# A SHARP RESULT FOR A NONLINEAR LAPLACIAN DIFFERENTIAL EQUATION 

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#### Abstract

We investigate relations between multiplicity of solutions and source terms in a elliptic equation. We have a concerne with a sharp result for multiplicity of a nonlinear Laplacian differential equation.


## 1. Introduction

A semilinear elliptic boundary value problem under the Dirichlet boundary condition

$$
\begin{align*}
A u+b u^{+}-a u^{-} & =t_{1} \phi_{1}+t_{2} \phi_{2} \text { in } \Omega .  \tag{1.1}\\
u & =0 \quad \text { on } \quad \partial \Omega .
\end{align*}
$$

Here, the second order elliptic differential operator

$$
A=\sum_{1 \leq i, j \leq n} a_{i, j}(x) D_{i} D_{j}
$$

is a mapping from $L^{2}(\Omega)$ into itself with compact inverse, with eigenvalues $-\lambda_{i}$, each repeated as often as multiplicity, where $a_{i j}=a_{j i} \in C^{\infty}(\bar{\Omega})$.
$\Omega$ be a bounded set in $\mathbf{R}^{n}(n \geq 1)$ with smooth boundary $\partial \Omega$. We denote $\phi_{n}$ to be the eigenfuction corresponding to $\lambda_{n}(n=1,2, \cdots)$ and the eigenfuction such that $\phi_{1}>0$ in $\Omega$ and $\int_{\Omega} \phi_{1}^{2}=1$. We will also let $\phi_{i}$ denote the eigeneunctions corresponding to $\lambda_{i}$ normalized by inner product

$$
\left(\phi_{i}, \phi_{j}\right)=\int_{\Omega} \phi_{i} \phi_{j}= \begin{cases}1 & \text { if } i=j, \\ 0 & \text { if } i \neq j,\end{cases}
$$

and the set $\left\{\phi_{n} \mid n=1,2, \cdots\right\}$ is an orthogonal set in Hilbert space $H$.

[^0]We suppose that $a<\lambda_{1}, \lambda_{2}<b<\lambda_{3}$. we have a concern with the multiplicity of solutions of (1.1) when $h=t_{1} \phi_{1}+t_{2} \phi_{2}$ is generated by two eigenfunctions $\phi_{1}$ and $\phi_{2}$. Then equation (1.1) is equivalent to

$$
\begin{equation*}
A u+b u^{+}-a u^{-}=h \quad \text { in } \quad H . \tag{1.2}
\end{equation*}
$$

Hence we will study the equation (1.2). We use the contraction mapping principle to reduce the problem from an infinite dimensional space in $H$ to a finite dimensional one.

Let $V$ be the two dimensional subspace of $H$ spanned by $\left\{\phi_{1}, \phi_{2}\right\}$ and W be the orthogonal complement of V in $H$. Let $P$ be an orthogonal projection $H$ onto $V$. Then every element $u \in H$ is expressed as

$$
u=v+w,
$$

where $v=P u, w=(I-P) u$. Hence equation (1.2) is equavelent to a system

$$
\begin{gather*}
A w+(I-P)\left(b(v+w)^{+}-a(v+w)^{-}\right)=0  \tag{1.3}\\
A v+P\left(b(v+w)^{+}-a(v+w)^{-}\right)=t_{1} \phi_{1}+t_{2} \phi_{2} \tag{1.4}
\end{gather*}
$$

Here we look on (1.3) and (1.4) as a system of two equation in the two unknows $v$ and $w$.

We know in [2] that for fixed $v \in V$ (1.3) has a unique solution $w=\theta(v)$. Furthermore, $\theta(v)$ is Lipschitz continuous(with respect to the $L^{2}$-norm) in terms of $v$.

Hence, the study of the multipicity of solution of (1.2) is reduced to the study of the multipicity of solutions of an equivalent problem

$$
\begin{equation*}
A v+P\left(b(v+\theta(v))^{+}-a(v+\theta(v))^{-}\right)=t_{1} \phi_{1}+t_{2} \phi_{2} \tag{1.5}
\end{equation*}
$$

defined on the two dimensional subspace $V$ spanned by $\left\{\phi_{1}, \phi_{2}\right\}$.
While one feels intuively that (1.5) ought to be easier to solve than (1.2), there is the disadvantage of an implicitly defined term $\theta(v)$ in the equation. However, in our case, it turns out that we know $\theta(v)$ for some special $v^{\prime} s$.

