# UNIMODULAR GROUPS OF TYPE $\mathbb{R}^3 \rtimes \mathbb{R}$

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ABSTRACT. There are 7 types of 4-dimensional solvable Lie groups of the form  $\mathbb{R}^3 \rtimes_{\varphi} \mathbb{R}$  which are unimodular and of type (R). They will have left-invariant Riemannian metrics with maximal symmetries. Among them, three nilpotent groups ( $\mathbb{R}^4$ ,  $\mathrm{Nil}^3 \times \mathbb{R}$  and  $\mathrm{Nil}^4$ ) are well known to have lattices.

All the compact forms modeled on the remaining four solvable groups  $\mathrm{Sol}^3 \times \mathbb{R}$ ,  $\mathrm{Sol}_0^4$ ,  $\mathrm{Sol}_0'^4$  and  $\mathrm{Sol}_\lambda^4$  are characterized: (1)  $\mathrm{Sol}^3 \times \mathbb{R}$  has lattices. For each lattice, there are infra-solvmanifolds with holonomy groups 1,  $\mathbb{Z}_2$  or  $\mathbb{Z}_4$ . (2) Only some of  $\mathrm{Sol}_\lambda^4$ , called  $\mathrm{Sol}_{m,n}^4$ , have lattices with no non-trivial infra-solvmanifolds. (3)  $\mathrm{Sol}_0'^4$  does not have a lattice nor a compact form. (4)  $\mathrm{Sol}_0^4$  does not have a lattice, but has infinitely many compact forms. Thus the first Bieberbach theorem fails on  $\mathrm{Sol}_0^4$ . This is the lowest dimensional such example. None of these compact forms has non-trivial infra-solvmanifolds.

#### 1. Introduction

We study certain class of 4-dimensional solvable Lie groups of the form  $\mathbb{R}^3 \rtimes_{\varphi} \mathbb{R}$ , where  $\varphi : \mathbb{R} \to \operatorname{GL}(3,\mathbb{R})$  is a continuous homomorphism. The homomorphism  $\varphi$  yields a Lie algebra homomorphism  $\psi : \mathbb{R} \to \mathfrak{gl}(3,\mathbb{R})$  so that  $\varphi(t) = e^{\psi(t)}$ . Therefore,  $\mathbb{R}^3 \rtimes_{\varphi} \mathbb{R}$  is completely determined by the matrix  $\mathcal{A} = \psi(1)$  only.

A connected Lie group G is of type (R) if for every  $X \in \mathfrak{g}$ ,  $\operatorname{ad}(X) : \mathfrak{g} \to \mathfrak{g}$  has only real eigenvalues. G is of type (E) if  $\exp : \mathfrak{g} \to G$  is surjective. It is unimodular if  $\operatorname{ad}(X)$  has trace 0 for every  $X \in \mathfrak{g}$ . For our  $\mathbb{R}^3 \rtimes_{\varphi} \mathbb{R}$  when it is unimodular and of type (R), up to conjugation and scalar multiple, there are 7 classes; only one class contains a parameter. We tabulate the isomorphism classes of 4-dimensional unimodular, type (R) Lie algebras of the form  $\mathbb{R}^3 \rtimes_{\mathcal{A}} \mathbb{R}$  and the associated simply connected Lie groups:

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$\mathcal{A}$ for Lie algebra $\mathbb{R}^3 \rtimes_{\mathcal{A}} \mathbb{R}$	Associated simply connected Lie group
	$\mathbb{R}^3 \rtimes_{arphi(s)} \mathbb{R}$
[0 0 0]	1 0 0
0 0 0	$\mid \mathbb{R}^4; \mid 0 \mid 1 \mid 0 \mid$
0 1 0	$\begin{bmatrix} 1 & s & 0 \end{bmatrix}$
	$\left  \text{Nil}^3 \times \mathbb{R}; \right  \left  0  1  0 \right $
	0 0 1
	$1  s  \frac{1}{2}s^2$
	Nil <sup>4</sup> ; 0 1 s
0 0 0	0 0 1
	$\begin{bmatrix} e^s & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$
	$\left  \text{Sol}^3 \times \mathbb{R}; \right  \left  \begin{array}{ccc} 0 & e^{-s} & 0 \\ 0 & 0 & 1 \end{array} \right $
0 0 0	0 0 1
	$\begin{array}{ c c c c c c c c c c c c c c c c c c c$
$\left  \begin{array}{ccc c} 0 & 1 & 0 \\ 0 & 0 & -2 \end{array} \right $	$egin{array}{ c c c c c c c c c c c c c c c c c c c$
<del>                                      </del>	$e^{\lambda s} = 0$
$\left  \begin{array}{cccc} \lambda & 0 & 0 \\ 0 & 1 & 0 \end{array} \right   (\lambda > 1)$	: . I
$\left\  \begin{array}{ccccc} 0 & 1 & 0 \\ 0 & 0 & -1 - \lambda \end{array} \right\  \left( \frac{\lambda > 1}{\lambda} \right)$	$\begin{vmatrix} \operatorname{Sol}_{\lambda}; & \operatorname{o} & e & 0 \\ 0 & 0 & e^{-(1+\lambda)s} \end{vmatrix}$
	$\begin{bmatrix} e^s & se^s & 0 \end{bmatrix}$
	$Sol'_0^4$ ; $0 e^s 0$
	$\begin{bmatrix} 501 & 0 & 0 & 0 & 0 \\ 0 & 0 & e^{-2s} \end{bmatrix}$

The group law of  $\mathbb{R}^3 \rtimes_{\omega} \mathbb{R}$  is

$$(\mathbf{x},s)(\mathbf{y},t) = (\mathbf{x} + \varphi(s)\mathbf{y}, s+t),$$

and it can be embedded in Aff(4) as

$$G = \left\{ \begin{bmatrix} \varphi(s) & 0 & \mathbf{x} \\ 0 & 1 & s \\ 0 & 0 & 1 \end{bmatrix} \right\} \subset \mathrm{Aff}(4) \subset \mathrm{GL}(5, \mathbb{R}),$$

where  $\varphi(s) \in GL(3,\mathbb{R})$ ,  $s \in \mathbb{R}$  and  $\mathbf{x} \in \mathbb{R}^3$  is a column vector.

For a Lie group G with a left-invariant metric,  $\operatorname{Isom}(G)$  denotes the group of isometries,  $\operatorname{Isom}_0(G)$  its connected component of the identity. Also  $\operatorname{Aut}(G)$  denotes the group of automorphisms of G. If  $\Pi$  is a discrete subgroup of  $\operatorname{Isom}(G)$  acting freely and properly discontinuously on G, the quotient space  $\Pi \backslash G$  is a compact form. If  $\Pi$  is a discrete cocompact subgroup of  $G \rtimes K$  (where K a compact subgroup of  $\operatorname{Aut}(G)$ ) and  $\Pi \subset G$  is a lattice of G, acting freely and properly discontinuously on G, the quotient space  $\Pi \backslash G$  is an infra-homogeneous space. If, in particular,  $\Pi \subset G$ , then  $\Pi \backslash G$  is a homogeneous space. If G is  $\mathbb{R}^n$ , nilpotent, solvable, then the homogeneous space (infra-homogeneous space)

is called a torus (flat manifold), nilmanifold (infra-nilmanifold), solvmanifold (infra-solvmanifold), respectively.

