DERIVATIONS ON SUBRINGS OF MATRIX RINGS

JANG-HO CHUN AND JUNE-WON PARK

ABSTRACT. For a lower niltriangular matrix ring $A = NT_n(K)$ $(n \geq 3)$, we show that every derivation of A is a sum of certain diagonal, trivial extension and strongly nilpotent derivation. Moreover, a strongly nilpotent derivation is a sum of an inner derivation and an uaz-derivation.

1. Introduction

Let $NT_n(K)$ $(n \geq 3)$ be the ring of all (lower niltriangular) $n \times n$ matrices over an associative ring with identity K which are all zeros on and above the main diagonal.

It is well-known(see [4], p.100) that if F is a field, then any F-derivation of $M_n(F)$ is inner. Moreover, Amitsur [1] showed that any derivation of $M_n(K)$ is a sum of an inner derivation and a trivial extension and Nowicki [8] characterized derivations of special subrings of $M_n(K)$.

Dubish and Perlis [3] classified automorphisms on $NT_n(F)$ over a field F. Every automorphism on $NT_n(F)$ is equal to a product of certain diagonal automorphism, inner automorphism and nil automorphism. Moreover, Levchuk ([6], [7]) characterized automorphisms of $NT_n(K)$ and Kuzucuoglu and Levchuk [5] characterized automorphisms on $R_n(K, J) = NT_n(K) + M_n(J)$.

In this paper, we will characterize derivations of $NT_n(K)$. In section 2, we characterize ideals and characteristic ideals of $NT_n(K)$. In section 3, we show that for a derivation δ on $NT_n(K)$, $\delta = i_d + \bar{\sigma} + s_t$ where i_d is a diagonal inner, $\bar{\sigma}$ is a trivial extension of K and s_t is a strongly nilpotent derivation. In section 4, we have that for a strongly

Received November 21, 2005.

²⁰⁰⁰ Mathematics Subject Classification: 16S32, 16D25.

Key words and phrases: derivations, diagonal derivations, strongly nilpotent derivations, inner derivations.

nilpotent derivation s_t , $s_t = s_i + s_{uaz}$ where s_i is an inner derivation and s_{uaz} is an uaz-derivation. Moreover, we characterize the difference between uaz-derivations and az-derivations.

For a ring R, not necessarily contains 1, a derivation δ is an additive map on R which satisfies

$$\delta(ab) = \delta(a)b + a\delta(b)$$
 $(a, b \in R)$.

We say that δ is an inner derivation if there exist $r \in R$ such that $\delta(x) = rx - xr$ for all $x \in R$.

For the convenience we have the followings:

- (1) $NT_n(K) \equiv A_n \equiv A$.
- (2) e_{ij} : matrix units of $M_n(K)$.
- (3) A^k : k-th product of A.
- (4) Any derivation σ of K can be extended to A by putting

$$\bar{\sigma}(\sum_{i>j}r_{ij}e_{ij}) = \sum_{i>j}\sigma(r_{ij})e_{ij} \qquad (r_{ij}\in K).$$

It is easy to show that $\bar{\sigma}$ is also a derivation of A. We call $\bar{\sigma}$ a trivial extension of σ .

- (5) Let B_n be the set of all matrices in $M_n(K)$ with zeros above the diagonal. Then each diagonal matrix $d = \sum d_i e_{ii} (d_i \in K)$ determines a derivation $i_d(x) = [d, x]$ of B_n and the derivation i_d induces on A. We call i_d a diagonal derivation.
- (6) Since we can regard A as a K-module, we define a K-derivation on A by $\delta(rx) = r\delta(x) (r \in K, x \in A)$.
 - (7) For all $x \in A$, we denote $\{x\}_{ij} = \pi_{ij}(x)$.

