

## TORQUES AND RIEMANN'S MINIMAL SURFACES

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ABSTRACT. In this article, we prove that a properly embedded minimal surface in  $\mathbf{R}^3$  of genus zero must be one of Riemann's minimal examples if outside of a solid cylinder it is the union of planar ends with the same torques at all integer heights.

### 1. Introduction

An immersed surface in  $\mathbf{R}^3$  is said to be *minimal* if its mean curvature vanishes identically. In 1867, Riemann [7] used elliptic functions to classify all minimal surfaces in  $\mathbf{R}^3$  that are foliated by circles and straight lines in horizontal planes. He showed that these examples are the plane, the catenoid, the helicoid and one parameter family  $\{R_t\}_{t>0}$  with infinity topology. The new surfaces  $R_t$ , called Riemann's minimal surfaces, intersect horizontal planes in lines at precisely integer heights. We have more characterizations of  $R_t$  by:

- (a) Each  $R_t$  is invariant under the reflection of  $\mathbf{R}^3$  in the  $(x_1, x_3)$ -plane and by the translation  $T$  by  $(t, 0, 2)$ .
- (b) In the complement of a solid cylinder of  $\mathbf{R}^3$ , the surface  $R_t$  consists of planar ends at integer heights. A *planar end* means that a properly embedded finite total curvature minimal annulus with compact boundary, which is asymptotic to the end of a plane.
- (c) Each  $R_t$  is conformally equivalent to  $\mathbf{C}^* = \mathbf{C} \setminus \{0\}$  punctured in a discrete set of points with 0 and  $\infty$  being limit points of ends.
- (d) The quotient surface  $R_t/T$  is a properly embedded finite total curvature minimal torus in  $\mathbf{R}^3/T$  with two planar ends.

In 2001, the author studied the characterization problem of Riemann's minimal surfaces without assuming periodicity and showed that:

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**THEOREM 1.1.** [2] *Let  $M$  be a properly embedded minimal surface in  $\mathbf{R}^3$  of genus zero, which is the union of planar ends  $\{E_n\}_{n \in \mathbf{N}}$  outside of a solid cylinder, at integer heights. Suppose that it is symmetric by the reflection in a plane, and there is a number  $k \in \mathbf{Z}$  such that  $\text{Torque}(E_{n+2k}) = \text{Torque}(E_n)$  for all  $n \in \mathbf{Z}$ . Then  $M$  must be one of Riemann's minimal examples.*

However, we realize that the assumption of the existence of symmetric plane is not necessarily, and can prove more elaborate result:

**THEOREM 1.2 (Main Theorem).** *A properly embedded minimal surface in  $\mathbf{R}^3$  of genus zero is a Riemann's minimal example if it is the union of planar ends with the same torques at all integer heights in the complement of a solid cylinder.*

Recall a torque vector of a closed curve points to the direction with the largest tendency of rotation of a surface in  $\mathbf{R}^3$  around the curve. In particular, for a minimal surface of  $\mathbf{R}^3$  the torque vector associated to a planar end whose Gauss map has ramification order 2, like as ends of  $R_t$ , describes the intersection of the surface with the limit affine tangent plane. Precisely, this intersection curve is asymptotic to a straight line in the direction of the torque. Recall in  $R_t$ , all of the torque vectors of the planar ends are the same. We use the maximum principle of a minimal surface and Liouville's theorem to prove that  $M$  is also periodic in such a setting. Then, by virtue of the previous result of Meeks, Pérez and Ros in [4], we can say that  $M$  is one of  $R_t$ .

## 2. Preliminaries

A *minimal surface* in the 3-dimensional Euclidean space is a conformal harmonic immersion  $X : \tilde{S} \hookrightarrow \mathbf{R}^3$  where  $\tilde{S}$  is a 2-dimensional smooth manifold, with or without boundary. The well known *Enneper-Weierstrass representation* of a minimal surface of  $\mathbf{R}^3$  follows that

$$(1) \quad X(p) = \Re \int^p \left( \frac{1}{2} f (1 - g^2), \frac{i}{2} f (1 + g^2), fg \right) dz$$

where  $f$  is a holomorphic function and  $g$  is a meromorphic function on  $M$ , such that when a pole of order  $m$  of  $g$  occurs,  $f$  has a zero of order  $2m$ , and this is the only case where  $f$  can vanish. In fact,  $g$  is the stereographic projection of the Gauss map of  $X$  with respect to the north

pole. Applying Stoke's theorem to the isometric (minimal) immersion  $X$  we have

$$\int_S \Delta_S X \, dA = \int_{\partial S} \nu \, ds = 0$$

where  $S$  is a compact domain of  $\tilde{S}$ ,  $dA$  is the element of area on  $S$ ,  $\Delta_S$  is the Laplacian on  $S$ ,  $ds$  is the line element on  $\partial S$ , and  $\nu$  is the outward conormal. Define the flux of  $X$  along a closed curve  $\gamma \subset S$  as

$$Flux(\gamma) := \int_{\gamma} \nu \, ds$$

which is well defined on the homology class of  $[\gamma]$ . Now let  $R_{\vec{u}}$  be the Killing field associated with counter-clockwise rotation about the axis  $\ell_{\vec{u}}$  in the  $\vec{u}$  direction, then

$$\int_{\partial S} R_{\vec{u}} \cdot \nu \, ds = \int_{\partial S} (X \wedge \nu) \cdot \vec{u} \, ds = 0.$$

