# HOMOGENEOUS REAL HYPERSURFACES IN <br> A COMPLEX HYPERBOLIC SPACE WITH FOUR CONSTANT PRINCIPAL CURVATURES 

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#### Abstract

We deal with the classification problem of real hypersurfaces in a complex hyperbolic space. In order to classify real hypersurfaces in a complex hyperbolic space we characterize a real hypersurface $M$ in $H_{n}(\mathbb{C})$ whose structure vector field is not principal. We also construct extrinsically homogeneous real hypersurfaces with four distinct curvatures and their structure vector fields are not principal.


## 1. Introduction

Since E. Cartan's work in the late 30's classification problem of hypersurfaces with constant principal curvatures is known to be far from trivial. Among the many great deals some differential geometers have studied the classification problem of real hypersurfaces in a complex hyperbolic space, however, a complete classification has not been obtained until now. This paper deals with the classification problem in a complex hyperbolic space.

Let $H_{n}(\mathbb{C})$ be a complex hyperbolic space of complex dimension $n(\geqq 2)$ endowed with the metric of constant holomorphic sectional curvature -4 , and $M$ be a real hypersurface in $H_{n}(\mathbb{C})$.
S. Montiel ([7]) gave the following classification theorem.

Theorem A. Let $M$ be a connected real hypersurface of $H_{n}(\mathbb{C}) n(\geqq$ 3) with two distinct constant principal curvatures, then $M$ is holomorphic congruent to one of the model spaces of $A_{0}$ and $A_{1}$.

Moreover, J. Berndt[2] proved the following theorem.

[^0]Theorem B. Let $M$ be a connected real hypersurface of $H_{n}(\mathbb{C})$ with constant principal curvatures. If $M$ has a principal structure vector field, then $M$ is holomorphic congruent to an open part of well-known homogeneous model spaces $A_{0}, A_{1}, A_{2}$, and $B$ type.

The homogeneous model spaces of $A_{0}$ are horospheres, and have two distinct principal curvatures 2 and 1 with multiplicities 1 and $2 n-2$ respectively. Those of type $A_{1}$ are geodesic spheres (resp. tubes over totally geodesic complex hyperbolic hyperplanes), and have two distinct principal curvatures $2 \operatorname{coth} 2 t$ and $\tanh t($ resp. $\operatorname{coth} t$ ) with multiplicities 1 and $2 n-2$ respectively. The $A_{2}$ types are tubes over totally geodesic $H_{k}(\mathbb{C})$ $(1 \leq k \leq n-2)$, and have three distinct principal curvatures $2 \operatorname{coth} 2 t, \tanh t$ and $\operatorname{coth} t$ with multiplicities $1,2 p$ and $2 q$ respectively, where $p>0, q>0$ and $p+q=n-1$. The $B$ types are tubes over totally real hyperbolic space $H_{n}(\mathbb{R})$, and have three distinct principal curvatures $2 \tanh 2 t$ of multiplicity 1 , $\operatorname{coth} t$ of multiplicity $n-1$ and $\tanh t$ of multiplicity $n-1$, unless $\operatorname{coth} t=\sqrt{3}$. When $\operatorname{coth} t=\sqrt{3}$, they have two distinct principal curvatures with multiplicities $n$ and $n-1$.

An orbit in $H_{n}(\mathbb{C})$ is said to be extrinsically homogeneous if it is an orbit under a closed subgroup $L$ of the identity component $G$ of the group of all isometries of $H_{n}(\mathbb{C})$. For such orbits, the orbit with the maximal dimension is called principal. Moreover, if such an principal orbit is a real hypersurface in $H_{n}(\mathbb{C})$ with $r$ distinct constant principal curvatures, then this orbit is said to be of $r$-type.

As proposed also in R. Niebergall and P. J. Ryan([5]), the following is an open problem : Classify all extrinsically homogeneous real hypersurfaces in $H_{n}(\mathbb{C})$. From theorem A it is well known that every extrinsically homogeneous real hypersurface $M$ in $H_{n}(\mathbb{C})$ of 2-type is congruent to one of the model spaces of $A_{0}$ and $A_{1}$. Recently when an extrinsically real hypersurface $M$ is of 3 -type in a $H_{n}(\mathbb{C})$ and its structure vector field is not principal, some differential geometers have studied this problem. For this problem J. Saito ([6]) proved that every extrinsically homogeneous real hypersurface of

3-type in $H_{n}(\mathbb{C})$ has a principal structure vector field. However there is a mistake in deduction to lead a certain formula. In fact J. Berndt ([1]) and I.-B. Kim, H.S. Kim and R.Takagi([4]) showed that there are real hypersurfaces with three distinct constant principal curvatures on which structure vector fields are not principal in $H_{n}(\mathbb{C})$. In addition, for these real hypersurfaces I.-B. Kim, H.S. Kim and R.Takagi([4]) classified all homogeneous real hypersurfaces in the case where: the multiplicities of the principal curvatures with respect to nonzero components of structure vector field are 1 and 1.

Recently, in [1], J. Berndt constructed subgroups $B_{n}$ and $L_{n}$ of the connected component of the group of isometries of $H_{n}(\mathbb{C})$ for each $n$ such that: (1) a certain orbit $B_{n}(o)$ under $B_{n}$ has three distinct principal curvatures $1,-1$ and 0 with multiplicities $1,1,2 n-3$ respectively and the structure vector field on $B_{n}(o)$ is not principal. These the number of distinct principal curvatures does not depend on all points. Such orbit $B_{n}(0)$ is said to be a Be type of first kind.
(2) a certain orbit $L_{n}(o)$ under $B_{n}$ has three distinct principal curvatures or four distinct principal curvatures, i.e., the number of distinct principal curvatures depend on a point. Such orbit $L_{n}(o)$ is said to be a Be type of second kind.

Through this paper we assume that:
(C) Every real hypersurface $M$ has three distinct constant principal curvatures and its structure vector field is not principal.
In this paper, we shall deal with an extrinsically homogeneous real hypersurface $M$ such that the structure vector field on $M$ is not principal and $M$ has four distinct principal curvatures in $H_{n}(\mathbb{C})$. First, we investigate some properties of multiplicities of the principal curvatures with respect to nonzero components of structure vector field. Next, we show that there is a real hypersurface $M$ in $H_{n}(\mathbb{C})$ for the case where: the multiplicities of the principal curvatures with respect to nonzero components of structure vector field are 1 and $k(\geq 2)$. Last, we construct extrinsically homogeneous real
hypersurfaces with four distinct curvatures and their structure vector fields are not principal.

