# UNIQUENESS AND MULTIPLICITY OF SOLUTIONS FOR THE NONLINEAR ELLIPTIC SYSTEM 

Tacksun Jung* and Q-Heung Choi **

Abstract. We investigate the uniqueness and multiplicity of solutions for the nonlinear elliptic system with Dirichlet boundary condition

$$
\begin{cases}-\Delta u+g_{1}(u, v)=f_{1}(x) & \text { in } \Omega, \\ -\Delta v+g_{2}(u, v)=f_{2}(x) & \text { in } \Omega,\end{cases}
$$

where $\Omega$ is a bounded set in $R^{n}$ with smooth boundary $\partial \Omega$. Here $g_{1}, g_{2}$ are nonlinear functions of $u, v$ and $g_{1}, g_{2}$ are nonlinear functions of $u, v$ and $f_{1}, f_{2}$ are source terms.

## 1. Introduction

In this paper we investigate the uniqueness and multiplicity of solutions for the nonlinear elliptic system with Dirichlet boundary condition

$$
\begin{cases}-\Delta u+g_{1}(u, v)=f_{1}(x) & \text { in } \Omega  \tag{1.1}\\ -\Delta v+g_{2}(u, v)=f_{2}(x) & \text { in } \Omega \\ u=0, \quad v=0 & \text { on } \partial \Omega\end{cases}
$$

where $\Omega$ is a bounded set in $R^{n}$ with smooth boundary $\partial \Omega$. Here $g_{1}, g_{2}$ are nonlinear functions of $u, v$ and $f_{1}, f_{2}$ are source terms.

System (1.1) can be rewritten by

$$
\left\{\begin{align*}
-\Delta U+G(U)=\binom{f_{1}}{f_{2}} & \text { in } \Omega  \tag{1.2}\\
U=\binom{0}{0} & \text { on } \partial \Omega
\end{align*}\right.
$$

where $U=\binom{u}{v}, G(U)=\binom{g_{1}}{g_{2}},-\Delta U=\binom{-\Delta u}{-\Delta v}$.
Received February 14, 2008.
2000 Mathematics Subject Classification: Primary 34C15, 34C25, 35Q72.
Key words and phrases: system of elliptic equations, Dirichlet boundary condition, eigenfunction, eigenvalue problem.

System (1.1) of the nonlinear biharmonic equations with Dirichlet boundary condition is considered as a model of the cross of the two nonlinear oscillations in differential equation.

For the case of the single biharmonic equation Tarantello([9]), Lazer and McKenna([7]), Choi and Jung ([4]) etc., investigate the multiplicity of the solutions via the degree theory or the critical point theory or the variational reduction method. In this paper we improve the multiplicity results of the single biharmonic equation to the case of the system of the nonlinear elliptic system.

Let $\Omega$ be a bounded set in $R^{n}$ with smooth boundary $\partial \Omega$. Let $\lambda_{k}, k=$ $1,2, \ldots$, denote the eigenvalues and $\phi_{k}, k=1,2, \ldots$, the corresponding eigenfunctions, suitably normalized with respect to $L^{2}(\Omega)$ inner product, of the eigenvalue problem

$$
\begin{gathered}
\Delta u+\lambda u=0 \quad \text { in } \Omega, \\
u=0 \quad \text { on } \partial \Omega,
\end{gathered}
$$

where each eigenvalue $\lambda_{k}$ is repeated as often as its multiplicity. We recall that $0<\lambda_{1}<\lambda_{2} \leq \lambda_{3} \leq \ldots \rightarrow+\infty$, and that $\phi_{1}(x)>0$ for $x \in \Omega$. The set of functions $\left\{\phi_{k}\right\}$ is an orthonormal base for $L^{2}(\Omega)$. Let us denote an element $u$, in $L^{2}(\Omega)$, as

$$
u=\sum h_{k} \phi_{k}, \quad \sum h_{k}^{2}<\infty .
$$

We define a subspace $\mathcal{D}$ of $L^{2}(\Omega)$ as follows

$$
\mathcal{D}=\left\{u \in L^{2}(\Omega) \mid \sum \lambda_{k} h_{k}^{2}<\infty\right\} .
$$