This motivates defining the homologous invariant torque of a closed curve  $\gamma$  on  $S$  by

$$Torque_0(\gamma) := \int_{\gamma} X \wedge \nu.$$

In general, the torque is dependent on the base point of the position vector  $X$ . If we move the base point from  $0$  to  $W \in \mathbf{R}^3$ , then the position vector based on  $W$  is  $X - W$ , and the torque is that

$$\begin{aligned} (2) \quad Torque_W(\gamma) &= Torque_0(\gamma) - W \wedge \int_{\gamma} \nu \\ &= Torque_0(\gamma) - W \wedge Flux(\gamma). \end{aligned}$$

Observe that we can define the flux and the torque associated to a planar end as that of one representative curve for the end.

### 3. Proof of main theorem

Since  $M$  is a properly embedded minimal surface of genus zero with two limit ends, by [6], it has the conformal type  $\mathbf{C}^* \setminus K$  where  $K$  is the set of discrete punctures  $p_n \in \mathbf{C}^*$ ,  $n \in \mathbf{Z}$ , corresponding to the planar ends  $E_n$  at integer height  $x_3 = n$ , respectively. Now we define a conformal harmonic embedding of  $M$  by

$$X : \mathbf{C}^* \setminus K \rightarrow \mathbf{R}^3.$$

Let  $X = (X^1, X^2, X^3)$ . Since  $M$  cuts transversally any horizontal plane, we can say that;

$$X^3(z) = \frac{1}{\log r} \log |z|$$

for some  $r > 1$ . Moreover, except at integer heights,  $M$  meets a horizontal plane in a compact Jordan curve, and hence  $X^3$  can be continuously extended to the whole  $\mathbf{C}^*$ . In particular, since  $E_n$  is close to  $\{x_3 = n\}$  at infinity, we have  $X^3(p_n) = \frac{1}{\log r} \log |p_n| = n$  for all  $p_n \in K$ . It follows that  $|p_n| = r^n$  for all  $n \in \mathbf{Z}$ . If  $(g, f dz)$  is the Weierstrass-data of  $X$ , then from (1) we have;

$$(3) \quad f(z)g(z) := 2 \frac{\partial X^3}{\partial z} = \frac{d}{dz} \left( \frac{1}{\log r} \log z \right) = \frac{1}{\log r} \frac{1}{z}$$

for all  $z \in \mathbf{C}^*$ . Since both  $z$  and  $dz$  have no zero or pole in  $\mathbf{C}^*$ , every planar end of  $M$  has the minimum branching order 2.

Let  $C_R \subset \mathbf{R}^3$  be a solid cylinder with sufficiently large radius  $R > 0$  such that  $M$  is the union of planar ends in complement of  $C_R$ , and let  $(s, t, 1) \in \mathbf{R}^3$  be the direction of the axis line of the cylinder for some  $s, t > 0$ . Denote by  $\tilde{M}$  the translation of  $M$  along the direction  $2(s, t, 1)$ . Since  $M$  and  $\tilde{M}$  are conformally equivalent, with another suitable coordinate  $\zeta$ , we have a minimal embedding

$$\tilde{X} : \mathbf{C}^* \setminus K \hookrightarrow \mathbf{R}^3$$

of  $\tilde{M}$  such that  $\tilde{X}^3(\zeta) = \frac{1}{\log r} \log |\zeta|$ . Therefore, we can say that

$$(4) \quad X^3 \equiv \tilde{X}^3 \quad \text{on } \mathbf{C}^*.$$

Now let  $(\tilde{g}, \tilde{f} dz)$  be the Weierstrass data of  $X$  and  $\tilde{X}$ , then similar to (3), we have  $\tilde{f}(z)\tilde{g}(z) = \frac{1}{\log r} \frac{1}{z}$  for all  $z \in \mathbf{C}^*$ . Since all the planar ends have the minimum branching order 2, we have

$$g(z) = (z - p_n)^2 h(z), \quad \tilde{g}(z) = (z - p_n)^2 \tilde{h}(z)$$

on a sufficiently small neighborhood  $D_n \subset \mathbf{C}^*$  of  $p_n$ , where  $p_m \notin D_n$  if  $m \neq n$ , and  $h$  and  $\tilde{h}$  are the holomorphic functions on  $D_n$  with  $h(p_n) \neq 0$  and  $\tilde{h}(p_n) \neq 0$ . Therefore,