## 2. Preliminaries

Let $H_{n}(\mathbb{C})$ be a complex hyperbolic space of complex dimension $n(\geqq 3)$ with the metric of constant holomorphic sectional curvature -4 , and $M$ be a real hypersurface in $H_{n}(\mathbb{C})$ with the induced metric. Choose a local field $\left\{e_{1}, \cdots, e_{2 n}\right\}$ of orthonormal frame in a way that, restricted to $M$, the vectors $e_{1}, \cdots, e_{2 n-1}$ are tangent to $M$. Hereafter let the indices $i, j, k, l$ run through from 1 to $2 n-1$ unless otherwise stated. We denote by $\theta^{i}, \theta_{j}^{i}$ and $\Theta_{j}^{i}$ the canonical 1-forms, the connection forms and curvature form of $M$ respectively. Then they satisfy

$$
\begin{align*}
& d \theta^{i}+\sum_{j} \theta_{j}^{i} \wedge \theta^{j}=0, \quad \theta_{j}^{i}+\theta_{i}^{j}=0, \\
& d \theta_{j}^{i}+\sum_{k} \theta_{k}^{i} \wedge \theta_{j}^{k}=\Theta_{j}^{i} \tag{2.1}
\end{align*}
$$

We denote by $\widetilde{J}$ the natural complex structure of $H_{n}(\mathbb{C})$ and $\left(J_{j}^{i}, \xi_{i}\right)$ be the almost contact structure of $M$, i.e., $\widetilde{J}\left(e_{i}\right)=\sum_{j} J_{i}^{j} e_{j}+\xi_{i} e_{2 n}$. Then $\left(J_{j}^{i}, \xi_{i}\right)$ satisfies

$$
\begin{equation*}
\sum_{k} J_{k}^{i} J_{j}^{k}=-\delta_{j}^{i}+\xi_{i} \xi_{j}, \quad \sum_{j} J_{i}^{j} \xi_{j}=0, \quad \sum_{i} \xi_{i} \xi_{i}=1, \tag{2.2}
\end{equation*}
$$

where $\xi=\sum \xi_{i} e_{i}$ is said to be the structure vector field of $M$ and $\xi_{i}$ is called the components of $\xi$. Let $\phi_{i}$ be 1 -forms of $M$ such that $\sum_{i} \phi_{i} \theta^{i}$ is the second fundamental form of $M$ for $e_{2 n}$. Then the parallelism of $\widetilde{J}$ of $H_{n}(\mathbb{C})$ implies

$$
\begin{gather*}
d J_{j}^{i}=\sum_{k}\left(J_{k}^{i} \theta_{j}^{k}-J_{k}^{j} \theta_{i}^{k}\right)-\xi_{i} \phi_{j}+\xi_{j} \phi_{i},  \tag{2.3}\\
d \xi_{i}=\sum_{k}\left(\xi_{k} \theta_{i}^{k}-J_{i}^{k} \phi_{k}\right) . \tag{2.4}
\end{gather*}
$$

The equation of Gauss is given by

$$
\begin{equation*}
\Theta_{j}^{i}=\phi_{i} \wedge \phi_{j}-\theta^{i} \wedge \theta^{j}-\sum_{k, l}\left(J_{k}^{i} J_{l}^{j}+J_{j}^{i} J_{l}^{k}\right) \theta^{k} \wedge \theta^{l} . \tag{2.5}
\end{equation*}
$$

The equation of Codazzi is given by

$$
\begin{equation*}
d \phi_{i}=-\sum_{j} \phi_{j} \wedge \theta_{i}^{j}-\sum_{j, k}\left(\xi_{j} J_{k}^{i}+\xi_{i} J_{k}^{j}\right) \theta^{j} \wedge \theta^{k} \tag{2.6}
\end{equation*}
$$

We assume that all principal curvatures $\lambda_{1}, \cdots, \lambda_{2 n-1}$ (not necessarily distinct) of $M$ for $e_{2 n}$ are constant. We may set $\phi_{i}=\lambda_{i} \theta^{i}$. For an index $i$, we denote by $[i]$ the set of indices $j$ with $\lambda_{i}=\lambda_{j}$. Then it is obvious that the vector $V_{i}=\sum_{j \in[i]} \xi_{j} e_{j}$ is independent of the choice of orthonormal frame $\left\{e_{j} \mid j \in[i]\right\}$ for the eigenspace belonging to $\xi_{i}$. Therefore for any index $i$ we can indicate a special index $i^{\prime}$ so that the vector $V_{i}$ linearly depends on $e_{i^{\prime}}$. In other words, we can choose an orthonormal frame for the eigenspace belonging to $\lambda_{i}$ so that $\xi_{j}=0$ for $j \in[i] \backslash\left\{i^{\prime}\right\}$. In the same way, for $J_{k}^{j}\left(j\right.$ is any index and fixed and $k$ is the index that $\left.\lambda_{k} \neq \lambda_{i^{\prime}}\right)$, we can indicate a special index $k^{\prime}$ and choose an orthonormal frame for the eigenspace belonging $\lambda_{k^{\prime}}$ so that $J_{l}^{j}=0$ for $l \in[k] \backslash\left\{k^{\prime}\right\}$.

Then by (2.1) and (2.6) we can write the connection forms $\theta_{j}^{i}$ in the form

$$
\begin{equation*}
\left(\lambda_{i}-\lambda_{j}\right) \theta_{j}^{i}=-\sum_{k}\left(A_{i j k}+\xi_{i} J_{k}^{j}+\xi_{j} J_{k}^{i}\right) \theta^{k}, \tag{2.7}
\end{equation*}
$$

where $A_{i j k}=A_{j i k}=A_{i k j}$. From (2.7), it is easily seen that

$$
\begin{equation*}
A_{i j k}=-\xi_{i} J_{k}^{j}-\xi_{j} J_{k}^{i} \quad \text { if } \lambda_{i}=\lambda_{j}, \tag{2.8}
\end{equation*}
$$

We quote an important formula,

$$
\begin{align*}
& 2 \sum_{k}^{\lambda_{k} \neq \lambda_{i}} \frac{\left(A_{i j k}+\xi_{k} J_{j}^{i}+\xi_{i} J_{j}^{k}\right)^{2}}{\lambda_{k}-\lambda_{i}} \\
&-2 \sum_{k}^{\lambda_{k} \neq \lambda_{j}} \frac{\left(A_{i j k}+\xi_{k} J_{i}^{j}+\xi_{j} J_{i}^{k}\right)^{2}}{\lambda_{k}-\lambda_{j}}  \tag{2.10}\\
&+6\left(\lambda_{i}-\lambda_{j}\right) J_{j}^{i^{2}}-3\left(\xi_{j}^{2} \lambda_{i}-\xi_{i}^{2} \lambda_{j}\right)-\left(\lambda_{i}-\lambda_{j}\right)\left(c+\lambda_{i} \lambda_{j}\right) \\
&= 0 .
\end{align*}
$$

Hereafter we assume that $M$ has three distinct constant principal curvatures $x, y$, and $z$. Let $m(x), m(y)$ and $m(z)$ be the multiplicities of $x, y$ and $z$ respectively. We shall make use of the following convention on the range of indices:

$$
\begin{aligned}
& 1 \leq a, b, c \leq m(x), \quad m(x)+1 \leq r, s, t \leq m(x)+m(y) \\
& m(x)+m(y)+1 \leq u, v, w \leq 2 n-1 .
\end{aligned}
$$

From now on $m(x), m(y)$, and $m(z)$ are called the multiplicities with respect to components $\xi_{a}, \xi_{r}$ and $\xi_{u}$, respectively.

## 3. Properties of the structure vector field on $M$

From now on we assume that the structure vector field $\xi$ is not principal and we investigate its properties.

Now we note the following fact.
Lemma ([6]). If $M$ has three distinct constant principal curvatures and its structure vector field is not principal, then there exists an orthonormal frame $\left\{e_{1}, e_{2}, \cdots, e_{2 n-1}\right\}$ on $M$ such that $\xi_{u}=0$ and $\xi_{a} \xi_{r} \neq 0$.

There are three cases for multiplicities as follows .
(1) $m(x)=m(y)=1$,
(2) $m(x), m(y) \geq 2$.
(3) $m(x)=1, m(y) \geq 2$.

