ON N(k)-QUASI EINSTEIN MANIFOLDS

MUKUT MANI TRIPATHI AND JEONG-SIK KIM

ABSTRACT. N(k)-quasi Einstein manifolds are introduced and studied.

1. Introduction

A non-flat Riemannian manifold (M^n, g) is said to be a *quasi Einstein manifold* [2] if its Ricci tensor S satisfies

$$(1.1) S(X,Y) = ag(X,Y) + b\eta(X)\eta(Y), X,Y \in TM$$

or equivalently, its Ricci operator Q satisfies

$$(1.2) Q = aI + b\eta \otimes \xi$$

for some smooth functions a and $b \neq 0$, where η is a nonzero 1-form such that

$$(1.3) g(X,\xi) = \eta(X), g(\xi,\xi) = \eta(\xi) = 1$$

for the associated vector field ξ . The 1-form η is called the associated 1-form and the unit vector field ξ is called the generator of the manifold. In an n-dimensional quasi Einstein manifold the Ricci tensor has precisely two distinct eigenvalues a and a+b, where a is of multiplicity (n-1) and a+b is simple [2]. A proper η -Einstein contact metric manifold ([1], [5]) is a natural example of a quasi Einstein manifold.

In this paper, we introduce the concept of N(k)-quasi Einstein manifolds. In section 2, it is proved that conformally flat quasi Einstein manifolds are certain N(k)-quasi Einstein manifolds. Semi-symmetric N(k)-quasi Einstein manifolds are studied in section 3. A necessary and a sufficient condition for an N(k)-quasi Einstein manifold to satisfy $R(\xi,X)\cdot S=0$ are obtained in section 4. In section 5, Ricci-recurrent quasi Einstein manifolds are studied. In the last section, it is proved that a quasi-umbilical hypersurface of an $N(\bar{k})$ -quasi Einstein manifold, such that it is normal to the generator of the ambient manifold, is an N(k)-quasi Einstein manifold.

Received March 9, 2007.

²⁰⁰⁰ Mathematics Subject Classification. 53C25.

Key words and phrases. conformal curvature tensor, k-nullity distribution, N(k)-quasi Einstein manifold, quasi-umbilical hypersurface, Ricci operator, Ricci-recurrent manifold, Ricci tensor, semi-symmetric space.

2. N(k)-quasi Einstein manifolds

The k-nullity distribution N(k) [7] of a Riemannian manifold M is defined by

$$N(k): p \to N_p(k) = \{Z \in T_pM \mid R(X,Y)Z = k(g(Y,Z)X - g(X,Z)Y)\}$$
 for all $X, Y \in TM$, where k is some smooth function.

Motivated by the above definition, we give the following definition.

Definition 2.1. Let (M^n, g) be a quasi Einstein manifold. If the generator ξ belongs to the k-nullity distribution N(k) for some smooth function k, then we say that (M^n, g) is an N(k)-quasi Einstein manifold.

Let (M^n, g) be a quasi Einstein manifold. From (1.2) and (1.3), it follows that

$$(2.1) S(X,\xi) = (a+b)\eta(X),$$

$$(2.2) Q\xi = (a+b)\,\xi,$$

$$(2.3) r = na + b,$$

where r is the scalar curvature of M^n .

In an *n*-dimensional Riemannian manifold (M^n, g) , the conformal curvature tensor C is given by [8]

$$C(X,Y)Z = R(X,Y)Z - \frac{1}{n-2} \{g(Y,Z)QX - g(X,Z)QY + S(Y,Z)X - S(X,Z)Y\} + \frac{r}{(n-1)(n-2)} \{g(Y,Z)X - g(X,Z)Y\}.$$

If (M^n, g) is a conformally flat quasi Einstein manifold, then in view of (1.2), (2.3) and (2.4) we have

$$R(X,Y)Z = \frac{(n-2)a-b}{(n-1)(n-2)} \{g(Y,Z)X - g(X,Z)Y\}$$

$$+ \frac{b}{n-2} \{g(Y,Z)\eta(X)\xi - g(X,Z)\eta(Y)\xi$$

$$+ \eta(Y)\eta(Z)X - \eta(X)\eta(Z)Y\}.$$
(2.5)