Remark 1.1. Our list consists of  $\mathbb{R}^4$ ,  $\operatorname{Nil}^3 \times \mathbb{R}$ ,  $\operatorname{Nil}^4$ ,  $\operatorname{Sol}^3 \times \mathbb{R}$ ,  $\operatorname{Sol}_0^4$ ,  $\operatorname{Sol}_0'^4$  and  $\operatorname{Sol}_\lambda^4$ , while the Lie groups in Filipkiewicz's list in [12] consist of  $\mathbb{R}^4$ ,  $\operatorname{\widetilde{SL}}(2,\mathbb{R}) \times \mathbb{R}$ ,  $\operatorname{Nil}^3 \times \mathbb{R}$ ,  $\operatorname{Nil}^4$ ,  $\operatorname{Sol}^3 \times \mathbb{R}$ ,  $\operatorname{Sol}_0^4$ ,  $\operatorname{Sol}_{m,n}^4$ .

Note that  $\widetilde{\mathrm{SL}}(2,\mathbb{R})\times\mathbb{R}$  and  $\mathrm{Sol}_1^4$  are not in our list since they are not of the type  $\mathbb{R}^3\rtimes_{\varphi}\mathbb{R}$ . Note also that  $\mathrm{Sol}_1^4$  has nil-radical  $\mathrm{Nil}^3$ . Our  $\mathrm{Sol}_0'^4$  is not in Filipkiewicz's list (with a unknown reason). We shall show the following:

- (1)  $\operatorname{Sol}_{0}^{\prime 4}$  does not have a lattice nor a compact-form, see Proposition 2.2 and Theorem 4.2.
- (2)  $\operatorname{Sol}_{\lambda}^4$  has a lattice if and only if it is of the form  $\operatorname{Sol}_{m,n}^4$ . Otherwise, there is no compact-form. See Proposition 2.1 and Theorem 4.2.
- (3) Sol<sub>0</sub><sup>4</sup> does not have a lattice, yet it has infinitely many compact-forms, see Proposition 2.2 and Theorem 4.3. This is a type (R) counter-example to the generalized Bieberbach's first Theorem.

# 2. Existence of lattices

For a simply connected solvable Lie group G, a lattice of G is a discrete cocompact subgroup of G. As is well known, the three nilpotent groups and the first solvable group  $\mathrm{Sol}^3 \times \mathbb{R}$  have lattices. We study the remaining three solvable cases. We shall prove  $\mathrm{Sol}_0^4$  and  $\mathrm{Sol'}_0^4$  do not have lattices; and the group  $\mathrm{Sol}_{\lambda}^4$  has generically no lattice except for countably many values of  $\lambda$ 's.

**Proposition 2.1** ([12]). The group  $\operatorname{Sol}_{\lambda}^4$  has a lattice if and only if there exist integers m, n such that the equation  $x^3 - mx^2 + nx - 1 = 0$  has 3 distinct positive real roots  $\alpha_1 > \alpha_2 > \alpha_3$  (with  $\lambda = \frac{\ln \alpha_1}{\ln \alpha_2}$ ). We call such  $\operatorname{Sol}_{\lambda}^4$  as  $\operatorname{Sol}_{m,n}^4$ . There are only countably many such  $\lambda$ 's.

*Proof.* Recall  $G = \operatorname{Sol}_{\lambda}^4 = \mathbb{R}^3 \rtimes_{\varphi} \mathbb{R}$ , where

$$arphi(s) = \left[ egin{array}{ccc} e^{\lambda s} & 0 & 0 \\ 0 & e^{s} & 0 \\ 0 & 0 & e^{-(1+\lambda)s} \end{array} 
ight], \quad (\lambda > 1).$$

Suppose  $\Gamma$  is a lattice. Since  $\mathbb{R}^3$  is the *nil-radical* (i.e., the maximal connected normal nilpotent subgroup) of G,  $\Gamma \cap \mathbb{R}^3 \cong \mathbb{Z}^3$  must be a lattice in  $\mathbb{R}^3$ . Thus  $\Gamma$  is of the form  $\mathbb{Z}^3 \rtimes \mathbb{Z}$ , where a generator of  $\mathbb{Z}$  acts on  $\mathbb{Z}^3$  via  $A \in GL(3,\mathbb{Z})$ . Let P be a matrix diagonalizing A. Then

$$\varphi(s_0) = PAP^{-1}.$$

Let

$$\chi_A(x) = x^3 - mx^2 + nx - 1$$

be the characteristic polynomial of A (so  $m, n \in \mathbb{Z}$ ). Since A and  $\varphi(s_0)$  have the same characteristic polynomial, we have

(2-1) 
$$\begin{cases} m = e^{\lambda s_0} + e^{s_0} + e^{-(1+\lambda)s_0}, \\ n = e^{-\lambda s_0} + e^{-s_0} + e^{(1+\lambda)s_0}. \end{cases}$$

Note that m, n > 0. For example, we know the companion matrix

$$\left[\begin{array}{ccc} 0 & 0 & 1 \\ 1 & 0 & -n \\ 0 & 1 & m \end{array}\right]$$

has the characteristic polynomial  $\chi_A(x)$ .

The function  $\chi_A(x)$  has two critical points

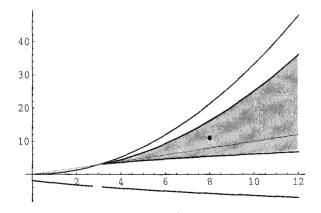
$$\frac{1}{3}(m \pm \sqrt{m^2 - 3n}).$$

Then  $\chi_A(x) = 0$  has 3 distinct positive real roots if and only if  $m^2 > 3n$  and

$$\chi_A(\frac{1}{3}(m-\sqrt{m^2-3n})) > 0,$$
  
 $\chi_A(\frac{1}{2}(m+\sqrt{m^2-3n})) < 0.$ 

We need one more condition: 1 cannot be the root. Otherwise, the eigenvalues will be  $e^{\lambda s}$ ,  $e^{-\lambda s}$  and 1 so that the Lie group becomes  $\mathrm{Sol}^3 \times \mathbb{R}$ . Since  $\chi_A(1) = 0$  if and only if m = n, we need to exclude the cases m = n.

Thus, if the group  $\operatorname{Sol}_{\lambda}^4 = \mathbb{R}^3 \rtimes_{\varphi} \mathbb{R}$  has a lattice, then there exists a pair of positive integers (m,n) for which  $x^3 - mx^2 + nx - 1 = 0$  has 3 distinct positive real roots  $e^{\lambda s_0}$ ,  $e^{s_0}$  and  $e^{-(1+\lambda)s_0}$ . [Then (m,n) lies in the region].