2. Ideals of A

The ideals of $NT_n(F)$ are characterized in Dubisch and Perlis [3], which are referred to "staircase open polygon". Also, the ideals of A can be regarded similarly. But we characterize ideals of A another way. For any subset H of A, trivially $\sum \pi_{ij}(H)e_{ij} \supseteq H$. If $H = \sum \pi_{ij}(H)e_{ij}$, we call H a direct subset of A.

PROPOSITION 2.1. Let H be a subset of A. If H is an ideal of A, then the followings hold;

(1) $\pi_{ij}(H)$ is a subgroup of K.

- (2) For all s > i, $\pi_{sj}(H) \supseteq K\pi_{ij}(H)$.
- (3) For all t < j, $\pi_{it}(H) \supseteq \pi_{ij}(H)K$.

Conversely, if H is a direct subset of A and satisfies above (1), (2) and (3), then H is an ideal of A.

Proof. The proof of the first statement is obvious. Conversely, by (2)

$$\pi_{ij}(NT_n(K)H) = \sum_{\lambda=1}^n \pi_{i\lambda}(NT_n(K))\pi_{\lambda j}(H)$$

$$= \sum_{\lambda=j+1}^{i-1} \pi_{i\lambda}(NT_n(K))\pi_{\lambda j}(H)$$

$$= \sum_{\lambda=j+1}^{i-1} K\pi_{\lambda j}(H) = K\pi_{i-1,j}(H) \subseteq \pi_{ij}(H).$$

Thus, by $\sum \pi_{ij}(H)e_{ij} = H$, $NT_n(K)H \subseteq H$, that is, $AH \subseteq H$. Similarly, by (3) and $\sum \pi_{ij}(H)e_{ij} = H$, $HA \subseteq H$. Therefore, H is an ideal of A.

Next example shows that an ideal of A is not necessarily direct and for noetherian ring K, A is not noetherian in general.

EXAMPLE 2.2. For the rational number field **Q** and the ring of integers **Z**, let $K = M_2(\mathbf{Q})$ and $A = NT_3(K)$. Denote $f_{ij}(i, j = 1, 2)$ by matrix units of $M_2(\mathbf{Q})$. Set

$$H_k = \left\{ \begin{pmatrix} 0 & 0 & 0 \\ \frac{n}{2^k} f_{21} & 0 & 0 \\ T & \frac{n}{2^k} f_{21} & 0 \end{pmatrix} \middle| n \in \mathbf{Z} \right\}, \qquad k = 1, 2, \dots$$

where $T = \mathbf{Q}f_{11} + \mathbf{Q}f_{21} + \mathbf{Q}f_{22}$. Then we have the following properties;

- (1) H_k are ideals but not direct.
- (2) T is not an ideal of K.
- (3) For a trivial extension δ of an inner derivation of K, H_k is not invariant in general.
- (4) K is noetherian. But since $H_1 \subsetneq H_2 \subsetneq H_3 \subsetneq \cdots, A$ is not noetherian.

DEFINITION 2.3. Let C be a subring of a ring R. C is called characteristic if every derivation δ on R induces a derivation on C.

Obviously for k(1 < k < n), the k-th powers A^k are characteristic ideals of A.

For $x \in A$, it is important to find characteristic ideals of A which contains $\delta(x)$. We introduce certain characteristic ideals of A which contains matrix unit $e_{ij}(i > j)$.

Let C_l be the totality of matrices in A whose columns beyond the l-th are zero. Then C_l is an ideal of A. Likewise, an ideal is given by the set R_k of all matrices in A whose first k-1 rows are zero.

PROPOSITION 2.4 [3]. C_l is the left annihilator of A^l and R_k is the right annihilator of A^k .

THEOREM 2.5. C_l and R_k are characteristic ideals. Moreover, for each derivation δ on A and each matrix unit $e_{kl} \in A$, $\delta(e_{kl}) \in C_l \cap R_k$.

