\delta(y) - yx\delta(x) \text{ for all } x, y \in R.$$

(iii) Replace x by $x + z$ in (2.6), to get

$$(2.7) \quad \begin{aligned} & G((x + z)y(x + z)) \\ &= xyG(x) + xyG(z) + zyG(x) + zyG(z) + 2xy\delta(x) \\ & \quad + 2xy\delta(z) + 2zy\delta(x) + 2zy\delta(z) + x^2\delta(y) + xz\delta(y) \\ & \quad + zx\delta(y) + z^2\delta(y) - yx\delta(x) - yx\delta(z) - yz\delta(x) - yz\delta(z) \\ & \quad \text{for all } x, y, z \in R. \end{aligned}$$

On the other hand, we have

$$(2.8) \quad \begin{aligned} & G((x + z)y(x + z)) \\ &= G(xy x) + G(zy z) + G(xyz + zyz) \\ &= xyG(x) + 2xy\delta(x) + x^2\delta(y) - yx\delta(x) + G(xyz + zyx) \\ & \quad + zyG(x) + 2zy\delta(z) + z^2\delta(y) - yz\delta(z) \text{ for all } x, y, z \in R. \end{aligned}$$

Comparing (2.7) and (2.8), we get (iii). \square

The following lemma play the key role in the proof of main theorem.

Lemma 2.3. *Let R be a 2-torsion free ring and $G : R \rightarrow R$ be a generalized Jordan left derivation with associated Jordan left derivation $\delta : R \rightarrow R$. Then*

$$(2.9) \quad [x, y]H(x, y) = 0 \quad \text{for all } x, y \in R.$$

Proof. Replace z by $xy - yx$ in Lemma 2.2(iii), to get

$$(2.10) \quad \begin{aligned} & G(xy(xy - yx) + (xy - yx)yx) \\ &= xyG(xy) - xyG(yx) + [x, y]yG(x) + [x, y]\delta([x, y]) + xy\delta([x, y]) \\ & \quad + 2[x, y]y\delta(x) + x[x, y]\delta(y) + [x, y]x\delta(y) - y[x, y]\delta(x) \\ & \quad \text{for all } x, y, z \in R. \end{aligned}$$

Now, application of Lemma 2.1(iii) yields that

$$\begin{aligned}
 & G(xy(xy - yx) + (xy - yx)yx) \\
 (2.11) \quad & = xyG(xy) - xyG(yx) + [x, y]yG(x) \\
 & \quad + 2[x, y]y\delta(x) + xy\delta([x, y]) + x[x, y]\delta(y) \\
 & \quad + [x, y]x\delta(y) - y[x, y]\delta(x) \text{ for all } x, y \in R.
 \end{aligned}$$

Also, we have

$$\begin{aligned}
 & G(xy(xy - yx) + (xy - yx)yx) \\
 (2.12) \quad & = G((xy)^2 - xy^2x + xy^2x - (yx)^2) \\
 & = G((xy)^2) - G((yx)^2) \\
 & = xyG(xy) + xy\delta(xy) - yxG(yx) - yx\delta(yx) \text{ for all } x, y \in R.
 \end{aligned}$$

Combining (2.11) and (2.12), we find that

$$\begin{aligned}
 (2.13) \quad & yxG(yx) - xyG(yx) + [x, y]yG(x) + 2[x, y]y\delta(x) \\
 & \quad + xy\delta([x, y]) + x[x, y]\delta(y) + [x, y]x\delta(y) - y[x, y]\delta(x) \\
 & \quad + yx\delta(yx) - xy\delta(xy) = 0 \text{ for all } x, y \in R.
 \end{aligned}$$

This implies that

$$\begin{aligned}
 (2.14) \quad & [y, x]G(yx) + [x, y]yG(x) + [x, y]x\delta(y) + 2[x, y]y\delta(x) \\
 & \quad - 2y[x, y]\delta(x) + x[x, y]\delta(y) + y[x, y]\delta(x) + yx\delta(xy) \\
 & \quad - xy\delta(xy) = 0 \text{ for all } x, y \in R.
 \end{aligned}$$