Conversely, suppose (m, n) lies in the shaded region minus the line n = m. Then the equation  $x^3 - mx^2 + nx - 1 = 0$  has 3 distinct positive real roots, say  $\alpha_1 > \alpha_2 > \alpha_3$ . Then the equations (2–1) yields

$$\lambda = \frac{\ln \alpha_1}{\ln \alpha_2}; \quad s_0 = \ln \alpha_2.$$

For example, for the point (m,n)=(8,11), the equation  $\chi_A(x)=0$  has 3 positive real roots. [All the integer points in the shaded region containing (8,11) in the picture give rise to the same results]. The region contains only countably infinite pairs (m,n) of integers. Consequently, for only countably infinite values of  $\lambda$ 's, the matrix  $\varphi(s)$  can be conjugated to an integral matrix for some s. This proves that  $\operatorname{Sol}_{\lambda}^4$  has generically no lattice except for countably many values of  $\lambda$ 's.

Next, we look at the groups  $Sol_0^4$  and  $Sol_0'^4$ .

**Proposition 2.2.** The groups  $Sol_0^4$  and  $Sol_0^{'4}$  do not admit any lattice.

*Proof.* Recall  $\operatorname{Sol}_0^4$  and  $\operatorname{Sol}_0'^4$  are of the form  $\mathbb{R}^3 \rtimes_{\varphi} \mathbb{R}$ ,

$$\varphi(s) = \left[ \begin{array}{ccc} e^s & 0 & 0 \\ 0 & e^s & 0 \\ 0 & 0 & e^{-2s} \end{array} \right] \quad \text{or} \quad \left[ \begin{array}{ccc} e^s & se^s & 0 \\ 0 & e^s & 0 \\ 0 & 0 & e^{-2s} \end{array} \right].$$

Suppose  $\Gamma$  is a lattice. As before,  $\Gamma \cap \mathbb{R}^3 \cong \mathbb{Z}^3$  must be a lattice in  $\mathbb{R}^3$ . Thus  $\Gamma$  is of the form  $\mathbb{Z}^3 \rtimes \mathbb{Z}$ , where a generator of  $\mathbb{Z}$  acts on  $\mathbb{Z}^3$  via  $A \in GL(3,\mathbb{Z})$ . Let P be a matrix diagonalizing A. Then

$$\varphi(s_0) = PAP^{-1}$$
.

Let

$$\chi_A(x) = x^3 - mx^2 + nx - 1$$

be the characteristic polynomial of A (so  $m, n \in \mathbb{Z}$ ). Since A and  $\varphi(s_0)$  have the same characteristic polynomial, we have

$$m = 2e^s + e^{-2s}$$

$$n = 2e^{-s} + e^{2s}.$$

The function  $\chi_A(x)$  has two critical points

$$\frac{1}{3}(m\pm\sqrt{m^2-3n}).$$

Then  $\chi_A(x) = 0$  has 2 positive real roots (one of them is a double root) if and only if

$$\chi_A(\frac{1}{3}(m-\sqrt{m^2-3n}))=0$$
 and  $\chi_A(\frac{1}{3}(m+\sqrt{m^2-3n}))<0$ 

or

$$\chi_A(\frac{1}{3}(m-\sqrt{m^2-3n})) > 0$$
 and  $\chi_A(\frac{1}{3}(m+\sqrt{m^2-3n})) = 0$ .

For the first, the equation

$$-27 - 2m^3 + 9mn + 2(m^2 - 3n)^{3/2} = 0$$

must have integer solutions m, n. Clearly,  $\sqrt{m^2 - 3n}$  must be an integer. Let

$$m^2 - 3n = r^2$$

with r > 0. Then the above equation yields the polynomial

$$g(m,r) = -27 + m^3 - 3mr^2 + 2r^3$$
$$= (m-r)^2(m+2r) - 27.$$

Suppose g(m,r)=0. Then, for m>26, we have 0<|r-m|<1, which is impossible since m and r are both integers. (In fact, this is true for  $m\geq 9$ ). By checking for  $1\leq m\leq 26$ , we conclude that g(m,r)=0 has no integer solutions. Consequently, the group does not admit a lattice.

For the second, the equation

$$-27 - 2m^3 + 9mn - 2(m^2 - 3n)^{3/2} = 0$$

must have integer solutions m, n. Clearly,  $\sqrt{m^2 - 3n}$  must be an integer. Let

$$m^2 - 3n = r^2$$

with r > 0. Then the above equation yields the polynomial

$$g(m,r) = -27 + m^3 - 3mr^2 - 2r^3$$
$$= (m+r)^2(m-2r) - 27.$$

Suppose g(m,r)=0. Then, for m>5, we have 0<|m-2r|<1, which is impossible since m and r are both integers. By checking for  $1\leq m\leq 5$ , we conclude that g(m,r)=0 has no integer solutions. Consequently, the group does not admit a lattice.

#### 3. Infra-homogeneous spaces

We shall need Gordon-Wilson's result:

**Theorem 3.1** ([7]). Let G be a solvable Lie group which is of type (R) and is unimodular. Then, with respect to any left-invariant Riemannian metric, the group of left-translations  $\ell(G)$  is normal in  $\mathrm{Isom}_0(G)$ , the connected component of the group of isometries of G.

Consequently, with respect to any left-invariant Riemannian metric on a unimodular Lie group G of type (R),

$$\text{Isom}(G) \subset \ell(G) \rtimes K$$
,

where K is a maximal compact subgroup of  $\operatorname{Aut}(G)$ . Conversely, for any maximal compact subgroup K of  $\operatorname{Aut}(G)$ , there exists a left-invariant Riemannian metric on G for which  $\operatorname{Isom}(G) = \ell(G) \rtimes K$ . Therefore, in order to understand the isometry group  $\operatorname{Isom}(G)$ , it is enough to calculate  $\operatorname{Aut}(G)$ .

For the case when  $\varphi(s)$  has all eigenvalues not equal to 1 (that is,  $\operatorname{Sol}_0^4$ ,  $\operatorname{Sol}_0^4$ ),  $\mathbb{R}^3$  is the nil-radical in  $\mathbb{R}^3 \rtimes_{\varphi} \mathbb{R}$ , and hence is a characteristic subgroup of  $\mathbb{R}^3 \rtimes_{\varphi} \mathbb{R}$ ; every automorphism of  $\mathbb{R}^3 \rtimes_{\varphi} \mathbb{R}$  restricts to an automorphism of

 $\mathbb{R}^3$ . Consequently an automorphism of  $\mathbb{R}^3 \rtimes_{\varphi} \mathbb{R}$  induces an automorphism on the quotient group  $\mathbb{R}$ . Thus there is a natural homomorphism

$$\begin{array}{ccc} \operatorname{Aut}(\mathbb{R}^3 \rtimes_{\varphi} \mathbb{R}) & \longrightarrow & \operatorname{GL}(3,\mathbb{R}) \times \operatorname{GL}(1,\mathbb{R}) \\ \theta & \mapsto & (\hat{\theta},\bar{\theta}). \end{array}$$

By Gram-Schmidt,  $\widehat{\theta}$  is conjugate to a blocked upper triangular matrix. We need to look into the eigenvalues of the matrix  $\widehat{\theta}$ . Except for the case when  $\widehat{\theta}$  has complex eigenvalues, G is always of type (R). But in general, the trace of  $\widehat{\theta}$  will not be zero. Such G will not have any lattice, and the group of isometries is hard to calculate.

