# THE NUMBER OF THE CRITICAL POINTS OF THE STRONGLY INDEFINITE FUNCTIONAL WITH ONE PAIR OF THE TORUS-SPHERE VARIATIONAL LINKING SUBLEVELS 

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#### Abstract

Let $I \in C^{1,1}$ be a strongly indefinite functional defined on a Hilbert space $H$. We investigate the number of the critical points of $I$ when $I$ satisfies one pair of Torus-Sphere variational linking inequality. We show that $I$ has at least two critical points when $I$ satisfies one pair of Torus-Sphere variational linking inequality with $(P . S .)_{c}^{*}$ condition. We prove this result by use of the limit relative category and critical point theory on the manifold with boundary.


## 1. Introduction and statement of the main result

Let $I \in C^{1,1}$ be a strongly indefinite functional defined on a Hilbert Space $H$. In this paper, we investigate the number of the critical points of $I$ when $I$ satisfies one pair of Torus-Sphere variational linking inequalities and (P.S. $)_{c}^{*}$ condition. We show that $I$ has at least two critical points when $I$ has the sublevel set satisfying one pair of Torus-Sphere variational linking inequalities and satisfying the (P.S. $)_{c}^{*}$ condition. We prove this result by use of the limit relative category and critical point theory on the manifold with boundary. In the case that $I$ is not strongly indefinite functional, Marino, A., Micheletti, A.M., Pistoia, Schechter, M., Tintarev. K., and Rabinowitz, P., proved in Theorem (3.4) of [4], [7] and $[8]$ a theorem of existence of two solutions when $I$ satisfies one pair of Sphere-Torus variational linking inequality by the mountain pass theorem and degree theory. Marino, A., Micheletti, A. M. and Pistoia, A.

[^0]proved in Theorem (8.4) of [5] a theorem of existence of three solutions when $I$ satisfies two pairs of Sphere-Torus variational linking inequalities and $(P . S .)_{c}$ condition by the mountain pass theorem and degree theory. In this paper we obtain the following results for the strongly indefinite functional case:

Theorem 1.1. (One pair of Torus-Sphere variational link) Let $H$ be a Hilbert space with a norm $\|\cdot\|$, which is topological direct sum of the three subspaces $X_{0}, X_{1}$ and $X_{2}$. Let $I \in C^{1,1}(H, R)$ be a strongly indefinite functional. Assume that
(1) $\operatorname{dim} X_{1}<+\infty$;
(2) There exist a small number $\rho>0, r>0$ and $R>0$ such that $r<R$ and

$$
\sup _{\Sigma_{R}\left(S_{1}(\rho), X_{0}\right)} I<\inf _{S_{r}\left(X_{1} \oplus X_{2}\right)} I,
$$

where

$$
\begin{gathered}
S_{1}(\rho)=\left\{u \in X_{1} \mid\|u\|=\rho\right\}, \\
S_{r}\left(X_{1} \oplus X_{2}\right)=\left\{u \in X_{1} \oplus X_{2} \mid\|u\|=r\right\}, \\
B_{r}\left(X_{1} \oplus X_{2}\right)=\left\{u \in X_{1} \oplus X_{2} \mid\|u\| \leq r\right\},
\end{gathered}
$$

$$
\Sigma_{R}\left(S_{1}(\rho), X_{0}\right) \quad=\left\{u=u_{1}+u_{2} \mid u_{1} \in S_{1}(\rho), u_{2} \in X_{0},\left\|u_{1}\right\|=\rho,\right.
$$

$$
\left.1 \leq\left\|u_{1}+u_{2}\right\|=R\right\} \cup\left\{u=u_{1}+u_{2} \mid u_{1} \in S_{1}(\rho),\right.
$$

$$
\left.\left\|u_{1}\right\|=\rho, 1 \leq\left\|u_{2}\right\| \leq R\right\}
$$

$\Delta_{R}\left(S_{1}(\rho), X_{0}\right)$

$$
\begin{aligned}
= & \left\{u=u_{1}+u_{2} \mid u_{1} \in S_{1}(\rho), u_{2} \in X_{0},\left\|u_{1}\right\|=\rho,\right. \\
& \left.1 \leq\left\|u_{1}+u_{2}\right\| \leq R\right\}
\end{aligned}
$$

(3) $\beta=\sup _{\Delta_{R}\left(S_{1}(\rho), X_{0}\right)} I<+\infty$;
(4) $(P . S .)_{c}^{*}$ condition holds for any $c \in[\alpha, \beta]$ where

$$
\alpha=\inf _{S_{r}\left(X_{1} \oplus X_{2}\right)} I ;
$$

(5) There exists one critical point $e$ in $X_{0} \oplus X_{2}$ with $I(e)<\alpha$.