By Lemma 2.1(iv), we have

$$\begin{aligned}
 (2.15) \quad & x[x, y]\delta(y) + y[x, y]\delta(x) + yx\delta(xy) - xy\delta(xy) \\
 & = (x^2y - 2xyx + yx^2)\delta(y) - (y^2x - 2yxy + xy^2)\delta(x) \\
 & = 0 \text{ for all } x, y \in R
 \end{aligned}$$

and

$$\begin{aligned}
 (2.16) \quad & 2[x, y]y\delta(x) - 2y[x, y]\delta(x) \\
 & = 2(y^2x - 2yxy + xy^2)\delta(x) = 0 \text{ for all } x, y \in R.
 \end{aligned}$$

Now, in view of (2.15) and (2.16), (2.14) reduces to

$$[y, x]G(yx) + [x, y]yG(x) + [x, y]x\delta(y) = 0 \text{ for all } x, y \in R.$$

This implies that

$$[x, y](G(xy) - xG(y) - y\delta(x)) = 0, \text{ i.e., } [x, y]H(x, y) = 0 \text{ for all } x, y \in R.$$

□

3. Main results

The main results of the present paper states as follows:

Theorem 3.1. *Let R be a 2-torsion free ring such that R has a commutator which is not a left zero divisor. Let $G : R \rightarrow R$ be a generalized Jordan left derivation with associated Jordan left derivation $\delta : R \rightarrow R$. Then every generalized Jordan left derivation on R is a generalized left derivation on R .*

Proof. By the assumption, for any fixed element $a, b \in R$ such that $[a, b]c = 0$ implies that $c = 0$. By Lemma 2.3, we have

$$(3.1) \quad H(a, b) = 0.$$

Replacing x by $x + a$ in (2.9) and using (2.9), we obtain

$$(3.2) \quad [x, y]H(a, y) + [a, y]H(x, y) = 0 \text{ for all } x, y \in R.$$

Linearizing (3.2) on y , we find that

$$(3.3) \quad [x, b]H(a, y) + [a, y]H(x, b) + [a, b]H(x, y) + [a, b]H(x, b) \\ = 0 \text{ for all } x, y \in R.$$

Substituting a for x in (3.3) and using (3.1), we have $2[a, b]H(a, y) = 0$ for all $x, y \in R$. Since $\text{char}R \neq 2$, the last expression yields that $[a, b]H(a, y) = 0$ for all $x, y \in R$ and hence $H(a, y) = 0$ for all $y \in R$. Again, put b for y in (3.2), we find that $H(x, b) = 0$ for all $x \in R$. Therefore, equation (3.3) reduces to $[a, b]H(x, y) = 0$ for all $x, y \in R$ and hence $H(x, y) = 0$ for all $x, y \in R$, i.e., $G(xy) = xG(y) + y\delta(x)$ for all $x, y \in R$. This completes the proof of our theorem. \square

Corollary 3.1. *Let R be a 2-torsion free ring such that R has a commutator which is not a left zero divisor. If $\delta : R \rightarrow R$ is a Jordan left derivation, then δ is a left derivation on R .*

If the ring R is prime, then we have the following results:

Proposition 3.1. *Let R be a 2-torsion free prime ring. If R admits a generalized left derivation with associated Jordan left derivation δ , then either $\delta = 0$ or R is commutative.*

Proof. Let $G : R \rightarrow R$ be a generalized left derivation with associated Jordan left derivation $\delta : R \rightarrow R$. Then for any $x, y \in R$, we have

$$(3.4) \quad G(x^2y) = x^2G(y) + 2yx\delta(x) \text{ for all } x, y \in R.$$

On the other hand, we find that

$$(3.5) \quad G(x^2y) = G(x(xy)) = x^2G(y) + 2xy\delta(x) \text{ for all } x, y \in R.$$