Case (1): In this case, we have $m(z) \geq 3$. Moreover $J_{12}=0$. Hence $J_{u v} \neq 0$ since $\operatorname{rank} J=2 n-2$. Now we can choose an orthonormal frame $\left\{e_{u}\right\}$ so that

$$
J_{13}=-\xi_{2}, J_{23}=\xi_{1} \quad \text { and } \quad J_{1 u}=J_{2 u}=J_{3 u}=0(u \neq 3) .
$$

Let us take the exterior derivative of $\xi_{u}=0$. Then we have

$$
\begin{gather*}
\frac{\xi_{1}^{2}}{x-z}+\frac{\xi_{2}^{2}}{y-z}=z  \tag{03.1}\\
\frac{3 \xi_{1}^{2}}{x-z}+\frac{A_{123}+\xi_{2}^{2}}{y-z}=x \tag{03.2}
\end{gather*}
$$

$$
\begin{gather*}
\frac{A_{123}-\xi_{1}^{2}}{x-z}-\frac{3 \xi_{2}^{2}}{y-z}=-y .  \tag{03.3}\\
A_{12 u}=0 \text { if } a \neq 3
\end{gather*}
$$

It follows from (03.1) and the relation $\xi_{1}^{2}+\xi_{2}^{2}=1$ that $\xi_{1}^{2}$ is constant. Taking account of the coefficient of $\theta_{3}$ in $d \xi_{1}=0$, from (03.2) and (03.3) we have

$$
\begin{equation*}
3 z^{2}-2 z(x+y)+x y+1=0 \tag{03.5}
\end{equation*}
$$

We put $i=1$ and $j=u$ in (2.10), then from (03.1) and (03.4) we have

$$
\begin{equation*}
\frac{2 \xi_{2}^{2}}{y-z}-3 z \xi_{2}^{2}+(y-z)(y z-1)=0 \tag{03.6}
\end{equation*}
$$

Similarly, putting $i=2$ and $j=u$ in (2.10), then we get

$$
\begin{equation*}
\frac{2 \xi_{1}^{2}}{y-z}-3 z \xi_{1}^{2}+(x-z)(x z-1)=0 \tag{03.7}
\end{equation*}
$$

Cancelling $\xi_{1}^{2}$ and $\xi_{2}^{2}$ from (03.6) and (03.7) we have

$$
z-(x+y)+y z(y-z)+x z(x-z)=0
$$

From the above equation and (03.5) we have

$$
\begin{equation*}
3 z=x+y \quad \text { and } \quad x y=3 z^{2}-1 \tag{03.8}
\end{equation*}
$$

Using $(03,8)$ I.-B. Kim, H.S. Kim and R.Takagi([4]) classified all extrinsically homogeneous real hypersurfaces, more precisely,

Theorem C ([4]). If $M$ is an extrinsically homogeneous real hypersurface in $H_{n}(\mathbb{C})$ with case $(1)$, then $M$ is congruent to Be type of first kind.

Case (2): In this case, we shall prove that this case does not occur. Now we have from (2.9) $J_{a b}=J_{r s}=0$. Here we indicate a special index 1(resp. $r^{\prime}$ ) and choose an orthonormal frame $\left\{e_{a}\right\}$ (resp, $\left\{e_{r}\right\}$ ) so that $\xi_{a}=0$ if $a \neq 1$ (resp. $\xi_{r}=0$ if $r \neq r^{\prime}$ ), Then we from (2.2)

$$
\begin{equation*}
J_{r}^{1}=0=J_{r^{\prime}}^{a} \tag{3.1}
\end{equation*}
$$

For indices $u$, we choose an orthonormal frame $\left\{e_{u}\right\}$ so that $J_{u^{\prime}}^{1}=\xi_{r^{\prime}}, J_{u}^{1}=0$ if $u \neq u^{\prime}$. Then, from (2.2) and (3.1)

$$
\begin{equation*}
J_{r^{\prime}}^{u^{\prime}}=\xi_{1}, \quad J_{u^{\prime}}^{a}=J_{u^{\prime}}^{r}=J_{u}^{r^{\prime}}=0 \quad \text { if } u \neq u^{\prime} \quad \text { and } a \neq 1 \tag{3.2}
\end{equation*}
$$

Taking the exterior derivative of $J_{r}^{1}=0$ and $\xi_{a}=0(a \neq 1)$, we have

$$
\begin{gathered}
\sum_{k} \frac{\xi_{r^{\prime}} A_{u^{\prime} r k} \theta^{k}}{y-z}-\sum_{a} J_{a}^{r} \theta_{1}^{a}-\sum_{v \neq u^{\prime}} \sum_{k} \frac{J_{v}^{r}\left(A_{1 v k}+\xi_{1} J_{k}^{v}\right) \theta^{k}}{x-z}-y \xi_{1} \theta^{r}=0 \\
\sum_{k} \frac{\xi_{r^{\prime}}\left(A_{a r^{\prime} k}+\xi_{r^{\prime}} J_{k}^{a}\right) \theta^{k}}{x-y}+\xi_{1} \theta_{a}^{1}+y \sum_{r} J_{r}^{a} \theta^{r}+z \sum_{v} J_{v}^{a} \theta^{v}=0
\end{gathered}
$$

Taking account of the coefficient of $\theta_{b}$ in the equations and using (2.2), (3.1) and (3.2) we have

$$
\begin{equation*}
A_{a r u^{\prime}}=0 . \quad\left(a \neq 1 \text { or } r \neq r^{\prime}\right) \tag{3.3}
\end{equation*}
$$

Now we put $i=u^{\prime}, j=a(a \neq 1)$ in (2.10). Then using (2.8), (3.1), (3.2) and (3.3) we have

$$
\begin{equation*}
y z-1=0 \tag{3.4}
\end{equation*}
$$

Moreover put $i=u^{\prime}, j=r\left(r \neq r^{\prime}\right)$. Then using (2.8), (3.1), (3.2) and (3.3) we have

$$
\begin{equation*}
x z-1=0 . \tag{3.5}
\end{equation*}
$$

From (3.4) and (3.5) we have $z=0$ which contradicts $-1 \neq 0$. Thus we have the following Theorem 1.

Theorem 1. There is no real hypersurface in $H_{n}(\mathbb{C})$ with three distinct principal curvatures such that multiplicities of the principal curvatures with respect to nonzero components of structure vector field are greater than 2.

Case (3): In this case we can choose $\left\{e_{r}\right\}$ so that $\xi_{r}=0$ if $r \neq 2$. Then we have

$$
\begin{equation*}
J_{r}^{1}=0 \tag{3.6}
\end{equation*}
$$

From (2.3) and (3.6) it follows that

$$
m(y)+\sum J_{v}^{u 2}=m(z)
$$

This implies that $m(z) \geq m(y)$. For simplicity we put $m(y)=k$. Now we choose an orthonormal frame $\left\{e_{u}\right\}$ so that

$$
J_{u^{\prime}}^{2}=-\xi_{1}, J_{v}^{2}=0 \quad \text { if } v \neq u^{\prime},
$$

where $u^{\prime}=k+2$. Then from (2.2) and (3.6)

$$
\begin{equation*}
J_{u^{\prime}}^{1}=-\xi_{2}, J_{v}^{u^{\prime}}=0, J_{v}^{1}=0, J_{u^{\prime}}^{r}=0 .\left(r \neq 2, v \neq u^{\prime}\right) \tag{3.7}
\end{equation*}
$$

Taking the exterior derivative of $\xi_{u^{\prime}}=0$, we have

$$
\begin{gather*}
3\left(\frac{y-z}{x-z}\right) \xi_{1}^{2}+3\left(\frac{x-z}{y-z}\right) \xi_{2}^{2}=x(y-z)+y(x-z)-1 .  \tag{3.8}\\
A_{1 r u^{\prime}}=0 \quad \text { if } r \neq 2 . \tag{3.9}
\end{gather*}
$$