Proof. For arbitrary derivation δ of A, let $c \in C_l$ and $x \in A^l$. Then by Proposition 2.4

$$0 = \delta(cx) = \delta(c)x + c\delta(x).$$

Since A^l is a characteristic ideal $\delta(x) \in A^l$ and $c\delta(x) = 0$. So, $\delta(c)x = 0$. This means $\delta(c)A^l = 0$. Thus $\delta(c) \in C_l$. Therefore C_l is a characteristic ideal.

Similarly, R_k is a characteristic ideal.

Moreover,
$$e_{kl} \in C_l \cap R_k$$
. So $\delta(e_{kl}) \in C_l \cap R_k$.

From the Theorem 2.5, $\delta(e_{kl}) \in C_l \cap R_k$. So we have the following;

(*)
$$\delta(e_{k,k-1}) = \sum_{i \ge k} \sum_{j \le k-1} \beta_{ij}^{(k)} e_{ij}, \qquad \beta_{ij}^{(k)} \in K.$$

Now we characterize the characteristic ideals of A

THEOREM 2.6. Let H be a characteristic ideal of A. Then the followings hold;

- (1) $\pi_{ij}(H)$ is an ideal of K.
- (2) H is direct.
- (3) $\pi_{ij}(H)$ is a characteristic ideal of K.

Proof. (1) For $r \in K$, let i_d be a diagonal derivation induced by $d = re_{ii}$, that is, $i_d(x) = dx - xd$ for all $x \in A$. Then

$$r\pi_{ij}(H) = \pi_{ij}(rH) = \pi_{ij}([d, H]) = \pi_{ij}(i_d(H)) \subseteq \pi_{ij}(H).$$

So, $\pi_{ij}(H)$ is a left ideal of K.

To show that $\pi_{ij}(H)$ is a right ideal, take $d = -re_{ij}$. Then

$$\pi_{ij}(H)r = \pi_{ij}(Hr) = \pi_{ij}([d, H]) = \pi_{ij}(i_d(H)) \subseteq \pi_{ij}(H).$$

So, $\pi_{ij}(H)$ is a right ideal of K. Therefore, $\pi_{ij}(H)$ is an ideal of K. (2) Since H is a characteristic ideal,

$$[-e_{jj}, [e_{ii}, H]] = \pi_{ij}(H)e_{ij} \subseteq H.$$

So, $\sum \pi_{ij}(H)e_{ij} \subseteq H$, that is, $\sum \pi_{ij}(H)e_{ij} = H$.

(3) Let σ be a derivation of K. Then trivial extension $\bar{\sigma}$ of σ is a derivation of A. So, $\bar{\sigma}(H) \subseteq H$. Thus, $\sigma(\pi_{ij}(H)) \subseteq \pi_{ij}(H)$. Therefore, $\pi_{ij}(H)$ is a characteristic ideal.

COROLLARY 2.7. Let H be a characteristic ideal of A. If $\pi_{ij}(H) = K$ or 0, then H is generated by $C_{l_1} \cap R_{k_1}, C_{l_2} \cap R_{k_2}, \ldots, C_{l_t} \cap R_{k_t}$.

3. Characterizations of derivations

Since A is a free K-module with basis $\{e_{ij}\}(i>j)$, derivations of A highly depends on the image of e_{ij} . Every K-module derivation of A is determined by the image of e_{ij} , but in general every derivation of A is not determined by the image of e_{ij} . However, we get a useful lemma which says that for any derivation δ of $\{\delta(e_{ij})\}_{ij} = 0$, the coordinate function of δ is also a derivation of K.

LEMMA 3.1. Suppose δ is a derivation of A and $\{\delta(e_{ij})\}_{ij} = 0$ for all i > j. Define the coordinate function $\delta_{ij} : K \longrightarrow K$ such that $\delta_{ij}(r) = \{\delta(re_{ij})\}_{ij} (r \in K)$. Then $\delta_{ij} = \delta_{21}$ and δ_{ij} is a derivation of K.