Then this is a complete normed space with a norm

$$
\|u\|=\left[\sum \lambda_{k} h_{k}^{2}\right]^{\frac{1}{2}} .
$$

Let us set $E=\mathcal{D} \times \mathcal{D}$. We endow the Hilbert $E$ with the norm

$$
\|(u, v)\|_{E}^{2}=\|u\|^{2}+\|v\|^{2} \quad \forall(u, v) \in E .
$$

We are looking for the weak solutions of (1.1) in $E$, that is, $(u, v)$ satisfying the equation

$$
\int_{\Omega}\left(-\Delta u+g_{1}(u, v)\right) z+\int_{\Omega}\left(-\Delta v+g_{2}(u, v)\right) w-\int_{\Omega} f_{1} z-\int_{\Omega} f_{2} w=0
$$

for all $(z, w) \in E$.

In section 2 we investigate the uniqueness of solutions for the nonlinear elliptic system with Dirichlet boundary condition

$$
\left\{\begin{array}{l}
-\Delta u+a v^{+}=\alpha \phi_{1}+f \quad \text { in } \Omega,  \tag{1.3}\\
-\Delta v+b u^{+}=\beta \phi_{1}+g \quad \text { in } \Omega, \\
u=0, \quad v=0 \quad \text { on } \partial \Omega,
\end{array}\right.
$$

where $u^{+}=\max \{u, 0\}, a, b \in R, \alpha, \beta \in R$,. Here $\phi_{1}$ is the positive eigenfunction of the eigenvalue problem $\Delta u+\lambda u=0 \quad$ in $\Omega, u=$ $0 \quad$ on $\partial \Omega$ and $\lambda_{1}$ is the first eigenvalue corresponding to $\phi_{1}$. In section 3 we investigate the multiplicity of solutions for the nonlinear elliptic system with Dirichlet boundary condition

$$
\left\{\begin{array}{l}
-\Delta u+a v^{-}=\alpha \phi_{1}+\epsilon_{1} f \quad \text { in } \Omega,  \tag{1.4}\\
-\Delta v+b u^{-}=\beta \phi_{1}+\epsilon_{2} g \quad \text { in } \Omega, \\
u=0, \quad v=0 \quad \text { on } \partial \Omega .
\end{array}\right.
$$

## 2. Uniqueness result for the elliptic system

In this section we investigate the uniqueness of solutions for the nonlinear elliptic system with Dirichlet boundary condition

$$
\left\{\begin{array}{l}
-\Delta u+a v^{+}=\alpha \phi_{1}+f \quad \text { in } \Omega,  \tag{2.1}\\
-\Delta v+b u^{+}=\beta \phi_{1}+g \quad \text { in } \Omega, \\
u=0, \quad v=0 \quad \text { on } \partial \Omega,
\end{array}\right.
$$

where $u^{+}=\max \{u, 0\}, a, b \in R, \alpha, \beta \in R$,. Here $\phi_{1}$ is the positive eigenfunction of the eigenvalue problem $\Delta u+\lambda u=0 \quad$ in $\Omega, u=$ 0 on $\partial \Omega$ and $\lambda_{1}$ is the first eigenvalue corresponding to $\phi_{1}$.

The subspace $\mathcal{D}$ of $L^{2}(\Omega)$,

$$
\mathcal{D}=\left\{u \in L^{2}(\Omega) \mid \sum \lambda_{k} h_{k}^{2}<\infty\right\},
$$

a complete normed space with a norm

$$
\|u\|=\left[\sum \lambda_{k} h_{k}^{2}\right]^{\frac{1}{2}}
$$

Let us set $E=\mathcal{D} \times \mathcal{D}$. We endow the Hilbert space $E$ with the norm

$$
\|(u, v)\|_{E}^{2}=\|u\|^{2}+\|v\|^{2}
$$

We are looking for the weak solutions of (2.1) in $\mathcal{D} \times \mathcal{D}$, that is, $(u, v)$ such that $u \in \mathcal{D}, v \in \mathcal{D}, L u+a v^{+}=\alpha \phi_{1}+f, L v+a u^{+}=\beta \phi_{1}+g$.