If $v \geq 0$ or $v \leq 0$, then $\theta(v) \equiv 0$. For example, let us take $v \geq 0$ and $\theta(v)=0$. Then equation (1.3) reduces to

$$
A 0+(I-P)\left(b v^{+}-a v^{-}\right)=0
$$

which is satisfied because $v^{+}=v, v^{-}=0$ and $(I-P) v=0$, since $v \in V$. Since the subspace $V$ is spanned by $\left\{\phi_{1}, \phi_{2}\right\}$ and $\phi_{1}$ is a positive eigenfuction, there exists a cone $C_{1}$ defined by

$$
C_{1}=\left\{v=c_{1} \phi_{1}+c_{2} \phi_{2} \quad\left|c_{1} \geq 0,\left|c_{2}\right| \leq q c_{1}\right\}\right.
$$

for some $q>0$ so that $v \geq 0$ for all $v \in C_{1}$ and a cone $C_{3}$ defined by

$$
C_{3}=\left\{v=c_{1} \phi_{1}+c_{2} \phi_{2} \quad\left|c_{1} \leq 0,\left|c_{2}\right| \leq q\right| c_{1} \mid\right\}
$$

so that $v \leq 0$ for all $v \in C_{3}$.
Thus, even if we do not know $\theta(v)$ for all $v \in V$, we know $\theta(v) \equiv 0$ for $v \in C_{1} \cup C_{3}$. Now we define a map $\Pi: V \rightarrow V$ given by

$$
\begin{equation*}
\Pi(v)=A v+P\left(b(v+\theta(v))^{+}-a(v+\theta(v))^{-}\right), \quad v \in V \tag{1.6}
\end{equation*}
$$

$\Pi$ of (1.6) is continuous on $V$, and we can see that for $v \in V$

$$
\begin{equation*}
\Pi(c v)=c \Pi(v) \quad(c \geq 0) \tag{1.7}
\end{equation*}
$$

We investigate the image of the cones $C_{1}, C_{3}$ under $\Pi$. First, we consider the image of cone $C_{1}$. If $v=c_{1} \phi_{1}+c_{2} \phi_{2} \geq 0$, we have

$$
\begin{aligned}
\Pi(v) & =A v+P\left(b(v+\theta(v))^{+}-a(v+\theta(v))^{-}\right) \\
& =-c_{1} \lambda_{1} \phi_{1}-c_{2} \lambda_{2} \phi_{2}+b\left(c_{1} \phi_{1}+c_{2} \phi_{2}\right) \\
& =c_{1}\left(b-\lambda_{1}\right) \phi_{1}+c_{2}\left(b-\lambda_{2}\right) \phi_{2}
\end{aligned}
$$

Thus the image of the rays $c_{1} \phi_{1} \pm q c_{1} \phi_{2}\left(c_{1} \geq 0\right)$ can be caculated and they are

$$
\begin{equation*}
c_{1}\left(b-\lambda_{1}\right) \phi_{1} \pm q c_{1}\left(b-\lambda_{2}\right) \phi_{2} \quad\left(c_{1} \geq 0\right) \tag{1.8}
\end{equation*}
$$

Therefore if $a<\lambda_{1}, \lambda_{2}<b<\lambda_{3}$, then $\Pi$ maps $C_{1}$ onto the cone

$$
D_{1}=\left\{d_{1} \phi_{1}+d_{2} \phi_{2}\left|d_{1} \geq 0,\left|d_{2}\right| \leq q\left(\frac{b-\lambda_{2}}{b-\lambda_{1}}\right) d_{1}\right\}\right.
$$

Second, we consider the image of the cone $C_{3}$. If

$$
v=-c_{1} \phi_{1}+c_{2} \phi_{2} \leq 0 \quad\left(c_{1} \geq 0,\left|c_{2}\right| \leq q c_{1}\right)
$$

we have

$$
\begin{aligned}
\Pi(v) & =A v+P\left(b(v+\theta(v))^{+}-a(v+\theta(v))^{-}\right) \\
& =A v+P(a v) \\
& =c_{1}\left(\lambda_{1}-a\right) \phi_{1}-c_{2}\left(\lambda_{2}-a\right) \phi_{2}
\end{aligned}
$$