Hence it follows from (3.8) and the equation $\xi_{1}^{2}+\xi_{2}^{2}=1$ that

$$
\begin{equation*}
-3 \frac{(x-y)(x+y-2 z)}{(x-z)(y-z)} \xi_{1}^{2}=x(y-z)+y(x-z)-1-3\left(\frac{x-z}{y-z}\right) . \tag{3.10}
\end{equation*}
$$

If $x+y-2 z \neq 0$, then $\xi_{1}$ is constant. Taking account of the coefficient of $\theta^{k+2}$ in $d \xi_{1}=0$, we have

$$
\begin{aligned}
& 3\left(\frac{x-y}{x-z}\right) \xi_{1}^{2}=z(x-y)-x(y-z)+2 \\
& 3\left(\frac{x-y}{y-z}\right) \xi_{2}^{2}=z(x-y)+y(x-z)-2
\end{aligned}
$$

From the equations above, we have

$$
\begin{equation*}
z(x+y-2 z)-(x-z)(y-z)-1=0 . \tag{3.11}
\end{equation*}
$$

If $x+y-2 z=0$ in the equation (3.10), then using $x-z=z-y$ and $y=2 z-x$ we have

$$
(y-z)(x-z)+1=0 .
$$

This implies that the equation (3.11) holds if $x+y-2 z=0$. Put $i=r(r \neq$ $2), j=k+2$ in (2.10), the using (2.8), (3.7) and (3.9) we have

$$
\begin{equation*}
y z-1=0 \tag{3.12}
\end{equation*}
$$

Taking the account of the coefficient of $\theta^{r}$ in $d J_{r}^{2}=0$ and using (2.2), (2.8) and (3.7), we have $y^{2}-y z=2$. From this equation, (3.11) and (3.12) we get

$$
\begin{equation*}
y^{2}=3, y=3 z, \quad \text { and } \quad x=0 \tag{3.13}
\end{equation*}
$$

From this equation we have $y= \pm \sqrt{3}$ and $z= \pm \frac{1}{\sqrt{3}}$. There is no loss of generality such that we may assume that

$$
y=\sqrt{3} \quad \text { and } \quad z=\frac{1}{\sqrt{3}}
$$

Let $E_{i j}$ denote a square matrix with entry 1 where the $i$ th row and the $j$ th column meet. From the above results and (2.2) we can write

$$
\begin{align*}
\xi= & \frac{1}{3} e_{1}+\frac{2 \sqrt{2}}{3} e_{2}, \\
J= & -\frac{2 \sqrt{2}}{3}\left(E_{1, k+2}-E_{k+2,1}\right)+\frac{1}{3}\left(E_{2, k+2}-E_{k+2,2}\right) \\
& -\sum_{\alpha=1}^{k-1}\left(E_{2+\alpha, k+2+\alpha}-E_{k+2+\alpha, 2+\alpha}\right)  \tag{3.14}\\
& -\sum_{p=1}^{n-k-1}\left(E_{2 k+1+2 p-1,2 k+1+2 p}-E_{2 k+1+2 p, 2 k+1+2 p-1}\right) .
\end{align*}
$$

From (2.1), (2.7) and (3.14) we have

$$
\begin{align*}
& \theta_{2}^{1}=-\frac{1}{\sqrt{3}} \theta^{u^{\prime}}, \quad \theta_{2+\alpha}^{1}=-\frac{1}{\sqrt{3}} \theta^{\alpha+u^{\prime}}, \quad \theta_{u^{\prime}}^{1}=\frac{1}{\sqrt{3}}\left(2 \sqrt{2} \theta^{1}-\theta^{2}\right) \\
& \theta_{\alpha+u^{\prime}}^{1}=-\frac{1}{\sqrt{3}} \theta^{2+\alpha}, \quad \theta_{2 k+2 p}^{1}=-z \theta^{2 k+2 p+1}  \tag{3.15}\\
& \theta_{2 k+2 p+1}^{1}=z \theta^{2 k+2 p} \\
& \theta_{2+\alpha}^{2}=\sqrt{\frac{2}{3}} \theta^{\alpha+u^{\prime}}, \quad \theta_{u^{\prime}}^{2}=\frac{1}{\sqrt{3}}\left(-\theta^{1}+\sqrt{2} \theta^{2}\right)
\end{align*}
$$

$$
\begin{aligned}
& \theta_{\alpha+u^{\prime}}^{2}=-2 \sqrt{\frac{2}{3}} \theta^{2+\alpha}, \quad \theta_{2 k+2 p}^{2}=\sqrt{\frac{2}{3}} \theta^{2 k+2 p+1} \\
& \theta_{2 k+2 p+1}^{2}=-\sqrt{\frac{2}{3}} \theta^{2 k+2 p} \\
& \theta_{2+\beta}^{2+\alpha}=\theta_{u^{\prime}+\beta}^{u^{\prime}+\alpha}, \quad \theta_{u^{\prime}+\beta}^{2+\alpha}=\delta_{\alpha \beta} \frac{1}{\sqrt{3}}\left(\theta^{1}-\sqrt{2} \theta^{2}\right) \\
& \theta_{2 k+2 p}^{2+\alpha}=\theta_{2 k+2 p+1}^{2+\alpha}=\theta_{u^{\prime}}^{2+\alpha}=0, \quad \theta_{u^{\prime}+\alpha}^{u^{\prime}}=-\sqrt{\frac{2}{3}} \theta^{u^{\prime}+\alpha} \\
& \theta_{2 k+2 p}^{u^{\prime}}=-\sqrt{\frac{2}{3}} \theta^{2 k+2 p}, \quad \theta_{2 k+2 p+1}^{u^{\prime}}=-\sqrt{\frac{2}{3}} \theta^{2 k+2 p+1} \\
& \theta_{2 k+2 p}^{u^{\prime}+\alpha}=\theta_{2 k+2 p+1}^{u^{\prime}+\alpha}=0
\end{aligned}
$$

where $1 \leq \alpha, \beta \leq k-1$ and $1 \leq p \leq n-k-1$.
For later use we choose a new orthonormal frame field $\hat{e}=\left\{\hat{e}_{1}, \ldots, \hat{e}_{2 n-1}\right\}$ in such a way that

$$
\begin{align*}
& \hat{e}_{1}=\xi=\frac{1}{3} e_{1}+\frac{2 \sqrt{2}}{3} e_{2}, \quad \hat{e}_{2}=-\frac{2 \sqrt{2}}{3} e_{1}+\frac{1}{3} e_{2} \\
& \hat{e}_{2+\alpha}=-e_{2+\alpha}, \quad \hat{e}_{k+1+s}=e_{2 n-s}, \quad(1 \leq s \leq m(z)-k)  \tag{3.16}\\
& \hat{e}_{k+1+m(z)-k+\alpha}=e_{2 k+2-\alpha} \quad(1 \leq \alpha \leq k-1) \quad \hat{e}_{2 n-1}=e_{u^{\prime}}
\end{align*}
$$

Then the transition matrix $F$ from the frame $\hat{e}$ to the frame $e$ is

$$
\begin{equation*}
F=\frac{1}{3}\left(E_{11}+E_{22}\right)+\frac{2 \sqrt{2}}{3}\left(E_{21}-E_{12}\right)-\sum_{r \neq 2} E_{r r}+\sum_{i=1}^{m(z)} E_{k+1+i, 2 n-i} \tag{3.17}
\end{equation*}
$$