### Proposition 3.2. Let

$$C = \{ (\widehat{\theta}, \overline{\theta}) \in \mathrm{GL}(3, \mathbb{R}) \times \mathrm{GL}(1, \mathbb{R}) : \varphi(\overline{\theta}(s)) = \widehat{\theta} \circ \varphi(s) \circ \widehat{\theta}^{-1} \}.$$

Then

$$\operatorname{Aut}(\mathbb{R}^3 \rtimes_{\varphi} \mathbb{R}) = \mathbb{R}^3 \rtimes C \ \subset \ \mathbb{R}^3 \rtimes \Big(\operatorname{GL}(3,\mathbb{R}) \times \operatorname{GL}(1,\mathbb{R})\Big).$$

*Proof.* Let  $\theta \in \operatorname{Aut}(\mathbb{R}^3 \rtimes_{\varphi} \mathbb{R})$ . Then  $(\hat{\theta}, \bar{\theta}) \in \operatorname{Aut}(\mathbb{R}^3) \times \operatorname{Aut}(\mathbb{R})$  and  $\theta(\mathbf{x}, 0) = (\hat{\theta}(\mathbf{x}), 0)$ . Define  $\eta : \mathbb{R} \to \mathbb{R}^3$  by  $\theta(\mathbf{0}, s) = (-\eta(\bar{\theta}(s)), \bar{\theta}(s))$ . Thus,

$$\theta(\mathbf{x},s) = \theta((\mathbf{x},0)(\mathbf{0},s)) = (\hat{\theta}(\mathbf{x}),0)(-\eta(\overline{\theta}(s)),\bar{\theta}(s)) = (\hat{\theta}(\mathbf{x})-\eta(\overline{\theta}(s)),\bar{\theta}(s)).$$

We write this  $\theta$  as  $(\eta, \hat{\theta}, \overline{\theta})$ . Thus,

$$(\eta, \hat{\theta}, \overline{\theta})(\mathbf{x}, s) = (\hat{\theta}(\mathbf{x}) - \eta(\overline{\theta}(s)), \overline{\theta}(s)).$$

For this to be an automorphism of  $\mathbb{R}^3 \rtimes_{\varphi} \mathbb{R}$ , it should satisfy

$$\begin{split} \varphi(\overline{\theta}(s)) &= \widehat{\theta} \circ \varphi(s) \circ \widehat{\theta}^{-1}, \\ \eta(s+t) &= \eta(s) + \varphi(\overline{\theta}(s)) \eta(t) \end{split}$$

for all  $s,t \in \mathbb{R}$ , or equivalently  $(\hat{\theta},\bar{\theta}) \in C$  and  $\eta: \mathbb{R} \to \mathbb{R}^3$  is a crossed homomorphism with respect to the action homomorphism  $\varphi \circ \bar{\theta}$ . Therefore, we have a homomorphism  $\operatorname{Aut}(\mathbb{R}^3 \rtimes_{\varphi} \mathbb{R}) \to C$ .

Conversely, suppose that  $(\hat{\theta}, \bar{\theta}) \in C$ . For any crossed homomorphism  $\eta : \mathbb{R} \to \mathbb{R}^3$  with respect to the action homomorphism  $\varphi \circ \bar{\theta}$ , we define  $\theta \in \operatorname{Aut}(\mathbb{R}^3 \rtimes_{\varphi} \mathbb{R})$  by

$$\theta(\mathbf{x}, s) = (\hat{\theta}(\mathbf{x}) - \eta(\overline{\theta}(s)), \overline{\theta}(s)).$$

Then it is easy to check that  $\theta$  is an automorphism of  $\mathbb{R}^3 \rtimes_{\varphi} \mathbb{R}$ . Moreover, this with  $\eta = 0$  defines a split homomorphism  $C \to \operatorname{Aut}(\mathbb{R}^3 \rtimes_{\varphi} \mathbb{R})$ .

In particular, we have observed that  $\theta \in \operatorname{Aut}(\mathbb{R}^3 \rtimes_{\varphi} \mathbb{R})$  with  $(\hat{\theta}, \bar{\theta}) = (\operatorname{id}_{\mathbb{R}^3}, \operatorname{id}_{\mathbb{R}})$  induces a crossed homomorphism with action homomorphism exactly  $\varphi \circ \bar{\theta} = \varphi$ .

Observe that a crossed homomorphism  $\eta$  is completely determined by the value  $\eta(1)$ , and hence the subgroup of all crossed homomorphisms is isomorphic to  $\mathbb{R}^3$ .

A finite quotient of a homogeneous space  $\Gamma \backslash G$  (where  $\Gamma$  is a lattice of G) is an infra-homogeneous space. We consider the infra-homogeneous spaces for each of the groups.

- (1)  $\mathbb{R}^4$ : There are 75 flat manifolds in dimension 4. See [3], for example.
- (2)  $\operatorname{Nil}^3 \times \mathbb{R}$ : There are 74 families of infra-nilmanifolds. For  $\operatorname{Nil}^4$ , roughly speaking, there are 7 families some of which split into 2 or 3 subfamilies. The only holonomy groups are 1,  $\mathbb{Z}_2$  and  $\mathbb{Z}_2 \times \mathbb{Z}_2$ . See [4] and [5].
- (3)  $\operatorname{Sol}^3 \times \mathbb{R}$ : See Proposition 3.4 below.
- (4) Sol<sub>0</sub><sup>4</sup> and Sol'<sub>0</sub><sup>4</sup>: No lattices, see Proposition 2.2.
- (5)  $\operatorname{Sol}_{\lambda}^{4}$ : Only  $\operatorname{Sol}_{m,n}^{4}$  has a lattice. There are no other infra-solvmanifolds, see Proposition 2.1.

Recall the embedding of  $G = \mathbb{R}^3 \rtimes_{\varphi} \mathbb{R}$  into Aff(4):

$$\begin{bmatrix} \varphi(s) & 0 & \mathbf{x} \\ 0 & 1 & s \\ 0 & 0 & 1 \end{bmatrix}$$

where  $\varphi(s) \in GL(3,\mathbb{R})$ ,  $\mathbf{x} \in \mathbb{R}^3$  is a column vector, and  $s \in \mathbb{R}$ .