Then there exist at least two distinct critical points except $e$, $u_{i}$, $i=1,2$, in $X_{1}$, of $I$ with

$$
\inf _{S_{r}\left(X_{1} \oplus X_{2}\right)} I \leq I\left(u_{i}\right) \leq \sup _{\Delta_{R}\left(S_{1}(\rho), X_{0}\right)} I .
$$

For the proof of the main result we use the critical point theory on the manifold with boundary. Since the functional $I$ is strongly indefinite functional, it is convenient to use the notion of the limit relative category instead of the relative category and the (P.S. $)_{c}^{*}$ condition which is a version of the Palais-Smale condition. We restrict the functional $I$ to the manifold $C$ with boundary, where $C$ is introduced in section 3. We study the geometry and topology of the sub-levels of $I$ and $\tilde{I}$ and investigate the limit relative category of the sub-level sets of $\tilde{I}$ and $(P . S .)_{c}^{*}$ condition in $C$. By the facts that the number of the limit relative category cat $_{\left(C, \Sigma_{R}\right)}^{*}\left(\tilde{\Delta_{R}}\right)$ is equal to 2 and the critical point theory on the manifold with boundary, we obtain at least two distinct critical points of $\tilde{I}$, so we obtain at least two distinct critical points of $I$.

## 2. Critical Point Theory on the manifold with boundary

Now, we consider the critical point theory on the manifold with boundary. Let $H$ be a Hilbert space and $M$ be the closure of an open subset of $H$ such that $M$ can be endowed with the structure of $C^{2}$ manifold with boundary. Let $f: W \rightarrow R$ be a $C^{1,1}$ functional, where $W$ is an open set containing $M$. For applying the usual topological methods of critical points theory we need a suitable notion of critical point for $f$ on $M$. Since the functional $I(u)$ is strongly indefinite, the notion of the $(P . S .)_{c}^{*}$ condition and the limit relative category (see [2]) is a useful tool for the proof of the main theorem.

Definition 2.1. If $u \in M$, the lower gradient of $f$ on $M$ at $u$ is defined by
$\operatorname{grad}_{M}^{-} f(u)= \begin{cases}\nabla f(u) & \text { if } u \in \operatorname{int}(M), \\ \nabla f(u)+[<\nabla f(u), \nu(u)>]^{-} \nu(u) & \text { if } u \in \partial M,\end{cases}$
where we denote by $\nu(u)$ the unit normal vector to $\partial M$ at the point $u$, pointing outwards. We say that $u$ is a lower critical for $f$ on $M$, if $\operatorname{grad}_{M}^{-} f(u)=0$.

Let $\left(H_{n}\right)_{n}$ be a sequence of closed finite dimensional subspace of $H$ with $\operatorname{dim} H_{n}<+\infty, H_{n} \subset H_{n+1}, \cup_{n \in N} H_{n}$ is dense in $H$.

Let $M_{n}=M \cap H_{n}$, for any $n$, be the closure of an open subset of $H_{n}$ and has the structure of a $C^{2}$ manifold with boundary in $H_{n}$. We
assume that for any $n$ there exists a retraction $r_{n}: M \rightarrow M_{n}$. For given $B \subset H$, we will write $B_{n}=B \cap H_{n}$.

Definition 2.2. Let $c \in R$. We say that $f$ satisfies the (P.S. $)_{c}^{*}$ condition with respect to $\left(M_{n}\right)_{n}$, on the manifold with boundary $M$, if for any sequence $\left(k_{n}\right)_{n}$ in $N$ and any sequence $\left(u_{n}\right)_{n}$ in $M$ such that $k_{n} \rightarrow \infty, u_{n} \in M_{k_{n}}, \forall n, f\left(u_{n}\right) \rightarrow c, \operatorname{grad}_{M_{k_{n}}}^{-} f\left(u_{n}\right) \rightarrow 0$, there exists a subsequence of $\left(u_{n}\right)_{n}$ which converges to a point $u \in M$ such that $\operatorname{grad}_{M}^{-} f(u)=0$.