Proof. For $r \in K$, we get

$$\delta_{31}(r) = \{\delta(re_{31})\}_{31} = \{\delta(re_{32}e_{21})\}_{31}$$

$$= \{\delta(re_{32})e_{21} + re_{32}\delta(e_{21})\}_{31}$$

$$= \{\delta(re_{32})e_{21}\}_{31}$$

$$= \{\delta_{32}(r)e_{31}\}_{31} = \delta_{32}(r).$$

On the other hand,

$$\delta_{31}(r) = \{\delta(re_{31})\}_{31} = \{\delta(re_{32}e_{21})\}_{31} = \{\delta(e_{32}re_{21})\}_{31}$$
$$= \{\delta(e_{32})re_{21} + e_{32}\delta(re_{21})\}_{31} = \{\delta_{21}(r)e_{31}\}_{31}$$
$$= \delta_{21}(r).$$

Hence, $\delta_{32} = \delta_{21}$. Similarly, we can show that for $4 \leq k \leq n$, $\delta_{k,k-1} = \delta_{21}$.

If $i - j \geq 2$,

$$\delta_{ij}(r) = \{\delta(re_{ij})\}_{ij} = \{\delta(re_{i,i-1} \cdots e_{j+1,j})\}_{ij}$$
$$= \{\delta_{i,i-1}(r)e_{ij}\}_{ij} = \delta_{i,i-1}(r).$$

Therefore, for all i > j, $\delta_{ij} = \delta_{21}(i > j)$.

Now we will show that δ_{31} is a derivation of K. For arbitrary $r, r' \in K$,

$$\delta_{31}(rr') = \{\delta(rr'e_{31})\}_{31} = \{\delta(re_{32}r'e_{21})\}_{31}$$

$$= \{\delta(re_{32})r'e_{21} + re_{32}\delta(r'e_{21})\}_{31}$$

$$= \{\delta(re_{32})\}_{32}r' + r\{\delta(r'e_{21})\}_{21}$$

$$= \delta_{32}(r)r' + r\delta_{21}(r') = \delta_{31}(r)r' + r\delta_{31}(r).$$

So, δ_{31} is a derivation of K. This means δ_{ij} is a derivation of K.

COROLLARY 3.2. Suppose that δ, δ' are derivations of A satisfying $\{\delta(e_{ij})\}_{ij} = \{\delta'(e_{ij})\}_{ij}$ for all i > j. Then $\delta_{ij} - \delta'_{ij} = \delta_{21} - \delta'_{21}$ and $\delta_{ij} - \delta'_{ij}$ is a derivation of K.

COROLLARY 3.3. Let $\delta_{ij}: K \longrightarrow K(i > j)$ be derivations. Define $\delta: A \longrightarrow A$ by $\delta(\sum_{i>j} r_{ij}e_{ij}) = \sum_{i>j} \delta_{ij}(r_{ij})e_{ij}$. If δ is a derivation of A, then for all i > j, $\delta_{ij} = \delta_{21}$.

Proof. Since $\delta(e_{ij}) = 0$, $\{\delta(e_{ij})\}_{ij} = 0$. And for all $r \in K$, $\delta_{ij}(r) = \{\delta(re_{ij})\}_{ij}$. So, by Lemma 3.1, $\delta_{ij} = \delta_{21}$.

Lemma 3.4. If δ is a diagonal derivation of A. Then

- (1) $\delta(e_{k,k-1}) = \alpha_k e_{k,k-1}$, where $\alpha_k \in K$ and $2 \le k \le n$.
- (2) $\delta(e_{kl}) = \alpha_{kl}e_{kl}$, where $\alpha_{kl} = \alpha_k + \alpha_{k-1} + \cdots + \alpha_{l+1}$.

Conversely, if δ is a derivation of A satisfying (1) and (2), then $(\delta - i_d)(e_{kl}) = 0$, where i_d is a diagonal derivation induced by $d = \alpha_2 e_{22} + \cdots + (\alpha_2 + \cdots + \alpha_n)e_{nn}$.