Putting $Z = \xi$, in the above equation, we obtain

(2.6)
$$R(X,Y)\xi = \frac{a+b}{n-1} \{ \eta(Y)X - \eta(X)Y \},$$

that is, in an *n*-dimensional conformally flat quasi Einstein manifold, the generator ξ belongs to the $\left(\frac{a+b}{n-1}\right)$ -nullity distribution $N\left(\frac{a+b}{n-1}\right)$. We can state this fact as the following:

Theorem 2.2. An n-dimensional conformally flat quasi Einstein manifold is an $N\left(\frac{a+b}{n-1}\right)$ -quasi Einstein manifold.

Thus, we see that n-dimensional conformally flat quasi Einstein manifolds are natural examples of N(k)-quasi Einstein manifolds. It is well-known that in a 3-dimensional Riemannian manifold (M^3, g) , the conformal curvature tensor vanishes, therefore we have the following

Corollary 2.3. Each 3-dimensional quasi Einstein manifold is an $N(\frac{a+b}{2})$ -quasi Einstein manifold.

Let (M^n, g) be an N(k)-quasi Einstein manifold. Then, we have

$$(2.7) R(Y,Z)\xi = k(\eta(Z)Y - \eta(Y)Z).$$

The equation (2.7) is equivalent to

$$(2.8) R(\xi, Y) Z = k \left(g(Y, Z) \xi - \eta(Z) Y \right).$$

In particular, the above equation implies that

$$(2.9) R(\xi, Y) \xi = k(\eta(Y) \xi - Y).$$

From (2.7) and (2.8), we have

$$(2.10) \eta(R(Y,Z)\xi) = 0,$$

$$(2.11) \eta(R(\xi, Y)Z) = k(g(Y, Z) - \eta(Y)\eta(Z)).$$

3. Semi-symmetric N(k)-quasi Einstein manifolds

As a generalization of locally symmetric spaces, many geometers have considered semi-symmetric spaces and in turn their generalizations. A Riemannian manifold M is said to be semi-symmetric if its curvature tensor R satisfies

$$R(X,Y) \cdot R = 0, \qquad X,Y \in TM,$$

where R(X,Y) acts on R as a derivation. In this section, we study N(k)-quasi Einstein manifolds M satisfying $R(\xi,X) \cdot R = 0, X \in TM$.

First, we prove the following theorem.

Theorem 3.1. An N(k)-quasi Einstein manifold (M^n, g) satisfies $R(\xi, X) \cdot R = 0$ if and only if k = 0.

Proof. The condition $R(\xi, X) \cdot R = 0$ implies that

$$0 = [R(\xi, X), R(Y, Z)] \xi - R(R(\xi, X)Y, Z) \xi - R(Y, R(\xi, X)Z) \xi,$$

which in view of (2.8) and (2.9) gives

$$0 = k \{g(X, R(Y, Z)\xi)\xi - \eta(X)R(Y, Z)\xi + R(Y, Z)X - g(X, Y)R(\xi, Z)\xi + \eta(Y)R(X, Z)\xi - g(X, Z)R(Y, \xi)\xi + \eta(Z)R(Y, X)\xi \}.$$

In view of (2.7), the above equation yields

$$0 = k \{R(Y, Z) X - k (g(Z, X) Y - g(Y, X) Z)\}.$$

Therefore, either k = 0 or

$$R(Y,Z)X = k(g(Z,X)Y - g(Y,X)Z).$$

In the second case, M^n becomes an Einstein space, which is not possible. Thus we have k = 0. Conversely, if k = 0, in view of (2.8) M^n satisfies $R(\xi, X) \cdot R = 0$. This completes the proof.

As a Corollary, we have the following

Corollary 3.2. If (M^n, g) is a semi-symmetric N(k)-quasi Einstein manifold, then k = 0.