Let $Y$ be a closed subspace of $M$.
Definition 2.3. Let $B$ be a closed subset of $M$ with $Y \subset B$. We define the relative category $\operatorname{cat}_{M, Y}(B)$ of $B$ in $(M, Y)$, as the least integer $h$ such that there exist $h+1$ closed subsets $U_{0}, U_{1}, \ldots, U_{h}$ with the following properties:
$B \subset U_{0} \cup U_{1} \cup \ldots \cup U_{h} ;$
$U_{1}, \ldots, U_{h}$ are contractible in $M$;
$Y \subset U_{0}$ and there exists a continuous map $F: U_{0} \times[0,1] \rightarrow M$ such that

$$
\begin{array}{rll}
F(x, 0) & =x & \forall x \in U_{0}, \\
F(x, t) \in Y & \forall x \in Y, \forall t \in[0,1], \\
F(x, 1) \in Y & \forall x \in U_{0} .
\end{array}
$$

If such an $h$ does not exist, we say that $\operatorname{cat}_{M, Y}(B)=+\infty$.
Definition 2.4. Let $(X, Y)$ be a topological pair and $\left(X_{n}\right)_{n}$ be a sequence of subsets of $X$. For any subset $B$ of $X$ we define the limit relative category of $B$ in $(X, Y)$, with respect to $\left(X_{n}\right)_{n}$, by

$$
\operatorname{cat}_{(X, Y)}^{*}(B)=\lim \sup _{n \rightarrow \infty} \operatorname{cat}_{\left(X_{n}, Y_{n}\right)}\left(B_{n}\right) .
$$

Let $Y$ be a fixed subset of $M$. We set

$$
\begin{gathered}
\mathcal{B}_{\mathrm{i}}=\left\{\mathrm{B} \subset \mathrm{M} \mid \operatorname{cat}_{(\mathrm{M}, \mathrm{Y})}^{*}(\mathrm{~B}) \geq \mathrm{i}\right\}, \\
c_{i}=\inf _{B \in \mathcal{B}_{\mathrm{i}}} \sup _{x \in B} f(x) .
\end{gathered}
$$

We have the following multiplicity theorem, which was proved in [6].
Theorem 2.1. Let $i \in N$ and assume that
(1) $c_{i}<+\infty$,
(2) $\sup _{x \in Y} f(x)<c_{i}$,
(3) the (P.S. $)_{c_{i}}^{*}$ condition with respect to $\left(M_{n}\right)_{n}$ holds.

Then there exists a lower critical point $x$ such that $f(x)=c_{i}$. If

$$
c_{i}=c_{i+1}=\ldots=c_{i+k-1}=c
$$

then

$$
\operatorname{cat}_{M}\left(\left\{x \in M \mid f(x)=c, \operatorname{grad}_{M}^{-} f(x)=0\right\}\right) \geq k .
$$

## 3. Proof of Theorem 1.1

Let $H$ be a Hilbert space with a norm $\|\cdot\|$ and $H=X_{0} \oplus X_{1} \oplus X_{2}$ with $\operatorname{dim} X_{1}<\infty$. Let $I \in C^{1,1}(H, R)$ be a strongly indefinite functional. Let $\left(H_{n}\right)_{n}$ be a sequence of closed subspaces of $H$ with finite dimension and such that for all $n$,

$$
X_{1} \subset H_{n}, \quad P_{X_{i}} \cdot P_{H_{n}}=P_{H_{n}} \cdot P_{X_{i}}\left(=P_{X_{i} \cap H_{n}}\right), \quad i=0,1,2,
$$

where, for all given subspace $X$ of $H, P_{X}$ is the orthogonal projection from $H$ onto $X$. Set

$$
C=\left\{u \in H \mid\left\|P_{X_{1}} u\right\| \geq 1\right\}
$$

Then $C$ is the smooth manifold with boundary. Let $C_{n}=C \cap H_{n}$. Let us define a functional $\psi: H \backslash\left(X_{0} \oplus X_{2}\right) \longrightarrow H$ by

$$
\begin{equation*}
\psi(u)=u-\frac{P_{X_{1}} u}{\left\|P_{X_{1}} u\right\|}=P_{X_{0} \oplus X_{2}} u+\left(1-\frac{1}{\left\|P_{X_{1}} u\right\|}\right) P_{X_{1}} u . \tag{3.1}
\end{equation*}
$$