Lemma 2.1. Suppose that $c$ is not an eigenvalue of $L: \mathcal{D} \rightarrow H_{0}$, $L u=u-\Delta u$, and let $f \in \mathcal{D}$. Then we have $(L-c)^{-1} f \in \mathcal{D}$.

Lemma 2.1 was proved in [3].
Lemma 2.2. The system

$$
\left\{\begin{array}{cc}
-\Delta u+a v=\alpha \phi_{1} & \text { in } \Omega,  \tag{2.2}\\
-\Delta v+b u=\beta \phi_{1} & \text { in } \Omega, \\
u=0, \quad v=0 & \text { on } \partial \Omega,
\end{array}\right.
$$

has a unique solution $\left(u^{*}, v^{*}\right) \in E=\mathcal{D} \times \mathcal{D}$, which is of the form

$$
u^{*}=\frac{\alpha \lambda_{1}-b \beta}{\lambda_{1}^{2}-a b} \phi_{1}, \quad v^{*}=\frac{\beta \lambda_{1}-a \alpha}{\lambda_{1}^{2}-a b} \phi_{1} .
$$

Proof. We note that $\left(u^{*}, v^{*}\right)$ is a solution of the system (2.2) and the uniqueness is trivial.

We need to find a spectral analysis for the linear operator $-\Delta U$. The following lemma need a simple 'Fourier Series' argument.

Lemma 2.3. Let $a, b \in R$ and let $\mathcal{L}_{a b}: \mathcal{D} \times \mathcal{D} \rightarrow L^{2}(\Omega) \times L^{2}(\Omega)$ be defined by $\mathcal{L}_{a b}(u, v)=(L u+a v, L v+b u)$. For $\mu \in R$ we have (a) if $\left(\lambda_{j}-\mu\right)^{2} \neq a b$ for every $j$, then

$$
\left(\mathcal{L}_{a b}-\mu I\right)^{-1}: L^{2}(\Omega) \times L^{2}(\Omega) \rightarrow L^{2}(\Omega) \times L^{2}(\Omega)
$$

is well defined and continuous;
(b) if $\left(\lambda_{j}-\mu\right)^{2}=a b$ for some $j$, then

$$
\operatorname{Ker}\left(\mathcal{L}_{a b}-\mu I\right)=\operatorname{span}\left\{\phi_{j}:\left(\lambda_{j}-\mu\right)^{2}=a b\right\} ;
$$

moreover if $X_{\mu}=\overline{\operatorname{span}\left\{\phi_{m n}:\left(\lambda_{m n}-\mu\right)^{2} \neq a b\right\}}$, then

$$
\left(\mathcal{L}_{a b}-\mu I\right)^{-1}: X_{\mu} \times X_{\mu} \rightarrow X_{\mu} \times X_{\mu}
$$

is well defined and continuous.
Notice that if $a b<0$, the second alternative can never occur.
For the proof of the lemma we refer [3].
We assume that

$$
\begin{equation*}
\lambda_{j}^{2}-a b \neq 0, \quad \text { for all } j \text { with } j \geq 0 \tag{2.3}
\end{equation*}
$$

$$
\begin{align*}
a & <\lambda_{1}, & b & <\lambda_{1},  \tag{2.4}\\
a b & >0, & \sqrt{a b} & <\lambda_{1} . \tag{2.5}
\end{align*}
$$

Using Lemma 2.3 with the case $\mathcal{L}(u, v)=(L u, L v)$ we can easily derive the following lemma.

Lemma 2.4. Assume that the conditions (2.3), (2.4) and (2.5) hold. Then the system

$$
\begin{cases}-\Delta u+a v=0 & \text { in } \Omega \\ -\Delta v+b u=0 & \text { in } \Omega \\ u=0, \quad v=0 & \text { on } \partial \Omega\end{cases}
$$

has only the trivial solution $U=\binom{0}{0}$.
Lemma 2.5. Assume that $f, g \in \mathcal{D}$ with $\int_{\Omega} f \phi_{1}=\int_{\Omega} g \phi_{1}=0$. Then the system

$$
\left\{\begin{array}{lc}
-\Delta u+a v=f & \text { in } \Omega \\
-\Delta v+b u=g & \text { in } \Omega \\
u=0, \quad v=0 & \text { on } \partial \Omega
\end{array}\right.
$$

has a unique solution $\left(u_{0}, v_{0}\right) \in E=\mathcal{D} \times \mathcal{D}$.