Now, we apply the above two results to conformally flat quasi Einstein manifolds and in result we may state the following

Theorem 3.3. A conformally flat quasi Einstein manifold satisfies $R(\xi, X)$ R = 0 if and only if a + b = 0. In particular, each conformally flat semi-symmetric quasi Einstein manifold satisfies a + b = 0.

4. N(k)-quasi Einstein manifolds satisfying $R(\xi, X) \cdot S = 0$

First, we prove the following

Theorem 4.1. An N(k)-quasi Einstein manifold (M^n, g) satisfies $R(\xi, X) \cdot S = 0$ if and only if k = 0.

Proof. Let (M^n, g) be a N(k)-quasi Einstein manifold. The condition $R(\xi, X) \cdot S = 0$ gives

(4.1)
$$S(R(\xi, X)Y, \xi) + S(Y, R(\xi, X)\xi) = 0.$$

In view of (2.1) and (2.11), we get

(4.2)
$$S(R(\xi, X)Y, \xi) = (a+b)k(g(X,Y) - \eta(X)\eta(Y)).$$

In view of (2.9) and (2.1) we have

$$(4.3) S(R(\xi, X)\xi, Y) = -kS(X, Y) + (a+b)k\eta(X)\eta(Y).$$

From (4.1), (4.2) and (4.3), we have

$$(4.4) k\{S - (a+b)g\} = 0.$$

Therefore, either k=0 or S=(a+b)g. In the second case, M^n becomes an Einstein space, which is not possible. Thus we have k=0. Conversely, if k=0 then in view of (2.8) M^n satisfies $R(\xi, X) \cdot S=0$.

As an application, we have the following

Theorem 4.2. A conformally flat quasi Einstein manifold satisfies $R(\xi, X) \cdot S = 0$ if and only if a + b = 0.

5. Ricci-recurrent quasi Einstein manifolds

A non-flat Riemannian manifold M is called a *Ricci-recurrent manifold* [6] if its Ricci tensor S satisfies the condition

$$(5.1) \qquad (\nabla_X S)(Y, Z) = A(X)S(Y, Z),$$

where ∇ is Levi-Civita connection of the Riemannian metric g and A is a 1-form on M.

Now, we prove the following

Theorem 5.1. If M is a Ricci-recurrent quasi Einstein manifold, then

(5.2)
$$(a+b) A(X) = X(a+b), X \in TM.$$

Proof. Using (5.1) in

$$(\nabla_X S)(Y,Z) = XS(Y,Z) - S(\nabla_X Y,Z) - S(Y,\nabla_X Z).$$

we get

$$A(X)S(Y,Z) = XS(Y,Z) - S(\nabla_X Y, Z) - S(Y, \nabla_X Z).$$

Putting $Y = Z = \xi$, in the above equation we obtain

$$S(\xi,\xi) A(X) = XS(\xi,\xi) - 2S(\nabla_X \xi, \xi),$$

from which, in view of (2.1), we get (5.2).

A Ricci-recurrent manifold is Ricci-symmetric if and only if the 1-form A is zero. Thus we have the following two corollaries:

Corollary 5.2. If M is a Ricci-symmetric quasi Einstein manifold, then a+b is constant.

Corollary 5.3. If M is a Ricci-recurrent quasi Einstein manifold and if a + b is constant, then either a + b = 0 or M reduces to a Ricci-symmetric quasi Einstein manifold.

6. Quasi-umbilical hypersurfaces

Let M^n be a hypersurface of a Riemannian manifold (\bar{M}^{n+1}, g) . We now assume that M^n is orientable and choose a unit vector field ξ of \bar{M}^{n+1} normal to M^n . Then Gauss and Weingarten formulae are given respectively by

(6.1)
$$\bar{\nabla}_X Y = \nabla_X Y + h(X, Y)\xi, \quad (X, Y \in TM^n),$$

$$(6.2) \bar{\nabla}_X \xi = -HX,$$

where ∇ and ∇ are respectively the Riemannian and induced Riemannian connections in \bar{M}^{n+1} and M^n and h is the second fundamental form related to H by

$$(6.3) h(X,Y) = g(HX,Y).$$

 M^n is called a quasi-umbilical hypersurface [3] if

$$(6.4) h(X,Y) = \alpha g(X,Y) + \beta u(X) u(Y), X,Y \in TM^n,$$

where α and β are some smooth functions and u is a 1-form. A quasi-umbilical hypersurface becomes umbilical, geodesic or cylindrical according as $\beta = 0$, $\alpha = 0 = \beta$ or $\alpha = 0$.