Proof. The proof of the first statement is obvious. Conversely, for all k > l,

$$i_d(e_{kl}) = de_{kl} - e_{kl}d$$

$$= (\alpha_2 + \dots + \alpha_k)e_{kl} - (\alpha_2 + \dots + \alpha_l)e_{kl}$$

$$= (\alpha_k + \dots + \alpha_{l+1})e_{kl}.$$

So,
$$(\delta - i_d)(e_{kl}) = 0$$
.

Lemma 3.5. Let δ be a derivation on A. Then there exists a diagonal derivation i_d such that $\{(\delta - i_d)(e_{ij})\}_{ij} = 0$.

Proof. The quantities $\delta(e_{k,k-1}), \ldots, \delta(e_{l+1,l})$ can be denoted as equations (*) in section 2 with corner coefficients $\beta_{k,k-1}^{(k)} \equiv \alpha_k, \dots, \beta_{l+1,l}^{(l+1)} \equiv$ α_{l+1} . By multiplying the equations, we find that

$$\delta(e_{kl}) = \sum_{i>k} \sum_{j< l} \beta_{ij}^{(kl)} e_{ij} \qquad (\beta_{ij}^{(kl)} \in K)$$

with corner coefficients $\beta_{kl}^{(kl)} \equiv \alpha_{kl} = \alpha_k + \alpha_{k-1} + \cdots + \alpha_{l+1}$. The quantities α_l, α_{kl} thus fulfill the conditions (1) and (2) of Lemma 3.4. So, the correspondence $e_{kl} \mapsto \alpha_{kl} e_{kl}$ generates a diagonal derivation i_d such that $\{\delta(e_{ij})\}_{ij} = \{i_d(e_{ij})\}_{ij}$, that is, $\{(\delta - i_d)(e_{ij})\}_{ij} = 0.\square$

Definition 3.6. Let s_t be a derivation on A. s_t is called a strongly nilpotent derivation if for all $x \in A^k$, $s_t(x) \in A^{k+1}$.

Obviously every strongly nilpotent derivation of A is nilpotent and every inner derivation of A is strongly nilpotent.

Proposition 3.7. Suppose that δ is a derivation on A such that $\{\delta(e_{ij})\}_{ij}=0$ for all i>j. Then there exists a trivial extension $\bar{\sigma}$ of A such that $\delta - \bar{\sigma}$ is strongly nilpotent.

Proof. By Lemma 3.1, it is obvious.
$$\Box$$

Theorem 3.8. Let δ be a derivation of A. Then $\delta = i_d + \bar{\sigma} + s_t$ where i_d is a diagonal inner, $\bar{\sigma}$ is a trivial extension of K and s_t is a strongly nilpotent derivation.

Proof. By Lemma 3.5, there exists a diagonal derivation i_d such that $\{(\delta - i_d)(e_{ij})\}_{ij} = 0$. And by Proposition 3.7, there exists a trivial extension $\bar{\sigma}$ of A such that $(\delta - i_d) - \bar{\sigma}$ is strongly nilpotent.

4. uaz- derivations of A

Matrix units $e_{21}, e_{31}, \ldots, e_{n1}$ are left annihilators of A and matrix units $e_{n1}, e_{n2}, \ldots, e_{n,n-1}$ are right annihilators of A. There exist derivations that the images of these matrix units are zero. These derivations are important role to characterize strongly nilpotent derivations.

DEFINITION 4.1. A strongly nilpotent derivation δ of A is called a uaz-derivation if $\delta(u) = 0$ for every matrix unit u which is an absolute left or right divisor of zero.

THEOREM 4.2. Let δ be a strongly nilpotent derivation of A. Then δ is a uaz-derivation of A if and only if $\delta(e_{k,k-1}) = \gamma_k e_{n1}(k=2,\dots,n)$ where $\gamma_2 = \gamma_n = 0$ and the remaining γ_k are arbitrary scalars.