Let $\hat{J}$ and $\hat{A}$ denote the almost contact structure and the shape operator of $M$ with respect to the frame $\hat{e}$, respectively. Then from (3.14) and (3.17) we have

$$
\begin{align*}
& \hat{J} \hat{e}_{i}=\hat{e}_{2 n+1-i}, \quad(1 \leq i \leq n) \\
& \begin{aligned}
\hat{A}=\frac{8}{3 \sqrt{3}} E_{11} & +\frac{1}{3 \sqrt{3}} E_{22}+\frac{2 \sqrt{2}}{3 \sqrt{3}}\left(E_{12}+E_{21}\right) \\
& +\sqrt{3} \sum_{r \neq 2} E_{r r}+\frac{1}{\sqrt{3}} \sum_{u} E_{u u}
\end{aligned} \tag{3.18}
\end{align*}
$$

For the corresponding dual 1-form $\hat{\theta}^{i}$ and connection form $\hat{\theta}_{j}^{i}$ to the fame $\hat{e}$,
it follows from (3.15) and (3.16)

$$
\begin{align*}
& \hat{\theta}_{2}^{1}=-\frac{1}{\sqrt{3}} \hat{\theta}^{2 n-1}, \quad \hat{\theta}_{2+\alpha}^{1}=-\frac{1}{\sqrt{3}} \hat{\theta}^{2 n-1-\alpha}, \\
& \hat{\theta}_{k+1+2 p}^{1}=\frac{1}{\sqrt{3}} \hat{\theta}^{k+2 p}, \quad \hat{\theta}_{k+2 p}^{1}=-\frac{1}{\sqrt{3}} \hat{\theta}^{k+2 p+1}, \\
& \hat{\theta}_{2+\alpha}^{2}=-\sqrt{\frac{2}{3}} \theta^{2 n-1-\alpha}, \quad \hat{\theta}_{k+2 p+1}^{2}=\sqrt{\frac{2}{3}} \hat{\theta}^{k+2 p}, \\
& \hat{\theta}_{k+2 p}^{2}=-\sqrt{\frac{2}{3}} \hat{\theta}^{k+2 p+1}, \\
& \hat{\theta}_{2 n-1-k-\alpha}^{1}=\sqrt{3} \hat{\theta}^{u^{\prime}-\alpha}, \quad \hat{\theta}_{2 n-1-k-\alpha}^{2}=0 \\
& \hat{\theta}_{2 n-1}^{1}=\frac{1}{3 \sqrt{3}}\left(2 \sqrt{2} \hat{\theta}^{1}+\hat{\theta}^{2}\right) \quad \hat{\theta}_{2 n-1}^{2}=\frac{1}{3 \sqrt{3}} \hat{\theta}^{1}+\frac{7 \sqrt{2}}{3 \sqrt{3}} \hat{\theta}^{2}  \tag{3.19}\\
& \hat{\theta}_{2+\beta}^{2+\alpha}=\theta_{2+\beta}^{2+\alpha}, \quad \hat{\theta}_{k+1+2 p}^{2+\alpha}=\hat{\theta}_{k+2 p}^{2+\alpha}=\hat{\theta}_{2 n-1}^{2+\alpha}=0, \\
& \hat{\theta}_{2 n-1-k-\alpha}^{2+\alpha}=\delta_{\alpha, k-\beta} \frac{1}{\sqrt{3}}\left(\hat{\theta}^{1}-\sqrt{2} \hat{\theta}^{2}\right) \\
& \hat{\theta}_{k+1+\beta}^{k+1+\alpha}=\hat{\theta}_{2 n-1-k-\beta}^{k+1+2 p}=\hat{\theta}_{2 n-1-k-\beta}^{k+2 p}=0, \\
& \hat{\theta}_{2 n-1}^{k+1+2 p}=\sqrt{\frac{2}{3}} \hat{\theta}^{k+1+2 p} \quad \hat{\theta}_{2 n-1}^{k++2 p}=\sqrt{\frac{2}{3}} \hat{\theta}^{k+2 p} \\
& \hat{\theta}_{2 n-1-k-\beta}^{2 n-1-k-\alpha}=\theta_{2 k+2-\beta}^{2 k+2-\alpha}=\theta_{u^{\prime}-\beta}^{u^{\prime}-\alpha}, \quad \hat{\theta}_{2 n-1}^{2 n-1-k-\alpha}=-\sqrt{\frac{2}{3}} \theta^{2 n-1-k-\alpha}
\end{align*}
$$

and

$$
\begin{align*}
& \hat{\theta}_{2}^{1}=-\frac{1}{\sqrt{3}} \hat{\theta}^{2 n-1}, \quad \hat{\theta}_{2+\alpha}^{1}=-\frac{1}{\sqrt{3}} \hat{\theta}^{2 n-1-\alpha}, \quad \hat{\theta}_{n+\alpha}^{1}=\sqrt{3} \hat{\theta}^{n+1-\alpha} \\
& \hat{\theta}_{2+\alpha}^{2}=-\sqrt{\frac{2}{3}} \hat{\theta}^{2 n-1-\alpha}, \quad \hat{\theta}_{n+\alpha}^{2}=0, \quad \hat{\theta}_{2+\beta}^{2+\alpha}=\theta_{2+\beta}^{2+\alpha} \\
& \hat{\theta}_{n+\beta}^{2+\alpha}=\frac{1}{\sqrt{3}} \delta_{\alpha, k-\beta}\left(\hat{\theta}^{1}+\sqrt{2} \hat{\theta}^{2}\right), \quad \hat{\theta}_{n+\beta}^{n+\alpha}=\hat{\theta}_{n+1-\beta}^{n+1-\alpha}  \tag{3.20}\\
& \hat{\theta}_{2 n-1}^{1}=\frac{1}{3 \sqrt{3}}\left(2 \sqrt{2} \hat{\theta}^{1}+\hat{\theta}^{2}\right) \quad \hat{\theta}_{2 n-1}^{2}=\frac{1}{3 \sqrt{3}} \hat{\theta}^{1}+\frac{7 \sqrt{2}}{3 \sqrt{3}} \hat{\theta}^{2} \\
& \hat{\theta}_{2 n-1}^{2+\alpha}=0, \quad \hat{\theta}_{2 n-1}^{n+\alpha}=\sqrt{\frac{2}{3}} \hat{\theta}^{n+\alpha}, \quad \text { for } 1 \leq \alpha, \beta \leq k-1
\end{align*}
$$

for $m(z)>m(y)$ and $m(z)=m(y)$, respectively.

## 4. Reconstructions of extrinsically homogeneous real hypersurfaces

In this section we shall construct extrinsically homogeneous real hypersurfaces with four distinct principal curvatures and their structure vector fields are not principal. In the following we construct this for $m(y)=m(z)$ and abbreviate the construction for $m(z)>m(y)$ since we have only to apply the same method.

Basically we shall adopt the notations in S. Helgason([3]).
Let $G L(n+1, \mathbb{C})$ be the general linear group of degree $n+1$ over $\mathbb{C}$. For $I=E_{11}-E_{22}-\cdots-E_{n+1, n+1}$, we put

$$
G=\left\{\sigma \in G L(n+1, \mathbb{C}) \mid \sigma^{t} I \bar{\sigma}=I, \operatorname{det} \sigma=1\right\}
$$

and

$$
K=\left\{\left.\left(\begin{array}{cc}
\sigma & 0 \\
0 & \tau
\end{array}\right) \right\rvert\, \sigma \in U(1), \operatorname{det} \sigma \operatorname{det} \tau=1\right\}
$$

Then $K$ is a closed subgroup of $G$, and the homogeneous space $G / K$ is just the hyperbolic complex space form of complex dimension $n$, which is denoted by $H_{n}$. The Riemannian metric and the complex structure on $H_{n}$ will be stated later.

In the following, given a Lie group (e.g. $G$ ), we denote the associated Lie algebra of $G$ by the corresponding German character $\mathfrak{g}$. Conversely, given a subalgebra (e.g. $\mathfrak{l}$ ) of $\mathfrak{g}$, we denote by the corresponding Roman character $L$ the connected Lie subgroup of $G$ whose Lie algebra is $\mathfrak{l}$.