Theorem 2.6. (Existence of a negative solution) Assume that the conditions (2.3), (2.4) and (2.5) hold. Assume that $f, g \in L^{2}(\Omega)$ with $\int_{\Omega} f \phi_{1}=\int_{\Omega} g \phi_{1}=0$. Then there exists $\left(\alpha_{0}, \beta_{0}\right)$ with $\alpha_{0}<0$ and $\beta_{0}<0$ such that the system (2.1) has a negative solution ( $\check{u}, \check{v}$ ) with $\check{u}<0$ and $\check{v}<0$ for each $\alpha$ and $\beta$ with $\alpha<\alpha_{0}$ and $\beta<\beta_{0}$,

Proof. By Lemma 2.2 and Lemma 2.5, $\left(u^{*}+u_{0}, v^{*}+v_{0}\right)$ is a solution of the system

$$
\left\{\begin{array}{l}
-\Delta u+a v=\alpha \phi_{1}+f \quad \text { in } \Omega \\
-\Delta v+b u=\beta \phi_{1}+g \quad \text { in } \Omega \\
u=0, \quad v=0 \quad \text { on } \partial \Omega
\end{array}\right.
$$

By Lemma 2.6, $u_{0} \in \mathcal{D}$ and $v_{0} \in \mathcal{D}$. Since the elements of $\mathcal{D}$ lies in $C^{1}$, the elements $u_{0}, v_{0} \in C^{1}$. Thus we can find $\left(\alpha_{0}, \beta_{0}\right)$ with $\alpha_{0}<0$ and $\beta_{0}<0$ such that $u^{*}+u_{0}<0$ and $v^{*}+v_{0}<0$ for each $\alpha<\alpha_{0}$ and $\beta<\beta_{0}$. Thus we prove the theorem .

THEOREM 2.7. (Existence of a positive solution) Assume that the conditions (2.3), (2.4) and (2.5) hold. Assume that $f, g \in L^{2}(\Omega)$ with $\int_{\Omega} f \phi_{1}=\int_{\Omega} g \phi_{1}=0$. Then there exists $\left(\alpha_{1}, \beta_{1}\right)$ with $\alpha_{1}>0$ and $\beta_{1}>0$ such that system (2.1) has a positive solution $(\hat{u}, \hat{v})$ with $\hat{u}>0$ and $\hat{v}>0$ for each $\alpha$ and $\beta$ with $\alpha>\alpha_{1}$ and $\beta>\beta_{1}$

Proof. By Lemma 2.2 and Lemma 2.5, $\left(u^{*}+u_{0}, v^{*}+v_{0}\right)$ is a solution of the system

$$
\left\{\begin{array}{l}
-\Delta u+a v=\alpha \phi_{1}+f \quad \text { in } \Omega \\
-\Delta v+b u=\beta \phi_{1}+g \quad \text { in } \Omega \\
u=0, \quad v=0 \quad \text { on } \partial \Omega
\end{array}\right.
$$

By Lemma 2.5, $u_{0} \in \mathcal{D}$ and $v_{0} \in \mathcal{D}$. Since the elements of $\mathcal{D}$ lies in $C^{1}$, the elements $u_{0}, v_{0} \in C^{1}$. Thus we can find $\left(\alpha_{1}, \beta_{1}\right)$ with $\alpha_{1}<0$ and $\beta_{1}<0$ such that $u^{*}+u_{0}<0$ and $v^{*}+v_{0}<0$ for each $\alpha<\alpha_{1}$ and $\beta<\beta_{1}$. Thus we prove the theorem .