Proof. (\iff) By the hypothesis, $\delta(e_{21}) = \delta(e_{n,n-1}) = 0$. Since δ is a derivation of A, we can get

$$\begin{split} \delta(e_{k,k-2}) &= \delta(e_{k,k-1}e_{k-1,k-2}) \\ &= \delta(e_{k,k-1})e_{k-1,k-2} + e_{k,k-1}\delta(e_{k-1,k-2}) \\ &= \gamma_k e_{n_1}e_{k-1,k-2} + e_{k,k-1}\gamma_{k-1}e_{n_1} = 0. \end{split}$$

So, $\delta(e_{kj}) = 0$ for j < k - 1. Thus, δ is a *uaz*-derivation.

 (\Longrightarrow) i) If k=2 or n, then $\gamma_2=\gamma_n=0$ by hypothesis.

ii) Assume 2 < k < n.

Since δ is a strongly nilpotent derivation, let $\delta(e_{k,k-1}) = t_k$ with $t_k \in A^2$ and $t_k \in C_{k-1} \cap R_k$ by the Theorem 2.5.

Now $0 = \delta(e_{k1}) = \delta(e_{k,k-1}e_{k-1,1}) = \delta(e_{k,k-1})e_{k-1,1} = t_k e_{k-1,1}$. So, (k-1)-th column of the matrix $t_k = 0$.

For 1 < j < k-1, $0 = \delta(e_{k,k-1}e_{j1}) = \delta(e_{k,k-1})e_{j1} = t_k e_{j1}$. So, the j-th column of $t_k = 0$ for all 1 < j < k-1.

Thus, the j-th column of $t_k = 0$ for all $1 < j \le k - 1$.

On the other hand, $0 = \delta(e_{nk}e_{k,k-1}) = e_{nk}\delta(e_{k,k-1}) = e_{nk}t_k$. So, the k-th row of $t_k = 0$. Also, for n > j > k, $0 = \delta(e_{nj}e_{k,k-1}) = e_{nj}\delta(e_{k,k-1}) = e_{nj}t_k$. So, j-th row of $t_k = 0$, for all k < j < n.

Thus, j-th row of $t_k = 0$, for all $k \ge j < n$.

Therefore, $t_k = \gamma_k e_{n1}$.

THEOREM 4.3. Let s_t be a strongly nilpotent derivation of A. Then $s_t = s_i + s_{uaz}$ where s_i is an inner derivation and s_{uaz} is a uaz-derivation.

Proof. It is enough to show that for a strongly nilpotent derivation s_t there exist an inner derivation s_i such that $s_t - s_i$ is a uaz-derivation. By (*) and the hypothesis, we can set

$$s_t(e_{k1}) = \sum_{p>k} \alpha_{pk} e_{p1} \qquad (k=2,\ldots,n-1).$$

The scalars α_{pk} are thus defined for $n \geq p > k > 1$ and $s_t(e_{k1}) =$ $(\sum_{p>q>1} \alpha_{pq} e_{pq}) e_{k1} = [a, e_{k1}], \text{ where } a = \sum_{p>q>1} \alpha_{pq} e_{pq}.$ So, the inner derivation $s_a(x) = [a, x]$ has the property $s_1 \equiv s_t - s_a$

maps e_{k1} to zero.

Since s_1 is strongly nilpotent, $s_1(e_{nk}) = \sum_{q < k} \beta_{kq} e_{nq}$. And since for all $p(1 , <math>e_{nk}e_{p1} = 0$. So, we have $0 = s_1(e_{nk}e_{p1}) = s_1(e_{nk})e_{p1} + s_1(e_{n$ $e_{nk}s_1(e_{p1}) = s_1(e_{nk})e_{p1} = (\sum_{q < k} \beta_{kq}e_{nq})e_{p1} = \beta_{kp}e_{n1}.$

It follows that the coefficients β_{kp} are zero except possibly for $\beta_{k1}(k=$ $2, \ldots, n-1$). So, $s_1(e_{nk}) = \beta_{k1}e_{n1} = e_{nk}(\sum_{j=2}^{n-1}\beta_{j1}e_{j1})$.