We put

$$
\begin{align*}
& A_{\alpha}=i E_{11}-i E_{\alpha+1, \alpha+1}, \tilde{Y}_{j k}=i E_{j k}+i E_{k j} \\
& Y_{j k}=E_{j k}-E_{k j}, \quad X_{\alpha}=i E_{1, \alpha+1}-i E_{\alpha+1,1}  \tag{4.1}\\
& X_{n+\alpha}=E_{1, n+2-\alpha}+E_{n+2-\alpha, 1}
\end{align*}
$$

where $1 \leq \alpha \leq n$ and $2 \leq j<k \leq n+1$. Then the set $\left\{A_{\alpha}, \tilde{Y}_{j k}, Y_{j k}, X_{\alpha}\right.$, $\left.X_{n+\alpha}\right\}_{1 \leq \alpha \leq n, 2 \leq j<k \leq n+1}$ (resp. the set $\left\{A_{\alpha}, \tilde{Y}_{j k}, Y_{j k}\right\}_{1 \leq \alpha \leq n, 2 \leq j<k \leq n+1}$ ) forms a basis for $\mathfrak{g}$ (resp. $\mathfrak{k}$ ). The bracket product of vectors given in (4.1) can be obtained by

$$
\begin{equation*}
\left[E_{j k}, E_{l m}\right]=\delta_{k l} E_{j m}-\delta_{m j} E_{l k} \tag{4.2}
\end{equation*}
$$

for $1 \leq j, k, l, m \leq n+1$.
We put $\mathfrak{p}=\sum_{\alpha=1}^{n} \mathbb{R} X_{\alpha}+\sum_{\alpha=1}^{n} \mathbb{R} X_{n+\alpha}$. Then we have a Cartan decomposition of $\mathfrak{g}$ :

$$
\mathfrak{g}=\mathfrak{k}+\mathfrak{p}, \quad[\mathfrak{k}, \mathfrak{k}] \subset \mathfrak{k}, \quad[\mathfrak{k}, \mathfrak{p}] \subset \mathfrak{p}, \quad[\mathfrak{p}, \mathfrak{p}] \subset \mathfrak{k} .
$$

We can identify $\mathfrak{p}$ with the tangent space $T_{o}\left(H_{n}\right)$ of $H_{n}$ at the origin $o$. We give on $H_{n}$, regarded as a symmetric space, a Riemannian metric $<,>$ in such a way that

$$
\begin{align*}
& <X_{\alpha}, X_{\beta}>=\delta_{\alpha \beta}, \quad<X_{\alpha}, X_{n+\beta}>=0 \\
& <X_{n+\alpha}, X_{n+\beta}>=\delta_{\alpha \beta} \quad \text { for } \quad 1 \leq \alpha, \beta \leq n \tag{4.3}
\end{align*}
$$

at $o$. Such a $H_{n}$ is the hyperbolic complex space form of constant holomorphic sectional curvature -4 of complex dimension $n$, which is denoted by $H_{n}(\mathbb{C})$. Then $G$ acts on $H_{n}(\mathbb{C})$ as a group of isometries. The complex structure $\hat{J}$ on $H_{n}(\mathbb{C})$ is given by at $o$

$$
\hat{J}\left(X_{\alpha}\right)=X_{2 n+1-\alpha}, \quad \text { for } \quad 1 \leq \alpha \leq n
$$

For any element $Z$ of $\mathfrak{g}$, we denote the $\mathfrak{k}$ (resp. $\mathfrak{p}$ )-component of $Z$ by $Z_{\mathfrak{k}}$ $\left(\right.$ resp. $\left.Z_{\mathfrak{p}}\right)$.

Here we shall construct the Lie algebra $\mathfrak{l}_{n}=\sum_{i=1}^{2 n-1} \mathbb{R} Z_{i}$ such that $Z_{i}$ satisfy and (3.18), (3.19) and $\left(Z_{i}\right)_{\mathfrak{p}}=X_{i}=\hat{e}_{i}$.

Let $\nabla$ be the Riemannian connection of $H_{n}(\mathbb{C})$ with respect to the Riemannian metric $<,>$ given in (4.3). Then it is also known that

$$
\begin{equation*}
\nabla_{\left(Z_{i}\right)_{\mathfrak{p}}} Z_{j}=\left[\left(Z_{i}\right)_{\mathfrak{k}},\left(Z_{j}\right)_{\mathfrak{p}}\right] \tag{4.4}
\end{equation*}
$$

From now on we assume that $m(y)=m(z)$. Let $z=\frac{1}{\sqrt{3}}$, and let $C_{j, k}^{i}(1 \leq$ $i, j, k \leq 2 n-1)$ be scalar functions on $H_{n}(\mathbb{C})$ such that $C_{j, k}^{i}=-C_{i, k}^{j}$. Using
(4.4), (3.18) and (3.20) we can put

$$
\begin{align*}
& Z_{1}=X_{1}+\frac{5}{3} z A_{1}-\frac{2}{3} z A_{2}-\frac{2 \sqrt{2}}{3} z \tilde{Y}_{23}, \\
& Z_{2}=X_{2}-\frac{\sqrt{2}}{3} z A_{1}+\frac{4 \sqrt{2}}{3} z A_{2}-\frac{z}{3} \tilde{Y}_{23}, \\
& Z_{2+\alpha}=X_{2+\alpha}-3 z \tilde{Y}_{2,3+\alpha}+\sum_{1 \leq \mu<\gamma \leq n-2} C_{3+\mu, 3+\gamma}^{2+\alpha} Y_{3+\mu, 3+\gamma},  \tag{4.5}\\
& Z_{n+\alpha}=X_{n+\alpha}-z Y_{2, n+2-\alpha}-\sqrt{2} z Y_{3, n+2-\alpha}, \\
& Z_{2 n-1}=X_{2 n-1}-z Y_{23}+\sum_{1 \leq \mu<\gamma \leq n-2} C_{3+\mu, 3+\gamma}^{2 n-1} Y_{3+\mu, 3+\gamma},
\end{align*}
$$

where $\hat{\theta}_{2+\beta}^{2+\alpha}\left(X_{2+\gamma}\right)=C_{3+\alpha, 3+\beta}^{2+\gamma}, \hat{\theta}_{2+\beta}^{2+\alpha}\left(X_{2 n-1}\right)=C_{3+\alpha, 3+\beta}^{2 n-1}$ and $1 \leq \alpha, \beta, \gamma \leq$ $n-2$.