Thus the image of the rays $-c_{1} \phi_{1} \pm q c_{1} \phi_{2}\left(c_{1} \geq 0\right)$ can be caculated and they are

$$
\begin{equation*}
c_{1}\left(\lambda_{1}-a\right) \phi_{1} \pm q c_{1}\left(\lambda_{2}-a\right) \phi_{2} \quad\left(c_{1} \geq 0\right) \tag{1.9}
\end{equation*}
$$

Therefore, if $a<\lambda_{1}, \lambda_{2}<b<\lambda_{3}$, then $\Pi$ maps $C_{3}$ onto the cone

$$
D_{3}=\left\{d_{1} \phi_{1}+d_{2} \phi_{2}\left|d_{1} \geq 0,\left|d_{2}\right| \leq q\left(\frac{\lambda_{2}-a}{\lambda_{1}-a}\right) d_{1}\right\}\right.
$$

## 2. The existence of solutions

We note that $D_{1} \subset D_{3}$ since $a<\lambda_{1}, \lambda_{2}<b<\lambda_{3}$. We investigate the images of the cones $C_{2}, C_{4}$ under $\Pi$. we suppose that $a<\lambda_{1}, \lambda_{2}<b<$ $\lambda_{3}, h=t_{1} \phi_{1}+t_{2} \phi_{2}$. Now we set

$$
\begin{gathered}
C_{2}=\left\{v=c_{1} \phi_{1}+c_{2} \phi_{2} \quad\left|\quad c_{2} \geq 0, c_{2} \geq q\right| c_{1} \mid\right\} \\
C_{4}=\left\{v=c_{1} \phi_{1}+c_{2} \phi_{2} \quad\left|\quad c_{2} \leq 0,\left|c_{2}\right| \geq q\right| c_{1} \mid\right\}
\end{gathered}
$$

Then the union of $C_{1}, C_{2}$, and $C_{3}, C_{4}$ are the space $V$.
We note that $D_{1} \subset D_{3}$ since $a<\lambda_{1}, \lambda_{2}<b<\lambda_{3}$. We investigate the images of the cones $C_{2}, C_{4}$ under $\Pi$.

To investigate the images of the cones $C_{2}, C_{4}$, we need the following lemma.

Lemma 2.1. There exists $d>0$ so that

$$
\left(\Pi(v), \phi_{1}\right) \geq d\left|c_{2}\right| \text { for all } v=c_{1} \phi_{1}+c_{2} \phi_{2} \in V .
$$

Proof. Let $g(u)=b u^{+}-a u^{-}$and let $v=c_{1} \phi_{1}+c_{2} \phi_{2}$. Let $u=c_{1} \phi_{1}+$ $c_{2} \phi_{2}+\theta\left(c_{1}, c_{2}\right)$. Then

$$
\Pi\left(c_{1} \phi_{1}+c_{2} \phi_{2}\right)=A\left(c_{1} \phi_{1}+c_{2} \phi_{2}\right)+P\left(g\left(c_{1} \phi_{1}+c_{2} \phi_{2}+\theta\left(c_{1}, c_{2}\right)\right)\right) .
$$

So we have

$$
\left(\Pi(v), \phi_{1}\right)=\left(\left(A+\lambda_{1}\right)\left(c_{1} \phi_{1}+c_{2} \phi_{2}\right), \phi_{1}\right)+\left(g(u)-\lambda_{1} u, \phi_{1}\right) .
$$

The first term is zero because $\left(A+\lambda_{1}\right) \phi_{1}=0$ and $A$ is a self-adjoint. The second term satisfies

$$
\begin{aligned}
g(u)-\lambda_{1} u & =b u^{+}-a u^{-}-\lambda_{1}\left(u^{+}-u^{-}\right) \\
& =\left(b-\lambda_{1}\right) u^{+}+\left(\lambda_{1}-a\right) u^{-} \geq \gamma|u|,
\end{aligned}
$$

where $\gamma=\min \left\{b-\lambda_{1}, \lambda_{1}-a\right\}>0$. Therefore

$$
\left(\Pi(v), \phi_{1}\right) \geq \gamma \int|u| \phi_{1} .
$$

Now there exists $d>0$ so that $\gamma \phi_{1} \geq d\left|\phi_{2}\right|$ and therefore

$$
\gamma \int|u| \phi_{1} \geq d \int|u|\left|\phi_{2}\right| \geq d\left|\int u \phi_{2}\right|=d\left|c_{2}\right| .
$$