We have

$$
\begin{equation*}
\psi^{\prime}(u)(v)=v-\frac{1}{\left\|P_{X_{1}} u\right\|}\left(P_{X_{1}} v-\left\langle\frac{P_{X_{1}} u}{\left\|P_{X_{1}} u\right\|}, v\right\rangle \frac{P_{X_{1}} u}{\left\|P_{X_{1}} u\right\|}\right) . \tag{3.2}
\end{equation*}
$$

Let us introduce the constrained functional $\tilde{I}: C \rightarrow H$ by

$$
\tilde{I}=I \cdot \psi
$$

Then $\tilde{I} \in C_{l o c}^{1,1}$. We note that if $\tilde{u}$ is the critical point of $\tilde{I}$ and lies in the interior of $C$, then $u=\psi(\tilde{u})$ is the critical point of $I$. We also note that

$$
\begin{equation*}
\left\|\operatorname{grad}_{C}^{-} \tilde{I}(\tilde{u})\right\| \geq\left\|P_{X_{0} \oplus X_{2}} \nabla I(\psi(\tilde{u}))\right\|, \quad \forall \tilde{u} \in \partial C . \tag{3.3}
\end{equation*}
$$

Let us set

$$
\begin{aligned}
\tilde{S_{r}} & =\psi^{-1}\left(S_{r}\left(X_{1} \oplus X_{2}\right)\right), \\
\tilde{\Sigma_{R}} & =\psi^{-1}\left(\Sigma_{R}\left(S_{1}(\rho), X_{0}\right),\right. \\
\tilde{\Delta_{R}} & =\psi^{-1}\left(\Delta_{R}\left(S_{1}(\rho), X_{0}\right) .\right.
\end{aligned}
$$

Then $\tilde{S}_{r}, \tilde{\Sigma_{R}}$ and $\tilde{\Delta_{R}}$ has the same topological structure as that of $S_{r}$, $\Sigma_{R}$ and $\Delta_{R}$.

From condition (2), we have

$$
\begin{equation*}
\sup _{\widetilde{\Sigma_{R}}} \tilde{I}=\sup _{\Sigma_{R}\left(S_{1}(\rho), X_{0}\right)} I<\inf _{S_{r}\left(X_{1} \oplus X_{2}\right)} I=\inf _{\tilde{S_{r}}} \tilde{I} . \tag{3.4}
\end{equation*}
$$

From the condition (4), $\tilde{I}$ satisfies the (P.S. $)_{c}^{*}$ condition on $C$ with respect to $\left(C_{n}\right)\left(C_{n}=C \cap H_{n}\right)$ for any $c$ such that

$$
\begin{equation*}
\inf _{\tilde{S}_{r}} \tilde{I}=\inf _{S_{r}\left(X_{1} \oplus X_{2}\right)} I \leq c \leq \sup _{\Delta_{R}\left(S_{1}(\rho), X_{0}\right)} I=\sup _{\Delta_{R}} \tilde{I} . \tag{3.5}
\end{equation*}
$$

Next, we claim that $\operatorname{cat}_{\left(C, \tilde{\left.\Sigma_{R}\right)}\right.}^{*}\left(\tilde{\Delta_{R}}\right)=2$. Let us set

$$
\begin{gathered}
\Sigma_{n}=\Sigma_{R}\left(S_{1}(\rho), X_{0}\right) \cap H_{n}, \quad \Delta_{n}=\Delta_{R}\left(S_{1}(\rho), X_{0}\right) \cap H_{n}, \\
\tilde{\Sigma_{n}}=\tilde{\Sigma_{R}} \cap H_{n} \quad \text { and } \quad \tilde{\Delta_{n}}=\tilde{\Delta_{R}} \cap H_{n} .
\end{gathered}
$$