Then it follows that

$$
\begin{align*}
& {\left[Z_{1}, Z_{2}\right]=0, \quad\left[Z_{1}, Z_{2+\alpha}\right]=2 z Z_{2 n-1-\alpha}, \quad\left[Z_{1}, Z_{n+\alpha}\right]=0,} \\
& {\left[Z_{1}, Z_{2 n-1}\right]=\frac{2 \sqrt{2}}{3} z Z_{1}-\frac{2}{3} z Z_{2}, \quad\left[Z_{2}, Z_{2+\alpha}\right]=-\sqrt{2} z Z_{2 n-1-\alpha},} \\
& {\left[Z_{2}, Z_{n+\alpha}\right]=0, \quad\left[Z_{2}, Z_{2 n-1}\right]=\frac{4}{3} z Z_{1}+\frac{7 \sqrt{2}}{3} Z_{2},} \\
& {\left[Z_{2+\alpha}, Z_{2+\beta}\right]=} \\
& +\sum_{1 \leq \lambda \leq n-2}\left(C_{3+\alpha, 3+\lambda}^{2+\beta}-C_{3+\beta, 3+\lambda}^{2+\alpha}\right) Z_{2+\lambda} \\
& \\
& \sum_{1 \leq \mu<\gamma \leq n-2}\left(\left(d C_{3+\mu, 3+\gamma}^{2+\alpha}\right)\left(X_{2+\beta}\right)\right.  \tag{4.6}\\
& \left.-\left(d C_{3+\mu, 3+\gamma}^{2+\beta}\right)\left(X_{2+\alpha}\right)\right) Y_{3+\mu, 3+\gamma},
\end{aligned} \quad \begin{aligned}
& {\left[Z_{2+\alpha}, Z_{n+\beta}\right]=} \sum_{\gamma=1}^{n-2} C_{3+\gamma, n+2-\beta}^{2+\alpha} Z_{2 n-1-\gamma} \\
&+\left\{\begin{array}{l}
4 z Z_{1}+\sqrt{2} z Z_{2} \\
0 \\
\text { if } \alpha+\beta=n-1 \\
\text { otherwise },
\end{array}\right. \\
& {\left[Z_{2+\alpha}, Z_{2 n-1}\right]=\sum_{1 \leq \lambda \leq n-2} C_{3+\alpha, 3+\lambda i}^{2 n-1} Z_{2+\lambda} } \\
& \quad+\sum_{1 \leq \mu<\gamma \leq n-2}\left(\left(d C_{3+\mu, 3+\gamma}^{2+\alpha}\right)\left(X_{2 n-1}\right)-\left(d C_{3+\mu, 3+\gamma}^{2 n-1}\right)\left(X_{2+\alpha}\right)\right), \\
& {\left[Z_{n+\alpha}, Z_{n+\beta}\right]=0, } \\
& {\left[Z_{n+\alpha}, Z_{2 n-1}\right]=} \sqrt{2} z Z_{n+\alpha}+\sum_{1 \leq \lambda \leq n-2} C_{n+2-\alpha, 3+\lambda}^{2 n-1} Z_{2 n-1-\lambda} .
\end{align*}
$$

For any Greek letters $\mu, \gamma$ and $\lambda$, we see that the coefficients $C_{3+\mu, 3+\gamma}^{2+\lambda}$ and $C_{3+\mu, 3+\gamma}^{2 n-1}$ of $Z_{2+\lambda}$ and $Z_{2 n-1}$ satisfy

$$
\begin{align*}
& \left(d C_{3+\alpha, 3+\beta}^{2+\alpha}\right)\left(X_{2+\beta}\right)-\left(d C_{3+\alpha, 3+\beta}^{2+\beta}\right)\left(X_{2+\alpha}\right)+\left(9 z^{2}-1\right) \\
& =\sum_{\lambda=1}^{n-2}\left(C_{3+\alpha, 3+\lambda}^{2+\alpha} C_{3+\lambda, 3+\beta}^{2+\beta}-C_{3+\alpha, 3+\lambda}^{2+\beta} C_{3+\lambda, 3+\beta}^{2+\alpha}\right) \\
& +\sum_{\lambda=1}^{n-2}\left(C_{3+\beta, 3+\lambda}^{2+\alpha} C_{3+\alpha, 3+\beta}^{2+\lambda}-C_{3+\alpha, 3+\lambda}^{2+\beta} C_{3+\alpha, 3+\beta}^{2+\lambda}\right) \\
& \text { and }  \tag{4.7}\\
& \begin{array}{c}
\left(d C_{3+\alpha, 3+\beta}^{2 n-1}\right)\left(X_{2+\mu}\right)-\left(d C_{3+\alpha, 3+\beta}^{2+\beta}\right)\left(X_{2 n-1}\right) \\
=\sum_{\lambda=1}^{n-2}\left(C_{3+\alpha, 3+\lambda}^{2 n-1} C_{3+\lambda, 3+\beta}^{2+\mu}-C_{3+\alpha, 3+\lambda}^{2+\mu} C_{3+\lambda, 3+\beta}^{2 n-1}\right. \\
\left.\quad-C_{3+\alpha, 3+\beta}^{2+\lambda} C_{3+\lambda, 3+\mu}^{2 n-1}\right)
\end{array}
\end{align*}
$$

respectively.
If we define a subspace $\mathfrak{l}_{n}$ of $\mathfrak{g}$ by

$$
\mathfrak{l}_{n}=\sum_{i=1}^{2 n-1} \mathbb{R} Z_{i}
$$

then we see from (4.6) and (4.7) that $\mathfrak{l}_{n}$ is a Lie subalgebra of $\mathfrak{g}$. For this Lie subalgebra $\mathfrak{l}_{n}$ we know the following:

Proposition 2. If we put $n=3$ in (4.6) then it is easy to see that the above Lie algebra $\mathfrak{l}_{3}$ is solvable. In the case where $n \geq 4$ we see from (4.6) and (4.7) that the Lie algebra $\mathfrak{l}_{n}($ i.e. $n \geq 4)$ is not solvable.

Now, we shall investigate the principal curvatures of each orbit in $H_{n}(\mathbb{C})$ under the Lie subgroup $L_{n}$. We put

$$
\sigma_{t}=\exp t X_{2 n} \quad \text { for } \quad t \in \mathbb{R}
$$

which is a 1-parameter subgroup of $G$.

Since the orbit $L_{n}\left(\sigma_{t}(o)\right)$ is congruent to the orbit $\left(\operatorname{Ad}\left(\sigma_{t}^{-1}\right) L_{n}\right)(o)$ under $A d\left(\sigma_{t}^{-1}\right) L_{n}$ in $H_{n}(\mathbb{C})$, we shall compute the shape operator and the structure vector on the latter. For simplicity, we put

$$
c_{t}=\cosh t \quad \text { and } \quad s_{t}=\sinh t
$$

Then we see that $\sigma_{t}=c_{t} E_{11}+c_{t} E_{22}+s_{t} E_{12}+s_{t} E_{21}+\sum_{k=3}^{n+1} E_{k k}$.
By a simple calculation, it follows from (4.5) that

$$
\begin{align*}
A d\left(\sigma_{t}\right) Z_{1}= & \left(c_{t}^{2}+s_{t}^{2}-\frac{8}{3} c_{t} s_{t} z\right) X_{1}-\frac{2 \sqrt{2}}{3} s_{t} z X_{2} \\
& +\left(\frac{5}{3} c_{t}^{2} z+s_{t}^{2} z-2 c_{t} s_{t}\right) A_{1}-\frac{2}{3} z A_{2}-\frac{2 \sqrt{2}}{3} c_{t} z \tilde{Y}_{23} \\
A d\left(\sigma_{t}\right) Z_{2}= & -\frac{2 \sqrt{2}}{3} c_{t} s_{t} z X_{1}+\left(c_{t}-\frac{s_{t}}{3} z\right) X_{2} \\
& +\left(s-\frac{c_{t}}{3} z\right) \tilde{Y}_{23}+\left(\sqrt{2} s_{t}^{2} z-\frac{\sqrt{2} c_{t}^{2}}{3} z\right) A_{1}+\frac{4 \sqrt{2}}{3} z A_{2} \\
A d\left(\sigma_{t}\right) Z_{2+\alpha} & =\left(c_{t}-3 s_{t} z\right) X_{2+\alpha}+\left(s_{t}-3 c_{t} z\right) \tilde{Y}_{2,3+\alpha}  \tag{4.8}\\
& +\sum_{1 \leq \mu<\gamma \leq n-2} C_{3+\mu, 3+\gamma}^{2+\alpha} Y_{3+\mu, 3+\gamma} \\
A d\left(\sigma_{t}\right) Z_{n+\alpha} & =\left(c_{t}-s_{t} z\right) X_{n+\alpha}+\left(s_{t}-c_{t} z\right) Y_{2, n+2-\alpha}-\sqrt{2} z Y_{3, n+2-\alpha} \\
A d\left(\sigma_{t}\right) Z_{2 n-1} & =\left(c_{t}-s_{t} z\right) X_{2 n-1}+\left(s_{t}-c_{t} z\right) Y_{23} \\
& +\sum_{1 \leq \mu<\gamma \leq n-2} C_{3+\mu, 3+\gamma}^{2 n-1} Y_{3+\mu, 3+\gamma},
\end{align*}
$$