Comparing (3.4) and (3.5), we obtain

$$(3.6) \quad 2[x, y]\delta(x) = 0 \text{ for all } x, y \in R.$$

Since R is a 2-torsion free, the equation (3.6) implies that $[x, y]\delta(x) = 0$ for all $x, y \in R$. Replacing y by yz in the last expression, we find that $[x, y]R\delta(x) = \{0\}$ for all $x, y \in R$. Thus for each $x \in R$, the primeness of R implies that either $[x, y] = 0$ or $\delta(x) = 0$ for all $y \in R$. Now, we put $A = \{x \in R \mid \delta(x) = 0\}$, and $B = \{x \in R \mid [x, y] = \{0\} \text{ for all } y \in R\}$. Then, clearly A and B are additive subgroups of R whose union is R . But a group can not be written as a set theoretic union of two of its proper subgroups and hence we obtain that either $A = R$ or $B = R$. If $A = R$, then $\delta(x) = 0$ for all $x \in R$. On the other hand, if $B = R$, then $[x, y] = 0$ for all $x, y \in R$ and hence R is commutative. The proof of the proposition is complete. \square

As a special case of above proposition, we have the following result:

Corollary 3.2. *Let R be a 2-torsion free prime ring. If R admits a nonzero Jordan left derivation δ , then R is commutative.*

Theorem 3.2. *Let R be a 2-torsion free prime ring. Let $G : R \rightarrow R$ be a generalized Jordan left derivation with associated Jordan left derivation $\delta : R \rightarrow R$. Then every generalized Jordan left derivation is a generalized left derivation on R .*

Proof. If the associated Jordan left derivation $\delta = 0$, then G is a Jordan left multiplier on R . Therefore in view of Proposition 1.4 [19], G is a left multiplier (right centralizer). Hence for $\delta = 0$, it is a generalized left derivation.

On the other hand suppose that the associated Jordan left derivation $\delta \neq 0$. Then, by Corollary 3.2, R is commutative. Notice that in view of main theorem of [4], every Jordan left derivation on a 2-torsion free prime ring is a left derivation. Hence by Lemma 2.2(i) and using the fact that R is 2-torsion free prime ring, we find that

$$\begin{aligned}
 (3.7) \quad G(xyz + zyx) &= G((xy)z + z(yx)) \\
 &= xyG(z) + zG(yx) + xy\delta(z) + zy\delta(x) + zx\delta(y) \\
 &\quad \text{for all } x, y, z \in R.
 \end{aligned}$$

Combining (3.7) with Lemma 2.2(iii), we find that

$$\begin{aligned}
 (3.8) \quad &zG(yx) + xy\delta(z) + zx\delta(y) + zy\delta(x) \\
 &= zyG(x) + 2xy\delta(z) + 2zy\delta(x) + xz\delta(y) + zx\delta(y) - yz\delta(x) - yx\delta(z) \\
 &\quad \text{for all } x, y, z \in R.
 \end{aligned}$$

Since R is commutative, so equation (3.8) reduces to

$$z(G(yx) - yG(x) - x\delta(y)) = 0 \text{ for all } x, y, z \in R.$$

This implies that

$$(G(yx) - yG(x) - x\delta(y))R(G(yx) - yG(x) - x\delta(y)) = \{0\} \text{ for all } x, y \in R.$$

Thus, the primeness of R yields that $G(yx) - yG(x) - x\delta(y) = 0$ for all $x, y \in R$. That is, $G(xy) = xG(y) + y\delta(x)$ for all $x, y \in R$. Hence, G is a generalized left derivation on R . This completes the proof of our theorem. \square

The following example demonstrates that R to be prime is essential in the hypotheses of the above theorem.

Example 3.1. Consider the rings S and R , as in Example 1.1, and define maps $G, \delta : R \rightarrow R$ in similar manner. Then, it can be easily seen that $G(r^2) = rG(r) = rG(s) = r\delta(r) = s\delta(r) = 0$ for all $r, s \in R$ but $G(rs) \neq 0$ for some nonzero elements $r, s \in R$.

In the end, it is to remark that the above result may be obtained for semiprime ring, but to our knowledge it has not yet been settled.

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MOHAMMAD ASHRAF
DEPARTMENT OF MATHEMATICS
ALIGARH MUSLIM UNIVERSITY
ALIGARH-202002, INDIA
E-mail address: mashraf80@hotmail.com

SHAKIR ALI
DEPARTMENT OF MATHEMATICS
ALIGARH MUSLIM UNIVERSITY
ALIGARH-202002, INDIA
E-mail address: shakir50@rediffmail.com