We consider a continuous deformation $r: \tilde{S}_{r} \backslash X_{2} \times[0,1] \rightarrow \tilde{S}_{r} \backslash X_{2}$ such that

$$
\begin{aligned}
& \cdot r(x, 0)=x, \quad \forall x \in \tilde{S}_{r} \backslash X_{2}, \\
& \cdot r(x, t)=x, \quad \forall x \in \tilde{S}_{r} \cap X_{1} \quad \forall t \in[0,1], \\
& \cdot r(x, 1) \in \tilde{S}_{r} \cap X_{1} \quad \forall x \in \tilde{S}_{r} \backslash X_{2} .
\end{aligned}
$$

Now we can define, if $x=x_{0}+x_{1}+x_{2}, x_{i} \in X_{i}, i=0,1,2, t \in[0,1]$,

$$
r_{1}(x, t)=x_{0}+\left\|x_{1}+x_{2}\right\| r\left(\frac{x_{1}+x_{2}}{\left\|x_{1}+x_{2}\right\|}, t\right) .
$$

Using $r_{1}$ we construct, for all $n$, a continuous deformation $\eta_{n}: C_{n} \times$ $[0,1] \rightarrow C_{n}$ such that

- $\eta_{n}(x, 0)=x \quad \forall x \in C_{n}$,
- $\eta_{n}(x, t)=x \quad \forall x \in \tilde{\Delta_{n}}, \quad \forall t \in[0,1]$,
- $\eta_{n}(x, 1) \in \tilde{\Delta}_{n} \quad \forall x \in C_{n}$.
- $\eta_{n}(x, t) \in C_{n} \backslash \tilde{S}_{r}, \quad \forall x \in C_{n} \backslash \tilde{S}_{r}, \quad \forall t \in[0,1]$.

The existence of $\eta_{n}$ implies that $\operatorname{cat}_{\left(C_{n}, \tilde{\Sigma_{n}}\right)}\left(\tilde{\Delta_{n}}\right)=\operatorname{cat}_{\left(\tilde{\Delta_{n}}, \tilde{\Sigma_{n}}\right)}\left(\tilde{\Delta_{n}}\right)$; moreover the pair $\left(\tilde{\Delta_{n}}, \tilde{\Sigma_{n}}\right)$ is homeomorphic to the pair $\left(\Delta_{n}, \Sigma_{n}\right)$ and $\left(\Delta_{n}, \Sigma_{n}\right)$ is homeomorphic to the pair $\left(\mathcal{B}^{p+1} \times \mathcal{S}^{q-1}, \mathcal{S}^{p} \times \mathcal{S}^{q-1}\right)$, so $\left(\tilde{\Delta_{n}}, \tilde{\Sigma_{n}}\right)$ is homeomorphic to the pair $\left(\mathcal{B}^{p+1} \times \mathcal{S}^{q-1}, \mathcal{S}^{p} \times \mathcal{S}^{q-1}\right)$, where $p=\operatorname{dim}\left(X_{0}\right) \cap$
$H_{n}, q=\operatorname{dim}\left(X_{1}\right) \cap H_{n}$ and we are denoting by $\mathcal{B}^{r}$ and $\mathcal{S}^{r}$ the $r$ dimensional ball and the $r$-dimensional sphere, respectively. This implies that $\operatorname{cat}_{\left(C_{n}, \tilde{\Sigma_{n}}\right)}\left(\tilde{\Delta_{n}}\right)=2$ (in the case $q=1$ a connection argument can be used, otherwise this is a consequence of the fact that cuplength $\left(\mathcal{B}^{p+1} \times \mathcal{S}^{q-1}, \mathcal{S}^{p} \times \mathcal{S}^{q-1}\right)=1$ and (b) of (3.7) in [7]). Thus $\operatorname{cat}_{\left(C_{n}, \tilde{\left.\Sigma_{n}\right)}\right.}\left(\tilde{\Delta_{n}}\right)=2$, so we have $\operatorname{cat}_{\left(C, \tilde{\left.\Sigma_{R}\right)}\right.}^{*}\left(\tilde{\Delta_{R}}\right)=2$. Thus we prove the claim. Let us set
$\mathcal{A}_{1}=\left\{A \subset C \mid \operatorname{cat}_{\left(C, \tilde{\Sigma_{R}}\right)}^{*}(A) \geq 1\right\}, \quad \mathcal{A}_{2}=\left\{A \subset C \mid \operatorname{cat}_{\left(C, \tilde{\left.\Sigma_{R}\right)}\right.}^{*}(A) \geq 2\right\}$.
Since $\operatorname{cat}_{\left(C, \tilde{\Sigma_{R}}\right)}^{*}\left(\tilde{\Delta_{R}}\right)=2, \tilde{\Delta_{R}} \in \mathcal{A}_{1}$ and $\tilde{\Delta_{R}} \in \mathcal{A}_{2}$. Let us set