Lemma 2.1 means that the image of $\Pi$ is contained in the right half-plane. That is, $\Pi\left(C_{2}\right)$ and $\Pi\left(C_{4}\right)$ are the cones in the right half-plane. The image of $C_{2}$ is the cone containing

$$
D_{2}=\left\{\begin{array}{l|l}
d_{1} \phi_{1}+d_{2} \phi_{2} & \left.d_{1} \geq 0,-q\left(\frac{\lambda_{2}-a}{\lambda_{1}-a}\right) d_{1} \leq d_{2} \leq q\left(\frac{\lambda_{2}-b}{\lambda_{1}-b}\right) d_{1}\right\}, ~
\end{array}\right.
$$

and the image of $C_{4}$ under $\Pi$ is the containing

$$
D_{4}=\left\{\begin{array}{l|l}
d_{1} \phi_{1}+d_{2} \phi_{2} & \left.d_{1} \geq 0,-q\left(\frac{\lambda_{2}-b}{\lambda_{1}-b}\right) d_{1} \leq d_{2} \leq q\left(\frac{\lambda_{2}-a}{\lambda_{1}-a}\right) d_{1}\right\} .
\end{array}\right.
$$

We consider the restriction $\left.\Pi\right|_{C_{i}}(1 \leq i \leq 4)$ of $\Pi$ to the cone $C_{i}$. Let $\Pi_{i}=\left.\Pi\right|_{C_{i}}$, i.e.,

$$
\Pi_{i}: C_{i} \rightarrow V
$$

We consider the segments $s_{2}$ and $s_{4}$ as follows

$$
\begin{aligned}
& s_{2}=\left\{\phi_{1}+d_{2} \phi_{2} \left\lvert\,-q\left(\frac{\lambda_{2}-a}{\lambda_{1}-a}\right) \leq d_{2} \leq q\left(\frac{\lambda_{2}-b}{\lambda_{1}-b}\right)\right.\right\} \\
& s_{4}=\left\{\phi_{1}+d_{2} \phi_{2} \left\lvert\,-q\left(\frac{\lambda_{2}-b}{\lambda_{1}-b}\right) \leq d_{2} \leq q\left(\frac{\lambda_{2}-a}{\lambda_{1}-a}\right)\right.\right\}
\end{aligned}
$$

We investigate the inverse image $\Pi_{2}^{-1}\left(s_{2}\right), \Pi_{4}^{-1}\left(s_{4}\right)$. We note that $\Pi_{i}\left(C_{i}\right)(i=$ $2,4)$ contains $D_{i}$.

By (1.7) and Lemma 2.1, we can see the following lemma.
Lemma 2.2. Let $\sigma_{i}(i=2,4)$ be any simple path in $D_{i}$ with end points on $\partial D_{i}$, where each ray (starting from the origin) in $D_{i}$ intersect only one point of $\sigma_{i}$. Then the inverse image $\Pi_{i}^{-1}\left(\sigma_{i}\right)$ of $\sigma_{i}$ is a simple path in $C_{i}$ with end points on $\partial C_{i}$, where any ray in $C_{i}$, starting from the origin, intersects only one point of this path.

With Lemma 2.1 and Lemma 2.2, we have the following theorem.
Theorem 2.3. (a) The restriction $\Pi_{i}: C_{i} \rightarrow D_{i}(i=1,3)$ is bijective.
(b) $\Pi: C_{j} \rightarrow D_{j}(j=2,4)$ is surjective. Therefore, $\Pi$ maps $V$ onto $D_{3}$.