Theorem 2.8. (Uniqueness Theorem) Assume that the conditions (1.2), (1.3) and (1.4) hold and $f, g \in L^{2}(\Omega)$ with $\int_{\Omega} f \phi_{1}=\int_{\Omega} g \phi_{1}=0$. Then, (i) system (2.1) has a unique solution in $\mathcal{D} \times \mathcal{D}$. In particular, (ii) there exists $\left(\alpha_{0}, \beta_{0}\right)$ with $\alpha_{0}<0$ and $\beta_{0}<0$ such that system (2.1) has a unique solution, which is a negative solution $(\check{u}, \check{v})$ with $\check{u}<0$ and $\check{v}<0$ in Theorem 2.6 for each $\alpha$ and $\beta$ with $\alpha<\alpha_{0}$ and $\beta<\beta_{0}$,
(iii) there exists $\left(\alpha_{1}, \beta_{1}\right)$ with $\alpha_{1}>0$ and $\beta_{1}>0$ such that system (2.1) has a unique solution, which is a positive solution $(\hat{u}, \hat{v})$ with $\hat{u}>0$ and $\hat{v}>0$ in Theorem 2.7 for each $\alpha$ and $\beta$ with $\alpha>\alpha_{1}$ and $\beta>\beta_{1}$.

Proof. Assume that conditions (2.3), (2.4) and (2.5) hold. First we will prove (i). To prove it we use the contraction mapping principle.
By assumption (2.5), $-\lambda_{1}<-\sqrt{a b}<0<\sqrt{a b}<\lambda_{1}$. Let us set $\delta=\lambda_{1}$. Then system (2.1) is equivalent to

$$
\begin{equation*}
U=(\mathcal{L}+\delta I)^{-1}\left[(\delta I-A) U^{+}-\delta I U^{-}+\binom{\alpha \phi_{1}+f}{\beta \phi_{1}+g}\right] \tag{2.6}
\end{equation*}
$$

where $A=\left(\begin{array}{ll}0 & a \\ b & 0\end{array}\right), U^{+}=\binom{u^{+}}{v^{+}}, U^{-}=\binom{u^{-}}{v^{-}}$and $(\mathcal{L}+\delta)^{-1}$ is a compact, self-adjoint, linear map from $L^{2}(\Omega) \times L^{2}(\Omega)$ into $L^{2}(\Omega) \times L^{2}(\Omega)$ with norm $\frac{1}{2 \lambda_{1}}$. We note that

$$
\begin{gathered}
\left\|(\delta I-A)\left(U_{2}^{+}-U_{1}^{+}\right)-\delta I\left(U_{2}^{-}-U_{1}^{-}\right)\right\| \leq \max \{\operatorname{det}(\delta I-A), \operatorname{det}(\delta I)\}\left\|U_{2}-U_{1}\right\| \\
<\left\|U_{2}-U_{1}\right\|
\end{gathered}
$$

It follows that the right hand side of (2.6) defines a Lipschitz mapping of $L^{2}(\Omega) \times L^{2}(\Omega)$ into $L^{2}(\Omega) \times L^{2}(\Omega)$ with Lipschitz constant $\gamma<1$. Therefore, by the contraction mapping principle, there exists a unique solution $U=\binom{u}{v} \in L^{2}(\Omega) \times L^{2}(\Omega)$ of (2.6). By Lemma 2.1, $U=\binom{u}{v} \in$ $\mathcal{D} \times \mathcal{D}$. Thus (i) is proved and (ii) and (iii) come from Theorem 2.6 and Theorem 2.7.

## 3. Multiple solutions for the elliptic system

In this section we investigate the multiplicity of solutions for the nonlinear elliptic system with Dirichlet boundary condition

$$
\left\{\begin{array}{l}
-\Delta u+a v^{-}=\alpha \phi_{1}+\epsilon_{1} f \quad \text { in } \Omega,  \tag{3.1}\\
-\Delta v+b u^{-}=\beta \phi_{1}+\epsilon_{2} g \quad \text { in } \Omega, \\
u=0, \quad v=0 \quad \text { on } \partial \Omega
\end{array}\right.
$$

Here we assume that $\alpha>0, \beta>0$.
Lemma 3.1. Assume that $\alpha>0, \beta>0$. Assume that $\left(\lambda_{1}^{2}-\right.$ $a b)\left(\lambda_{1} \beta-\alpha b\right)<0,\left(\lambda_{1}^{2}-a b\right)\left(\lambda_{1} \alpha-\beta a\right)<0$. Then the system

$$
\left\{\begin{array}{l}
-\Delta u+a v^{-}=\alpha \phi_{1} \quad \text { in } \Omega  \tag{3.2}\\
-\Delta v+b u^{-}=\beta \phi_{1} \quad \text { in } \Omega \\
u=0, \quad v=0 \quad \text { on } \partial \Omega
\end{array}\right.
$$

has at least two solutions, one of which is positive, and one of which is positive.