In general, the normalizer of G in Aff(4) is not enough to get all of automorphisms of G. But for our  $G = \mathbb{R}^3 \rtimes_{\varphi} \mathbb{R}$ , the natural map  $N_{\mathrm{Aff}(4)}(G) \to \mathrm{Aut}(G)$  is surjective. The normalizer of G is

$$\alpha = \begin{bmatrix} \widehat{\theta} & \mathbf{m} & \mathbf{u} \\ 0 & \overline{\theta} & v \\ 0 & 0 & 1 \end{bmatrix}$$

with the conditions

$$\widehat{\theta} \circ \varphi(s) \circ \widehat{\theta}^{-1} = \varphi(\overline{\theta}(s))$$

(3–2) 
$$(I - \varphi(\overline{\theta}(s)))\mathbf{m} = 0$$

for all  $s \in \mathbb{R}$ . For such  $\alpha$ ,

$$(3-3) \qquad \begin{bmatrix} \widehat{\boldsymbol{\theta}} & \mathbf{m} & \mathbf{u} \\ \mathbf{0} & \overline{\boldsymbol{\theta}} & v \\ \mathbf{0} & \mathbf{0} & 1 \end{bmatrix} \begin{bmatrix} \varphi(s) & \mathbf{0} & \mathbf{x} \\ \mathbf{0} & 1 & s \\ \mathbf{0} & \mathbf{0} & 1 \end{bmatrix} \begin{bmatrix} \widehat{\boldsymbol{\theta}} & \mathbf{m} & \mathbf{u} \\ \mathbf{0} & \overline{\boldsymbol{\theta}} & v \\ \mathbf{0} & \mathbf{0} & 1 \end{bmatrix}^{-1} = \begin{bmatrix} \varphi(\overline{\boldsymbol{\theta}}(s)) & \mathbf{0} & \mathbf{x}' \\ \mathbf{0} & 1 & \overline{\boldsymbol{\theta}}(s) \\ \mathbf{0} & \mathbf{0} & 1 \end{bmatrix}$$

where  $\mathbf{x}' = \widehat{\theta}(\mathbf{x}) + s\mathbf{m} + (I - \varphi(\overline{\theta}(s)))\mathbf{u}$ . This shows conjugation by  $(\widehat{\theta}, \overline{\theta})$  (i.e., with  $\mathbf{m} = \mathbf{u} = 0$  and v = 0) is an automorphism. Conversely, for any  $\eta(1) \in \mathbb{R}^3$ , write it as

$$\eta(1) = \mathbf{m} + (I - \varphi(1))\mathbf{u},$$

where  $\mathbf{m} \in \ker(I - \varphi(1))$ . Then conjugation by  $(\mathbf{m}, \mathbf{u}, v)$  (with  $\widehat{\theta} = \mathrm{id}, \overline{\theta} = \mathrm{id}$ ) is exactly the automorphism induced by  $\eta$ .

The equation (3-3) shows also the centralizer of G in Aff(4). It consists of

$$\begin{bmatrix} I & 0 & \mathbf{u}_0 \\ 0 & 1 & v \\ 0 & 0 & 1 \end{bmatrix}$$

where  $(I - \varphi(1))\mathbf{u}_0 = 0$ . In case 1 is an eigenvalue of  $\varphi(1)$ , we denote the "complementary eigenspace" (so that V is  $\varphi(1)$ -invariant) by

$$\ker(I-\varphi(1))^{\perp}$$
.

Proposition 3.3. There is a one-one correspondence

$$\operatorname{Aut}(\mathbb{R}^3 \rtimes_{\varphi} \mathbb{R}) \cong \left\{ \begin{bmatrix} \widehat{\theta} & \mathbf{m} & \mathbf{u} \\ 0 & \overline{\theta} & 0 \\ 0 & 0 & 1 \end{bmatrix} \right\}$$

where  $\widehat{\theta}$ ,  $\overline{\theta}$ , **m** and **u** satisfy

$$\widehat{\boldsymbol{\theta}} \circ \varphi(s) \circ \widehat{\boldsymbol{\theta}}^{-1} = \varphi(\overline{\boldsymbol{\theta}}(s))$$
$$\mathbf{m} \in \ker(I - \varphi(\overline{\boldsymbol{\theta}}(s)))$$
$$\mathbf{u} \in \ker(I - \varphi(1))^{\perp}.$$

Note that conjugations by the two matrices

$$\begin{bmatrix} \varphi(s) & 0 & \mathbf{x} \\ 0 & 1 & s \\ 0 & 0 & 1 \end{bmatrix} \quad \text{and} \quad \begin{bmatrix} \varphi(s) & 0 & \mathbf{x} \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix},$$

(where the latter is used in the Proposition 3.3) result in the same automorphism.

The isometry group of  $\mathrm{Sol}^3$  is not always  $\mathrm{Sol}^3 \rtimes D_8$ . Sometimes, it is  $\mathrm{Sol}^3 \rtimes (\mathbb{Z}_2)^2$ , depending on the left-invariant Riemannian metric. See Ha-Lee [8] and [9, Theorem 3.3]. With the best left-invariant Riemannian metric,  $\mathrm{Sol}^3$  has isometry group  $\mathrm{Sol}^3 \rtimes D_8$  (see for example, [11]). None of these finite subgroups of the isometry group can act freely. We denote by  $\mathbb{R}^*$  the multiplicative group  $\mathbb{R} - \{0\}$ . On  $\mathrm{Sol}^3 \times \mathbb{R}$ , it is not too hard to see the following:

**Theorem 3.4.** The group of automorphisms of  $Sol^3 \times \mathbb{R}$  is  $\mathbb{R}^3 \rtimes ((\mathbb{R}^*)^3 \rtimes \mathbb{Z}_2)$ , and the maximal group of isometries is

$$Isom(Sol^{3} \times \mathbb{R}) = (Sol^{3} \times \mathbb{R}) \rtimes ((\mathbb{Z}_{2})^{3} \rtimes \mathbb{Z}_{2})$$
$$= (Sol^{3} \times \mathbb{R}) \rtimes (D_{8} \times \mathbb{Z}_{2}).$$

Every infra-solvmanifold is the quotient by torsion free extension  $\pi$  of a lattice  $\Gamma$  (=  $\Delta \times \mathbb{Z}$ , where  $\Delta$  is a lattice of  $Sol^3$ ) by a cyclic subgroup of  $D_8$ . The possible holonomies are 1,  $\mathbb{Z}_2$  and  $\mathbb{Z}_4$ . The group  $\pi$  is again an extension of  $\Delta$  by  $\mathbb{Z}$ .