Let $-b = \sum_{j=2}^{n-1} \beta_{j1} e_{j1}$. Then the inner derivation $s_b(x) = [b, x]$ has the property $(s_1 - s_b)e_{nl} = 0(l = 1, ..., n - 1)$ and $(s_1 - s_b)e_{k1} =$ $-s_b(e_{k1}) = 0 (k = 2, ..., n).$

Therefore, $s_1 - s_b = s_t - (s_a + s_b)$ is a uaz-derivation and $s_a + s_b$ is an inner derivation.

COROLLARY 4.4. Let δ be a derivation of A. Then $\delta = i_d + \bar{\sigma} + s_i + \bar{\sigma} + \bar$ s_{uaz} where i_d is a diagonal inner, $\bar{\sigma}$ is a trivial extension of K, s_i is an inner derivation and s_{uaz} is a uaz-derivation.

The left(right) annihilators of A are the quantities $e_{21}, e_{31}, \ldots, e_{n1}$ $(e_{n1}, e_{n2}, \ldots, e_{n,n-1})$ and their linear combinations.

Definition 4.5. A strongly nilpotent derivation δ of A is called an az-derivation (annihilator zero derivation) if $\delta(a) = 0$ for every absolute left or right divisor of zero a.

It is obvious that an az-derivation is a uaz-derivation. Moreover, for a K-derivation, an az-derivation is equal to a uaz-derivation.

In general, every derivation cannot be expressed as a sum of diagonal, trivial extension, inner and az-derivations. The derivation given in the next example is a uaz-derivation, but not an az-derivation.

Example 4.6. Let

$$A = \begin{pmatrix} 0 & 0 & 0 \\ \mathbf{Z}[X] & 0 & 0 \\ \mathbf{Z}[X] & \mathbf{Z}[X] & 0 \end{pmatrix}$$

where $\mathbf{Z}[X]$ is a polynomial ring over an integer \mathbf{Z} . Define $\delta: A \longrightarrow A$ by

$$\delta(\sum f_{ij}e_{ij})(i>j) = \frac{d}{dx}f_{21}e_{31}.$$

Then δ is strongly nilpotent and inner part of δ is 0, that is, δ is a uaz-derivation. But $\delta \neq az$ -derivation.

References

- [1] S. A. Amitsur, Extension of derivations to central simple algebras, Comm. Algebra 10 (1982), no. 8, 797–803.
- [2] J. H. Chun and J. W. Park, *Prime ideals of subrings of matrix rings*, Commun. Korean Math. Soc. **19** (2004), no. 2, 211–217.
- [3] R. Dubisch and S. Perlis, On total nilpotent algebra, Amer. J. Math. 73 (1951), 439–452
- [4] I. N. Herstein, Noncommutative rings, The Mathematical Association of America, 1968.
- [5] F. Kuzucuoglu and V. M. Levchuk, The automorphism group of certain radical matrix rings, J. Algebra 243 (2001), no. 2, 473-485.
- [6] V. M. Levchuk, Automorphisms of certain nilpotent matrix groups and rings, Dokl. Akad. Nauk SSSR 222 (1975), no. 6, 1279–1282.
- [7] _____, Connections between the unitriangular group and certain rings. II. Groups of automorphisms, Sibirsk. Mat. Zh. 24 (1983), no. 4, 64-80.
- [8] A. Nowicki, Derivations of special subrings of matrix rings and regular graph, Tsukuba J. Math. 7 (1983), no. 2, 281–297.

Jang-Ho Chun, Department of mathematics, Yeungnam University, Kyongsan 712-749, Korea

E-mail: jhchun@yu.ac.kr

June-Won Park, Department of mathematics, Kyungil University, Kyongsan 712-701, Korea

E-mail: jwpark@kiu.ac.kr