Proof. First, we shall show that $\Pi_{1}: C_{1} \rightarrow D_{1}$ is bijective. By (1.8), the restriction $\Pi_{1}$ maps $C_{1}$ onto $D_{1}$. We consider the segment

$$
s_{1}=\left\{\phi_{1}+d_{2} \phi_{2}| | d_{2} \left\lvert\, \leq q\left(\frac{b-\lambda_{2}}{b-\lambda_{1}}\right)\right.\right\}
$$

Then the inverse image $\Pi_{1}^{-1}\left(s_{1}\right)$ is a segment

$$
\mathcal{S}_{1}=\left\{\left.\frac{1}{b-\lambda_{1}}\left(\phi_{1}+c_{2} \phi_{2}\right)| | c_{2} \right\rvert\, \leq q\right\}
$$

By Lemma 2.2, $\Pi_{1}: C_{1} \rightarrow D_{1}$ is bijective. Second, in the same way we can show that $\Pi_{3}: C_{3} \rightarrow D_{3}$ is bijective. (b) By (1.9) and Lemma 2.2, the restriction $\Pi_{j}: C_{j} \rightarrow D_{j}(j=2,4)$ is surjective.

We note that all cones $D_{2}, D_{3}, D_{4}$ contain the cone $D_{1}$. Also $D_{3}, D_{2}$ contain the cone $D_{2} \backslash D_{1}$, and $D_{3}, D_{4}$ contain the cone $D_{4} \backslash D_{1}$.

Hence we have the following theorem.
Theorem 2.3 Suppose $a<\lambda_{1}, \lambda_{2}<b<\lambda_{3}$. Let $h=t_{1} \phi_{1}+t_{2} \phi_{2}$. Then we have the following.
(a) If $h \in \operatorname{Int} D_{1}$, then equation (1.1) has at least four solutions.
(b) If $h \in \partial D_{1}$, then equation (1.1) has at least three solutions.
(c) If $h \in \operatorname{Int}\left(D_{3} \backslash D_{1}\right)$, then equation (1.1) has at least two solutions.
(d) If $h \in \partial D_{3}$, then equation (1.1) has at least one solution.
(e) If $h$ does not belong to the cone $D_{3}$, then equation (1.1) has no solution.

## 3. A sharp result for multiplicity

We shall investigate a sharp result for the multiplicity of equation (1.1) when the source term $h$ belong to the interior $\operatorname{Int} D_{1}$ of the cone $D_{1}$, and $A$ is the Laplacian operator $L$.

Let $A$ be a second order linear elliptic differential operator. Given a function $\eta \in L^{\infty}(\Omega)$, let us consider the linear eigenvalue problem

$$
\begin{align*}
-A u & =\lambda \eta u \quad \text { in } \quad \Omega, \\
u & =0 \quad \text { on } \quad \partial \Omega . \tag{3.1}
\end{align*}
$$

An eigenvalue of (3.1) is a $\lambda$ such that (3.1) has a solution $u \neq 0$. Any $\phi \neq 0$ satisfying (3.1) is an eigenfunction associated to the eigenvalue $\lambda$.

Lemma 3.1.(Comparison Property)[1]. If $\eta \leq \xi$ in $\Omega$, then $\lambda_{k}(\eta) \geq \lambda_{k}(\xi)$; if $\eta<\xi$ in a subset of positive measure, then $\lambda_{k}(\eta)>\lambda_{k}(\xi)$. In particular, if $\eta<\lambda_{k}$, then $\lambda_{k}(\eta)>1$; if $\eta>\lambda_{k}$, then $\lambda_{k}(\eta)<1$.

Given $u$, we denote by $\mathcal{C}(u)$ the characteristic function of the positive set of $u$, that is,

$$
[\mathcal{C}(u)](x)=\left\{\begin{array}{lll}
1, & \text { if } & u(x)>0 \\
0, & \text { if } & u(x) \leq 0
\end{array}\right.
$$

We set $\alpha(u)=b \mathcal{C}(u)+a \mathcal{C}(-u)$ when the measure of $\{x \mid u(x)=0\}$ is zero.

Definition[6]. We say that $u$ is a nondegenerate solution of equation (1.1) if the problem

$$
\begin{array}{rlrl}
-A v & =\alpha(u) v & & \text { in } \quad \Omega \\
v & =0 & \text { on } & \\
& \partial \Omega
\end{array}
$$

has only the trivial solution $v \equiv 0$.

We have a concern only when $A$ is the Laplacian operator $L$. We denote by $K$ the operator $(-L)^{-1}$ from $H^{-1}(\Omega)$ into $E$ and we consider it as a compact operator on $H$ in a view of Sobolev's imbeding theorems.