Proof. Recall

$$arphi(s) = \left[ egin{array}{ccc} e^s & 0 & 0 \ 0 & e^{-s} & 0 \ 0 & 0 & 1 \end{array} 
ight].$$

The conditions on m and u in Proposition 3.3 yield

$$\mathbf{m} = \begin{bmatrix} 0 \\ 0 \\ m \end{bmatrix}, \quad \mathbf{u} = \begin{bmatrix} u_1 \\ u_2 \\ 0 \end{bmatrix}.$$

Examining the first condition there, we find

$$\operatorname{Aut}(\operatorname{Sol}^3 \times \mathbb{R}) = \mathbb{R}^3 \rtimes ((\mathbb{R}^*)^3 \rtimes \mathbb{Z}_2)$$

corresponds to the following matrices:

$$\begin{bmatrix} p_{11} & 0 & 0 & 0 & u_1 \\ 0 & p_{22} & 0 & 0 & u_2 \\ 0 & 0 & p_{33} & m & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}, \qquad \begin{bmatrix} 0 & 1 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

where  $(u_1, u_2, m) \in \mathbb{R}^3$ ,  $(p_{11}, p_{22}, p_{33}) \in (\mathbb{R}^*)^3$ , respectively. The maximal compact subgroup is  $D_8 \times \mathbb{Z}_2$  generated by

$$\begin{bmatrix} \pm 1 & 0 & 0 & 0 & 0 \\ 0 & \pm 1 & 0 & 0 & 0 \\ 0 & 0 & \pm 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}, \qquad \begin{bmatrix} 0 & 1 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}.$$

The factor  $\mathbb{Z}_2$  is generated by -1 on (3,3)-slot. Every element of the dihedral group has fixed point on  $\mathrm{Sol}^3$ . For a cyclic subgroup, one can resolve the fixed point by advancing to the  $\mathbb{R}$ -direction ((3,5)-slot) so that finite power generates a lattice of  $\mathbb{R}$ . The cyclic subgroup  $\Phi$  is either trivial,  $\mathbb{Z}_2$  or  $\mathbb{Z}_4$ . The extended group  $\pi$  fits the short exact sequence

$$1 \to \Delta \rtimes \mathbb{Z} \to \pi \to \Phi \to 1$$
.

Note that  $\pi/\Delta \cong \mathbb{Z}$  also.

**Theorem 3.5.** (1) The group of isometries of  $\operatorname{Sol}_{\lambda}^4$  is  $\operatorname{Sol}_{\lambda}^4 \rtimes (\mathbb{Z}_2)^3$ . (2) The only infra-solvmanifolds modeled on  $\operatorname{Sol}_{m,n}^4$  are solvmanifolds  $\Gamma \backslash \operatorname{Sol}_{m,n}^4$  for some lattice  $\Gamma$ .

Proof. Recall

$$\varphi(s) = \left[ \begin{array}{ccc} e^{\lambda s} & 0 & 0 \\ 0 & e^{s}0 & \\ 0 & 0 & e^{-(1+\lambda)s} \end{array} \right].$$

The conditions on m and u in Proposition 3.3 yield

$$\mathbf{m} = egin{bmatrix} 0 \ 0 \ 0 \ \end{pmatrix}, \quad \mathbf{u} = egin{bmatrix} u_1 \ u_2 \ u_3 \ \end{pmatrix}.$$

Examining the first condition there, we find

$$\operatorname{Aut}(\operatorname{Sol}^4) = \mathbb{R}^3 \rtimes (\mathbb{R}^*)^3$$

corresponds to the following matrices:

$$\begin{bmatrix} p_{11} & 0 & 0 & 0 & u_1 \\ 0 & p_{22} & 0 & 0 & u_2 \\ 0 & 0 & p_{33} & 0 & u_3 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

where  $(u_1, u_2, u_3) \in \mathbb{R}^3$ ,  $(p_{11}, p_{22}, p_{33}) \in (\mathbb{R}^*)^3$ , respectively. The maximal compact subgroup is the diagonal matrices  $(\mathbb{Z}_2)^3$  in  $(\mathbb{R}^*)^3$ .

Clearly, then an element of  $\operatorname{Aut}(\mathbb{R}^3 \rtimes_{\varphi} \mathbb{R})$  is torsion if and only if it is of the form

$$\alpha = \begin{bmatrix} \epsilon & 0 & \mathbf{x} \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \text{ where } \epsilon = \begin{bmatrix} \pm 1 & 0 & 0 \\ 0 & \pm 1 & 0 \\ 0 & 0 & \pm 1 \end{bmatrix}$$

satisfying

$$(I + \epsilon)\mathbf{x} = 0.$$

Consequently, such a torsion element lies in  $(\mathbb{R}^3 \rtimes_{\varphi} \mathbb{R}) \rtimes (\mathbb{Z}_2)^3$ .

Now we specialize to the case where  $\operatorname{Sol}_{\lambda}^4 = \operatorname{Sol}_{m,n}^4$ . We claim that  $\alpha$  cannot leave any lattice  $\Gamma$  invariant. [Therefore, there cannot exist a finite extension of  $\Gamma$ ]. Since  $\mathbb{R}^3$  is a nil-radical of our group,

$$Z = \Gamma \cap \mathbb{R}^3$$

is a lattice of  $\mathbb{R}^3$ , and is a characteristic subgroup of  $\Gamma$ . See, [10, Corollary 3.5]. Thus,  $\alpha$  should leave Z invariant as well. Let

$$\mathbf{z} = \begin{bmatrix} 1 & 0 & z \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \in Z.$$

Then

$$(\alpha \mathbf{z} \alpha^{-1}) \mathbf{z}^{-1} = (\epsilon - I) \mathbf{z}.$$

Therefore, for  $\mathbf{z} \in \mathbb{Z}$ , we must have

$$(\epsilon - I)\mathbf{z}, \ (\epsilon + I)\mathbf{z} \in Z.$$

Recall that  $\epsilon$  was a diagonal matrix with entries  $\pm 1$ 's. Unless  $\epsilon = I$ , at least one axis contains a subgroup  $\mathbb{Z}$  of Z. This is not possible because each of the 3 axes is an eigenspace of  $\varphi(s)$ ;  $\epsilon$  should conjugate this  $\mathbb{Z}$  onto itself, but  $\varphi(s)$ 

does not have eigenvalue 1. This completes the proof that any lattice  $\Gamma$  does not have an extension by a finite group.

#### 4. The first Bieberbach Theorem

**Statement 4.1.** Let G be a connected, simply connected Lie group and let K be a compact subgroup of  $\operatorname{Aut}(G)$ . Suppose  $\pi \subset G \rtimes K$  is a lattice, then  $\Gamma = \pi \cap G$  is a lattice of G (and  $\Gamma$  has finite index in  $\pi$ ).

The first Bieberbach Theorem states that Statement 4.1 holds for  $G = \mathbb{R}^n$ . This was generalized to nilpotent Lie groups by L. Auslander, [1] and [2]. Statement 4.1 was further generalized to some solvable Lie groups, see [6]. Using the results in [6], we can see easily that the first Bieberbach Theorem holds for all the Lie groups  $\mathbb{R}^3 \rtimes_{\wp} \mathbb{R}$  except for  $\mathrm{Sol}_0^6$ .

**Theorem 4.2.** [6, Theorem B] Let G be a connected, simply connected solvable Lie group of type (E) with nil-radical N, and let  $G/N = \mathbb{R}^n$ . Let  $\rho : \mathbb{R}^n \to Out(N)$  be the canonical representation. Assume:

The centralizer of  $\rho(\mathbb{R}^n)$  in Out(N) has trivial maximal torus. Then Statement 4.1 holds for this G.