$$
\tilde{c_{1}}=\inf _{A \in \mathcal{A}_{1}} \sup _{\tilde{u} \in A} \tilde{I}(\tilde{u}) \quad \text { and } \quad \tilde{c_{2}}=\inf _{A \in \mathcal{A}_{2}} \sup _{\tilde{u} \in A} \tilde{I}(\tilde{u}) .
$$

From the condition (3) and $\widetilde{\Delta_{R}} \in \mathcal{A}_{i}, i=1,2$, it follows that

$$
\tilde{c}_{i}=\inf _{A \in \mathcal{A}_{i}} \sup _{\tilde{u} \in A} \tilde{I}(\tilde{u}) \leq \sup _{\tilde{u} \in \Delta_{R}} \tilde{I}(\tilde{u})=\sup _{u \in \Delta_{R}\left(S_{1}(\rho), X_{0}\right)} I(u)<\infty, i=1,2 .
$$

It is easily checked that for $\tilde{\Sigma_{R}} \subset A \in \mathcal{A}_{i}, i=1,2$,

$$
\sup _{\tilde{u} \in \tilde{\Sigma}_{R}} \tilde{I}(\tilde{u}) \leq \sup _{\tilde{u} \in A} \tilde{I}(\tilde{u})
$$

and hence $\sup _{\tilde{u} \in \tilde{\Sigma}_{R}} \tilde{I}(\tilde{u}) \leq \inf _{A \in \mathcal{A}_{i}} \sup _{\tilde{u} \in A} \tilde{I}(\tilde{u})=\tilde{c}_{i}$. From the condition (4), $\tilde{I}$ satisfies the (P.S. $)_{c}^{*}$ condition on $C$ with respect to $\left(C_{n}\right)$ for any $c$ with (3.5). Thus, by Theorem 2.1, there exist two critical points $\tilde{u_{1}}, \tilde{u_{2}}$ such that

$$
\tilde{I}\left(\tilde{u_{1}}\right)=\tilde{c_{1}} \quad \text { and } \quad \tilde{I}\left(\tilde{u_{2}}\right)=\tilde{c_{2}} .
$$

We claim that

$$
\inf _{\tilde{u} \in \tilde{S}_{r}} \tilde{I}(\tilde{u}) \leq \tilde{c_{1}} \leq \tilde{c_{2}} \leq \sup _{\tilde{u} \in \tilde{\Delta_{R}}} \tilde{I}(\tilde{u})
$$

In fact, since cat ${ }_{\left(C, \tilde{\Sigma_{R}}\right)}^{*}\left(\tilde{\Delta_{R}}\right)=2, \tilde{\Delta_{R}} \in \mathcal{A}_{2}$ and hence

$$
\tilde{c_{2}}=\inf _{A \in \mathcal{A}_{2}} \sup _{\tilde{u} \in A} \tilde{I}(\tilde{u}) \leq \sup _{\tilde{u} \in \Delta_{R}} \tilde{I}(\tilde{u}), \forall A \in \mathcal{A}_{2} .
$$

For the proof of $\tilde{c_{1}} \geq \inf _{\tilde{u} \in \tilde{S}_{r}} \tilde{I}(\tilde{u})$, we construct a deformation $\eta_{n}^{\prime}: C_{n} \backslash \tilde{S}_{r} \times$ $[0,1] \rightarrow C_{n} \backslash \tilde{S}_{r}$ such that

- $\eta_{n}^{\prime}(x, 0)=x \forall x \in C_{n} \backslash \tilde{S}_{r}$,
- $\eta_{n}^{\prime}(x, t)=x \forall x \in \tilde{\Sigma_{n}} \forall t \in[0,1]$,
- $\eta_{n}^{\prime}(x, 1) \in \tilde{\Sigma_{n}} \forall x \in C_{n}$.