$$f(z) = \frac{1}{\log r} \frac{1}{z g(z)} = \frac{1}{\log r} \frac{1}{p_n h(p_n)} \frac{1}{(z - p_n)^2} + F(z)$$

$$\tilde{f}(z) = \frac{1}{\log r} \frac{1}{z \tilde{g}(z)} = \frac{1}{\log r} \frac{1}{p_n \tilde{h}(p_n)} \frac{1}{(z - p_n)^2} + \tilde{F}(z)$$

where  $F$  and  $\tilde{F}$  are holomorphic functions on  $D_n$ , and hence from (1);

$$\begin{aligned} (X^1 - iX^2)(z) &= \frac{-1}{2 \log r} \frac{1}{p_n h(p_n)} \frac{1}{z - p_n} + O(|z - p_n|) \\ (\tilde{X}^1 - i\tilde{X}^2)(z) &= \frac{-1}{2 \log r} \frac{1}{p_n \tilde{h}(p_n)} \frac{1}{z - p_n} + O(|z - p_n|). \end{aligned}$$

Take a representative curve  $\gamma_n$  for the planar end  $E_n$  of  $M$  by

$$\gamma_n(\theta) = \left( R \cos \theta, R \sin \theta, \frac{1}{R}(\gamma_n^1 \cos \theta + \gamma_n^2 \sin \theta) + O(R^{-2}) \right)$$

where  $0 \leq \theta \leq 2\pi$  and

$$\gamma_n^1 X^1 + \gamma_n^2 X^2 = \Re \left( \frac{1}{-2(\log r)^2 p_n^2 h(p_n)} (X^1 + iX^2) \right).$$

Then the conormal is  $\nu(\theta) = (\cos \theta, \sin \theta, 0) + O(R^{-2})$ , and so we can compute the flux  $Flux(E_n) = (0, 0, 0)$  and the torque by

$$Torque(E_n) = \pi(-\gamma_n^2, \gamma_n^1, 0) = -\frac{i\pi}{2(\log r)^2} \left( (\overline{p_n^2 h(p_n)})^{-1}, 0 \right)$$

which is independent of the base point, see (2). Similarly, the torque of the end  $\tilde{E}_n$  of  $\tilde{M}$  at the height  $x_3 = n$  is

$$Torque(\tilde{E}_n) = -\frac{i\pi}{2(\log r)^2} \left( (\overline{p_n^2 \tilde{h}(p_n)})^{-1}, 0 \right).$$

Since both  $E_n$  and  $\tilde{E}_n$  have the same torques,  $\tilde{h}(p_n) = h(p_n)$  and

$$(X^1 - iX^2)(z) - (\tilde{X}^1 - i\tilde{X}^2)(z) = O(|z - p_n|)$$

on the small neighborhood of  $p_n$ . Together with (4), it shows that each  $p_n \in K$  is the removable singularity of  $X - \tilde{X}$ . Hence, we can obtain the extended harmonic map

$$Y : \mathbf{C}^* \hookrightarrow \mathbf{R}^3$$

of  $X - \tilde{X}$  such that  $Y(p_n) = 0$  for all  $n \in \mathbf{Z}$ . Take a pairwise disjoint connected neighborhood  $U_n \subset \mathbf{C}^*$  of  $p_n$ ,  $n \in \mathbf{Z}$ , respectively, such that both  $M \setminus \bigcup_{n \in \mathbf{Z}} X(U_n)$  and  $\tilde{M} \setminus \bigcup_{n \in \mathbf{Z}} \tilde{X}(U_n)$  are contained in  $C_R$ , then;

$$\|Y(z)\| = \|(X^1 - iX^2)(z) - (\tilde{X}^1 - i\tilde{X}^2)(z)\| \leq 2R\sqrt{1 + s^2 + t^2}$$

on  $\partial U_n$ . By the maximum principle of the harmonic map, we have;

$$\|Y\| \leq 2R\sqrt{1 + s^2 + t^2} \quad \text{on } U_n$$

for all  $n \in \mathbf{Z}$ . By the definition of  $U_n$ , the above inequality also holds in the complement of  $\bigcup_{n \in \mathbf{Z}} U_n$ , so  $Y$  is a bounded harmonic map on the

punctured plane  $\mathbf{C}^*$ . By virtue of the Liouville's theorem,  $Y$  is then a constant map  $Y \equiv 0$  by  $Y(p_n) = 0$ . Hence  $M = \tilde{M}$  and  $M$  is periodic under a translation. However, we know the result of [4]: A properly periodic embedded minimal annulus in  $\mathbf{R}^3$  must be one of Riemann's minimal examples. Thus  $M$  is also one of Riemann's minimal examples, and we have proved the theorem.

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