If M^n is a quasi-umbilical hypersurface of a Riemannian manifold (\bar{M}^{n+1}, g) , then the Gauss equation becomes [4]

$$\bar{R}(X,Y,Z,W) = R(X,Y,Z,W) + \alpha^{2} (g(X,Z)g(Y,W) - g(X,W)g(Y,Z)) + \alpha\beta (u(Y)u(W)g(X,Z) + u(X)u(Z)g(Y,W) - u(Y)u(Z)g(X,W) - u(X)u(W)g(Y,Z))$$
(6.5)

for all $X, Y, Z, W \in TM^n$. From the above equation, we get

$$\bar{S}(X,Y) = \bar{R}(\xi, X, Y, \xi) + S(X,Y) - (n\alpha^2 + \alpha\beta) g(X,Y) - (n-1) \alpha\beta u(X) u(Y),$$

where \bar{S} and S are Ricci tensors of \bar{M}^{n+1} and M^n respectively.

Now, we prove the following:

Theorem 6.1. If M^n is a quasi-unbilical hypersurface of an $N(\bar{k})$ -quasi Einstein manifold (\bar{M}^{n+1}, g) , such that M^n is normal to the generator ξ of \bar{M}^{n+1} , then M^n is an N(k)-quasi Einstein manifold.

Proof. Using (2.8) in (6.6), we see that M^n is a quasi Einstein manifold. Moreover, using (2.7) in (6.5), we find that M^n is an N(k)-quasi Einstein manifold, where $k = \bar{k} + \alpha (\alpha + \beta)$.

Remark 6.2. The above result is also true in the following cases (a) if M^n is umbilical, geodesic or cylindrical and/or (b) \bar{M}^{n+1} is a conformally flat quasi Einstein manifold.

Acknowledgement. The second author acknowledges the financial support from Korea Science and Engineering Foundation Grant (R05-2004-000-11588).

References

- [1] D. E. Blair, Riemannian geometry of contact and symplectic manifolds, Progress in Mathematics, 203. Birkhauser Boston, Inc., Boston, MA, 2002.
- [2] M. C. Chaki and R. K. Maity, On quasi Einstein manifolds, Publ. Math. Debrecen 57 (2000), no. 3-4, 297–306.
- [3] B.-Y. Chen, Geometry of submanifolds, Pure and Applied Mathematics, No. 22, Marcel Dekker New York, 1973.
- [4] U. C. De and G. C. Ghosh, On quasi Einstein manifolds II, Bull. Calcutta Math. Soc. 96 (2004), no. 2, 135–138.
- [5] M. Okumura, Some remarks on space with a certain contact structure, Tôhoku Math. J. 14 (1962), 135–145.
- [6] E. M. Patterson, Some theorems on Ricci-recurrent spaces, J. London Math. Soc. 27 (1952), 287–295.

- [7] S. Tanno, Ricci curvatures of contact Riemannian manifolds, Tôhoku Math. J. 40 (1988), 441–448.
- [8] K. Yano and S. Bochner, *Curvature and Betti numbers*, Annals of Mathematics Studies **32**, Princeton University Press, 1953.

MUKUT MANI TRIPATHI
DEPARTMENT OF MATHEMATICS AND ASTRONOMY
LUCKNOW UNIVERSITY
LUCKNOW 226 007, INDIA
E-mail address: mmtripathi66@yahoo.com

JEONG-SIK KIM
DEPARTMENT OF MATHEMATICS AND MATHEMATICAL INFORMATION

Yosu National University Yosu 550-749, South Korea

 $E ext{-}mail\ address: jskim315@hotmail.com}$