Actually $\eta_{n}^{\prime}$ can be defined taking the restriction of $\eta_{n}$ on $C_{n} \backslash \tilde{S}_{r}$ followed by a retraction of $\tilde{\Delta_{n}} \backslash \tilde{S}_{r}$ to $\tilde{\Sigma_{n}}$. The existence of $\eta_{n}^{\prime}$, for all $n$, implies that any $A \in \mathcal{A}_{1}$ must intersect $\tilde{S}_{r}$, so $\sup \tilde{I}(A) \geq \inf _{\tilde{u} \in \tilde{S}_{r}} \tilde{I}(\tilde{u}), \forall A \in \mathcal{A}_{1}$. So we have that $\tilde{c_{1}}=\inf _{A \in \mathcal{A}_{1}} \sup _{\tilde{u} \in A} \tilde{I}(\tilde{u}) \geq \inf _{\tilde{u} \in \tilde{S}_{r}} \tilde{I}(\tilde{u})$. Thus we prove the claim. Setting $u_{i}=\psi\left(\tilde{u}_{i}\right), i=1,2$, we have

$$
\begin{aligned}
\inf _{u \in S_{r}\left(X_{1} \oplus X_{2}\right)} I(u) & =\inf _{\tilde{u} \in \tilde{S}_{r}} \tilde{I}(\tilde{u}) \leq \tilde{I}\left(\tilde{u}_{1}\right)=I\left(u_{1}\right) \leq \tilde{I}\left(\tilde{u_{2}}\right)=I\left(u_{2}\right) \\
& \leq \sup _{\tilde{u} \in \Delta_{R}} \tilde{I}(\tilde{u})=\sup _{u \in \Delta_{R}\left(S_{1}(\rho), X_{0}\right)} I(u) .
\end{aligned}
$$

Next, we claim that $\tilde{u}_{i} \notin \partial C$, that is $u_{i} \notin X_{0} \oplus X_{2}$, which implies that $u_{i}$ are critical points of $I$ in $X_{1}$. For this we assume by contradiction that $u_{i} \in X_{0} \oplus X_{2}$. From (3.3), $\left\|\operatorname{grad}_{C}^{-} \tilde{I}(\tilde{u})\right\| \geq\left\|P_{X_{0} \oplus X_{2}} \nabla I(\psi(\tilde{u}))\right\|$, $\forall \tilde{u} \in \partial C$ and $P_{X_{0} \oplus X_{2}} \nabla I\left(u_{i}\right)=0$, namely $u_{i}, i=1,2$, are critical points for $\left.I\right|_{X_{0} \oplus X_{2}}$. Just notice that, for fixed $w_{0} \in X_{0}$ the functional $w_{2} \mapsto$ $I\left(w_{0}+w_{2}\right)$ is weakly convex in $X_{2}$, while, for fixed $w_{2} \in X_{2}$ the functional $w_{0} \mapsto I\left(w_{0}+w_{2}\right)$ is strictly concave in $X_{0}$. Moreover $e$ is the critical point in $X_{0} \oplus X_{2}$ with $I(e)<\alpha=\inf _{S_{r}\left(X_{1} \oplus X_{2}\right)} I$. If $u_{1}=w_{0}+w_{2}$ is another critical point, we have

$$
I(e) \leq I\left(w_{2}\right) \leq I\left(w_{0}+w_{2}\right)=I\left(u_{1}\right) \leq I\left(w_{0}\right) \leq I(e),
$$

so we have $I\left(u_{1}\right)=I(e)$. Similary we have $I\left(u_{2}\right)=I(e)$, so we have $I\left(u_{1}\right)=I\left(u_{2}\right)=I(e)<\alpha$, which is absurd for the fact that $\alpha=$ $\inf _{u \in S_{r}\left(X_{1} \oplus X_{2}\right)} I(u) \leq I\left(u_{1}\right) \leq I\left(u_{2}\right) \leq \sup _{u \in \Delta_{R}\left(S_{1}(\rho), X_{0}\right)} I(u)=\beta$. Thus $u_{i} \notin X_{0} \oplus X_{2}, i=1,2$. Moreover it is easily checked that there is no critical point $u \in X_{0} \oplus X_{2}$ such that $I(u) \in[\alpha, \beta]$. Hence $u_{i}, i=1,2$, are critical points of $I$, in $X_{1}$. Thus we prove the theorem.

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