for $1 \leq \alpha, \mu, \gamma \leq n-2$.
The vector $\nu=X_{2 n}$ is the normal vector of the orbit $\left(\operatorname{Ad}\left(\sigma_{t}^{-1}\right) L_{n}\right)(o)$. Then the shape operator $T_{\nu}$ of $\left(\operatorname{Ad}\left(\sigma_{t}^{-1}\right) L_{n}\right)(o)$ in the direction $\nu$ is given by

$$
T_{\nu}\left(\left(Z_{j}\right)_{\mathfrak{p}}\right)=-\left[\left(Z_{j}\right)_{\mathfrak{k}}, \nu\right]_{\left(A d\left(\sigma_{t}^{-1}\right) L_{n}\right)(o)}
$$

for $1 \leq j \leq 2 n-1$ ( see also [9]).

Then it follows from (4.6) that

$$
\begin{gathered}
\left(c_{t}^{2}+s_{t}^{2}-\frac{8}{3} c_{t} s_{t} z\right) T_{\nu}\left(X_{1}\right)-\frac{2 \sqrt{2}}{3} s_{t} z T_{\nu}\left(X_{2}\right) \\
=\left(4 c_{t} s_{t}-\frac{8}{3}\left(c_{t}^{2}+s_{t}^{2}\right) z\right) X_{1}-\frac{2 \sqrt{2}}{3} c_{t} z X_{2}, \\
-\frac{2 \sqrt{2}}{3} c_{t} s_{t} z T_{\nu}\left(X_{1}\right)+\left(c_{t}-\frac{s_{t}}{3} z\right) T_{\nu}\left(X_{2}\right) \\
=-\frac{2 \sqrt{2}}{3} z\left(c_{t}^{2}+s_{t}^{2}\right) X_{1}+\left(s_{t}-\frac{c_{t}}{3} z\right) X_{2}, \\
\left(c_{t}-3 s_{t} z\right) T_{\nu}\left(X_{2+\alpha}\right)=\left(s_{t}-3 c_{t} z\right) X_{2+\alpha} \\
\left(c_{t}-s_{t} z\right) T_{\nu}\left(X_{n+\alpha}\right)=\left(s_{t}-c z\right) X_{n+\alpha}, \\
\left(c_{t}-s_{t} z\right) T_{\nu}\left(X_{2 n-1}\right)=\left(s_{t}-c z\right) X_{2 n-1} .
\end{gathered}
$$

We see that $\tanh t-3 z \neq 0$ because $z^{2}=\frac{1}{3}$. Therefore, from the above equations, the shape operator $T_{\nu}$ is given by

$$
\begin{align*}
& T_{\nu}\left(X_{1}\right)=\frac{12(\tanh t-z)(\tanh t-2 z)}{(\tanh t-3 z)^{3}} X_{1}+\frac{2 \sqrt{2} \operatorname{sech}^{3} t}{(\tanh t-3 z)^{3}} X_{2}, \\
& T_{\nu}\left(X_{2}\right)=\frac{2 \sqrt{2} \operatorname{sech}^{3} t}{(\tanh t-3 z)^{3}} X_{1}-\frac{9 z(\tanh t-z)^{3}}{(\tanh t-3 z)^{3}} X_{2}, \\
& T_{\nu}\left(X_{2+\alpha}\right)=-\frac{z(\tanh t-3 z)}{\tanh t-z} X_{2+\alpha},  \tag{4.9}\\
& T_{\nu}\left(X_{n+\alpha}\right)=-\frac{3 z(\tanh t-z)}{\tanh t-3 z} X_{n+\alpha}, \\
& T_{\nu}\left(X_{2 n-1}\right)=-\frac{3 z(\tanh t-z)}{\tanh t-3 z} X_{2 n-1}, \quad(1 \leq \alpha \leq n-2)
\end{align*}
$$

for any $t \in \mathbb{R} \backslash\{t \mid \tanh t=z\}$.
It is easy to see from (4.9) that the orbit $L_{n}\left(\sigma_{t}(o)\right)$ has four distinct principal curvatures

$$
\begin{gathered}
\frac{-9 z(\tanh t-z) \pm \sqrt{9-6 z \tanh t-5 \tanh ^{2} t}}{2(\tanh t-3 z)} \\
\frac{-z(\tanh t-3 z)}{\tanh t-z}, \frac{-3 z(\tanh t-z)}{\tanh t-3 z}
\end{gathered}
$$

with multiplicities $1,1, n-2, n-1$ respectively, provided that $t \neq 0, \tanh ^{-1} z$. When $t=0$, the orbit $L_{n}\left(\sigma_{0}(o)\right)$ has three distinct principal curvatures

$$
0,-3 z,-z
$$

with multiplicities $1, n-1, n-1$ respectively.
In the case where $m(y)<m(z)$, by a similar computation as in the above, we see that the orbit $L_{n}\left(\sigma_{t}(o)\right)$ has four distinct principal curvatures

$$
\begin{gathered}
\frac{-9 z(\tanh t-z) \pm \sqrt{9-6 z \tanh t-5 \tanh ^{2} t}}{2(\tanh t-3 z)} \\
\frac{-z(\tanh t-3 z)}{\tanh t-z}, \frac{-3 z(\tanh t-z)}{\tanh t-3 z}
\end{gathered}
$$

with multiplicities $1,1, k, 2 n-k-3$ respectively, provided that $t \neq 0, \tanh ^{-1} z$. When $t=0$, the orbit $L_{n}\left(\sigma_{0}(o)\right)$ has three distinct principal curvatures

$$
0,-3 z,-z
$$

with multiplicities $1, k, 2 n-k-2$ respectively.
From (4.9) we see that the structure vector field $X_{1}$ of $L_{n}\left(\sigma_{t}(o)\right)$ is not principal.

Summing up the above results, we have
Theorem 3. There is an extrinsically homogeneous real hypersurface $M$ such that $M$ has four distinct principal curvatures

$$
\begin{gathered}
\frac{-9 z(\tanh t-z) \pm \sqrt{9-6 z \tanh t-5 \tanh ^{2} t}}{2(\tanh t-3 z)} \\
\frac{-z(\tanh t-3 z)}{\tanh t-z}, \frac{-3 z(\tanh t-z)}{\tanh t-3 z}
\end{gathered}
$$

with multiplicities $1,1, k,(\geq 2) 2 n-k-3$ and the structure vector field on $M$ is not principal.

Moreover if $M$ is an extrinsically homogeneous real hypersurface with case (3), then $M$ must obtain the connection forms satisfying (3.15). Therefore if such $M$ is existed, then $M$ is congruent to one of new model spaces $B e$ type type of second kind. From Theorem C, Theorem 1 and the above results, we have

Theorem 4. Let $M$ be an extrinsically homogeneous real hypersurface of 3-type whose structure vector field is not principal. Then $M$ is holomorphic congruent to an open part of one of the new model spaces Be type of first kind and Be type of second kind.

## References

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