The condition (3–1) indicates that, unless  $\varphi(s)$  has two dimensional eigenspace,  $\widehat{\theta}$  cannot contain a circle. Thus, except for  $G = \operatorname{Sol}_0^4$ , Statement 4.1 holds for all other solvable G's. (Thus, if there is no lattice in G, then there is no compact form in  $\operatorname{Isom}(G)$  either).

**Theorem 4.3.** For the group  $G = \operatorname{Sol}_0^4$ ,

- (1) The group of isometries is  $\text{Isom}_0(G) = G \rtimes (O(2) \times O(1))$ .
- (2) There is no lattice in G.
- (3) There are countably infinite distinct lattices in  $Isom_0(G)$ . Consequently, the first Bieberbach theorem does not hold for G.
- (4) For any lattice  $\Pi$  of  $\mathrm{Isom}_0(G)$ , there is no extension  $\pi \subset \mathrm{Isom}(G)$  such that the image of  $\pi$  under the natural map

$$\operatorname{Isom}(G) \longrightarrow \operatorname{Isom}(G)/\operatorname{Isom}_0(G) = \mathbb{Z}_2 \times \mathbb{Z}_2$$

is non-trivial.

*Proof.* With the conditions in Proposition 3.3, we get

$$\operatorname{Aut}(\operatorname{Sol}_0^4) = \operatorname{Sol}_0^4 \rtimes (\operatorname{GL}(2,\mathbb{R}) \times \operatorname{GL}(1,\mathbb{R}))$$

where  $GL(2,\mathbb{R}) \times GL(1,\mathbb{R})$  is generated by

$$\begin{bmatrix} p_{11} & p_{12} & 0 & 0 & 0 \\ p_{21} & p_{22} & 0 & 0 & 0 \\ 0 & 0 & p_{33} & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}.$$

A maximal compact subgroup is  $O(2) \times O(1)$  which is of the form

$$\begin{bmatrix} p_{11} & p_{12} \\ p_{21} & p_{22} \end{bmatrix} \in O(2), \qquad p_{33} = \pm 1 \in O(1)$$

in the above matrix representation. Then with the best left-invariant Riemannian metric on G, we have

$$\mathrm{Isom}(G) = G \rtimes (O(2) \times O(1)) \subset \mathrm{Aut}(G).$$

We shall find a lattice  $\Pi$  of  $\mathrm{Isom}_0(G) = G \rtimes \mathrm{SO}(2)$ . As noted before,  $\mathbb{R}^3$  is the nil-radical of G, so  $\Pi \cap \mathbb{R}^3 = \mathbb{Z}^3$  must be a lattice in  $\mathbb{R}^3$ . Thus  $\Pi$  is of the form  $\mathbb{Z}^3 \rtimes_A \mathbb{Z}$ , where the generator  $1 \in \mathbb{Z}$  acts on  $\mathbb{Z}^3$  by  $A \in \mathrm{GL}(3,\mathbb{Z})$ . Consider the commutative diagram

$$1 \longrightarrow \mathbb{Z}^{3} \longrightarrow \mathbb{Z}^{3} \rtimes_{A}\mathbb{Z} \longrightarrow \mathbb{Z} \longrightarrow 1$$

$$\downarrow \qquad \qquad \downarrow \qquad \qquad \downarrow$$

$$1 \longrightarrow \mathbb{R}^{3} \longrightarrow \mathbb{R}^{3} \rtimes_{\alpha}(\mathbb{R} \times SO(2)) \longrightarrow \mathbb{R} \times SO(2) \longrightarrow 1$$

Since  $\mathbb{Z}^3 \rtimes_A \mathbb{Z} \hookrightarrow \mathbb{R}^3 \rtimes_{\varphi} (\mathbb{R} \times SO(2))$ , there exists a matrix  $P \in GL(3,\mathbb{R})$  so that

$$A' \equiv PAP^{-1} = \begin{bmatrix} e^{\alpha} & 0 & 0 \\ 0 & e^{\alpha} & 0 \\ 0 & 0 & e^{-2\alpha} \end{bmatrix} \begin{bmatrix} \cos \beta & \sin \beta & 0 \\ -\sin \beta & \cos \beta & 0 \\ 0 & 0 & 1 \end{bmatrix}$$
$$= \begin{bmatrix} e^{\alpha} \cos \beta & e^{\alpha} \sin \beta & 0 \\ -e^{\alpha} \sin \beta & e^{\alpha} \cos \beta & 0 \\ 0 & 0 & e^{-2\alpha} \end{bmatrix}$$

for some  $\alpha, \beta \in \mathbb{R}$ . The vertical maps are

and  $(\alpha n, e^{i\beta n})$  acts on  $P\mathbf{z}$  by  $PA^nP^{-1}$ . Let

$$\chi_A(x) = x^3 - mx^2 + nx - 1$$

be the characteristic polynomial of A (so  $m, n \in \mathbb{Z}$ ). Since A is conjugate to A', they have the same characteristic polynomial. Thus,  $\chi_A(x) = 0$  must have only *one* (positive) real root.

Conversely, suppose  $x^3 - mx^2 + nx - 1 = 0$  has only one positive real root so that

$$x^3 - mx^2 + nx - 1 = (x - a)((x - b)^2 + c^2)$$

for some real a > 0, b and  $c \neq 0$ . Then

$$a(b^2 + c^2) = 1.$$

Therefore, if we set  $a = e^{-2\alpha}$ , then

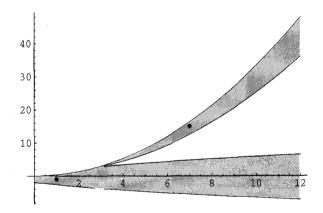
$$b = e^{\alpha} \cos \beta$$
$$c = e^{\alpha} \sin \beta$$

for some  $\beta$ .

Since  $\chi_A(0) = -1$  and  $\lim_{x\to\infty} = +\infty$ , by intermediate value theorem, the condition having a positive real root is automatic. That is, there always exists one positive real root. Therefore, the following are equivalent:

- (1)  $\chi_{A'}(x) = \chi_A(x)$  (=  $x^3 mx^2 + nx 1$ ) (2)  $\chi_A(x) = 0$  has only one (positive) real root
- (3) (a)  $m^2 > 3n$  and  $\chi_A(\frac{1}{3}(m + \sqrt{m^2 3n})) > 0$ , or (b)  $m^2 > 3n$  and  $\chi_A(\frac{1}{3}(m \sqrt{m^2 3n})) < 0$ .