Given $\alpha \in L^{\frac{n}{2}}(\Omega)$ one can consider the eigenvalue problem

$$
\begin{align*}
-L v & =\nu \alpha v \quad \text { in } \quad \Omega \\
v & =0 \quad \text { on } \quad \partial \Omega \tag{3.2}
\end{align*}
$$

It is well known $([6])$ that if $\alpha>0$ in a set of positive measure, then the positive number $\nu$ for which (3.2) has a nontrivial solution that is a term of a sequence $\nu_{1}(\alpha), \nu_{2}(\alpha), \cdots, \nu_{j}(\alpha), \cdots$ diverging to $+\infty$. Since each eigenvalue $\nu_{j}$ has finite multiplicity, we can repeat it in the sequence as many times as its multiplicity.

We consider the nonlinear Lapacian differential equation

$$
\begin{equation*}
L u+b u^{+}-a u^{-}=h(x) \quad \text { in } \quad H \tag{3.3}
\end{equation*}
$$

Lemma 3.2. Assume $a<\lambda_{1}$ and $b \leq \lambda_{k}$ for a given integer $k>2$. Let $h(x)=\phi_{1}+t_{2} \phi_{2} \in \operatorname{Int} D_{1}$. Then if $u$ is a solution of (3.3) which changes sign in $\Omega$, we have

$$
\nu_{1}(\alpha(u))<1<\nu_{k-1}(\alpha(u))
$$

Proof. Equation (3.3) has the positive solution $u_{p}=\left(b-\lambda_{1}\right)^{-1} \phi_{1}+t_{2}(b-$ $\left.\lambda_{2}\right)^{-1} \phi_{2}$ and a negative solution $u_{n}=\left(a-\lambda_{1}\right)^{-1} \phi_{1}+t_{2}\left(a-\lambda_{2}\right)^{-1} \phi_{2}$. Writing (3.3) for $u$ and $u_{p}$ and substracting we get:

$$
\begin{equation*}
-L\left(u_{p}-u\right)=b\left(u_{p}-u^{+}\right)+a u^{-} \tag{3.4}
\end{equation*}
$$

Let us use the notation

$$
\hat{\alpha}=\frac{b\left(u_{p}-u^{+}\right)+a u^{-}}{u_{p}-u} .
$$

We have the inequalities:

$$
\begin{equation*}
a<\alpha(u)<\hat{\alpha}<b \tag{3.5}
\end{equation*}
$$

By (3.4), $\nu_{j}(\hat{\alpha})=1$ for some $j$ and by (3.5) $j \in\{1,2, \cdots, k-1\}$. We have similar computations with $u_{n}$ and find a function $\check{\alpha}$ such that $\nu_{j}(\check{\alpha})=1$ for some $j^{\prime} \in\{1,2, \cdots, k-1\}$ and

$$
\begin{equation*}
a<\check{\alpha}<\alpha(u)<b, \tag{3.6}
\end{equation*}
$$

where each inequality holds on a subset of positive measure in $\Omega$. By Lemma 3.1, we have

$$
\begin{gathered}
1=\nu_{j}(\hat{\alpha}) \leq \nu_{k-1}(\hat{\alpha})<\nu_{k-1}(\alpha(u)), \\
\nu_{1}(\alpha(u))<\nu_{1}(\check{\alpha}) \leq \nu_{j^{\prime}}(\check{\alpha})=1,
\end{gathered}
$$

which proves the lemma.

Theorem 3.3. Let $a<\lambda_{1}, \lambda_{2}<b<\lambda_{3}$ and let $h \in \operatorname{Int} D_{1}$. Then equation (3.3) has exactly four nondegenerate solutions.

Proof. The staetment follows from Lemma 3.2 which ensures that any solution which changes sign is nondegenerate and has local degree -1 . Since we know that the solutions of constant sign only are $u_{p}$ and $u_{n}$ and they have local degree 1 , by using the equality:

$$
d_{L S}\left(u-K\left(b u^{+}-a u^{-}\right), B(0, r),-K \phi_{1}\right)=0
$$

which is proved in [6] for large positive $r$. By the homotopy invariance property of degree, if $h \in \operatorname{Int} D_{1}$, then

$$
d_{L S}\left(u-K\left(b u^{+}-a u^{-}\right), B(0, r),-K h\right)=0
$$

for large positive $r$. This completes the proof.

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