Proof. Assume that $\alpha>0, \beta>0$. Then system (3.2) has a positive solution $U_{1}=\binom{u_{1}}{v_{1}}$ :

$$
u_{1}=\frac{\alpha}{\lambda_{1}} \phi_{1}, \quad v_{1}=\frac{\beta}{\lambda_{1}} \phi_{1}
$$

Since $\left(\lambda_{1}^{2}-a b\right)\left(\lambda_{1} \beta-\alpha b\right)<0,\left(\lambda_{1}^{2}-a b\right)\left(\lambda_{1} \alpha-\beta a\right)<0$, system (3.2) has a negative solution $U_{2}=\binom{u_{2}}{v_{2}}$ :

$$
u_{2}=\frac{\lambda_{1} \beta-\alpha b}{\lambda_{1}^{2}-a b} \phi_{1}, \quad v_{2}=\frac{\lambda_{1} \alpha-\beta a}{\lambda_{1}^{2}-a b} \phi_{1} .
$$

Hence (3.2) has at least two solutions, one of which is positive, and one of which is positive.

Theorem 3.2. (Existence of two solutions) Assume that $\alpha>0$, $\beta>0$. Assume that $\left(\lambda_{1}^{2}-a b\right)\left(\lambda_{1} \beta-\alpha b\right)<0,\left(\lambda_{1}^{2}-a b\right)\left(\lambda_{1} \alpha-\beta a\right)<0$. Let $\|f\|=\|g\|=1$. Then there exists $\left(\epsilon_{1}^{*}, \epsilon_{2}^{*}\right)$ such that if $\epsilon_{1}<\epsilon_{1}^{*}, \epsilon_{2}<\epsilon_{2}^{*}$ then system (3.1) has at least two solutions, one of which is positive, and one of which is positive.

The proof of Theorem 3.2 is similar to that of Theorem 2.8.

## References

[1] H. Amann, Saddle points and multiple solutions of differential equations, Math. Z., (1979), 127-166.
[2] Q. H. Choi and T. Jung, An application of a variational reduction method to a nonlinear wave equation, J. Differential Equations 7, (1995) 390-410.
[3] T. Jung and Q. H. Choi, The existence of a positive solution of the system of the nonlinear wave equations with jumping nonlinearities, Nonlinear Analysis, TMA., to be appeared.
[4] Q. H. Choi and T. Jung Multiplicity results on a nonlinear biharmonic equation, Rocky Mountain J. Math. 29 (1999), no. 1, 141-164.
[5] Q. H. Choi and T. Jung, On periodic solutions of the nonlinear suspension bridge equation, Diff. Int. Eq. 4 (1991), no. 2, 383-396.
[6] Q. H. Choi , T. Jung, and P.J. McKenna, The study of a nonlinear suspension bridge equation by a variational reduction method, Applicable Analysis, 50, (1993), 73-92.
[7] A. C. Lazer and P.J. McKenna, Critical points theory and boundary value problems with nonlinearities crossing multiple eigenvalues II, Comm. P.D.E. 11(15) (1986), 1653-1676.
[8] L. Nirenberg, Topics in Nonlinear Functional Analysis, Courant Inst. Lecture Notes (1974).
[9] G. Tarantello, A note on a semilinear elliptic problem, Differential and Integral Equations, 5, no. 3, May 1992, 561-565.

## *

Department of Mathematics
Kunsan National University
Kunsan 573-701, Republic of Korea
E-mail: tsjung@kunsan.ac.kr
**
Department of Mathematics Education
Inha University
Incheon 402-751, Republic of Korea
E-mail: qheung@inha.ac.kr