(Observe that  $\frac{1}{3}(m \pm \sqrt{m^2 - 3n})$  are the two critical points of  $\chi_A(x)$ ). All the integer points in the region containing (7,15) in the picture satisfy the first inequalities (3a). All the integer points in the region containing (1,-1)surrounded by the 3 curves together with x > 0 in the picture satisfy the second inequalities (3b). We can easily see that there are infinitely many pairs (m, n)



of integers which satisfy the above inequalities. Then

$$m = e^{-2\alpha} + 2e^{\alpha} \cos \beta$$
$$n = e^{2\alpha} + 2e^{-\alpha} \cos \beta$$

which determines  $\alpha$  and  $\beta$ . For example, if (m,n)=(7,15), we get

$$\alpha = -\frac{1}{2} \ln \left[ \frac{1}{3} \left\{ 4 - \left( \frac{2}{\omega} \right)^{\frac{1}{3}} - \left( \frac{\omega}{2} \right)^{\frac{1}{3}} \right\} \right],$$

where  $\omega = 25 - 3\sqrt{69}$ . Thus,  $\alpha \approx 0.702999$  and  $\beta \approx 0.929517$  (thus, the pair (m,n) determines  $\alpha$  and  $\beta$ ). Since we already know G does not have a lattice, the intersection  $(\mathbb{Z}^3 \rtimes_{A'} \mathbb{Z}) \cap G$  cannot be a lattice of G.

Different values of (m, n) yield different lattices of G. There are countably infinite distinct lattices in G. The  $\mathbb{Z}$ -factor of the lattice  $H = \mathbb{Z}^3 \rtimes \mathbb{Z}$  is embedded as  $\varphi(n)$ ,  $n \in \mathbb{Z}$ , where

$$\varphi(s) = \begin{bmatrix} e^{\alpha s} \cos(\beta s) & e^{\alpha s} \sin(\beta s) & 0 & 0 & 0\\ -e^{\alpha s} \sin(\beta s) & e^{\alpha s} \cos(\beta s) & 0 & 0 & 0\\ 0 & 0 & e^{-2\alpha s} & 0 & 0\\ 0 & 0 & 0 & 1 & s\\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}.$$

Suppose there exists  $\pi \subset \text{Isom}(G)$  so that the commutative diagram of exact rows commute:

The following are generators of  $\mathbb{Z}_2 \times \mathbb{Z}_2$ :

$$B_1 = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}, \quad B_2 = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}.$$

The equality

$$\begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} e^{\alpha s} \cos(\beta s) & e^{\alpha s} \sin(\beta s) & 0 \\ -e^{\alpha s} \sin(\beta s) & e^{\alpha s} \cos(\beta s) & 0 \\ 0 & 0 & e^{-2\alpha s} \end{bmatrix} \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}^{-1}$$
$$= \begin{bmatrix} e^{\alpha s} \cos(\beta s) & -e^{\alpha s} \sin(\beta s) & 0 \\ e^{\alpha s} \sin(\beta s) & e^{\alpha s} \cos(\beta s) & 0 \\ 0 & 0 & e^{-2\alpha s} \end{bmatrix}$$

shows that  $B_1$  does not normalize  $\Pi$ . For  $B_2$ , suppose it normalized  $\Pi$ . Then it will normalize  $\mathbb{Z}^3$  since it is a characteristic subgroup. Let

$$\mathbf{z} = \begin{bmatrix} 1 & 0 & 0 & 0 & z_1 \\ 0 & 1 & 0 & 0 & z_2 \\ 0 & 0 & 1 & 0 & z_3 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix} \in P\mathbb{Z}^3.$$

We denote **z** by  $(z_1, z_2, z_3)$ . Then

$$B_2(z_1, z_2, z_3)B_2^{-1} = (z_1, z_2, -z_3).$$

This implies

$$(0,0,2z_3) = (z_1,z_2,z_3) \left( B_2(z_1,z_2,z_3) B_2^{-1} \right)^{-1} \in P\mathbb{Z}^3.$$

This is impossible since the 3rd axis is an eigenspace of A' with eigenvalue  $e^{-2a}$  with a > 0, (a lattice cannot be expanded or shrunk by its automorphism).

Consequently, there is no extension of  $\Pi$  by any subgroup of  $\mathbb{Z}_2 \times \mathbb{Z}_2$ .

Remark 4.4. This is the lowest dimensional example of a solvable Lie group of type (R) where the first Bieberbach theorem fails. There was a 5-dimensional example in [6, Example 3.2]. In both cases, the existence of a compact subgroup SO(2) of Aut(G) is essential, as it was a necessary condition for the failure. See Theorem 4.2. There exists a 3-dimensional example which is not of type (E), see below.

Since  $\mathbb{R}^2$  is the only 2-dimensional simply connected solvable Lie group, we need to check only 3-dimensional Lie groups. Suppose G is a 3-dimensional simply connected solvable Lie group. Obviously, the nil-radical of G cannot be 1-dimensional. If it is 3-dimensional, G itself is nilpotent, and we know Statement 4.1 holds for nilpotent groups. Now suppose the nil-radical of G is 2-dimensional. Then G is of the form  $\mathbb{R}^2 \rtimes_{\mathcal{G}} \mathbb{R}$  (and its Lie algebra must be of the form  $\mathbb{R}^2 \rtimes_{\mathcal{G}} \mathbb{R}$ ). If G is of type (R), possible A's are

$$\mathcal{A} = \begin{bmatrix} \lambda & 0 \\ 0 & \lambda \end{bmatrix}, \quad \begin{bmatrix} \lambda & c \\ 0 & \lambda \end{bmatrix}, \quad \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix}.$$

For this to have a lattice, the trace must be 0. Then the first case yields G abelian, the second case yields G nilpotent, while the third case  $(\lambda_1 + \lambda_2 = 0)$  yields G the 3-dimensional Sol. Note that the first Bieberbach theorem holds for all these cases. Thus the group  $G = \operatorname{Sol}_0^4$  in Theorem 4.3 is the lowest dimensional example of a solvable Lie group of type (R) where the first Bieberbach theorem fails.

On the other hand, consider the universal covering group G of  $E_2(2) = \mathbb{R}^2 \rtimes \mathrm{SO}(2)$ . So, G is isomorphic to  $\mathbb{R}^2 \rtimes_{\varphi} \mathbb{R}$ , where  $\varphi(t) = \begin{bmatrix} \cos 2\pi t & \sin 2\pi t \\ -\sin 2\pi t & \cos 2\pi t \end{bmatrix}$ . (This is where the  $\mathcal{A} = \psi(1)$  above is  $\mathcal{A} = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$ ). Aut(G) contains SO(2).

Now consider the subgroup of  $G \times SO(2) = (\mathbb{R}^2 \times \mathbb{R}) \times SO(2)$  generated by

$$\left(\begin{bmatrix}1\\0\end{bmatrix},0,I\right),\left(\begin{bmatrix}0\\1\end{bmatrix},0,I\right),\left(\begin{bmatrix}0\\0\end{bmatrix},\alpha,\varphi(-\alpha)\right),$$

where  $\alpha$  is an irrational number. Clearly, this group  $\Gamma$  is isomorphic to  $\mathbb{Z}^3$ , but  $\Gamma \cap G$  is just  $\mathbb{Z}^2$ , violating the first Bieberbach theorem. Note that this G is not of type (E).

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